Computer-Aided Reasoning for Software

Symbolic Execution

courses.cs.washington.edu/courses/cse507/18sp/

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Today

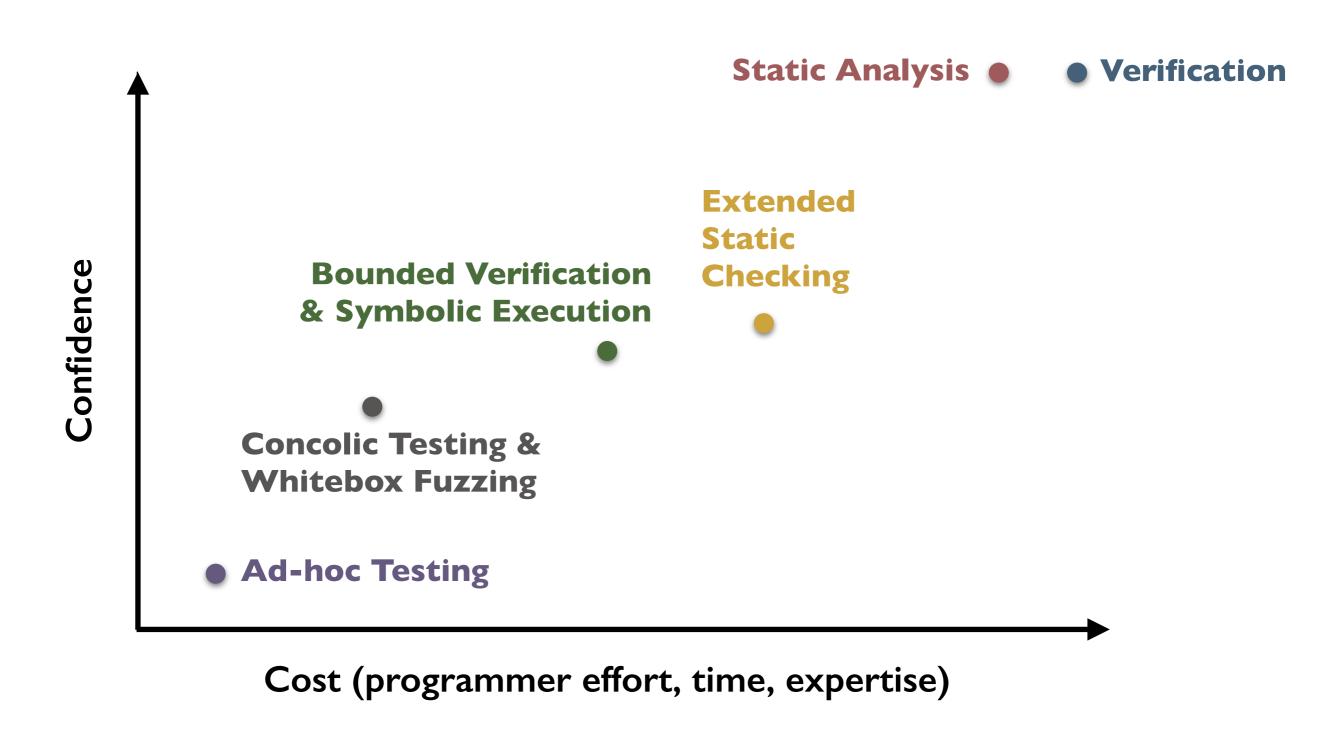
Last lecture

Bounded verification: forward VCG for finitized programs

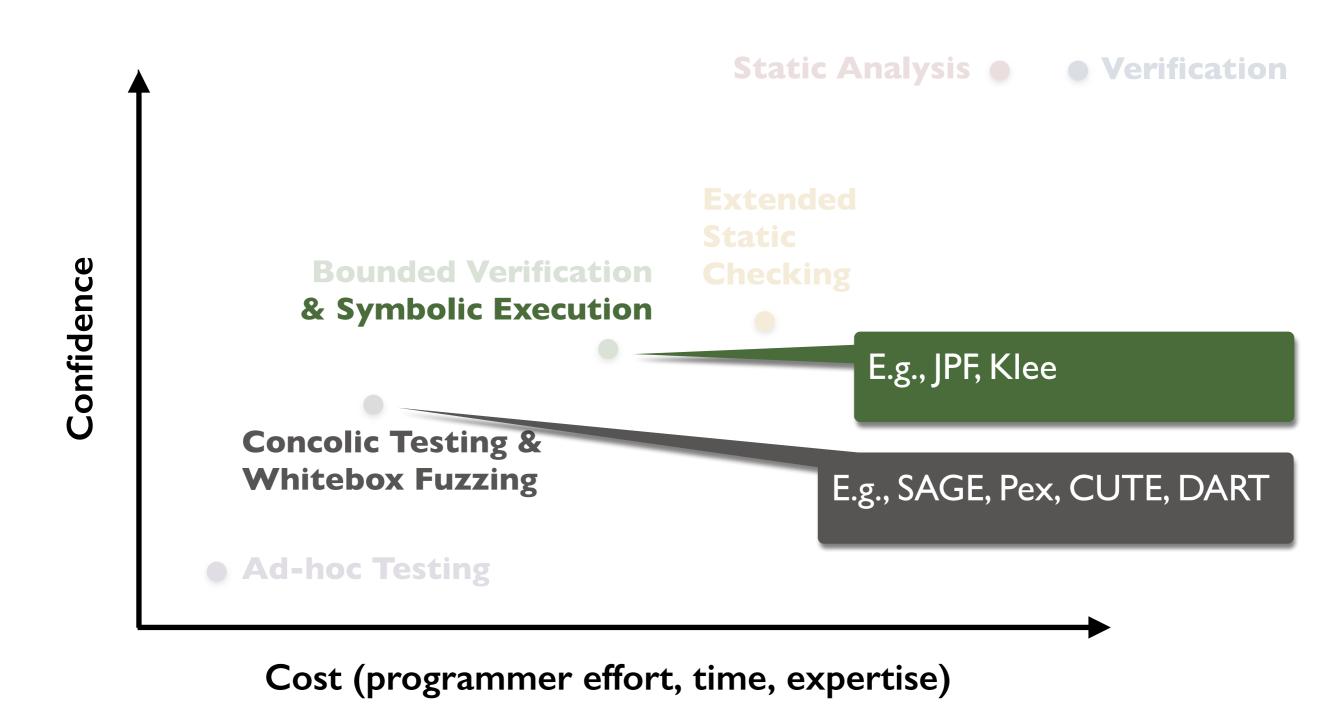
Today

- Symbolic execution: a path-based translation
- Concolic testing

The spectrum of program validation tools



The spectrum of program validation tools



A brief history of symbolic execution

1976: A system to generate test data and symbolically execute programs (Lori Clarke)

1976: Symbolic execution and program testing (James King)

2005-present: practical symbolic execution

- Using SMT solvers
- Heuristics to control exponential explosion
- Heap modeling and reasoning about pointers
- Environment modeling
- Dealing with solver limitations

```
def f (x, y):
    if (x > y):
        x = x + y
        y = x - y
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        if (x - y > 0):
        assert false
    return (x, y)
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Execute the program on symbolic values.

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Execute the program on symbolic values.

Symbolic state maps variables to symbolic values.

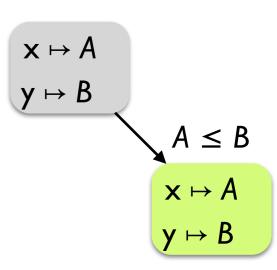
 $x \mapsto A$ $y \mapsto B$

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Path condition is a quantifier-free formula over the symbolic inputs that encodes all branch decisions taken so far.

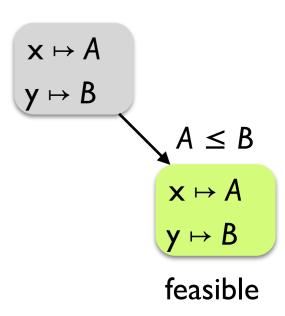


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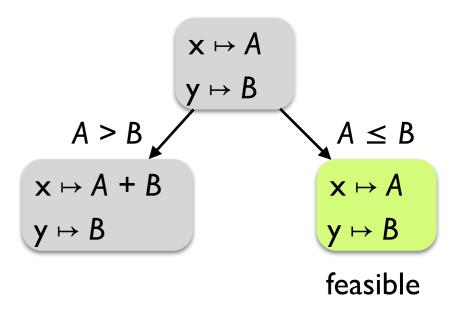


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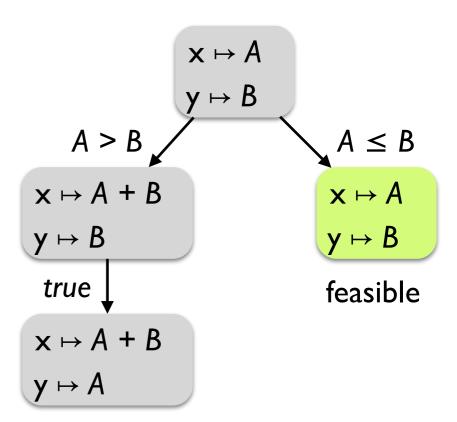


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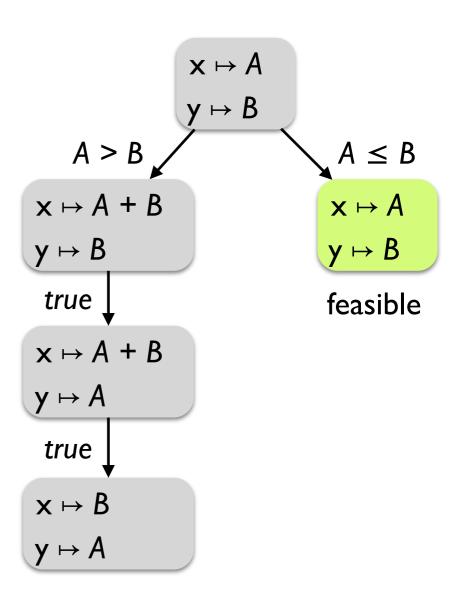


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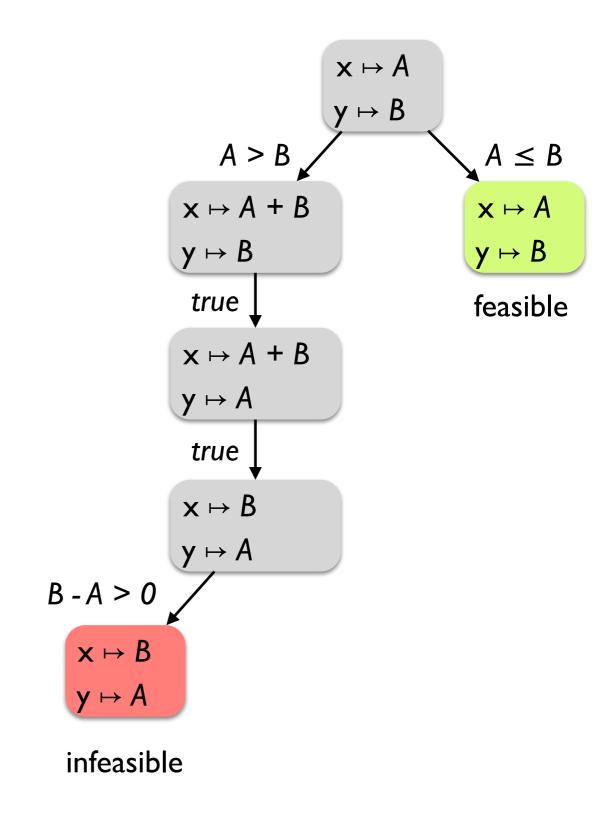


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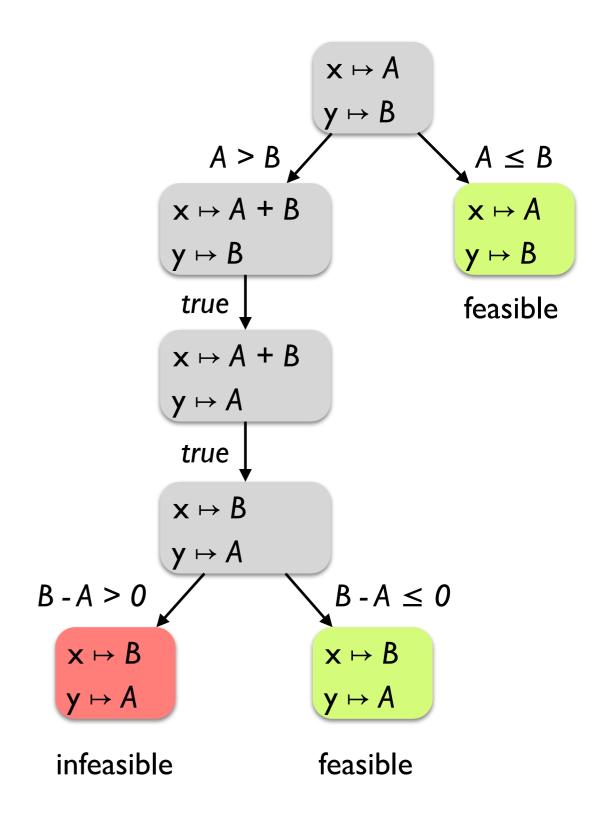


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Symbolic execution: practical issues

Loops and recursion: infinite execution trees

Path explosion: exponentially many paths

Heap modeling: symbolic data structures and pointers

Solver limitations: dealing with complex PCs

Environment modeling: dealing with native / system / library calls

Dealing with infinite execution trees:

- Finitize paths by unrolling loops and recursion (bounded verification)
- Finitize paths by limiting the size of PCs (bounded verification)
- Use loop invariants (verification)

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```
init;
while (C) {
   B;
}
assert P;
```

Dealing with infinite execution trees:

- Finitize paths by unrolling loops and recursion (bounded verification)
- Finitize paths by limiting the size of PCs (bounded verification)
- Use loop invariants (verification)

```
assert I;
init;
while (C) {
   B;
}
assert P;

assume I;
if (C) {
   B;
   assert I;
} else {
   assert P;
}
```

init;

Dealing with infinite execution trees:

• Finitize paths by unrolling loops and recursion (bounded verification)

init;

- Finitize paths by limiting the size of PCs (bounded verification)
- Use loop invariants (verification)

```
assert I;
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}
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I

assume I;
if (C) {
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Path explosion

Achieving good coverage in the presence of exponentially many paths:

- Select next branch at random
- Select next branch based on coverage
- Interleave symbolic execution with random testing

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Heap modeling

Modeling symbolic heap values and pointers

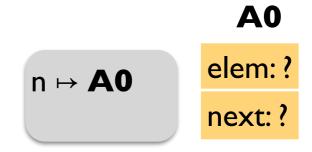
- Bit-precise memory modeling with the theory of arrays (EXE, Klee, SAGE)
- Lazy concretization (JPF)
- Concolic lazy concretization (CUTE)

```
class Node {
   int elem;
   Node next;
}

n = symbolic(Node);
x = n.next;
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```
class Node {
  int elem;
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n = symbolic(Node);
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A0.next = null

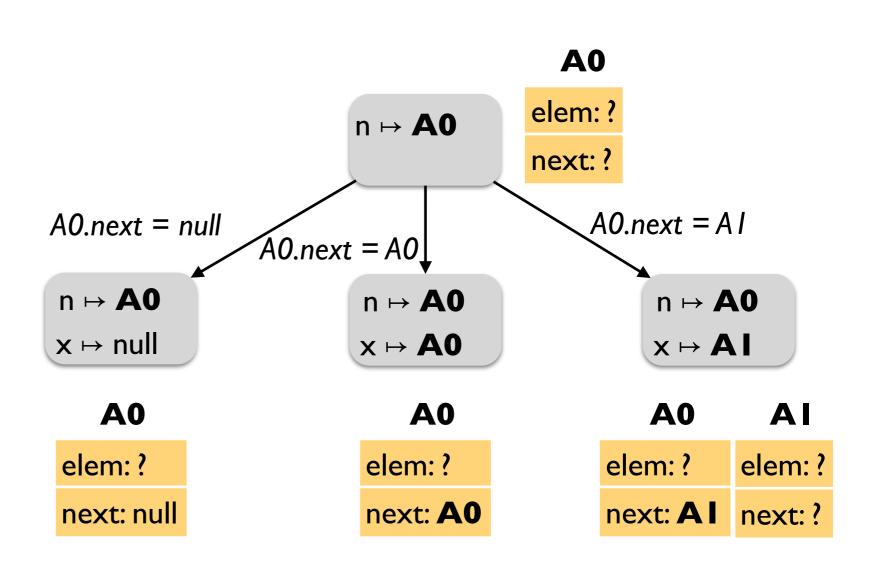
n \to A0
  x \to null

A0
  elem:?
  next: null
```

```
A0
                                                                               elem:?
class Node {
                                                                n \mapsto \mathbf{A0}
   int elem;
                                                                               next:?
  Node next;
                                     A0.next = null
                                                        A0.next = A0
                                      n \mapsto A0
                                                                 n \mapsto \mathbf{A0}
n = symbolic(Node);
                                      x \mapsto null
                                                                x \mapsto A0
x = n.next;
                                          A0
                                                                     A0
                                      elem:?
                                                                 elem:?
                                       next: null
                                                                 next: A0
```

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   int elem;
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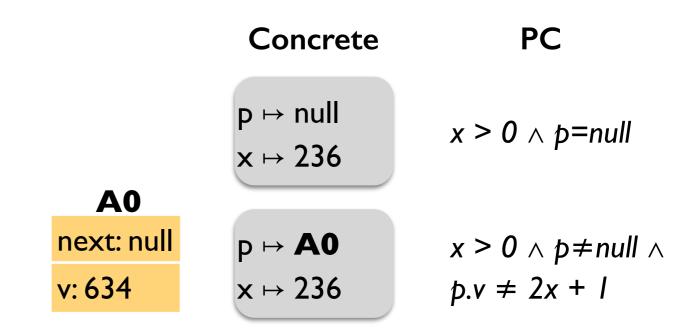
```
typedef struct cell {
 int ∨;
 struct cell *next;
} cell;
int f(int v) {
  return 2*v + 1;
int testme(cell *p, int x) {
  if (x > 0)
    if (p != NULL)
      if (f(x) == p->v)
        if (p->next == p)
          abort();
  return 0;
```

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```
Concrete PC
p \mapsto \text{null} \\ x \mapsto 236
x > 0 \land p = \text{null}
```

Execute concretely and symbolically.

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typedef struct cell {
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Execute concretely and symbolically.

Negate last decision and solve for new inputs.

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```

```
Concrete
                                               PC
                  p \mapsto null
                                        x > 0 \land p=null
                  x \mapsto 236
    A0
next: null
                  p → A0
                                        x > 0 \land p \neq null \land
v: 634
                  x \mapsto 236
                                       p.v \neq 2x + 1
    A0
                                        x > 0 \land p \neq null \land
next: null
                  p → A0
                                        p.v = 2x + 1 \wedge
v: 3
                  X \mapsto I
                                        p.next \neq p
```

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PC
                   Concrete
                  p \mapsto null
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                  p → A0
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v: 3
                  X \mapsto I
                                        p.next = p
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Execute concretely and symbolically.

Negate last decision and solve for new inputs.

Solver limitations

Reducing the demands on the solver:

- On-the-fly expression simplification
- Incremental solving
- Solution caching
- Substituting concrete values for symbolic in complex PCs (CUTE)

Environment modeling

Dealing with system / native / library calls:

- Partial state concretization
- Manual models of the environment (Klee)

Summary

Today

Practical symbolic execution and concolic testing

Next lecture

Angelic execution