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## CSE505, Winter 2012, Final Examination March 12, 2012

Rules:

- The exam is closed-book, closed-notes, except for one side of one $8.5 \times 11$ in piece of paper.
- Please stop promptly at 2:20.
- You can rip apart the pages.
- There are $\mathbf{1 0 0}$ points total, distributed unevenly among $\mathbf{7}$ questions, most of which have multiple parts.

Advice:

- Read questions carefully. Understand a question before you start writing.
- Write down thoughts and intermediate steps so you can get partial credit.
- The questions are not necessarily in order of difficulty. Skip around. In particular, make sure you get to all the problems.
- If you have questions, ask.
- Relax. You are here to learn.

For your reference (page 1 of 2 ):

$$
\begin{aligned}
e & ::=\lambda x . e|x| e e|c|\left\{l_{1}=e_{1}, \ldots, l_{n}=e_{n}\right\}\left|e . l_{i}\right| \text { fix } e \\
v & ::=\lambda x \cdot e|c|\left\{l_{1}=v_{1}, \ldots, l_{n}=v_{n}\right\} \\
\tau & ::=\text { int }|\tau \rightarrow \tau|\left\{l_{1}: \tau_{1}, \ldots, l_{n}: \tau_{n}\right\}
\end{aligned}
$$

$$
e \rightarrow e^{\prime}
$$

$$
\overline{(\lambda x . e) v \rightarrow e[v / x]} \quad \frac{e_{1} \rightarrow e_{1}^{\prime}}{e_{1} e_{2} \rightarrow e_{1}^{\prime} e_{2}} \quad \frac{e_{2} \rightarrow e_{2}^{\prime}}{v e_{2} \rightarrow v e_{2}^{\prime}} \quad \frac{e \rightarrow e^{\prime}}{\operatorname{fix} e \rightarrow \operatorname{fix} e^{\prime}} \quad \overline{\text { fix } \lambda x . e \rightarrow e[(\operatorname{fix} \lambda x . e) / x]}
$$

$$
\overline{\left\{l_{1}=v_{1}, \ldots, l_{n}=v_{n}\right\} \cdot l_{i} \rightarrow v_{i}}
$$

$$
\frac{e_{i} \rightarrow e_{i}^{\prime}}{\left\{l_{1}=v_{1}, \ldots, l_{i-1}=v_{i-1}, l_{i}=e_{i}, \ldots, l_{n}=e_{n}\right\} \rightarrow\left\{l_{1}=v_{1}, \ldots, l_{i-1}=v_{i-1}, l_{i}=e_{i}^{\prime}, \ldots, l_{n}=e_{n}\right\}}
$$

```
\Gamma\vdashe:\tau
```

$\overline{\Gamma \vdash c: \operatorname{int}} \quad \overline{\Gamma \vdash x: \Gamma(x)} \quad \frac{\Gamma, x: \tau_{1} \vdash e: \tau_{2}}{\Gamma \vdash \lambda x . e: \tau_{1} \rightarrow \tau_{2}} \quad \frac{\Gamma \vdash e_{1}: \tau_{2} \rightarrow \tau_{1} \quad \Gamma \vdash e_{2}: \tau_{2}}{\Gamma \vdash e_{1} e_{2}: \tau_{1}} \quad \frac{\Gamma \vdash e: \tau \rightarrow \tau}{\Gamma \vdash \mathrm{fix} e: \tau}$

$$
\frac{\Gamma \vdash e_{1}: \tau_{1} \quad \ldots \quad \Gamma \vdash e_{n}: \tau_{n} \quad \text { labels distinct }}{\Gamma \vdash\left\{l_{1}=e_{1}, \ldots, l_{n}=e_{n}\right\}:\left\{l_{1}: \tau_{1}, \ldots, l_{n}: \tau_{n}\right\}} \quad \frac{\Gamma \vdash e:\left\{l_{1}: \tau_{1}, \ldots, l_{n}: \tau_{n}\right\}}{\Gamma \vdash e . l_{i}: \tau_{i}} \quad 1 \leq i \leq n
$$

$$
\frac{\Gamma \vdash e: \tau \quad \tau \leq \tau^{\prime}}{\Gamma \vdash e: \tau^{\prime}}
$$

## $\tau_{1} \leq \tau_{2}$

$$
\overline{\left\{l_{1}: \tau_{1}, \ldots, l_{i-1}: \tau_{i-1}, l_{i}: \tau_{i}, \ldots, l_{n}: \tau_{n}\right\} \leq\left\{l_{1}: \tau_{1}, \ldots, l_{i}: \tau_{i}, l_{i-1}: \tau_{i-1}, \ldots, l_{n}: \tau_{n}\right\}}
$$

$$
\overline{\left\{l_{1}: \tau_{1}, \ldots, l_{n}: \tau_{n}, l: \tau\right\} \leq\left\{l_{1}: \tau_{1}, \ldots, l_{n}: \tau_{n}\right\}} \quad \frac{\tau_{i} \leq \tau_{i}^{\prime}}{\left\{l_{1}: \tau_{1}, \ldots, l_{i}: \tau_{i}, \ldots, l_{n}: \tau_{n}\right\} \leq\left\{l_{1}: \tau_{1}, \ldots, l_{i}: \tau_{i}^{\prime}, \ldots, l_{n}: \tau_{n}\right\}}
$$

$$
\begin{array}{ll}
\frac{\tau_{3} \leq \tau_{1} \quad \tau_{2} \leq \tau_{4}}{\tau_{1} \rightarrow \tau_{2} \leq \tau_{3} \rightarrow \tau_{4}} & \overline{\tau \leq \tau}
\end{array} \frac{\tau_{1} \leq \tau_{2} \quad \tau_{2} \leq \tau_{3}}{\tau_{1} \leq \tau_{3}}
$$

[^0]For your reference (page 2 of 2 ):

$$
\begin{aligned}
& e::= \\
& \tau \ldots:|\mathrm{A}(e)| \mathrm{B}(e) \mid(\text { match } e \text { with } \mathrm{A} x . e \mid \mathrm{B} x . e)|(e, e)| e .1 \mid e .2 \\
& v::= \\
& \ldots\left|\tau_{1}+\tau_{2}\right| \tau_{1} * \tau_{2} \\
&(v)|\mathrm{B}(v)|(v, v)
\end{aligned}
$$

$$
e \rightarrow e^{\prime}
$$

$$
\frac{e \rightarrow e^{\prime}}{\mathrm{A}(e) \rightarrow \mathrm{A}\left(e^{\prime}\right)} \quad \frac{e \rightarrow e^{\prime}}{\mathrm{B}(e) \rightarrow \mathrm{B}\left(e^{\prime}\right)} \quad \frac{e \rightarrow e^{\prime}}{\text { match } e \text { with } \mathrm{A} x . e_{1} \mid \mathrm{B} y . e_{2} \rightarrow \text { match } e^{\prime} \text { with } \mathrm{A} x . e_{1} \mid \mathrm{B} y \cdot e_{2}}
$$

$$
\overline{\text { match } \mathrm{A}(v) \text { with } \mathrm{A} x . e_{1} \mid \mathrm{B} y . e_{2} \rightarrow e_{1}[v / x]} \quad \overline{\text { match } \mathrm{B}(v) \text { with } \mathrm{A} x . e_{1} \mid \mathrm{B} y . e_{2} \rightarrow e_{2}[v / y]}
$$

$$
\frac{e_{1} \rightarrow e_{1}^{\prime}}{\left(e_{1}, e_{2}\right) \rightarrow\left(e_{1}^{\prime}, e_{2}\right)} \quad \frac{e_{2} \rightarrow e_{2}^{\prime}}{\left(v, e_{2}\right) \rightarrow\left(v, e_{2}^{\prime}\right)} \quad \frac{e \rightarrow e^{\prime}}{e .1 \rightarrow e^{\prime} .1} \quad \frac{e \rightarrow e^{\prime}}{e .2 \rightarrow e^{\prime} .2} \quad \overline{\left(v_{1}, v_{2}\right) .1 \rightarrow v_{1}} \quad \overline{\left(v_{1}, v_{2}\right) .2 \rightarrow v_{2}}
$$

## $\Gamma \vdash e: \tau$

$$
\frac{\Gamma \vdash e: \tau_{1}+\tau_{2} \quad \Gamma, x: \tau_{1} \vdash e_{1}: \tau \quad \Gamma, y: \tau_{2} \vdash e_{2}: \tau}{\Gamma \vdash \text { match } e \text { with Ax. } e_{1} \mid \mathrm{B} y . e_{2}: \tau} \quad \frac{\Gamma \vdash e: \tau_{1}}{\Gamma \vdash \mathrm{~A}(e): \tau_{1}+\tau_{2}} \quad \frac{\Gamma \vdash e: \tau_{2}}{\Gamma \vdash \mathrm{~B}(e): \tau_{1}+\tau_{2}}
$$

$$
\frac{\Gamma \vdash e_{1}: \tau_{1} \quad \Gamma \vdash e_{2}: \tau_{2}}{\Gamma \vdash\left(e_{1}, e_{2}\right): \tau_{1} * \tau_{2}} \quad \frac{\Gamma \vdash e: \tau_{1} * \tau_{2}}{\Gamma \vdash e .1: \tau_{1}} \quad \frac{\Gamma \vdash e: \tau_{1} * \tau_{2}}{\Gamma \vdash e .2: \tau_{2}}
$$

$$
\begin{aligned}
e & ::=x|\lambda x . e| e e|(e, e)| e .1|e .2| \text { letcc } x . e \mid \text { throw } e e \mid \text { cont } E \\
v & ::=\lambda x . e|(v, v)| \operatorname{cont} E \\
E & ::=[\cdot]|E e| v E|(E, e)|(v, E)|E .1| E .2 \mid \text { throw } E \text { e throw } v E
\end{aligned}
$$

$$
\begin{array}{rcc}
\frac{e{ }^{\mathrm{p}} e^{\prime}}{E[e] \rightarrow E\left[e^{\prime}\right]} & \overline{E[\text { letcc } x . e] \rightarrow E[(\lambda x . e)(\text { cont } E)]} & \overline{\left.E\left[\text { throw (cont } E^{\prime}\right) v\right] \rightarrow E^{\prime}[v]} \\
& \overline{(\lambda x . e) v \xrightarrow{\mathrm{p}} e[v / x]} & \overline{\left(v_{1}, v_{2}\right) \cdot 1 \xrightarrow{\mathrm{p}} v_{1}}
\end{array}
$$

Module Thread:
type t
val create : ('a -> 'b) -> 'a -> t
val join : t -> unit
Module Mutex:
type t
val create : unit -> t
val lock : t -> unit
val unlock : t -> unit

Futures:
type 'a promise
val future : (unit -> 'a) -> 'a promise
val force : 'a promise -> 'a
Module Event:

```
type 'a channel
type 'a event
val new_channel : unit -> 'a channel
val send : 'a channel -> 'a -> unit event
val receive : 'a channel -> 'a event
val choose : 'a event list -> 'a event
val wrap : 'a event -> ('a -> 'b) -> 'b event
val sync : 'a event -> 'a
```

Name: $\qquad$

1. ( $\mathbf{1 2}$ points) Suppose you design a new type system for Java to prevent null-pointer dereferences. However, due to poor design, your type system has the strange property that it does not accept any programs that are more than 12 lines long (it accepts some but not all shorter programs).

## Explain your answers briefly.

(a) Is it definitely the case given just the information above that your type system is sound with respect to null-pointer dereferences?
(b) Is it possible that your type system is sound with respect to null-pointer dereferences?
(c) Is it definitely the case given just the information above that your type system is complete with respect to null-pointer dereferences?
(d) Is it possible that your type system is complete with respect to null-pointer dereferences?

## Solution:

(a) No, it might accept a program less than 12 lines long that on some inputs dereferences null.
(b) Yes, soundness means the type system accepts no programs that dereference null. That might be the case for all the accepted programs.
(c) No, it is not even possible (see part (d)).
(d) No, completeness means the type system rejects no programs that definitely do not dereference null. There are an infinite number of such programs, some of which are longer than 12 lines.

Name: $\qquad$
2. ( $\mathbf{2 0}$ points) Consider a typed-lambda calculus with subtyping. Assume:

- The types are $\tau::=\operatorname{int}|\tau \rightarrow \tau|\left\{l_{1}: \tau_{1}, \ldots, l_{n}: \tau_{n}\right\}$.
- The subtyping judgment has exactly the six inference rules on page 2 of this exam.

For each of the following claims, if it is true, prove it. If it is false, provide a counterexample by giving a $\tau_{1}$ and $\tau_{2}$.
(a) If $\tau_{1} \neq \tau_{2}$ and there is a complete derivation of $\tau_{1} \leq \tau_{2}$ that has no use of the rule for function subtyping, then there is a complete derivation of $\tau_{1} \leq \tau_{2}$ that does not use the rule for reflexivity.
(b) If $\tau_{1} \neq \tau_{2}$ and there is a complete derivation of $\tau_{1} \leq \tau_{2}$ that has no use of the rule for width subtyping on records, then there is a complete derivation of $\tau_{1} \leq \tau_{2}$ that does not use the rule for reflexivity.

## Solution:

(a) True. Proof is by induction on the derivation of $\tau_{1} \leq \tau_{2}$ assuming $\tau_{1} \neq \tau_{2}$ and the derivation does not use function subtyping. Proceed by cases on the rule used in the bottommost step of the derivation:

- Reflexivity: This case holds vacuously because $\tau_{1} \neq \tau_{2}$, but the rule requires $\tau_{1}=\tau_{2}$.
- Function: This case holds vacuously because the assumed derivation does not use this rule.
- Permutation: This case holds trivially because the derivation does not use reflexivity.
- Width: This case holds trivially because the derivation does not use reflexivity.
- Depth: First notice $\tau_{1} \neq \tau_{2}$ implies $\tau_{i} \neq \tau_{i}^{\prime}$. Second notice the derivation of $\tau_{i} \leq \tau_{i}^{\prime}$ does not use function subtyping since the derivation of $\tau_{1} \leq \tau_{2}$ does not. So by induction there exists a derivation of $\tau_{i} \leq \tau_{i}^{\prime}$ that does not use reflexivity. So we can use that derivation and depth subtyping to show $\tau_{1} \leq \tau_{2}$ without using reflexivity.
- Transitivity: We know there exists a $\tau$ such that $\tau_{1} \leq \tau$ and $\tau \leq \tau_{2}$ and there are derivations of both facts that do not use function subtyping. Consider these exhaustive cases:
- If $\tau_{1}=\tau$, then $\tau_{1} \neq \tau_{2}$ ensures $\tau \neq \tau_{2}$. So by induction on the derviation of $\tau \leq \tau_{2}$, there exists a derivation of $\tau \leq \tau_{2}$ without using reflexvity. Since $\tau_{1}=\tau$, this suffices.
- If $\tau=\tau_{2}$, then $\tau_{1} \neq \tau_{2}$ ensures $\tau_{1} \neq \tau$. So by induction on the derviation of $\tau_{1} \leq \tau$, there exists a derivation of $\tau_{1} \leq \tau$ without using reflexvity. Since $\tau=\tau_{2}$, this suffices.
- If $\tau_{1} \neq \tau$ and $\tau \neq \tau_{2}$, then by induction (twice) on the derivations of $\tau_{1} \leq \tau$ and $\tau \leq \tau_{2}$, there exist derivations of $\tau_{1} \leq \tau$ and $\tau \leq \tau_{2}$ without using reflexivity. We can use these derivations and transitivity to derive $\tau_{1} \leq \tau_{2}$ without using reflexivity.
(b) False. Let $\tau_{1}=$ int $\rightarrow\left\{l_{1}:\right.$ int, $l_{2}:$ int $\}$ and $\tau_{2}=$ int $\rightarrow\left\{l_{2}:\right.$ int, $l_{1}:$ int $\}$.

Additional unnecessary explanation: Note $\tau_{1} \neq \tau_{2}$ and we can derive $\tau_{1} \leq \tau_{2}$ as follows:

$$
\begin{aligned}
& \overline{\text { int } \leq \text { int }} \quad \overline{\left\{l_{1}: \text { int }, l_{2}: \text { int }\right\} \leq\left\{l_{2}: \text { int }, l_{1}: \text { int }\right\}} \\
& \hline \text { int } \rightarrow\left\{l_{1}: \text { int }, l_{2}: \text { int }\right\} \leq \text { int } \rightarrow\left\{l_{2}: \text { int }, l_{1}: \text { int }\right\}
\end{aligned}
$$

This derivation does not use width subtyping. Any derivation of $\tau_{1} \leq \tau_{2}$ must show at some point int $\leq$ int and doing so requires reflexivity at some point.

Name: $\qquad$
3. ( $\mathbf{1 3}$ points) This problem considers System F (extended with constants, addition, and multiplication).
(a) Consider the type $\forall \alpha_{1} . \forall \alpha_{2} . \forall \alpha_{3} .\left(\alpha_{1} \rightarrow \alpha_{2}\right) \rightarrow\left(\alpha_{2} \rightarrow \alpha_{3}\right) \rightarrow \alpha_{1} \rightarrow \alpha_{3}$.
i. Give a (closed) term with this type.
ii. Letting $e_{1}$ be your answer to part (i), what does $e_{1}[$ int $][$ int $][$ int $](\lambda x:$ int. $x+1)(\lambda x$ :int. $x * 2) 17$ evaluate to?
iii. Is there a term $e_{2}$ with this type that is not equivalent to your answer to part (i)? If so, give such a term and what $e_{2}$ [int] [int] [int] $(\lambda x:$ int. $x+1)(\lambda x:$ int. $x * 2) 17$ evaluates to. If not, explain briefly.
(b) Consider the type $\forall \alpha_{1} \cdot \forall \alpha_{2} \cdot\left(\alpha_{1} \rightarrow \alpha_{1}\right) \rightarrow\left(\alpha_{1} \rightarrow \alpha_{2}\right) \rightarrow \alpha_{1} \rightarrow \alpha_{2}$.
i. Give a (closed) term with this type.
ii. Letting $e_{1}$ be your answer to part (i), what does $e_{1}$ [int] [int] ( $\lambda x:$ int. $x+1$ ) ( $\lambda x$ :int. $x * 2$ ) 17 evaluate to?
iii. Is there a term $e_{2}$ with this type that is not equivalent to your answer to part (i)? If so, give such a term and what $e_{2}$ [int] [int] $(\lambda x:$ int. $x+1)(\lambda x$ :int. $x * 2) 17$ evaluates to. If not, explain briefly.

## Solution:

(a) i. $\Lambda \alpha_{1} \cdot \Lambda \alpha_{2} \cdot \Lambda \alpha_{3} . \lambda f: \alpha_{1} \rightarrow \alpha_{2} . \lambda g: \alpha_{2} \rightarrow \alpha_{3} . \lambda x: \alpha_{1} . g(f x)$
ii. 36
iii. No, due to parametricity, the only terms with this type are equivalent to computing $g(f(x))$ - there are no side-effects and no other way to convert an $\alpha_{1}$ to an $\alpha_{3}$.
(b) i. $\Lambda \alpha_{1} \cdot \Lambda \alpha_{2} \cdot \lambda f: \alpha_{1} \rightarrow \alpha_{1} \cdot \lambda g: \alpha_{1} \rightarrow \alpha_{2} . \lambda x: \alpha_{1} . g(f x)$
ii. 36
iii. Yes, consider $\Lambda \alpha_{1} . \Lambda \alpha_{2} . \lambda f: \alpha_{1} \rightarrow \alpha_{1} . \lambda g: \alpha_{1} \rightarrow \alpha_{2} . \lambda x: \alpha_{1} . g(f(f x))$ which produces 38. Another example is $\Lambda \alpha_{1} . \Lambda \alpha_{2} . \lambda f: \alpha_{1} \rightarrow \alpha_{1} . \lambda g: \alpha_{1} \rightarrow \alpha_{2} . \lambda x: \alpha_{1} . g x$ which produces 34.

Name: $\qquad$
4. ( $\mathbf{1 6}$ points) Consider this Caml code, which purposely uses unillimunating names. Assume max3 is a provided library function that returns the maximum of three int arguments:

```
type t1 = A of int | B of int * t1 * t1
type t2 = C of string | D of string * t2 * t2
type t3 = E of t1 | F of t2
let foo x =
    match x with
        E e ->
            let rec f y =
                match y with
                                A z -> z
                                | B(z,a,b) -> max3 z (f a) (f b)
            in f e
        | F _ -> 505
```

(a) t3 describes a simple if slightly unusual data structure. Describe the data structure in 1-2 English sentences.
(b) Give the type of foo and the type of the helper function $f$.
(c) Describe what foo computes in 1-2 English sentences.
(d) Write a Caml function bar that (1) is equivalent to foo (same type and behavior) and (2) never uses more than a small, constant amount of call-stack space when executed.
(e) Your solution to part (d) needed a recursive helper function. What type does this helper function have?

## Solution:

(a) A data structure of type t 3 holds either a binary tree of ints (with ints at leaves and interior nodes) or a binary tree of strings (with strings at leaves and interior nodes)
(b) foo has type t3->int and $f$ has type t1->int.
(c) Given a t3, foo returns the largest int in the tree or 505 if the tree has no ints.
(d) The hoped-for solution uses continuation-passing style, but an explicit work-stack also satisfies the constraints of the problem:

```
let bar x =
    match x with
        E e ->
            let rec f y k =
                match y with
                    A z -> k z
                    | B(z,a,b) -> f a (fun i >> f b (fun j >> k (max3 z i j)))
            in f e (fun x -> x)
        | F _ -> 505
let bar x = (* uses a 2-argument max *)
    match x with
        E (B(z,a,b)) ->
```

```
        let rec f m stk =
            match stk with
                [] -> m
            | (A z)::tl -> f (max m z) tl
            | (B(z,a,b))::tl -> f (max m z) (a::b::tl)
        in f z [a;b]
| E (A z) -> z
| F _ -> 505
```

(e) For the hoped-for solution: $f$ has type t1 -> (int -> 'a) -> 'a. For the explicit work-stack solution: f has type int $->$ t1 list -> int.

Name: $\qquad$
5. ( $\mathbf{1 6}$ points) In this problem, you are given an implementation of a functional queue and you will use Concurrent ML to implement an imperative queue. Your solution should not use any mutable features (e.g., references). Assume the functional queue given to you has this interface:

```
type 'a queue
val empty_queue : 'a queue (* create a queue *)
val is_empty : 'a queue -> bool (* return true iff queue is empty *)
val enqueue : 'a queue -> 'a -> 'a queue (* add 'a to queue; return result *)
val peek : 'a queue -> 'a (* return element that was added to the queue the longest ago;
    raises an exception if the queue is empty *)
val drop: 'a queue -> 'a queue (* result is like the argument but the element first added
is no longer in the queue;
raises an exception if the queue is empty *)
```

The queue you will implement will differ in that (1) it is imperative (a queue has state and enqueuing and dequeing update this state), (2) it supports only enqueue and dequeue operations, and (3) it never raises an exception; instead dequeue operations should block as necessary to wait for another thread to perform an enqueue. Also note you must use the type definition of 'a mqueue given below. Provide definitions for new_mqueue, $m_{-}$enqueue, and $m_{-}$dequeue:

```
type 'a mqueue = 'a channel * 'a channel
val new_mqueue : unit -> 'a mqueue
val m_enqueue : 'a mqueue -> 'a -> unit
val m_dequeue : 'a mqueue -> 'a
```


## Solution:

```
open Event
let new_mqueue () =
    let enq_ch = new_channel() in
    let deq_ch = new_channel() in
    let rec loop q =
        if is_empty q
        then loop (enqueue q (sync (receive enq_ch)))
        else sync (choose [
                wrap (receive enq_ch) (fun v -> loop (enqueue q v));
                wrap (send deq_ch (peek q)) (fun () -> loop (drop q)) ])
    in
    let _ = Thread.create loop empty_queue in
    (enq_ch,deq_ch)
let m_enqueue (e,_) v = sync (send e v)
let m_dequeue (_,d) = sync (receive d)
```

Name: $\qquad$
6. (13 points) Assume a class-based OOP language like we discussed in class, with single inheritance and types (and subtypes) that correspond to classes (and subclasses). Assume assert raises an exception if its argument evaluates to false. Assume there are no threads. Consider this code:

```
class A {
    int x;
}
class B extends A {
    void m() { x = 7; }
}
class C extends B {
    void m() { x = 4; }
    void f() {
        m();
        assert(x==4); // (*)
    }
}
```

(a) Is it possible to make (only) a change to class B such that class B still type-checks but class C no longer type-checks? If so, explain how and if not, explain why not.
(b) Is it possible to make (only) a change to class B such that class B and class C type-check but there are programs where the assertion at the line marked (*) raises an exception? If so, explain how and if not, explain why not.
(c) Is it possible to create (only) a subclass D that extends class C such that class D type-checks but class C no longer type-checks? If so, explain how and if not, explain why not.
(d) Is it possible to create (only) a subclass $D$ that extends class $C$ such that class $C$ and class $D$ type-check but there are programs where the assertion at the line marked (*) raises an exception? If so, explain how and if not, explain why not.

## Solution:

(a) Yes, assuming using the same method name means overriding, then changing class B to have $m$ take an argument would suffice. With static overloeading like in Java or C++, we instead need to change the return type to something other than void, such as int.
(b) No, no change in class B can affect how $f()$ executes because late-binding of $m$ will always resolve the call to the method defined in class C or some subclass, so without creating a subclass, x will be 4 and the assertion will succeed.
(c) No, type-checking any class depends only on the definition of that class and any superclasses.
(d) Yes, we can override $m$ to set $x$ to a value other than 4 . With late-binding, the call to $f$ on an instance of $D$ will then execute the new $m$ and then the old assertion, which will fail.

Name: $\qquad$
7. ( $\mathbf{1 0}$ points) This problem considers static overloading and multimethods. Consider this code skeleton:

```
class A {}
class B extends A {}
class C extends B {}
class D {
    void m(B x, A y) { } // 1
    void m(A x, B y) { } // 2
    void m(A x, A y) { } // 3
    void main() {
    }
}
```

Replace the ... with a few lines of code such that:

- If the language uses static overloading, then each of the three m methods is called exactly once. Indicate which line of code calls which method.
- If the language uses multimethods, then every method call is ambiguous because there is "no best match" (where we assume the "goodness" of a match is the number of subsumptions to immediate supertypes and fewer is better). Indicate for each call, which methods are tied for the best match.

Note the same code should satisfy both these requirements.

## Solution:

One possible answser is below; note it also works to bind both o1 and o2 to instances of B.

```
B o1 = new C();
A o2 = new C();
m(o1,o2); // (static: 1, multi: 1 and 2)
m(o2,o1); // (static: 2, multi: 1 and 2)
m(o2,o2); // (static: 3, multi: 1 and 2)
```


[^0]:    $e::=c|x| \lambda x: \tau . e|e e| \Lambda \alpha . e \mid e[\tau]$
    $\tau::=$ int $|\tau \rightarrow \tau| \alpha \mid \forall \alpha . \tau$
    $v::=c|\lambda x: \tau . e| \Lambda \alpha . e$
    $\Gamma::=\quad \mid \Gamma, x: \tau$
    $\Delta::=\cdot \mid \Delta, \alpha$
    $e \rightarrow e^{\prime}$

    $$
    \frac{e_{1} \rightarrow e_{1}^{\prime}}{e_{1} e_{2} \rightarrow e_{1}^{\prime} e_{2}} \quad \frac{e_{2} \rightarrow e_{2}^{\prime}}{v e_{2} \rightarrow v e_{2}^{\prime}} \quad \frac{e \rightarrow e^{\prime}}{e[\tau] \rightarrow e^{\prime}[\tau]} \quad \overline{(\lambda x: \tau . e) v \rightarrow e[v / x]} \quad \overline{(\Lambda \alpha . e)[\tau] \rightarrow e[\tau / \alpha]}
    $$

    $\Delta ; \Gamma \vdash e: \tau$

    $$
    \begin{gathered}
    \overline{\Delta ; \Gamma \vdash x: \Gamma(x)} \frac{\Delta ; \Gamma \vdash c: \text { int }}{\Delta ; \Gamma} \frac{\Delta ; \Gamma, x: \tau_{1} \vdash e: \tau_{2}}{\Delta ; \Gamma \vdash \lambda x: \tau_{1} \cdot e: \tau_{1} \rightarrow \tau_{2}} \quad \frac{\Delta \vdash \tau_{1}}{\Delta ; \Gamma \vdash \Lambda \alpha \cdot e: \forall \alpha \cdot \tau_{1}} \\
    \frac{\Delta ; \Gamma \vdash e_{1}: \tau_{2} \rightarrow \tau_{1} \quad \Delta ; \Gamma \vdash e_{2}: \tau_{2}}{\Delta ; \Gamma \vdash e_{1} e_{2}: \tau_{1}}
    \end{gathered}
    $$

