

Chapter 5.

the reason above problem has low sample complexity for PAC learning is that we had a prior knowledge $\left\{ \begin{array}{l} \text{ground truth } D \text{ has a circular decision boundary} \\ H \text{ is collection of circular decision boundaries} \end{array} \right.$

Q. is such prior knowledge necessary? yes.

Learning Problem, X, Y fixed

NATURE

D

S

LEARNER

H, Algo

Goal

$L_D(h)$

h

Q. Can there be a universal algorithm Algo

that is PAC learnable for all problem instances D ?

Q. is prior knowledge necessary for PAC learning?

should we use Agnostic PAC, otherwise.

How much prior knowledge is good to assume?

a lot

- Learner knows $D, h^* \rightarrow H = \{h^*\}$ achieves minimum Risk
e.g. Bayes Optimal

- Learner knows a class $\rightarrow$ PAC learnable $m \approx \frac{\log |H|}{\epsilon}$

- Lecture 2: realizable finite $H \rightarrow$ PAC learnable $m \approx \frac{\log |H|}{\epsilon}$

- Lecture 3: e.g. $H = \{h_v: I_{\{v\}}(x) \in \{0,1\}\}$ $\rightarrow$ PAC learnable $m \approx \frac{\log |H|}{\epsilon}$

- Learner knows nothing: no-free-lunch Theorem.

No-free-lunch theorem

Theorem. Let Algo be any learning algorithm. $Y = \{0,1\}$, any X , $m \leq \frac{|X|}{2}$

Then exists a distribution D over $X \times Y$ s.t.

1. $\exists f: X \rightarrow \{0,1\}$ with $L_D(f) = 0$

2. $P_S (L_D(\text{Algo}(S)) \geq \frac{1}{8}) \geq \frac{1}{4}$

Constructive Proof

Negative Result.

proof sketch: $|X| \geq 2m$, $C \subseteq X$, and $|C| = 2m$, and we observe random S of m samples.

$|H| = 2^{2m}$ all possible ^{ways to} label.
 $= \{h_0, h_1, \dots, h_{2^{2m}-1}\}$

for any Algo , $\exists D$ s.t. one cannot do better than random guess on $\frac{1}{2}$ of the samples not observed.

$\mathbb{E}_S [L_D(\text{Algo}(S))] \geq \frac{1}{4} \rightarrow$ claim by ^{light} Markov's inequality.
 $\underbrace{\mathbb{E}_S [L_D(\text{Algo}(S))]}_{\text{positive R.V.}} \geq \frac{1}{4} \rightarrow \frac{1}{2} \text{ of samples error } \frac{1}{2}.$

Corollary. X is infinite & H is all possible functions from X to $\{0,1\}$ then H is not PAC learnable.

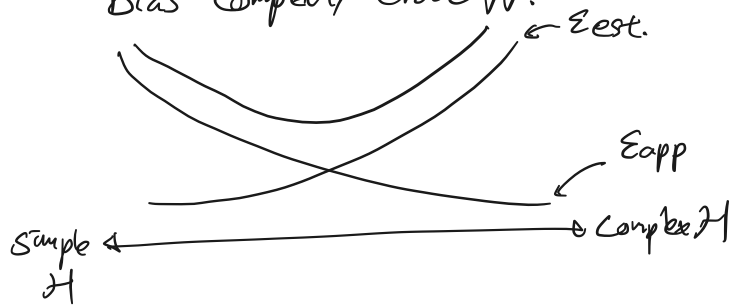
Q. How do we choose the right hypothesis class?

$$L_D(h_S) = \underbrace{(L_D(h_S) - \min_{h' \in H} L_D(h'))}_{\epsilon_{\text{est}} = \text{Estimation error}} + \underbrace{\min_{h' \in H} L_D(h')}_{\epsilon_{\text{app}} = \text{approximation}}$$

ERM

- goes down with m
- depends on complexity H
- error
- does not depend on m
- property of D, H , complex

Bias-Complexity Tradeoff.



chapter 6.

realizable + finite $H \rightarrow$ PAC learnable (lec 2)

finite $H \rightarrow$ Agnostic PAC learnable (lec 3).

realizable + infinite $H = \{h_r: \mathbb{I}(1/2 \leq r) \} \rightarrow$ PAC learnable (lec 4)

$C \subset \mathcal{X}, |C| \geq 2^m, H$ contains all possible 2^m labels $\rightarrow$ no learning (lec 4)

Q. What class H is PAC learnable? Vladimir Vapnik & Alexey 1970
Chervonenkis

Definition. (Restriction of H to C)

H is class of functions $\mathcal{X} \rightarrow \{0, 1\}$, and $C = \{c_1, \dots, c_m\} \subseteq \mathcal{X}$,
the Restriction of H to C

$$H_C \triangleq \{ \tilde{h}: C \rightarrow \{0, 1\} \mid h \in H \}$$

$$c_i \mapsto h(c_i)$$

equivalently we can represent $\tilde{h}$ by a vector $(h(c_1), \dots, h(c_m))$.

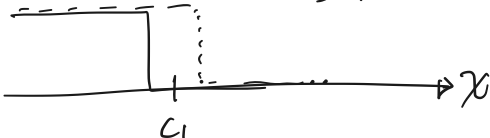
Definition. (Shattering)

A hypothesis class H shatters a set $C \subseteq \mathcal{X}$ if
the restriction of H to C is the set of all
functions from C to $\{0, 1\}$. That is $|H_C| = 2^{|C|}$.

Example. $H = \{h_a: \mathbb{R} \rightarrow \mathbb{R} = \mathbb{I}(x \leq a)\}$ class of all threshold functions.

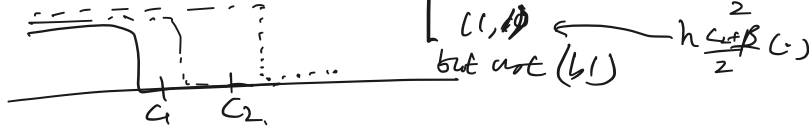
① $C = \{c_1\}$

$$H_C = \begin{cases} (h(c_1)=1) \\ (h(c_1)=0) \end{cases} \leftarrow \begin{matrix} h_{c_1+\beta} \\ h_{c_1-\beta} \end{matrix}$$



$\therefore H$ shatters $C = \{c_1\}$

② $C = \{c_1, c_2\}, H_C = \begin{cases} (0, 0) \\ (1, 0) \end{cases} \leftarrow \begin{matrix} h_{c_1-\beta}(\cdot) \\ h_{c_1+c_2}(\cdot) \end{matrix}$



° H does not shatter $C = \{c_1, c_2\}$

Corollary (No-free-search theorem restated)

for some $\mathcal{H}$, $\mathcal{X}$, $\mathcal{Y} = \{0, 1\}$, if $\exists C \subseteq \mathcal{X}$, $|C| = 2m$, & shattered by $\mathcal{H}$,

then for any learning algorithm, $\exists D$ & $h \in \mathcal{H}$ st.

$$L_D(h) = 0 \text{ but } \mathbb{P}(L_D(A(S)) \geq \frac{1}{8}) \leq \frac{1}{7}.$$

Definition (VC-dimension)

The VC-dimension of $\mathcal{H}$, $\triangleq \text{VCdim}(\mathcal{H})$,

is the maximal size of $C \subseteq \mathcal{X}$ that can be shattered by $\mathcal{H}$.

→ NO set of size $|C|+1$ can be shattered.

Example need to show that $\exists C$ of $|C|=d$ shattered

& $\forall C$ of $|C|=d+1$, not shattered.

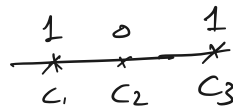
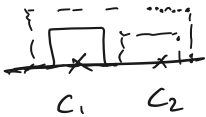
Example (Threshold: $\mathcal{H} = \{ \mathbb{I}_{(-\infty, a]} : a \in \mathbb{R} \}$)

$\exists C = \{c_1\}$ can be shattered.

all $C = \{c_1, c_2\}$ can not be shattered.

$$\text{VCdim}(\mathcal{H}) = 1.$$

Example (Intervals: $\mathcal{H} = \{ \mathbb{I}_{(a, b)} : a, b \in \mathbb{R} \}$)

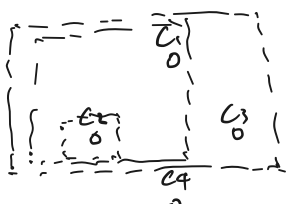


$$\text{VCdim}(\mathcal{H}) = 2.$$

existence of shattered set all set not shattered.

Example (axis aligned rectangles: $\mathcal{H} = \{ \mathbb{I}_{(a_1 \leq x_1 \leq b_1, a_2 \leq x_2 \leq b_2)} : a_1 \leq b_1, a_2 \leq b_2 \}$)

$$\text{VCdim}(\mathcal{H}) = 4$$



existence of shattered set.

all set of 5 not shattered.

Example (finite classes: $|\mathcal{H}| < \infty$)

shattering requires at least $2^{|C|}$ hypothesis. so

$$2^{|K|} \leq |\mathcal{H}|$$

$$\rightarrow |K| \leq \log_2 |\mathcal{H}|$$

$$\rightarrow \text{VCdim} \leq \log_2 |\mathcal{H}|$$

→ tight in the worst case

→ VCdim can be much smaller.

e.g. finite & threshold.

Example (number of parameters).

above examples have # parameters match VCdim,

Not always true: $\mathcal{H} = \{h_\theta : \theta \in \mathbb{R}\}$, $\text{VCdim}(\mathcal{H}) = \infty$ [HW1 Problem 4]

$$\parallel$$

$$\lceil \cos \sin(\theta x) \rceil$$