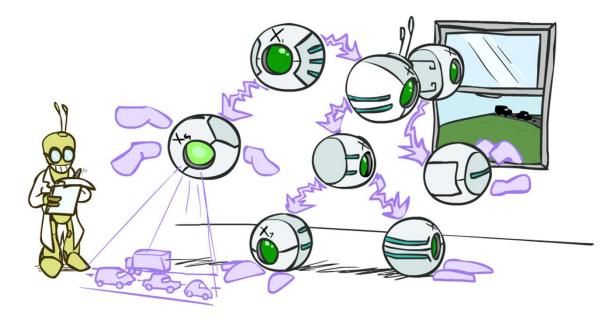
#### CSE 473: Artificial Intelligence

#### Bayes' Nets: Inference



Steve Tanimoto

[These slides were created by Dan Klein and Pieter Abbeel for CS188 Intro to AI at UC Berkeley. All CS188 materials are available at http://ai.berkeley.edu.]

#### Inference

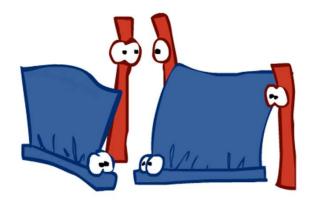
 Inference: calculating some useful quantity from a joint probability distribution

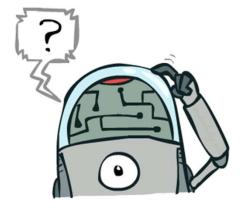
- Examples:
  - Posterior probability

 $P(Q|E_1 = e_1, \dots E_k = e_k)$ 

Most likely explanation:

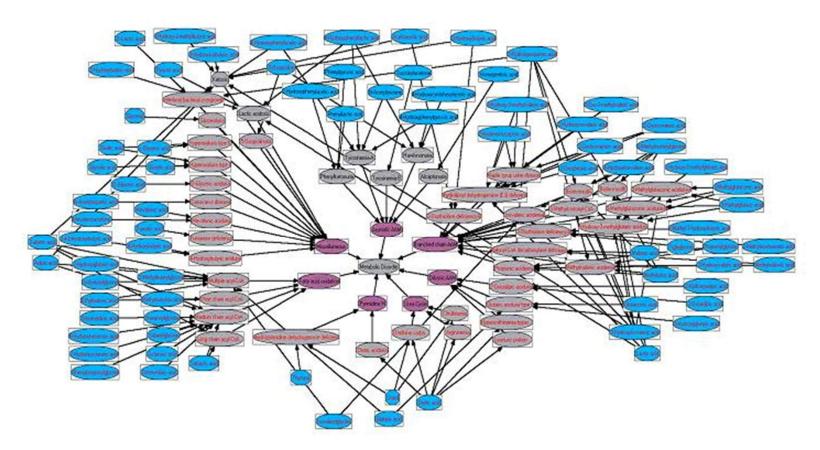
 $\operatorname{argmax}_q P(Q = q | E_1 = e_1 \dots)$ 





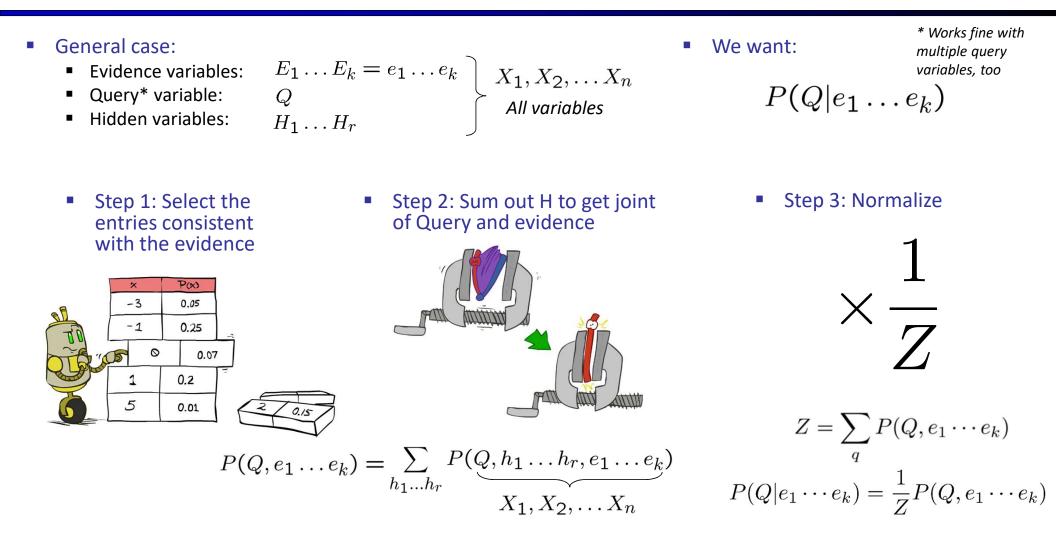


#### Test for Infant Metabolic Defects



Blue ovals represent chromatographic peaks, grey ovals represent 20 metabolic diseases

#### Inference by Enumeration



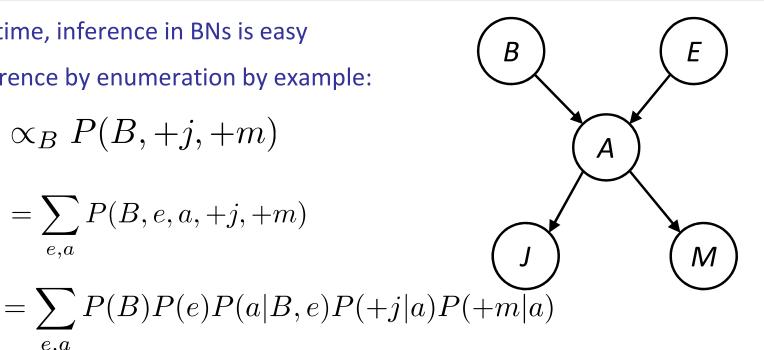
#### Inference by Enumeration in Bayes' Net

- Given unlimited time, inference in BNs is easy
- Reminder of inference by enumeration by example:

 $P(B \mid +j,+m) \propto_B P(B,+j,+m)$ 

e.a

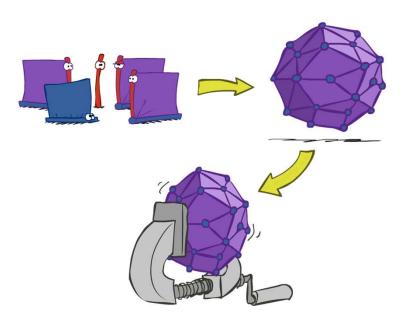
$$=\sum_{e,a} P(B,e,a,+j,+m)$$



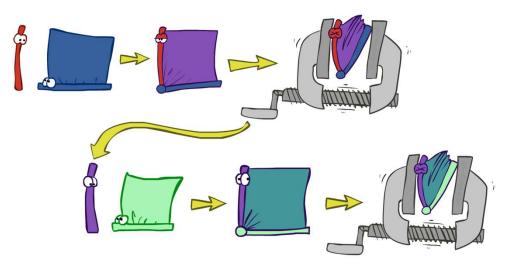
= P(B)P(+e)P(+a|B,+e)P(+j|+a)P(+m|+a) + P(B)P(+e)P(-a|B,+e)P(+j|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)P(+m|-a)PP(B)P(-e)P(+a|B,-e)P(+j|+a)P(+m|+a) + P(B)P(-e)P(-a|B,-e)P(+j|-a)P(+m|-a)P(+m|-a)P(-a|B,-e)P(+j|-a)P(+m|-a)P(-a|B,-e)P(+j|-a)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e)P(-a|B,-e

## Inference by Enumeration vs. Variable Elimination

- Why is inference by enumeration so slow?
  - You join up the whole joint distribution before you sum out the hidden variables

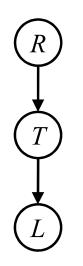


- Idea: interleave joining and marginalizing!
  - Called "Variable Elimination"
  - Still NP-hard, but usually much faster than inference by enumeration

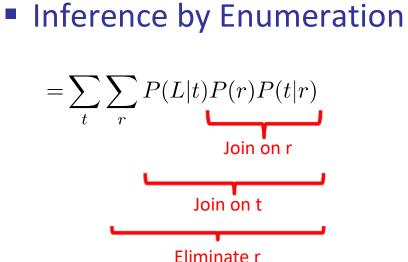


First we'll need some new notation: factors

#### **Traffic Domain**



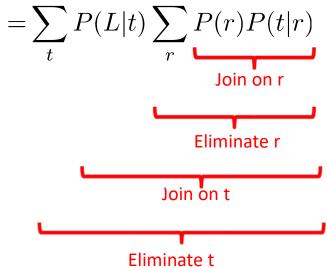
$$P(L) = ?$$



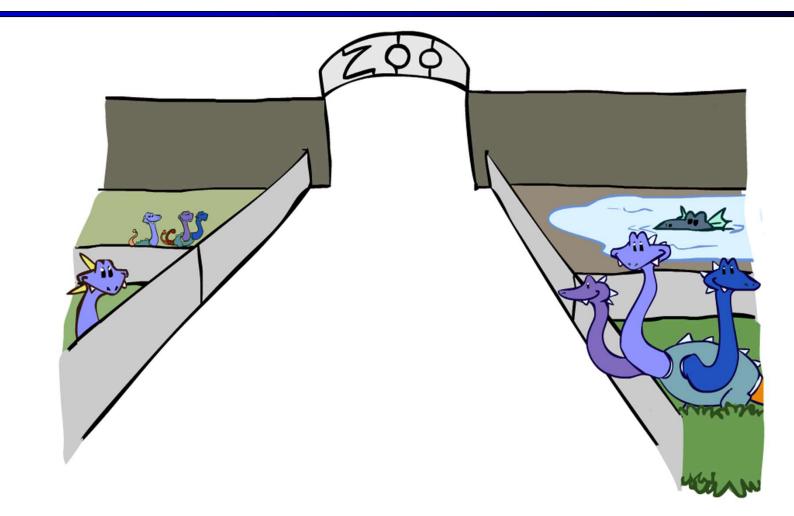
Eliminate r

Eliminate t

Variable Elimination



#### Factor Zoo



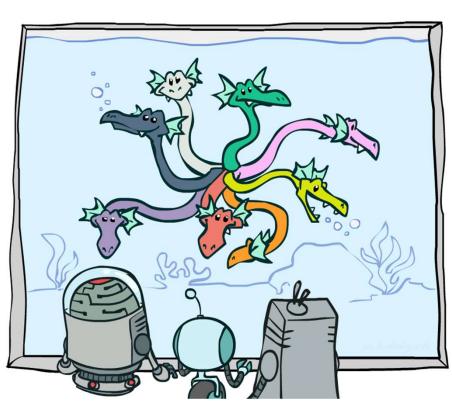
## Factor Zoo I

- Joint distribution: P(X,Y)
  - Entries P(x,y) for all x, y
  - Sums to 1

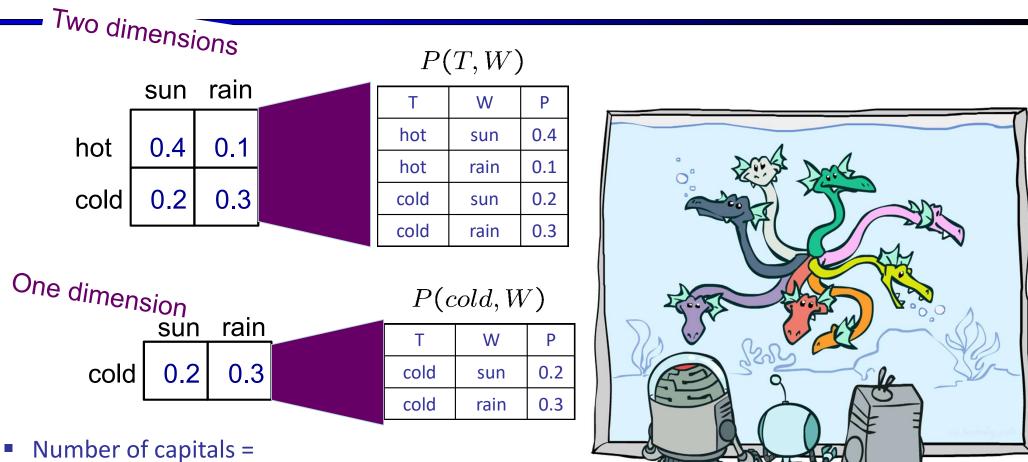
- Selected joint: P(x,Y)
  - A slice of the joint distribution
  - Entries P(x,y) for fixed x, all y
  - Sums to P(x)
- Number of capitals = dimensionality of the table

P(	(T, W)	)
Т	W	Р
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

P(c	$\mathcal{P}(cold, W)$	
Т	W	Ρ
cold	sun	0.2
cold	rain	0.3



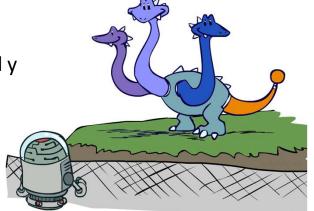
### Factor Zoo I



dimensionality of the table

## Factor Zoo II

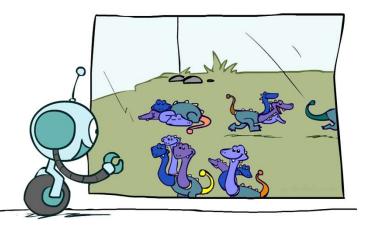
- Single conditional: P(Y | x)
  - Entries P(y | x) for fixed x, all y
  - Sums to 1



P(W	cold

Т	W	Р
cold	sun	0.4
cold	rain	0.6

- Family of conditionals: P(X | Y)
  - Multiple conditionals
  - Entries P(x | y) for all x, y
  - Sums to |Y|



$\boldsymbol{P}$	(W	$ T\rangle$
Γ		

Т	W	Р
hot	sun	0.8
hot	rain	0.2
cold	sun	0.4
cold	rain	0.6

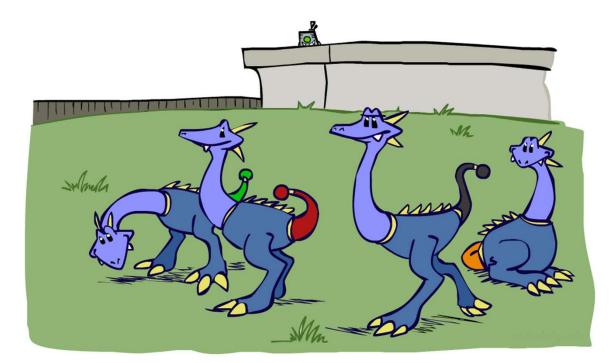
P(W|hot)P(W|cold)

#### Factor Zoo III

- Specified family: P( y | X )
  - Entries P(y | x) for fixed y, but for all x
  - Sums to ... who knows!

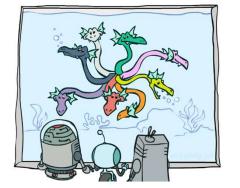
P(rain|T)

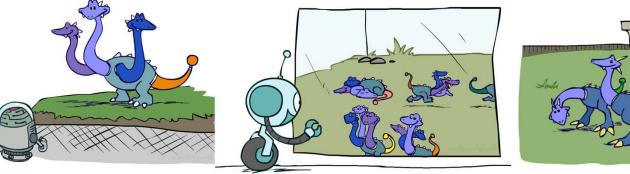
Т	W	Р	
hot	rain	0.2	P(rain hot)
cold	rain	0.6	$\left  \frac{1}{2} P(rain cold) \right $

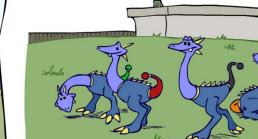


#### Factor Zoo Summary

- In general, when we write  $P(Y_1 ... Y_N | X_1 ... X_M)$ 
  - It is a "factor," a multi-dimensional array
  - Its values are P(y<sub>1</sub> ... y<sub>N</sub> | x<sub>1</sub> ... x<sub>M</sub>)
  - Any assigned (=lower-case) X or Y is a dimension missing (selected) from the array

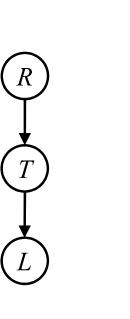






#### **Example: Traffic Domain**

# Random Variables R: Raining T: Traffic L: Late for class! P(L) = ? $= \sum_{r,t} P(r,t,L)$ $= \sum_{r,t} P(r)P(t|r)P(L|t)$



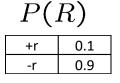
P(R)	
+r	0.1
-r	0.9

<i>P</i> (	T R	)
+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

+t	+	0.3
+t	-	0.7
-t	+	0.1
-t	-	0.9

## Inference by Enumeration: Procedural Outline

- Track objects called factors
- Initial factors are local CPTs (one per node)

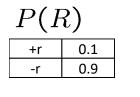


P(T R)		
+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	_t	ΛQ

P(L I)			
	+t	+	0.3
	+t	-	0.7
	-t	+	0.1
	-t	-	0.9

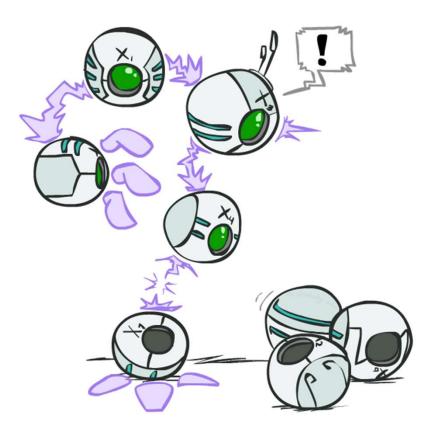
D(T|T)

- Any known values are selected
  - E.g. if we know  $L = +\ell$ , the initial factors are



P(T R)			
+r	+t	0.8	
+r	-t	0.2	
-r	+t	0.1	
-r	-t	0.9	

$P(+\ell T)$		
+t	+	0.3
-t	+	0.1



Procedure: Join all factors, then eliminate all hidden variables

### **Operation 1: Join Factors**

- First basic operation: joining factors
- **Combining factors:** 
  - Just like a database join
  - Get all factors over the joining variable
  - Build a new factor over the union of the variables involved

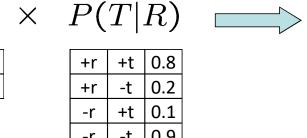


R

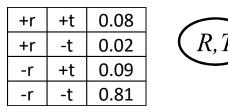
T

P(R)0.1 +r 0.9 -r

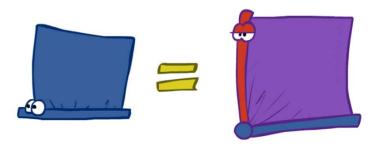
+t 0.8 +r 0.2 -t | +r +t | 0.1 -r -t | 0.9 -r



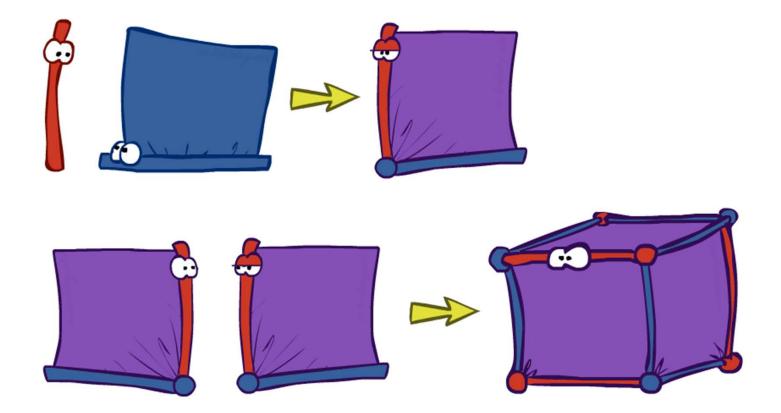
P(R,T)

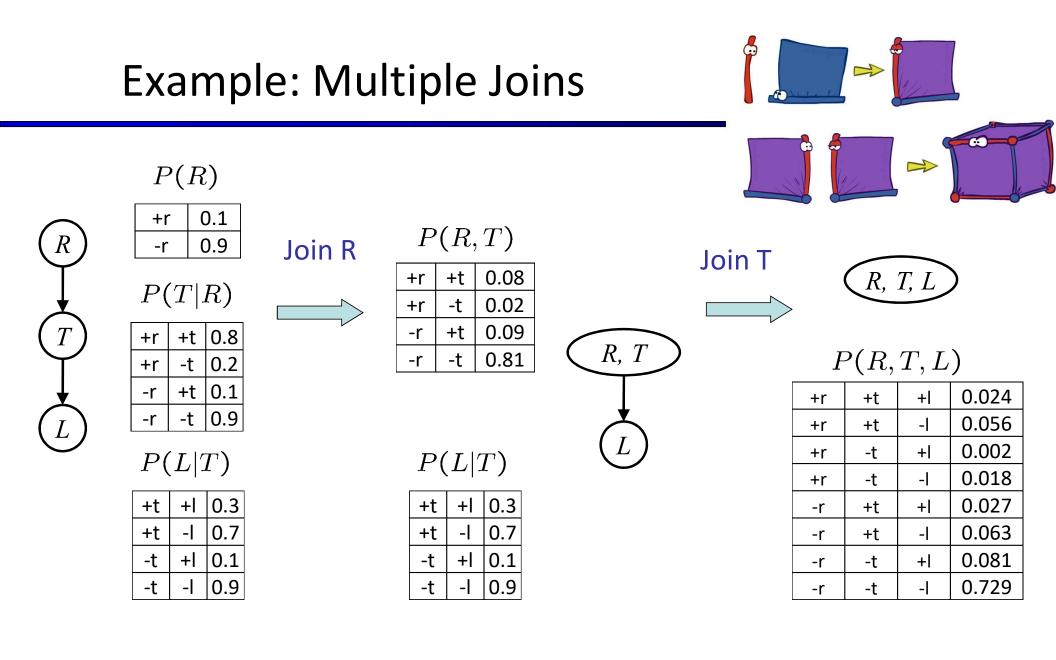


• Computation for each entry: pointwise products  $\forall r, t : P(r, t) = P(r) \cdot P(t|r)$ 

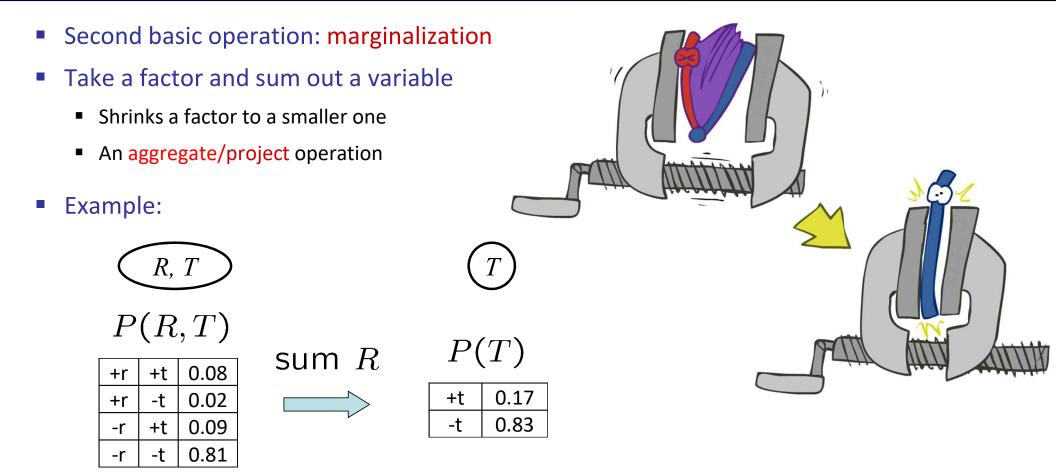


## Example: Multiple Joins

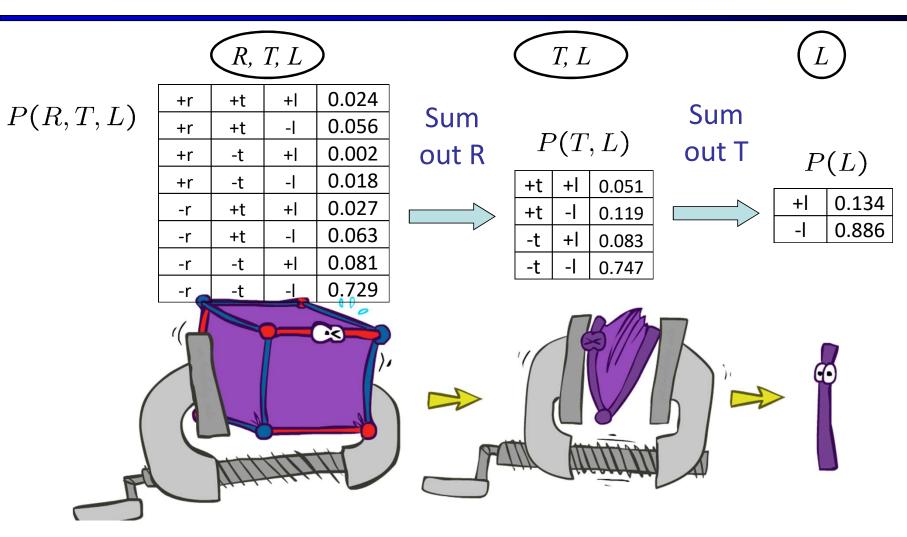




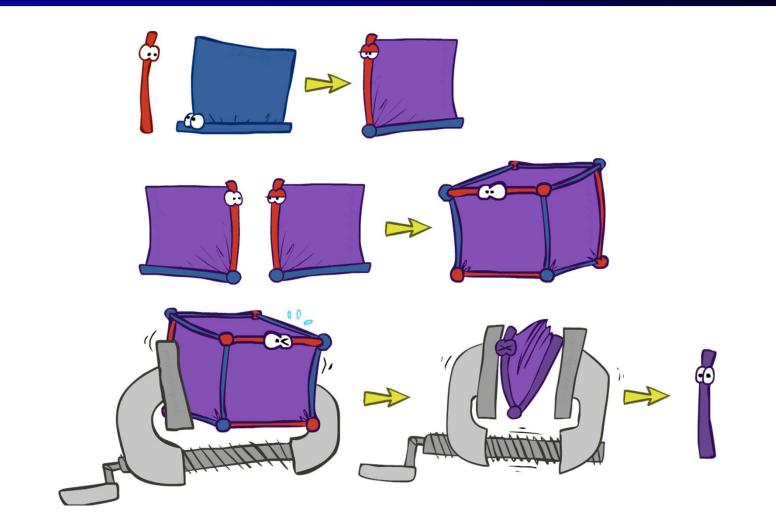
## **Operation 2: Eliminate**



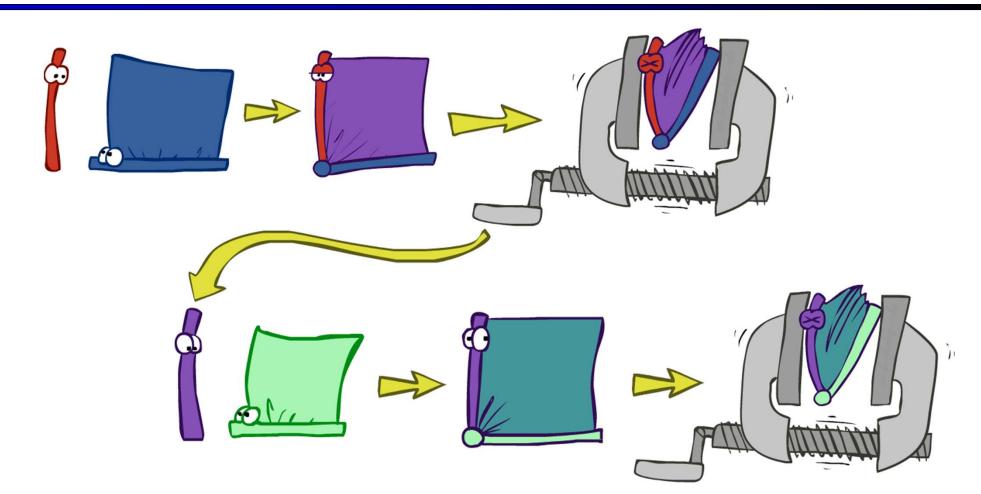
#### **Multiple Elimination**



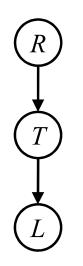
#### Thus Far: Multiple Join, Multiple Eliminate (= Inference by Enumeration)



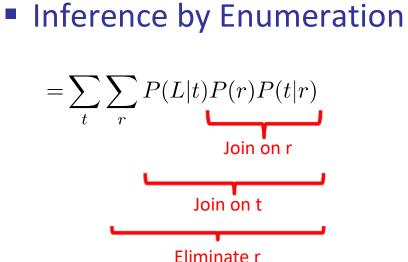
## Marginalizing Early (= Variable Elimination)



#### **Traffic Domain**



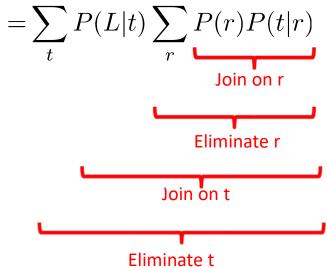
$$P(L) = ?$$



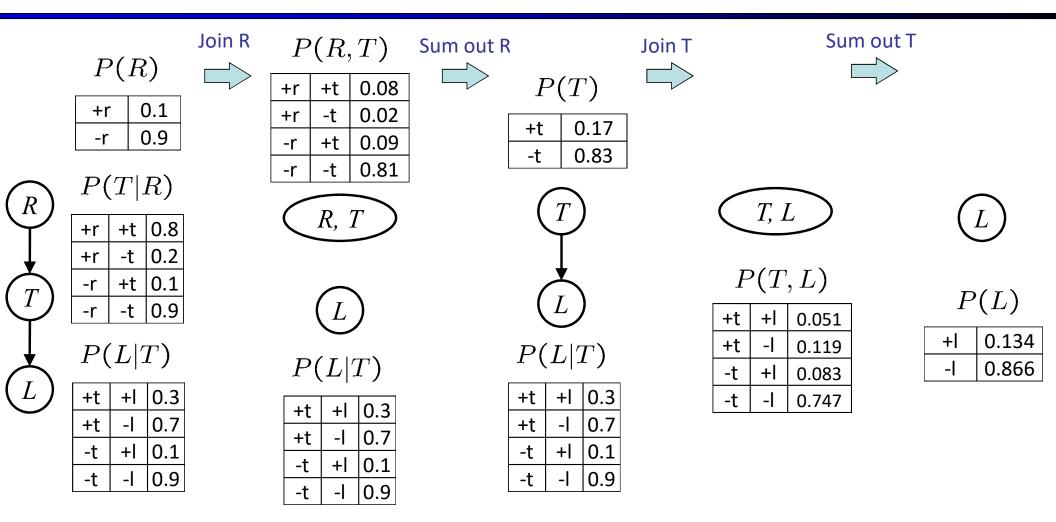
Eliminate r

Eliminate t

Variable Elimination



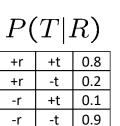
#### Marginalizing Early! (aka VE)



#### Evidence

- If evidence, start with factors that select that evidence
  - If there is no evidence, then use these initial factors:

P(R)		
+r	0.1	
-r	0.9	



P(L T)			
	+t	+	0.3
	+t	-	0.7
	-t	+	0.1
	-t	-	0.9

- But if given some evidence, eg +r, then select for it...
- Computing P(L| + r) the initial factors become:

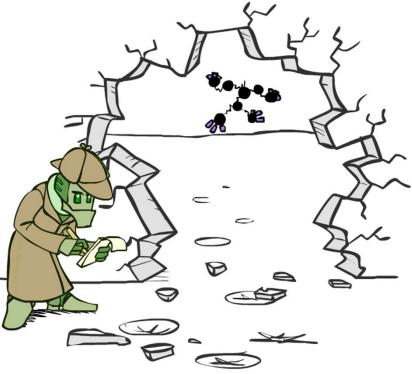
+t -t

+r)

0.8

P(T
+r
+r

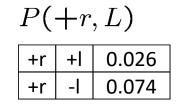
P(L T)			
+t	+	0.3	
+t	-	0.7	
-t	+	0.1	
-t	-	0.9	

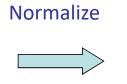


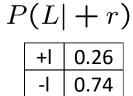
Next do joins & eliminate, removing all vars other than query + evidence

#### **Evidence II**

- Result will be a selected joint of query and evidence
  - E.g. for P(L | +r), we would end up with:







- To get our answer, just normalize this!
- That 's it!

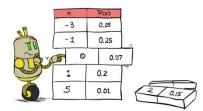


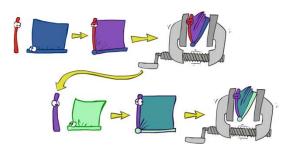
#### **General Variable Elimination**

• Query: 
$$P(Q|E_1 = e_1, \dots E_k = e_k)$$

- Start with initial factors:
  - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
  - Choose a hidden variable H
  - Join all factors mentioning H
  - Eliminate (sum out) H

#### Join all remaining factors and normalize

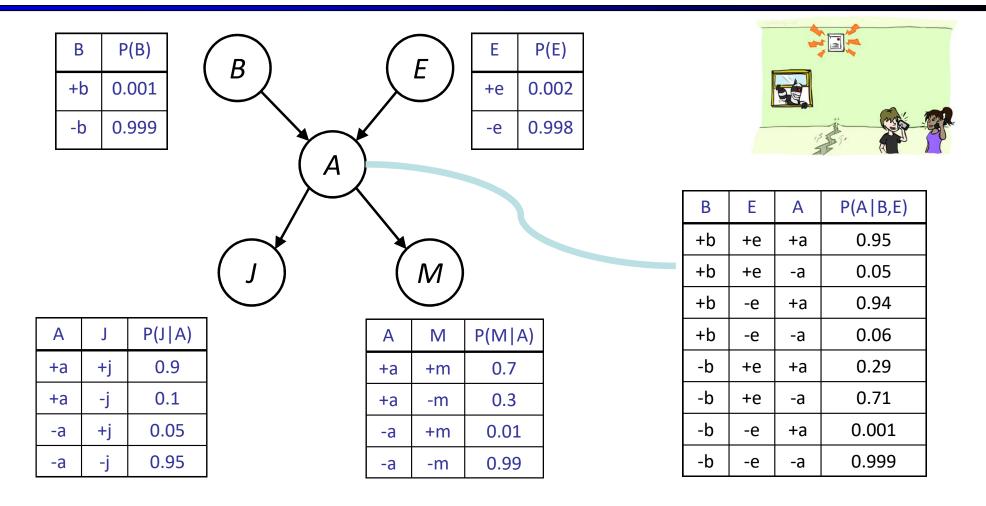




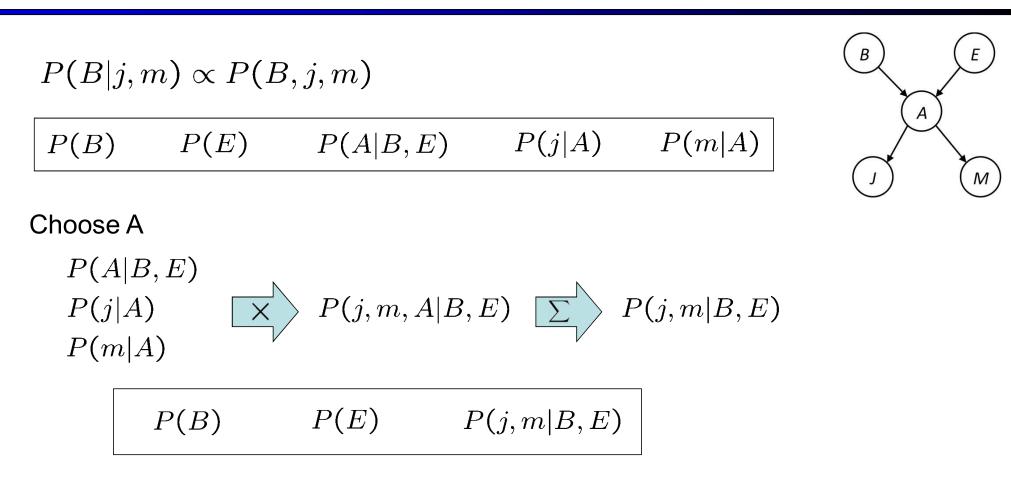


## Example: Alarm Network

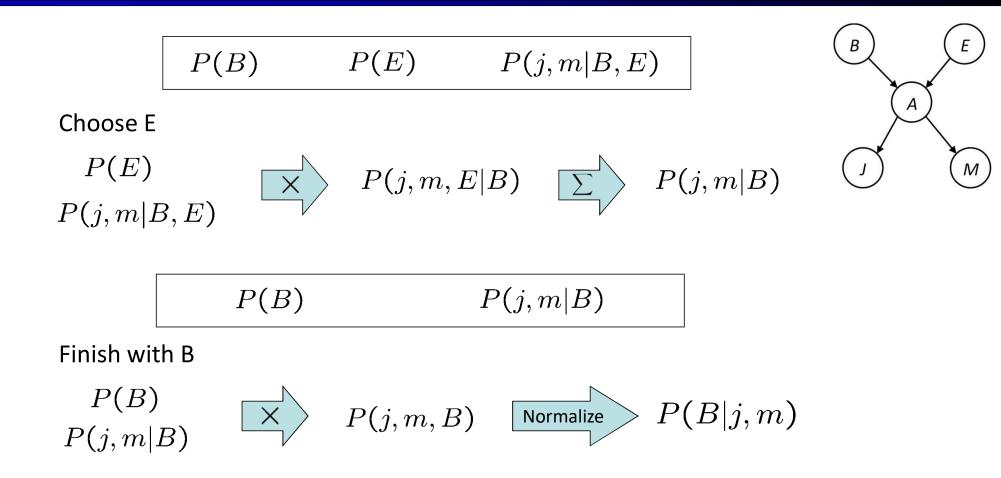
P(B | j, m) = ?



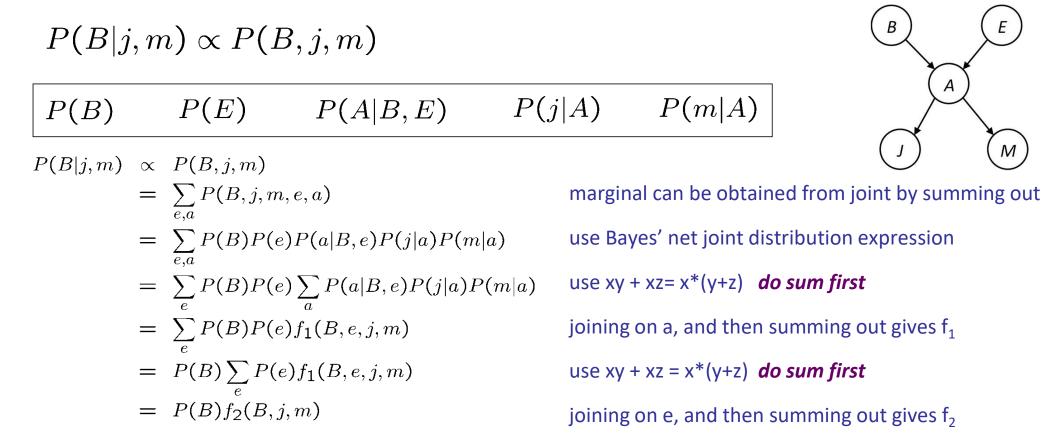
## Example



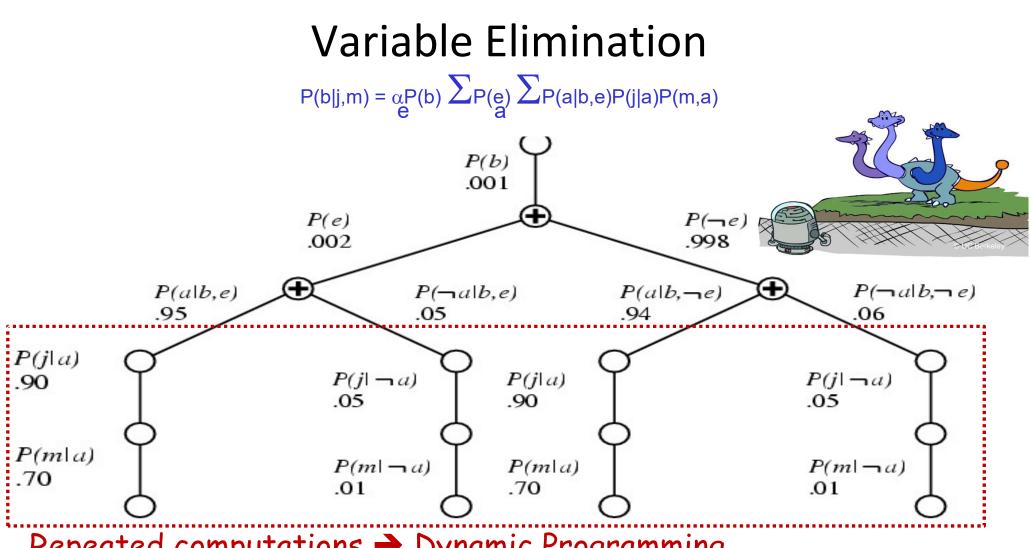
#### Example



#### Same Example in Equations



Simple! Exploiting uwy + uwz + uxy + uxz + vwy + vwz + vxy +vxz = (u+v)(w+x)(y+z) to reduce computation



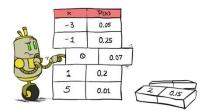
Repeated computations -> Dynamic Programming

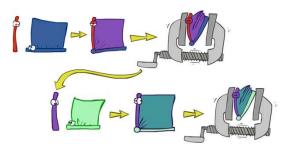
#### **Choices during Variable Elimination**

• Query: 
$$P(Q|E_1 = e_1, \dots E_k = e_k)$$

- Start with initial factors:
  - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
  - Choose a hidden variable H
  - Join all factors mentioning H
  - Eliminate (sum out) H

#### Join all remaining factors and normalize





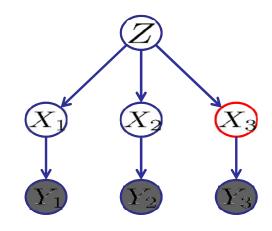


Query:  $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$ 

Start by inserting evidence, which gives the following initial factors:

 $p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$ 

#### What variables could we eliminate?



Query:  $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$ 

Start by inserting evidence, which gives the following initial factors:

 $p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$ 

Eliminate  $X_1$ , this introduces the factor  $f_1(Z, y_1) = \sum_{x_1} p(x_1|Z)p(y_1|x_1)$ , and we are left with:

 $p(Z) \underline{f_1(Z, y_1)} p(X_2|Z) p(X_3|Z) p(y_2|X_2) p(y_3|X_3)$ 

Eliminate  $X_2$ , this introduces the factor  $\underline{f_2(Z, y_2)} = \sum_{x_2} p(x_2|Z)p(y_2|x_2)$ , and we are left with:

$$p(Z)f_1(Z, y_1)\underline{f_2(Z, y_2)}p(X_3|Z)p(y_3|X_3)$$

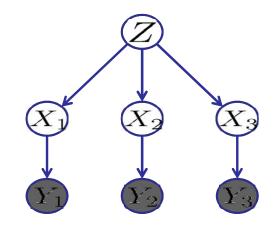
Eliminate Z, this introduces the factor  $f_3(y_1, y_2, X_3) = \sum_z p(z) f_1(z, y_1) f_2(z, y_2) p(X_3|z)$ , and we are left:

$$p(y_3|X_3), f_3(y_1, y_2, X_3)$$

No hidden variables left. Join the remaining factors to get:

 $f_4(y_1, y_2, y_3, X_3) = P(y_3 | X_3) f_3(y_1, y_2, X_3).$ 

Normalizing over  $X_3$  gives  $P(X_3|y_1, y_2, y_3)$ .



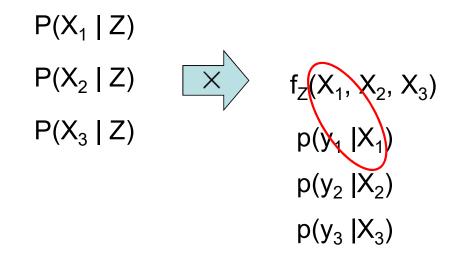
What dimension are  $f_1$ ,  $f_2 \& f_3$ ?

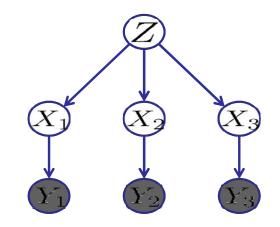
Query:  $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$ 

Start by inserting evidence, which gives the following initial factors:

 $p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$ 

#### Alternatively, suppose we start by eliminating Z:





What is the resulting factor?What dimension is it? 3How many entries? k<sup>3</sup>

Query:  $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$ 

Start by inserting evidence, which gives the following initial factors:

 $p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$ 

Eliminate  $X_1$ , this introduces the factor  $f_1(Z, y_1) = \sum_{x_1} p(x_1|Z)p(y_1|x_1)$ , and we are left with:

 $p(Z) \underline{f_1(Z, y_1)} p(X_2|Z) p(X_3|Z) p(y_2|X_2) p(y_3|X_3)$ 

Eliminate  $X_2$ , this introduces the factor  $\underline{f_2(Z, y_2)} = \sum_{x_2} p(x_2|Z)p(y_2|x_2)$ , and we are left with:

 $p(Z)f_1(Z, y_1)\underline{f_2(Z, y_2)}p(X_3|Z)p(y_3|X_3)$ 

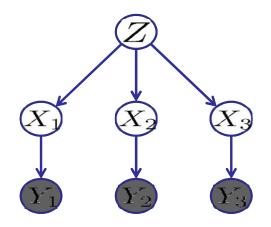
Eliminate Z, this introduces the factor  $f_3(y_1, y_2, X_3) = \sum_z p(z) f_1(z, y_1) f_2(z, y_2) p(X_3|z)$ , and we are left:

$$p(y_3|X_3), f_3(y_1, y_2, X_3)$$

No hidden variables left. Join the remaining factors to get:

 $f_4(y_1, y_2, y_3, X_3) = P(y_3 | X_3) f_3(y_1, y_2, X_3).$ 

Normalizing over  $X_3$  gives  $P(X_3|y_1, y_2, y_3)$ .

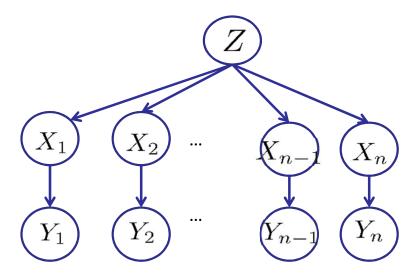


Computational complexity depends on the *largest factor* generated by the process.

Size of factor = number of entries in table.

### Variable Elimination Ordering

For the query P(X<sub>n</sub>|y<sub>1</sub>,...,y<sub>n</sub>) work through the following two different orderings as done in previous slide: Z, X<sub>1</sub>, ..., X<sub>n-1</sub> and X<sub>1</sub>, ..., X<sub>n-1</sub>, Z. What is the size of the maximum factor generated for each of the orderings?



- Answer: 2<sup>n+1</sup> versus 2<sup>2</sup> (assuming binary)
- In general: the ordering can greatly affect efficiency.

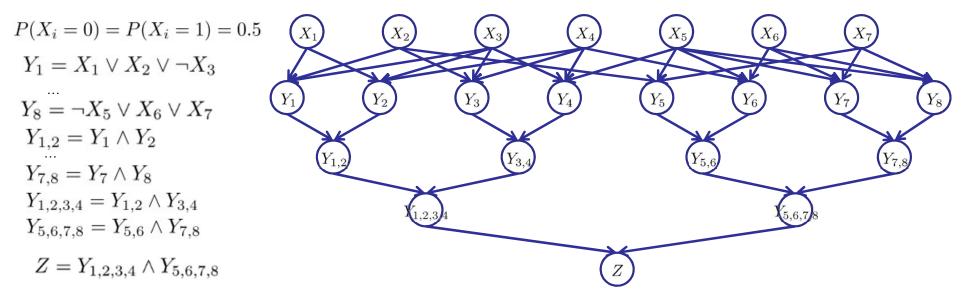
#### VE: Computational and Space Complexity

- The computational and space complexity of variable elimination is determined by the largest factor
- The elimination ordering can greatly affect the size of the largest factor.
  - E.g., previous slide's example 2<sup>n</sup> vs. 2
- Does there always exist an ordering that only results in small factors?
  - No!

#### Worst Case Complexity?

#### CSP:

 $(x_1 \lor x_2 \lor \neg x_3) \land (\neg x_1 \lor x_3 \lor \neg x_4) \land (x_2 \lor \neg x_2 \lor x_4) \land (\neg x_3 \lor \neg x_4 \lor \neg x_5) \land (x_2 \lor x_5 \lor x_7) \land (x_4 \lor x_5 \lor x_6) \land (\neg x_5 \lor x_6 \lor \neg x_7) \land (\neg x_5 \lor \neg x_6 \lor x_7) \land (\neg x_5 \lor x_6 \lor x_7) \land (\neg x_6$ 



- If we can answer P(z) equal to zero or not, we answered whether the 3-SAT problem has a solution.
- Hence inference in Bayes' nets is NP-hard. No known efficient probabilistic inference in general.

#### Bayes' Nets

#### Representation

- Conditional Independences
- Probabilistic Inference
  - Enumeration (exact, exponential complexity)
  - Variable elimination (exact, worst-case exponential complexity, often better)
  - 🖌 Inference is NP-complete
  - Sampling (approximate)
- Learning Bayes' Nets from Data