

1987-95 Stuart Russell (Berkeley) and Peter Norvig (Google) A.I.A.M.A. 1995-2003 This presentation includes slides from : Dieter Fox, Dan Weld, Dan Klein, Stuart Russell, Andrew Moore, Luke Zettlemoyer

Course Logistics

Textbook:

Artificial Intelligence: A Modern Approach, Russell and Norvig (3rd ed)

Prerequisites:

- Data Structures (CSE 332)
- Understanding of probability, logic, algorithms, complexity

Work:

Readings (text & papers) Programming assignments / hw (40%), Midterm (20%) Final (30%) Class participation (10%)





Today

Selected Texts and Authors

■ What is (AI)?

Earl Hunt (UW) A.I. 1975

S. Tanimoto (UW) E.A.I.

- Agents
- What is this course?



Brain: Can We Build It?



10¹¹ neurons 10¹⁴ synapses cycle time: 10⁻³ sec

VS.

10⁹ transistors 10¹² bits of RAM cycle time: 10-9 sec



What Can AI Do?

Quiz: Which of the following can be done at present?

- Play a decent game of Soccer?
- Play a winning game of Chess? Go? Jeopardy?
- Drive safely along a curving mountain road? University Way?
- Buy a week's worth of groceries on the Web? At QFC?
- Make a car? Bake a cake?
- Discover and prove a new mathematical theorem?
- Perform a complex surgical operation?
- Unload a dishwasher and put everything away?
- Translate Chinese into English in real time?
- Design a company web page?

What is AI?

The science of making machines that:

Think like humans	Think rationally
Act like humans	Act rationally

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Rational Decisions

We'll use the term **rational** in a particular way:

- Rational: maximally achieving pre-defined goals
- Rational only concerns what decisions are made (not the thought process behind them)
- Goals are expressed in terms of the utility of outcomes
- Being rational means maximizing your expected utility

A better title for this course might be:

Computational Rationality

A (Short) History of Al

Prehistory

 Logical Reasoning: (4th C BC+) Aristotle, George Boole, Gottlob Frege, Alfred Tarski



Medieval Times

Probabilistic Reasoning: (16th C+) Gerolamo Cardano, Pierre Fermat, James Bernoulli, Thomas Bayes



1940-1950: Early Days



1942: Asimov: Positronic Brain; Three Laws of Robotics

- 1. A robot may not injure a human being or, through inaction, allow a human being to come to harm.
- 2. A robot must obey the orders given to it by human beings, except where such orders would conflict with the First Law.
- 3. A robot must protect its own existence as long as such protection does not conflict with the First or Second Laws.

1943: McCulloch & Pitts: Boolean circuit model of brain



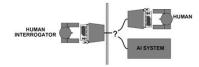
1943, 1946: First electronic digital computers -

Colossus (Thomas H. Flowers*), ENIAC (John Mauchly & John Presper Eckert, Jr.)

The Turing Test

Turing (1950) "Computing machinery and intelligence"

- "Can machines think?"
- "Can machines behave intelligently?"
- The Imitation Game:



 Suggested major components of Al: knowledge, reasoning, language understanding, learning

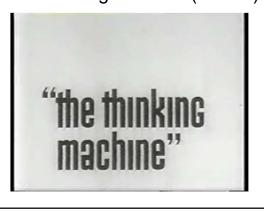
1950-1970: Excitement

- 1950s: Early AI programs, including
 - Samuel's checkers program,
 - Newell & Simon's Logic Theorist,
 - Gelernter's Geometry Theorem-Proving Machine
- 1956: Dartmouth meeting: "Artificial Intelligence" adopted
- 1965: Robinson's complete algorithm for logical reasoning

"Over Christmas, Allen Newell and I created a thinking machine."

-Herbert Simon

The Thinking Machine (1960's)



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1970-1980: Knowledge Based Systems

- 1969-79: Early development of knowledge-based systems
- 1980-88: Expert systems industry booms
- 1988-93: Expert systems industry busts "Al Winter"

The knowledge engineer practices the art of bringing the principles and tools of AI research to bear on difficult applications problems requiring experts' knowledge for their solution.

- Edward Felgenbaum in "The Art of Artificial Intelligence"

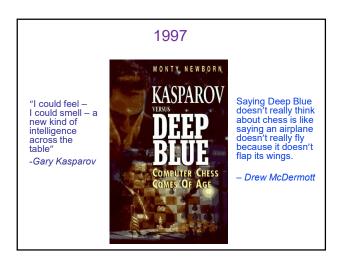
1988--: Statistical Approaches



- 1985-1990: Rise of Probability and Decision Theory Eg, Bayes Nets
 - Judea Pearl ACM Turing Award 2011
- 1990-2000: Machine learning takes over subfields: Vision, Natural Language, etc.

"Every time I fire a linguist, the performance of the speech recognizer goes up"

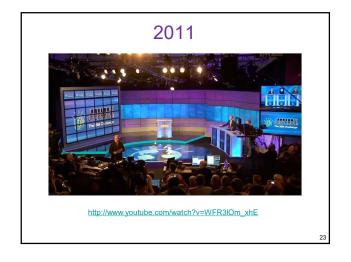
- Fred Jelinek, IBM Speech Team













Judges were not so smart

Conversation with Scott Aaronson:

Scott: Which is bigger, a shoebox or Mount Everest?

Eugene: I can't make a choice right now. I should think it out later. And I forgot to ask you where you are from...

Scott: How many legs does a camel have?

Eugene: Something between 2 and 4. Maybe, three? :-))) By the way, I still don't know your specialty – or, possibly, I've missed it?

Scott: How many legs does a millipede have?

Eugene: Just two, but Chernobyl mutants may have them up to five. I know you are supposed to trick me.

Scott: No, I need to know that you're not a chatbot. Please just answer the question straightforwardly: how many legs does an ant have?

Eugene: Something between 2 and 4. Maybe, three? :-))) Oh, what a fruitful conversation;-)

Scott: Do you understand why I'm asking such basic questions? Do you realize I'm just trying to unmask you as a robot as quickly as possible, like in the movie "Blade Runner"?

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Judges were not so smart (cont.)

Eugene: ...wait

Scott: Do you think your ability to fool unsophisticated judges indicates a flaw with the Turing Test itself, or merely with the way people have interpreted the test?

Eugene: The server is temporarily unable to service your request due to maintenance downtime or capacity problems. Please try again later.

Scott: Do you think Alan Turing, brilliant though he was, had trouble imagining that the judges of his "imitation game" wouldn't think to ask commonsense questions like the ones above—or that, if they did, they'd actually accept evasion or irrelevant banter as answers?

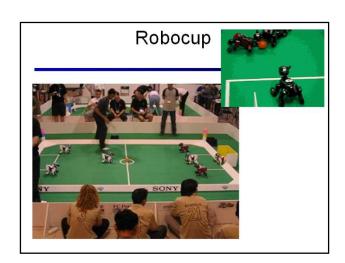
Eugene: No, not really. I don't think alan turing brilliant although this guy was had trouble imagining that the judges of his imitation game would not consider to Oooh. Anything else?

For more details, see: http://www.scottaaronson.com/blog/?p=1858

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Robocup (Stockholm '99)





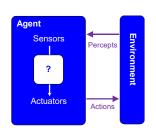
What is AI?

The science of making machines that:

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Agent vs. Environment

- An agent is an entity that perceives and acts.
- A rational agent selects actions that maximize its utility function.
- Characteristics of the percepts, environment, and action space dictate techniques for selecting rational actions.



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Actions? Percepts?



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Actions? Percepts?

amazon

More Top Picks for You



Recommender System

3

Types of Environments

- Fully observable vs. partially observable
- Single agent vs. multiagent
- Deterministic *vs.* stochastic
- Episodic *vs.* sequential
- Discrete vs. continuous

Fully observable vs. Partially observable
Can the agent observe the

can the agent observe the complete state of the environment?



VS.



Single agent vs. Multiagent

Is the agent the only thing acting in the world?



Aka static vs. dynamic

Deterministic vs. Stochastic

Is there uncertainty in how the world works?





Episodic vs. Sequential

Episodic: next episode doesn't depend on previous actions.



vs.



Discrete vs. Continuous

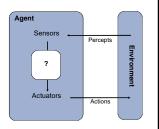
Is there a finite (or countable) number of possible environment states?





Types of Agent

- An **agent** is an entity that *perceives* and *acts*.
- A rational agent selects actions that maximize its utility function.
- Characteristics of the percepts, environment, and action space dictate techniques for selecting rational actions.



Reflex Agents

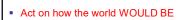
- Reflex agents:
 - Choose action based on current percept (and maybe memory)
 - Do not consider the future consequences of their actions
 - Act on how the world IS





Goal Based Agents

- Plan ahead
- Ask "what if"
- Decisions based on (hypothesized) consequences of actions
- Must have a model of how the world evolves in response to actions





Utility Based Agents

- Like goal-based, but
- Trade off multiple goals
- Reason about probabilities of outcomes
- Act on how the world will LIKELY be





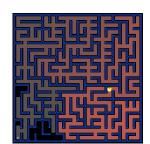
Project 1: Search

Goal:

• Help Pac-man find its way through the maze

Techniques:

- · Search: breadthfirst, depth-first, etc.
- Heuristic Search: Best-first, A*, etc.

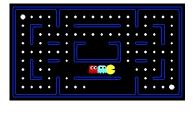


Project 2: Game Playing

Techniques:

• Play Pac-man!

 Adversarial Search: minimax, alpha-beta, expectimax, etc.



Project 3: Planning and Learning

• Help Pac-man learn about the world

Techniques:

- Planning: MDPs, Value Iterations
- Learning: Reinforcement Learning



Project 4: Ghostbusters

Goal:

• Help Pac-man hunt down the ghosts

Techniques:

- Probabilistic models: HMMS, **Bayes Nets**
- Inference: State estimation and particle filtering



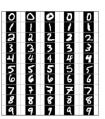
Project 5: Pattern Classification

Goal:

 Build a classifier that learns to recognize digits

Techniques:

- Perceptrons
- ML training strategies



Course Topics

- Part I: Making Decisions
 Fast search / planning
 Constraint satisfaction

 - Adversarial and uncertain search
- Part II: Reasoning under Uncertainty

- Bayes' netsDecision theoryMachine learning
- Throughout: ApplicationsNatural language, vision, robotics, games, ...

