## Recap: Search Problem

## CSE 473: Artificial Intelligence

 Winter 2017Heuristics \& Pattern Databases for Search

Steve Tanimoto

With thanks to Dan Weld, Dan Klein, Richard Korf, Stuart Russell, Andrew Moore, and Luke Zettlemoyer


States are Board Positions


## Search Methods

- Depth first search (DFS)
- Breadth first search (BFS)
- Iterative deepening depth-first search (IDS)
- Best first search
- Uniform cost search (UCS)
- Greedy search
- A*
- Iterative Deepening A* (IDA*)
- Beam search, hill climbing
- Stochastic Search
- Constraint Satisfaction

- Given N x N chess board

- Can you place N queens so they don't fight?



## Best-First Search

Generalization of breadth-first search

- Fringe = Priority queue of nodes to be explored
- Cost function $f(n)$ applied to each node

Add initial state to priority queue
While queue not empty
Node = head(queue)
If goal?(node) then return node
Add children of node to queue
"expanding the node"

## IDA* Analysis

- Complete \& Optimal (a la A*)
- Space usage $\propto$ depth of solution
- Each iteration is DFS - no priority queue!
- \# nodes expanded relative to $A^{*}$
- Depends on \# unique values of heuristic function
- In 8 puzzle: few values $\Rightarrow$ close to \# A* expands
- In eastern-europe travel: each $f$ value is unique $\Rightarrow 1+2+\ldots+n=O\left(n^{2}\right) \quad$ where $n=$ nodes $A^{*}$ expands if n is too big for main memory, $\mathrm{n}^{2}$ is too long to wait!
- Generates duplicate nodes in cyclic graphs


## Iterative-Deepening A*

- Like iterative-deepening depth-first, but...
- Depth bound modified to be an f-limit
- Start with f-limit $=h($ start $)$
- Prune any node if $f$ (node) >f-limit
- Next f-limit = min-cost of any node pruned



## Beam Search

- Idea
- Best first
- But discard all but N best items on priority queue
- Evaluation
- Complete?
- Time Complexity? $\mathrm{O}\left(\mathrm{b}^{\wedge} \mathrm{d}\right)$
- Space Complexity? $\mathrm{O}(\mathrm{b}+\mathrm{N})$


## Heuristics

It's what makes search actually work

## Admissable Heuristics

- $f(x)=g(x)+h(x)$
- g: cost so far
- h : underestimate of remaining costs

Where do heuristics come from?

## Relaxed Problems

- Derive admissible heuristic from exact cost of a solution to a relaxed version of problem
- For blocks world, distance = \# move operations
- heuristic = number of misplaced blocks
- What is relaxed problem?

- Cost of optimal soln to relaxed problem $\leq$ cost of optimal soln for real problem
© Daniel S. Weld


## Traveling Salesman Problem

Objective: shortest path visiting every city

What can be
Relaxed?


## Importance of Heuristics

 h1 = number of tiles in wrong place

## Importance of Heuristics

$\mathrm{h} 1=$ number of tiles in wrong place h2 $=\Sigma$ distances of tiles from correct loc


| D | IDS | A*(h1) | A*(h2) |
| :---: | ---: | :---: | :---: |
| 2 | 10 | 6 | 6 |
| 4 | 112 | 13 | 12 |
| 6 | 680 | 20 | 18 |
| 8 | 6384 | 39 | 25 |
| 10 | 47127 | 93 | 39 |
| 12 | 364404 | 227 | 73 |
| 14 | 3473941 | 539 | 113 |
| 18 |  | 3056 | 363 |
| 24 |  | 39135 | 1641 |

Decrease effective branching factor

## Subgoal Interactions

- Manhattan distance assumes
- Each tile can be moved independently of others
- Underestimates because
- Doesn't consider interactions between tiles

© Daniel S. Weld


## Using a Pattern Database

- As each state is generated
- Use position of chosen tiles as index into DB
- Use lookup value as heuristic, h(n)
- Admissible?


## Need More Power!

Performance of Manhattan Distance Heuristic

- 8 Puzzle < 1 second
- 15 Puzzle 1 minute
- 24 Puzzle 65000 years

Need even better heuristics!
© Daniel S. Weld

## Pattern Databases

- Pick any subset of tiles
- E.g., 3, 7, 11, 12, 13, 14, 15
- (or as drawn)
- Precompute a table
- Optimal cost of solving just these tiles
- For all possible configurations
- 57 Million in this case
- Use A* or IDA*
- State = position of just these tiles (\& blank)


## Combining Multiple Databases

- Can choose another set of tiles
- Precompute multiple tables
- How combine table values?

| 1 | 2 | 3 | 4 |
| :---: | :---: | :---: | :---: |
| 5 | 6 | 7 | 8 |
| 9 | 10 | 11 | 12 |
| 13 | 14 | 15 |  |

- E.g. Optimal solutions to Rubik's cube
- First found w/ IDA* using pattern DB heuristics
- Multiple DBs were used (dif cubie subsets )
- Most problems solved optimally in 1 day
- Compare with 574,000 years for IDDFS


## Drawbacks of Standard Pattern DBs

- Since we can only take max
- Diminishing returns on additional DBs
- Would like to be able to add values


## Performance

- 15 Puzzle: 2000x speedup vs Manhattan dist
- IDA* with the two DBs shown previously solves 15 Puzzles optimally in 30 milliseconds
- 24 Puzzle: 12 million x speedup vs Manhattan
- IDA* can solve random instances in 2 days.
- Requires 4 DBs as shown
- Each DB has 128 million entries
- Without PDBs: 65,000 years


Adapted from Richard Korf presentation 32

## Disjoint Pattern DBs

- Partition tiles into disjoint sets
- For each set, precompute table
- E.g. 8 tile DB has 519 million entries
- And 7 tile DB has 58 million
- During search
- Look up heuristic values for each set
- Can add values without overestimating!
- Manhattan distance is a special case of this idea where each set is a single tile

