CSE 473: Artificial Intelligence Winter 2017 Introduction & Agents



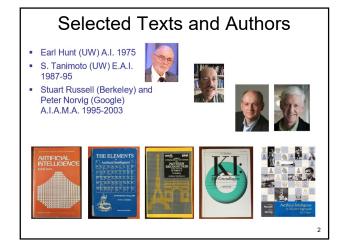


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Course Logistics

Textbook:

Artificial Intelligence: A Modern Approach, Russell and Norvig (3rd ed)

Prerequisites:

• Data Structures (CSE 332) • Understanding of probability, logic, algorithms, complexity

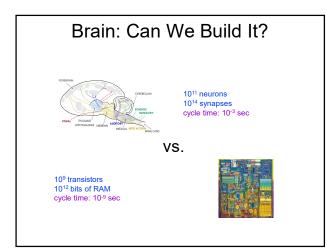
Work:

Readings (text & papers) Programming assignments / hw (40%), Midterm (20%) Final (30%) Class participation (10%)









What Can AI Do?

Quiz: Which of the following can be done at present?

- Play a decent game of Soccer?
- Play a winning game of Chess? Go? Jeopardy?
- Drive safely along a curving mountain road? University Way?
- Buy a week's worth of groceries on the Web? At QFC?
- Make a car? Bake a cake? •
- Discover and prove a new mathematical theorem?
- Perform a complex surgical operation?
- Unload a dishwasher and put everything away?
- Translate Chinese into English in real time?
- Design a company web page?

What is AI?					
The	science of making	machines that:			
	Think like humans	Think rationally			
	Act like humans	Act rationally			

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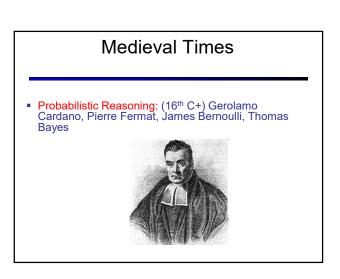
Rational Decisions

We'll use the term **rational** in a particular way:

- Rational: maximally achieving pre-defined goalsRational only concerns what decisions are made
- (not the thought process behind them)
- Goals are expressed in terms of the utility of outcomes
- Being rational means maximizing your expected utility

A better title for this course might be: Computational Rationality

Prehistory • Logical Reasoning: (4th C BC+) Aristotle, George Boole, Gottlob Frege, Alfred Tarski



A (Short) History of Al

1940-1950: Early Days

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1942: Asimov: Positronic Brain; Three Laws of Robotics1. A robot may not injure a human being or, through inaction, allow a human being to come to harm.

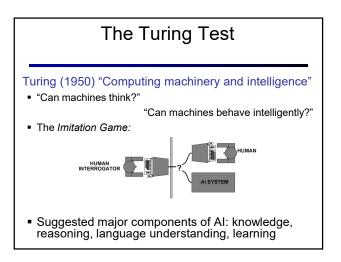
 $2.\ A$ robot must obey the orders given to it by human beings, except where such orders would conflict with the First Law.

3. A robot must protect its own existence as long as such protection does not conflict with the First or Second Laws

1943: McCulloch & Pitts: Boolean circuit model of brain

1943, 1946: First electronic digital computers -

Colossus (Thomas H. Flowers*), ENIAC (John Mauchly & John Presper Eckert, Jr.)

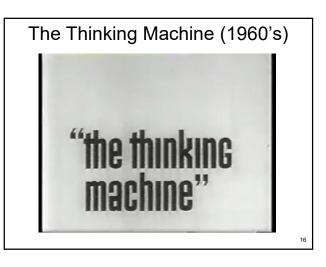


1950-1970: Excitement

- 1950s: Early AI programs, including
 - Samuel's checkers program,
 - Newell & Simon's Logic Theorist,
 - Gelernter's Geometry Theorem-Proving Machine
- 1956: Dartmouth meeting: "Artificial Intelligence" adopted
- 1965: Robinson's complete algorithm for logical reasoning

"Over Christmas, Allen Newell and I created a thinking machine."

-Herbert Simon



1970-1980: Knowledge Based Systems

- 1969-79: Early development of knowledge-based systems
- 1980-88: Expert systems industry booms
- 1988-93: Expert systems industry busts
 "Al Winter"

The knowledge engineer practices the art of bringing the principles and tools of AI research to bear on difficult applications problems requiring experts' knowledge for their solution.

- Edward Felgenbaum in "The Art of Artificial Intelligence"

1988--: Statistical Approaches

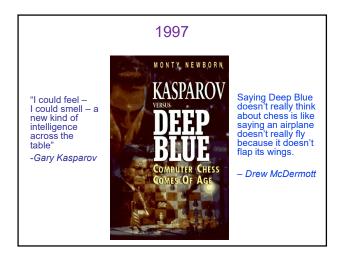


 1985-1990: Rise of Probability and Decision Theory Eg, Bayes Nets

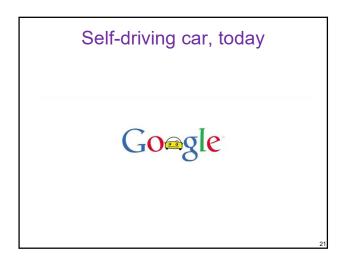
Judea Pearl - ACM Turing Award 2011

 1990-2000: Machine learning takes over subfields: Vision, Natural Language, etc.

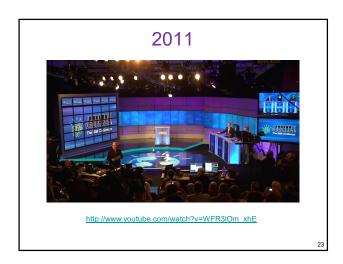
"Every time I fire a linguist, the performance of the speech recognizer goes up" - Fred Jelinek, IBM Speech Team













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Judges were not so smart

Conversation with Scott Aaronson:

Scott: Which is bigger, a shoebox or Mount Everest?

Eugene: I can't make a choice right now. I should think it out later. And I forgot to ask you where you are from...

Scott: How many legs does a camel have?

Eugene: Something between 2 and 4. Maybe, three? :-))) By the way, I still don't know your specialty – or, possibly, I've missed it?

Scott: How many legs does a millipede have?

Eugene: Just two, but Chernobyl mutants may have them up to five. I know you are supposed to trick me.

Scott: No, I need to know that you're not a chatbot. Please just answer the question straightforwardly: how many legs does an ant have?

Eugene: Something between 2 and 4. Maybe, three? :-))) Oh, what a fruitful conversation;-)

Scott: Do you understand why I'm asking such basic questions? Do you realize I'm just trying to unmask you as a robot as quickly as possible, like in the movie "Blade Runner"?

Judges were not so smart (cont.)

Eugene: ...wait

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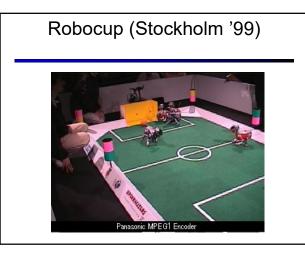
Scott: Do you think your ability to fool unsophisticated judges indicates a flaw with the Turing Test itself, or merely with the way people have interpreted the test?

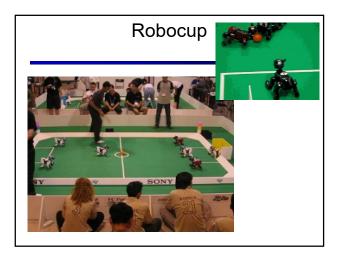
Eugene: The server is temporarily unable to service your request due to maintenance downtime or capacity problems. Please try again later.

Scott: Do you think Alan Turing, brilliant though he was, had trouble imagining that the judges of his "imitation game" wouldn't think to ask commonsense questions like the ones above—or that, if they did, they'd actually accept evasion or irrelevant banter as answers?

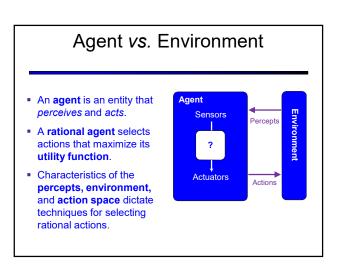
Eugene: No, not really. I don't think alan turing brilliant although this guy was had trouble imagining that the judges of his imitation game would not consider to Oooh. Anything else?

For more details, see: http://www.scottaaronson.com/blog/?p=1858





The science of making machines that:					
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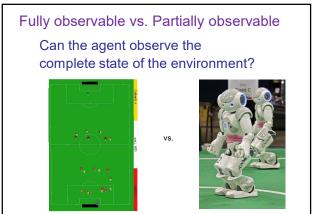


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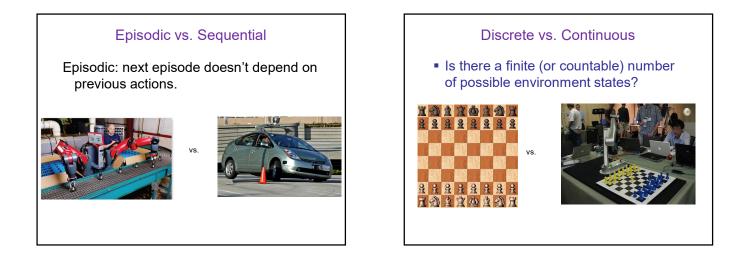
Types of Environments

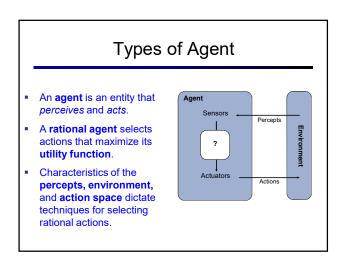
- Fully observable *vs.* partially observable
- Single agent vs. multiagent
- Deterministic vs. stochastic
- Episodic vs. sequential
- Discrete vs. continuous











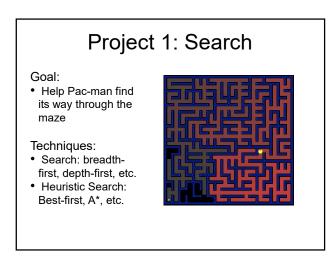


Goal Based Agents

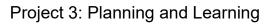
- Plan ahead
- Ask "what if"
- Decisions based on (hypothesized) consequences of actions
- Must have a model of how the world evolves in response to actions
- Act on how the world WOULD BE

Utility Based Agents Like goal-based, but Trade off multiple goals Reason about probabilities of outcomes Act on how the world will LIKELY be









Goal:

 Help Pac-man learn about the world Techniques:

- Planning: MDPs, Value Iterations
- Learning: Reinforcement Learning



