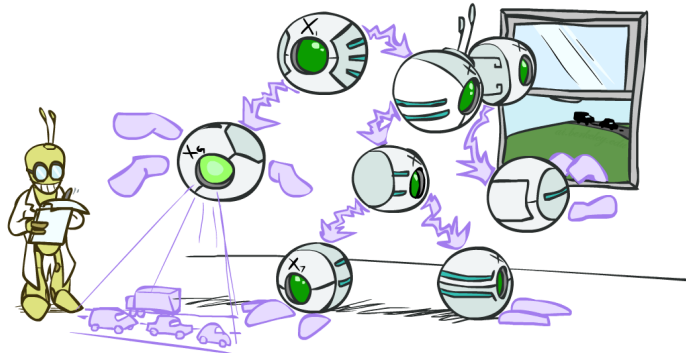


CSE 473: Artificial Intelligence

Bayes' Nets: Inference



Dan Weld

[These slides were created by Dan Klein and Pieter Abbeel for CS188 Intro to AI at UC Berkeley. All CS188 materials are available at <http://ai.berkeley.edu>.]

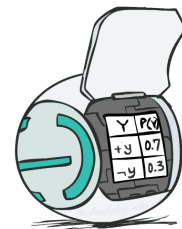
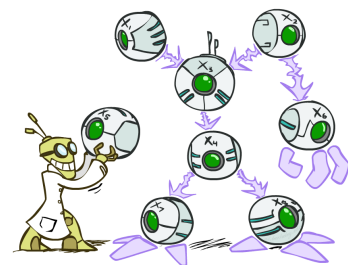
Bayes' Net Representation

- A directed, acyclic graph, one node per random variable
- A conditional probability table (CPT) for each node
 - A collection of distributions over X , one for each combination of parents' values

$$P(X|a_1 \dots a_n)$$

- Bayes' nets implicitly encode joint distributions
 - As a product of local conditional distributions
 - To see what probability a BN gives to a full assignment, multiply all the relevant conditionals together:

$$P(x_1, x_2, \dots, x_n) = \prod_{i=1}^n P(x_i | \text{parents}(X_i))$$

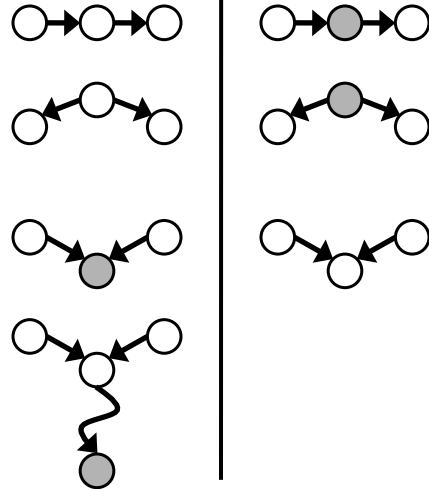


Active / Inactive Paths

- Question: Are X and Y conditionally independent given evidence variables {Z}?
 - Yes, if X and Y “d-separated” by Z
- Consider all (undirected) paths from X to Y...
- If **all** paths are inactive \rightarrow independence!
- A path is active if **every** triple is active:
 - Causal chain $A \rightarrow B \rightarrow C$ where B is unobserved (either direction)
 - Common cause $A \leftarrow B \rightarrow C$ where B is unobserved
 - Common effect (aka v-structure) $A \rightarrow B \leftarrow C$ where B or one of its descendants is observed
- All it takes to block a path is a **single** inactive segment
 - But every **path** must be blocked

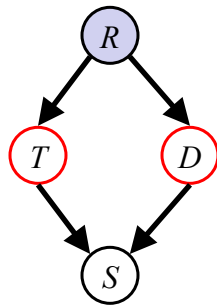
Active Triples

Inactive Triples



Example

- Variables:
 - R: Raining
 - T: Traffic
 - D: Roof drips
 - S: I'm sad



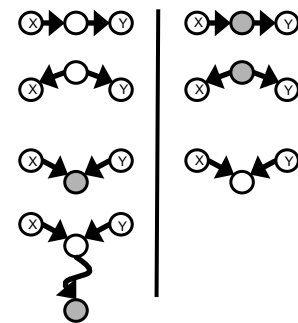
- Questions:

$T \perp\!\!\!\perp D$ **No**

$T \perp\!\!\!\perp D | R$ **Yes, Independent**

Active Triples

Inactive Triples

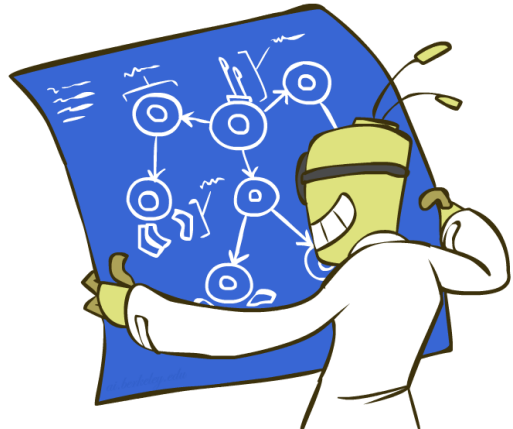


Structure Implications

- Given a Bayes net structure, can run d-separation algorithm to build a complete list of conditional independences that are necessarily true of the form

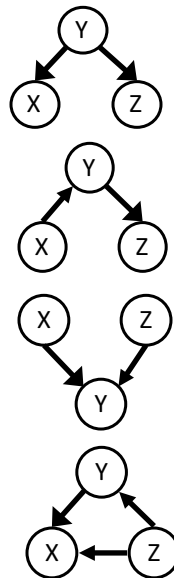
$$X_i \perp\!\!\!\perp X_j \mid \{X_{k_1}, \dots, X_{k_n}\}$$

- This list determines the set of probability distributions that can be represented



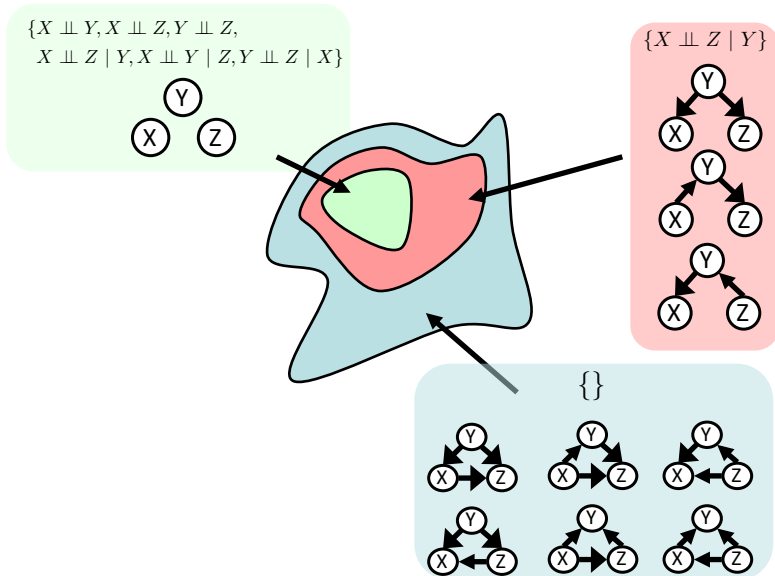
Computing All Independences

COMPUTE ALL THE
INDEPENDENCES!



Topology Limits Distributions

- Given some graph topology G , only certain joint distributions can be encoded
- The graph structure guarantees certain (conditional) independences
- (There might be more independence)
- Adding arcs increases the set of distributions, but has several costs
- Full conditioning can encode any distribution



Bayes' Nets

- ✓ Representation
- ✓ Conditional Independences
 - Probabilistic Inference
 - Enumeration (exact, exponential complexity)
 - Variable elimination (exact, worst-case exponential complexity, often better)
 - Probabilistic inference is NP-complete
 - Sampling (approximate)
 - Learning Bayes' Nets from Data

Inference

- Inference: calculating some useful quantity from a joint probability distribution

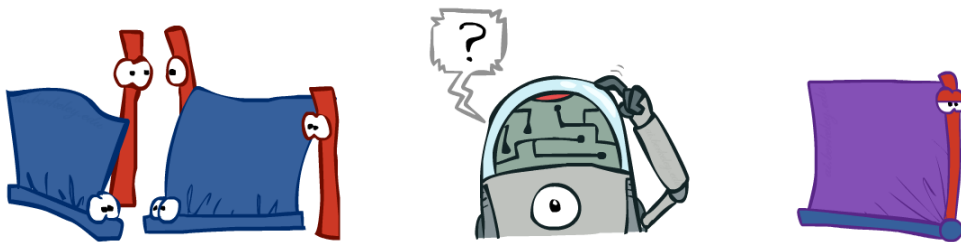
- Examples:

- Posterior probability

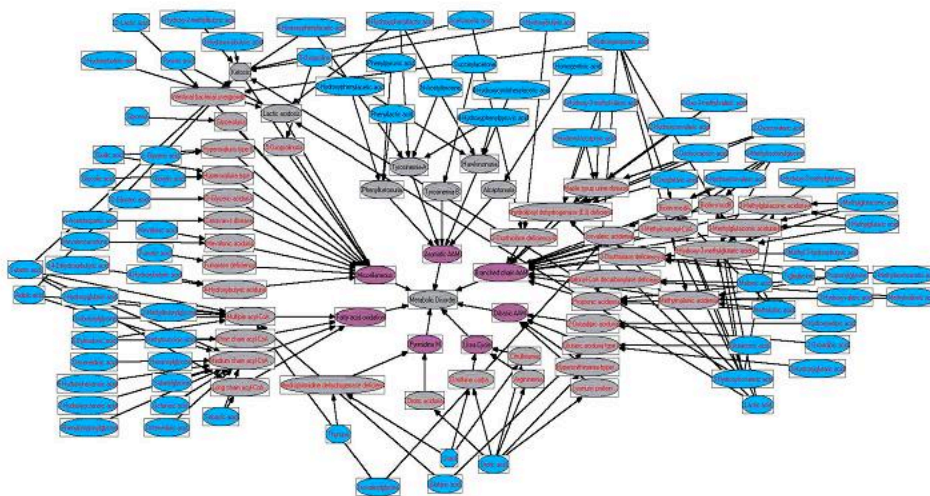
$$P(Q|E_1 = e_1, \dots, E_k = e_k)$$

- Most likely explanation:

$$\operatorname{argmax}_q P(Q = q|E_1 = e_1 \dots)$$



Test for Infant Metabolic Defects



Blue ovals represent chromatographic peaks, grey ovals represent 20 metabolic diseases

Inference by Enumeration

▪ **General case:**

- Evidence variables: $E_1 \dots E_k = e_1 \dots e_k$
- Query* variable: Q
- Hidden variables: $H_1 \dots H_r$

}

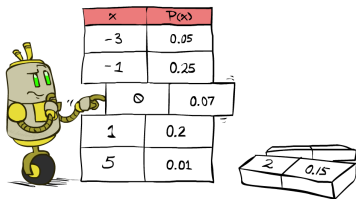
X_1, X_2, \dots, X_n
All variables

▪ **We want:**

$$P(Q|e_1 \dots e_k)$$

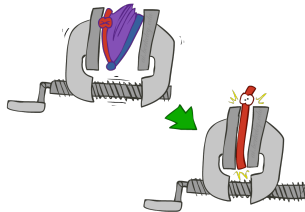
** Works fine with multiple query variables, too*

▪ **Step 1: Select the entries consistent with the evidence**



x	P(x)
-3	0.05
-1	0.25
0	0.07
1	0.2
5	0.01

▪ **Step 2: Sum out H to get joint of Query and evidence**



▪ **Step 3: Normalize**

$$\times \frac{1}{Z}$$

$$Z = \sum_q P(Q, e_1 \dots e_k)$$

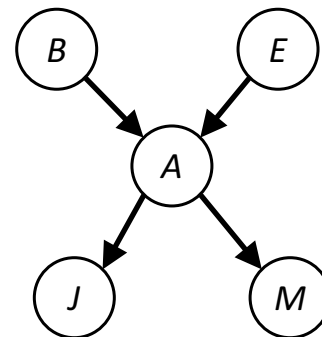
$$P(Q|e_1 \dots e_k) = \frac{1}{Z} P(Q, e_1 \dots e_k)$$

$$P(Q, e_1 \dots e_k) = \sum_{h_1 \dots h_r} P(Q, h_1 \dots h_r, e_1 \dots e_k)$$

X_1, X_2, \dots, X_n

Inference by Enumeration in Bayes' Net

- Given unlimited time, inference in BNs is easy
- Reminder of inference by enumeration by example:



$$P(B | +j, +m) \propto_B P(B, +j, +m)$$

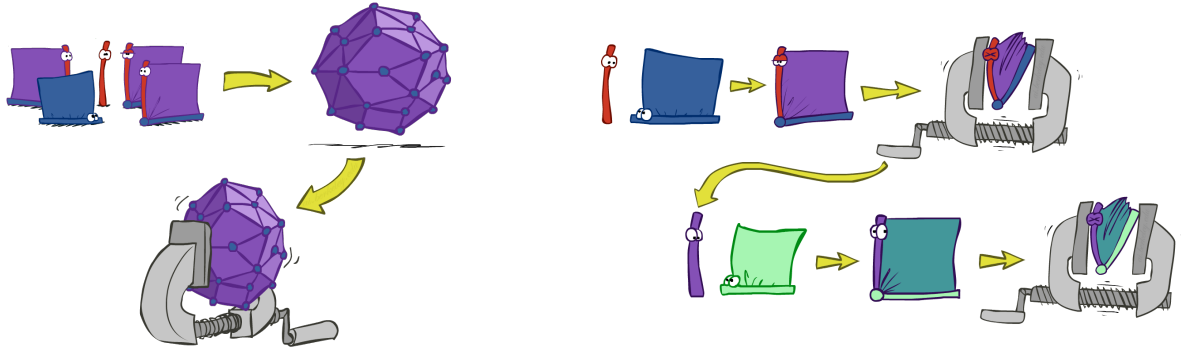
$$= \sum_{e,a} P(B, e, a, +j, +m)$$

$$= \sum_{e,a} P(B)P(e)P(a|B, e)P(+j|a)P(+m|a)$$

$$= P(B)P(+e)P(+a|B, +e)P(+j|+a)P(+m|+a) + P(B)P(+e)P(-a|B, +e)P(+j|-a)P(+m|-a) + P(B)P(-e)P(+a|B, -e)P(+j|+a)P(+m|+a) + P(B)P(-e)P(-a|B, -e)P(+j|-a)P(+m|-a)$$

Inference by Enumeration vs. Variable Elimination

- Why is inference by enumeration so slow?
 - You join up the whole joint distribution before you sum out the hidden variables
- Idea: interleave joining and marginalizing!
 - Called “Variable Elimination”
 - Still NP-hard, but usually much faster than inference by enumeration



First we'll need some new notation: factors

Traffic Domain



$$P(L) = ?$$

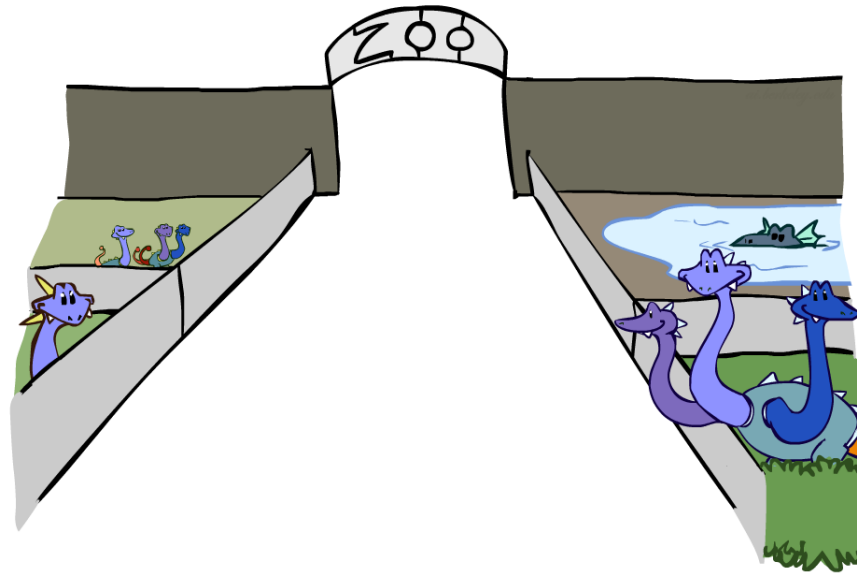
- Inference by Enumeration

$$= \sum_t \sum_r \underbrace{P(L|t)P(r)P(t|r)}_{\text{Join on } r} \underbrace{}_{\text{Join on } t} \underbrace{}_{\text{Eliminate } r} \underbrace{}_{\text{Eliminate } t}$$

- Variable Elimination

$$= \sum_t P(L|t) \sum_r \underbrace{P(r)P(t|r)}_{\text{Join on } r} \underbrace{}_{\text{Eliminate } r} \underbrace{}_{\text{Join on } t} \underbrace{}_{\text{Eliminate } t}$$

Factor Zoo



Factor Zoo I

- **Joint distribution: $P(X,Y)$**

- Entries $P(x,y)$ for all x, y
- Sums to 1

$$P(T, W)$$

T	W	P
hot	sun	0.4
hot	rain	0.1
cold	sun	0.2
cold	rain	0.3

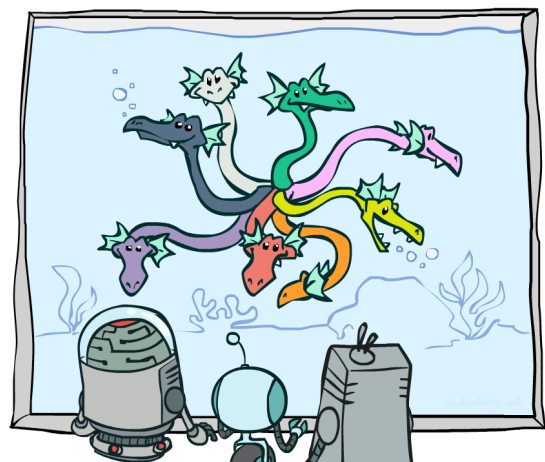
- **Selected joint: $P(x,y)$**

- A slice of the joint distribution
- Entries $P(x,y)$ for fixed x , all y
- Sums to $P(x)$

$$P(\text{cold}, W)$$

T	W	P
cold	sun	0.2
cold	rain	0.3

- **Number of capitals = dimensionality of the table**



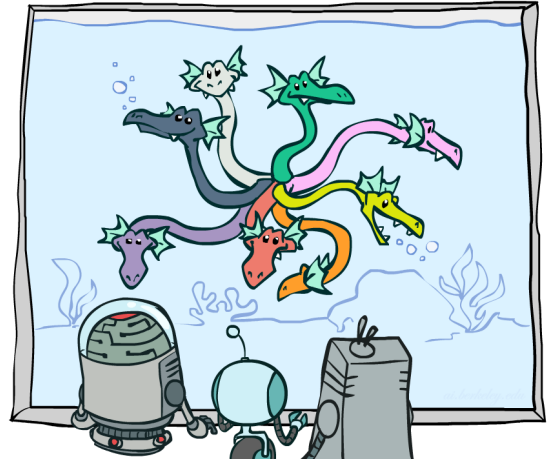
Factor Zoo I

Two dimensions

		$P(T, W)$		
		sun	rain	
hot	sun	0.4	0.1	
	rain			
cold	sun	0.2	0.3	
	rain			

One dimension

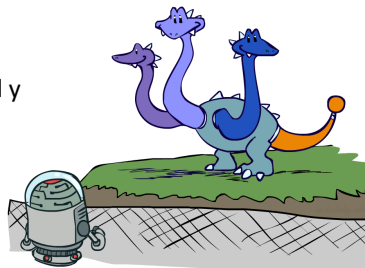
		$P(cold, W)$		
		sun	rain	
cold	sun	0.2	0.3	
	rain			



- Number of capitals = dimensionality of the table

Factor Zoo II

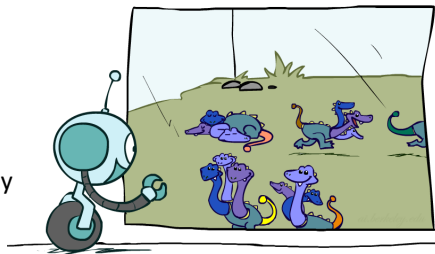
- Single conditional: $P(Y | x)$
 - Entries $P(y | x)$ for fixed x , all y
 - Sums to 1



$P(W|cold)$

T	W	P
cold	sun	0.4
cold	rain	0.6

- Family of conditionals: $P(X | Y)$
 - Multiple conditionals
 - Entries $P(x | y)$ for all x, y
 - Sums to $|Y|$



$P(W|T)$

T	W	P	
hot	sun	0.8	} $P(W hot)$
hot	rain	0.2	
cold	sun	0.4	} $P(W cold)$
cold	rain	0.6	

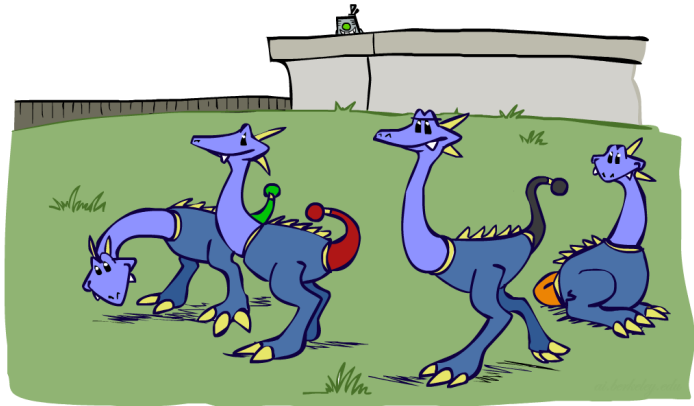
Factor Zoo III

- Specified family: $P(y | X)$
 - Entries $P(y | x)$ for fixed y , but for all x
 - Sums to ... who knows!

$$P(\text{rain}|T)$$

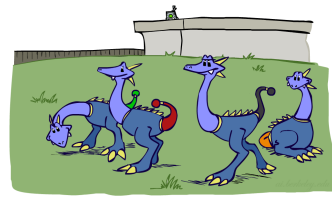
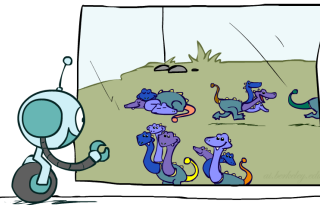
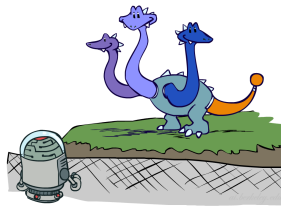
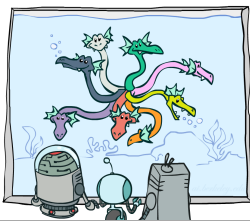
T	W	P
hot	rain	0.2
cold	rain	0.6

} $P(\text{rain}|\text{hot})$
 } $P(\text{rain}|\text{cold})$



Factor Zoo Summary

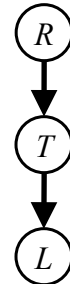
- In general, when we write $P(Y_1 \dots Y_N | X_1 \dots X_M)$
 - It is a “factor,” a multi-dimensional array
 - Its values are $P(y_1 \dots y_N | x_1 \dots x_M)$
 - Any assigned (=lower-case) X or Y is a dimension missing (selected) from the array



Example: Traffic Domain

- Random Variables

- R: Raining
- T: Traffic
- L: Late for class!



$$P(L) = ?$$

$$= \sum_{r,t} P(r, t, L)$$

$$= \sum_{r,t} P(r)P(t|r)P(L|t)$$

$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

Inference by Enumeration: Procedural Outline

- Track objects called **factors**
- Initial factors are local CPTs (one per node)

$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- Any known values are selected
 - E.g. if we know $L = +l$, the initial factors are

$$P(R)$$

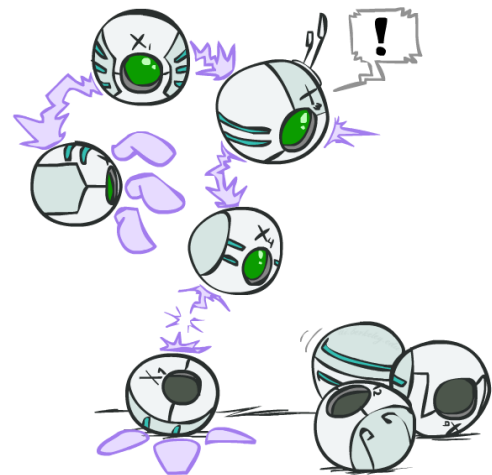
+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(+l|T)$$

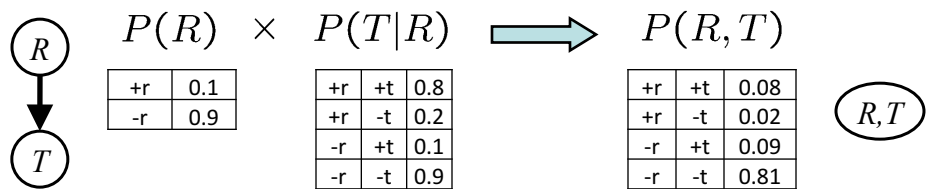
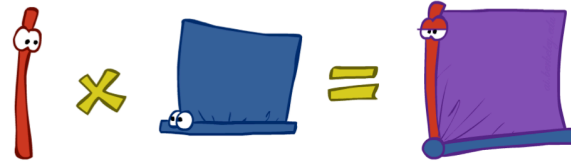
+t	+l	0.3
-t	+l	0.1



- Procedure: Join all factors, then eliminate all hidden variables

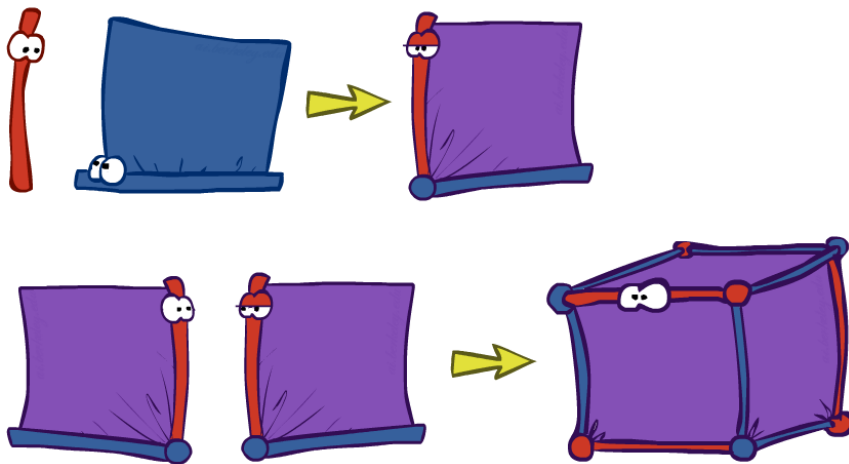
Operation 1: Join Factors

- First basic operation: **joining factors**
- Combining factors:
 - **Just like a database join**
 - Get all factors over the joining variable
 - Build a new factor over the union of the variables involved
- Example: Join on R

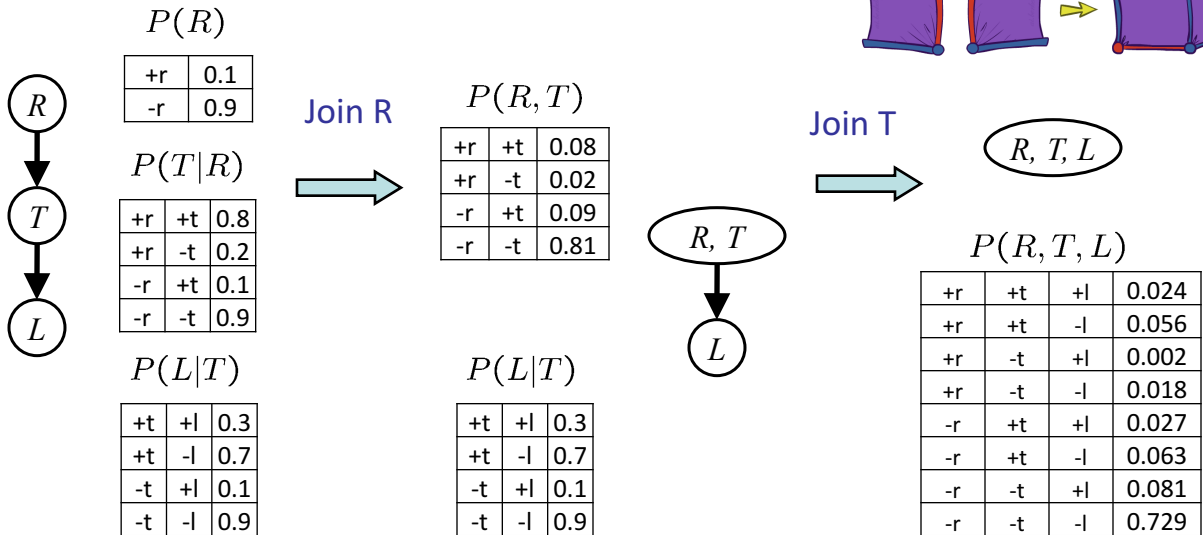
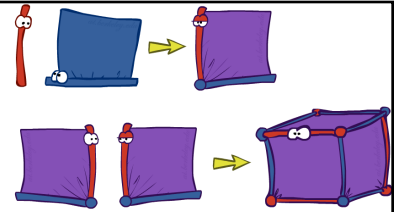


- Computation for each entry: pointwise products $\forall r, t : P(r, t) = P(r) \cdot P(t|r)$

Example: Multiple Joins

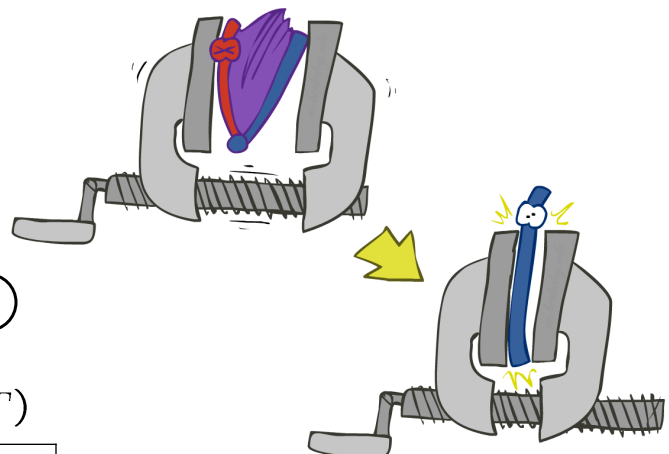
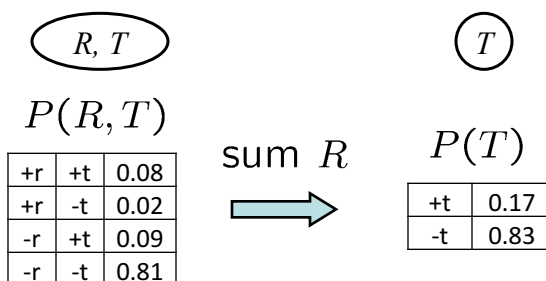


Example: Multiple Joins

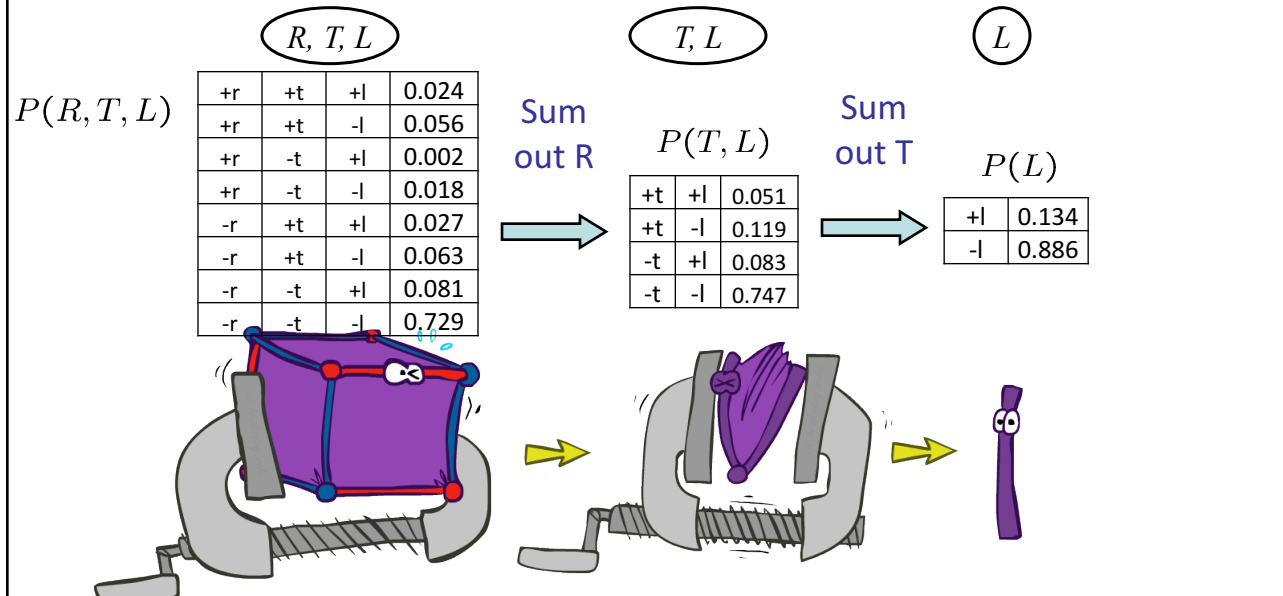


Operation 2: Eliminate

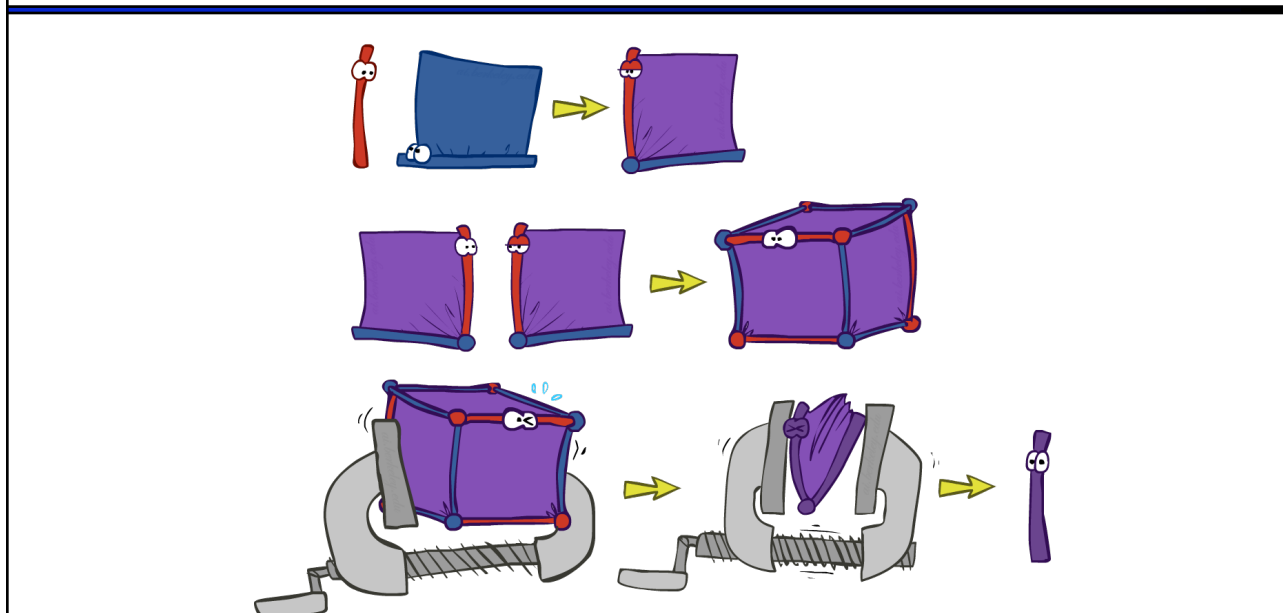
- Second basic operation: **marginalization**
- Take a factor and sum out a variable
 - Shrinks a factor to a smaller one
 - An **aggregate/project** operation
- Example:



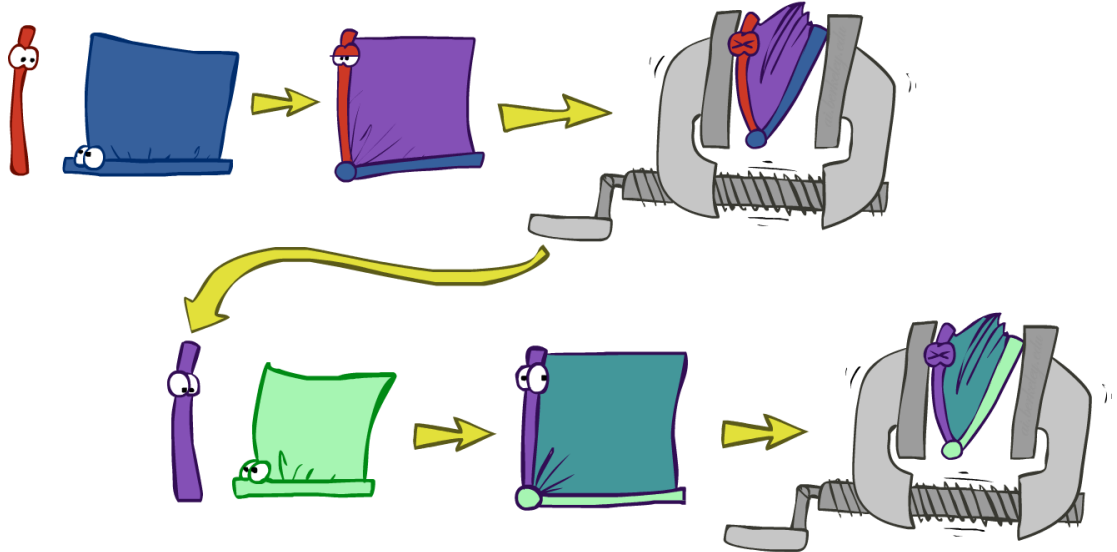
Multiple Elimination



Thus Far: Multiple Join, Multiple Eliminate (= Inference by Enumeration)



Marginalizing Early (= Variable Elimination)



Traffic Domain



$$P(L) = ?$$

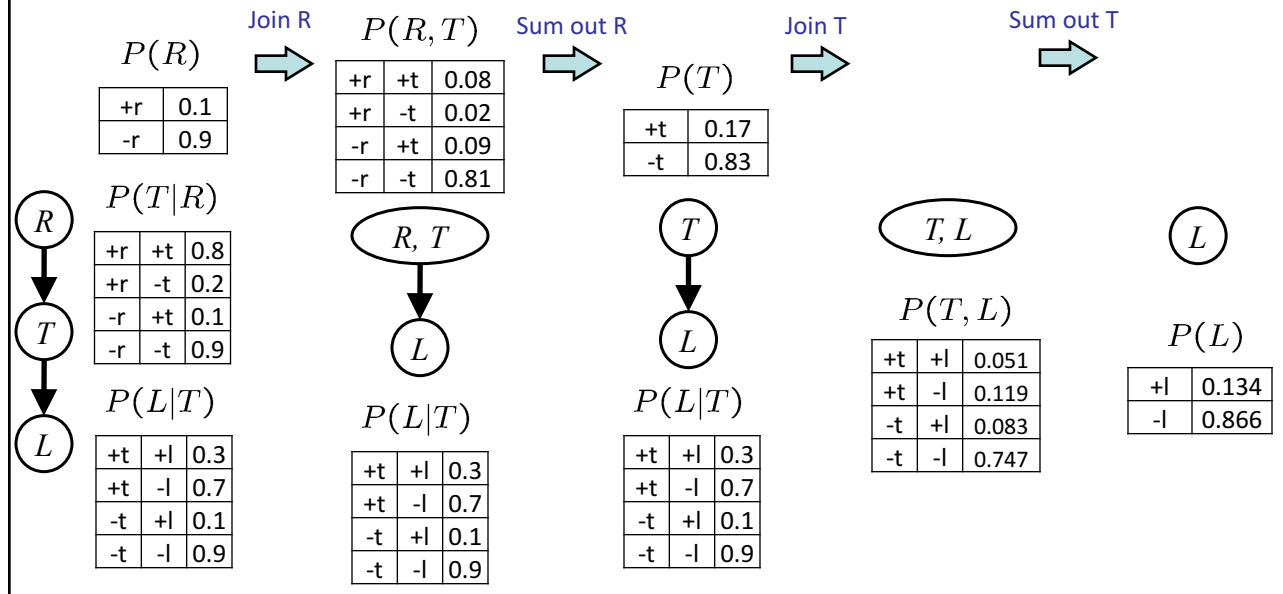
▪ Inference by Enumeration

$$= \sum_t \sum_r \underbrace{P(L|t)P(r)}_{\text{Join on } r} \underbrace{P(t|r)}_{\text{Join on } t} \underbrace{P(L)}_{\text{Eliminate } r} \underbrace{P(t)}_{\text{Eliminate } t}$$

▪ Variable Elimination

$$= \sum_t P(L|t) \underbrace{\sum_r P(r)P(t|r)}_{\text{Join on } r} \underbrace{P(L)}_{\text{Eliminate } r} \underbrace{P(t)}_{\text{Join on } t} \underbrace{P(L)}_{\text{Eliminate } t}$$

Marginalizing Early! (aka VE)



Evidence

- If evidence, start with factors that select that evidence

- If there is no evidence, then use these initial factors:

$$P(R)$$

+r	0.1
-r	0.9

$$P(T|R)$$

+r	+t	0.8
+r	-t	0.2
-r	+t	0.1
-r	-t	0.9

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9

- But if given some evidence, eg +r, then select for it...
- Computing $P(L|+r)$ the initial factors become:

$$P(+r)$$

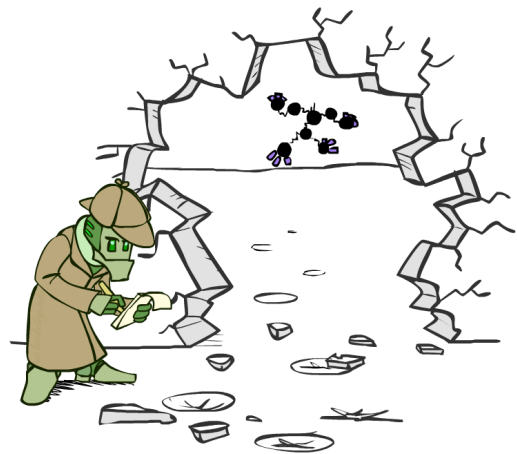
+r	0.1
----	-----

$$P(T|+r)$$

+r	+t	0.8
+r	-t	0.2

$$P(L|T)$$

+t	+l	0.3
+t	-l	0.7
-t	+l	0.1
-t	-l	0.9



- Next do joins & eliminate, removing all vars other than query + evidence

Evidence II

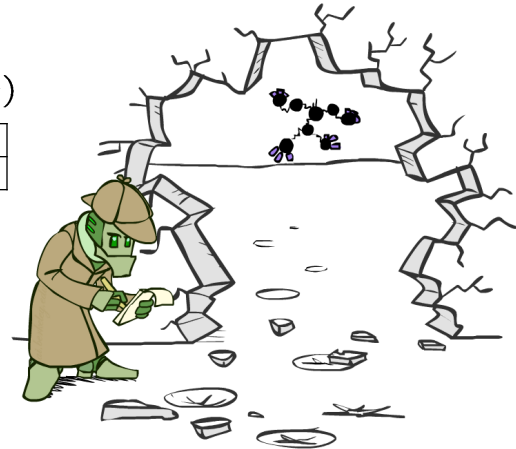
- Result will be a selected joint of query and evidence
 - E.g. for $P(L | +r)$, we would end up with:

$$P(+r, L) \xrightarrow{\text{Normalize}} P(L | +r)$$

+r	+l	0.026
+r	-l	0.074

+l	0.26
-l	0.74

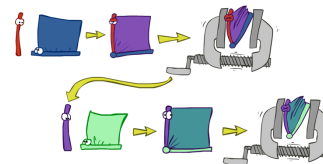
- To get our answer, just normalize this!
- That's it!



General Variable Elimination

- Query: $P(Q | E_1 = e_1, \dots, E_k = e_k)$
- Start with initial factors:
 - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
 - Choose a hidden variable H
 - Join all factors mentioning H
 - Eliminate (sum out) H
- Join all remaining factors and normalize

x	Pos
-5	0.05
-1	0.25
0	0.37
1	0.2
5	0.01

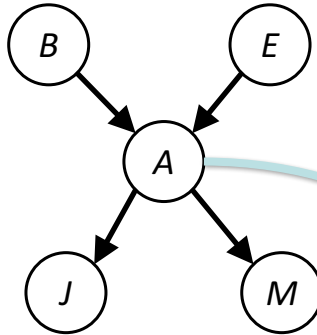


$$\text{Factor} \times \text{Factor} = \text{Factor} \times \frac{1}{Z}$$

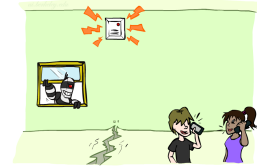
Example: Alarm Network

$P(B | j, m) = ?$

B	P(B)
+b	0.001
-b	0.999



E	P(E)
+e	0.002
-e	0.998



A	J	P(J A)
+a	+j	0.9
+a	-j	0.1
-a	+j	0.05
-a	-j	0.95

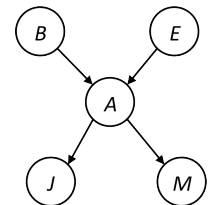
A	M	P(M A)
+a	+m	0.7
+a	-m	0.3
-a	+m	0.01
-a	-m	0.99

B	E	A	P(A B,E)
+b	+e	+a	0.95
+b	+e	-a	0.05
+b	-e	+a	0.94
+b	-e	-a	0.06
-b	+e	+a	0.29
-b	+e	-a	0.71
-b	-e	+a	0.001
-b	-e	-a	0.999

Example

$P(B|j, m) \propto P(B, j, m)$

$$P(B) \quad P(E) \quad P(A|B, E) \quad P(j|A) \quad P(m|A)$$



Choose A

$P(A|B, E)$

$P(j|A)$

$P(m|A)$



$P(j, m, A|B, E)$



$P(j, m|B, E)$

$$P(B) \quad P(E) \quad P(j, m|B, E)$$

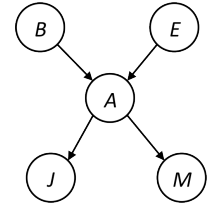
Example

$$P(B) \quad P(E) \quad P(j, m|B, E)$$

Choose E

$$P(E) \quad P(j, m, E|B) \quad P(j, m|B)$$

$\xrightarrow{\times}$
 $\xrightarrow{\Sigma}$



$$P(B) \quad P(j, m|B)$$

Finish with B

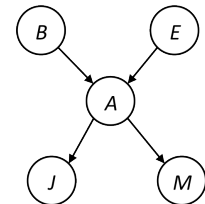
$$P(B) \quad P(j, m, B) \quad P(B|j, m)$$

$\xrightarrow{\times}$
 $\xrightarrow{\text{Normalize}}$

Same Example in Equations

$$P(B|j, m) \propto P(B, j, m)$$

$$P(B) \quad P(E) \quad P(A|B, E) \quad P(j|A) \quad P(m|A)$$



$$\begin{aligned}
 P(B|j, m) &\propto P(B, j, m) \\
 &= \sum_{e, a} P(B, j, m, e, a) \\
 &= \sum_{e, a} P(B)P(e)P(a|B, e)P(j|a)P(m|a) \\
 &= \sum_e P(B)P(e) \sum_a P(a|B, e)P(j|a)P(m|a) \\
 &= \sum_e P(B)P(e) f_1(B, e, j, m) \\
 &= P(B) \sum_e P(e) f_1(B, e, j, m) \\
 &= P(B) f_2(B, j, m)
 \end{aligned}$$

marginal can be obtained from joint by summing out

use Bayes' net joint distribution expression

use $xy + xz = x*(y+z)$ **do sum first**

joining on a, and then summing out gives f_1

use $xy + xz = x*(y+z)$ **do sum first**

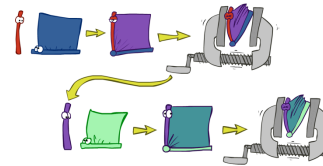
joining on e, and then summing out gives f_2

Simple! Exploiting $uwy + uwz + uxy + uxz + vwy + vwz + vxy + vxz = (u+v)(w+x)(y+z)$ to reduce computation

Choices during Variable Elimination

- Query: $P(Q|E_1 = e_1, \dots, E_k = e_k)$
- Start with initial factors:
 - Local CPTs (but instantiated by evidence)
- While there are still hidden variables (not Q or evidence):
 - Choose a hidden variable H
 - Join all factors mentioning H
 - Eliminate (sum out) H
- Join all remaining factors and normalize

x	p(x)
-3	0.05
-1	0.25
0	0.07
1	0.2
5	0.01



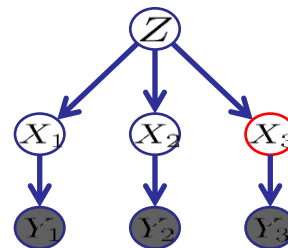
$$f \times g = h \times \frac{1}{Z}$$

Another Variable Elimination Example

Query: $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$

Start by inserting evidence, which gives the following initial factors:

$$p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$$



What variables could we eliminate?

Another Variable Elimination Example

Query: $P(X_3 | Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$

Start by inserting evidence, which gives the following initial factors:

$$p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$$

Eliminate X_1 , this introduces the factor $f_1(Z, y_1) = \sum_{x_1} p(x_1|Z)p(y_1|x_1)$, and we are left with:

$$p(Z)f_1(Z, y_1)p(X_2|Z)p(X_3|Z)p(y_2|X_2)p(y_3|X_3)$$

Eliminate X_2 , this introduces the factor $f_2(Z, y_2) = \sum_{x_2} p(x_2|Z)p(y_2|x_2)$, and we are left with:

$$p(Z)f_1(Z, y_1)f_2(Z, y_2)p(X_3|Z)p(y_3|X_3)$$

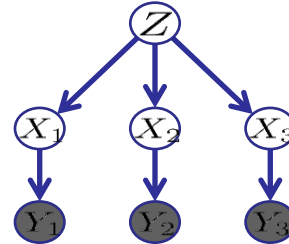
Eliminate Z , this introduces the factor $f_3(y_1, y_2, X_3) = \sum_z p(z)f_1(z, y_1)f_2(z, y_2)p(X_3|z)$, and we are left:

$$p(y_3|X_3), f_3(y_1, y_2, X_3)$$

No hidden variables left. Join the remaining factors to get:

$$f_4(y_1, y_2, y_3, X_3) = P(y_3|X_3)f_3(y_1, y_2, X_3).$$

Normalizing over X_3 gives $P(X_3|y_1, y_2, y_3)$.



What dimension are f_1, f_2 & f_3 ?

1

Another Variable Elimination Example

Query: $P(X_3 | Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$

Start by inserting evidence, which gives the following initial factors:

$$p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$$

Alternatively, suppose we start by eliminating Z :

$$P(X_1 | Z)$$

$$P(X_2 | Z)$$

$$P(X_3 | Z)$$

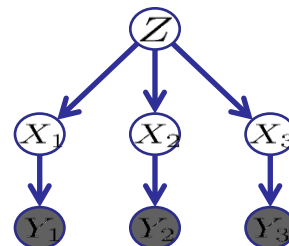


$$f_Z(X_1, X_2, X_3)$$

$$p(y_1 | X_1)$$

$$p(y_2 | X_2)$$

$$p(y_3 | X_3)$$



What is the resulting factor?

What dimension is it? 3

How many entries? k^3

Another Variable Elimination Example

Query: $P(X_3|Y_1 = y_1, Y_2 = y_2, Y_3 = y_3)$

Start by inserting evidence, which gives the following initial factors:

$$p(Z)p(X_1|Z)p(X_2|Z)p(X_3|Z)p(y_1|X_1)p(y_2|X_2)p(y_3|X_3)$$

Eliminate X_1 , this introduces the factor $f_1(Z, y_1) = \sum_{x_1} p(x_1|Z)p(y_1|x_1)$, and we are left with:

$$p(Z)f_1(Z, y_1)p(X_2|Z)p(X_3|Z)p(y_2|X_2)p(y_3|X_3)$$

Eliminate X_2 , this introduces the factor $f_2(Z, y_2) = \sum_{x_2} p(x_2|Z)p(y_2|x_2)$, and we are left with:

$$p(Z)f_1(Z, y_1)f_2(Z, y_2)p(X_3|Z)p(y_3|X_3)$$

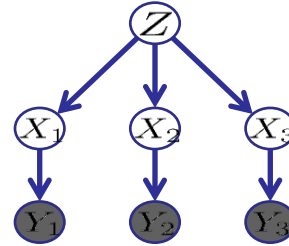
Eliminate Z , this introduces the factor $f_3(y_1, y_2, X_3) = \sum_z p(z)f_1(z, y_1)f_2(z, y_2)p(X_3|z)$, and we are left:

$$p(y_3|X_3), f_3(y_1, y_2, X_3)$$

No hidden variables left. Join the remaining factors to get:

$$f_4(y_1, y_2, y_3, X_3) = P(y_3|X_3)f_3(y_1, y_2, X_3).$$

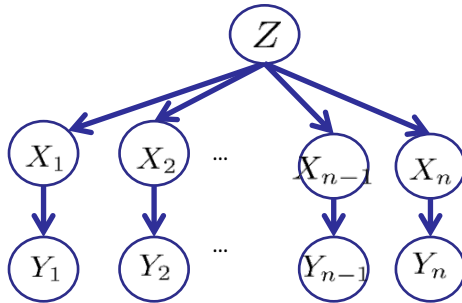
Normalizing over X_3 gives $P(X_3|y_1, y_2, y_3)$.



Computational complexity depends on the **largest factor** generated by the process.
Size of factor = number of entries in table.

Variable Elimination Ordering

- For the query $P(X_n|y_1, \dots, y_n)$ work through the following two different orderings as done in previous slide: Z, X_1, \dots, X_{n-1} and X_1, \dots, X_{n-1}, Z . What is the size of the maximum factor generated for each of the orderings?



- Answer: 2^{n+1} versus 2^2 (assuming binary)
- In general: the ordering can **greatly** affect efficiency.

VE: Computational and Space Complexity

- The computational and space complexity of variable elimination is determined by the largest factor
- The elimination ordering can greatly affect the size of the largest factor.
 - E.g., previous slide's example 2^n vs. 2
- Does there always exist an ordering that only results in small factors?
 - **No!**

Worst Case Complexity?

- CSP:

$$(x_1 \vee x_2 \vee \neg x_3) \wedge (\neg x_1 \vee x_3 \vee \neg x_4) \wedge (x_2 \vee \neg x_2 \vee x_4) \wedge (\neg x_3 \vee \neg x_4 \vee \neg x_5) \wedge (x_2 \vee x_5 \vee x_7) \wedge (x_4 \vee x_5 \vee x_6) \wedge (\neg x_5 \vee x_6 \vee \neg x_7) \wedge (\neg x_5 \vee \neg x_6 \vee x_7)$$

$$P(X_i = 0) = P(X_i = 1) = 0.5$$

$$Y_1 = X_1 \vee X_2 \vee \neg X_3$$

...

$$Y_8 = \neg X_5 \vee X_6 \vee X_7$$

$$Y_{1,2} = Y_1 \wedge Y_2$$

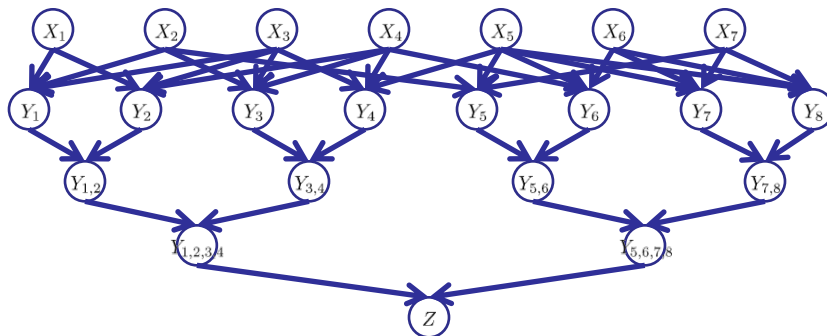
...

$$Y_{7,8} = Y_7 \wedge Y_8$$

$$Y_{1,2,3,4} = Y_{1,2} \wedge Y_{3,4}$$

$$Y_{5,6,7,8} = Y_{5,6} \wedge Y_{7,8}$$

$$Z = Y_{1,2,3,4} \wedge Y_{5,6,7,8}$$



- If we can answer $P(z)$ equal to zero or not, we answered whether the 3-SAT problem has a solution.
- Hence inference in Bayes' nets is NP-hard. No known efficient probabilistic inference in general.

Polytrees

- A **polytree** is a directed graph *with no undirected cycles*
- For poly-trees you can always find an ordering that is efficient
 - Try it!!
- Cut-set conditioning for Bayes' net inference
 - Choose set of variables such that if removed only a polytree remains
 - Exercise: Think about how the specifics would work out!

Bayes' Nets

- ✓ Representation
- ✓ Conditional Independences
- Probabilistic Inference
 - ✓ Enumeration (exact, exponential complexity)
 - ✓ Variable elimination (exact, worst-case exponential complexity, often better)
 - ✓ Inference is NP-complete
 - Sampling (approximate)
- Learning Bayes' Nets from Data