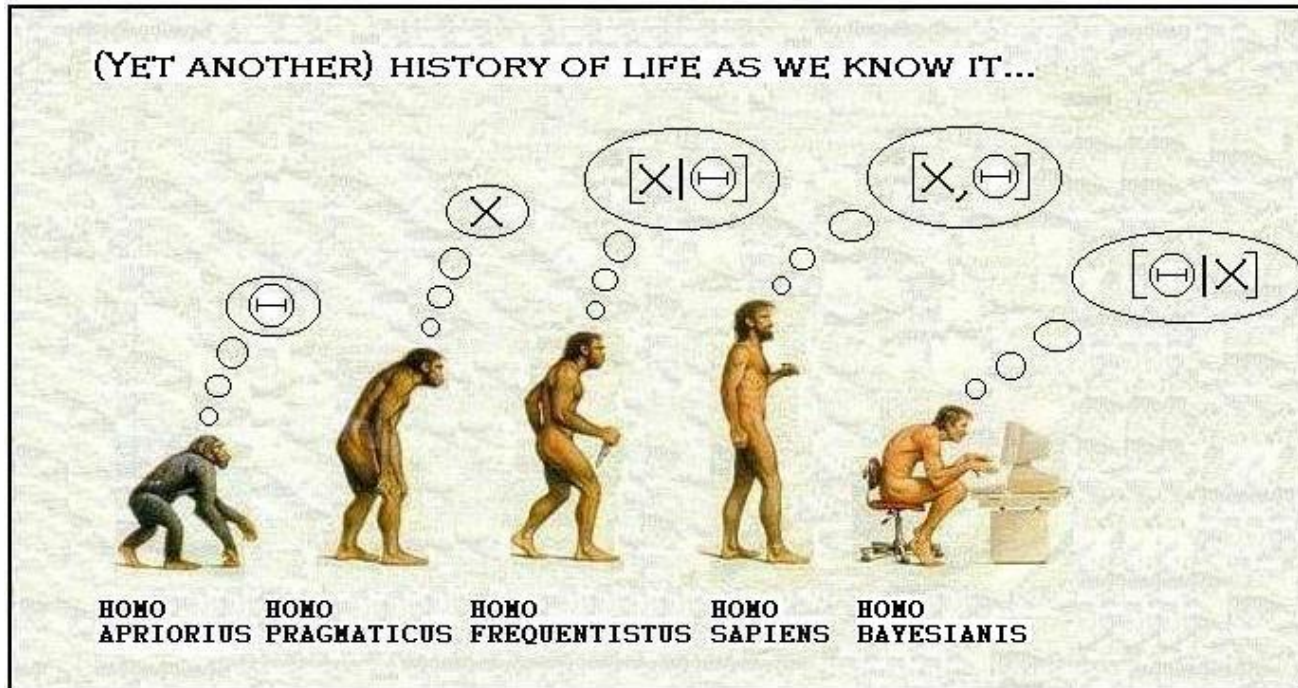


CSE 473

Lecture 21 (Chapter 14)

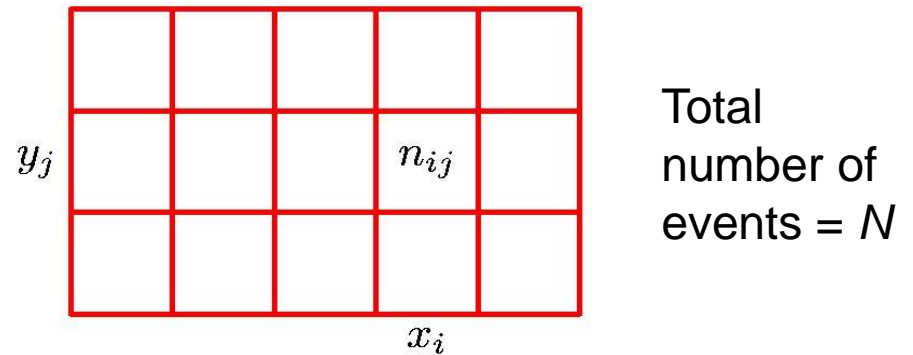
Bayesian Networks



(Courtesy Mike West)

Joint Probability

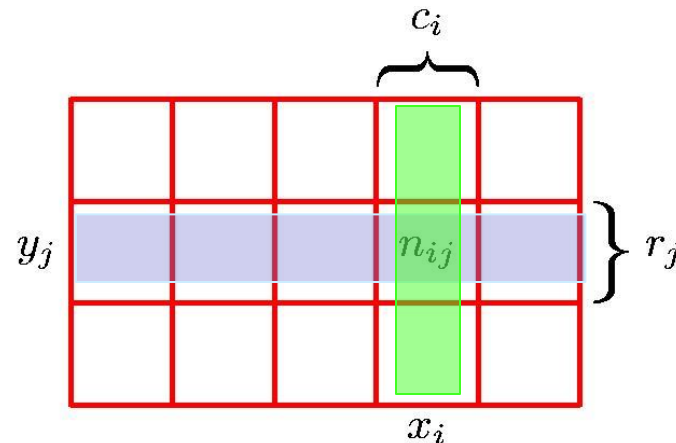
$$p(X = x_i, Y = y_j) = \frac{n_{ij}}{N}$$



Marginal Probability

$$P(X = x_i) = \sum_j P(x_i, y_j) = \frac{c_i}{N}$$

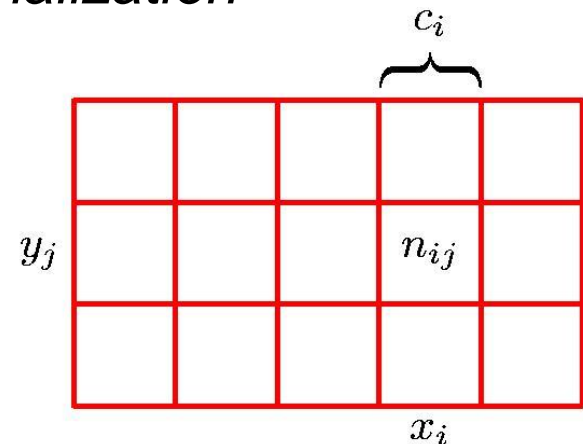
$$P(Y = y_j) = \sum_i P(x_i, y_j) = \frac{r_j}{N}$$



Summing out a variable is called *marginalization*

Conditional Probability

$$p(Y = y_j | X = x_i) = \frac{n_{ij}}{c_i}$$

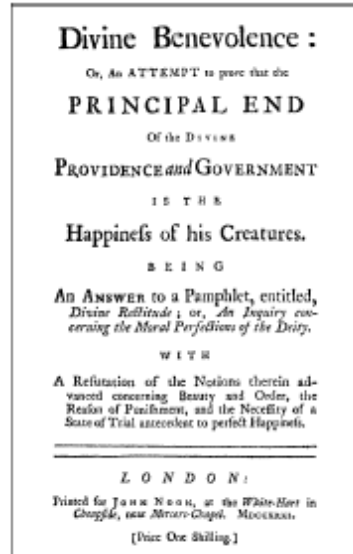


Thomas Bayes

Reverend Thomas Bayes
Nonconformist minister
(1702-1761)



- Publications:
- *Divine Benevolence, or an Attempt to Prove That the Principal End of the Divine Providence and Government is the Happiness of His Creatures* (1731)
- *An Introduction to the Doctrine of Fluxions* (1736)
- *An Essay Towards Solving a Problem in the Doctrine of Chances* (1764)



Start with Definition of Conditional Probability

$$P(x | y) = \frac{P(x, y)}{P(y)}$$

$$P(y | x) = \frac{P(y, x)}{P(x)} = \frac{P(x, y)}{P(x)}$$



Therefore?

Bayes' Rule

$$P(x, y) = P(x | y)P(y) = P(y | x)P(x)$$

i.e.

$$P(x | y) = \frac{P(y | x) P(x)}{P(y)}$$

What is this useful for?

$$P(Cause | Effect) = \frac{P(Effect | Cause) P(Cause)}{P(Effect)}$$

Bayes' rule is used to Compute Diagnostic Probability from Causal Probability

$$P(\text{Cause}|\text{Effect}) = \frac{P(\text{Effect}|\text{Cause})P(\text{Cause})}{P(\text{Effect})}$$

E.g. let M be meningitis, S be stiff neck

$$P(M) = 0.0001,$$

$$P(S) = 0.1,$$

$$P(S|M) = 0.8 \quad (\text{note: these can be estimated from patients})$$

$$P(M|S) = \frac{P(S|M)P(M)}{P(S)} = \frac{0.8 \times 0.0001}{0.1} = 0.0008$$

Note: posterior probability of meningitis still very small!

(But chance of M did increase from 0.0001 to 0.0008 given stiff neck)

Normalization in Bayes' Rule

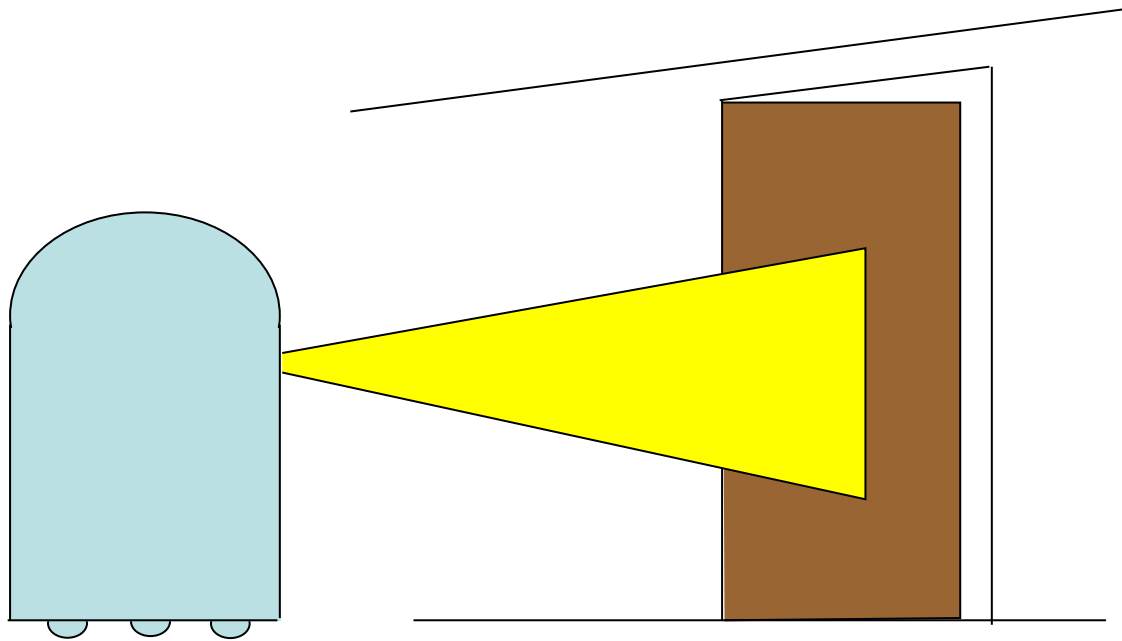
$$P(x | y) = \frac{P(y | x) P(x)}{P(y)} = \alpha P(y | x) P(x)$$

$$\alpha = \frac{1}{P(y)} =$$

α is called the normalization constant
(can be calculated by **summing over numerator values**)

Bayes Example 1: State Estimation

- Suppose a robot obtains measurement z
- What is $P(\text{doorOpen}/z)$?
- Use Bayes' rule!



Causal vs. Diagnostic Reasoning

- $P(open|z)$ is **diagnostic**.
- $P(z|open)$ is **causal**.
- Often **causal** knowledge is easier to obtain. count frequencies!
- Bayes rule allows us to use causal knowledge to diagnose a situation:

$$P(open | z) = \frac{P(z | open)P(open)}{P(z)}$$

State Estimation Example

- *Suppose: $P(z/open) = 0.6$ $P(z/\neg open) = 0.3$*
- *$P(open) = P(\neg open) = 0.5$*
- *$P(open/z) = ?$*

$$P(open | z) = \frac{P(z | open)P(open)}{P(z | open)p(open) + P(z | \neg open)p(\neg open)}$$

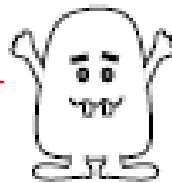
$$P(open | z) = \frac{0.6 \cdot 0.5}{0.6 \cdot 0.5 + 0.3 \cdot 0.5} = \frac{0.30}{0.45} = 0.67$$

Measurement z raises the probability that the door is open from 0.5 to 0.67

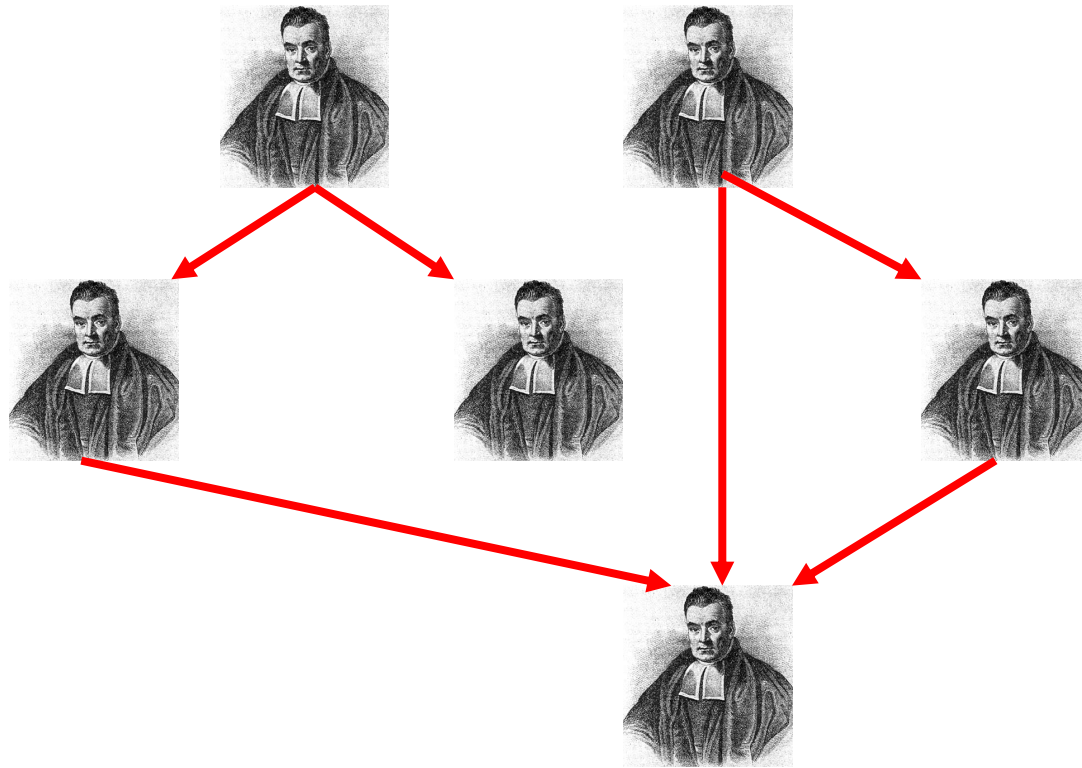
Is there a general representation scheme for efficient probabilistic inference?



Yes!



Enter...Bayesian networks

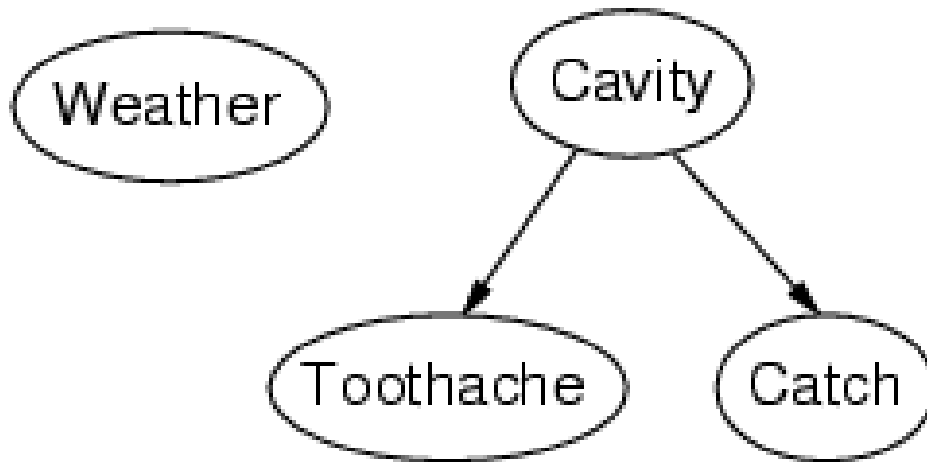


What are Bayesian networks?

- Simple, graphical notation for conditional independence assertions
 - Allows compact specification of full joint distributions

Example: Back at the Dentist's

- Topology of network encodes conditional independence assertions:



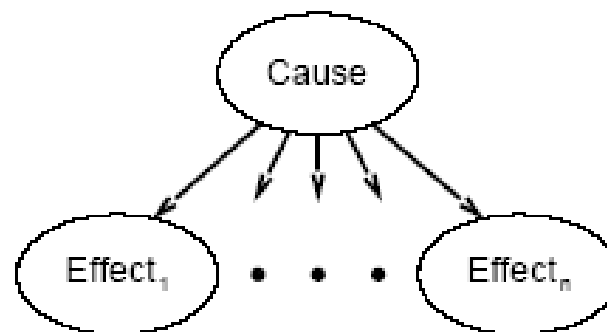
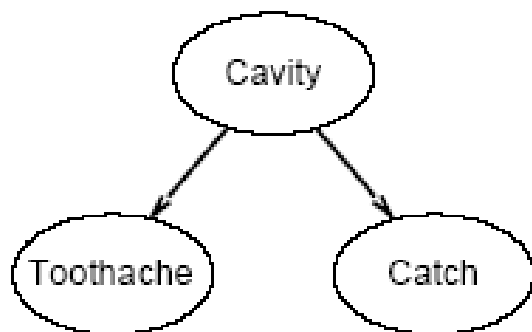
- *Weather* is independent of the other variables
- *Toothache* and *Catch* are conditionally independent of each other **given *Cavity***

Conditional Independence and the “Naïve Bayes Model”

$$\begin{aligned} & \mathbf{P}(Cavity|toothache \wedge catch) \\ &= \alpha \mathbf{P}(toothache \wedge catch|Cavity)\mathbf{P}(Cavity) \\ &= \alpha \mathbf{P}(toothache|Cavity)\mathbf{P}(catch|Cavity)\mathbf{P}(Cavity) \end{aligned}$$

This is an example of a *naive Bayes* model:

$$\mathbf{P}(Cause, Effect_1, \dots, Effect_n) = \mathbf{P}(Cause)\prod_i \mathbf{P}(Effect_i|Cause)$$



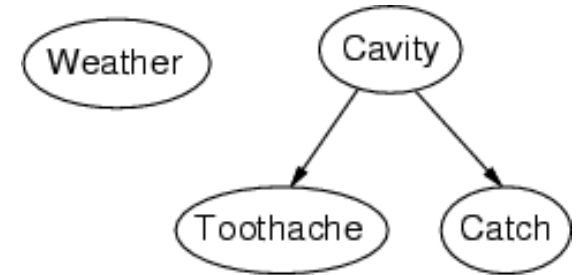
Total number of parameters is *linear* in n

Bayesian networks

Syntax:

- set of nodes, one per random variable
- directed, acyclic graph (link \approx "directly influences")
- conditional distribution for each node given its parents:

$$P(X_i | \text{Parents}(X_i))$$



- For discrete variables X_i , conditional distribution = conditional probability table (CPT) = probabilities for X_i given each combination of parent values

Example 2: Burglars and Earthquakes

- You are at a “Done with the AI class” party.
- Neighbor John calls to say your home alarm has gone off (but neighbor Mary doesn't).
- Sometimes your alarm is set off by minor earthquakes.
- Question: Is your home being burglarized?

Next Time

- Bayesian Networks for Burglary Detection and More!
- Inference Algorithms
 - Variable Elimination (VE)
- Hidden Markov Models
- To Do:
 - Project 3 due Sunday before midnight



Bayes
rules!