Knowledge Representation IV Inference for First-Order Logic

CSE 473

FOL Reasoning

 Basics of FOL reasoning
 Classes of FOL reasoning methods Forward & Backward Chaining

Resolution Compilation to SAT









Unification

- Match up expressions by finding variable values that make the expressions identical Variables denoted 2x
- Unify(x, y) returns "mgu" Unify(city(?a), city(kent)) returns {?a/kent}

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    Substitute(expr, mapping) returns new expr
Substitute(connected(?a, ?b), {?a/kent})
returns connected(kent, ?b)
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Unification Examples I

- Unify(road(?a, kent), road(seattle, ?b)) Unification ok Returns {?a / seattle, ?b / kent} When substituted in both expressions, they match. Each is (road(seattle, kent))
- Unify(road(?a, ?a), road(seattle, kent)) Impossible: ?a can't be seattle and kent at the same time!

Unification Examples II

- Unify(f(g(?x, dog), ?y)), f(g(cat, ?y), dog) {?x / cat, ?y / dog}
- Unify(f(g(?x)), f(?x)) They don't unify: no substitution makes them the same. E.g. consider: {?x / g(?x) }
- We get f(g(g(?x))) and f(g(?x)) ... not equal! • Thus: A variable value may not *contain* itself
- Directly or indirectly

Unification Examples III

Unify(f(g(cat, dog), ?y)), f(?x), dog)
 {?x / g(cat, dog), ?y / dog}
 Unify(f(g(?y)), f(?x))
 {?x / g(?y), ?y / ?y}

Back to fuzzy monkeys: Fuzzy(x) ^ Monkey(x) → Curious(x) Fuzzy(George) ^ Monkey(George) Curious(George)

Unify and then use modus ponens = generalized modus ponens

Inference I: Forward Chaining • Given: Prove: ∀x Monkey(x) ^ Fuzzy(x) → Curious(x) ∀y Fuzzy(y) Monkey(George) Curious(George) • The algorithm: Start with the KB Add any fact you can generate with GMP Repeat until: goal reached or generation halts. • Sound? Complete? Decidable? • Speed concerns? Unification; premise rechecking; irrelevant fact gen.

Inference II: Backward Chaining

Given: Prove: ∀x Monkey(x) ^ Fuzzy(x) → Curious(x) ∀y Fuzzy(y) Monkey(George) Curious(George) The algorithm: Start with KB and goal. Find all rules whose results unify with the goal: Add the bodies of these rules to the goal list Remove the corresponding result from the goal list Stop when: Goal list is empty (SUCCEED) Progress halts (FAIL)





First-Order Resolution

• Answers: Is it the case that $\Sigma \models \Phi$?

Method

- Let S = KB $\land \neg$ goal
- Convert S to clausal form
- Standardize variables
- Move quantifiers to front, skolemize to remove \exists
- $\boldsymbol{\cdot} \ \textbf{Replace} \Rightarrow \textbf{with} \lor \textbf{and} \neg$
- Demorgan's laws to get CNF (ands-of-ors) Resolve S goal until get empty clause

First-Order Resolution Example

• Given

∀?x man(?x) => human(?x) ∀?x woman(?x) => human(?x) ∀?x prof(?x) => man(?x) ∨ woman(?x) prof(dieter)

• Prove

human(dieter)

 $[\neg m(?x),h(?x)]$ $[\neg w(?y), h(?y)]$ $[\neg p(?z),m(?z),w(?z)]$ $[p(d)][\neg h(d)]$





Inference IV: Compilation to Prop. Logic • Sentence S: ∀_{city} a,b connected(a,b) • Universe Cities: seattle, tacoma, enumclaw • Equivalent propositional formula:

 $Cst \land Cse \land Cts \land Cte \land Ces \land Cet$

Compilation to Prop. Logic (cont)

- Sentence S:
 - $\exists_{city} c biggest(c)$
- Universe
 - Cities: seattle, tacoma, enumclaw
- Equivalent propositional formula:

Bs \lor Bt \lor Be



Hey!

- You said FO Inference is semi-decidable
- But you compiled it to SAT Which is NP Complete
- So now we can always do the inference?!? Tho it might take exponential time...

Something seems wrong here?????

Compilation to Prop. Logic (cont for the last time) • Universe • People: homer, bart, marge • First-Order formula ∀_{people} p Male(FatherOf(p)) • Equivalent propositional formula

[(Mfather-homer ^ Mfather-bart ^ Mfather-marge ^ (Mfather-father-homer ^ Mfather-father-bart ^ ... (Mfather-father-father-homer ^]

Restricted Forms of FO Logic

- Known, Finite Universes Compile to SAT
- Frame Systems
- Ban certain types of expressions
- Horn Clauses (at most one negative literal) Aka Prolog
- Function-Free Horn Clauses Aka Datalog



Back To the Wumpus World

- "Squares next to pits are breezy":
 ∀x, y, a, b:
 Pit([x, y]) ^ Adjacent([x, y], [a, b]) → Breezy([a, b])
- "Breezes happen only and always next to pits" ∀a,b Breezy([a, b]) <=> ∃ x,y Pit([x, y]) ^ Adjacent([x, y], [a, b])

Back To the Wumpus World • Given:

∀a,b Breezy([a, b]) <=> ∃ x,y Pit([x, y]) ^ Adjacent([x, y], [a, b])

Breezy([1,2])

 Prove: Pit([3,2]) v Pit([2,2])



What About Our Agent? Still don't know how to deal with time Still don't know how to go from knowledge of the world to *action* in the world → Planning