## Constraint Satisfaction

CSE 473 University of Washington

### Today: Constraint Satisfaction Problems

- Definition Factoring state spaces
- Variable-ordering heuristics
- Backtracking policies
- Preprocessing algorithms

## **Constraint Satisfaction**

- Kind of *search* in which States are *factored* into sets of variables Search = assigning values to these variables Structure of space is encoded with constraints
- Backtracking-style algorithms work E.g. DFS for SAT (i.e. DPLL)
- But other techniques add speed Propagation Variable ordering
  - Preprocessing



## Chinese Food as Search

#### States?

Partially specified meals

#### Operators?

- Add, remove, change dishes
- Start state?
  - Null meal

Suppose every meal for n people has n dishes plus soup

#### Goal states?

 Meal meeting certain conditions Two non-peanut dishes, with at least one of the others non-spicy.

## Factoring States

• Break the state into its independent components:

State = (dish1, ... dishN, soup)

#### Becomes variables:

Soup = Dish 1 = Dish 2 =

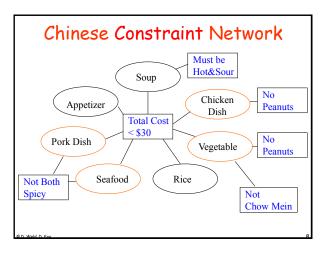
Dish n =

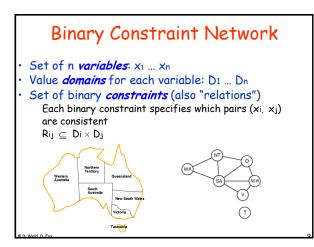
## Factoring States

- Encode the structure of the problem as constraints
- Often this structure is the description of the goal state:

Goal condition = "Two peanut-free dishes; of the others, at least one must be non-spicy"

How to express this as constraints?





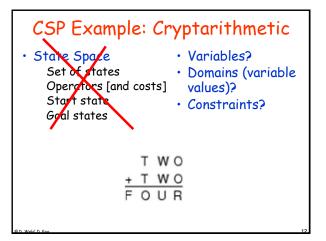
### **Binary Constraint Network**

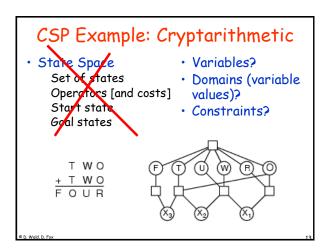
Partial *assignment* of values = tuple of pairs {...(x, a)...} means variable x gets value a... Tuple=*consistent* if all constraints satisfied Tuple=*full solution* if consistent + has all vars

Tuple {(xi, ai) ... (xj, aj)} = *consistent w/ a set of vars* {xm ... xn} iff ∃ am ... an such that {(xi, ai)...(xj, aj), (xm, am)...(xn, an)} } = consistent

### CSPs in the Real World

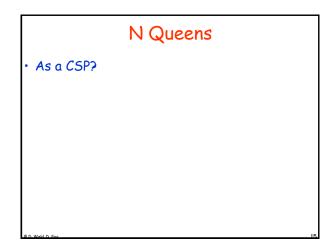
- · Scheduling space shuttle repair
- Airport gate assignments
- Transportation Planning
- Supply-chain management
- Computer configuration
- Diagnosis
- UI optimization
- Etc...

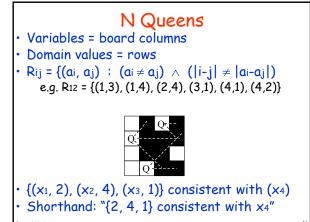


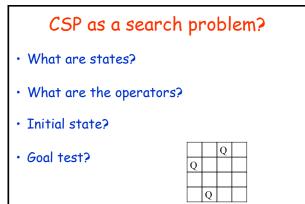


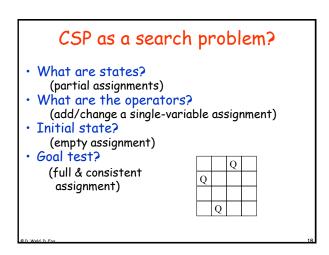
## CSP Example: Classroom Scheduling

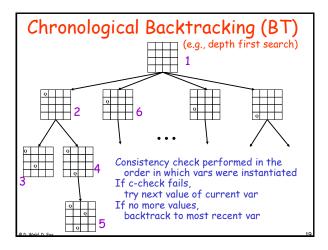
- Variables?
- Domains (possible values for variables)?
- · Constraints?

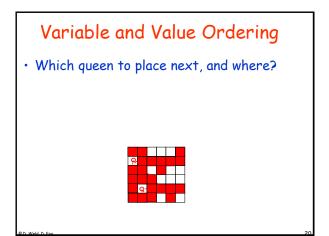


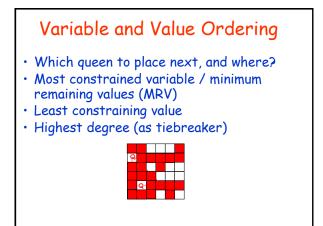












## Backjumping (BJ) Similar to BT, but more efficient when no consistent instantiation can be found for the current var Instead of backtracking to most recent var... BJ reverts to deepest var which was c-checked

BJ reverts to deepest var which was c-checked against the current var

BJ Discovers (2, 5, 3, 6) inconsistent with  $x_6$ No sense trying other values of  $x_5$ Backtrack to  $x_4$  and try a new placement

## Forward Checking (FC)

- Perform Consistency Check Forward
- Whenever a var is assigned a value Prune inconsistent values from As-yet unvisited variables

Backtrack if domain of any var ever collapses

FC can't detect that (2, 5, 3) inconsistent with {x₅, x₀} → Arc consistency can fix this



# CSP Summary

 CSPs are a special kind of problem states defined by values of a fixed set of variables

goal test defined by *constraints* on variable values

- Forward checking prevents assignments that guarantee later failure
- Variable ordering and value selection heuristics help significantly
- Complexity depends on constraint graph: linear time if tree structured