

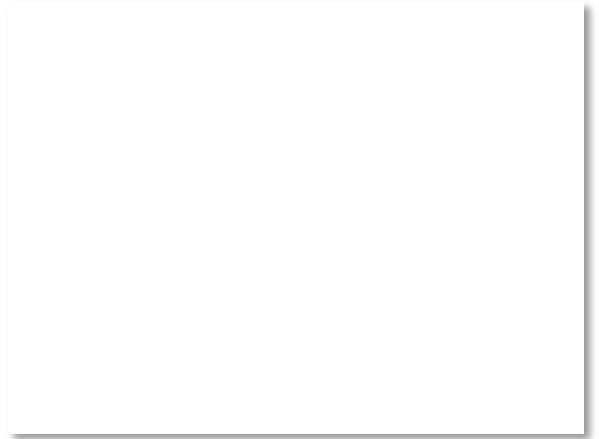
Hamming Code

- Gives a method for constructing a code with a distance of 3
 - Uses $n = 2^k - k - 1$, e.g., $n=4, k=3$
 - Put check bits in positions p that are powers of 2, starting with position 1
 - Check bit in position p is parity of positions with a p term in their values
- Plus an easy way to correct [soon]

Hamming Code (2)

- Example: data=0101, 3 check bits
 - 7 bit code, check bit positions 1, 2, 4
 - Check 1 covers positions 1, 3, 5, 7
 - Check 2 covers positions 2, 3, 6, 7
 - Check 4 covers positions 4, 5, 6, 7

1 2 3 4 5 6 7



Hamming Code (3)

- Example: data=0101, 3 check bits
 - 7 bit code, check bit positions 1, 2, 4
 - Check 1 covers positions 1, 3, 5, 7
 - Check 2 covers positions 2, 3, 6, 7
 - Check 4 covers positions 4, 5, 6, 7

0 1 0 0 1 0 1 →
1 2 3 4 5 6 7

$$p_1 = 0+1+1 = 0, \quad p_2 = 0+0+1 = 1, \quad p_4 = 1+0+1 = 0$$

Hamming Code (4)

- To decode:
 - Recompute check bits (with parity sum including the check bit)
 - Arrange as a binary number
 - Value (syndrome) tells error position
 - Value of zero means no error
 - Otherwise, flip bit to correct

Hamming Code (5)

- Example, continued

→ 0 1 0 0 1 0 1
1 2 3 4 5 6 7

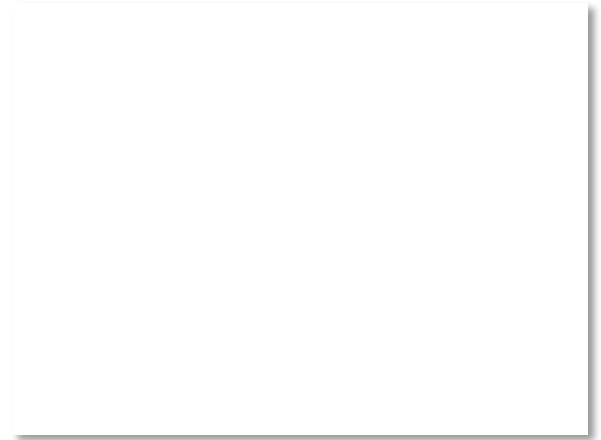
$p_1 =$

$p_2 =$

$p_4 =$

Syndrome =

Data =



Hamming Code (6)

- Example, continued

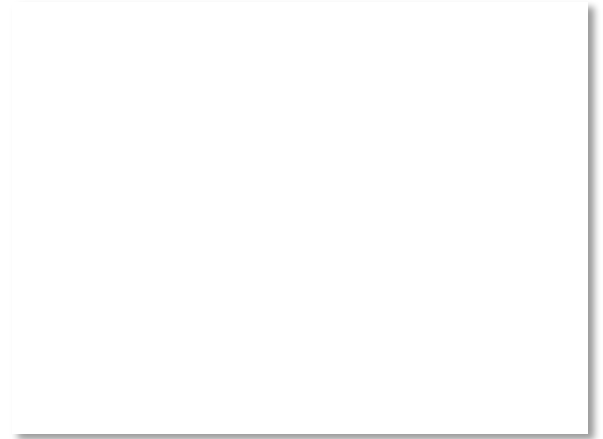
→ 0 1 0 0 1 0 1
1 2 3 4 5 6 7

$$p_1 = 0 + 0 + 1 + 1 = 0, \quad p_2 = 1 + 0 + 0 + 1 = 0,$$

$$p_4 = 0 + 1 + 0 + 1 = 0$$

Syndrome = 000, no error

Data = 0 1 0 1



Hamming Code (7)

- Example, continued

→ 0 1 0 0 1 1 1
1 2 3 4 5 6 7

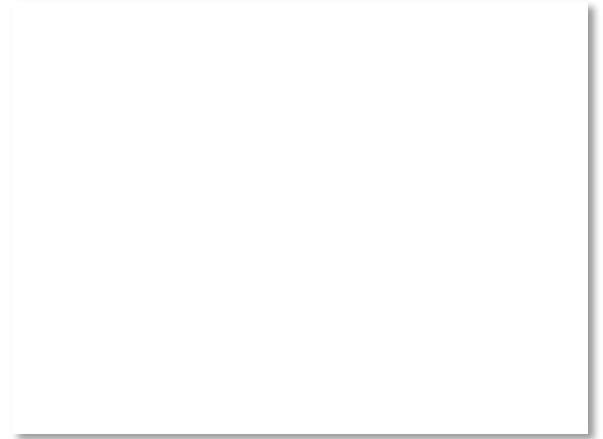
$p_1 =$

$p_2 =$

$p_4 =$

Syndrome =

Data =



Hamming Code (8)

- Example, continued

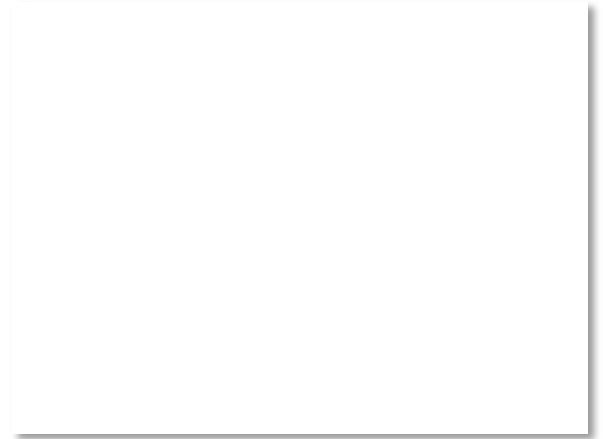
→ $\underline{0}$ $\underline{1}$ 0 $\underline{0}$ 1 1 1
1 2 3 4 5 6 7

$$p_1 = 0 + 0 + 1 + 1 = 0, \quad p_2 = 1 + 0 + 1 + 1 = 1,$$

$$p_4 = 0 + 1 + 1 + 1 = 1$$

Syndrome = 1 1 0, flip position 6

Data = 0 1 0 1 (correct after flip!)



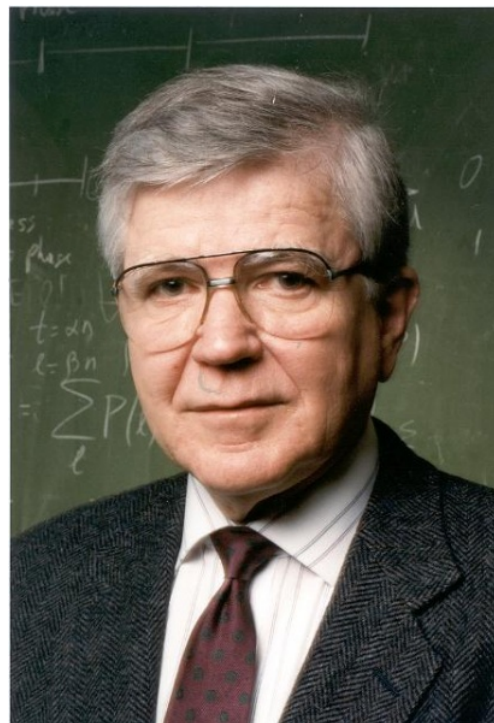
Other Error Correction Codes

- Codes used in practice are much more involved than Hamming
- Convolutional codes (§3.2.3)
 - Take a stream of data and output a mix of the recent input bits
 - Makes each output bit less fragile
 - Decode using Viterbi algorithm (which can use bit confidence values)



Other Codes (2) – LDPC

- Low Density Parity Check (§3.2.3)
 - LDPC based on sparse matrices
 - Decoded iteratively using a belief propagation algorithm
 - State of the art today
- Invented by Robert Gallager in 1963 as part of his PhD thesis
 - Promptly forgotten until 1996 ...



Source: IEEE GHN, © 2009 IEEE

Detection vs. Correction

- Which is better will depend on the pattern of errors. For example:
 - 1000 bit messages with a bit error rate (BER) of 1 in 10000
- Which has less overhead?

Detection vs. Correction

- Which is better will depend on the pattern of errors. For example:
 - 1000 bit messages with a bit error rate (BER) of 1 in 10000
- Which has less overhead?
 - It still depends! We need to know more about the errors

Detection vs. Correction (2)

1. Assume bit errors are random
 - Messages have 0 or maybe 1 error
- Error correction:
 - Need ~ 10 check bits per message
 - Overhead:
- Error detection:
 - Need ~ 1 check bits per message plus 1000 bit retransmission 1/10 of the time
 - Overhead:

Detection vs. Correction (3)

2. Assume errors come in bursts of 100
 - Only 1 or 2 messages in 1000 have errors
- Error correction:
 - Need $\gg 100$ check bits per message
 - Overhead:
- Error detection:
 - Need 32? check bits per message plus 1000 bit resend 2/1000 of the time
 - Overhead:

Detection vs. Correction (4)

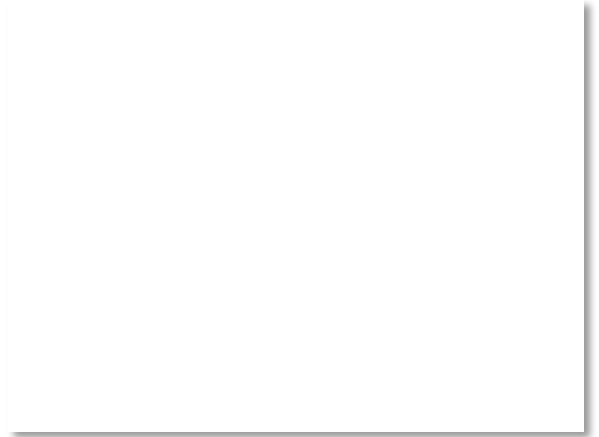
- Error correction:
 - Needed when errors are expected
 - Or when no time for retransmission
- Error detection:
 - More efficient when errors are not expected
 - And when errors are large when they do occur

Error Correction in Practice

- Heavily used in physical layer
 - LDPC is the future, used for demanding links like 802.11, DVB, WiMAX, LTE, power-line, ...
 - Convolutional codes widely used in practice
- Error detection (w/ retransmission) is used in the link layer and above for residual errors
- Correction also used in the application layer
 - Called Forward Error Correction (FEC)
 - Normally with an erasure error model
 - E.g., Reed-Solomon (CDs, DVDs, etc.)

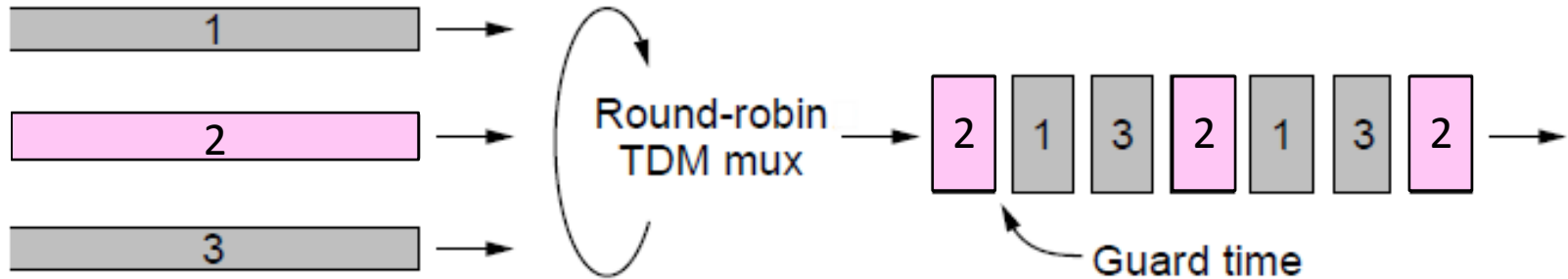
Topic

- Multiplexing is the network word for the sharing of a resource
- Classic scenario is sharing a link among different users
 - Time Division Multiplexing (TDM) »
 - Frequency Division Multiplexing (FDM) »



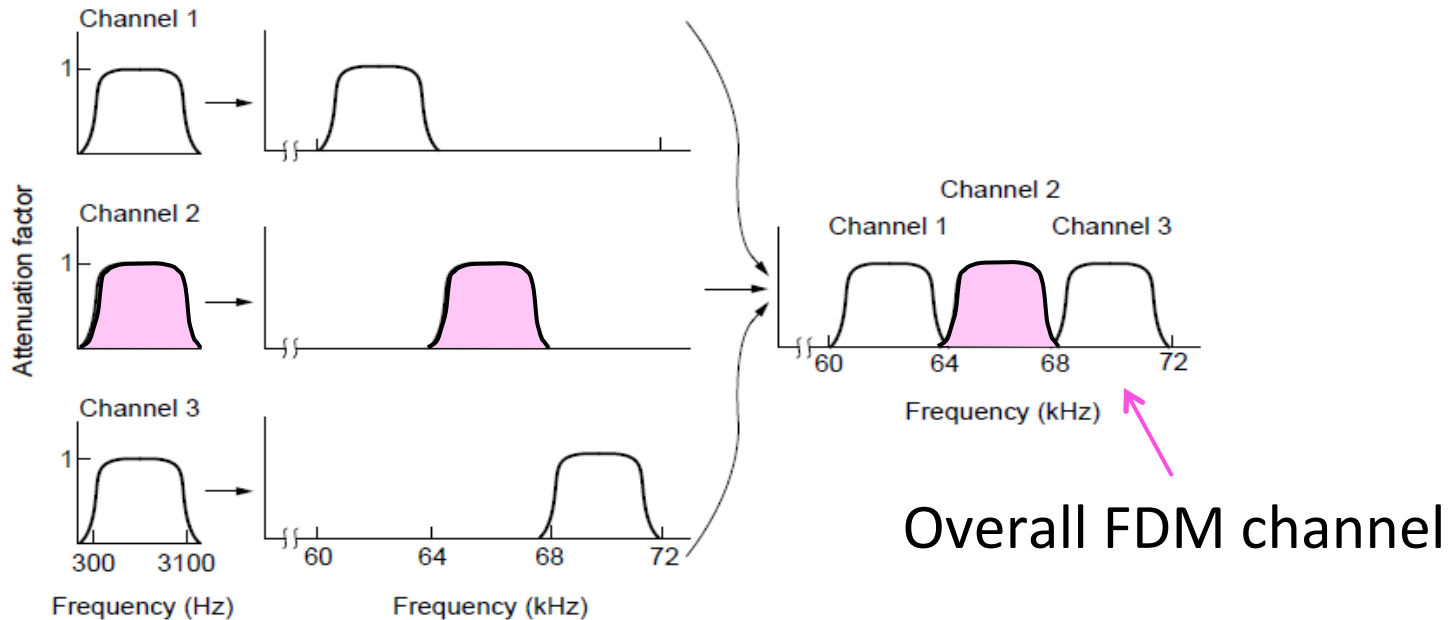
Time Division Multiplexing (TDM)

- Users take turns on a fixed schedule



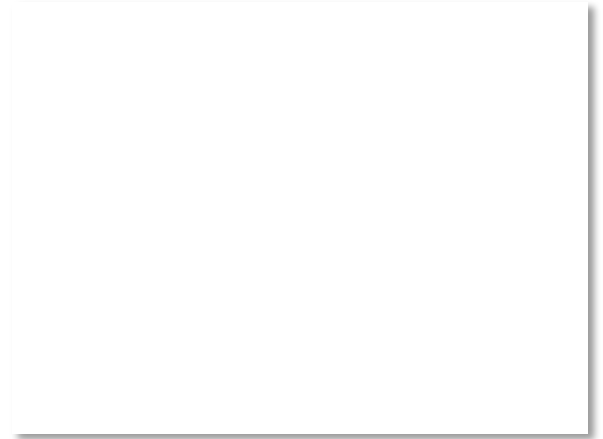
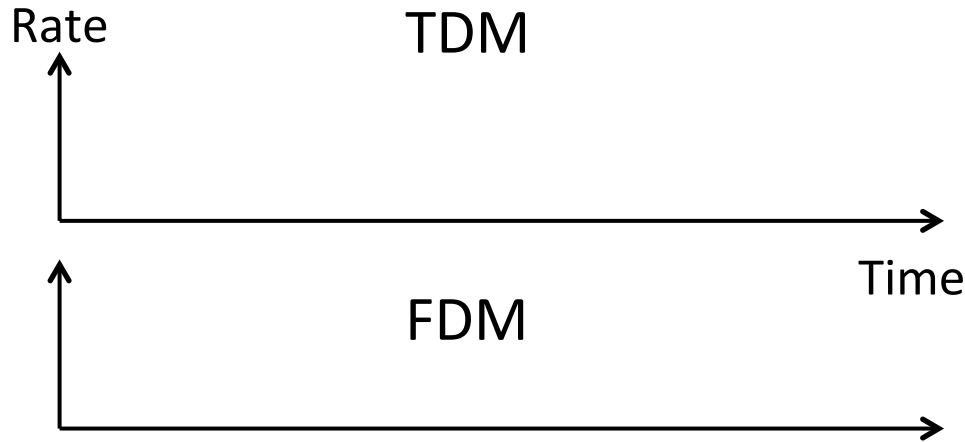
Frequency Division Multiplexing (FDM)

- Put different users on different frequency bands



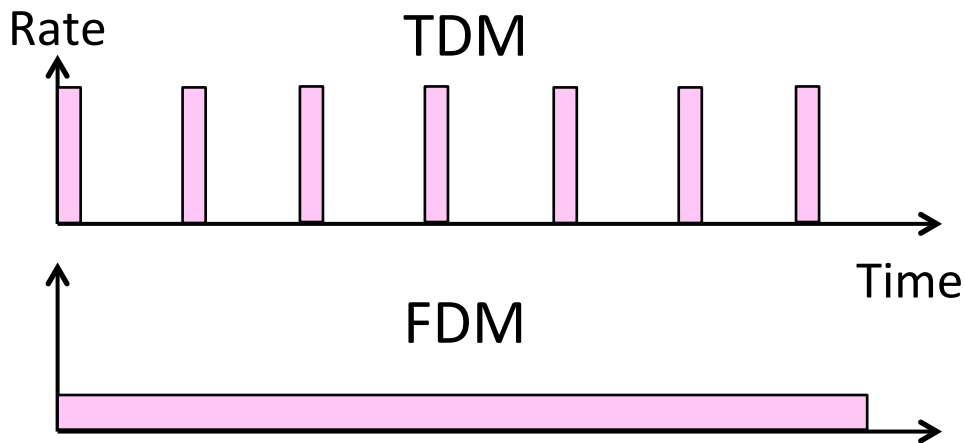
TDM versus FDM

- In TDM a user sends at a high rate a fraction of the time; in FDM, a user sends at a low rate all the time



TDM versus FDM (2)

- In TDM a user sends at a high rate a fraction of the time; in FDM, a user sends at a low rate all the time



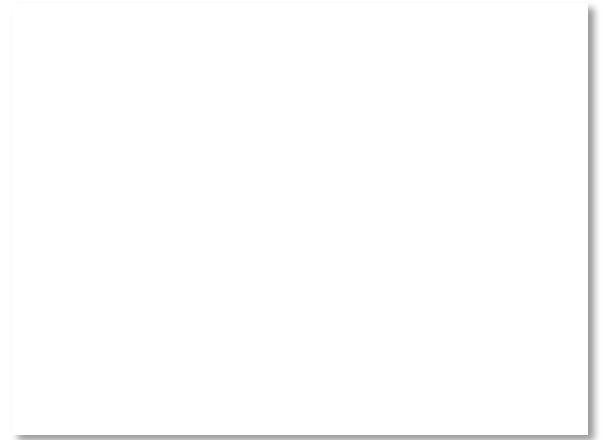
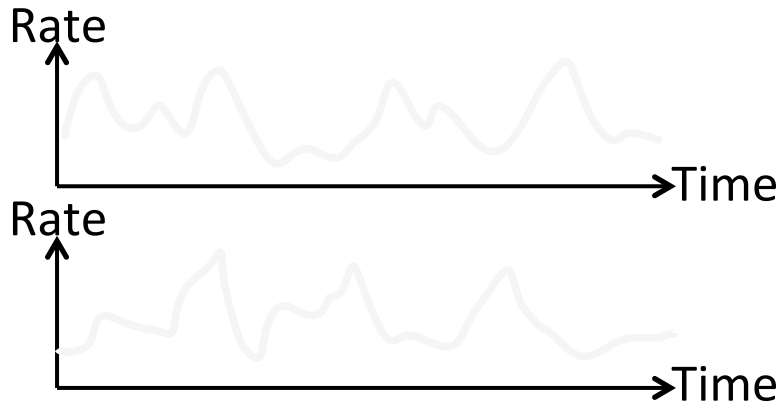
TDM/FDM Usage

- Statically divide a resource
 - Suited for continuous traffic, fixed number of users
- Widely used in telecommunications
 - TV and radio stations (FDM)
 - GSM (2G cellular) allocates calls using TDM within FDM



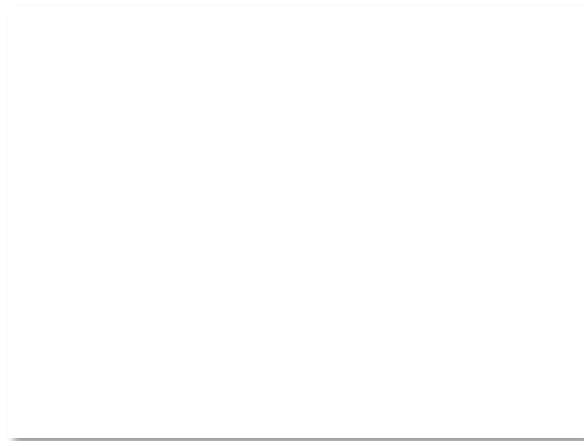
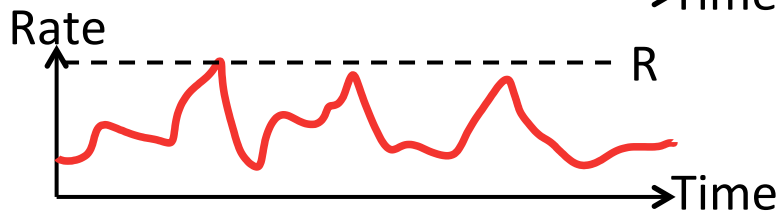
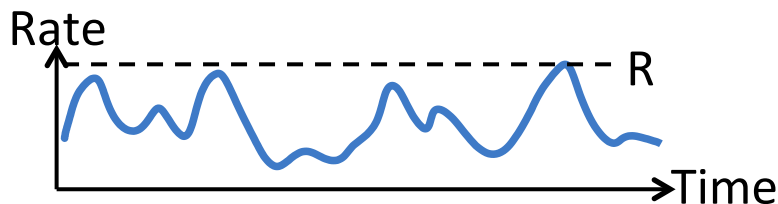
Multiplexing Network Traffic

- Network traffic is bursty
 - ON/OFF sources
 - Load varies greatly over time



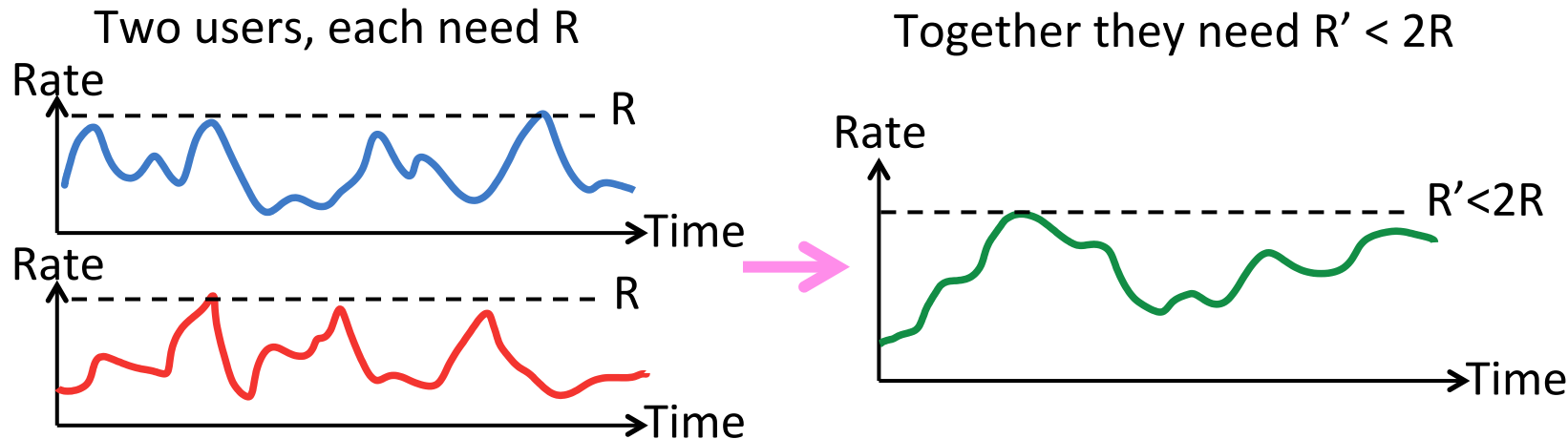
Multiplexing Network Traffic (2)

- Network traffic is bursty
 - Inefficient to always allocate user their ON needs with TDM/FDM



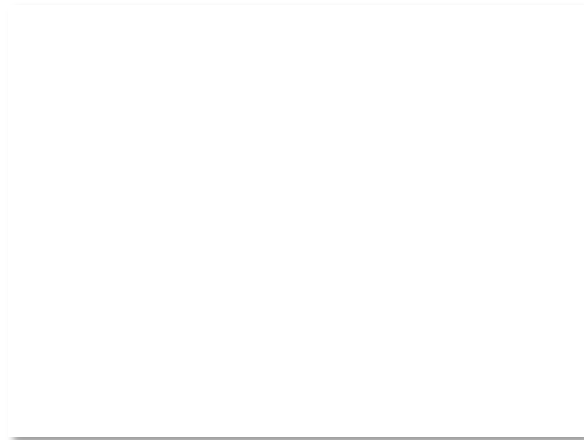
Multiplexing Network Traffic (3)

- Multiple access schemes multiplex users according to their demands – for gains of statistical multiplexing



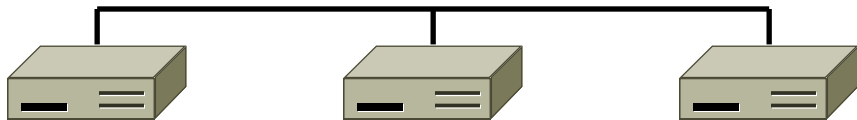
Multiple Access

- We will look at two kinds of multiple access protocols
 1. Randomized. Nodes randomize their resource access attempts
 - Good for low load situations
 2. Contention-free. Nodes order their resource access attempts
 - Good for high load or guaranteed quality of service situations

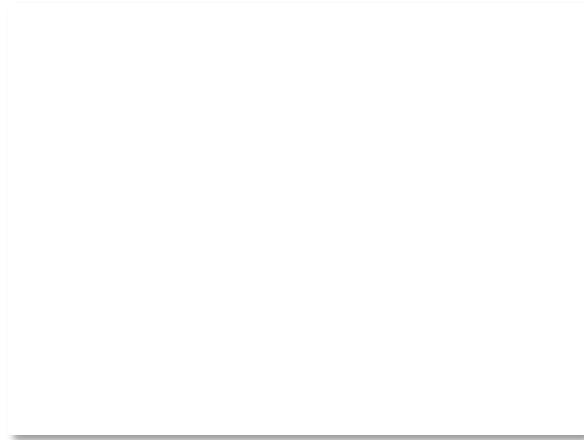


Topic

- How do nodes share a single link?
Who sends when, e.g., in WiFi?
 - Explore with a simple model

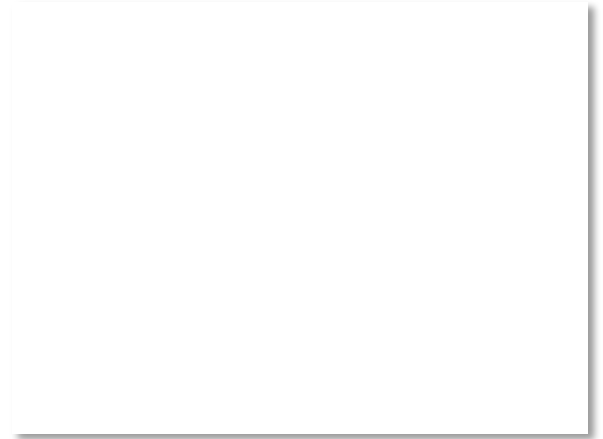


- Assume no-one is in charge; this is a distributed system



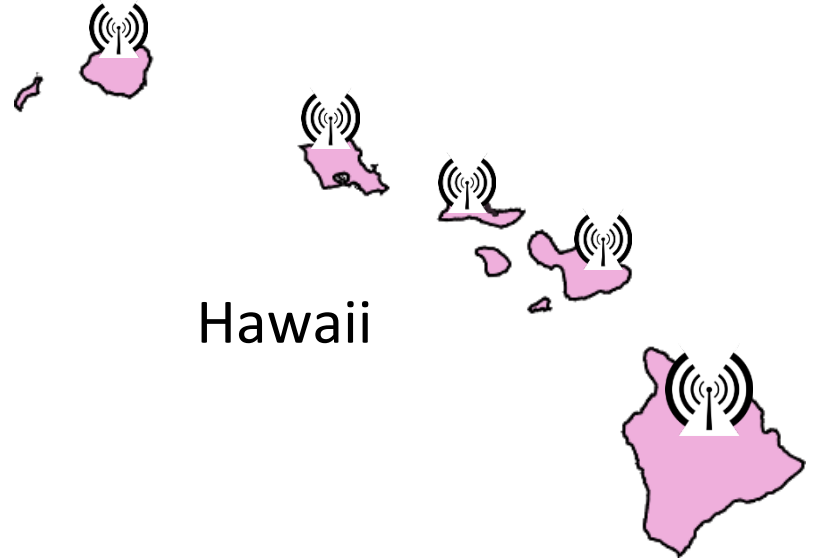
Topic (2)

- We will explore random multiple access control (MAC) protocols
 - This is the basis for classic Ethernet
 - Remember: data traffic is bursty



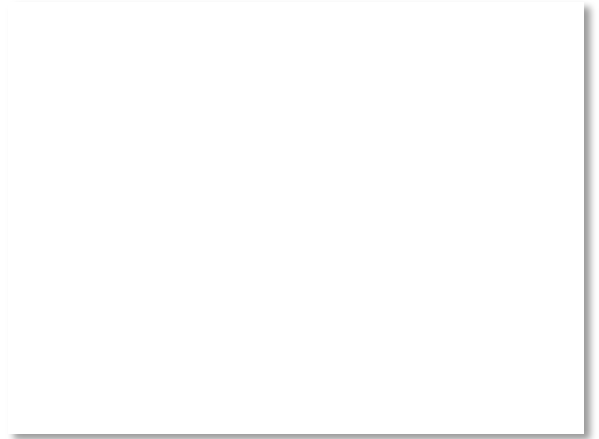
ALOHA Network

- Seminal computer network connecting the Hawaiian islands in the late 1960s
 - When should nodes send?
 - A new protocol was devised by Norm Abramson ...



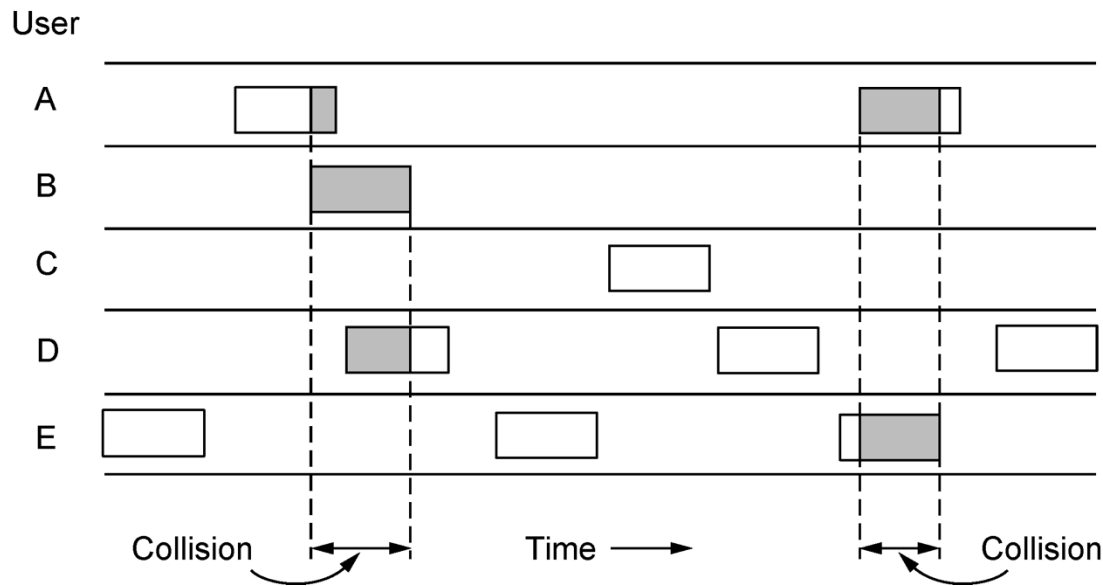
ALOHA Protocol

- Simple idea:
 - Node just sends when it has traffic.
 - If there was a collision (no ACK received) then wait a random time and resend
- That's it!



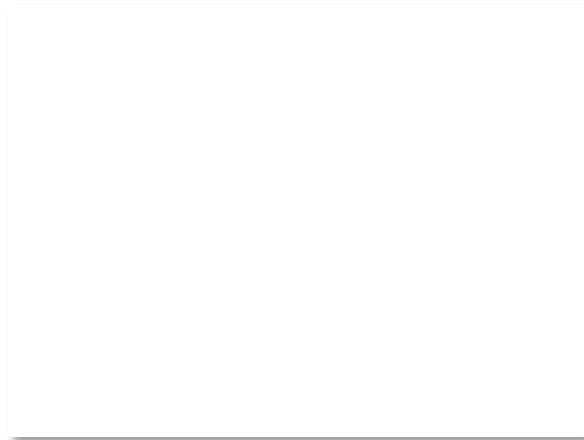
ALOHA Protocol (2)

- Some frames will be lost, but many may get through...
- Good idea?



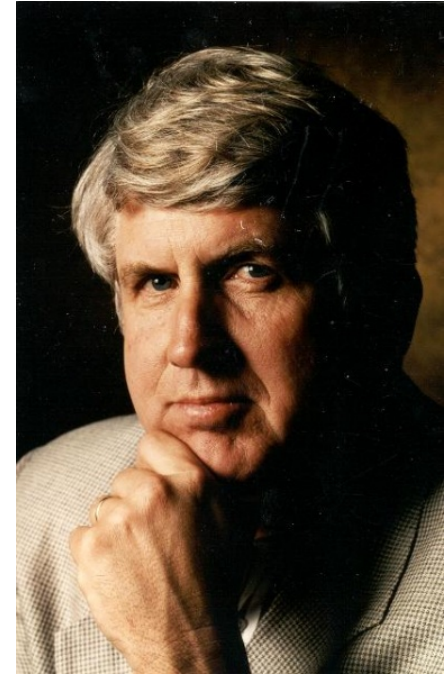
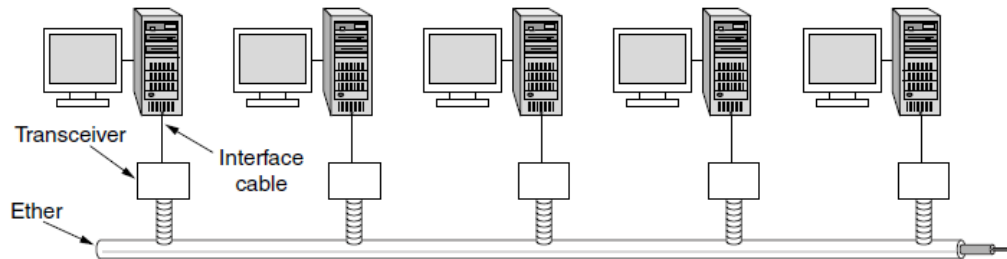
ALOHA Protocol (3)

- Simple, decentralized protocol that works well under low load!
- Not efficient under high load
 - Analysis shows at most 18% efficiency
 - Improvement: divide time into slots and efficiency goes up to 36%
- We'll look at other improvements



Classic Ethernet

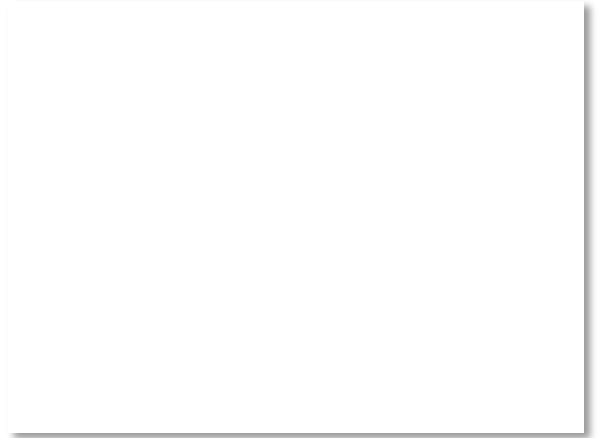
- ALOHA inspired Bob Metcalfe to invent Ethernet for LANs in 1973
 - Nodes share 10 Mbps coaxial cable
 - Hugely popular in 1980s, 1990s



: © 2009 IEEE

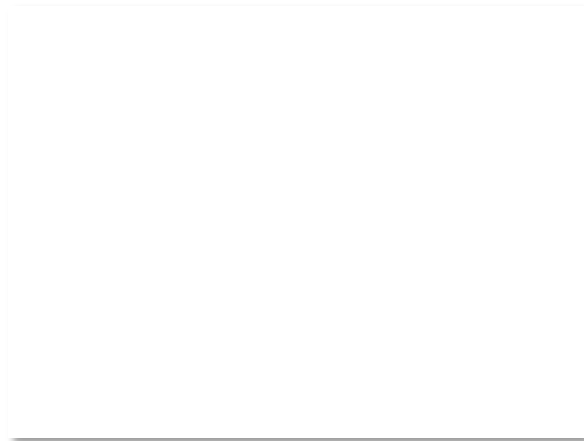
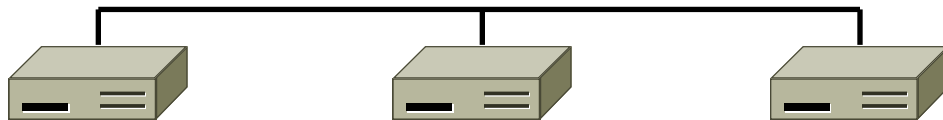
CSMA (Carrier Sense Multiple Access)

- Improve ALOHA by listening for activity before we send (Doh!)
 - Can do easily with wires, not wireless
- So does this eliminate collisions?
 - Why or why not?



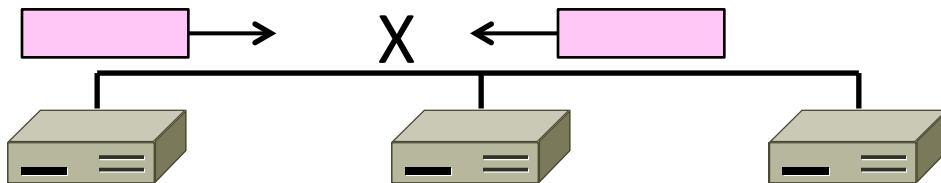
CSMA (2)

- Still possible to listen and hear nothing when another node is sending because of delay



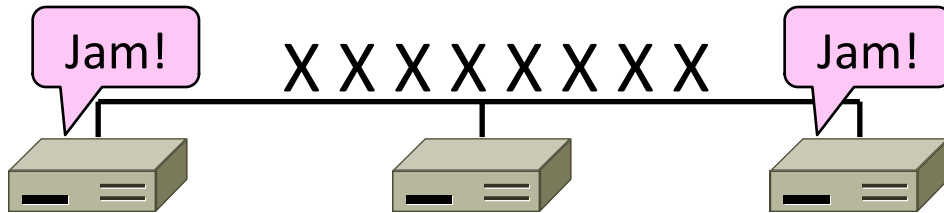
CSMA (3)

- CSMA is a good defense against collisions only when BD is small



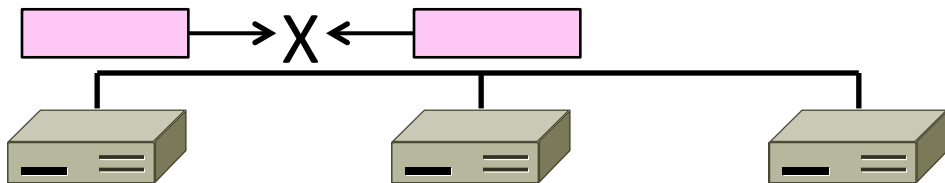
CSMA/CD (with Collision Detection)

- Can reduce the cost of collisions by detecting them and aborting (Jam) the rest of the frame time
 - Again, we can do this with wires



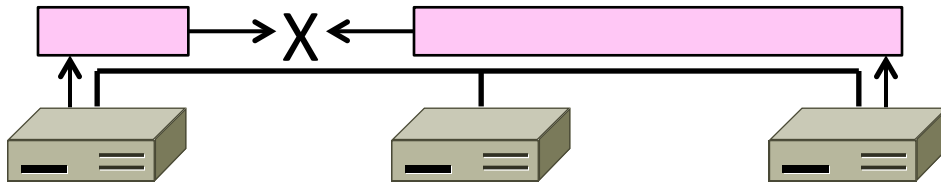
CSMA/CD Complications

- Want everyone who collides to know that it happened
 - Time window in which a node may hear of a collision is $2D$ seconds



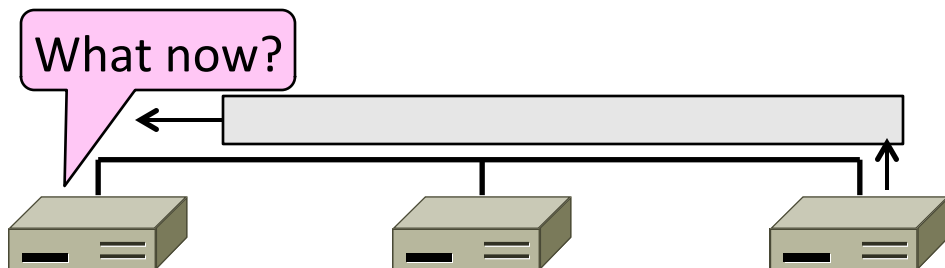
CSMA/CD Complications (2)

- Impose a minimum frame size that lasts for $2D$ seconds
 - So node can't finish before collision
 - Ethernet minimum frame is 64 bytes



CSMA “Persistence”

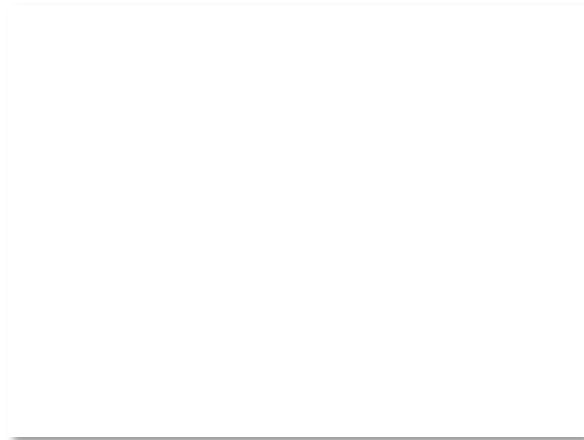
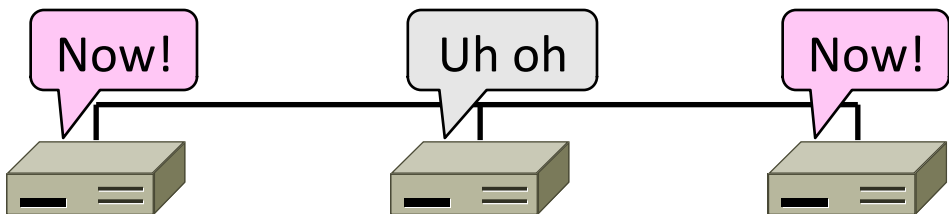
- What should a node do if another node is sending?



- Idea: Wait until it is done, and send

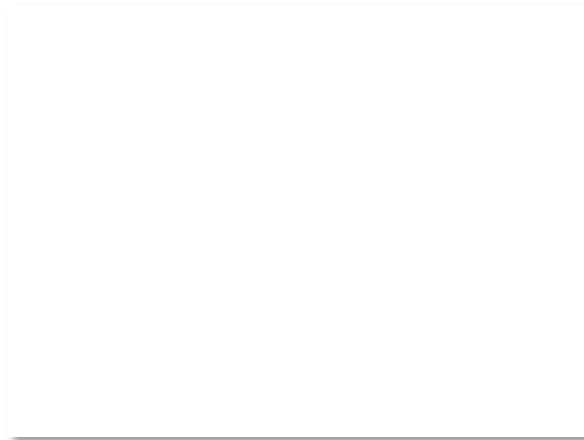
CSMA “Persistence” (2)

- Problem is that multiple waiting nodes will queue up then collide
 - More load, more of a problem



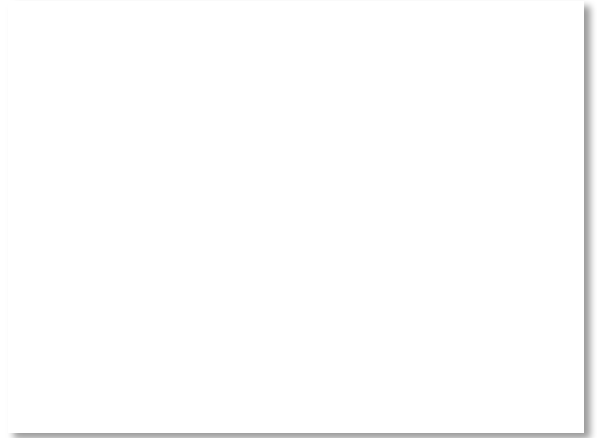
CSMA “Persistence” (3)

- Intuition for a better solution
 - If there are N queued senders, we want each to send next with probability $1/N$



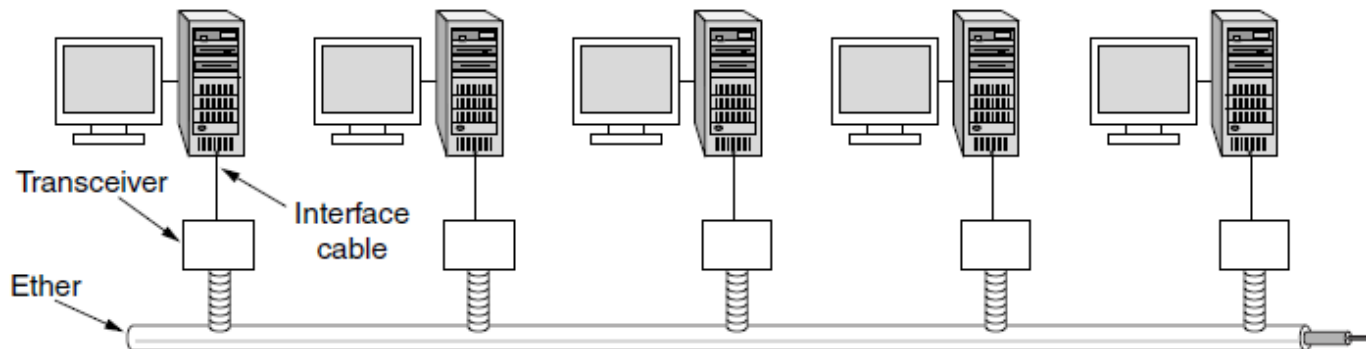
Binary Exponential Backoff (BEB)

- Cleverly estimates the probability
 - 1st collision, wait 0 or 1 frame times
 - 2nd collision, wait from 0 to 3 times
 - 3rd collision, wait from 0 to 7 times ...
- BEB doubles interval for each successive collision
 - Quickly gets large enough to work
 - Very efficient in practice



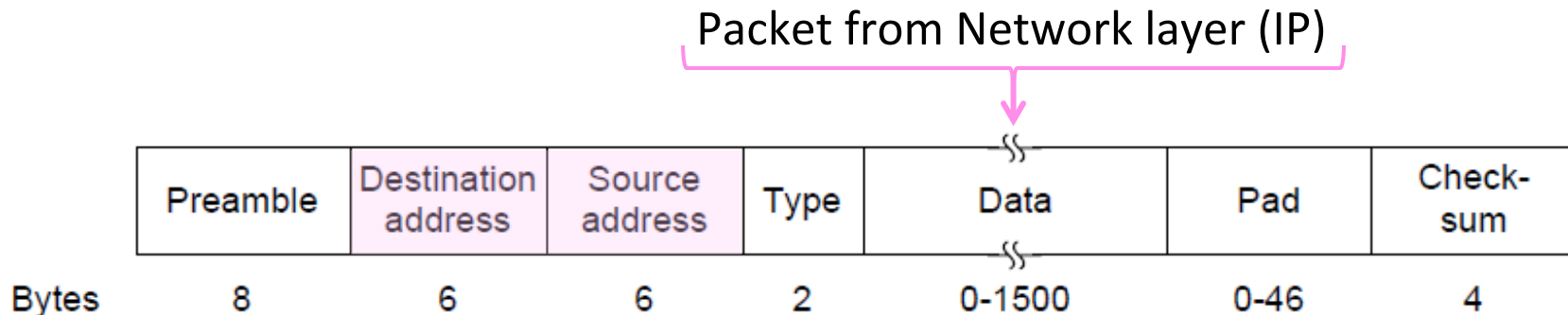
Classic Ethernet, or IEEE 802.3

- Most popular LAN of the 1980s, 1990s
 - 10 Mbps over shared coaxial cable, with baseband signals
 - Multiple access with “1-persistent CSMA/CD with BEB”



Ethernet Frame Format

- Has addresses to identify the sender and receiver
- CRC-32 for error detection; no ACKs or retransmission
- Start of frame identified with physical layer preamble



Modern Ethernet

- Based on switches, not multiple access, but still called Ethernet
 - We'll get to it in a later segment

