

# How do we share a channel?

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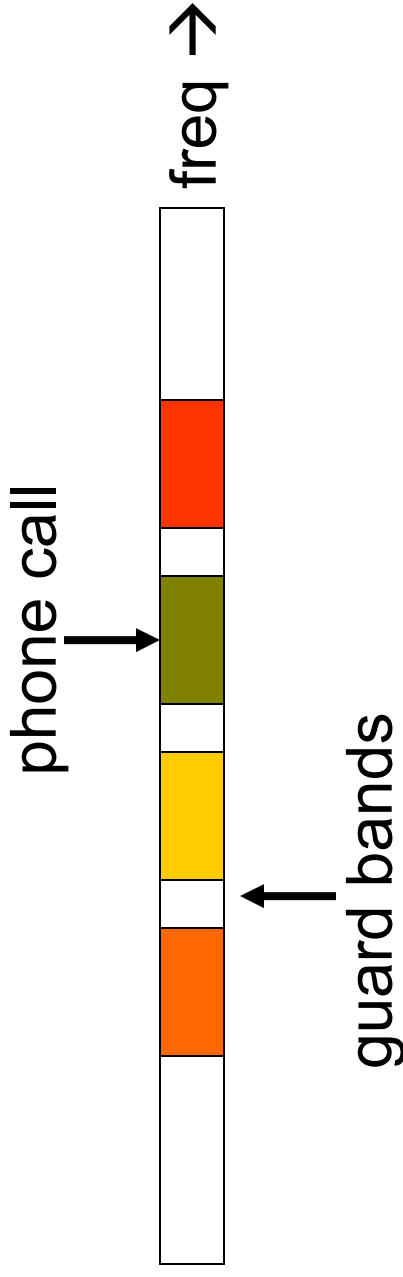
- Ideas:
  - Division via time, frequency and codes
  - Statistical multiplexing
  - Randomized access protocols
    - Aloha
    - CSMA variants
    - Classic Ethernet
    - Wireless
  - Contention-free protocols
    - Token ring
    - DQDB

Application
Presentation
Session
Transport
Network
Data Link
Physical

# Frequency Division Multiple Access

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- Simultaneous transmission in different frequency bands
  - Analog: Radio/TV, AMPS cell phones (800MHz)
  - Also called Wavelength DMA (WDM) for fiber

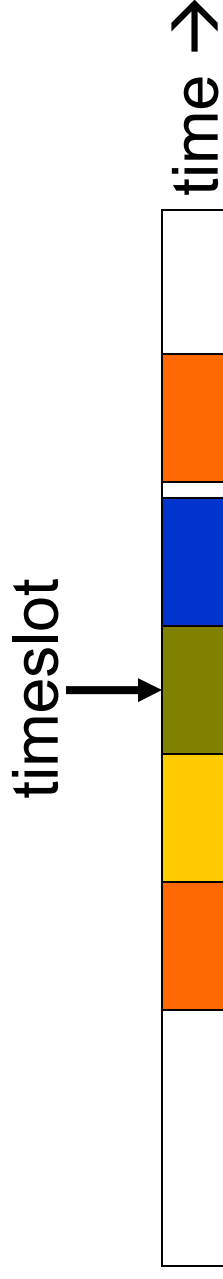


“Speaking at different pitches”

# Time Division Multiple Access

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- Timeslice given frequency band between users
  - Digital: used extensively inside the telephone network
  - T1 (1.5Mbps) is 24 x 8 bits/125us; also E1 (2Mbps, 32 slots)



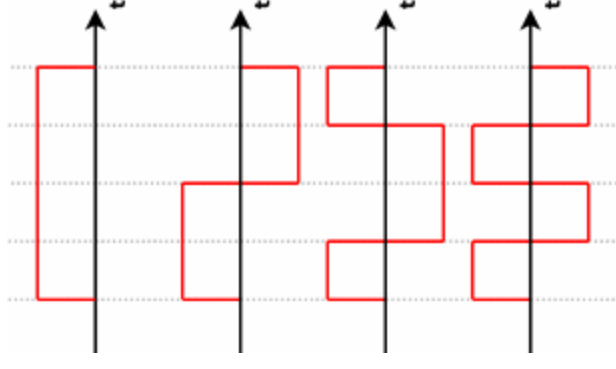
“Speaking at different times”

- Advantage: lower delay; Disadvantage: synchronization

# Code Division Multiple Access

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- Give each user a different code (right)
  - Send +ve or -ve code for 1/0
  - All users send at once
  - Uses bandwidth for N users
    - “chip rate”  $\gg$  data rate
  - Mixes time and frequency
- Codes are orthogonal to each other
  - Can correlate for one code
    - This will ignore the rest
- Widely used for 3G mobile phones



Four “4 chip”  
orthogonal codes

# Statistical Multiplexing

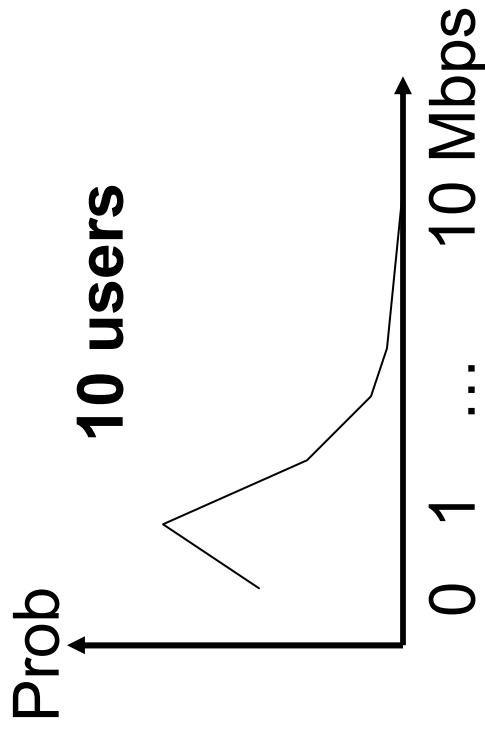
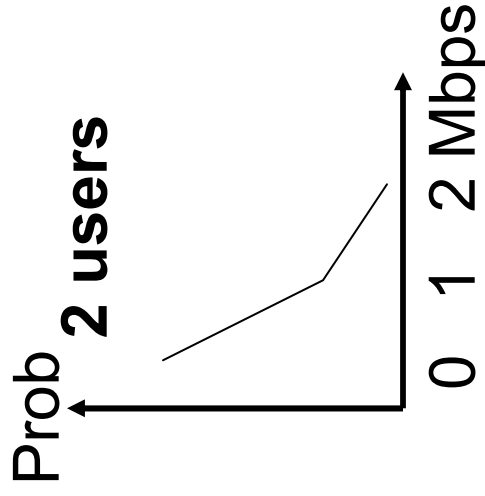
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- Static partitioning schemes are not suited to data communications where peak rate  $\gg$  average rate.
- If we share on demand we can support more users
  - Based on the statistics of their transmissions
  - Occasionally we might be oversubscribed
  - This is called statistical multiplexing
- Statistical multiplexing is heavily used in data networks
  - But not to capture (self-similar) packet bursts at small timescales!

# Example

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- One user sends at 1 Mbps and is idle 90% of the time.
  - 10 Mbps channel; 10 users if statically allocated



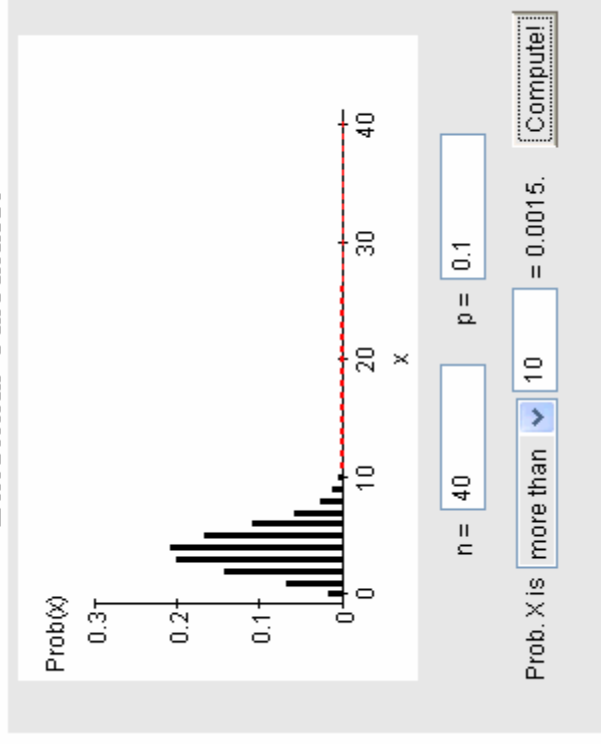
- What are the likely loads if we share on demand?

# Example continued

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- For 10 users,  $\text{Prob}(\text{need } 10 \text{ Mbps}) = 10^{-10}$  Not likely!
- For 40 users,  $\text{Prob}(>10 \text{ active users}) = 0.15\%$ , which is low
- We can support 4X users!
- But: important caveats ...

**Binomial Calculator**



# ALOHA

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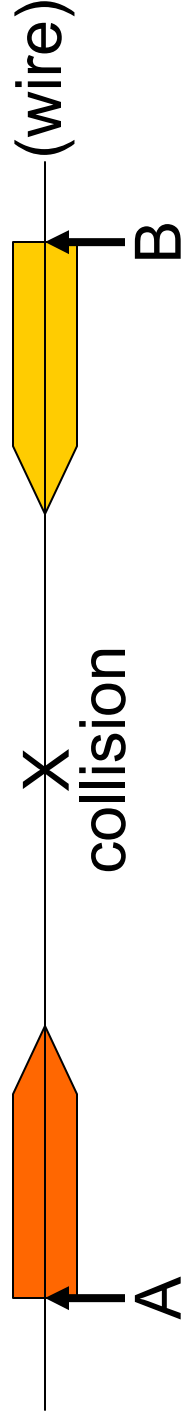
- Wireless links between the Hawaiian islands in the 70s
- Want distributed allocation
  - no special channels, or single point of failure
- Aloha protocol:
  - Just send when you have data!
  - There will be some collisions of course ...
  - Detect errored frames and retransmit a random time later
- Simple, decentralized and works well for low load
  - For many users, analytic traffic model, max efficiency is 18%



# Carrier Sense Multiple Access

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- We can do better by listening before we send (CSMA)
  - good defense against collisions only if “a” is small (LANs)



- “a” parameter: number of packets that fit on the wire
  - a = bandwidth \* delay / packet size
  - Small ( $\ll 1$ ) for LANs, large ( $\gg 1$ ) for satellites

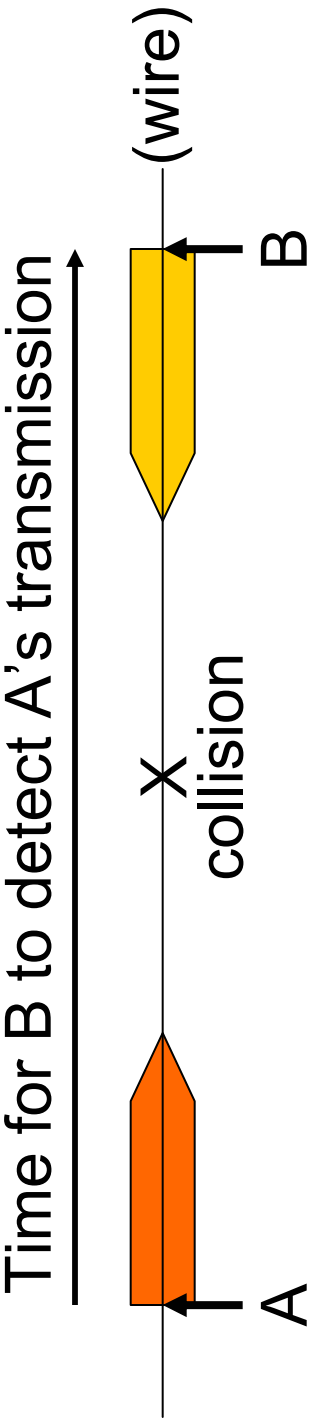
# What if the Channel is Busy?

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- 1-persistent CSMA
  - Wait until idle then go for it
  - Blocked senders can queue up and collide
- non-persistent CSMA
  - Wait a random time and try again
  - Less greedy when loaded, but larger delay
- p-persistent CSMA
  - If idle send with prob  $p$  until done; assumed slotted time
  - Choose  $p$  so  $p * \#$  senders  $< 1$ ; avoids collisions at cost of delay

# CSMA with Collision Detection

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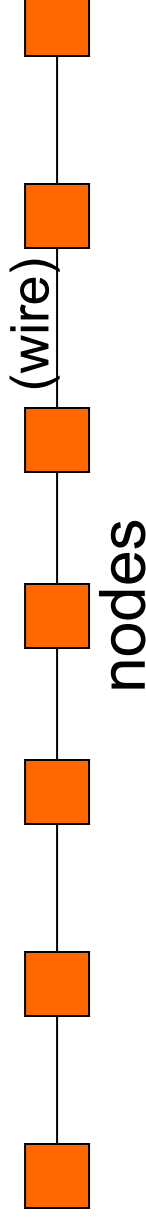
- Even with CSMA there can still be collisions. Why?  


The diagram shows a horizontal line representing a wire. On the left side, node A is indicated by an upward arrow. An orange packet is shown moving to the right from node A. On the right side, node B is indicated by an upward arrow. A yellow packet is shown moving to the left from node B. The two packets meet in the center of the wire, where the word 'collision' is written below the wire and an 'X' is placed above it. Above the wire, a horizontal arrow points from left to right, with the text 'Time for B to detect A's transmission' written above it.
- For wired media we can detect all collisions and abort (CSMA/CD):
  - Requires a minimum frame size (“acquiring the medium”)
  - B must continue sending (“jam”) until A detects collision

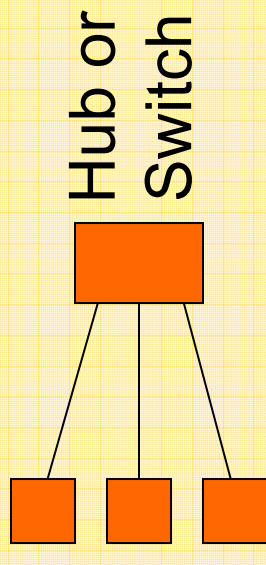
# Classic Ethernet

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- IEEE 802.3 standard wired LAN (1-persistent CSMA/CD)
- Classic Ethernet: 10 Mbps over coaxial cable
  - baseband signals, Manchester encoding, preamble, 32 bit CRC

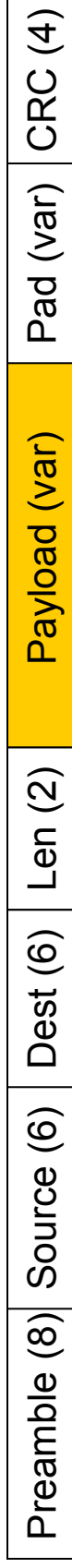


- BUT: Newer versions are much faster
  - Gigabit Ethernet (1 Gbps)
- Modern equipment isn't one long wire
  - We cover switches later



# Ethernet Frames

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- Min frame 64 bytes, max 1500 bytes
- Max length 2.5km, max between stations 500m (repeaters)
- Addresses unique per adaptor; globally assigned
- Broadcast media

# Binary Exponential Backoff

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- Build on 1-persistent CSMA/CD
- On collision: jam and exponential backoff
  - Jamming: send 48 bit sequence to ensure collision detection
- Backoff:
  - First collision: wait 0 or 1 frame times at random and retry
  - Second time: wait 0, 1, 2, or 3 frame times
  - Nth time ( $N \leq 10$ ): wait 0, 1, ...,  $2^{N-1}$  times
  - Max wait 1023 frames, give up after 16 attempts
  - Scheme balances average wait with load

# Classic Ethernet Performance

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- Much better than Aloha or CSMA!
  - Works very well in practice
  - “Measured Capacity of an Ethernet: Myths and Reality,” Boggs, Mogul and Kent, SIGCOMM 88.
- Source of protocol inefficiency: collisions
  - More efficient to send larger frames
    - Acquire the medium and send lots of data
  - Less efficient as the network grows in terms of frames
    - recall “a” = delay / (frame size \* transmission rate)
    - “a” grows as the path gets longer (satellite)
    - “a” grows as the bit rates increase (Fast, Gigabit Ethernet)

# Wireless Multiple Access

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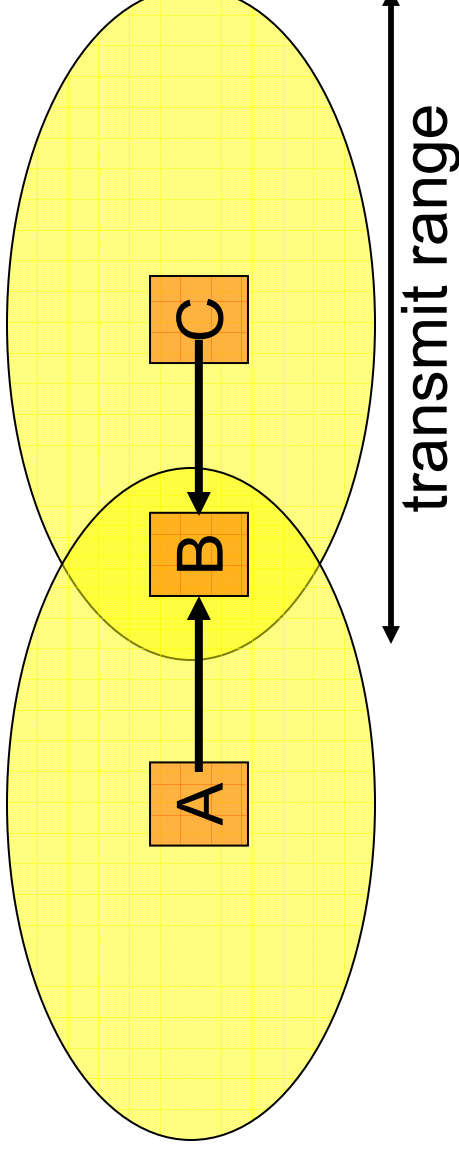
Wireless is more complicated than wired ...

1. Cannot detect collisions
  - Transmitter swamps co-located receiver
2. Different transmitters have different coverage areas
  - Asymmetries lead to hidden/exposed terminal problems



# Hidden Terminals

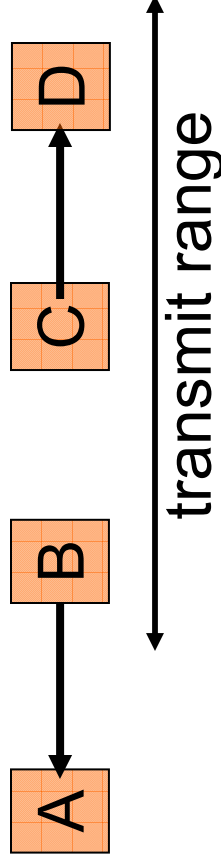
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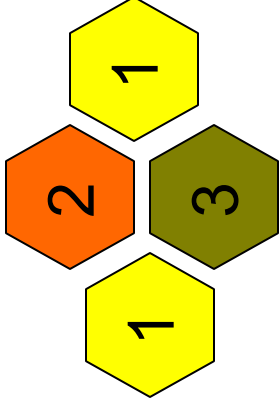


- A and C can both send to B but can't hear each other
  - A is a hidden terminal for C and vice versa
- CSMA will be ineffective – want to sense at receiver

# Exposed Terminals

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- B, C can hear each other but can safely send to A, D
- Compare to spatial phones:  
 reuse in cell

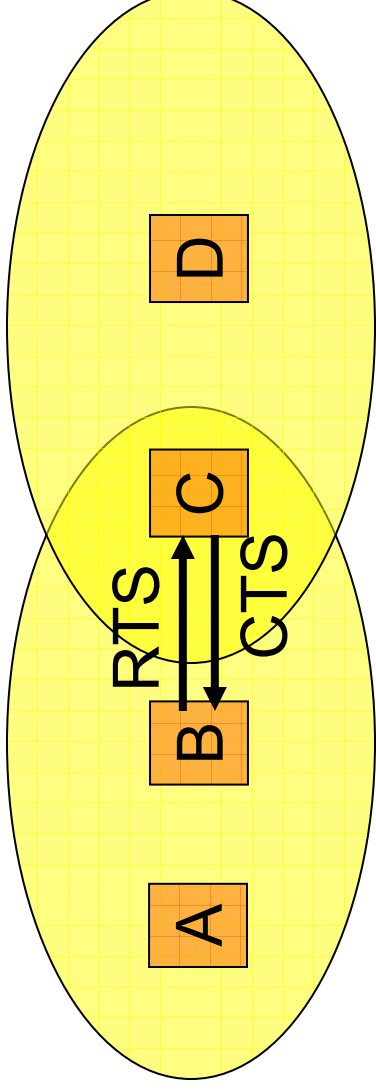
# CSMA with Collision Avoidance

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- Since we can't detect collisions, we avoid them
  - CSMA/CA as opposed to CSMA/CD
  - Not greedy like Ethernet
- When medium busy, choose random backoff interval
  - Wait for that many idle timeslots to pass before sending
  - Remember p-persistence ... a refinement
- When a collision is inferred, retransmit with binary exponential backoff (like Ethernet)
  - Use CRC and ACK from receiver to infer “no collision”
  - Again, exponential backoff helps us adapt “p” as needed

## Aside: RTS / CTS for hidden terminals

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1. B stimulates C with Request To Send (RTS)
2. A hears RTS and defers to allow the CTS
3. C replies to B with Clear To Send (CTS)
4. D hears CTS and defers to allow the data
5. B sends to C

# 802.11 Wireless LANs

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- Dominant standard with a many PHY/MAC options/features



- Wireless plus wired infrastructure
- Avoids collisions with CSMA/CA; RTS/CTS largely unused
- Much PHY processing for high-rate physical links

# CSMA Story

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- Aloha
- Classic Ethernet
- 802.11
- Cable modems
- RFID
  - Explore this in Homework 2

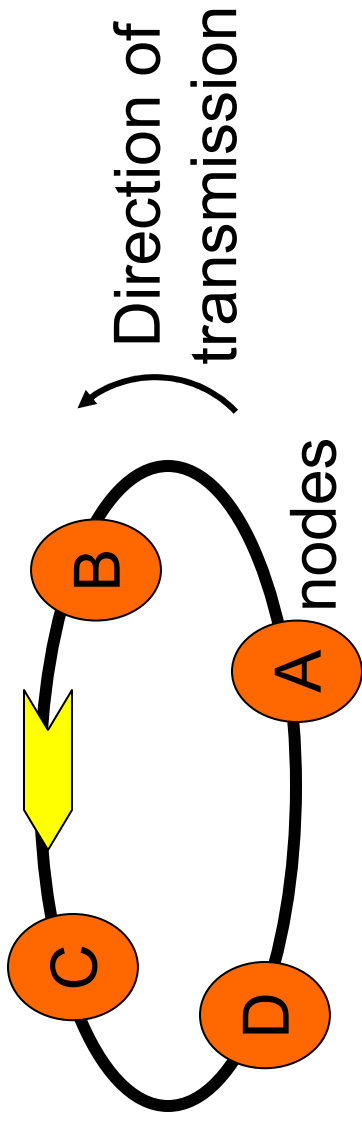
# Contention-free Protocols

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- Collisions are the main difficulty with random schemes
  - To improve efficiency/scalability, many schemes grant ongoing bandwidth and use random schemes for request traffic
- Q: Can we avoid collisions altogether?
- A: Yes. By taking turns or with reservations
  - Token Ring / FDDI, DQDB
- More generally, what else might we want?
  - Deterministic service, priorities/QOS, reliability

# Token Ring (802.5)

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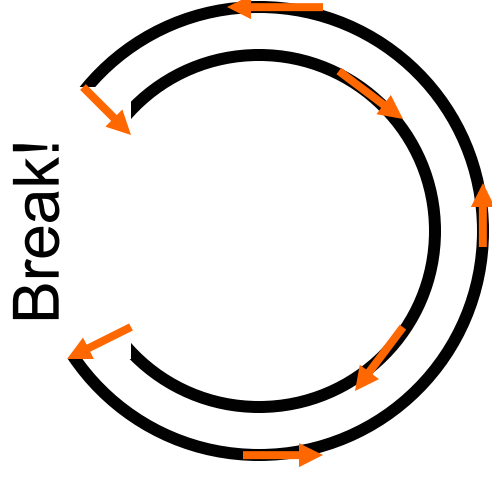
- Token rotates permission to send around node
- Sender injects packet into ring and removes later
  - Maximum token holding time (THT) bounds access time
  - Early or delayed token release
  - Round robin service, acknowledgments and priorities
- Monitor nodes ensure health of ring



# FDDI (Fiber Distributed Data Interface)

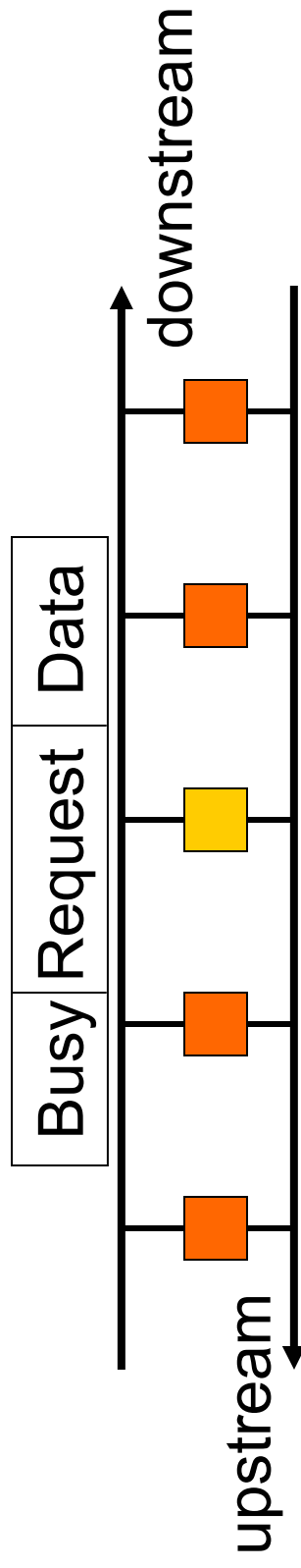
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- Roughly a large, fast token ring
  - 100 Mbps and 200km vs 4/16 Mbps and local
  - Dual counter-rotating rings for redundancy
  - Complex token holding policies for voice etc. traffic
- Token ring advantages
  - No contention, bounded access delay
  - Support fair, reserved, priority access
- Disadvantages
  - Complexity, reliability, scalability



# DQDB (Distributed Queue Dual Bus)

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- Two unidirectional buses that carry fixed size cells
  - Cells are marked busy/free and can signal a request too
- Nodes maintain a distributed FIFO queue
  - By sending requests they are reserving future access

# DQDB Algorithm

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- Two counters per direction (UP, DN)
  - RC (request count), CD (countdown)
- Consider sending downstream (DN):
  - Always have RC count UP requests, minus free DN cells if larger than zero
  - This is a measure of how many others are waiting to send
  - To send, copy RC to CD, decrement CD for each free DN cell, send when zero
  - This waits for earlier requests to be satisfied before sending
- Highly scalable, efficient, but not perfectly fair