CSE/EE 461

Retransmission and Timers

<section-header><section-header><text><text><text><text><text><text><text><text><text>







- In the limit, early retransmissions lead to congestion collapse
 - Sending more packets into the network when it is overloaded exacerbates the problem of congestion
 - Network stays busy but very little useful work is being done
- This happened in real life ~1987
 - Led to Van Jacobson's TCP algorithms, which form the basis of congestion control in the Internet today [See "Congestion Avoidance and Control", SIGCOMM'88]
 - Observed 1000x bandwidth reduction between two hosts separated by 400 yards.
 - Led to researchers asking two questions:
 - Was TCP/IP misbehaving?
 - Could TCP/IP be "trained" to work better under 'absymal network conditions'















1988 Observations on Congestion Collapse

- Implementation, not the protocol, leads to collapse
- "Obvious" ways of doing things lead to non-obvious and undesirable results
 - "send eff-wind-size # packets, wait rtt, try again"
- Remedial algorithms achieve network stability by forcing the transport connection to obey a 'packet conservation' principle.
 - For a connection in 'equilibrium, that is, running stably with a full window of data in transit, the packet flow is "conservative": a new packet is not put into the network until an old packet leaves.

12





















Bad Estimators and the Bad Things They Do

• Problem:

- Variance in RTTs gets large as network gets loaded
- So an average RTT isn't a good predictor when we need it most
 - Time out too soon, unnecessarily drop another packet onto the network.
 - Timing out too soon occurs during load increase
 - if we time out when load increases but packet not yet lost, then we'll inject another packet onto the network which will increase load, which will cause more timeouts, which will increase load, until we actually starting dropping packets!





Cheap Algorithm For Keeping Running Tabs

- Solution: Track variance too. •
 - Difference = SampleRTT EstimatedRTT
 - EstimatedRTT = EstimatedRTT + (δx Difference)
 - Deviation = Deviation + δ (|Difference|-Deviation)
 - Timeout = μx EstimatedRTT + ϕx Deviation
 - In practice, $\delta = 1/8$, $\mu = 1$ and $\phi = 4$
- See paper for details

A Fast Algorithm for RTT Mean and Variation Let a = estimated round trip time, v = estimated error, g = gain (0 < g < 1), m = new sampled round trip time

- a = (1-g)a + gm// compute new estimate using gain
 - a = a + g(m-a)// rearrange terms:
 - a is a prediction of next measurement, and (m-a) is the "error" in that prediction.
 - so, the new prediction is the old prediction plus some fraction of the prediction error.
 - The prediction error is the sum of two components:
 - E_r = noise (random unpredictable effects like fluctations in competing traffic)
 - E_e = bad choice of a

 - $a = a + g E_r + g E_e$ The term g E_e kicks *a* in the right direction towards the real estimate

 - The term g E, kicks it off in the random direction Over many samples, the random errors cancel each other so we get closer and closer to the real estimate
 - But, g represents a compromise.
 - Big 'g' means that we get a lot of value out of a prediction error, but it also means that the random errors introduce a lot of noise.

25

26

Since $g \in g_b$ moves a in the right direction regardless of g, we're better off using a small g and waiting a bit longer to get a better estimate than to very quickly get a lousy estimate

Or,

- Err = (m a) // Sampled Error
- _ a = a + g (Err) // Estimate of round trip time
- _ v = v + g(|Err| - v)// Estimate of error













