Texture Mapping

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Reading

Optional

- Angel and Shreiner: 7.4-7.10
- Marschner and Shirley: 11.1-11.2.3, 11.2.5, 11.4-11.5

Further reading

- Paul S. Heckbert. Survey of texture mapping. IEEE Computer Graphics and Applications 6(11): 56--67, November 1986.
- Woo, Neider, & Davis, Chapter 9
- James F. Blinn and Martin E. Newell. Texture and reflection in computer generated images. Communications of the ACM 19(10): 542-547, October 1976.

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Texture mapping



Texture mapping (Woo et al., fig. 9-1)

Texture mapping allows you to take a simple polygon and give it the appearance of something much more complex.

- Due to Ed Catmull, PhD thesis, 1974
- Refined by Blinn & Newell, 1976

A texture can modulate just about any parameter – diffuse color, specular color, specular exponent,

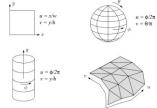
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Implementing texture mapping

A texture lives in it own abstract image coordinates paramaterized by (u, v) in the range ([0..1], [0..1]):



It can be wrapped around many different surfaces:

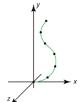


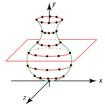
With a ray caster, we can do the sphere and cylinder mappings directly (as we will see later). For graphics hardware, everything gets converted to a triangle mesh with associated (u,v) coordinates.

Note: if the surface moves/deforms, the texture goes with it.

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Texture coordinates on a surface of revolution





Recall that for a surface of revolution, we have:

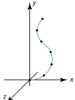
Profile curve: C[j] where $j \in [0..M-1]$

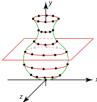
Rotation angles: $\theta[i] = 2\pi i / N$ where $i \in [0..N]$

The simplest assignment of texture coordinates would be:

Note that you should include the rotation angles for i=0 and i=N, even though they produce the same points (after rotating by 0 and 2π). Why do this??

Texture coordinates on a surface of revolution





If we wrap an image around this surface of revolution, what artifacts would we expect to see?

We can reduce distortion in v. Define:

$$d[j] = \begin{cases} ||C[j] - C[j-1]||, & \text{if } j \neq 0 \\ 0, & \text{if } j = 0 \end{cases}$$

and set v to fractional distance along the curve:

You must do this for ν for the programming assignment!

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Mapping to texture image coords

The texture is usually stored as an image. Thus, we need to convert from abstract texture coordinate:

$$(u, v)$$
 in the range ([0..1], [0..1])

to texture image coordinates:

$$(u_{tex}, v_{tex})$$
 in the range ([0.. w_{tex}], [0.. h_{tex}])



Point on triangle mesh

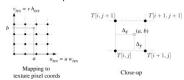


 $v_{lex} = v h_{lex}$ b a $u_{lex} = u w_{lex}$ Mapping to texture pixel coords

Q: What do you do when the texture sample you need lands between texture pixels?

Texture resampling

We need to resample the texture:



Thus, we seek to solve for: $T(a,b) = T(i + \Delta_x, j + \Delta_y)$

A common choice is bilinear interpolation:

$$\mathsf{T}\!\left(i\!+\!\Delta_{_{\boldsymbol{X}}},j\right)\!=\!\underline{\qquad}\mathsf{T}\!\left[i\!+\!1,j\right]\\ \qquad \qquad + \qquad \underline{\qquad}\mathsf{T}\!\left[i\!+\!1,j\right]$$

$$T(i + \Delta_x, j + 1) = \underline{\qquad} T[i, j + 1] + \underline{\qquad} T[i + 1, j + 1]$$

$$\begin{split} &\mathbf{T} \left(i + \Delta_z, j + \Delta_y \right) = \underline{\hspace{1cm}} &\mathbf{T} \left(i + \Delta_z, j \right) &+ \underline{\hspace{1cm}} &\mathbf{T} \left(i + \Delta_z, j + 1 \right) \\ &= \underline{\hspace{1cm}} &\mathbf{T} [i, j] &+ \underline{\hspace{1cm}} &\mathbf{T} [i + 1, j] &+ \underline{\hspace{1cm}} &\mathbf{T} [i + 1, j] &+ \underline{\hspace{1cm}} &\mathbf{T} [i, j] &+ \underline$$

$$T[i,j+1]$$
 + $T[i+1,j+1]$

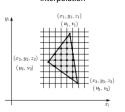
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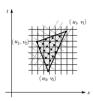
Texture mapping and rasterization

Texture-mapping can also be handled in rasterization algorithms.

Method:

- Scan conversion is done in screen space, as usual
- Each pixel is colored according to the texture
- Texture coordinates are found by Gouraud-style interpolation





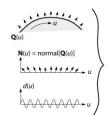
<u>Note</u>: Mapping is more complicated to handle perspective correctly.

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Displacement mapping

Textures can be used for more than just color.

In **displacement mapping**, a texture is used to perturb the surface geometry itself. Here's the idea in 2D:





- These displacements "animate" with the surface
- In 3D, you would of course have (u, v) parameters instead of just u.

Suppose Q is a simple surface, like a cube. Will it take more work to render the modified surface Q?

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Bump and normal mapping

In **bump mapping**, a texture is used to perturb the normal:

- Use the original, simpler geometry, Q(u), for hidden surfaces
- Use the normal from the displacement map for shading:

$$\tilde{\mathbf{N}} = \text{normal}[\tilde{\mathbf{Q}}(u)]$$

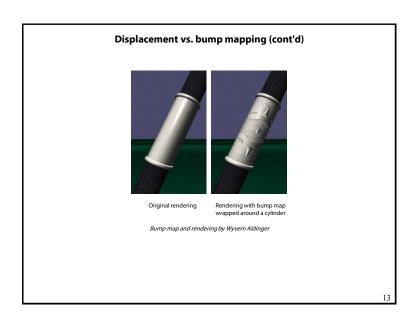


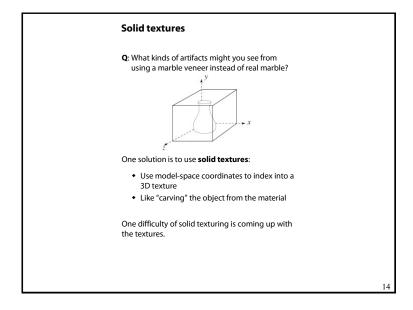
An alternative to compute the normals from the original bump map height field and map them over the smooth surface. This is called **normal mapping**.

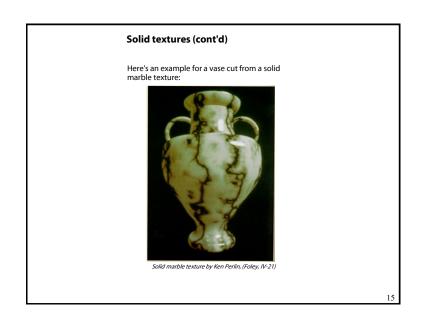
What artifacts in the images would reveal that bump (or normal) mapping is fake?

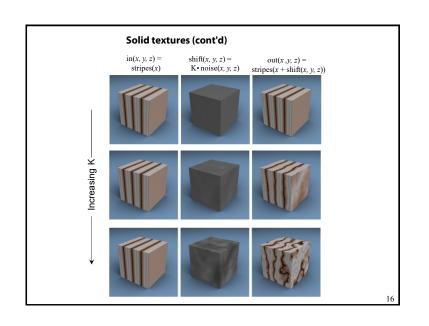
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Input texture Rendered as displacement map over a rectangular surface









Environment mapping







In **environment mapping** (also known as **reflection mapping**), a texture is used to model an object's environment:

- Rays are bounced off objects into environment
- Color of the environment used to determine color of the illumination
- Environment mapping works well when there is just a single object – or in conjunction with ray tracing

This can be readily implemented (without interreflection) in graphics hardware using a fragment shader, where the texture is stored in a "cube map" instead of a sphere.

With a ray tracer, the concept is easily extended to handle refraction as well as reflection (and interreflection).

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Summary

What to take home from this lecture:

- 1. The meaning of the boldfaced terms.
- Familiarity with the various kinds of texture mapping, including their strengths and limitations.

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