

## Subdivision curves and surfaces

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1

## Reading

Recommended:

- ♦ Stollnitz, DeRose, and Salesin. *Wavelets for Computer Graphics: Theory and Applications*, 1996, section 6.1-6.3, 10.2, A.5. (online handout)

Note: there is an error in Stollnitz, et al., section A.5. Equation A.3 should read:

$$MV = VL$$

This is already fixed in the handout.

2

## Subdivision curves

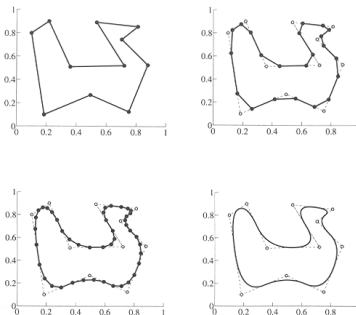
Idea:

- ♦ repeatedly refine the control polygon

$$P_1 \rightarrow P_2 \rightarrow P_3 \rightarrow \dots$$

- ♦ curve is the limit of an infinite process

$$Q = \lim_{j \rightarrow \infty} P_j$$

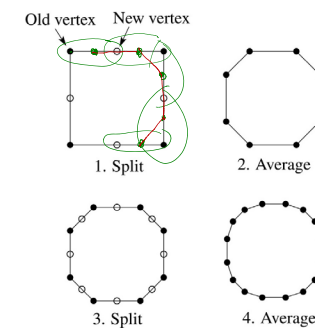


3

## Chaikin's algorithm

Chakin introduced the following "corner-cutting" scheme in 1974:

- ♦ Start with a piecewise linear curve
- ♦ Insert new vertices at the midpoints (the **splitting step**)
- ♦ Average each vertex with the "next" (clockwise) neighbor (the **averaging step**)
- ♦ Go to the splitting step



4

## Averaging masks

The limit curve is a quadratic B-spline!

Instead of averaging with the nearest neighbor, we can generalize by applying an **averaging mask** during the averaging step:

$$a = (\dots, a_{-1}, a_0, a_1, \dots) \quad (0, 0, \frac{1}{2}, \frac{1}{2}, 0)$$

In the case of Chaikin's algorithm:

$$a = (0, \frac{1}{2}, \frac{1}{2}) \quad (\frac{1}{2}, \frac{1}{2})$$

Different averaging masks lead to different curves.

For example,

$$a = \left( \frac{1}{4}, \frac{1}{2}, \frac{1}{4} \right)$$

Leads to **cubic** B-spline curves.

After each split and average step, we are closer to the **limit curve**.

Q: How many steps until we reach the final (limit) position?  $\infty$

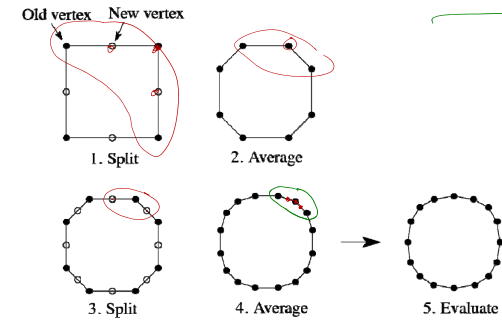
5

## Limit curves and evaluation masks

Can we push a curve to the limit position in one step? Yes!!

We can stop after a number of split-average steps and apply an **evaluation mask** to push the vertices onto the limit curve.

For Chaikin's algorithm, the evaluation masks is:  $e = \left( 0, \frac{1}{2}, \frac{1}{2} \right)$

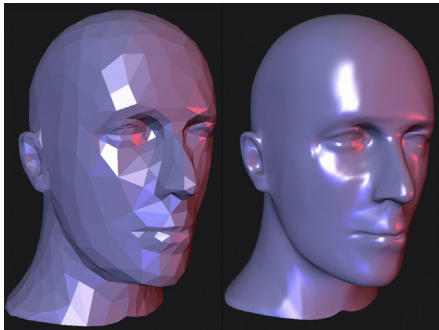


For cubic subdivision, the evaluation masks is:  $e = \left( \frac{1}{6}, \frac{2}{3}, \frac{1}{6} \right)$

6

## Building complex models

We can extend the idea of subdivision from curves to surfaces...



7

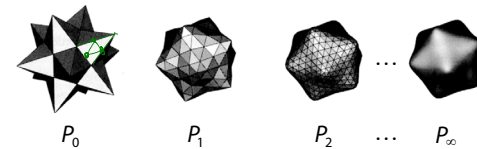
## Subdivision surfaces

Chaikin's use of subdivision for curves inspired similar techniques for subdivision surfaces.

Iteratively refine a **control polyhedron** (or **control mesh**) to produce the limit surface

$$S = \lim_{j \rightarrow \infty} P_j$$

using splitting and averaging steps.

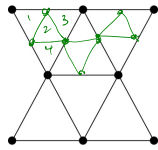


8

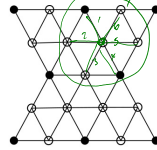
## Triangular subdivision

There are a variety of ways to subdivide a polygon mesh.

A common choice for triangle meshes is 4:1 subdivision – each triangular face is split into four smaller triangles:



Original

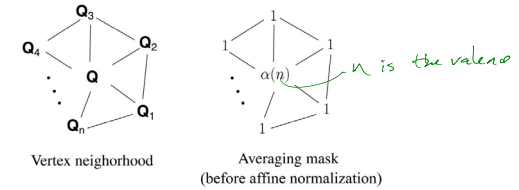


After splitting

*1-ring neighborhood  
6 edges ...  
# of edges  
is the valence  
of a vertex*

## Loop averaging step

Once again we can use **masks** for the averaging step:



$$Q \leftarrow \frac{\alpha(n)Q + Q_1 + \dots + Q_n}{\alpha(n) + n}$$

where

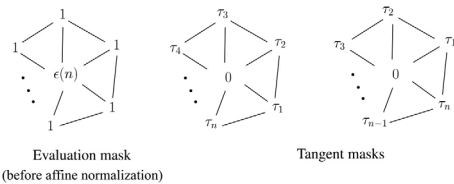
$$\alpha(n) = \frac{n(1-\beta(n))}{\beta(n)} \quad \beta(n) = \frac{5}{4} - \frac{(3+2\cos(2\pi/n))^2}{32}$$

These values, due to Charles Loop, are carefully chosen to ensure smoothness – namely, tangent plane or normal continuity.

Note: tangent plane continuity is also known as  $G^1$  continuity for surfaces.

## Loop evaluation and tangent masks

As with subdivision curves, we can split and average a number of times and then push the points to their limit positions.



$$Q^\infty = \frac{\epsilon(n)Q + Q_1 + \dots + Q_n}{\epsilon(n) + n}$$

$$T_1^\infty = \tau_1(n)Q_1 + \tau_2(n)Q_2 + \dots + \tau_n(n)Q_n$$

$$T_2^\infty = \tau_n(n)Q_1 + \tau_1(n)Q_2 + \dots + \tau_{n-1}(n)Q_n$$

where

$$\epsilon(n) = \frac{3n}{\beta(n)} \quad \tau_i(n) = \cos(2\pi i/n)$$

How do we compute the normal?

$$N \sim T_1^\infty \times T_2^\infty$$

## Recipe for subdivision surfaces

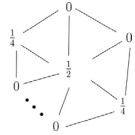
As with subdivision curves, we can now describe a recipe for creating and rendering subdivision surfaces:

- Subdivide (split+average) the control polyhedron a few times. Use the averaging mask.
- Compute two tangent vectors using the tangent masks.
- Compute the normal from the tangent vectors.
- Push the resulting points to the limit positions. Use the evaluation mask.
- Render!

## Adding creases without trim curves

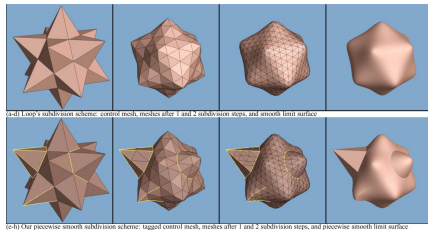
For NURBS surfaces, adding sharp features like creases required the use of trim curves.

For subdivision surfaces, we can just modify the subdivision masks. E.g., we can mark some edges and vertices as "creases" and modify the subdivision mask for them (and their children):



This gives rise to  $G^0$  continuous surfaces (i.e., having positional but not tangent plane continuity).

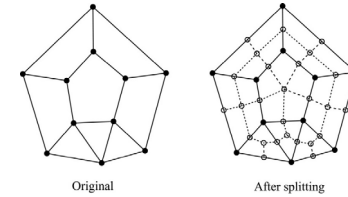
[Hoppe, SIGGRAPH 1994]



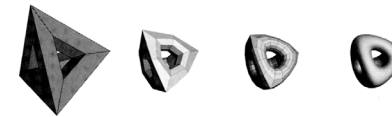
## Catmull-Clark subdivision

4:1 subdivision of triangles is sometimes called a **face scheme** for subdivision, as each face begets more faces.

An alternative face scheme starts with arbitrary polygon meshes and inserts vertices along edges and at face centroids:



**Catmull-Clark subdivision:**



Note: after the first subdivision, all polygons are quadrilaterals in this scheme.

## Catmull-Clark subdivision (cont'd)

Here's an example using Catmull-Clark surfaces (based on subdividing quadrilateral meshes):



This particular example uses the hybrid technique of DeRose, et al., which applies sharp subdivision rules at some creases for a finite number of steps, and then switches to smooth subdivision, giving more gentle creases. This technique was used in Geri's Game.

## Summary

What to take home:

- ◆ The meanings of all the **boldfaced** terms.
- ◆ How to perform the splitting and averaging steps on subdivision curves.
- ◆ How to perform mesh splitting steps for subdivision surfaces, especially Loop.
- ◆ How to construct and render subdivision surfaces from their averaging masks, evaluation masks, and tangent masks.