

Accelerated ray tracing

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CSE 457
Autumn 2017

1

Reading

Required:

- ♦ Marschner and Shirley, Sections 12.3 (online handout)

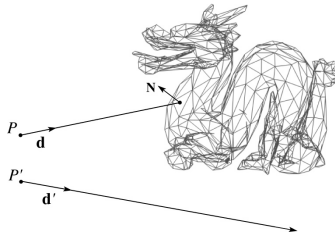
Further reading:

- ♦ A. Glassner. An Introduction to Ray Tracing. Academic Press, 1989.

2

Faster ray-polyhedron intersection

Let's say you were intersecting a ray with a triangle mesh:



Straightforward method

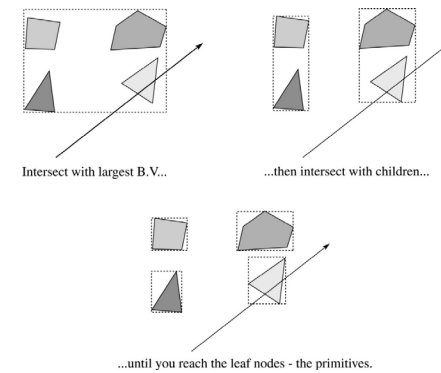
- ♦ intersect the ray with each triangle
- ♦ return the intersection with the smallest t -value.

Q: How might you speed this up?

3

Bounding Volume Hierarchies (BVHs)

We can generalize the idea of bounding volume acceleration with **bounding volume hierarchies (BVHs)**.

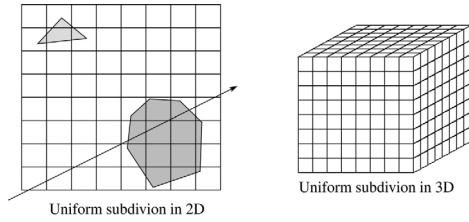


Key: build balanced trees with *tight bounding volumes*.

4

Uniform spatial subdivision

Another approach is **uniform spatial subdivision**.



Idea:

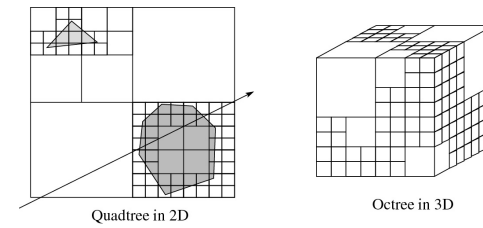
- ◆ Partition space into cells (voxels)
- ◆ Associate each primitive with the cells it overlaps
- ◆ Trace ray through voxel array using fast incremental arithmetic to step from cell to cell

Q: Given a 10^6 triangle football stadium with a 10^6 triangle teapot on one of the seats, would a single uniform spatial subdivision be a good idea?

5

Non-uniform spatial subdivision: octrees

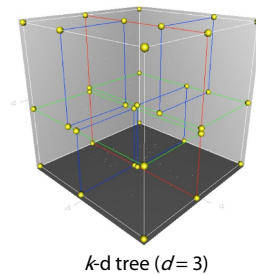
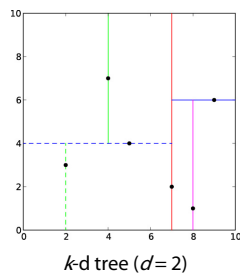
Another approach is **non-uniform spatial subdivision**. One version of this is octrees:



6

Non-uniform spatial subdivision: k -d trees

Another non-uniform subdivision is k -d (k -dimensional) trees:



If the planes can be non-axis aligned, then you get BSP (binary space partitioning) trees.

Various combinations of these ray intersection techniques are also possible.

[Image credits: Wikipedia.]

7

Summary

What to take home from this lecture:

- ◆ An intuition for how ray tracers can be accelerated.

8