

Accelerated ray tracing

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Reading

Required:

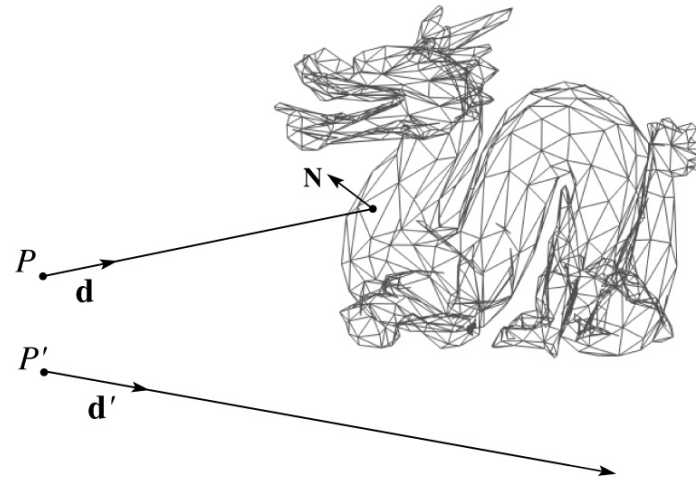
- ◆ Marschner and Shirley, Sections 12.3 (online handout)

Further reading:

- ◆ A. Glassner. An Introduction to Ray Tracing. Academic Press, 1989.

Faster ray-polyhedron intersection

Let's say you were intersecting a ray with a triangle mesh:



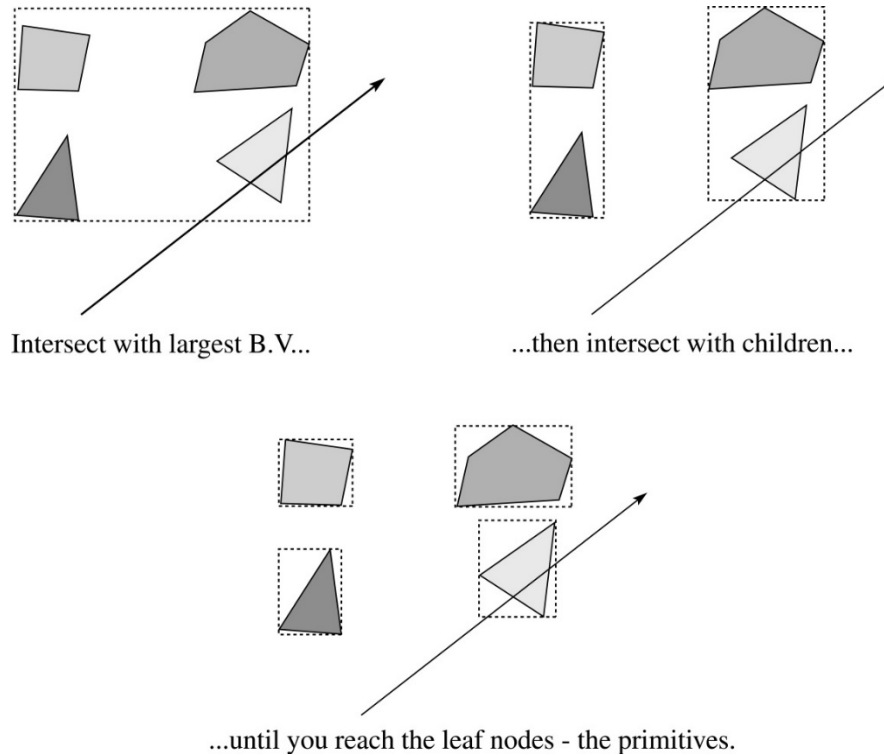
Straightforward method

- ◆ intersect the ray with each triangle
- ◆ return the intersection with the smallest t -value.

Q: How might you speed this up?

Bounding Volume Hierarchies (BVHs)

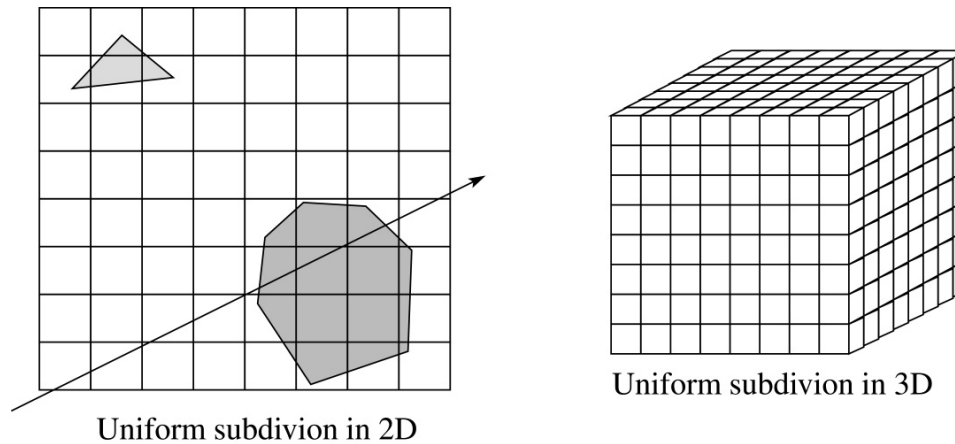
We can generalize the idea of bounding volume acceleration with **bounding volume hierarchies (BVHs)**.



Key: build balanced trees with *tight bounding volumes*.

Uniform spatial subdivision

Another approach is **uniform spatial subdivision**.



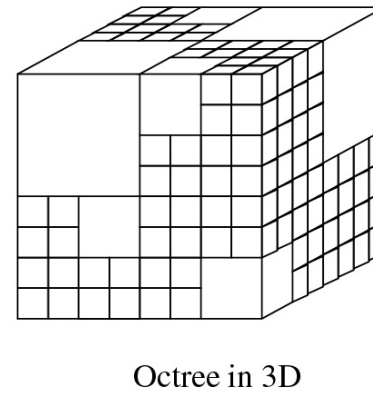
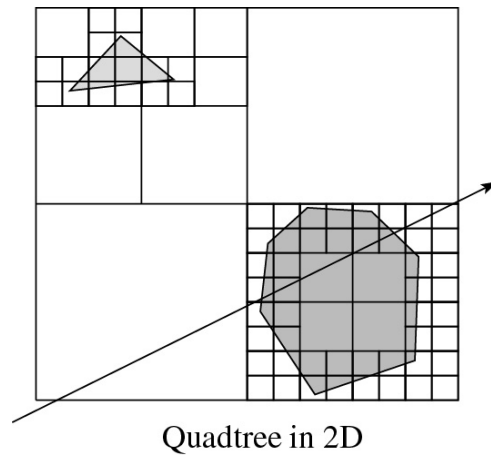
Idea:

- ◆ Partition space into cells (voxels)
- ◆ Associate each primitive with the cells it overlaps
- ◆ Trace ray through voxel array using fast incremental arithmetic to step from cell to cell

Q: Given a 10^6 triangle football stadium with a 10^6 triangle teapot on one of the seats, would a single uniform spatial subdivision be a good idea?

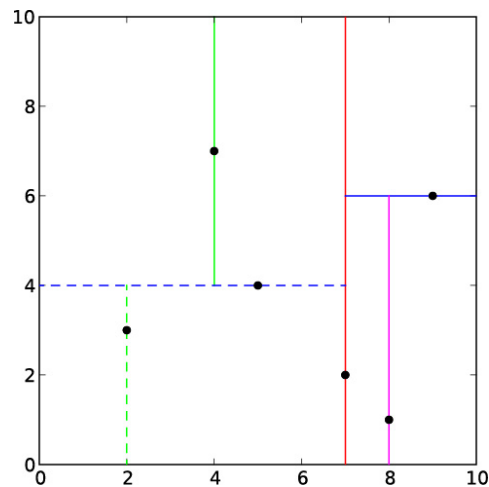
Non-uniform spatial subdivision: octrees

Another approach is **non-uniform spatial subdivision**. One version of this is octrees:

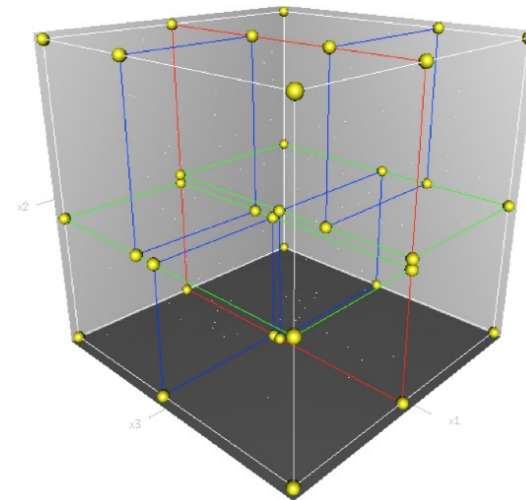


Non-uniform spatial subdivision: k -d trees

Another non-uniform subdivision is k -d
(k -dimensional) trees:



k -d tree ($d=2$)



k -d tree ($d=3$)

If the planes can be non-axis aligned, then you get BSP (binary space partitioning) trees.

Various combinations of these ray intersections techniques are also possible.

[Image credits: Wikipedia.]

Summary

What to take home from this lecture:

- ◆ An intuition for how ray tracers can be accelerated.