# Subdivision curves and surfaces

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## Reading

#### Recommended:

 Stollnitz, DeRose, and Salesin. Wavelets for Computer Graphics: Theory and Applications, 1996, section 6.1-6.3, 10.2, A.5. (online handout)

Note: there is an error in Stollnitz, et al., section A.5. Equation A.3 should read:

MV = VL

This is already fixed in the handout.

#### **Subdivision curves**

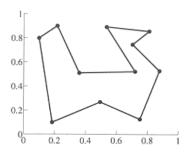
Idea:

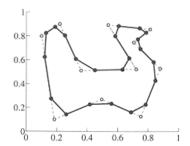
repeatedly refine the control polygon

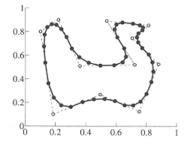
$$P_1 \rightarrow P_2 \rightarrow P_3 \rightarrow \cdots$$

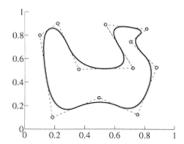
• curve is the limit of an infinite process

$$Q = \lim_{j \to \infty} P_j$$





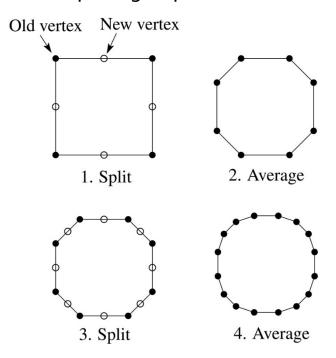




## Chaikin's algorithm

Chakin introduced the following "corner-cutting" scheme in 1974:

- Start with a piecewise linear curve
- Insert new vertices at the midpoints (the splitting step)
- Average each vertex with the "next" (clockwise) neighbor (the averaging step)
- Go to the splitting step



### **Averaging masks**

The limit curve is a quadratic B-spline!

Instead of averaging with the nearest neighbor, we can generalize by applying an **averaging mask** during the averaging step:

$$a = (..., a_{-1}, a_0, a_1, ...)$$

In the case of Chaikin's algorithm:

$$a = \begin{pmatrix} 0 & \frac{1}{2} & \frac{1}{2} \end{pmatrix}$$

Different averaging masks lead to different curves.

For example,

$$a = \begin{pmatrix} \frac{1}{4} & \frac{1}{2} & \frac{1}{4} \end{pmatrix}$$

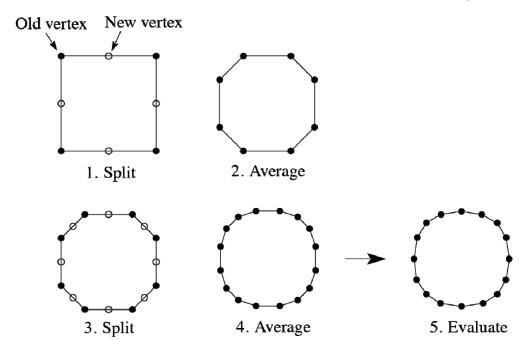
Leads to *cubic* B-spline curves.

#### **Limit curves and evaluation masks**

After each split-average step, we are closer to the **limit curve**.

We can stop after a number of split-average steps and apply an **evaluation mask** to push the vertices onto the limit curve.

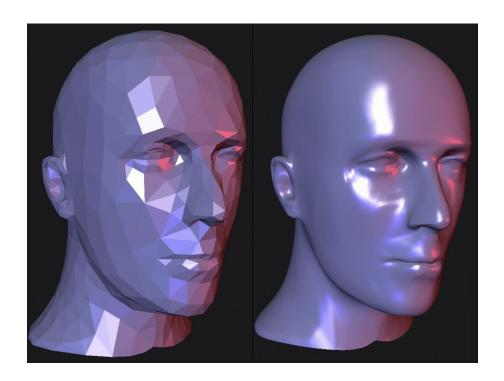
For Chaikin's algorithm, the evaluation masks is:  $e = \begin{pmatrix} 0 & \frac{1}{2} & \frac{1}{2} \end{pmatrix}$ 



For cubic subdivision, the evaluation masks is:  $e = \begin{pmatrix} \frac{1}{6} & \frac{2}{3} & \frac{1}{6} \end{pmatrix}$ 

# **Building complex models**

We can extend the idea of subdivision from curves to surfaces...



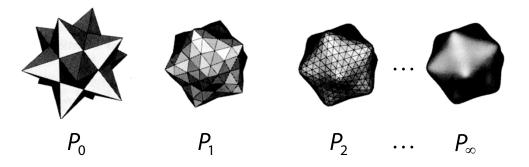
#### **Subdivision surfaces**

Chaikin's use of subdivision for curves inspired similar techniques for subdivision surfaces.

Iteratively refine a **control polyhedron** (or **control mesh**) to produce the limit surface

$$S = \lim_{j \to \infty} P_j$$

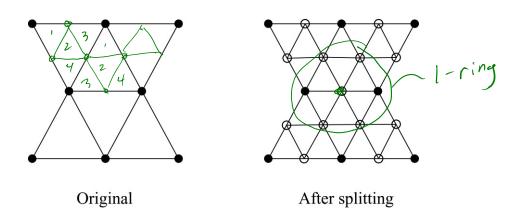
using splitting and averaging steps.



# Triangular subdivision

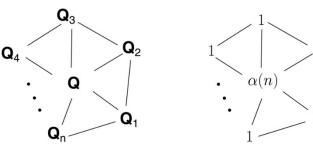
There are a variety of ways to subdivide a poylgon mesh.

A common choice for triangle meshes is 4:1 subdivision – each triangular face is split into four smaller triangles:



### Loop averaging step

Once again we can use **masks** for the averaging step:



Vertex neighorhood

Averaging mask (before affine normalization)

$$\mathbf{Q} \leftarrow \frac{\alpha(n)\mathbf{Q} + \mathbf{Q}_1 + \dots + \mathbf{Q}_n}{\alpha(n) + n}$$

where

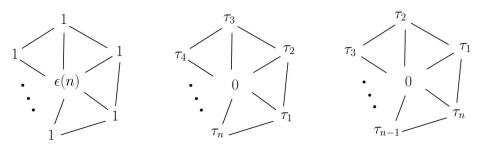
$$\alpha(n) = \frac{n(1-\beta(n))}{\beta(n)}$$
  $\beta(n) = \frac{5}{4} - \frac{(3+2\cos(2\pi/n))^2}{32}$ 

These values, due to Charles Loop, are carefully chosen to ensure smoothness – namely, tangent plane or normal continuity.

Note: tangent plane continuity is also know as G<sup>1</sup> continuity for surfaces.

### **Loop evaluation and tangent masks**

As with subdivision curves, we can split and average a number of times and then push the points to their limit positions.



Evaluation mask (before affine normalization)

Tangent masks

$$\mathbf{Q}^{\infty} = \frac{\varepsilon(n)\mathbf{Q} + \mathbf{Q}_1 + \dots + \mathbf{Q}_n}{\varepsilon(n) + n}$$

$$\mathbf{T}_1^{\infty} = \tau_1(n)\mathbf{Q}_1 + \tau_2(n)\mathbf{Q}_2 + \dots + \tau_n(n)\mathbf{Q}_n$$

$$\mathbf{T}_2^{\infty} = \tau_n(n)\mathbf{Q}_1 + \tau_1(n)\mathbf{Q}_2 + \dots + \tau_{n-1}(n)\mathbf{Q}_n$$

where

$$\varepsilon(n) = \frac{3n}{\beta(n)} \quad \tau_i(n) = \cos(2\pi i/n)$$

How do we compute the normal?

### **Recipe for subdivision surfaces**

As with subdivision curves, we can now describe a recipe for creating and rendering subdivision surfaces:

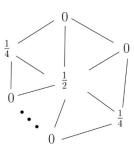
- Subdivide (split+average) the control polyhedron a few times. Use the averaging mask.
- Compute two tangent vectors using the tangent masks.
- Compute the normal from the tangent vectors.
- Push the resulting points to the limit positions.
   Use the evaluation mask.
- Render!

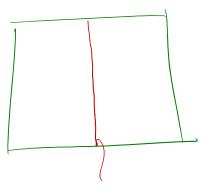
## Adding creases without trim curves

For NURBS surfaces, adding sharp features like creases required the use of trim curves.

1/2 1/2 1/4 1/4 1/4 1/4 1/4 1/4 1/4

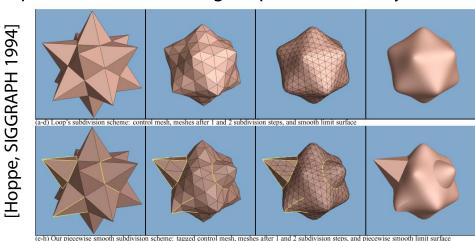
For subdivision surfaces, we can just modify the subdivision masks. E.g., we can mark some edges and vertices as "creases" and modify the subdivision mask for them (and their children):





This gives rise to  $G^0$  continuous surfaces (i.e., having positional but not tangent plane continuity).

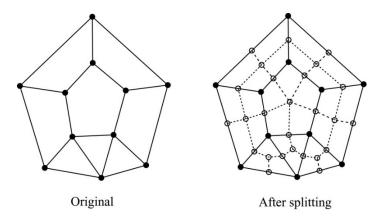




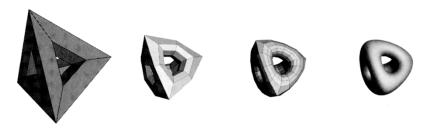
### **Catmull-Clark subdivision**

4:1 subdivision of triangles is sometimes called a **face scheme** for subdivision, as each face begets more faces.

An alternative face scheme starts with arbitrary polygon meshes and inserts vertices along edges and at face centroids:



#### **Catmull-Clark subdivision:**



Note: after the first subdivision, all polygons are quadilaterals in this scheme.

#### **Catmull-Clark subdivision (cont'd)**

Here's an example using Catmull-Clark surfaces (based on subdividing quadrilateral meshes):



This particular example uses the hybrid technique of DeRose, et al., which applies sharp subdivision rules at some creases for a finite number of steps, and then switches to smooth subdivision, giving more gentle creases. This technique was used in Geri's Game.

#### **Summary**

#### What to take home:

- The meanings of all the **boldfaced** terms.
- How to perform the splitting and averaging steps on subdivision curves.
- How to perform mesh splitting steps for subdivision surfaces, especially Loop.
- How to construct and render subdivision surfaces from their averaging masks, evaluation masks, and tangent masks.