# Lecture 4

# Derivatives and edges





### Administrative

A1 is out

- It is graded
- Due April 18







### Administrative

Recitation

• Friday 1:30-2:20pm @ BAG 154

This week:

We will go over Python & Numpy basics

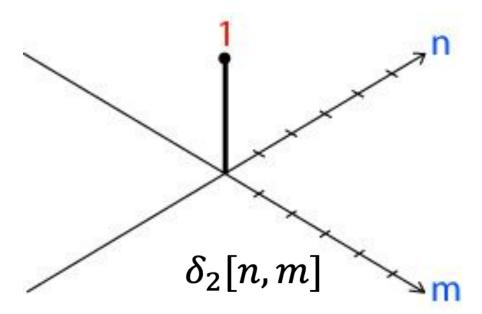
- will have polls
- prep for final exam

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#### Lecture 4 - 3

### So far: 2D impulse function

- A special function
- 1 at the origin [0,0].
- 0 everywhere else



Lecture 4 - 4

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# So far: We get the impulse response when we pass an impulse function through a LSI system

• The moving average filter equation again:  $g[n,m] = \frac{1}{9} \sum_{n=1}^{1} \sum_{j=1}^{1} f[n-k,m-l]$ 

$$\begin{aligned} \delta_2[n,m] \xrightarrow{S} h[n,m] \\ \text{Pass in an impulse function} \\ \end{aligned}$$

$$h[n,m] = \begin{bmatrix} 1/9 & 1/9 & 1/9 \\ 1/9 & 1/9 & 1/9 \\ 1/9 & 1/9 & 1/9 \end{bmatrix}$$

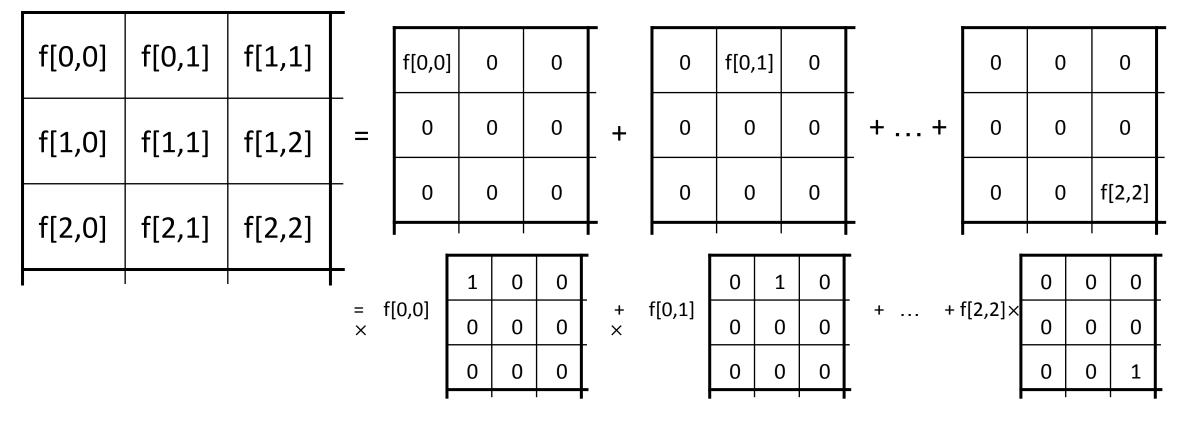
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### So far: write down *f* as a sum of impulses

Let's say our input *f* is a 3x3 image:



 $= f[0,0] \cdot \delta_2[n,m] + f[0,1] \cdot \delta_2[n,m-1] + \ldots + f[2,2] \cdot \delta_2[n-2,m-2]$ 

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### So far: write down *f* as a sum of impulses

• Superposition:

$$S\{lpha f_1[n,m]+eta f_2[n,m]\}=lpha S\{f_1[n,m]\}+eta S\{f_2[n,m]\}$$

$$\mathcal{S}[\sum_{i} \alpha_{i} f_{i}[n, m]] = \sum_{i} \alpha_{i} \mathcal{S}[f_{i}[n, m]]$$

• We can now use superposition to see what the output g is:

$$\begin{split} f[n,m] &\xrightarrow{S} g[n,m] \\ f[n,m] &= \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} f[k,l] \cdot \delta_2[n-k,m-l] \\ & \boxed{\frac{S}{\rightarrow} \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} f[k,l] \cdot S\{\delta_2[n-k,m-l]\} } \end{split}$$

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#### Lecture 4 - 7

 $l]\}$ 

### So far: We derived convolutions

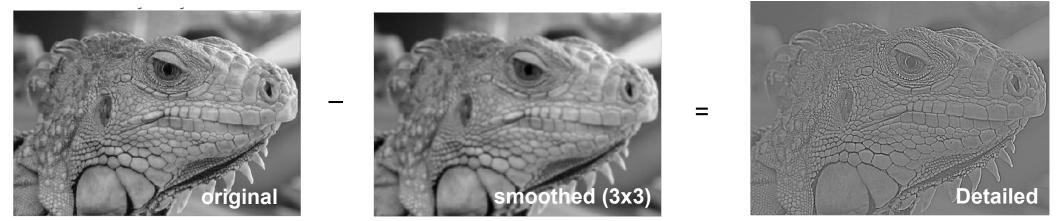
- An LSI system is completely specified by its impulse response.
  - $\circ$  For any input *f*, we can compute the output *g* in terms of the impulse response *h*.

$$f[n,m] * h[n,m] = \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} f[k,l] \cdot h[n-k,m-l]$$

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Discrete Convolution

### So far: We created a sharpening system by combining filters



#### Let's add it back to get a sharpening system:



#### Raymond Yu

#### Lecture 4 - 9

### (Cross) correlation – symbol: \*\*

Cross correlation of two 2D signals f[n,m] and h[n,m]

$$f[n,m] ** h[n,m] = \sum_{k} \sum_{l} f[k,l]h[n+k,m+l]$$

Equivalent to a convolution without the flip

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## Today's agenda

- Convolutions and Cross-Correlation
- Edge detection
- Image Gradients
- A simple edge detector



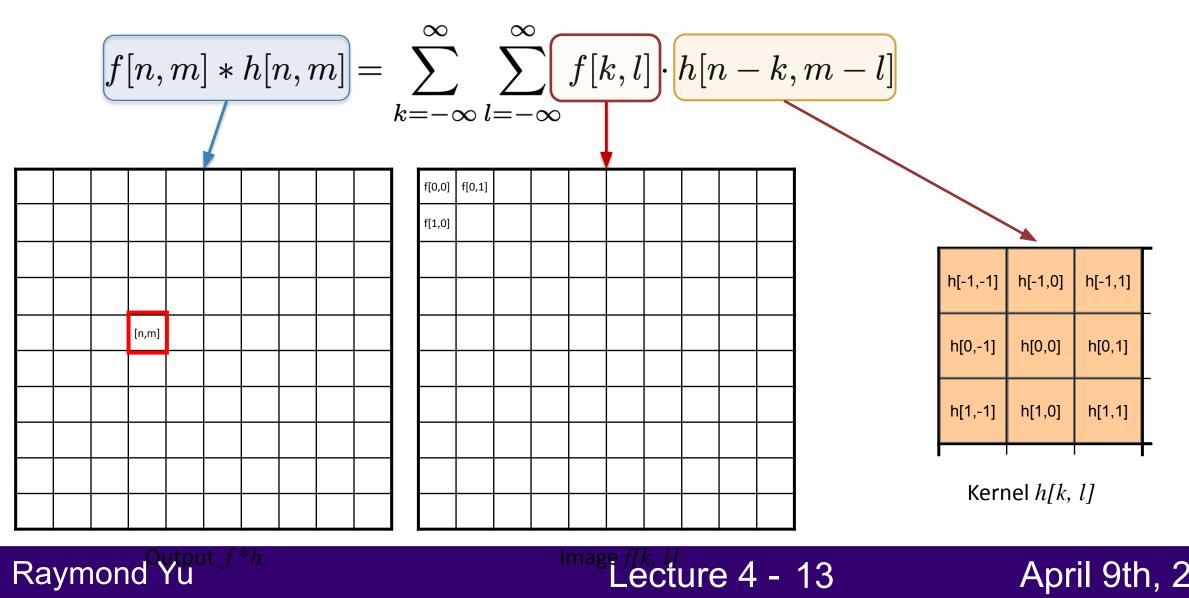


## Today's agenda

- Convolutions and Cross-Correlation
- Edge detection
- Image Gradients
- A simple edge detector

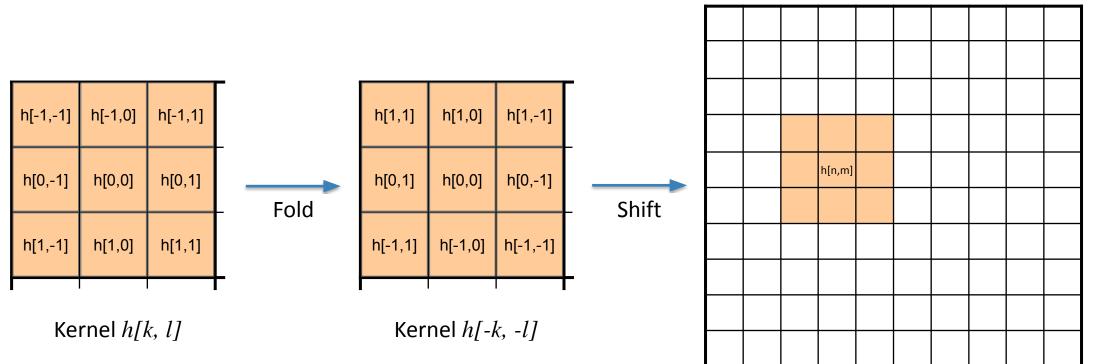






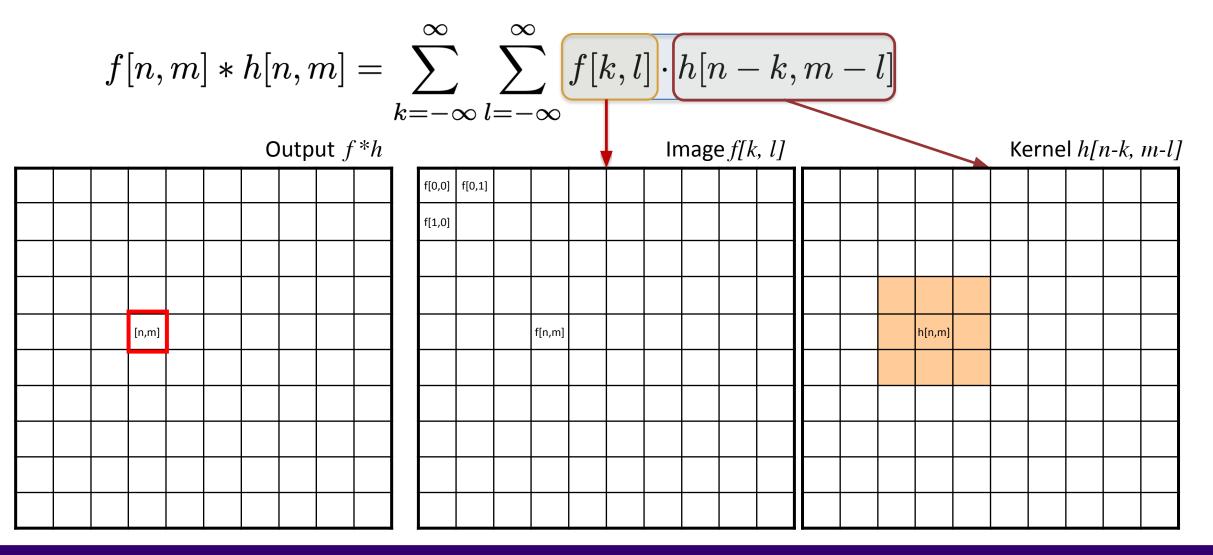
$$f[n,m] * h[n,m] = \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} f[k,l] \cdot \frac{h[n-k,m-l]}{k}$$

Kernel *h*[*n*-*k*, *m*-*l*]



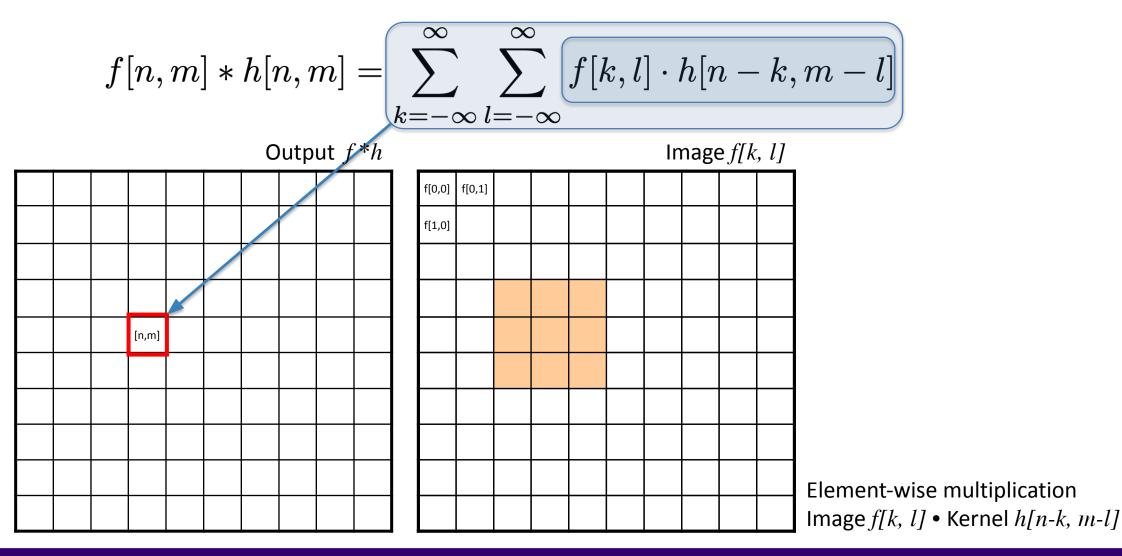
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#### Lecture 4 - 14



#### Raymond Yu

#### Lecture 4 - 15



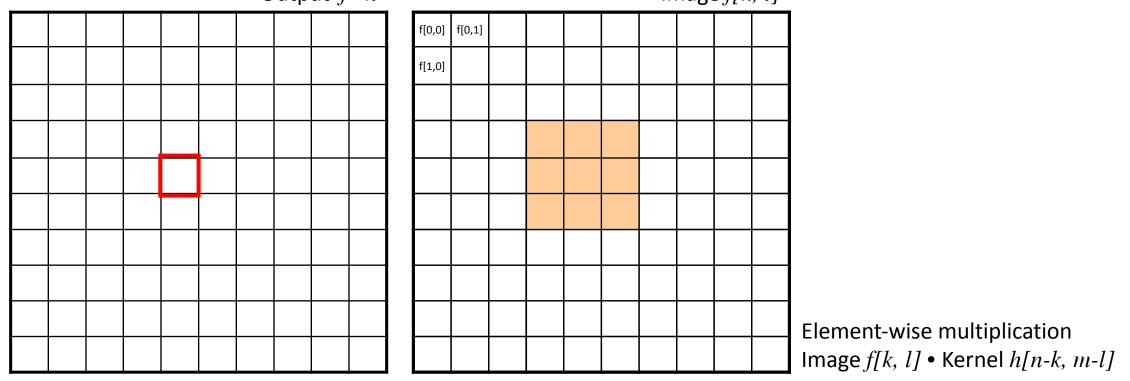
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$$f[n,m] * h[n,m] = \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} f[k,l] \cdot h[n-k,m-l]$$

Output f \*h

Image *f[k, l]* 



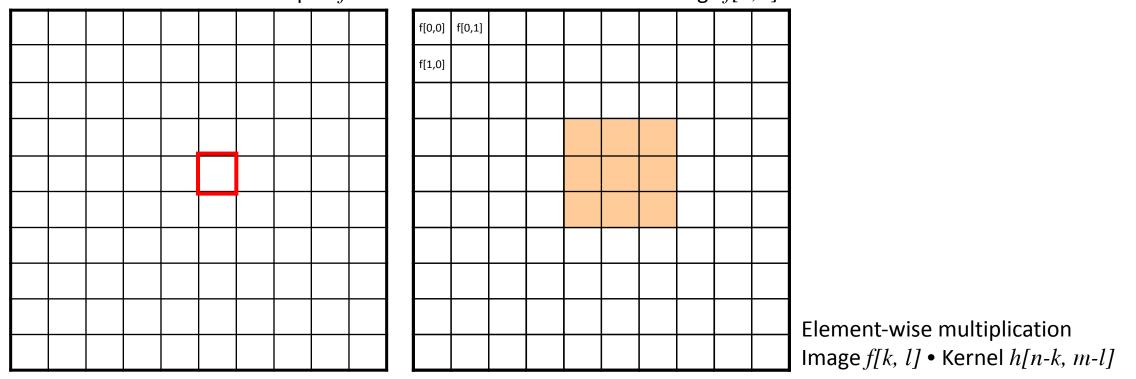
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#### Lecture 4 - 17

$$f[n,m] * h[n,m] = \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} f[k,l] \cdot h[n-k,m-l]$$

Output f \*h

Image *f[k, l]* 



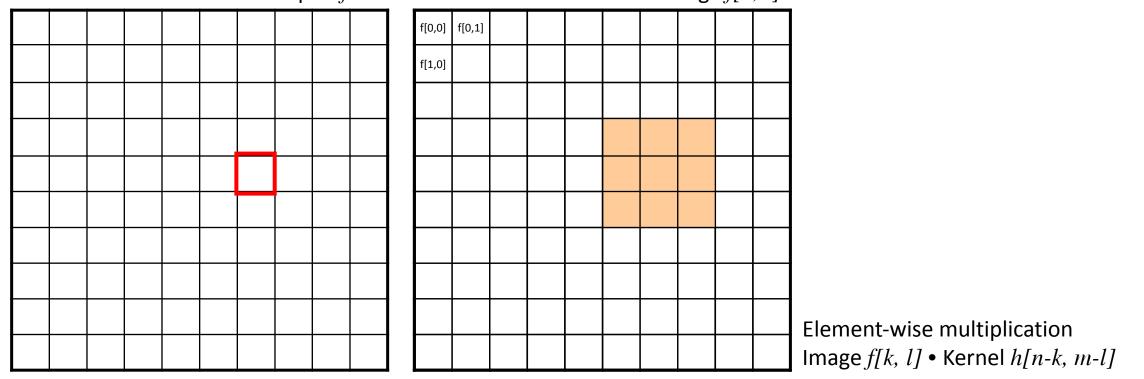
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#### Lecture 4 - 18

$$f[n,m] * h[n,m] = \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} f[k,l] \cdot h[n-k,m-l]$$

Output f \*h

Image *f[k, l]* 



#### Raymond Yu

#### Lecture 4 - 19

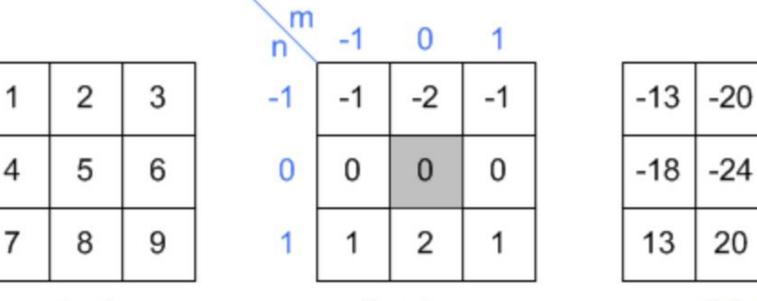
• 
$$f[n,m] * h[n,m] = \sum_{k=-\infty}^{\infty} \sum_{l=-\infty}^{\infty} f[k,l] \cdot h[n-k,m-l]$$

#### Algorithm:

Raymond Yu

- Fold h[k, l] about origin to form h[-k, -l]
- Shift the folded results by n, m to form h[n k, m l]
- Multiply *h*[*n* − *k*, *m* − *l*] by *f*[*k*, *l*]
- Sum over all k, l, store result in output position [n, m]
- Repeat for every *n*, *m*





Input

Kernel

Output

-17

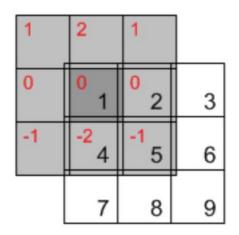
-18

17

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 $= x[-1,-1] \cdot h[1,1] + x[0,-1] \cdot h[0,1] + x[1,-1] \cdot h[-1,1]$  $+ x[-1,0] \cdot h[1,0] + x[0,0] \cdot h[0,0] + x[1,0] \cdot h[-1,0]$  $+ x[-1,1] \cdot h[1,-1] + x[0,1] \cdot h[0,-1] + x[1,1] \cdot h[-1,-1]$  $= 0 \cdot 1 + 0 \cdot 2 + 0 \cdot 1 + 0 \cdot 0 + 1 \cdot 0 + 2 \cdot 0 + 0 \cdot (-1) + 4 \cdot (-2) + 5 \cdot (-1) = -13$ 

-13	-20	-17
-18	-24	-18
13	20	17

Output

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1	2	1
<mark>0</mark> 1	<mark>0</mark> 2	<mark>0</mark> 3
-1 4	<mark>-2</mark> 5	-1 6
7	8	9

 $= x[0,-1] \cdot h[1,1] + x[1,-1] \cdot h[0,1] + x[2,-1] \cdot h[-1,1]$  $+ x[0,0] \cdot h[1,0] + x[1,0] \cdot h[0,0] + x[2,0] \cdot h[-1,0]$  $+ x[0,1] \cdot h[1,-1] + x[1,1] \cdot h[0,-1] + x[2,1] \cdot h[-1,-1]$  $= 0 \cdot 1 + 0 \cdot 2 + 0 \cdot 1 + 1 \cdot 0 + 2 \cdot 0 + 3 \cdot 0 + 4 \cdot (-1) + 5 \cdot (-2) + 6 \cdot (-1) = -20$ 

-13	-20	-17
-18	-24	-18
13	20	17

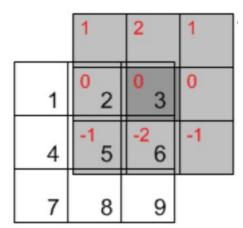
Output

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 $x[1,-1] \cdot h[1,1] + x[2,-1] \cdot h[0,1] + x[3,-1] \cdot h[-1,1]$  $+ x[1,0] \cdot h[1,0] + x[2,0] \cdot h[0,0] + x[3,0] \cdot h[-1,0]$  $+ x[1,1] \cdot h[1,-1] + x[2,1] \cdot h[0,-1] + x[3,1] \cdot h[-1,-1]$  $= 0 \cdot 1 + 0 \cdot 2 + 0 \cdot 1 + 2 \cdot 0 + 3 \cdot 0 + 0 \cdot 0 + 5 \cdot (-1) + 6 \cdot (-2) + 0 \cdot (-1) = -17$ 

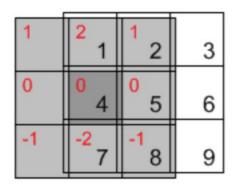
-13	-20	-17
-18	-24	-18
13	20	17

Output

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 $\begin{aligned} &= x[-1,0] \cdot h[1,1] + x[0,0] \cdot h[0,1] + x[1,0] \cdot h[-1,1] \\ &+ x[-1,1] \cdot h[1,0] + x[0,1] \cdot h[0,0] + x[1,1] \cdot h[-1,0] \\ &+ x[-1,2] \cdot h[1,-1] + x[0,2] \cdot h[0,-1] + x[1,2] \cdot h[-1,-1] \\ &= 0 \cdot 1 + 1 \cdot 2 + 2 \cdot 1 + 0 \cdot 0 + 4 \cdot 0 + 5 \cdot 0 + 0 \cdot (-1) + 7 \cdot (-2) + 8 \cdot (-1) = -18 \end{aligned}$ 

-13	-20	-17
-18	-24	-18
13	20	17

Output

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1	<mark>2</mark> 2	1 3
<mark>0</mark> 4	<mark>0</mark> 5	<mark>0</mark> 6
<sup>-1</sup> 7	-2 8	-1 9

 $= x[0,0] \cdot h[1,1] + x[1,0] \cdot h[0,1] + x[2,0] \cdot h[-1,1]$  $+ x[0,1] \cdot h[1,0] + x[1,1] \cdot h[0,0] + x[2,1] \cdot h[-1,0]$  $+ x[0,2] \cdot h[1,-1] + x[1,2] \cdot h[0,-1] + x[2,2] \cdot h[-1,-1]$  $= 1 \cdot 1 + 2 \cdot 2 + 3 \cdot 1 + 4 \cdot 0 + 5 \cdot 0 + 6 \cdot 0 + 7 \cdot (-1) + 8 \cdot (-2) + 9 \cdot (-1) = -24$ 

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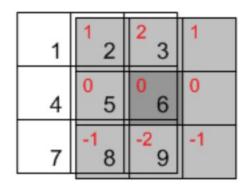
-13	-20	-17
-18	-24	-18
13	20	17

Output

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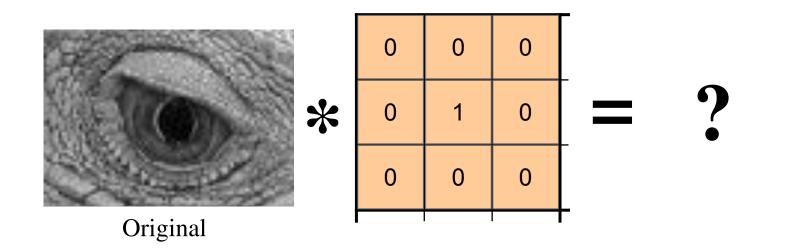
 $= x[1,0] \cdot h[1,1] + x[2,0] \cdot h[0,1] + x[3,0] \cdot h[-1,1]$  $+ x[1,1] \cdot h[1,0] + x[2,1] \cdot h[0,0] + x[3,1] \cdot h[-1,0]$  $+ x[1,2] \cdot h[1,-1] + x[2,2] \cdot h[0,-1] + x[3,2] \cdot h[-1,-1]$  $= 2 \cdot 1 + 3 \cdot 2 + 0 \cdot 1 + 5 \cdot 0 + 6 \cdot 0 + 0 \cdot 0 + 8 \cdot (-1) + 9 \cdot (-2) + 0 \cdot (-1) = -18$ 

-13	-20	-17
-18	-24	-18
13	20	17

Output

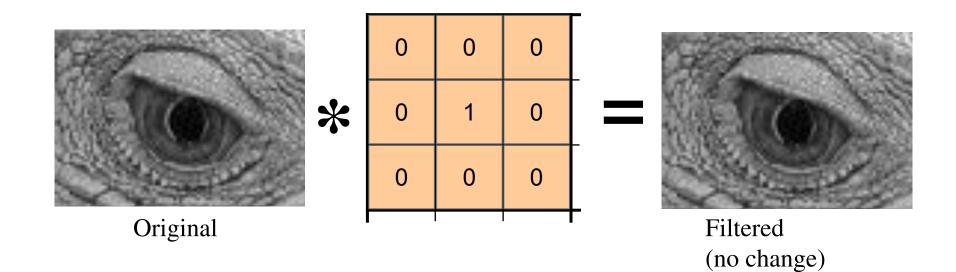
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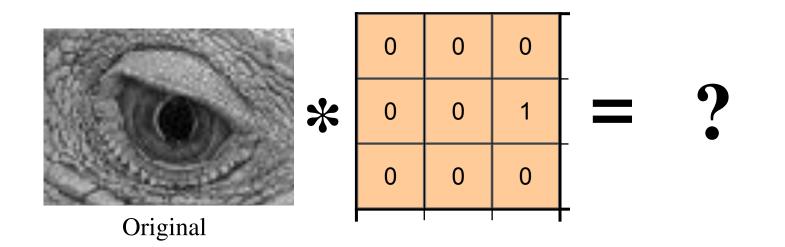






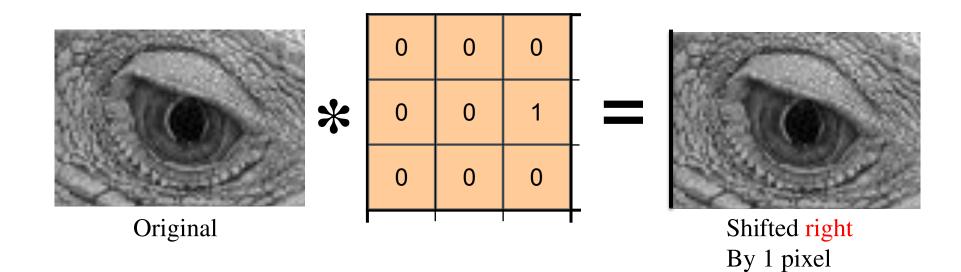
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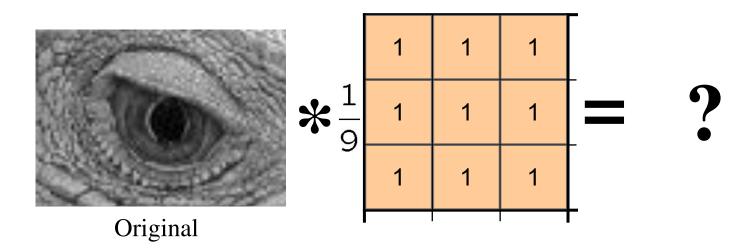






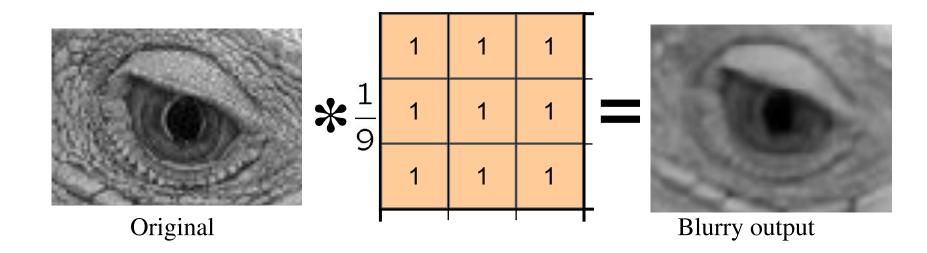
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#### Lecture 4 - 31









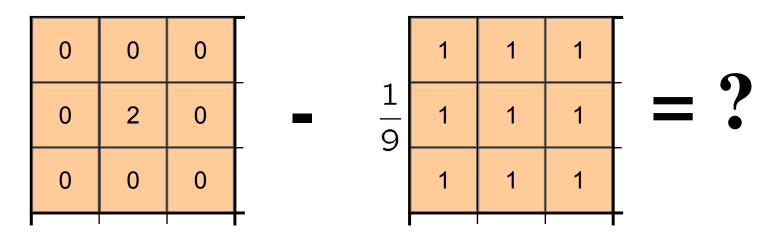




### What happens if a system contains multiple filters?



Original

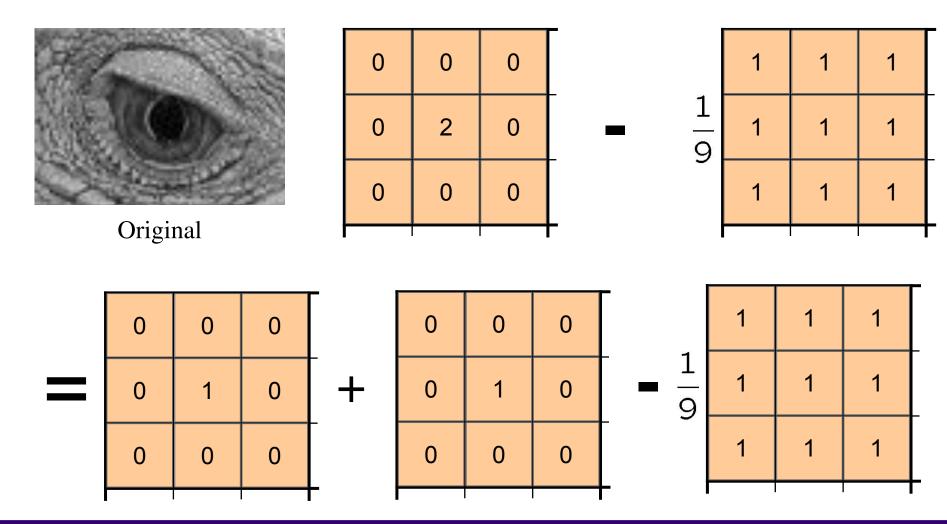


(Note that filter sums to 1)

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### What happens if a system contains multiple filters?

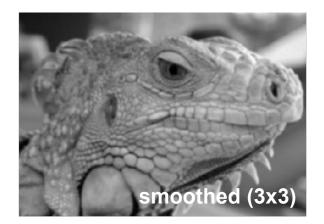


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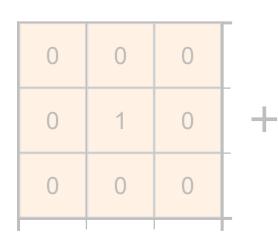
Lecture 4 - 35

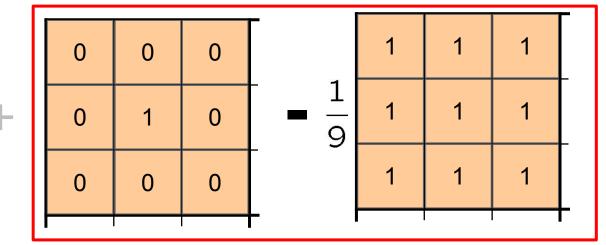
### What does blurring take away?







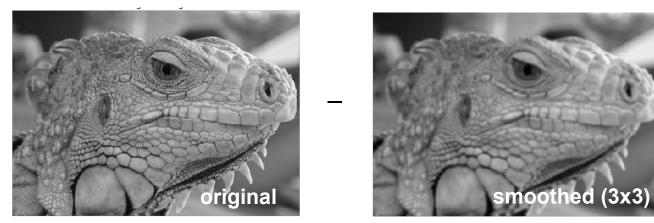




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# What does blurring take away?





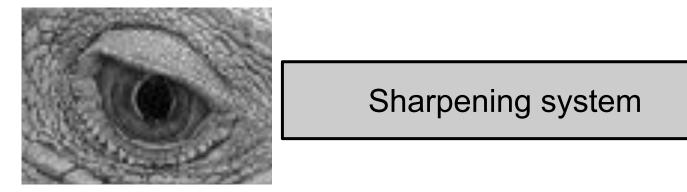
#### Let's add it back to get a sharpening system:

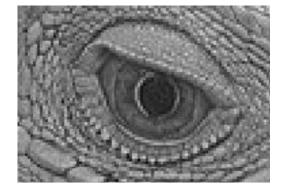


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## Lecture 4 - 37

# Convolution in 2D – Sharpening filter





Original

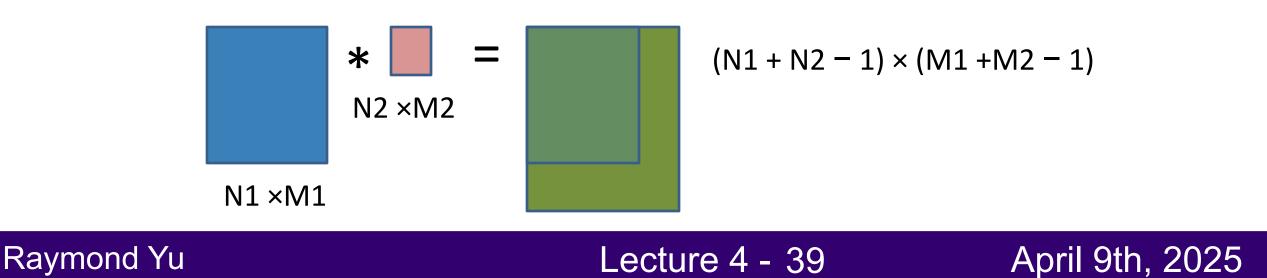
Sharpening system: Accentuates differences with local average

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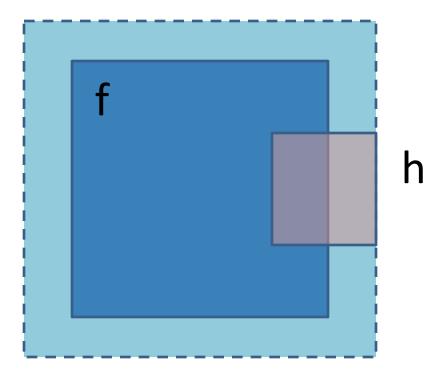
# Implementation detail: Image support and edge effect

- •A computer will only convolve finite support signals.
  - That is: images that are zero for n,m outside some rectangular region
- numpy's convolution performs 2D convolution of finite-support signals.



# Image support and edge effect

- •A computer will only convolve finite support signals.
- What happens at the edge?



Raymond Yu

- zero "padding"
- edge value replication
- mirror extension
  - **MORE** (beyond the scope of this class)

# Lecture 4 - 40

# Today's agenda

- Convolutions and Cross-Correlation
- Edge detection
- Image Gradients
- A simple edge detector





# (Cross) correlation – symbol: \*\*

Cross correlation of two 2D signals f[n,m] and h[n,m]

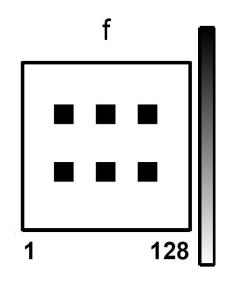
$$f[n,m] ** h[n,m] = \sum_{k} \sum_{l} f[k,l]h[n+k,m+l]$$

- Equivalent to a convolution without the flip
- Use it to measure 'similarity' between f and h.

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# (Cross) correlation – example



Courtesy of J. Fessler

# April 9th, 2025

## Lecture 4 - 43

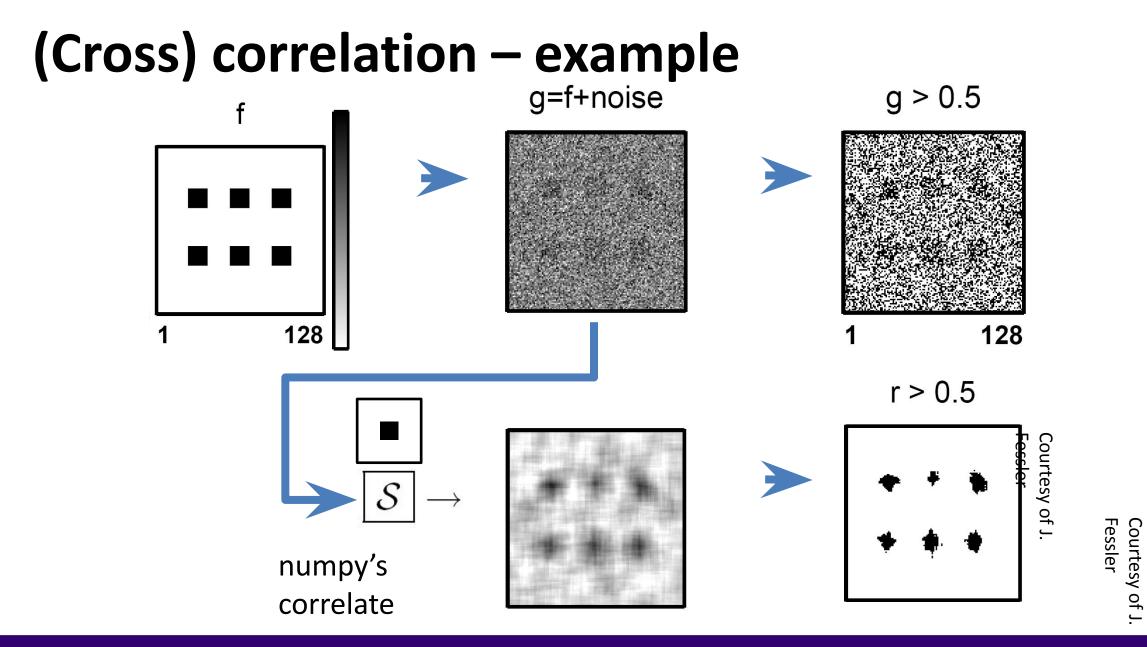
## Raymond Yu

# 

Raymond Yu

Courtesy of J Fessler

# Lecture 4 - 44

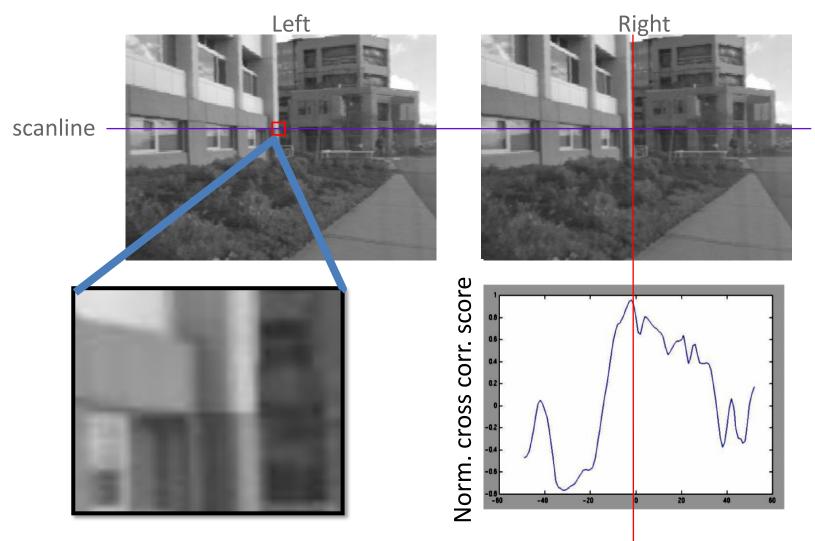


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#### Lecture 4 - 45

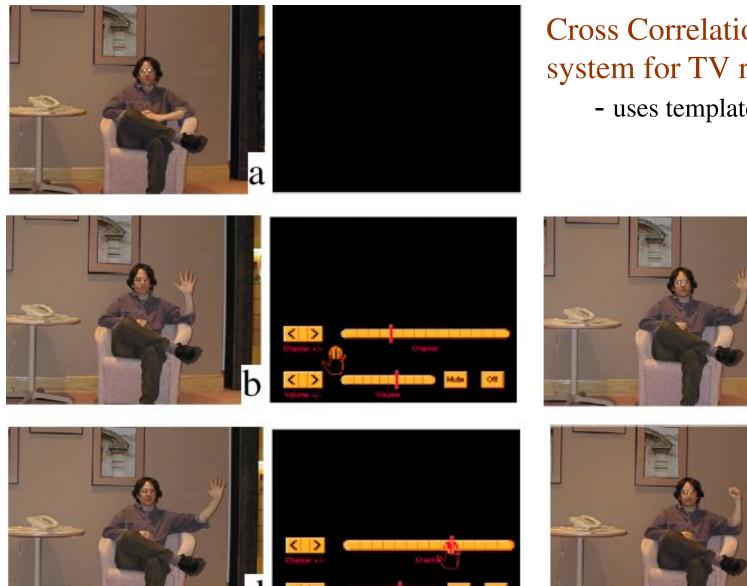
#### Raymond Yu

# (Cross) correlation – example



### Raymond Yu

# Lecture 4 - 46



# **Cross Correlation Application: Vision** system for TV remote control

- uses template matching

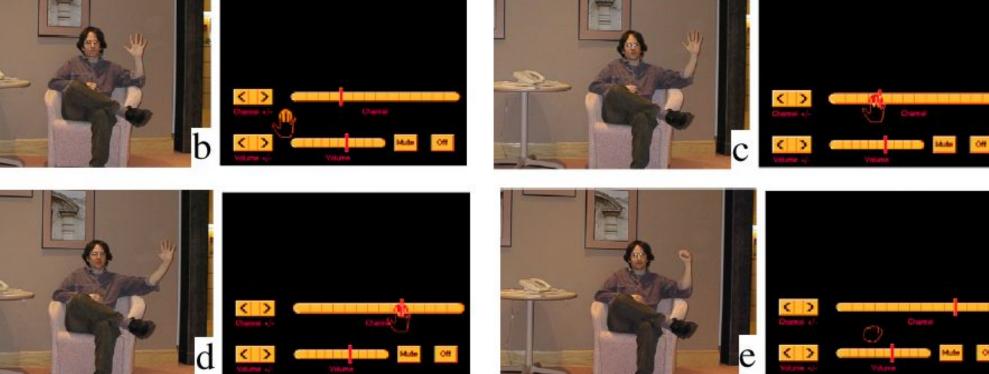


Figure from "Computer Vision for Interactive Computer Graphics," W.Freeman et al, IEEE Computer Graphics and Applications, 1998 copyright 1998, IEEE

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# **Properties of cross correlation**

• Associative property:

$$(f * * h_1) * * h_2 = f * * (h_1 * * h_2)$$

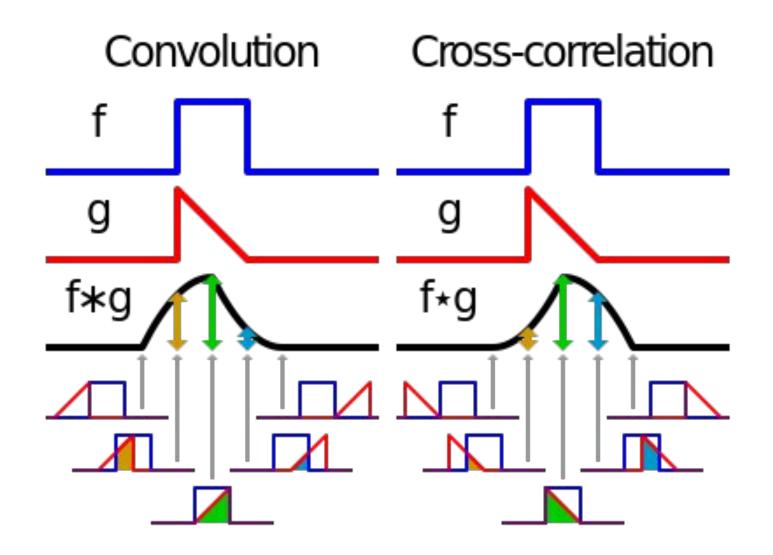
• Distributive property:

$$f \ast \ast (h_1 + h_2) = (f \ast \ast h_1) + (f \ast \ast h_2)$$

The order doesn't matter!  $h_1 * * h_2 = h_2 * * h_1$ 

## Raymond Yu

# Lecture 4 - 48





Lecture 4 - 49

# Convolution vs. (Cross) Correlation

- When is correlation equivalent to convolution?
- In other words, Q. when is f\*\*g = f\*g?





# Convolution vs. (Cross) Correlation

• A <u>convolution</u> is an integral that expresses the amount of overlap of one function as it is shifted over another function.

convolution is a filtering operation

• <u>Correlation</u> compares the *similarity* of *two* sets of *data*. Correlation computes a measure of similarity of two input signals as they are shifted by one another. The correlation result reaches a maximum at the time when the two signals match best .

correlation is a measure of relatedness of two signals

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# Lecture 4 - 51

# What we will learn today

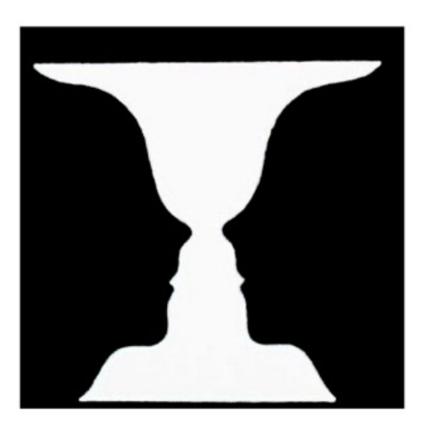
- Convolutions and Cross-Correlation
- Edge detection
- Image Gradients
- A simple edge detector

Some background reading: Forsyth and Ponce, Computer Vision, Chapter 8

# Raymond Yu

Lecture 4 - 52

# Q. What do you see?









- (A) Cave painting at Chauvet, France, about 30,000B.C.;
- (B) Aerial photograph of the picture of a monkey as part of the Nazca Lines geoglyphs, Peru, about 700 200 B.C.;
- (C) Shen Zhou (1427-1509A.D.): Poet on a mountain top, ink on paper, China;
- (D) Line drawing by 7-year old I. Lleras (2010 A.D.).

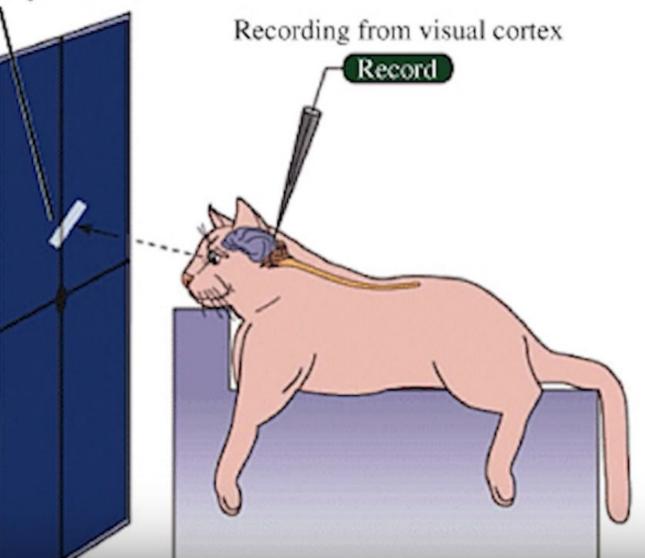


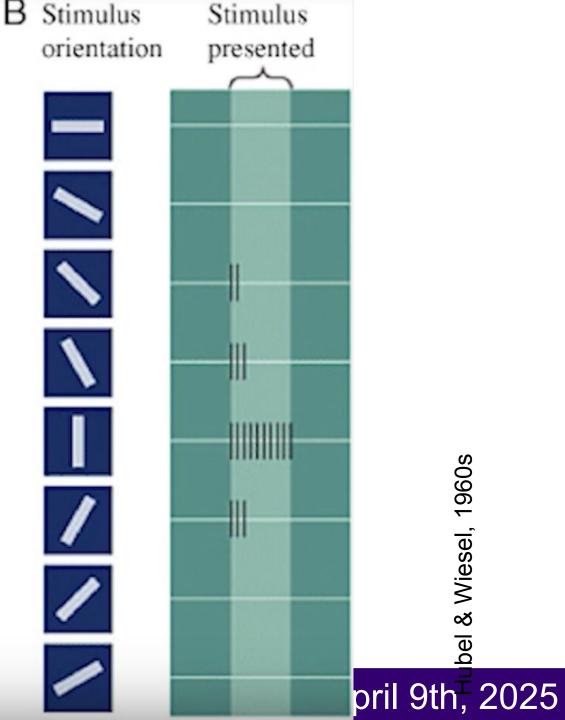
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## Lecture 4 -

# A Experimental setup

Light bar stimulus projected on screen







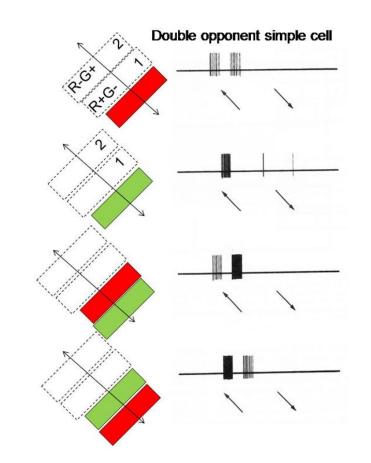
# Raymond Yu

# Lecture 4 - 56

# We know edges are special from human (mammalian) vision studies



Raymond Yu 1960s





# We know edges are special from human (mammalian) vision studies

152 Biederman

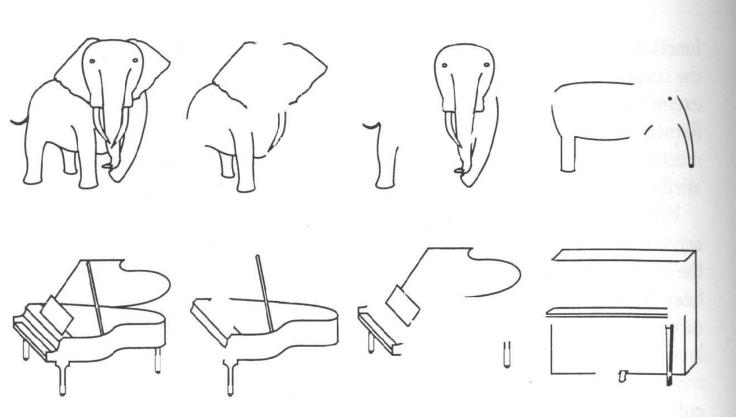
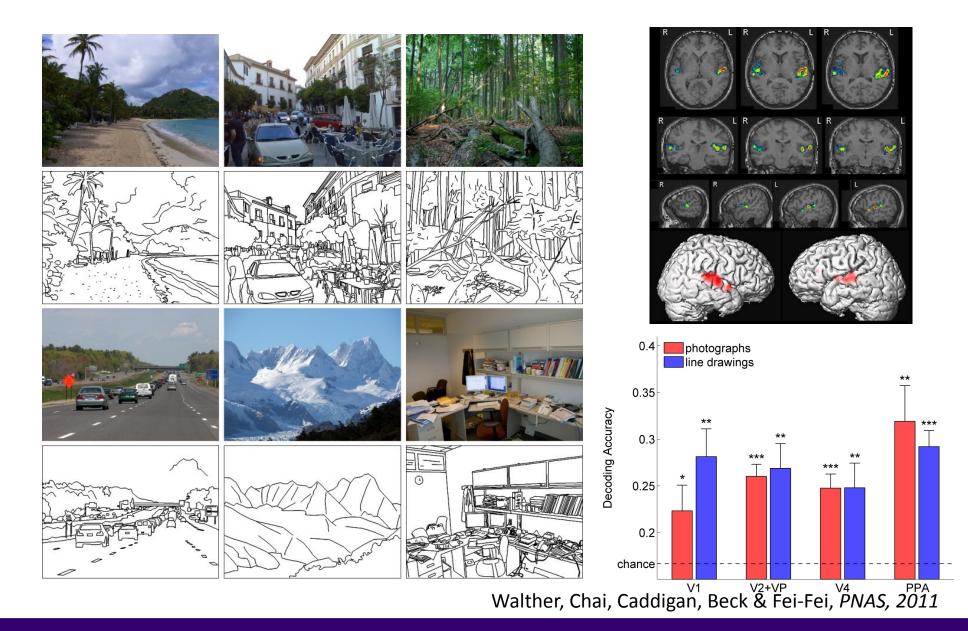


Figure 4.14 Complementary-part images. From an original intact image (left column), two complemen-

Lecture 4 -

# April 9th, 2025

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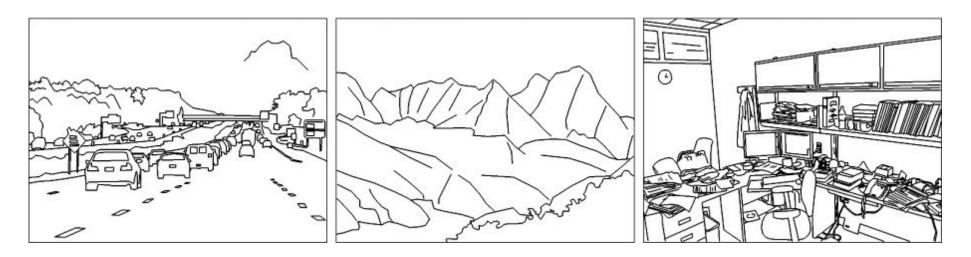


## Raymond Yu

## Lecture 4 - 59

# Edge detection

- **Goal:** Identify sudden changes (discontinuities) in an image
  - Intuitively, most semantic and shape information from the image can be encoded in the edges
  - $\, \odot \,$  More compact than pixels
- Ideal: artist's line drawing (but artist is also using object-level knowledge)



## Raymond Yu

## Lecture 4 - 60

# Why do we care about edges?

• Extract information, recognize objects

 Recover geometry and viewpoint
 Vertical vanishing point (at infinity)
 Vanishing point
 Vanishing point

## Raymond Yu



# Origins of edges



surface normal discontinuity

depth discontinuity

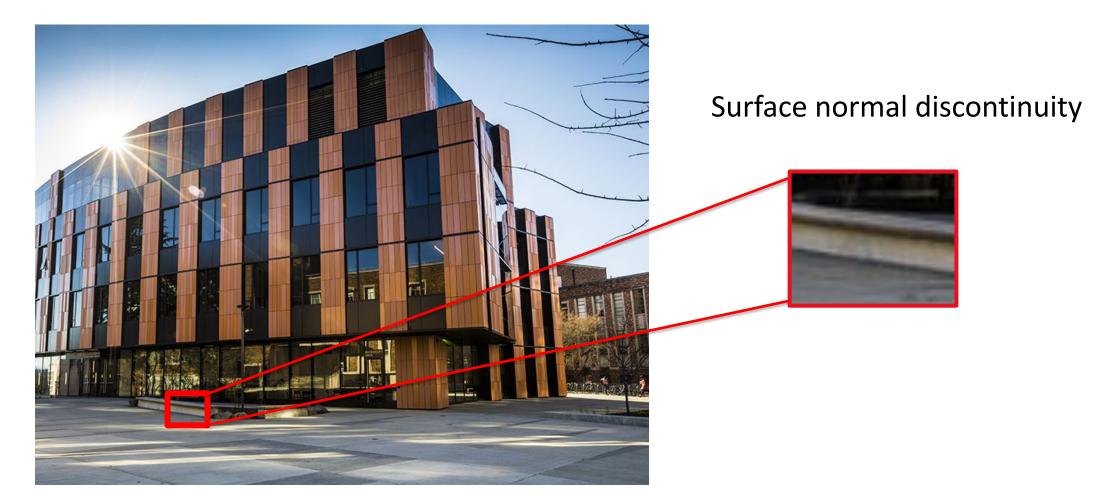
surface color discontinuity

illumination discontinuity

# Raymond Yu

## Lecture 4 - 62

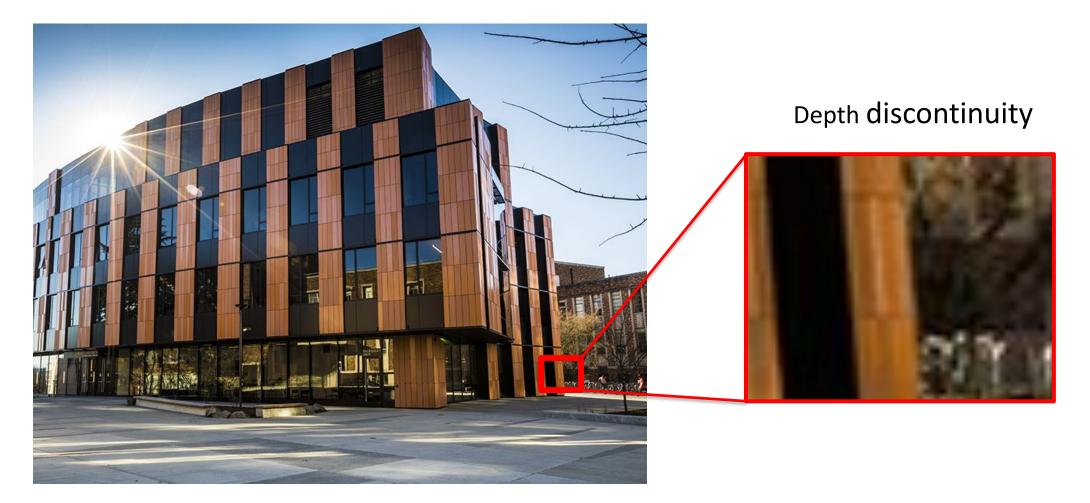
# Closeup of edges



## Raymond Yu



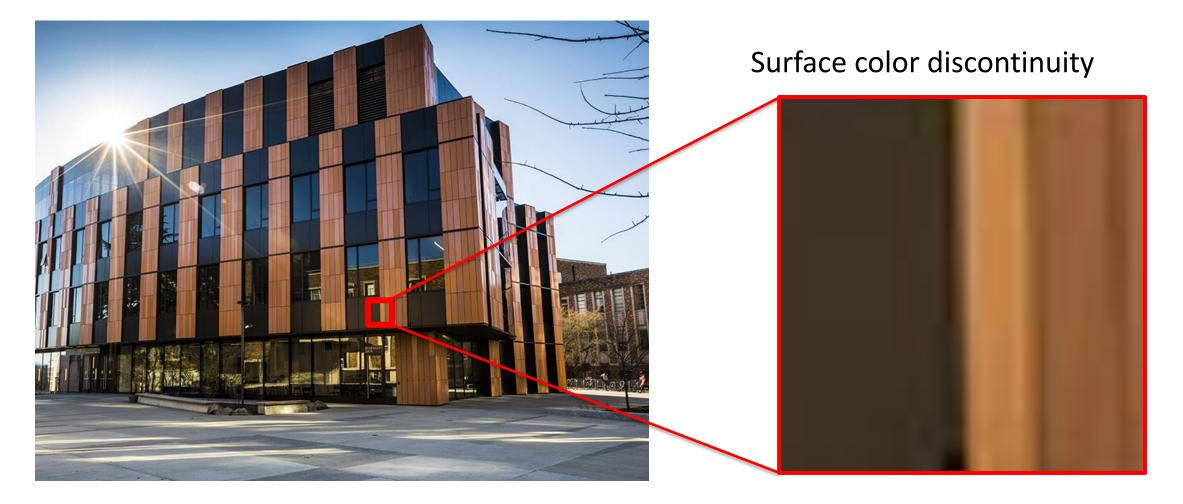
# Closeup of edges



## Raymond Yu

# Lecture 4 - 64

# Closeup of edges



## Raymond Yu

## Lecture 4 - 65

# What we will learn today

- Convolutions and Cross-Correlation
- Edge detection
- Image Gradients
- A simple edge detector





# Review: Derivatives in 1D - example

$$y = x^2 + x^4$$

Q. What is the dy/dx?





# Review: Derivatives in 1D - example

$$y = x^{2} + x^{4}$$
$$\frac{dy}{dx} = 2x + 4x^{3}$$

#### Raymond Yu

## Lecture 4 - 68

# Derivatives in 1D - example

$$y = x^{2} + x^{4}$$

$$y = \sin x + e^{-x}$$

$$\frac{dy}{dx} = 2x + 4x^{3}$$
Q. What is the dy/dx?



# Derivatives in 1D - example

$$y = x^{2} + x^{4}$$
$$y = \sin x + e^{-x}$$
$$\frac{dy}{dx} = 2x + 4x^{3}$$
$$\frac{dy}{dx} = \cos x + (-1)e^{-x}$$

### Raymond Yu

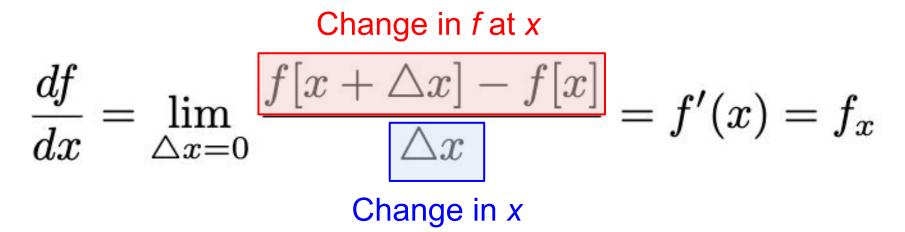
Lecture 4 - 70

# Approximating derivatives using numerical differentiation

$$\frac{df}{dx} = \lim_{\Delta x=0} \frac{f[x + \Delta x] - f[x]}{\Delta x} = f'(x) = f_x$$



# Approximating derivatives using numerical differentiation









## In discrete derivatives with images, smallest value of x is 1 pixel

$$\begin{aligned} \frac{df}{dx} &= \lim_{\Delta x=0} \frac{f[x + \Delta x] - f[x]}{\Delta x} = f'(x) = f_x \\ &= \frac{f[x + 1] - f[x]}{1} \\ &= f[x + 1] - f[x] \end{aligned}$$

This is called a forward derivative

Raymond Yu

Lecture 4 - 73

# But change at x can be measured in many different ways

$$\frac{df}{dx} = f[x] - f[x - 1]$$

#### Raymond Yu

#### Lecture 4 - 74

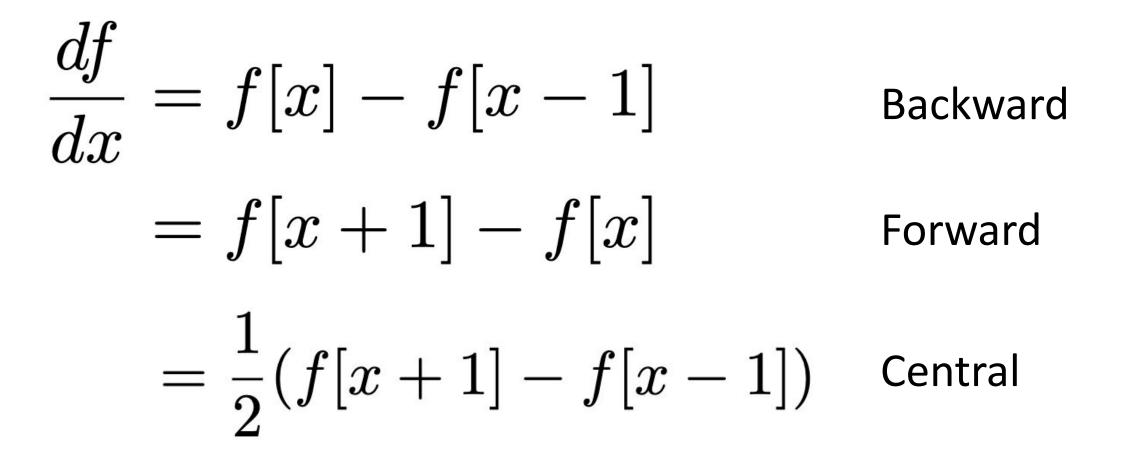
# But change at x can be measured in many different ways

$$\label{eq:general} \begin{split} \frac{df}{dx} &= f[x] - f[x-1] & \mbox{Backward} \\ &= f[x+1] - f[x] & \mbox{Forward} \end{split}$$





# But change at x can be measured in many different ways



#### Raymond Yu

Lecture 4 - 76

Using Backward differentiation

$$g[n,m] = ??$$

Q. What is the equation in width (2nd) dimension?





Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

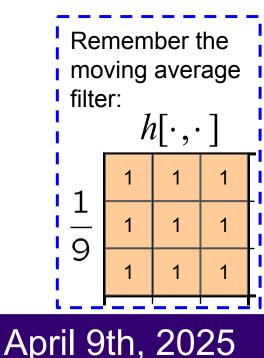




Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Let's write this as a filter

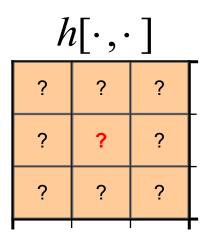


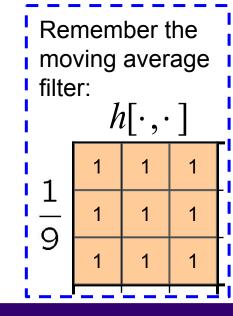
#### Raymond Yu

Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Let's write this as a filter





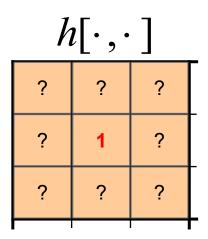
#### Raymond Yu

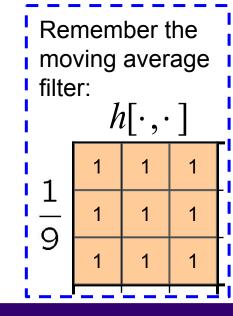
#### Lecture 4 - 80

Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Let's write this as a filter





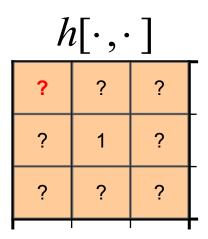
#### Raymond Yu

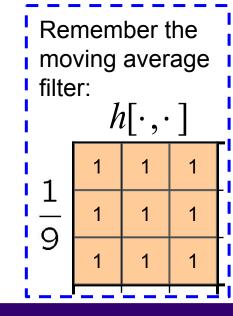
#### Lecture 4 - 81

Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Let's write this as a filter





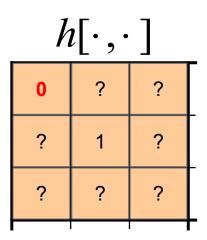
#### Raymond Yu

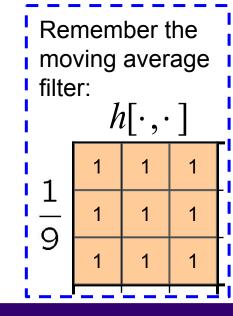
#### Lecture 4 - 82

Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Let's write this as a filter





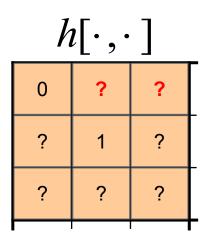
#### Raymond Yu

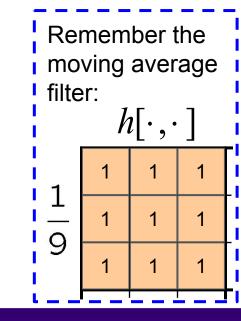
#### Lecture 4 - 83

Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Let's write this as a filter





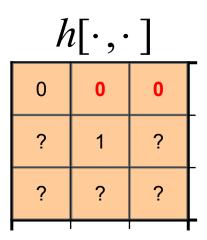
#### Raymond Yu

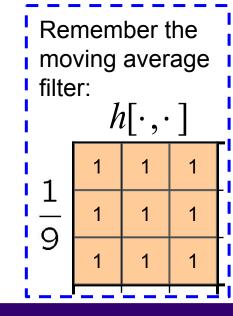
#### Lecture 4 - 84

Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Let's write this as a filter





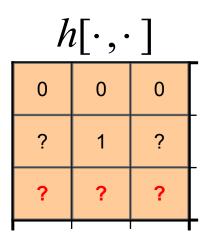
#### Raymond Yu

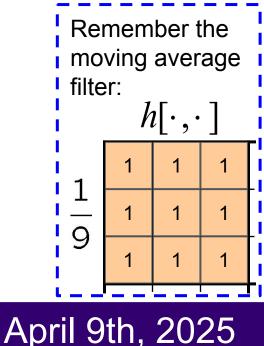
#### Lecture 4 - 85

Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Let's write this as a filter



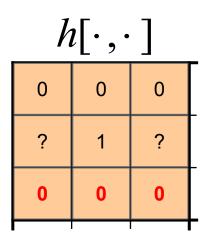


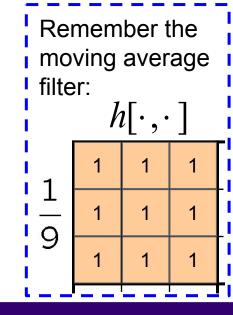
#### Raymond Yu

Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Let's write this as a filter





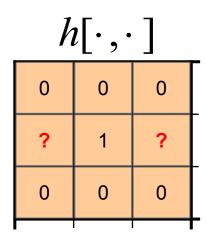
#### Raymond Yu

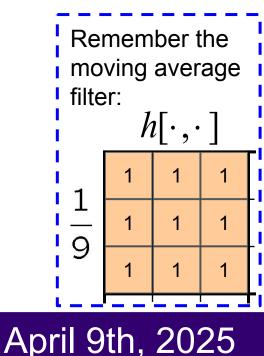
#### Lecture 4 - 87

Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Last ones: What are these two?



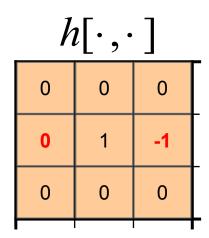


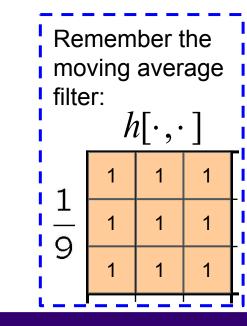
#### Raymond Yu

Using Backward differentiation

$$g[n,m] = f[n,m] - f[n,m-1]$$

Q. Last ones: What are these two?





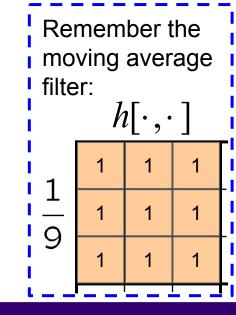
#### Raymond Yu

#### Lecture 4 - 89

• Using Backward differentiation:

**Raymond Yu** 

$$g[n,m] = f[n,m] - f[n,m-1]$$



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• Using Backward differentiation:

$$g[n,m] = f[n,m] - f[n,m-1]$$

• Using Forward differentiation:

### Q. What is the formula?

#### Raymond Yu



• Using Backward differentiation:

$$g[n,m] = f[n,m] - f[n,m-1]$$

• Using Forward differentiation:

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$$g[n,m] = f[n,m+1] - f[n,m]$$

Q. What is the filter look like?

#### Raymond Yu

• Using Backward differentiation:

$$g[n,m] = f[n,m] - f[n,m-1]$$

• Using Forward differentiation:

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$$g[n,m] = f[n,m+1] - f[n,m]$$

Raymond Yu

• Using Backward differentiation:

$$g[n,m] = f[n,m] - f[n,m-1]$$

• Using Forward differentiation:

$$g[n,m] = f[n,m+1] - f[n,m]$$

• Using Central differentiation:

Q. What is the formula?

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#### Raymond Yu

• Using Backward differentiation:

$$g[n,m] = f[n,m] - f[n,m-1]$$

• Using Forward differentiation:

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$$g[n,m] = f[n,m+1] - f[n,m]$$

• Using Central differentiation:

$$\operatorname{aymo}^{g[n,m]} = f[n,m+1] - f[n,m-1]$$

• Using Backward differentiation:

$$g[n,m] = f[n,m] - f[n,m-1]$$

• Using Forward differentiation:

$$g[n,m] = f[n,m+1] - f[n,m]$$

• Using Central differentiation:

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$$\operatorname{Raymo}^{g[n,m]} = f[n,m+1] - f[n,m-1]$$

Using backward differentiation:

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$$g[n,m] = f[n,m] - f[n,m-1]$$

### f[0,:] = [10, 15, 10, 10, 25, 20, 20, 20]



Using backward differentiation:

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$$g[n,m] = f[n,m] - f[n,m-1]$$

$$f[0,:] = [10, 15, 10, 10, 25, 20, 20, 20]$$
$$\frac{df}{dm}[0,:] = [?]$$

#### Raymond Yu

Using backward differentiation:

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$$g[n,m] = f[n,m] - f[n,m-1]$$

$$f[0,:] = [10, 15, 10, 10, 25, 20, 20, 20]$$

$$\frac{df}{dm}[0,:] = [10, ? ]$$

$$\int_{0}^{1} \frac{1}{1} + 10x + 15x = 0$$

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Using backward differentiation:

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$$g[n,m] = f[n,m] - f[n,m-1]$$

$$f[0,:] = \begin{bmatrix} 10, \ 15, \ 10, \ 10, \ 25, \ 20, \ 20, \ 20 \end{bmatrix}$$

$$\frac{df}{dm} \begin{bmatrix} 0,:] = \begin{bmatrix} 10, \ 5, \ 20, \ 20, \ 20 \end{bmatrix}$$

#### Raymond Yu

Using backward differentiation:

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$$g[n,m] = f[n,m] - f[n,m-1]$$

$$f[0,:] = \begin{bmatrix} 10, 15, 10, 10, 25, 20, 20, 20 \end{bmatrix}$$

$$\frac{df}{dm} \begin{bmatrix} 0,:] = \begin{bmatrix} 10, 5, -5, ? \end{bmatrix}$$

#### Raymond Yu

Using backward differentiation:

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$$g[n,m] = f[n,m] - f[n,m-1]$$

$$f[0,:] = \begin{bmatrix} 10, & 15, & 10, & 10, & 25, & 20, & 20 \end{bmatrix}$$

$$\frac{df}{dm}[0,:] = \begin{bmatrix} 10, & 5, & -5, & 0, & ? \end{bmatrix}$$

#### Raymond Yu

Using backward differentiation:

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$$g[n,m] = f[n,m] - f[n,m-1]$$

$$f[0,:] = \begin{bmatrix} 10, 15, 10, 10, 25, 20, 20, 20 \end{bmatrix}$$

$$\frac{df}{dm}[0,:] = \begin{bmatrix} 10, 5, -5, 0, 15, ??? \end{bmatrix}$$

#### Raymond Yu

Using backward differentiation:

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$$g[n,m] = f[n,m] - f[n,m-1]$$

$$f[0,:] = \begin{bmatrix} 10, & 15, & 10, & 10, & 25, & 20, & 20, & 20 \end{bmatrix}$$
$$\frac{df}{dm}[0,:] = \begin{bmatrix} 10, & 5, & -5, & 0, & 15, & -5, & 0, & 0 \end{bmatrix}$$

#### Raymond Yu

### Discrete derivation in 2D:

Given function f[n,m]

Gradient filter 
$$\nabla f[n,m] = \begin{bmatrix} \frac{df}{dn} \\ \frac{df}{dm} \end{bmatrix} = \begin{bmatrix} f_n \\ f_m \end{bmatrix}$$





### Discrete derivation in 2D:

Given function f[n, m]

Gradient filter 
$$\nabla f[n,m] = \begin{bmatrix} \frac{df}{dn} \\ \frac{df}{dm} \end{bmatrix} = \begin{bmatrix} f_n \\ f_m \end{bmatrix}$$
  
Gradient magnitude  $|\nabla f[n,m]| = \sqrt{f_n^2 + f_m^2}$ 

Lecture 4 - 106

### Discrete derivation in 2D:

Given function f[n, m]

Gradient filter 
$$\nabla f[n,m] = \begin{bmatrix} \frac{df}{dn} \\ \frac{df}{dm} \end{bmatrix} = \begin{bmatrix} f_n \\ f_m \end{bmatrix}$$

Gradient magnitude  $|\nabla f[n,m]| = \sqrt{f_n^2 + f_m^2}$ Gradient direction  $\theta = \tan^{-1}(\frac{f_m}{f_n})$ 

#### Raymond Yu

Lecture 4 - 107

### 2D discrete derivative - example

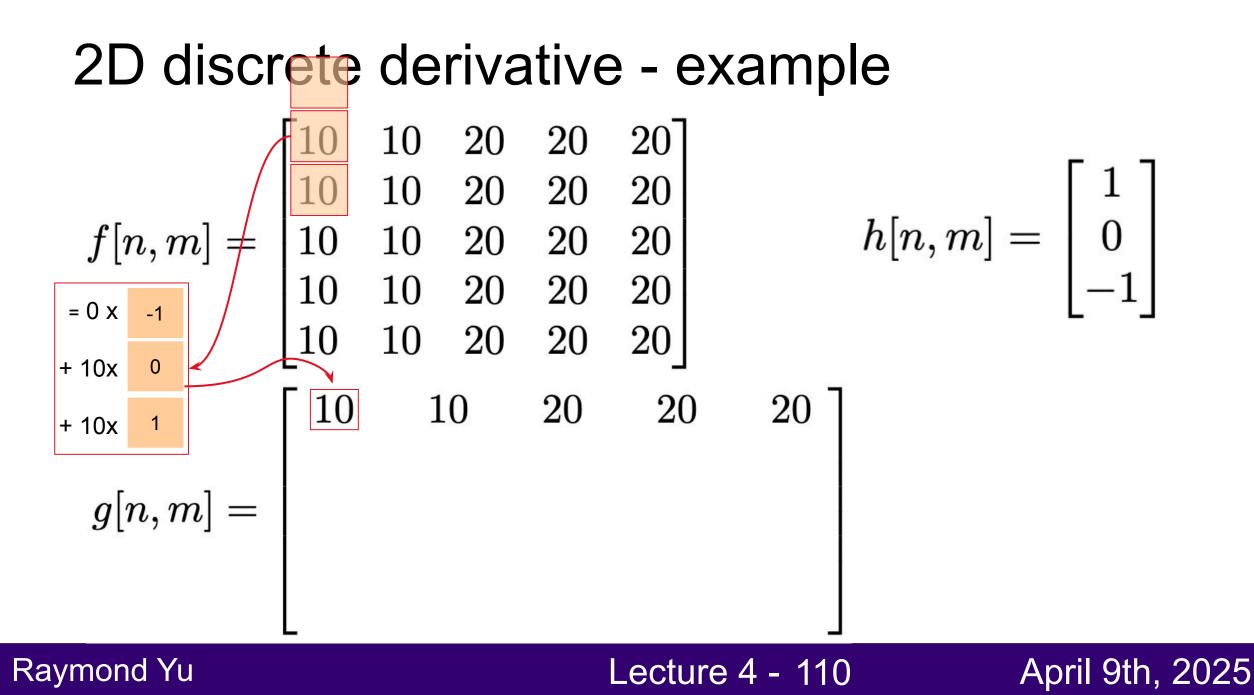
$$f[n,m] = \begin{bmatrix} 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \end{bmatrix}$$



$$h[n,m] = \begin{bmatrix} 1\\0\\-1 \end{bmatrix}$$

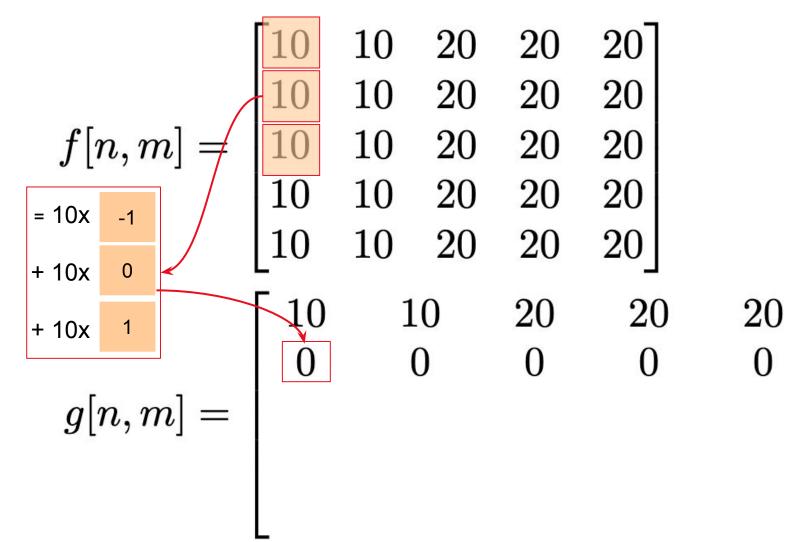
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Lecture 4 - 111



$$h[n,m] = \begin{bmatrix} 1\\ 0\\ -1 \end{bmatrix}$$

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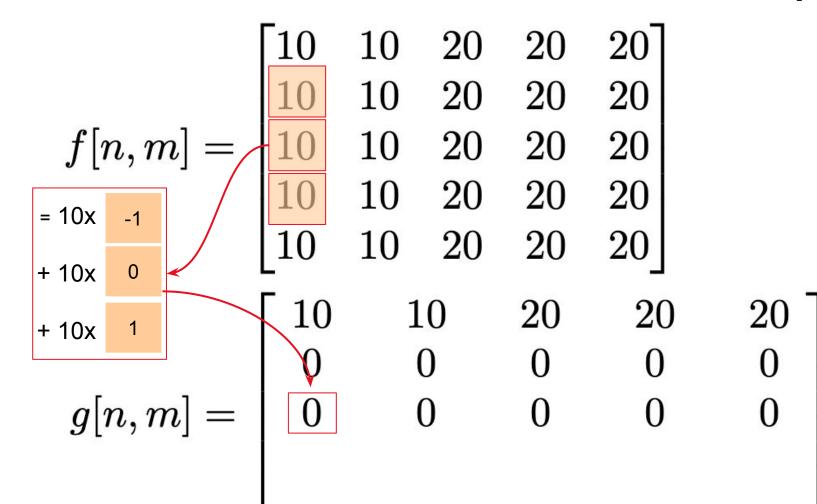
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$$f[n,m] = \begin{bmatrix} 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \end{bmatrix} \qquad h[n]$$
$$g[n,m] = \begin{bmatrix} 10 & 10 & 20 & 20 & 20 \\ 0 & 0 & 0 & 0 & 0 \\ ? & ? & ? & ? & ? \end{bmatrix}$$

$$h[n,m] = \begin{bmatrix} 1\\ 0\\ -1 \end{bmatrix}$$

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$$h[n,m] = \begin{bmatrix} 1\\ 0\\ -1 \end{bmatrix}$$

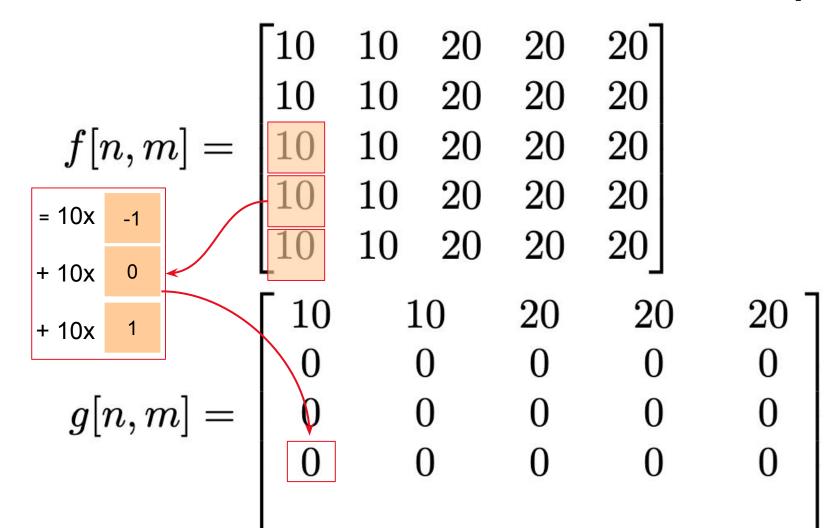
#### Raymond Yu

#### Lecture 4 - 114

$$h[n,m] = \begin{bmatrix} 1\\ 0\\ -1 \end{bmatrix}$$

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#### Lecture 4 - 115



 $h[n,m] = \begin{bmatrix} 1\\0\\-1 \end{bmatrix}$ 

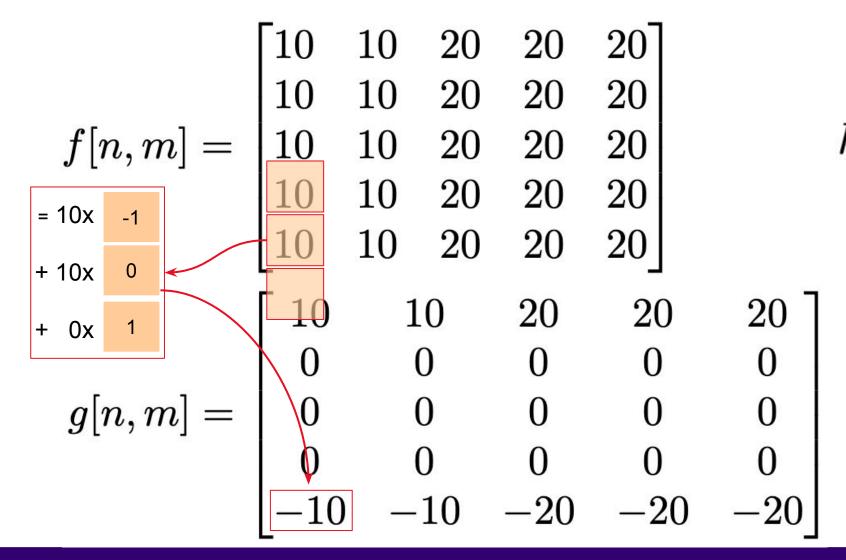
#### Raymond Yu

Lecture 4 - 116

$$n[n,m] = \begin{bmatrix} 1\\ 0\\ -1 \end{bmatrix}$$

#### Raymond Yu

Lecture 4 - 117



$$h[n,m] = \begin{bmatrix} 1\\ 0\\ -1 \end{bmatrix}$$

#### Raymond Yu

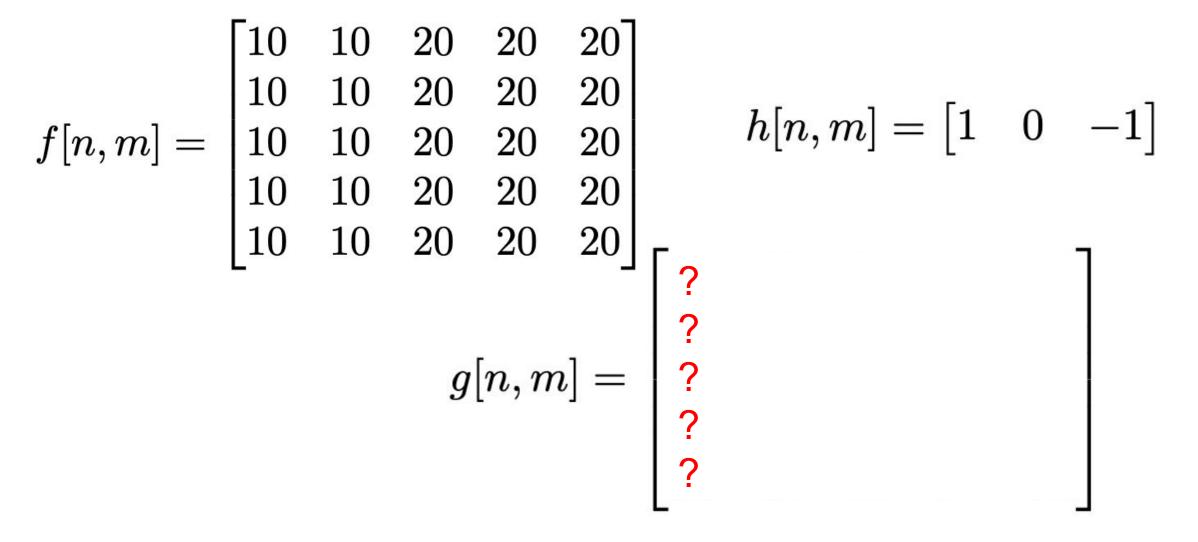
Lecture 4 - 118

$$f[n,m] = \begin{bmatrix} 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \end{bmatrix}$$

$$h[n,m] = \begin{bmatrix} 1 & 0 & -1 \end{bmatrix}$$

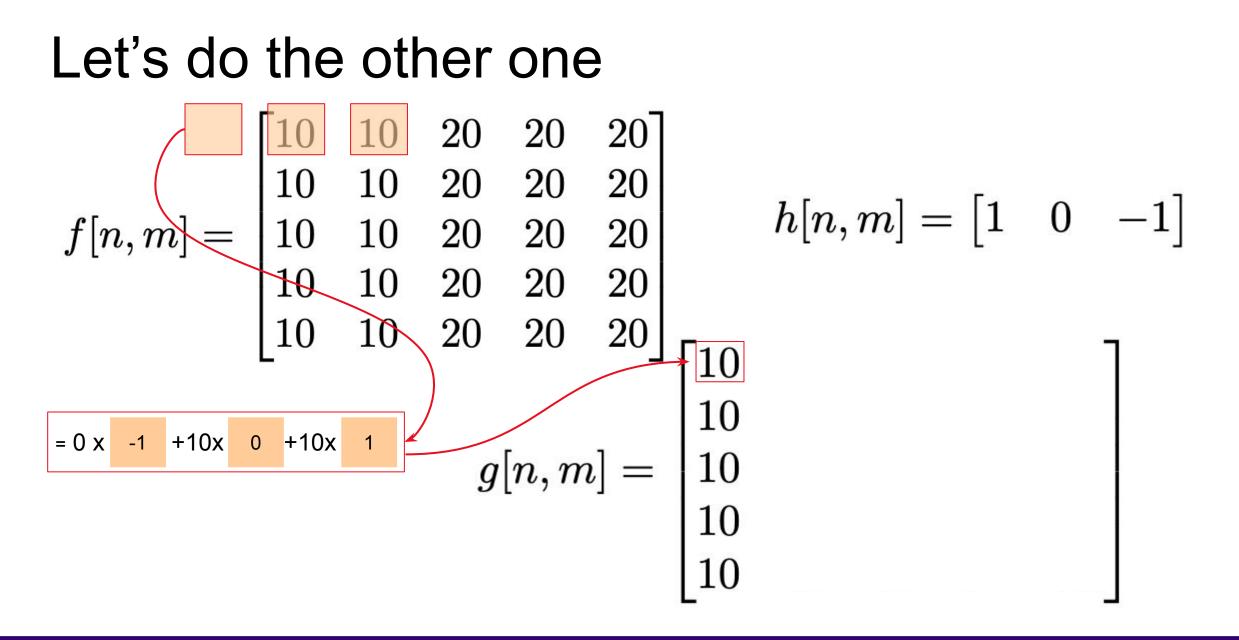
#### Raymond Yu





#### Raymond Yu

Lecture 4 - 120



#### Raymond Yu

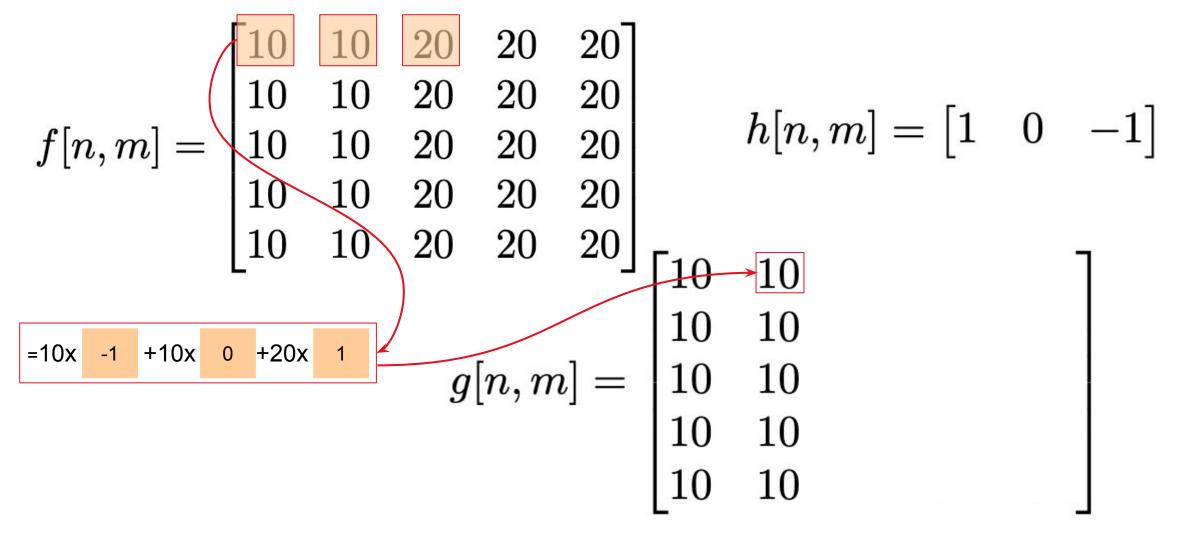
Lecture 4 - 121

$$f[n,m] = \begin{bmatrix} 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \end{bmatrix} h[n,m] = \begin{bmatrix} 1 & 0 & -1 \end{bmatrix}$$
$$g[n,m] = \begin{bmatrix} 10 & ? \\ 10 & ? \\ 10 & ? \\ 10 & ? \\ 10 & ? \\ 10 & ? \end{bmatrix}$$

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## Raymond Yu

Lecture 4 - 122



#### Raymond Yu

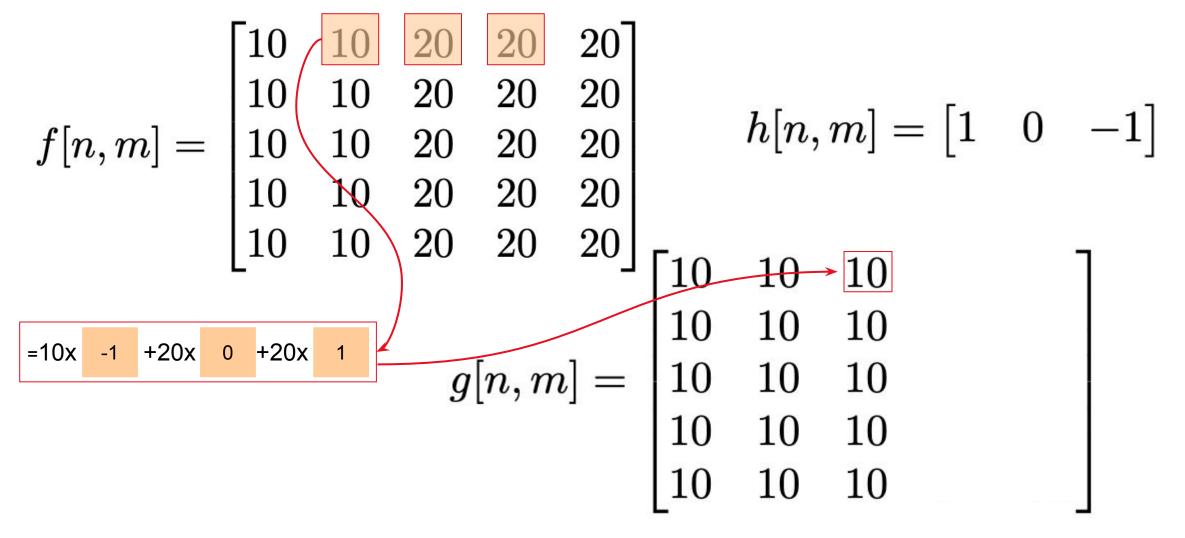
Lecture 4 - 123

Raymond Yu

$$f[n,m] = \begin{bmatrix} 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \end{bmatrix} h[n,m] = \begin{bmatrix} 1 & 0 & -1 \end{bmatrix}$$
$$g[n,m] = \begin{bmatrix} 10 & 10 & ? \\ 10 & 10 & ? \\ 10 & 10 & ? \\ 10 & 10 & ? \\ 10 & 10 & ? \\ 10 & 10 & ? \\ 10 & 10 & ? \end{bmatrix}$$

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## Lecture 4 - 124



#### Raymond Yu

Lecture 4 - 125

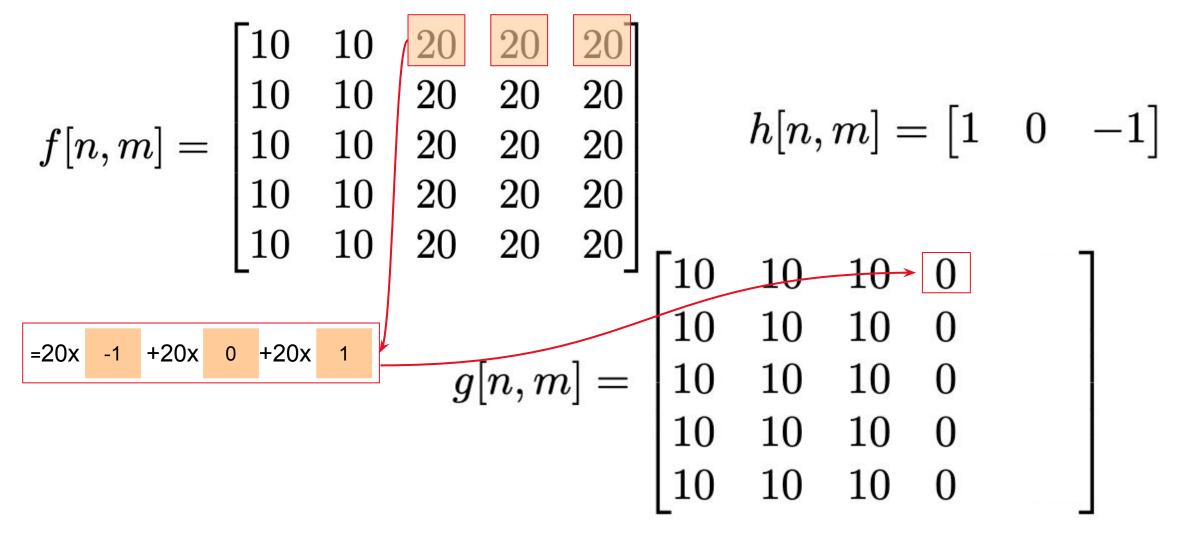
$$f[n,m] = \begin{bmatrix} 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \end{bmatrix} \qquad h[n,m] = \begin{bmatrix} 1 & 0 & -1 \end{bmatrix}$$
$$g[n,m] = \begin{bmatrix} 10 & 10 & 10 & 2 \\ 10 & 10 & 10 & 2 \\ 10 & 10 & 10 & 2 \\ 10 & 10 & 10 & 2 \\ 10 & 10 & 10 & 2 \\ 10 & 10 & 10 & 2 \\ 10 & 10 & 10 & 2 \\ 10 & 10 & 10 & 2 \end{bmatrix}$$

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### Lecture 4 - 126

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### Raymond Yu



#### Raymond Yu

Lecture 4 - 127

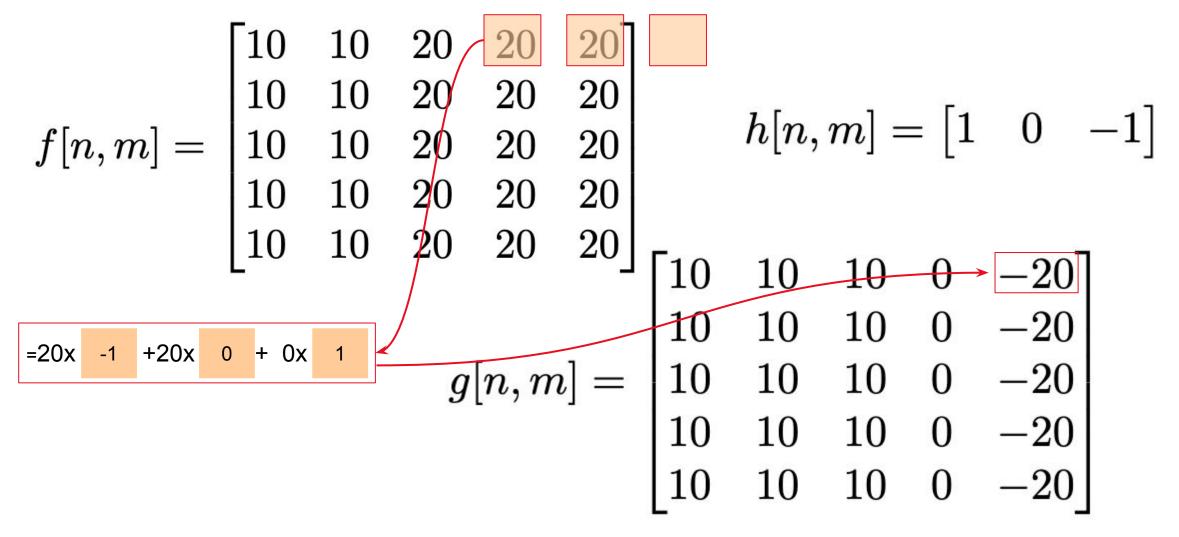
$$f[n,m] = \begin{bmatrix} 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \\ 10 & 10 & 20 & 20 & 20 \end{bmatrix} \qquad h[n,m] = \begin{bmatrix} 1 & 0 & -1 \end{bmatrix}$$
$$g[n,m] = \begin{bmatrix} 10 & 10 & 10 & 0 & ? \\ 10 & 10 & 10 & 0 & ? \\ 10 & 10 & 10 & 0 & ? \\ 10 & 10 & 10 & 0 & ? \\ 10 & 10 & 10 & 0 & ? \\ 10 & 10 & 10 & 0 & ? \\ 10 & 10 & 10 & 0 & ? \end{bmatrix}$$

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### Lecture 4 - 128

### Raymond Yu



### April 9th, 2025

#### Lecture 4 - 129

#### Raymond Yu

## 2D discrete derivative filters

Q. What does this filter do?

$$h[n,m] = \begin{bmatrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix}$$





## 2D discrete derivative filters

$$h[n,m] = \begin{bmatrix} 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \\ 1 & 0 & -1 \end{bmatrix}$$

Q. What does this filter do?

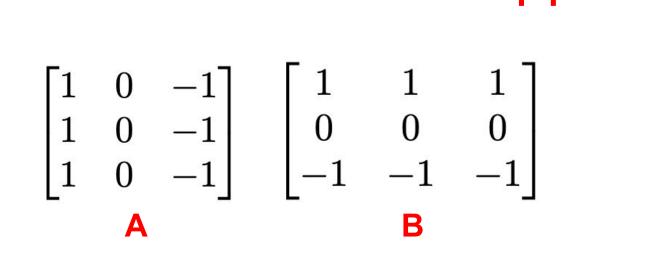
$$h[n,m] = \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ -1 & -1 & -1 \end{bmatrix}$$

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Lecture 4 - 131

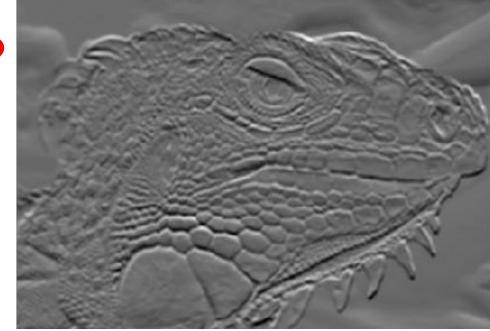
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## Q. Which filter was applied?



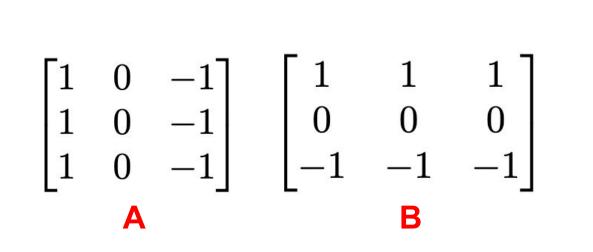


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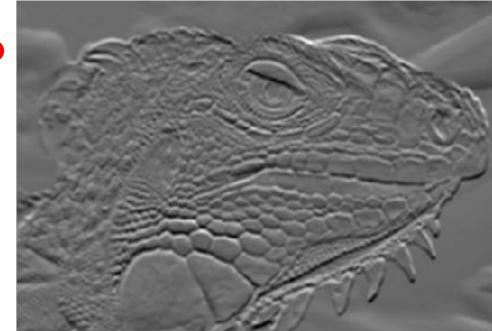


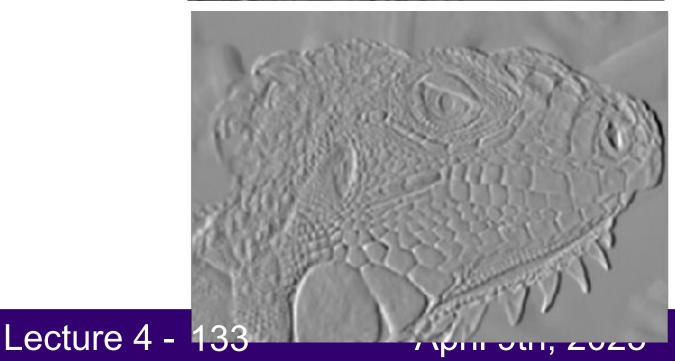


## Q. Which filter was applied?









### Raymond Yu

# What we will learn today

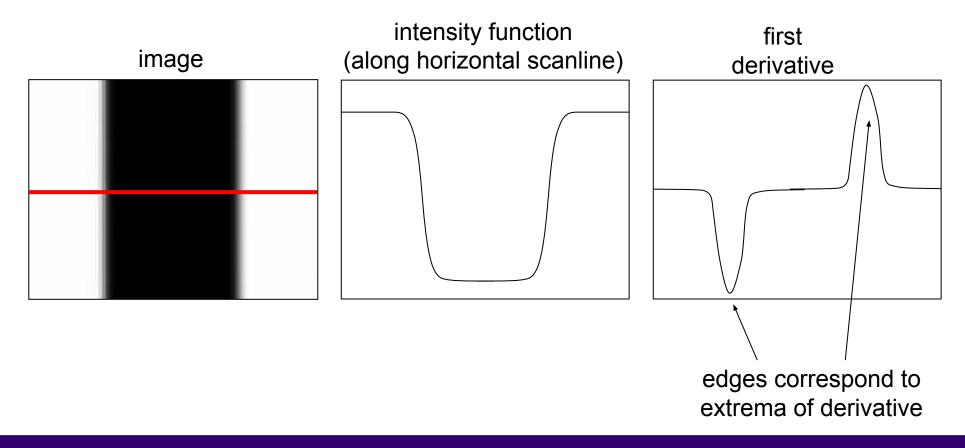
- Convolutions and Cross-Correlation
- Edge detection
- Image Gradients
- A simple edge detector





# Characterizing edges

An edge is a place of rapid change in the image intensity function



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### Lecture 4 - 135

# Image gradient

The gradient of an image:

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 $\blacktriangleright \nabla_m f[n,m] = \begin{bmatrix} 0 & \frac{df}{dm} \end{bmatrix}$ 

$$\nabla_n f[n,m] = \begin{bmatrix} \frac{df}{dn} & 0 \end{bmatrix} \qquad \begin{array}{c} \nabla f[n,m] = \begin{bmatrix} \frac{df}{dn} & \frac{df}{dm} \end{bmatrix}$$

The gradient vector points in the direction of most rapid increase in intensity

$$\theta = \tan^{-1}(\frac{f_m}{f_n})$$



# Image gradient

The gradient of an image:

 $\blacktriangleright \nabla_m f[n,m] = \begin{bmatrix} 0 & \frac{df}{dm} \end{bmatrix}$ 

$$\nabla_n f[n,m] = \begin{bmatrix} \frac{df}{dn} & 0 \end{bmatrix} \qquad \nabla f[n,m] = \begin{bmatrix} \frac{df}{dn} & \frac{df}{dm} \end{bmatrix}$$

The gradient vector points in the direction of most rapid increase in intensity

The edge strength is given by the gradient magnitude

$$|\nabla f[n,m]| = \sqrt{f_n^2 + f_m^2}$$

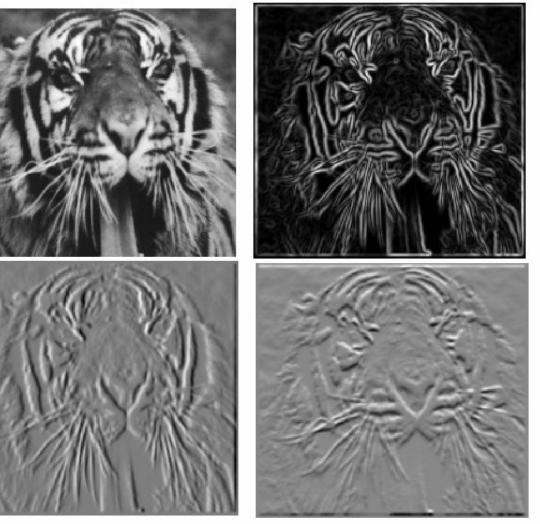
$$\theta = \tan^{-1}(\frac{f_m}{f_n})$$

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## Finite differences: example

Original Image



Gradient magnitude

height-direction

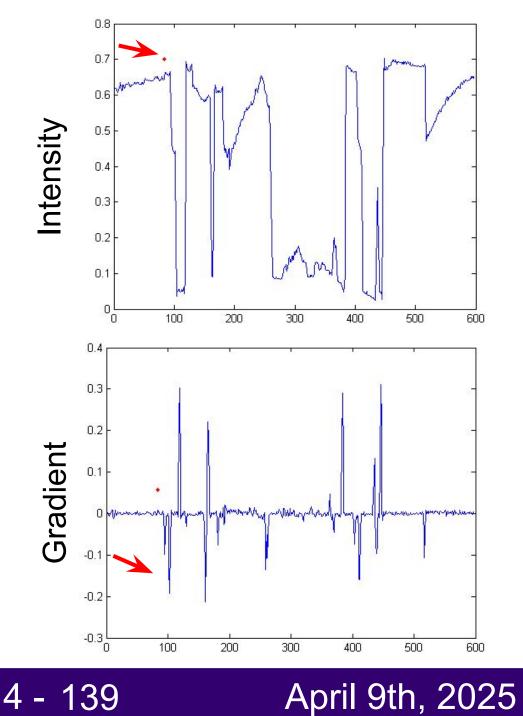
width-direction

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## Intensity profile





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# Summary

- Convolutions and Cross-Correlation
- Edge detection
- Image Gradients
- A simple edge detector





# Next time: Detecting lines



