Computer Vision

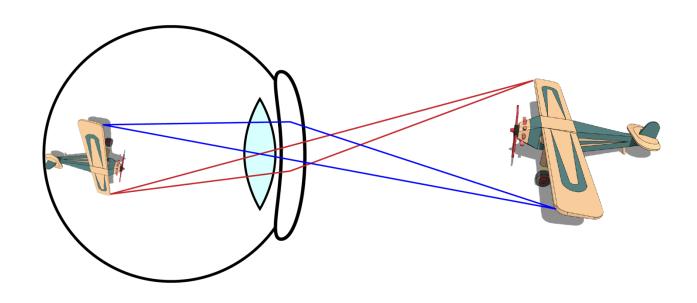
CSE 455 Image Coordinates and Resizing

Linda Shapiro

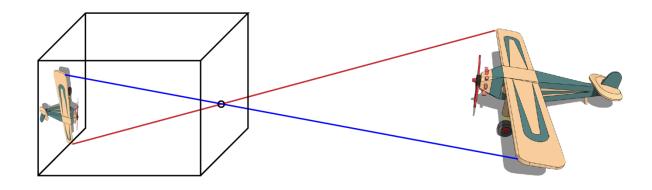
Professor of Computer Science & Engineering Professor of Electrical & Computer Engineering

What is an image?

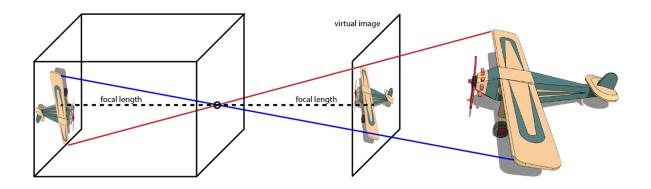
Eyes: projection onto retina



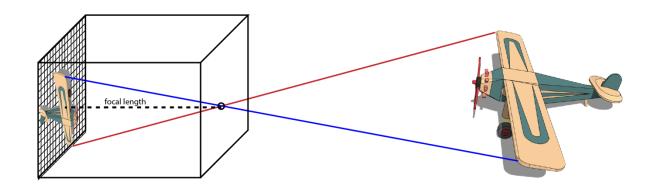
Model: pinhole camera



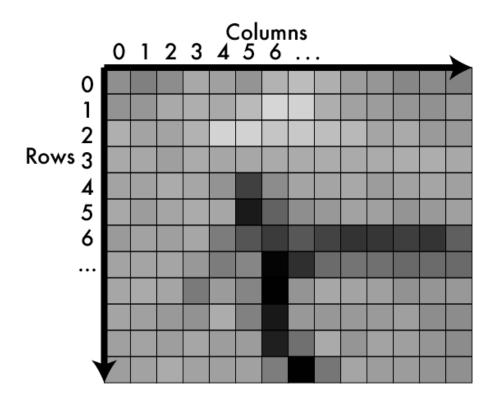
Model: pinhole camera



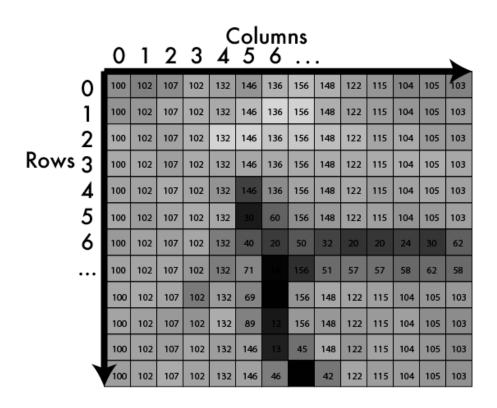
At each point we record incident light



An image is a matrix of light

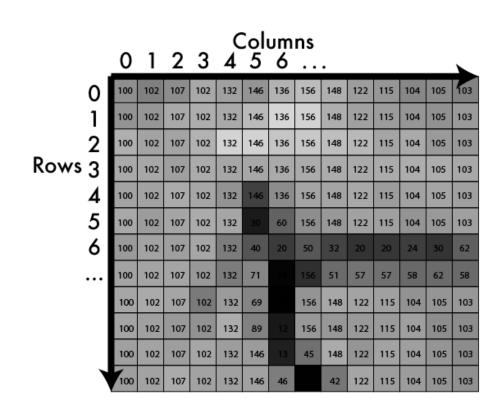


Values in matrix = how much light



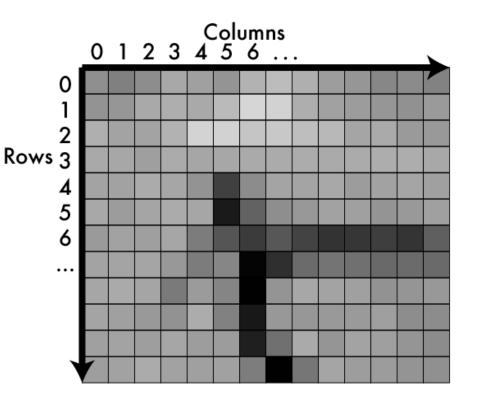
Values in matrix = how much light

- Higher = more light
- Lower = less light
- Bounded
 - No light = 0
 - Sensor/device limit = max
 - Typical ranges:
 - [0-255], fit into byte
 - [0-1], floating point
- Called pixels

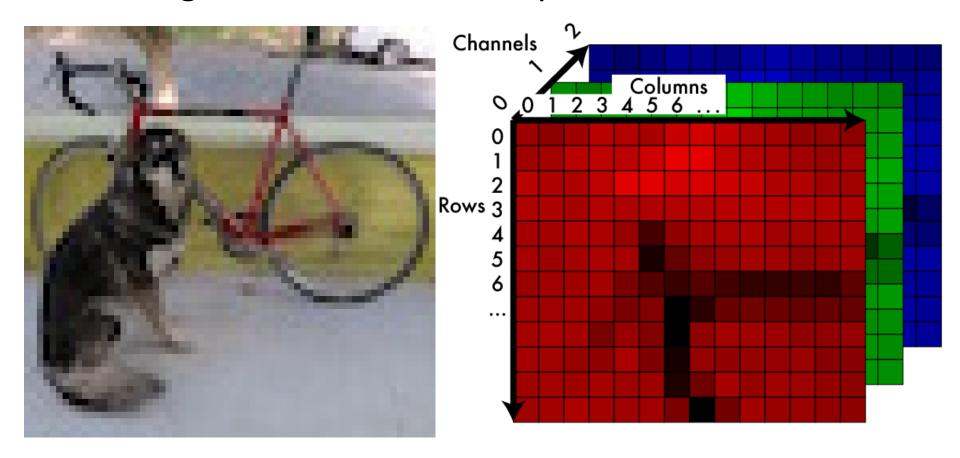


Addressing pixels

- Ways to index:
 - (r,c)
 - Like matrix notation
 - (3,6) is row 3 column 6
 - (x,y)
 - Like cartesian coordinates (but from the TOP)
 - (3,6) is column 3 row 6
- We use (x,y)
 - So does your homework!
 - Arbitrary
 - Only thing that matters is consistency



Color image: 3d tensor in colorspace



RGB information in separate "channels"

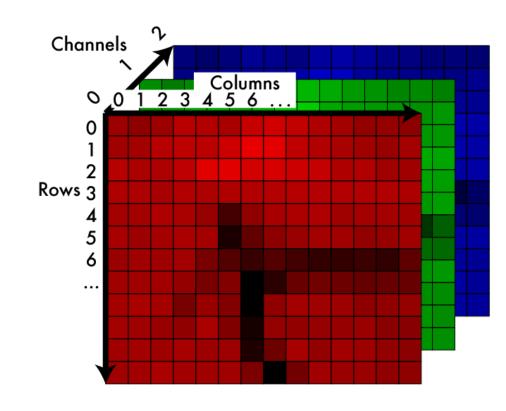
Remember: we can match "real" colors using a mix of primaries.

Each channel encodes one primary. Adding the light produced from each primary mimics the original color.

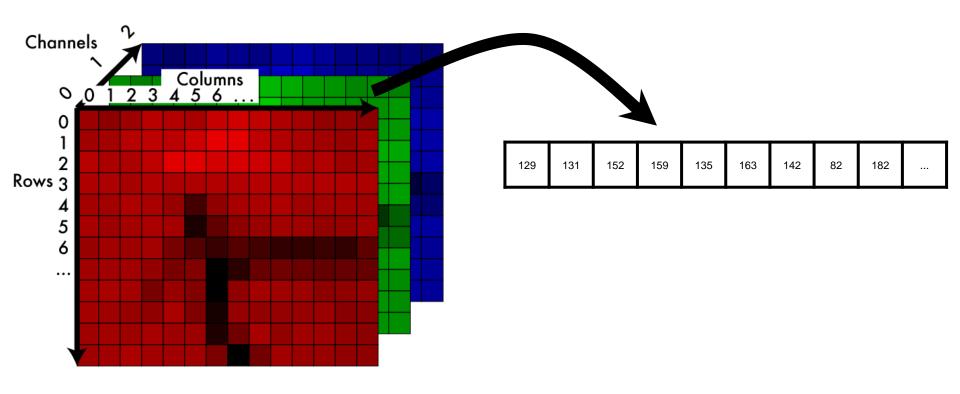


Addressing pixels

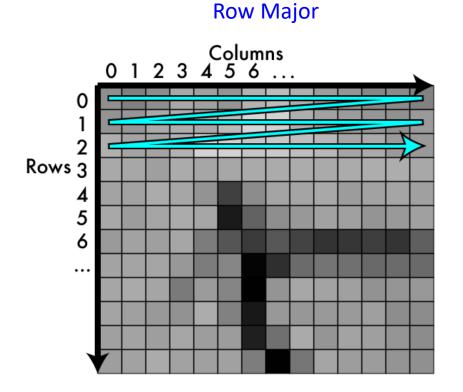
- We use (x,y,c)
 - (1,2,0):
 - column 1, row 2,channel 0
- Be consistent
- But do what we do for homeworks :-)
- Also for size:
 - 1920 x 1080 x 3 image:
 - 1920 px wide
 - 1080 px tall
 - 3 channels



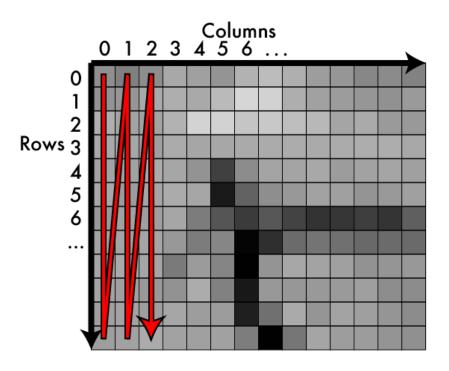
How do we store them?



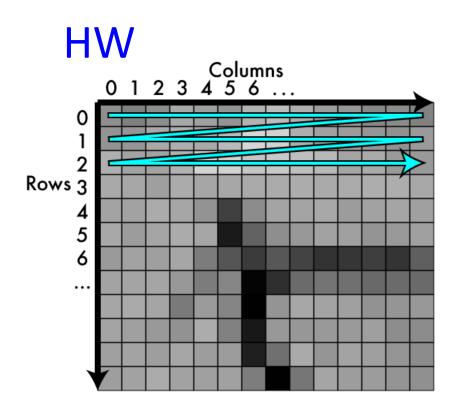
Storage: row major vs column major

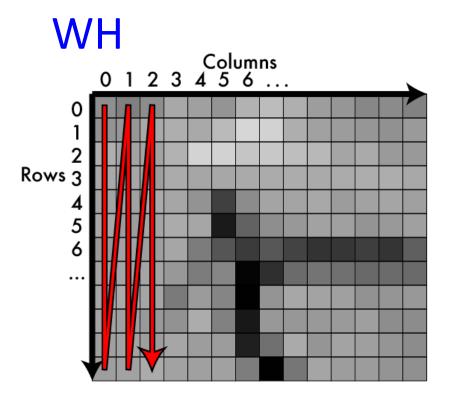


Column Major

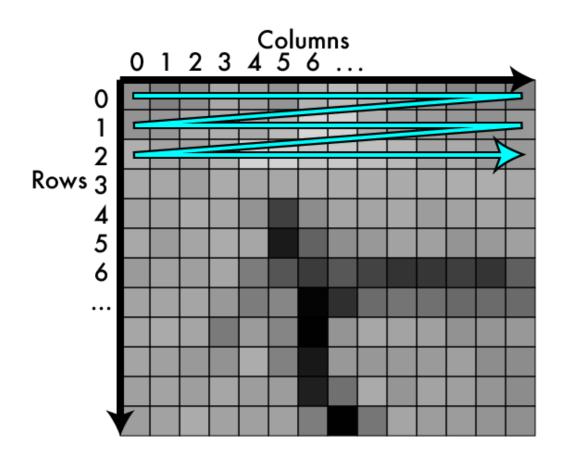


Storage: row major vs column major

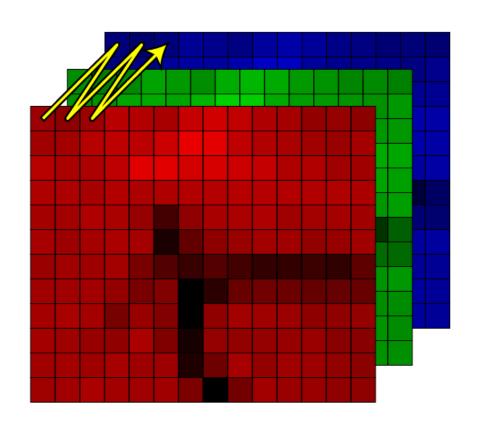


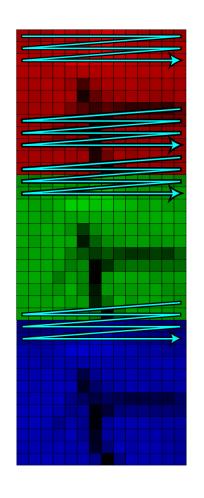


Typically use row-major or HW

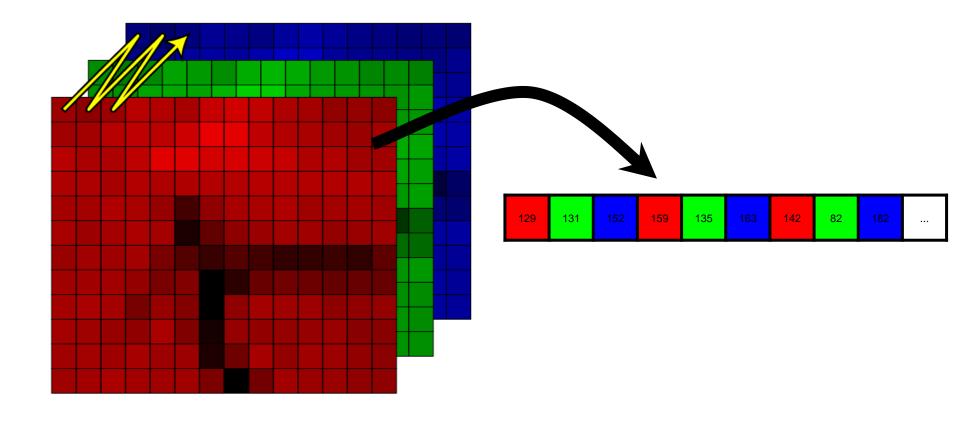


In 3d we have more choices!

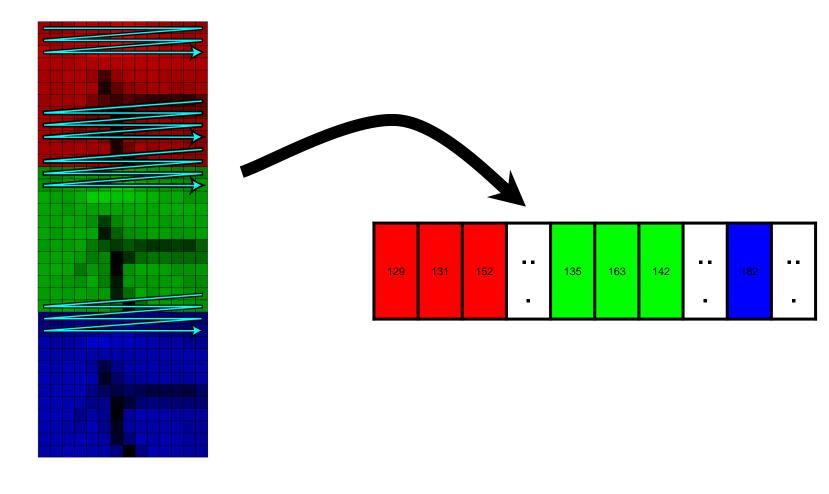




HWC: channels interleaved



CHW: channels separated



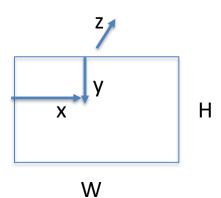
CHW Pop quiz

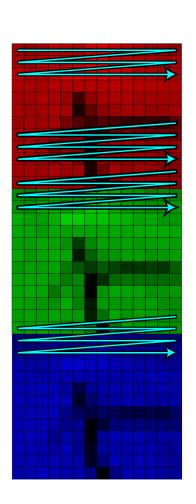
We'll use CHW, it's what a lot of other libraries use.

In an array for a 1920 x 1080 x 3 image what entry would contain the pixel (15,192,2)?

Formula:

$$x + y*W + z*W*H$$





CHW Pop quiz

In an array for a $1920 \times 1080 \times 3$ image what entry would contain the pixel (15,192,2)?

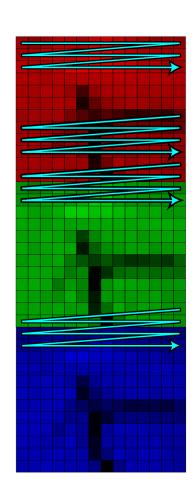
In general for (x,y,z) of image (W,H,C)

$$x + y*W + z*W*H$$

Remember, everything is 0 indexed

Where does (0,0,0) go?

Position
$$0 + 0 + 0 = 0$$



In your homework

```
typedef struct {
  int w,h,c;
  float *data;
} image;
```

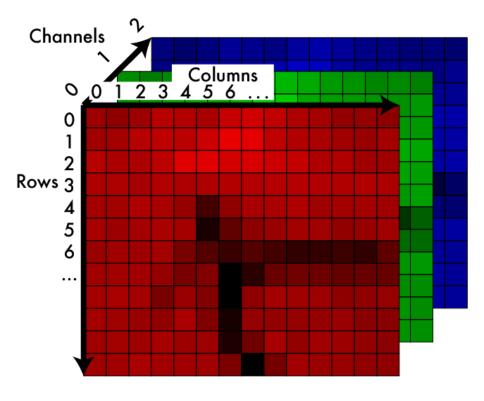


Image interpolation and resizing

An image is kinda like a function

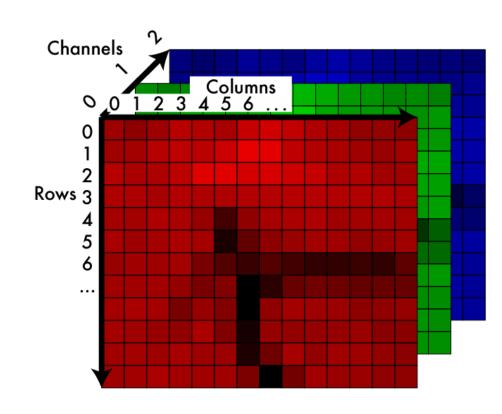
An image is a mapping from indices to pixel value:

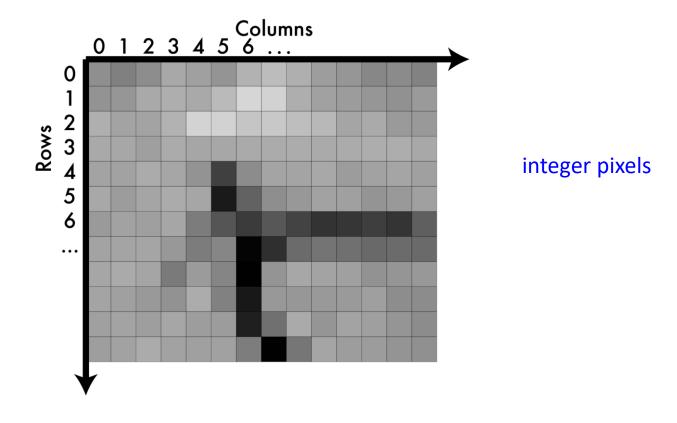
- lm: | x | x | -> R

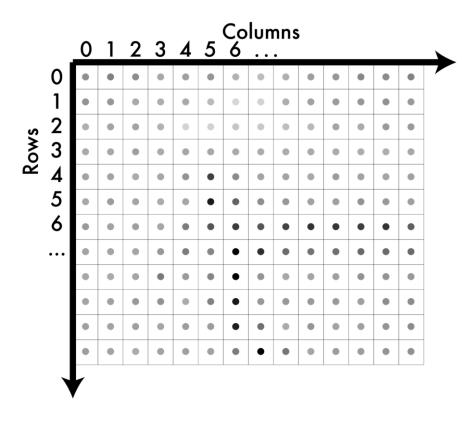
We may want to pass in

non-integers:

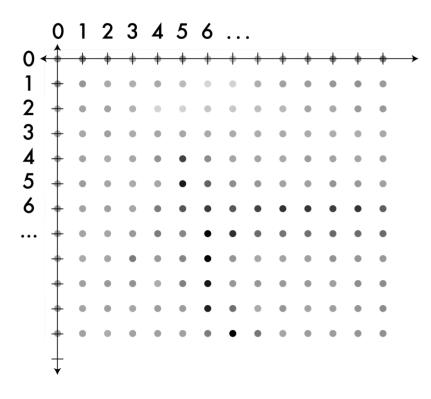
- $Im': R \times R \times I -> R$



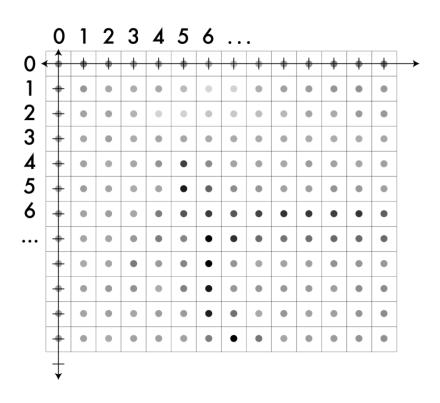




We can think of their values as being at the centers.

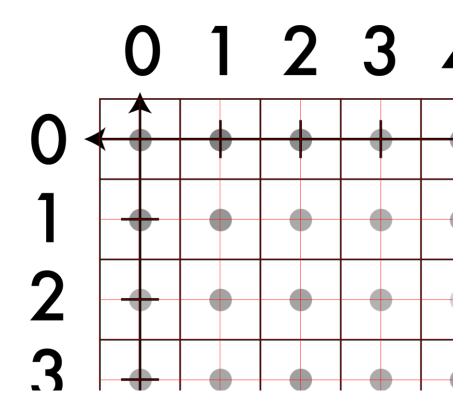


Now we can move to a real coordinate system.



On the image

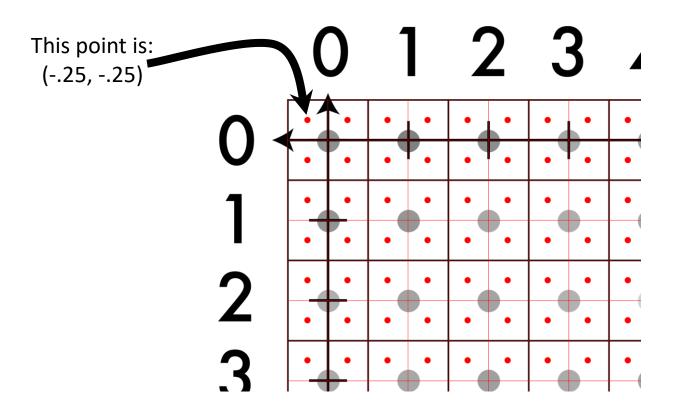
So, the value of the pixel (x,y) is now centered at (x,y).



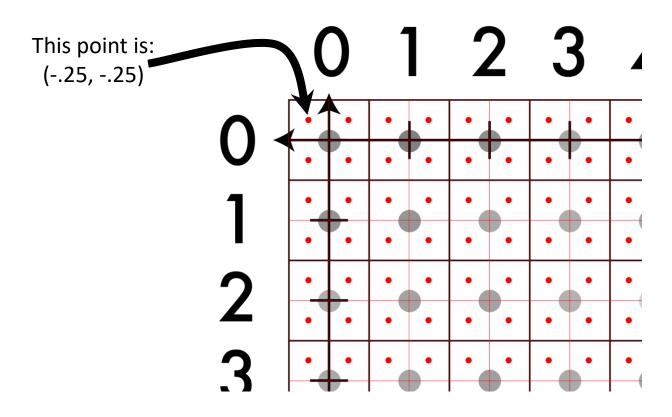
But there are other real-valued points.

O 1 2 3

O 1 1 2 3



Just be careful



Interpolation

- How do we find out the VALUE of a noninteger point, when the image only comes with integer points, ie (25,45,3).
- For our assignment:
 - 1. Nearest-Neighbor Interpolation
 - 2. Bilinear Interpolation

Nearest neighbor: what it sounds like

f(x,y,z) = Im(round(x), round(y), z)

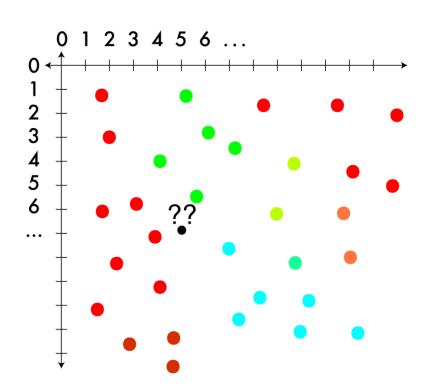
- Looks blocky
- Common pitfall: Integer division rounds down in C
- Note: z is still int



Triangle interpolation: for less structured image (alternate approach)

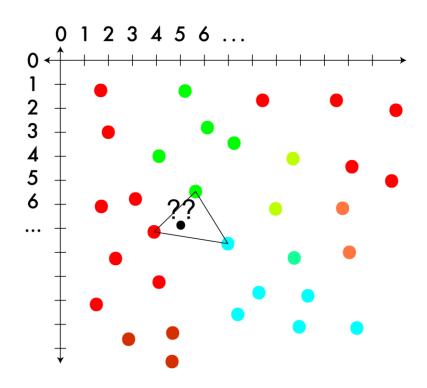
Sometimes you have a regular grid, sometimes you don't.

When you don't, you can look for triangles!



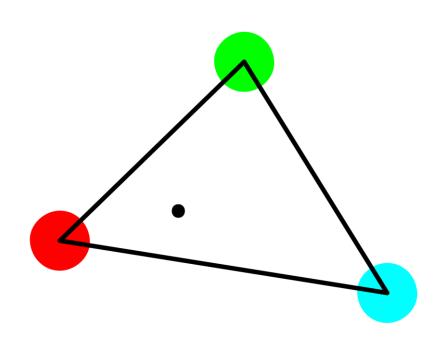
Sometimes you have a regular grid, sometimes you don't.

When you don't look for triangles!



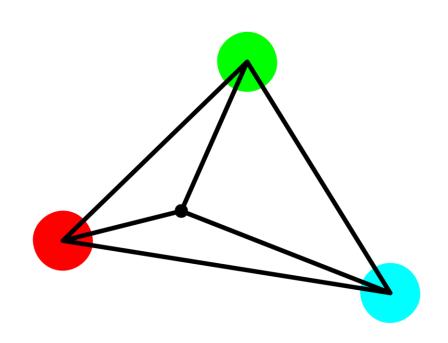
Sometimes you have a regular grid, sometimes you don't.

When you don't look for triangles!



Sometimes you have a regular grid, sometimes you don't.

When you don't look for triangles!



Weighted sum using triangles:

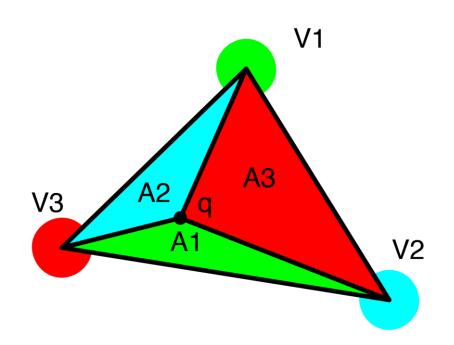
$$Q = V1*A1 + V2*A2 + V3*A3$$

WHY?

V1 is the furthest from q and A1 gives the smallest area.

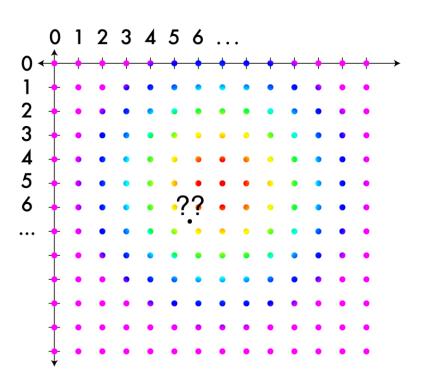
V2 is next furthest from 1 and A2 gives the next smallest area...

Should normalize this based on total area, but we won't use this.



Bilinear interpolation: for grids, pretty good; easier than triangles

This time find the closest pixels in a box



This time find the closest pixels in a box

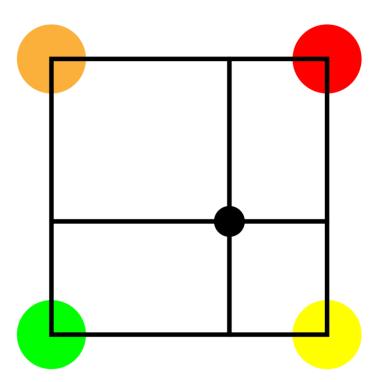








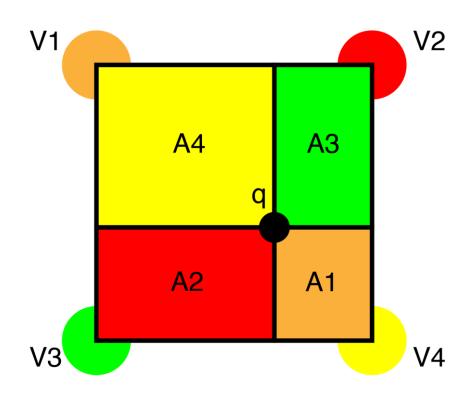
This time find the closest pixels in a box



This time find the closest pixels in a box

Same plan, weighted sum based on area of opposite rectangle

Q = V1*A1 + V2*A2 + V3*A3 + V4*A4



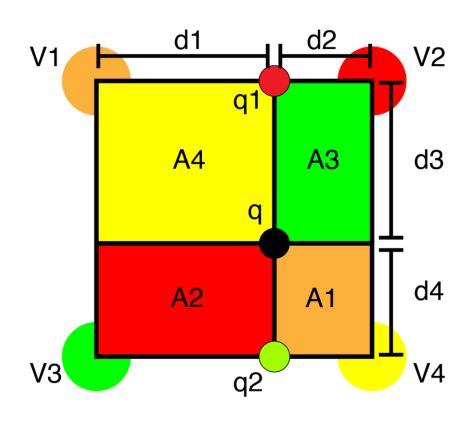
$$A1 = d2*d4$$

$$A2 = d1*d4$$

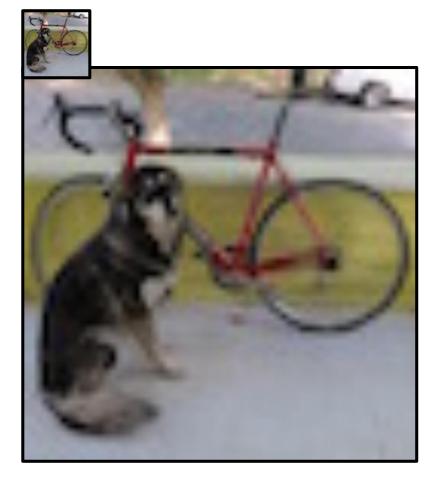
$$A3 = d2*d3$$

$$A4 = d1*d3$$

$$q = V1*A1 + V2*A2 + V3*A3 + V4*A4$$

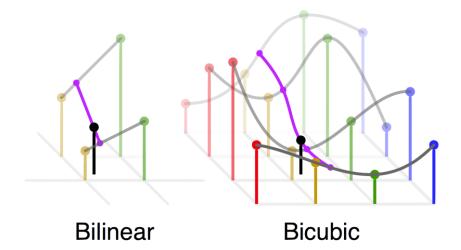


- Smoother than NN
- More complex
 - 4 lookups
 - Some math
- Often the right tradeoff of speed vs final result

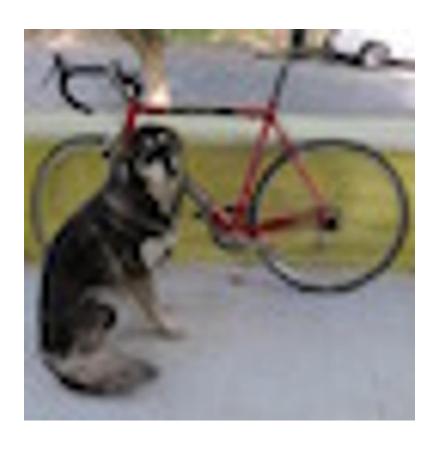


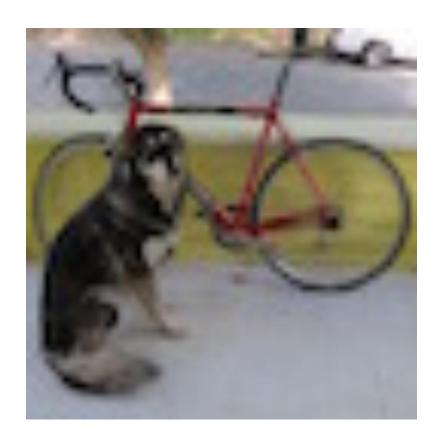
Bicubic sampling: more complex, maybe better?

- A cubic interpolation of 4 cubic interpolations
- Smoother than bilinear, no "star"
- 16 nearest neighbors
- Fit 3rd order poly:
 - $f(x) = a + bx + cx^2 + dx^3$
- Interpolate along axis
- Fit another poly to interpolated values

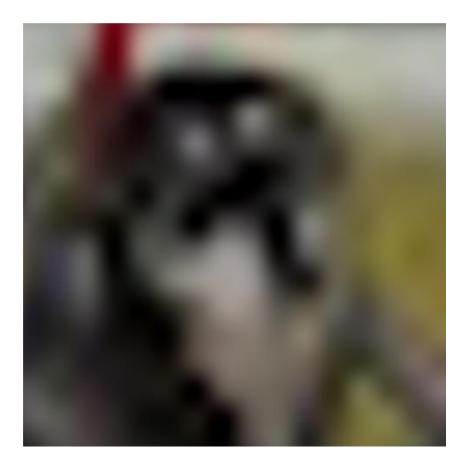


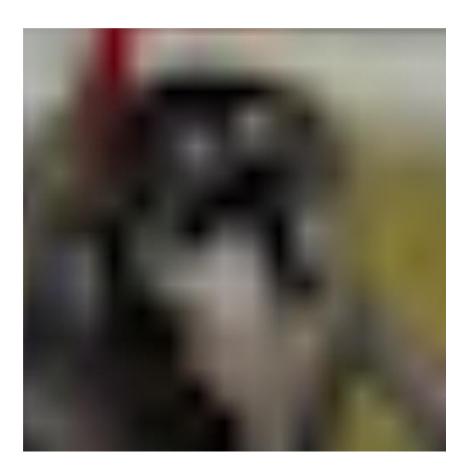
Bicubic vs bilinear





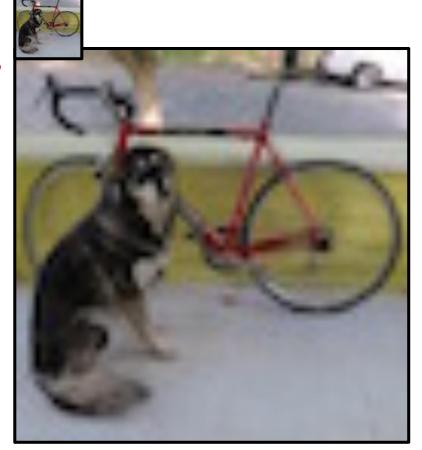
Bicubic vs bilinear





Resize algorithm:

- For each pixel in new image:
 - 1. Map to old im coordinates
 - 2. Interpolate value
 - 3. Set new value in image



What about shrinking?

- NN and Bilinear only look at small area
- Lots of artifacting
- Staircase pattern on diagonal lines
- We'll fix this next class with filters!



So what is this interpolation useful for?

Image resizing!

Say we want to increase the size of an image...

This is a beautiful image of a sunset... it's just very small...

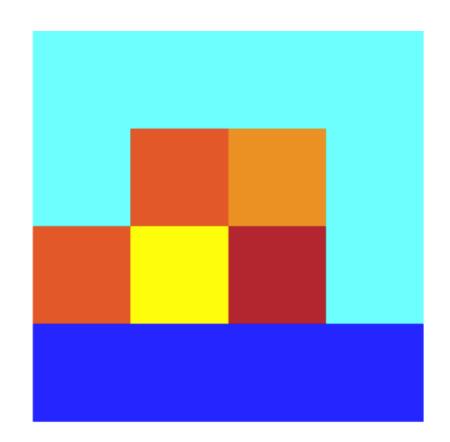
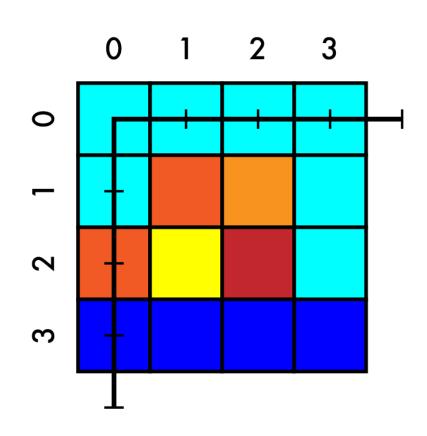


Image resizing!

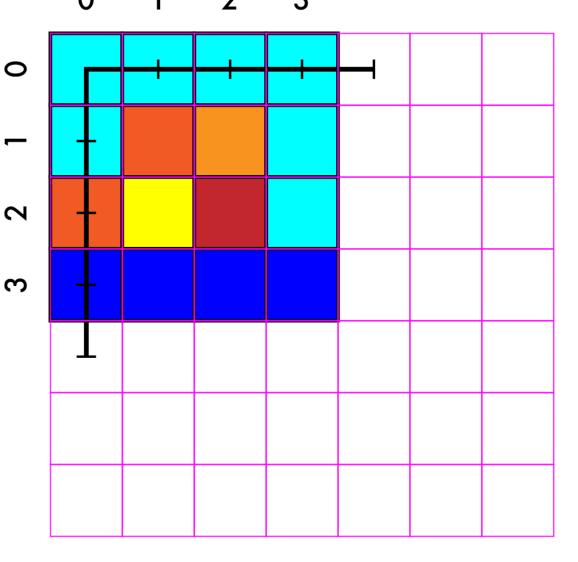
Say we want to increase the size of an image...

This is a beautiful image of a sunset... it's just very small...

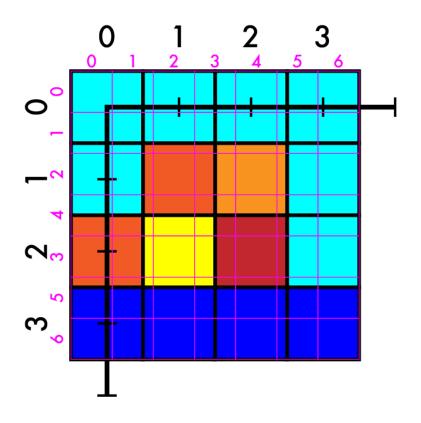
Say we want to increase size 4x4 - > 7x7



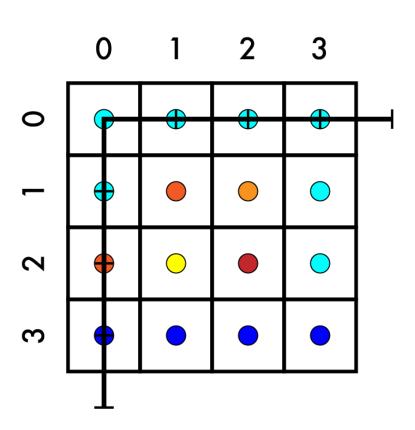
- Create our new image



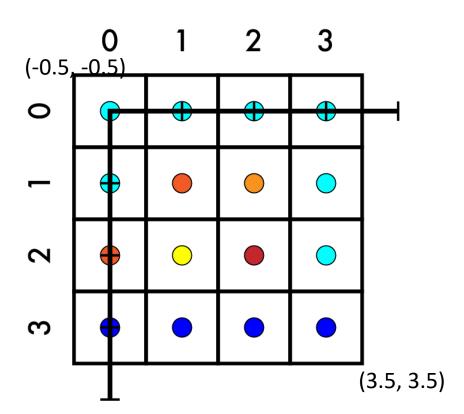
- Create our new image
- Match up coordinates



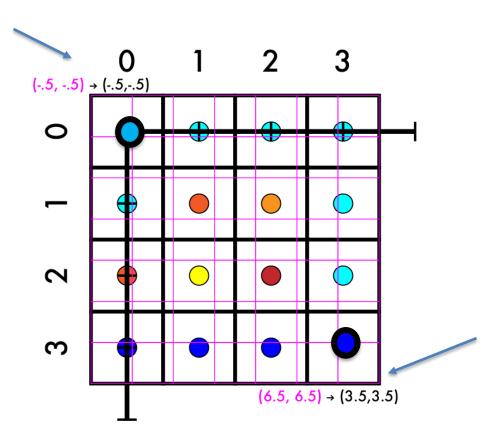
- Create our new image
- Match up coordinates



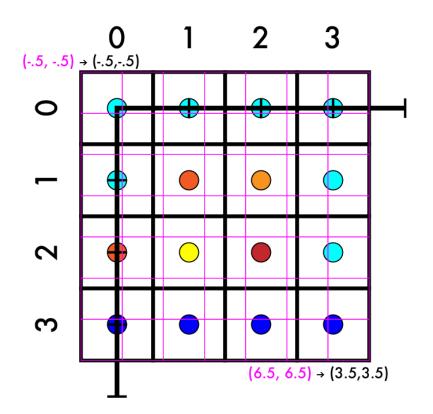
- Create our new image
- Match up coordinates



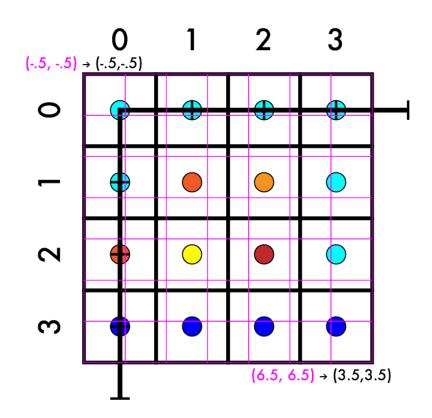
- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5



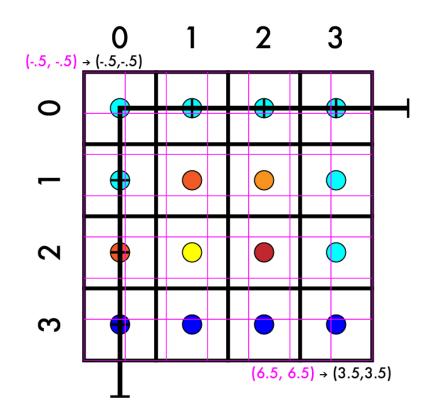
- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - a^* -.5 + b = -.5
 - a*6.5 + b = 3.5
 - a*7 = 4



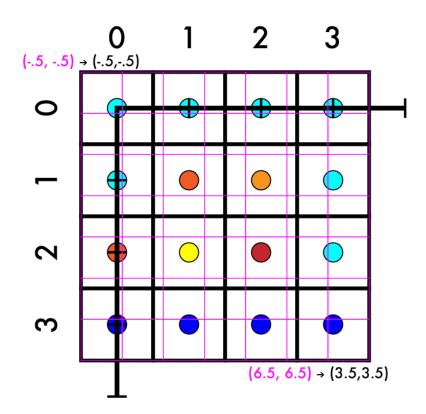
- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - a^* -.5 + b = -.5
 - a*6.5 + b = 3.5
 - a*7 = 4
 - a = 4/7



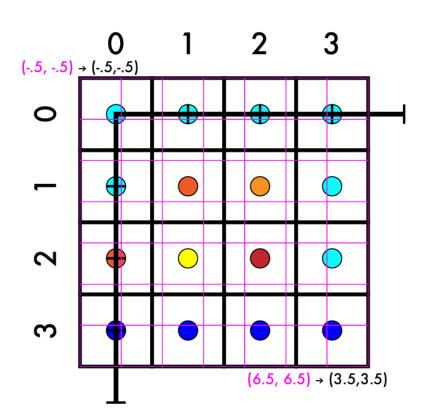
- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5
 - a = 4/7



- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - a^* -.5 + b = -.5
 - a*6.5 + b = 3.5
 - a = 4/7
 - $a^* .5 + b = -.5$



- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5
 - a = 4/7
 - $a^* .5 + b = -.5$
 - -4/7*-1/2 + b = -1/2



- Create our new image
- Match up coordinates
 - System of equations

-
$$aX + b = Y$$

-
$$a^*$$
-.5 + b = -.5

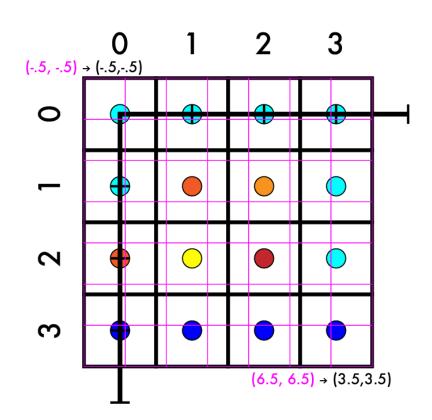
-
$$a*6.5 + b = 3.5$$

-
$$a = 4/7$$

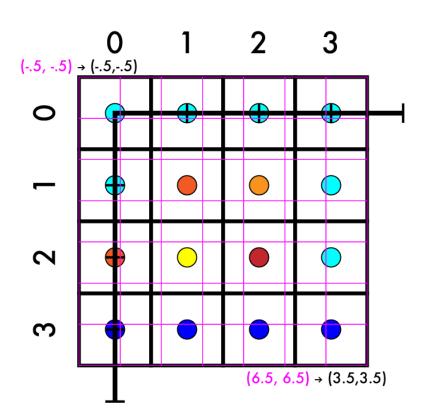
$$- a^* - .5 + b = -.5$$

$$-4/7*-1/2 + b = -1/2$$

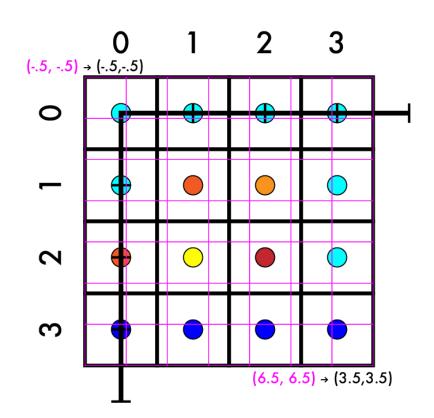
$$-4/14 + b = -7/14$$



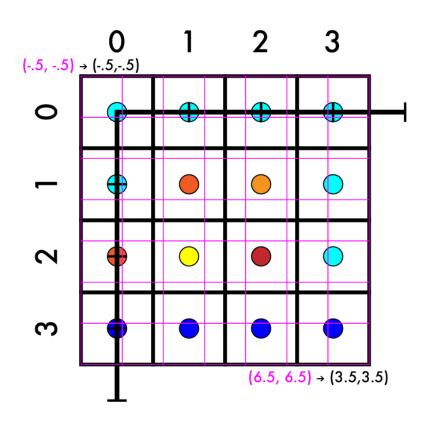
- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - $a^*-.5 + b = -.5$
 - a*6.5 + b = 3.5
 - a = 4/7
 - $a^* .5 + b = -.5$
 - -4/7*-1/2 + b = -1/2
 - -4/14 + b = -7/14
 - b = -3/14



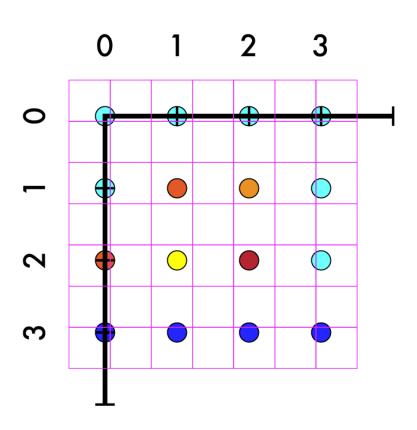
- Create our new image
- Match up coordinates
 - System of equations
 - aX + b = Y
 - a^* -.5 + b = -.5
 - a*6.5 + b = 3.5
 - -a = 4/7
 - b = -3/14
- So, we can start with any coordinate X of the big (new) image and use a and b to get Y on the smaller (old) image.



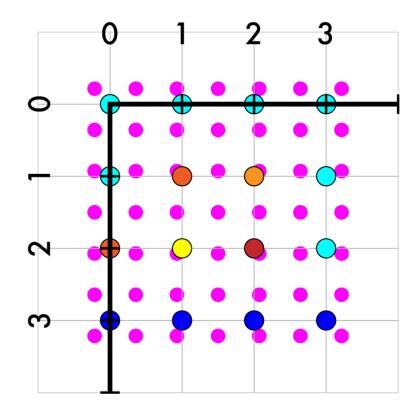
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y



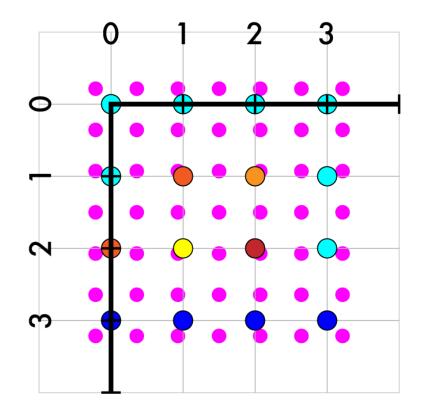
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y



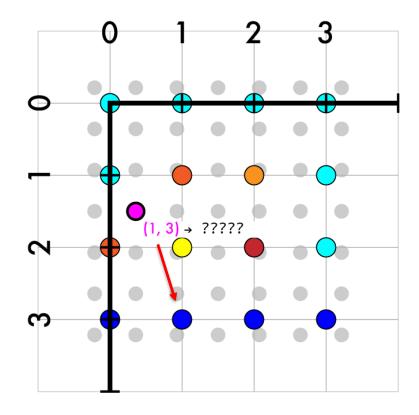
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts



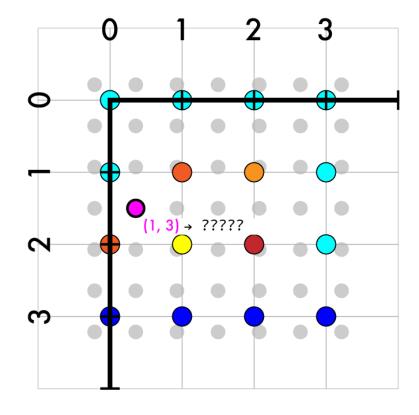
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords (Y is old)



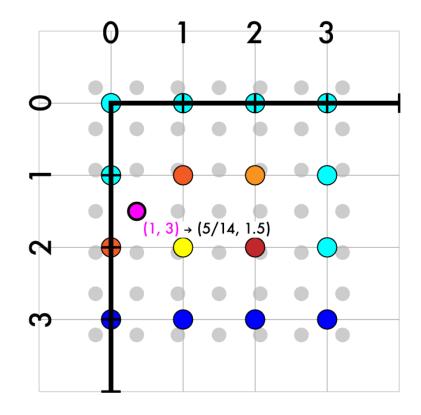
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords (Y is old)
 - (1, 3)



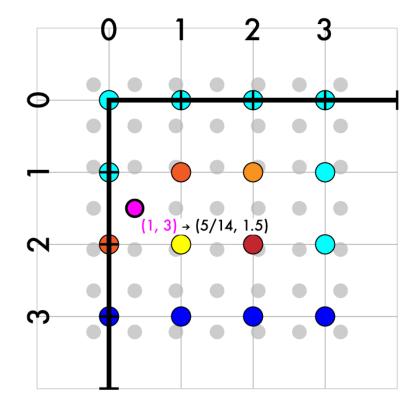
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - (1, 3)
 - 4/7*1 3/14
 - 4/7*3 3/14



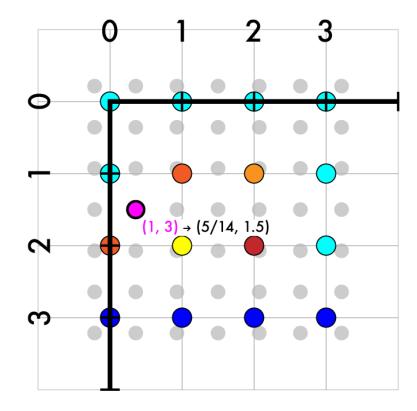
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - -(1,3)
 - 4/7*1 3/14
 - 4/7*3 3/14
 - (5/14, 21/14)



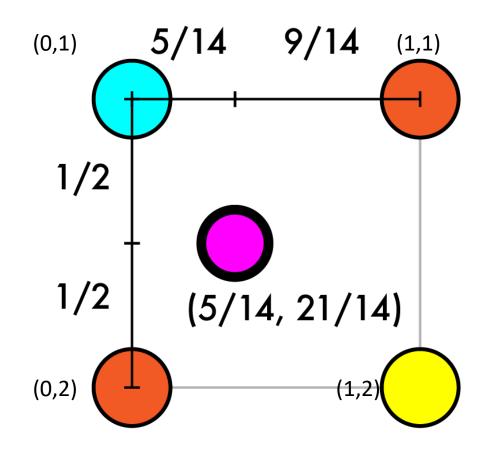
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - **-** (1, 3) -> (5/14, 21/14)



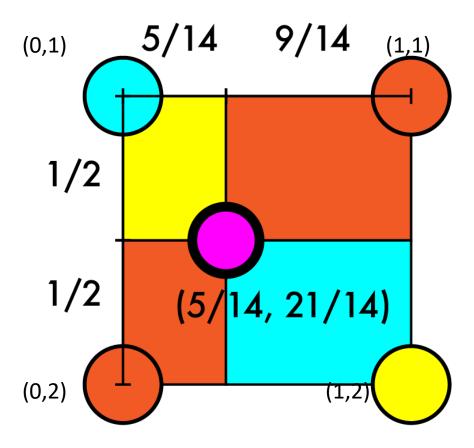
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - **-** (1, 3) -> (5/14, 21/14)
 - Interpolate old values



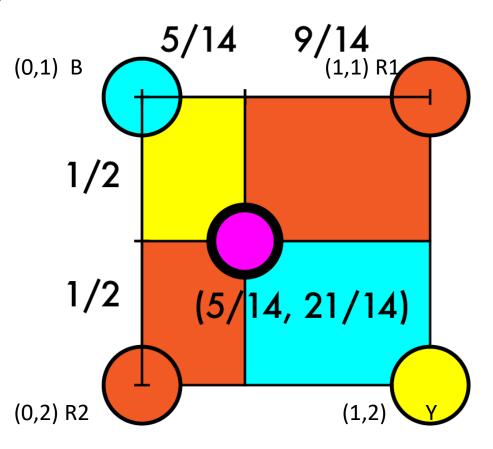
- Create our new image
- Match up coordinates
 - -4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - **-** (1, 3) -> (5/14, 21/14)
 - Interpolate old values



- Create our new image
- Match up coordinates
 - -4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - **-** (1, 3) -> (5/14, 21/14)
 - Interpolate old values
 - Size of opposite rects



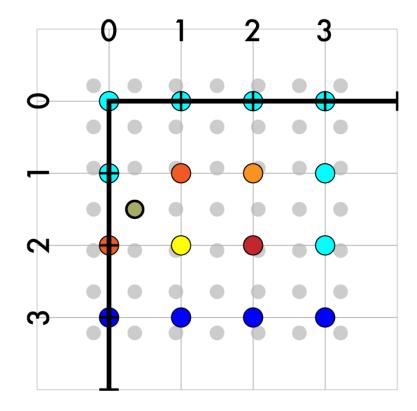
- Create our new image
- Match up coordinates
 - -4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - **-** (1, 3) -> (5/14, 21/14)
 - Interpolate old values
 - Yar = (1/2)(5/14)
 - Bar = (1/2)(9/14)
 - R1ar = (1/2)(5/14)
 - R2ar = (1/2)(9/14)



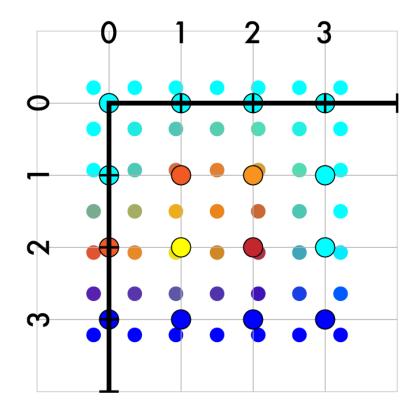
V = Yval*Yar+Bval*Var+R1val*R1ar+R2val*R2ar

- For each channel c, put the interpolated value from that channel in position (1,3,c).

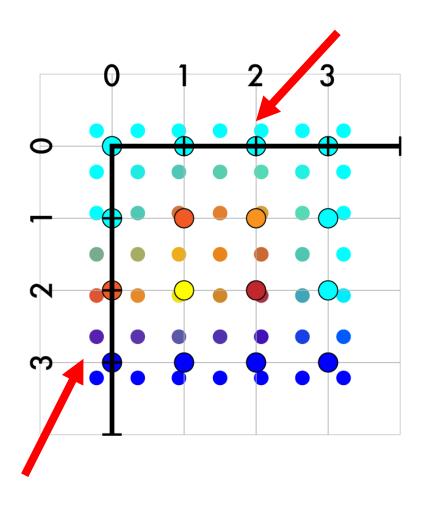
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - **-** (1, 3) -> (5/14, 21/14)
 - Interpolate old values



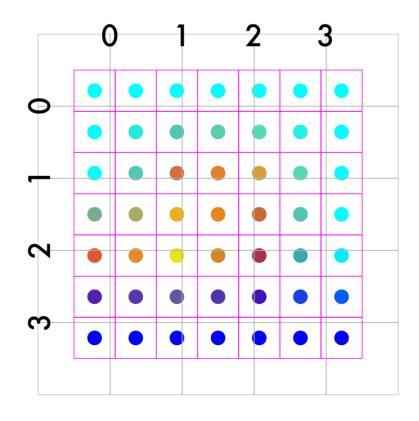
- Create our new image results
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - **-** (1, 3) -> (5/14, 21/14)
 - Interpolate old values



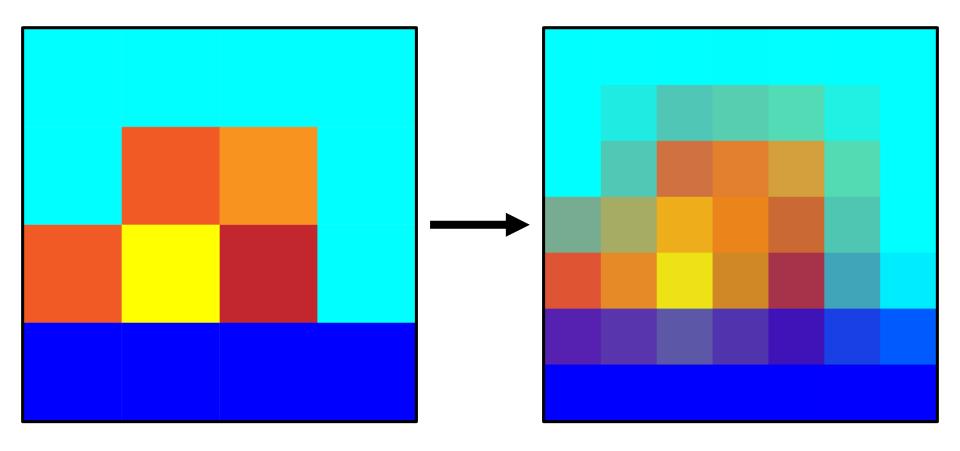
- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - **-** (1, 3) -> (5/14, 21/14)
 - Interpolate old values
- Fill in the rest
 - On outer edges use padding!



- Create our new image
- Match up coordinates
 - 4/7 X 3/14 = Y
- Iterate over new pts
 - Map to old coords
 - **-** (1, 3) -> (5/14, 21/14)
 - Interpolate old values
- Final result 7 x 7



We did it!



Let's do something interesting already!!

Want to make image smaller











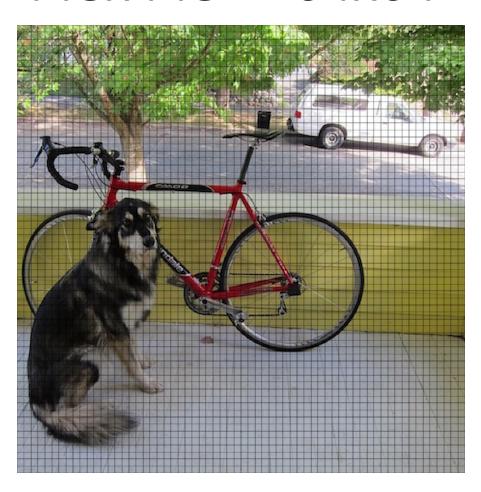








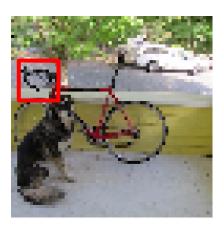




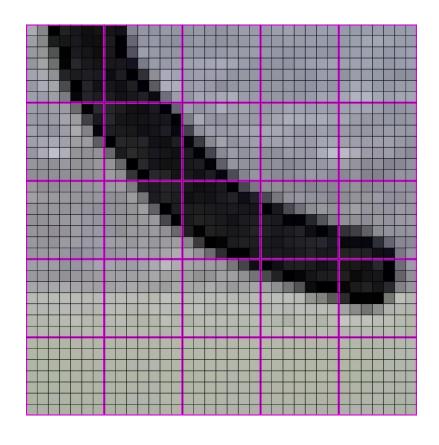


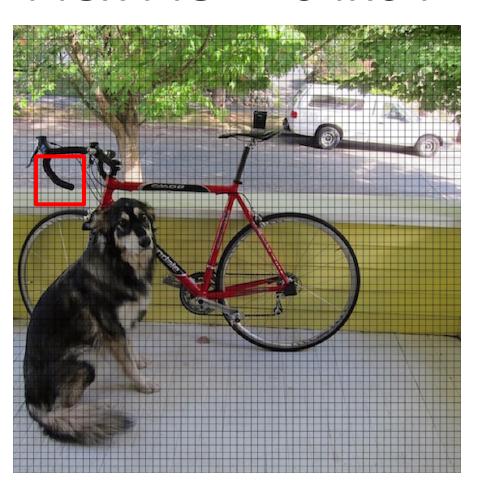


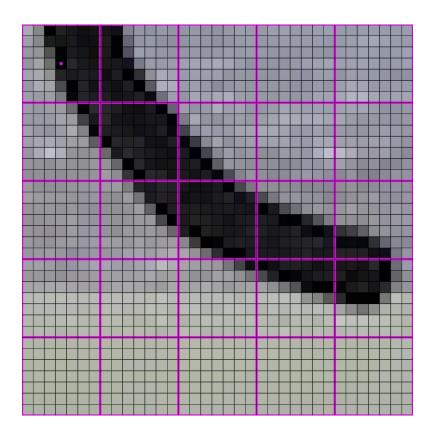




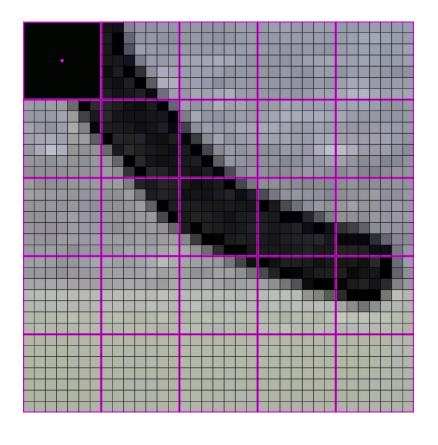




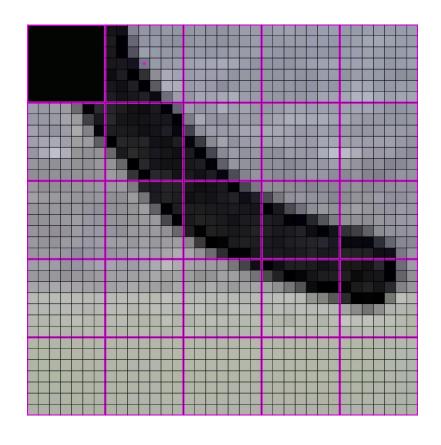


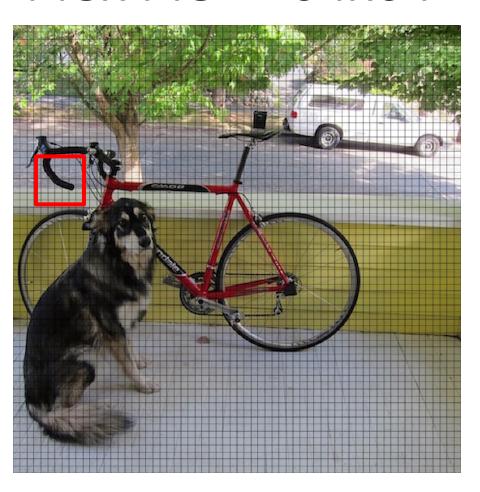


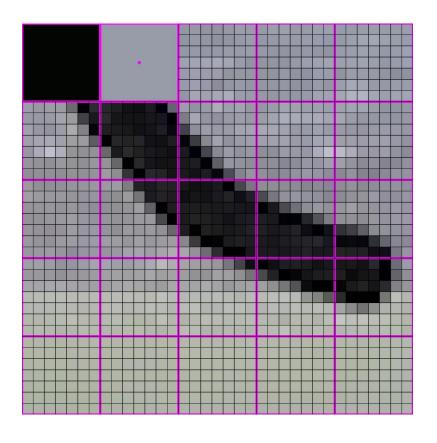




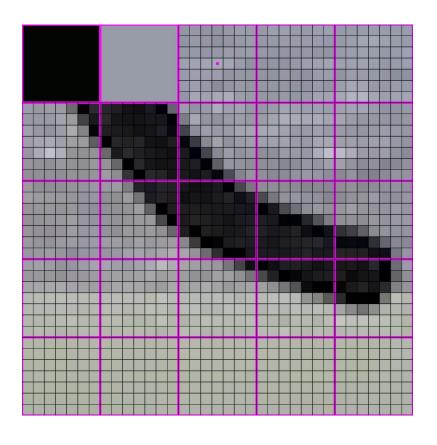




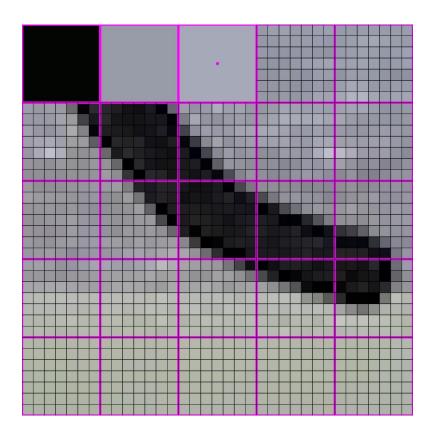




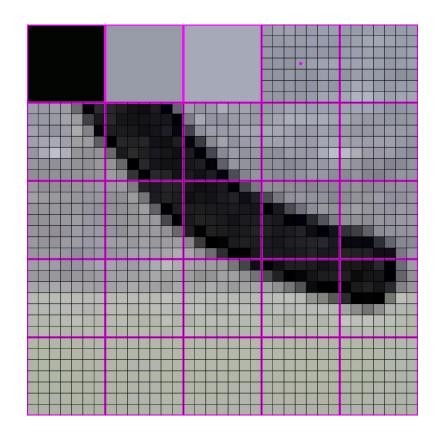




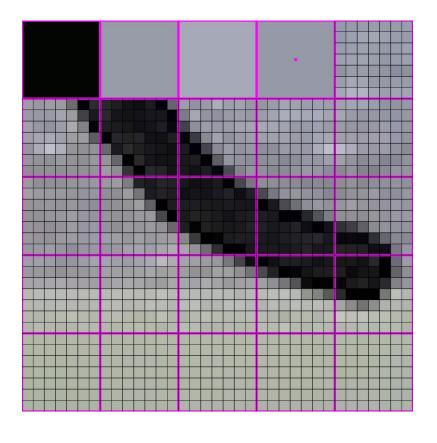




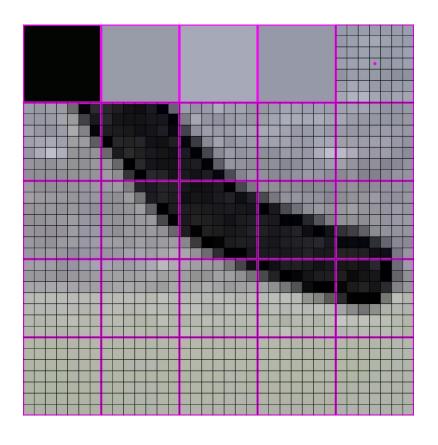




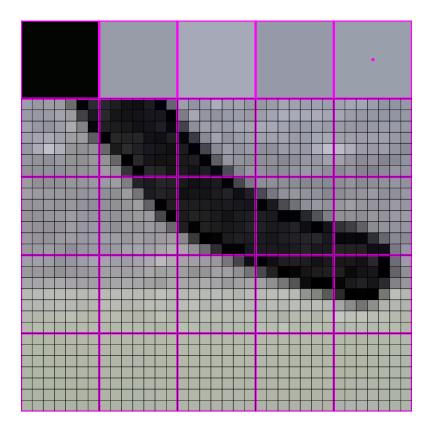




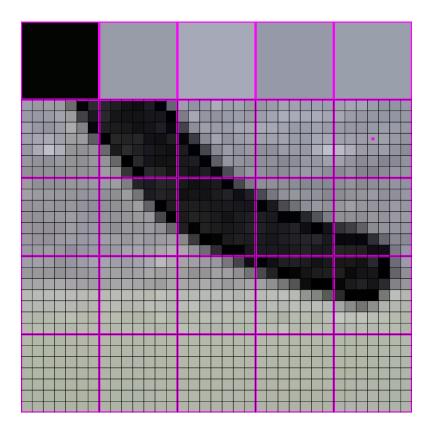


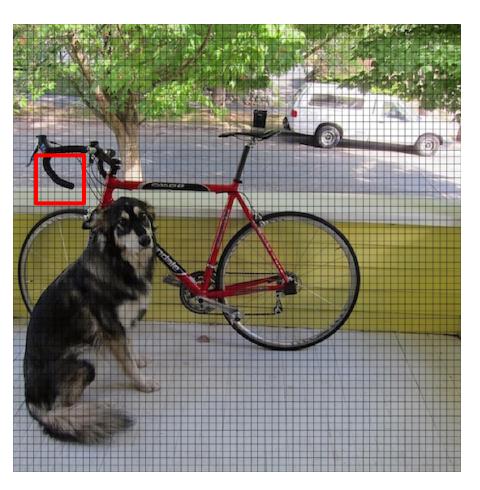


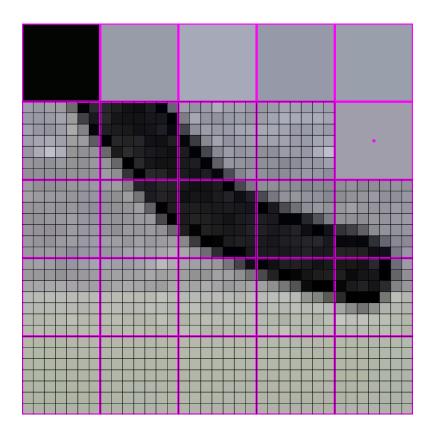




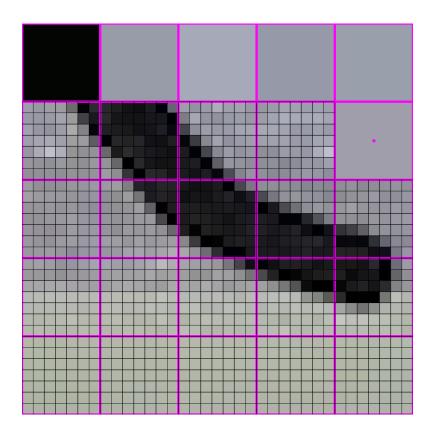




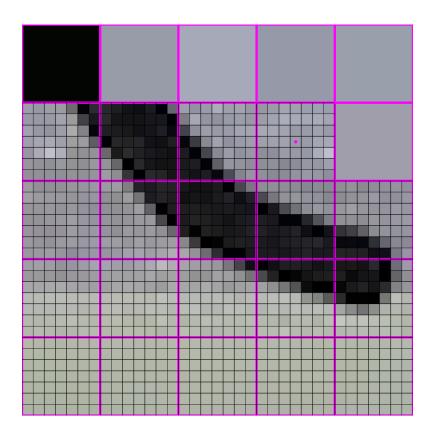




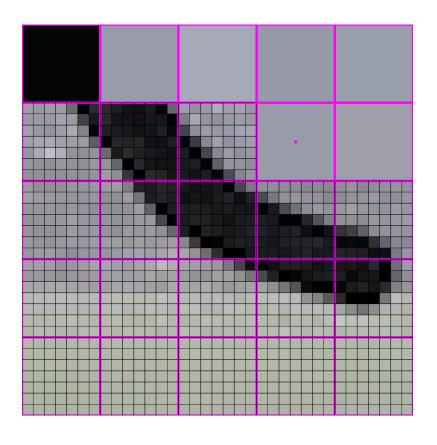




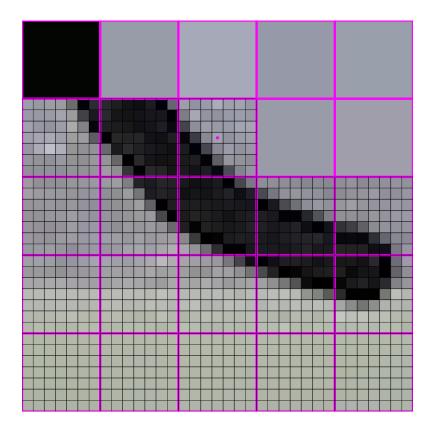




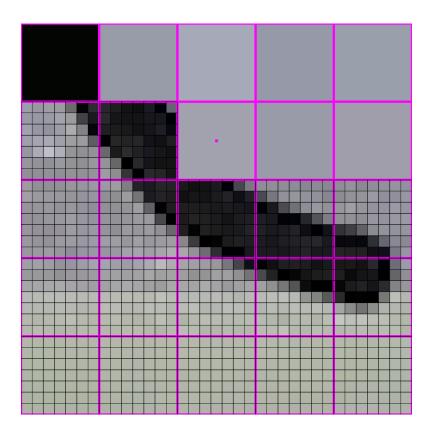




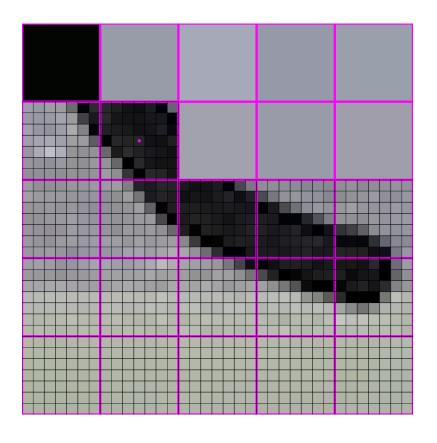




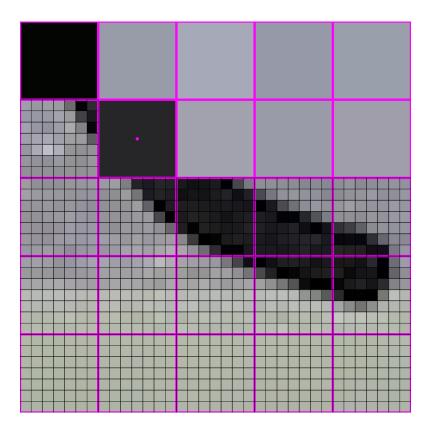




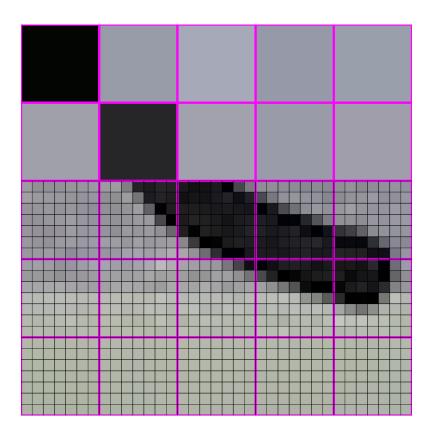




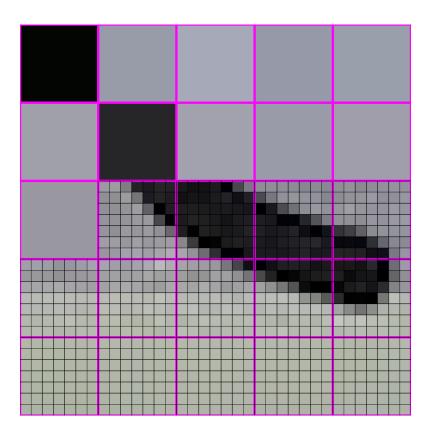




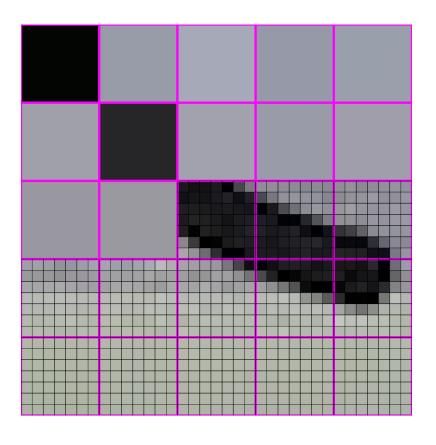




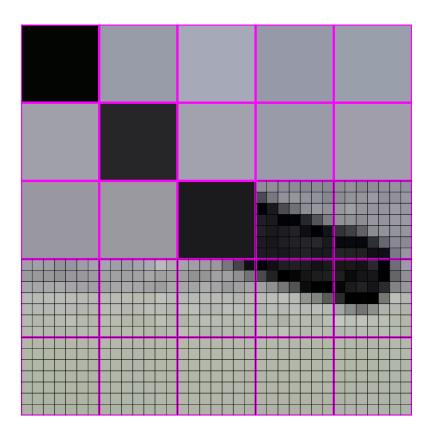


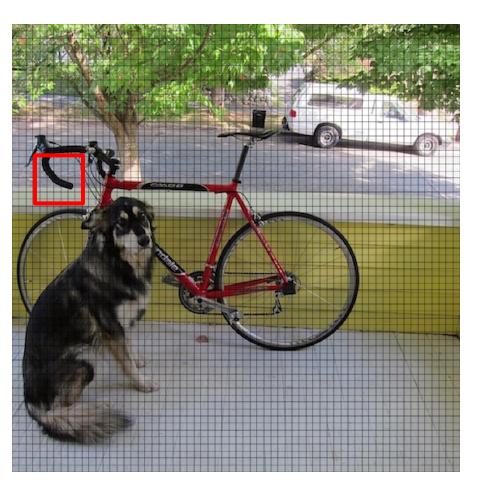


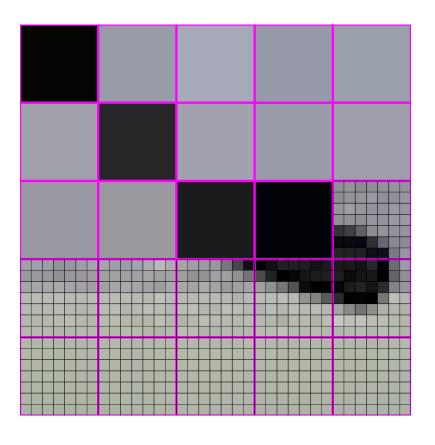


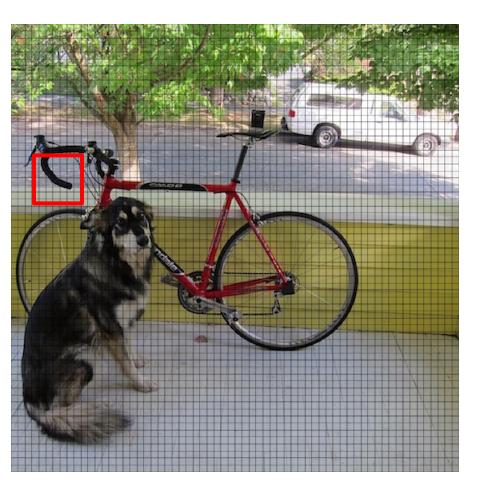


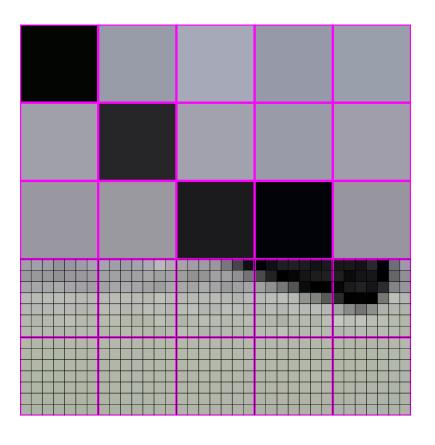


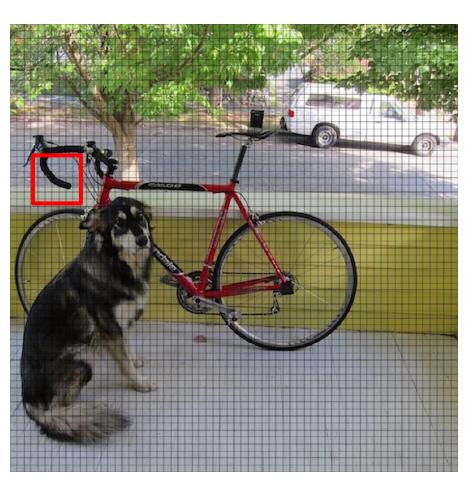


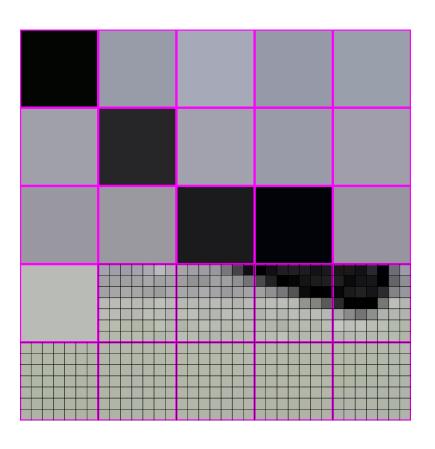




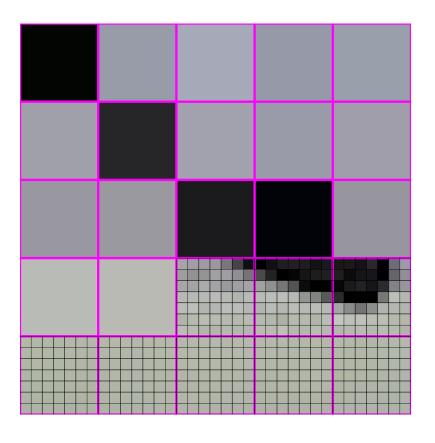


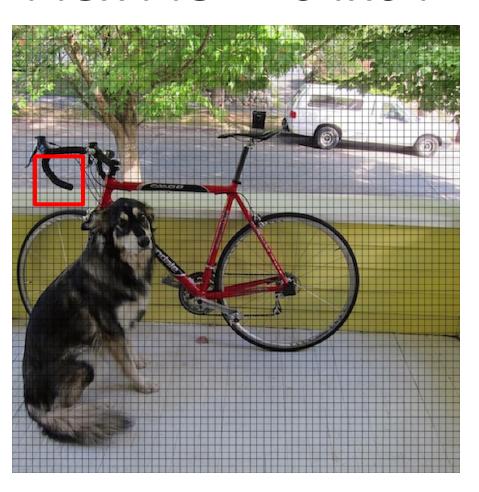


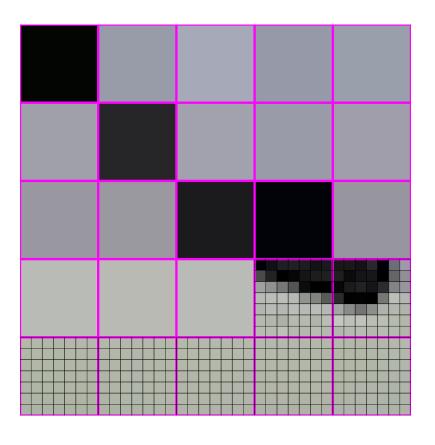


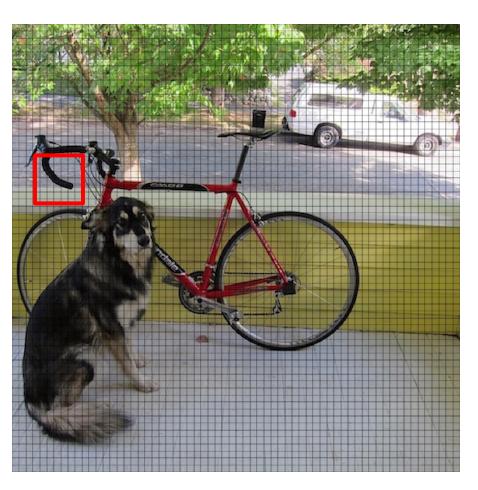


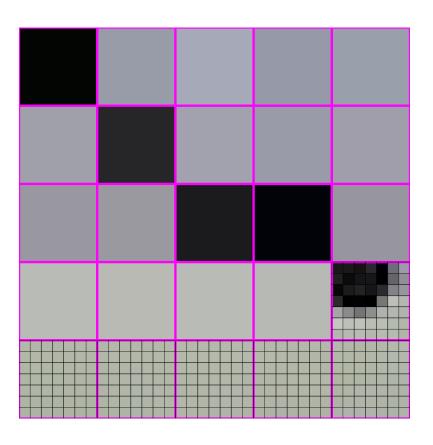




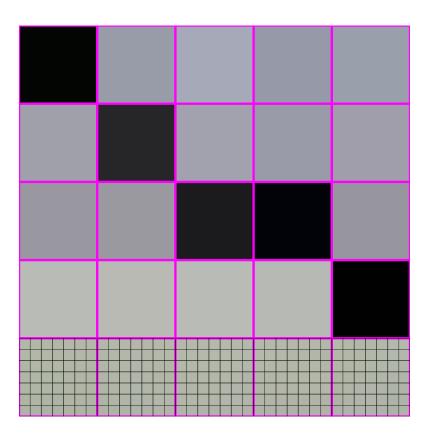




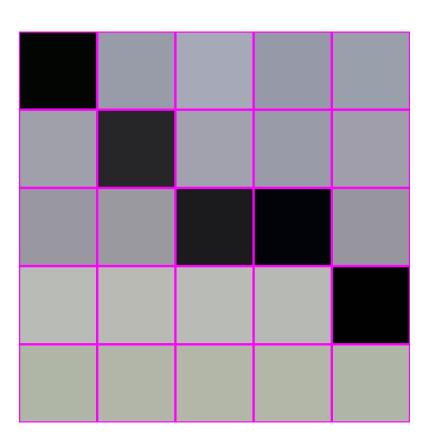








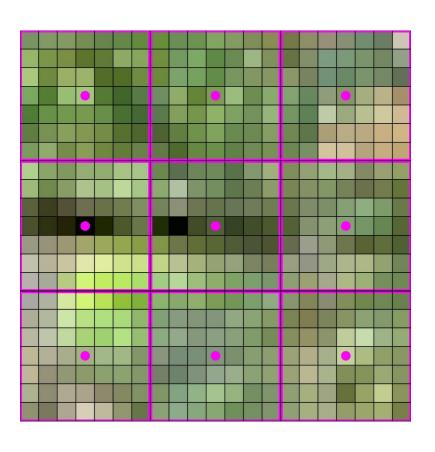




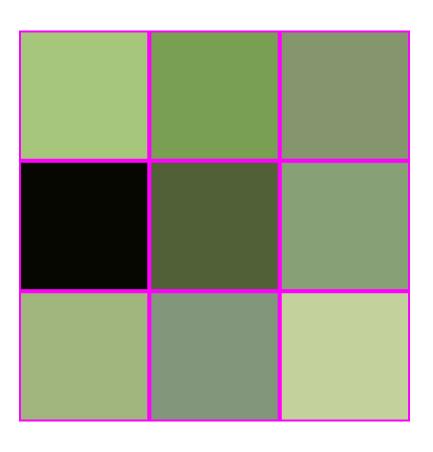




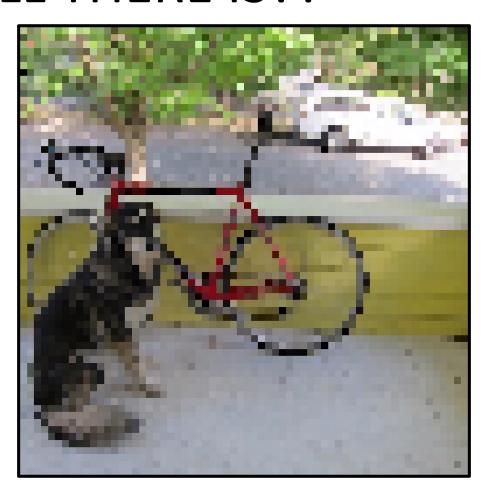








IS THIS ALL THERE IS??



THERE IS A BETTER WAY!



Next Time: Filtering