Computer Vision

CSE 455

Linda Shapiro
Professor of Computer Science & Engineering
Professor of Electrical & Computer Engineering

Course Information

- Time:
  - TTH 10:00-11:20
- Location:
  - CSE2 G01
- Contact:
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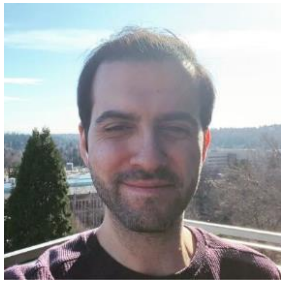
- TAs:
  - Kechun Liu
  - kechun@cs.washington.edu
  - Nishat Khan
  - nkhan51@uw.edu
  - Mehmet Saygin Seyfioğlu
  - msaygin@uw.edu



- Website:
  - https://courses.cs.washington.edu/courses/cse455/24wi/

Topics

- Introduction
- Color and Texture
- Image Coordinates, Transforms, and Resizing
- Filters and Convolutions
- Edges and Lines
- Interest Operators, Image Matching, Image Stitching
- Face Detection/Recognition
- Machine Learning Overview including Neural Nets
- Object Detection and Recognition with ML
- Convolutional Neural Networks
- CNN Applications
- Motion/Optical Flow
- Stereo and 3D Depth Perception

Grading (tentative)

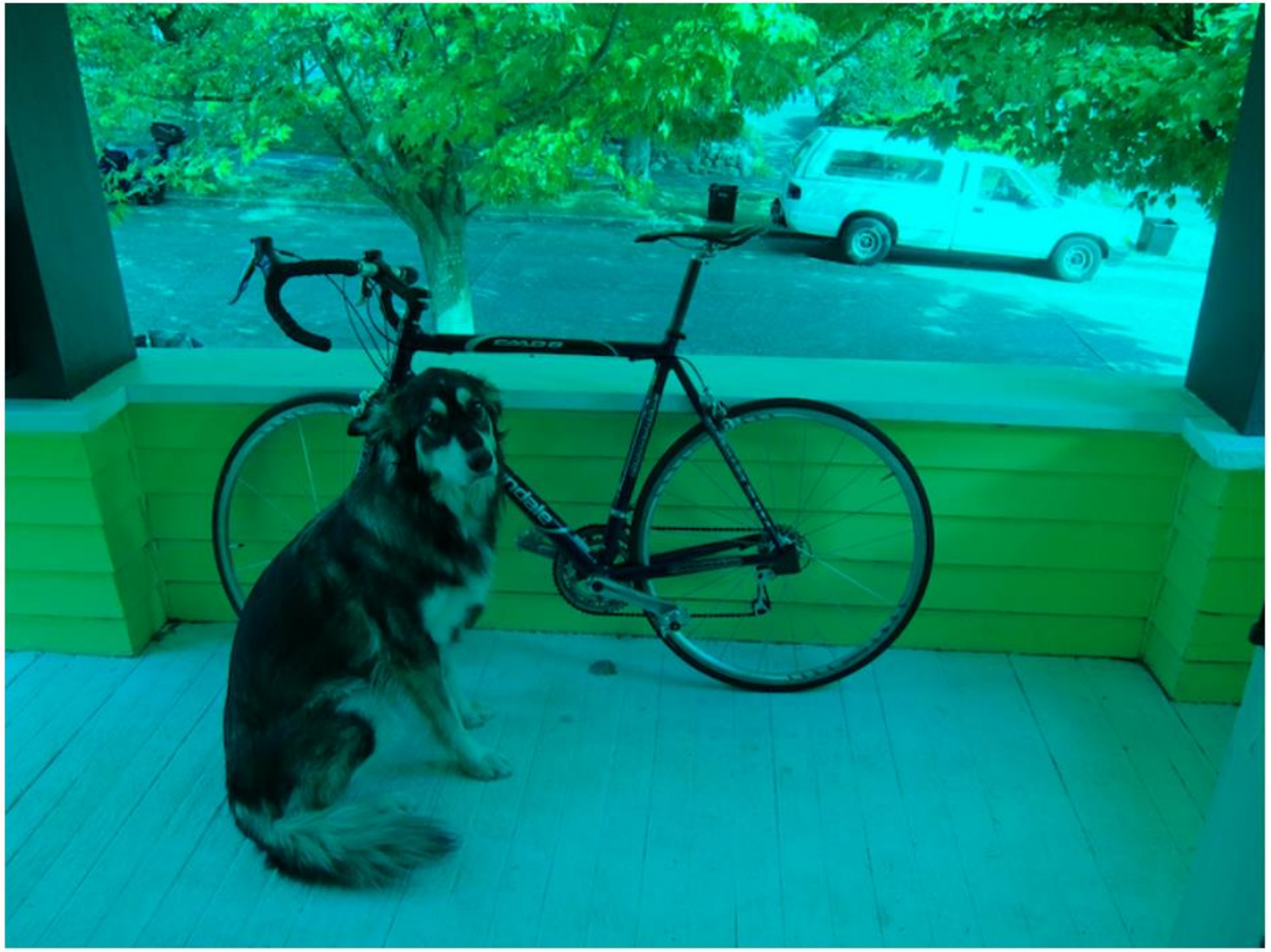
- Six regular assignments (75%)
- One Course Project (25%)
- NO EXAMS (Yay!)

Assignments

- Build a vision library from the ground up
- Mostly in C
- Play with advanced tools, neural networks

- Beginning: lots of skeleton code, explanations
- End: less guidance, more experimentation

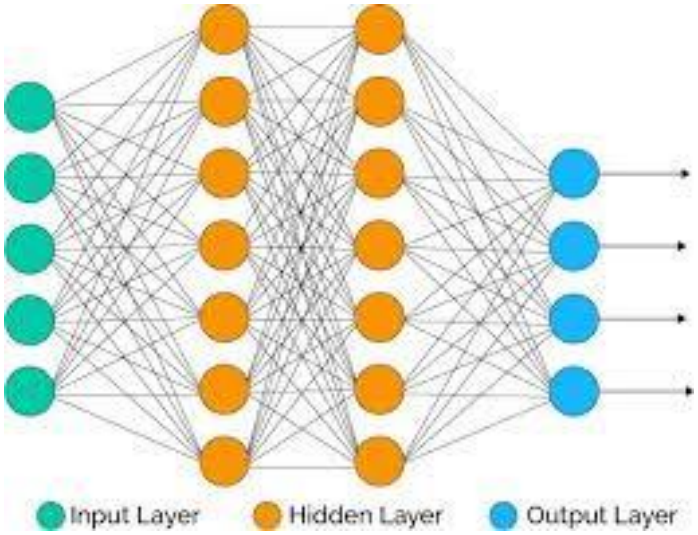
Assignment 1: Fun with Color



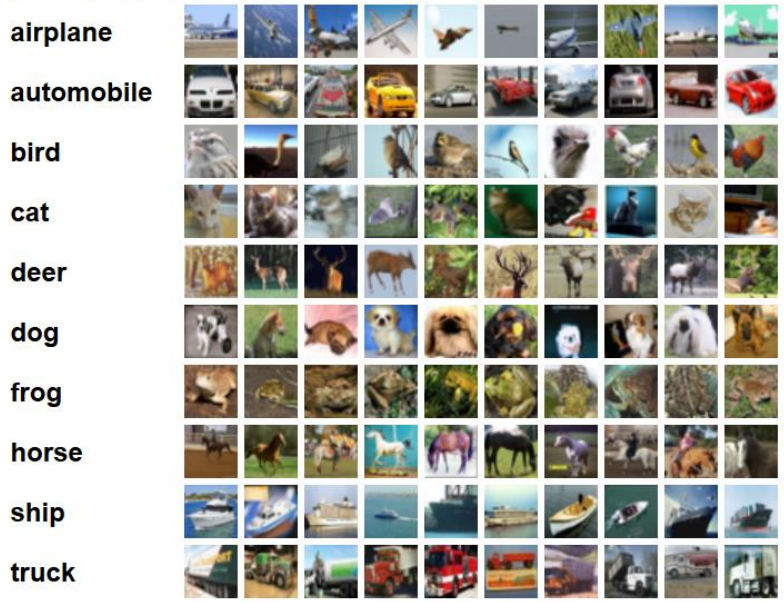
Assignment 2: Image Resizing and Filtering

Assignment 3: Panorama Stitching

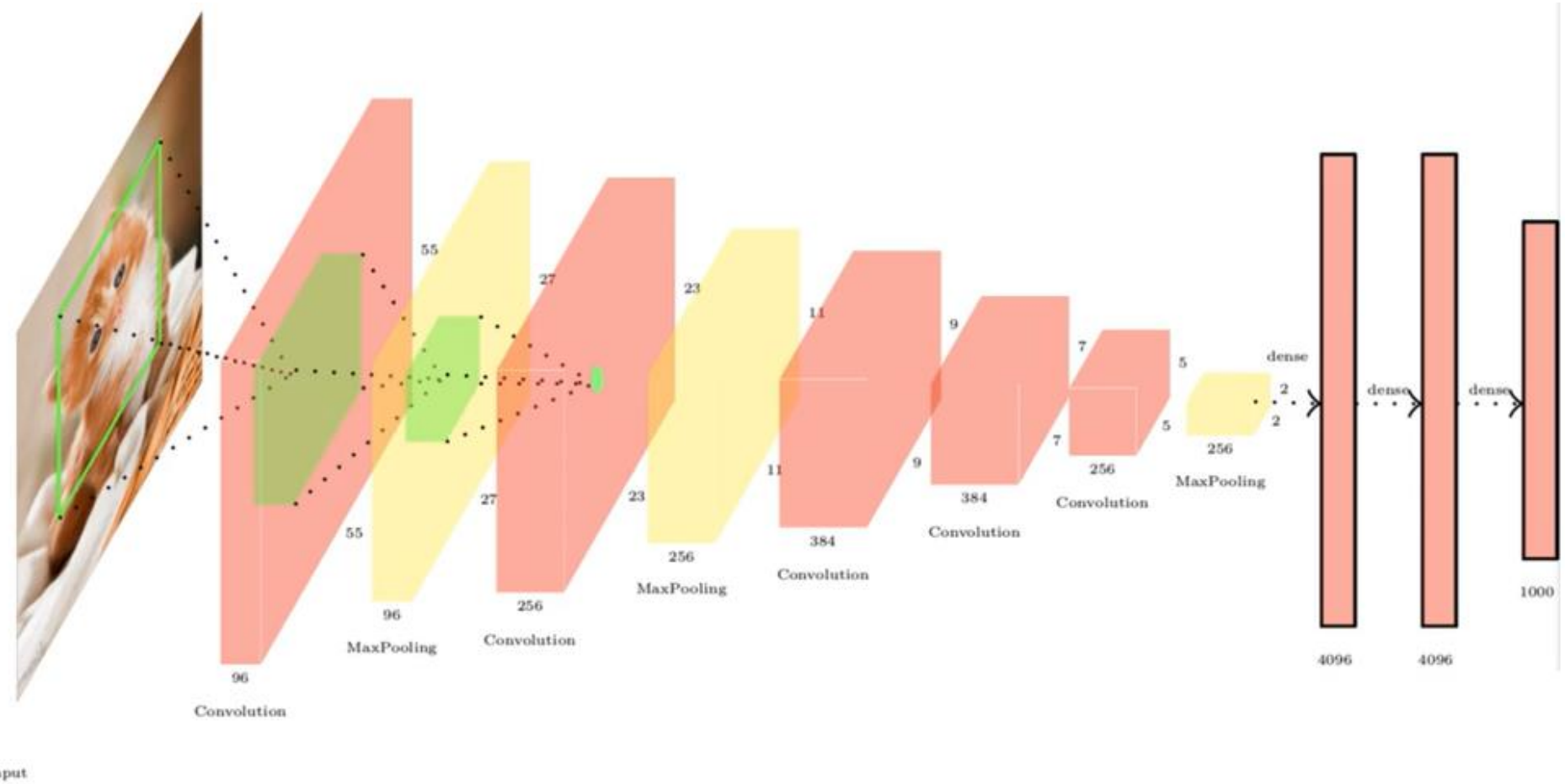
Assignment 4: Neural Networks



Here are the classes in the dataset, as well as 10 random images from each:

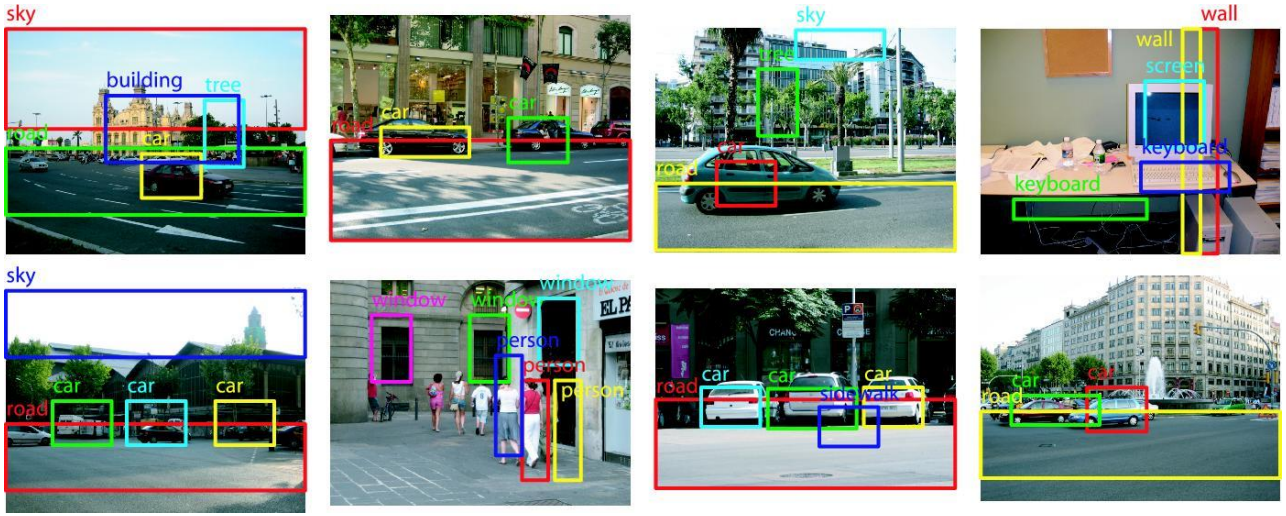


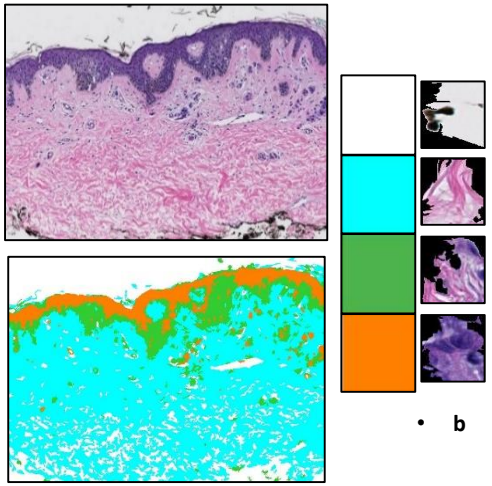
Assignment 5: PyTorch



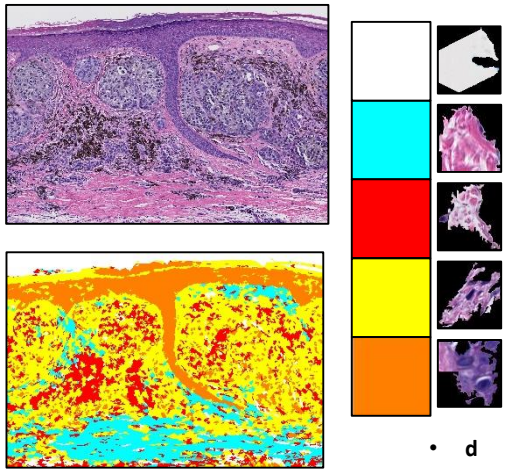
Assignment 6: Optical Flow

Final Course Project: Machine Learning for Some Kind of Application

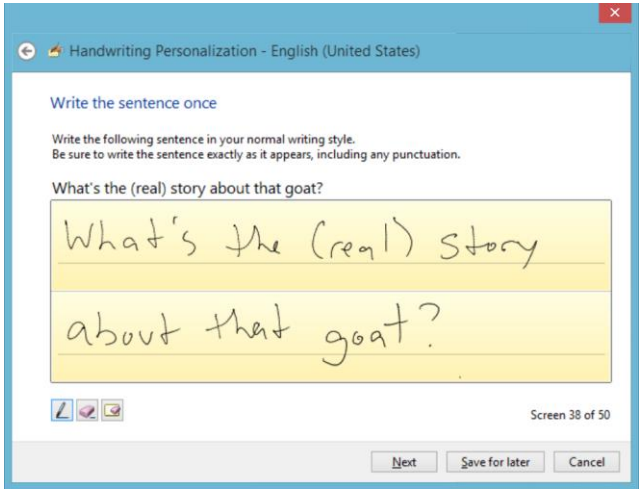




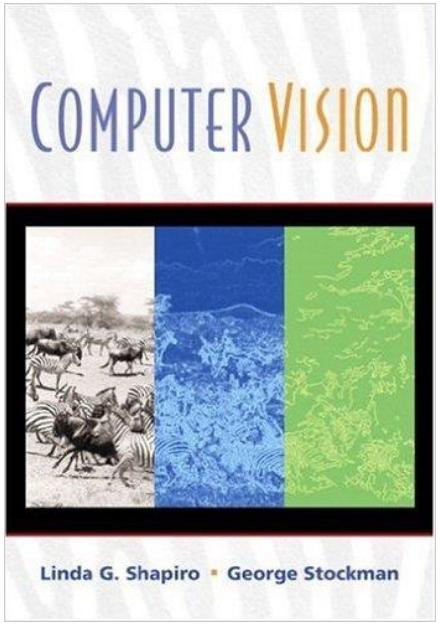
• a • b



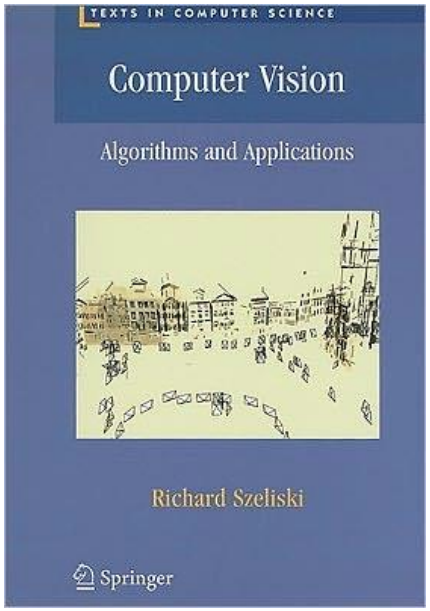
• c • d



Books

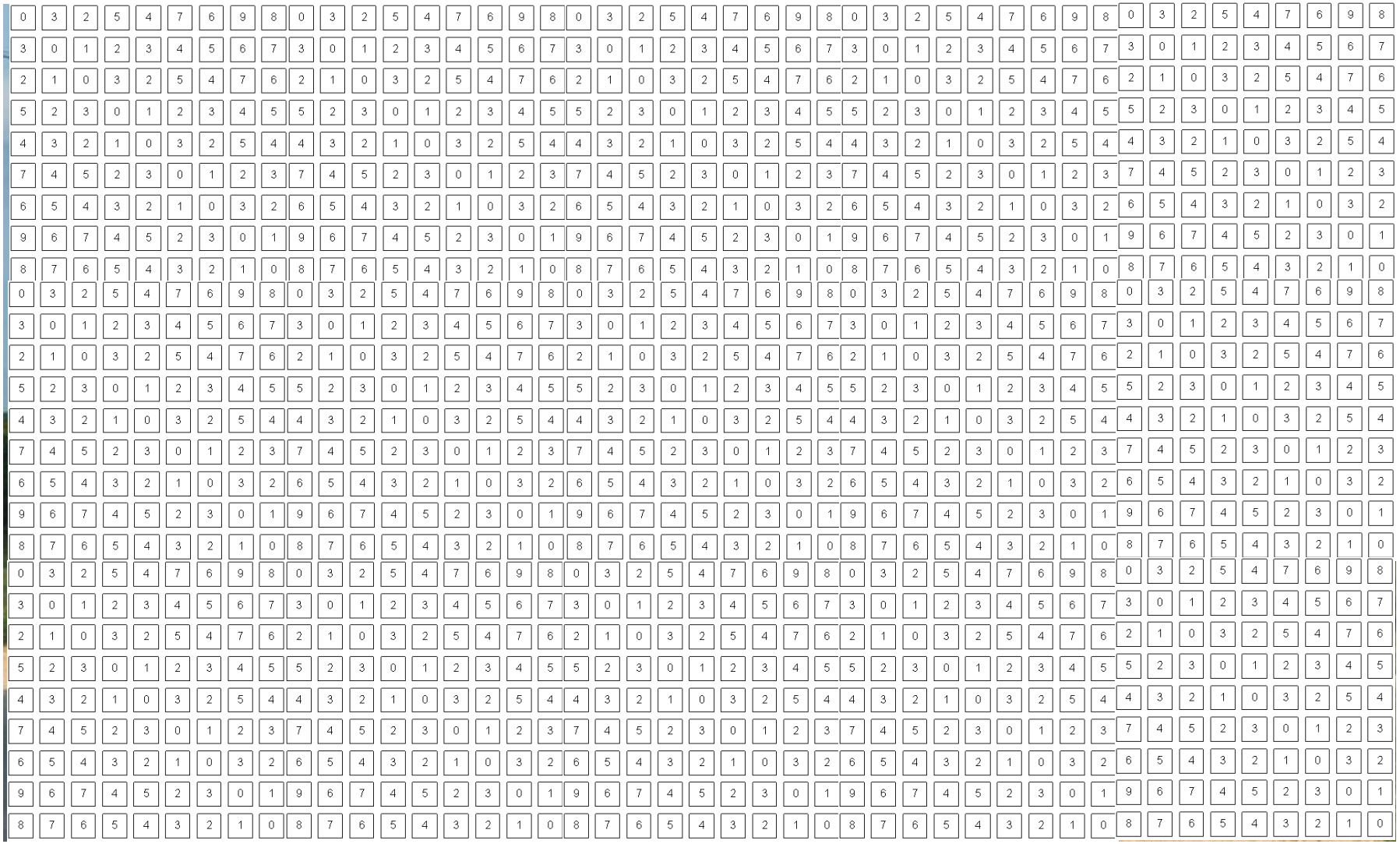


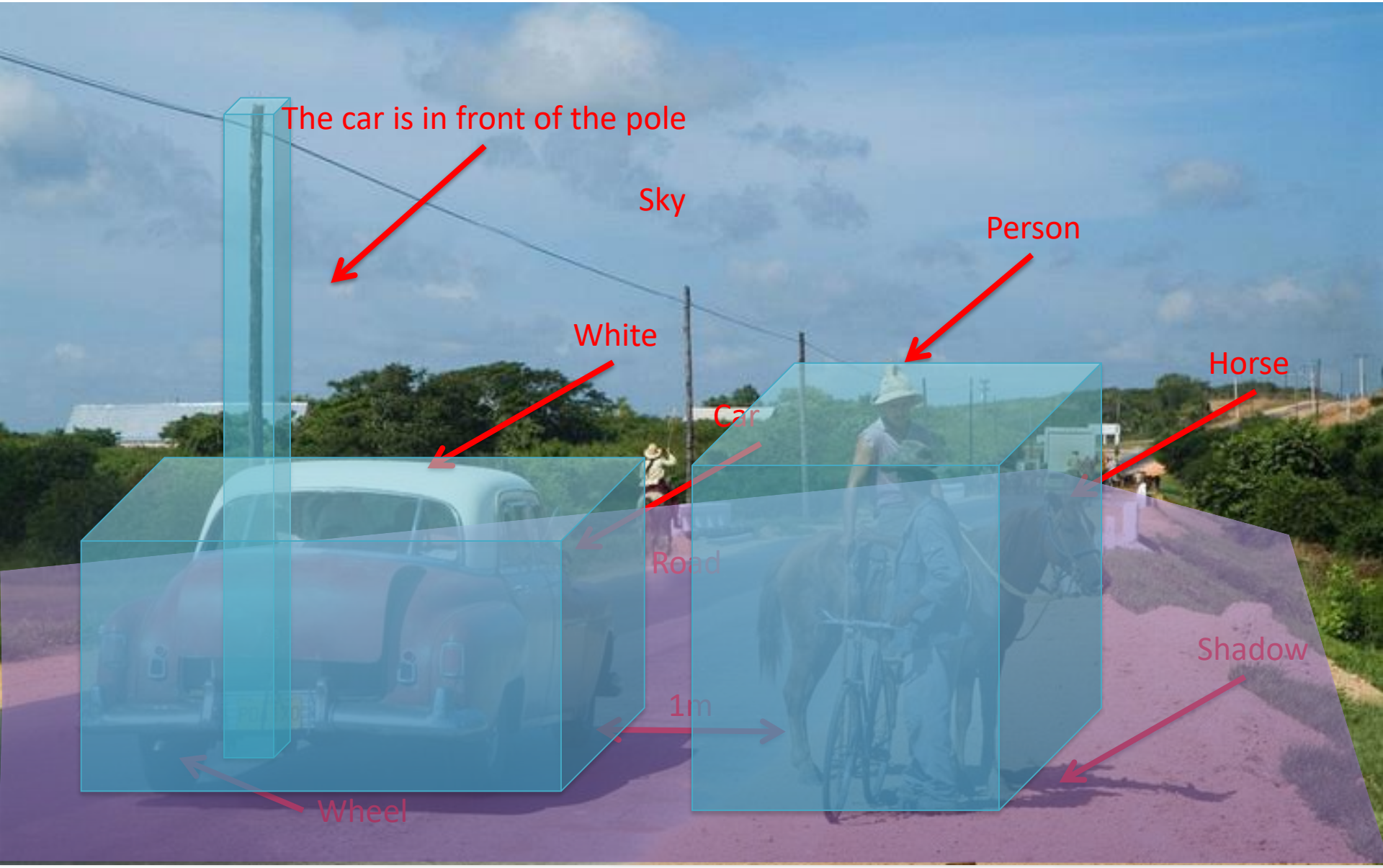
Older, but designed for undergrads and has the basics. Chapters available from our web page.



Newest and available as a pdf online (both the 2010 and 2020 versions).


One Look Is Worth A Thousand Words--
One look at our line of Republic, Firestone, Miller and United States tires can tell you more than a hundred personal letters or advertisements.
WE WILL PROVE THEIR VALUE BEFORE YOU INVEST ONE DOLLAR IN THEM.
Ever consider buying Supplies from a catalog?
What's the use! Call and see what you are buying. One look at our display of automobile and motorcycle accessories will convince you of the fact.
THAT WE HAVE EVERYTHING FOR THE AUTO
Piqua Auto Supply House
133 N. Main St.—Piqua, O.




The car is in front of the pole
Sky
Person
White
Horse
Car
Road
Shadow
1m
Wheel

Computer Vision

- Low Level Vision
  - Measurements
  - Enhancements
  - Region segmentation
  - Features
- Mid Level Vision
  - Reconstruction
  - Depth
  - Motion Estimation
- High Level Vision
  - Category detection
  - Activity recognition
  - Deep understandings

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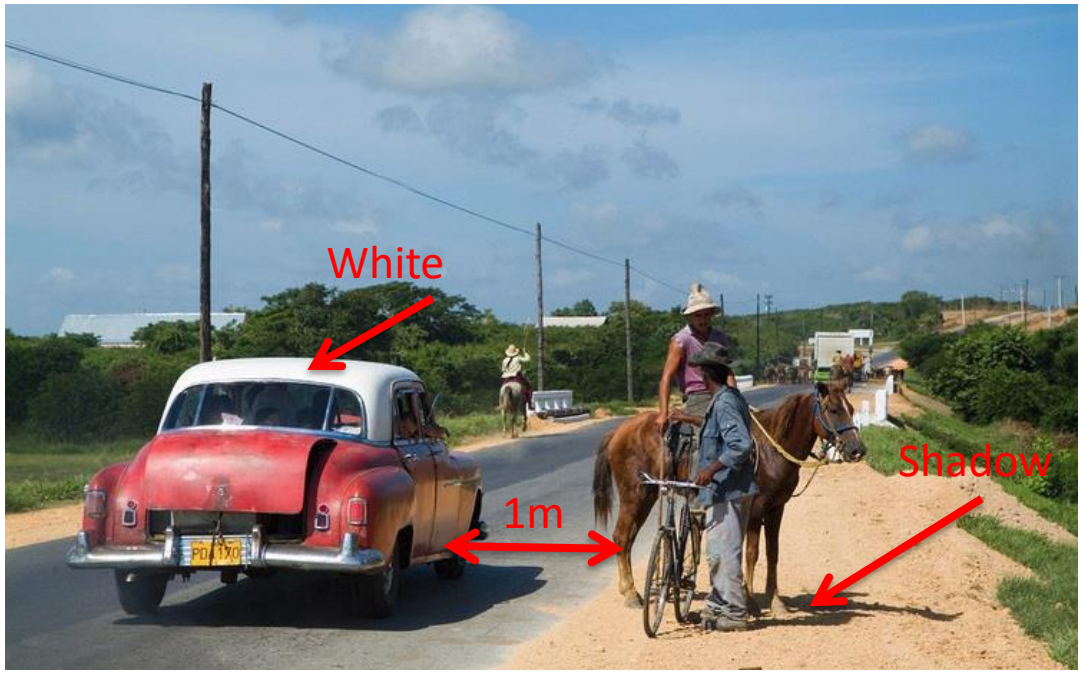
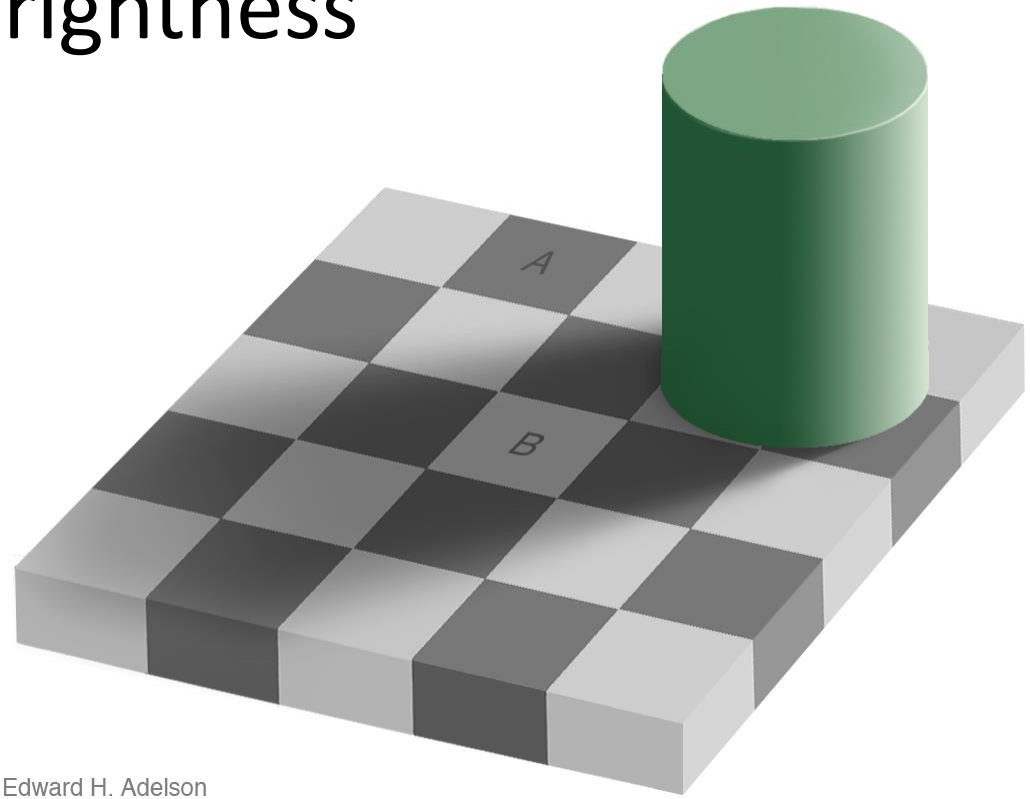


Measurement

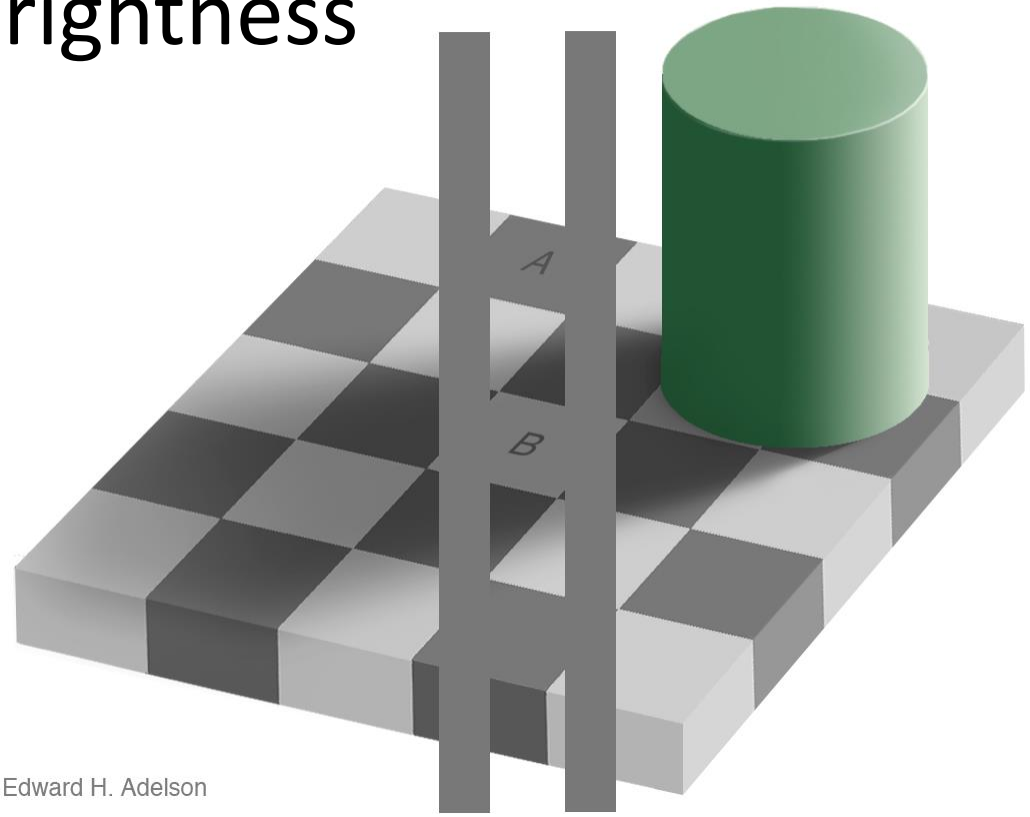
Brightness



Edward H. Adelson

Measurement

Brightness

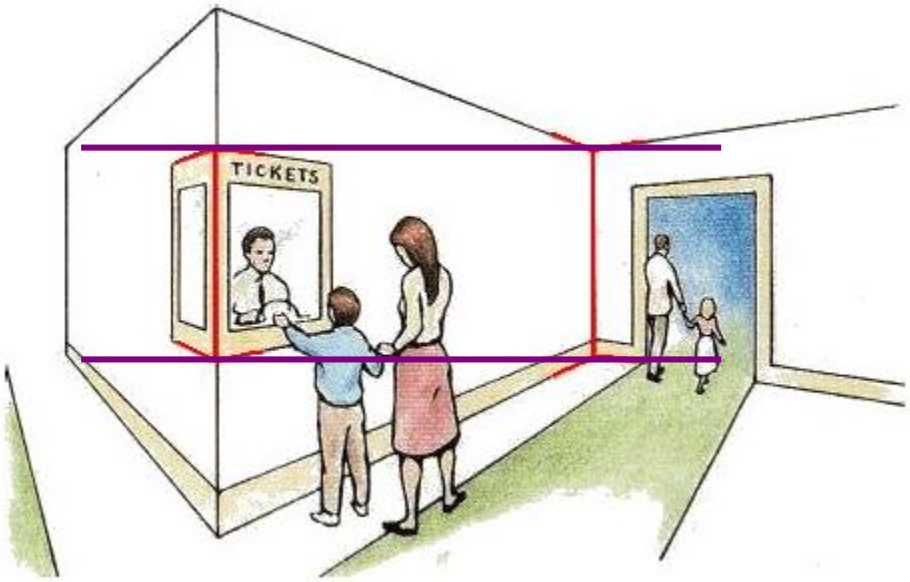


http://www.newworldencyclopedia.org/entry/Same_color_illusion

Slide Credit: Alyosha Efros

Measurement

Length



Müller-Lyer Illusion

http://www.michaelbach.de/ot/sze_muelue/index.html

Slide Credit: Alyosha Efros

Image Enhancement

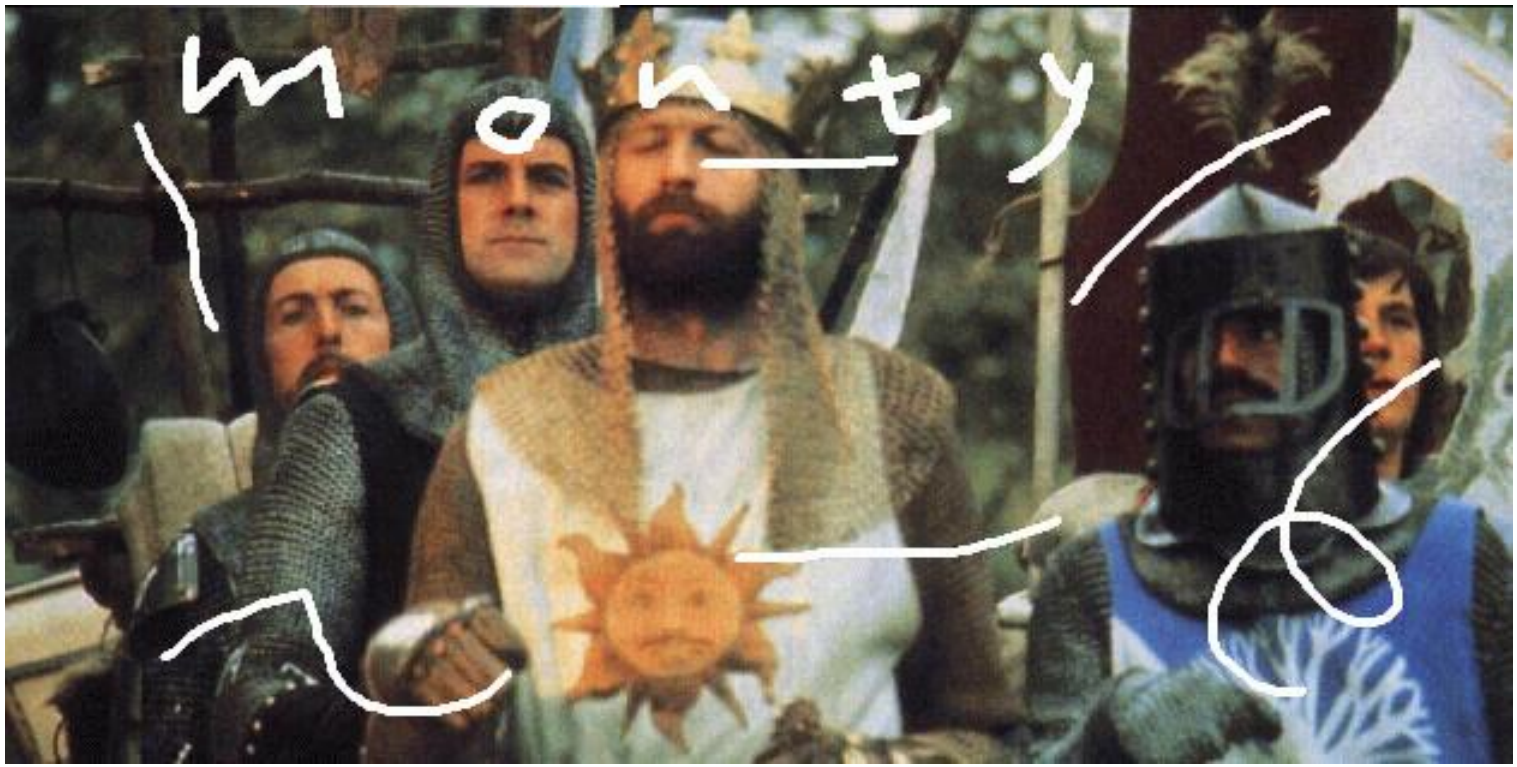


Image Inpainting, M. Bertalmío et al.
http://www.iua.upf.es/~mbertalmio//restoration.html

Image Enhancement

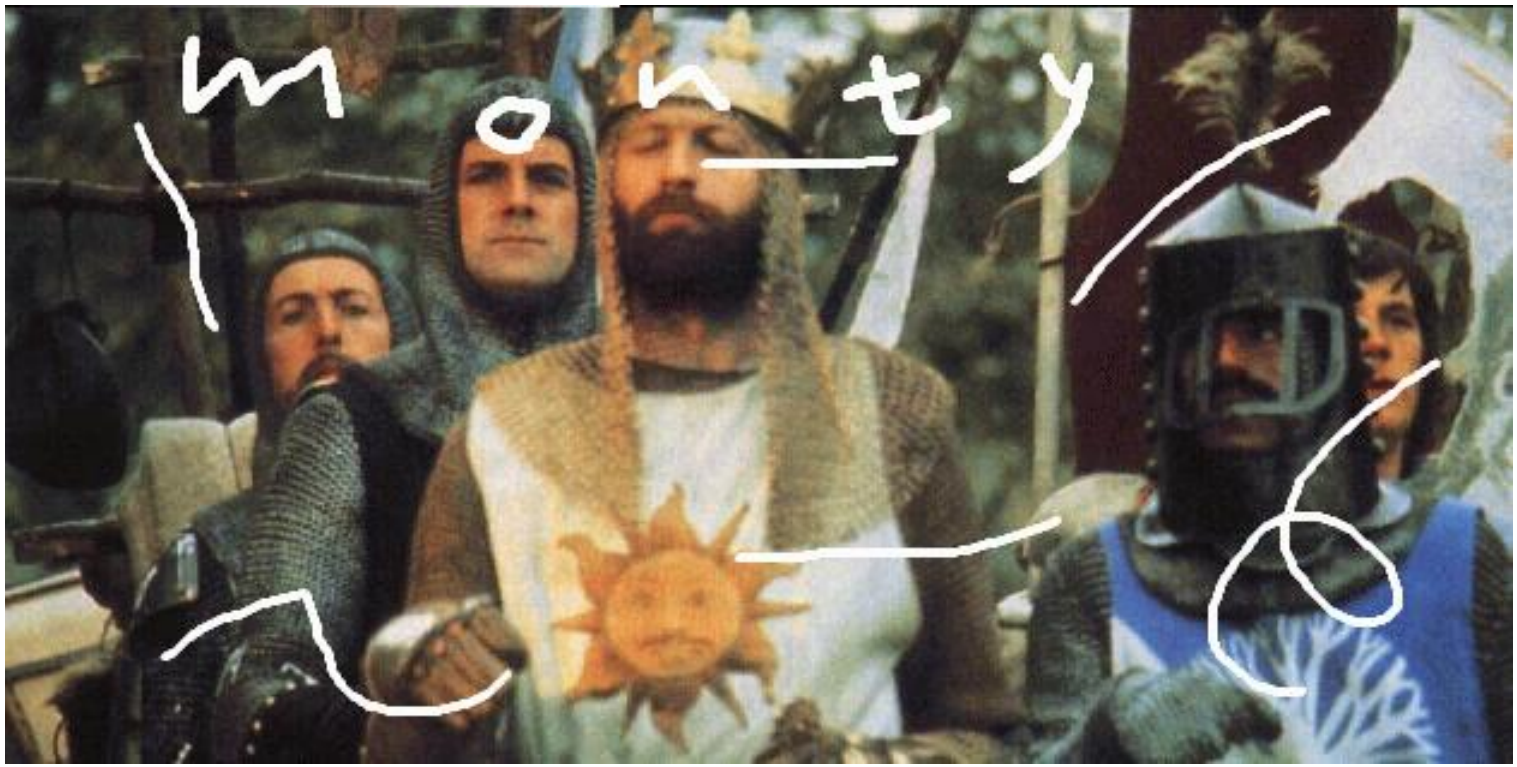


Image Inpainting, M. Bertalmío et al.
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Image Enhancement

Image Inpainting, M. Bertalmío et al.
http://www.iua.upf.es/~mbertalmio//restoration.html

Seam Carving

less important

[Shai & Avidan, SIGGRAPH 2007]

Traditional resizing uses and stretches the whole image.

Content-aware resizing uses important areas.
Extends in horizontal direction and reduces in vertical.

[Shai & Avidan, SIGGRAPH 2007]

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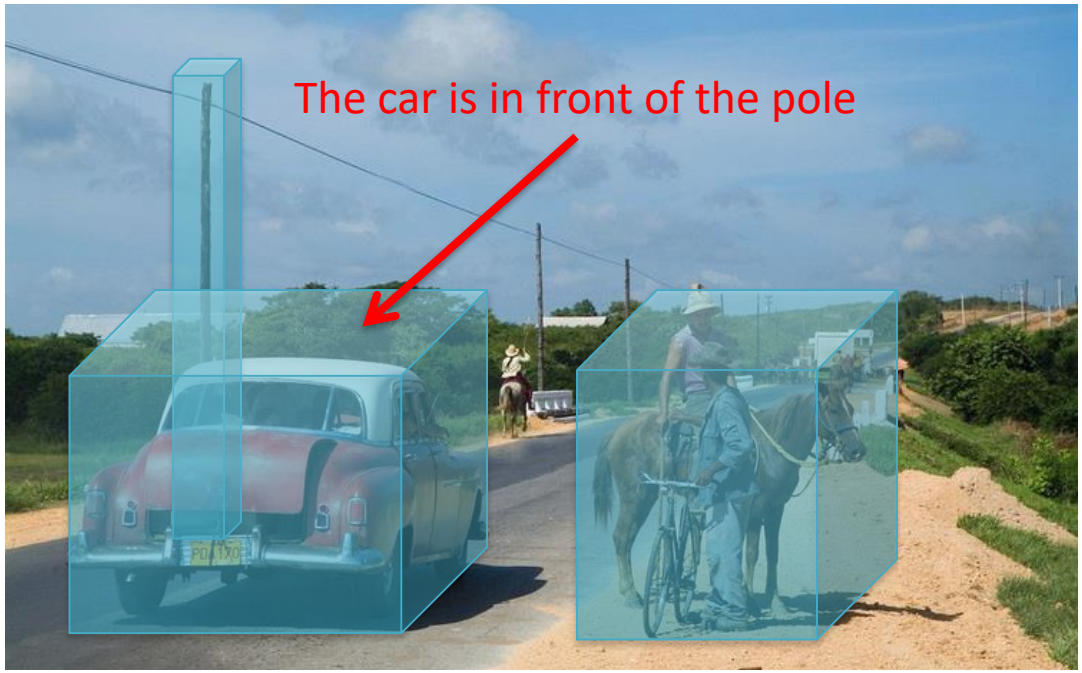
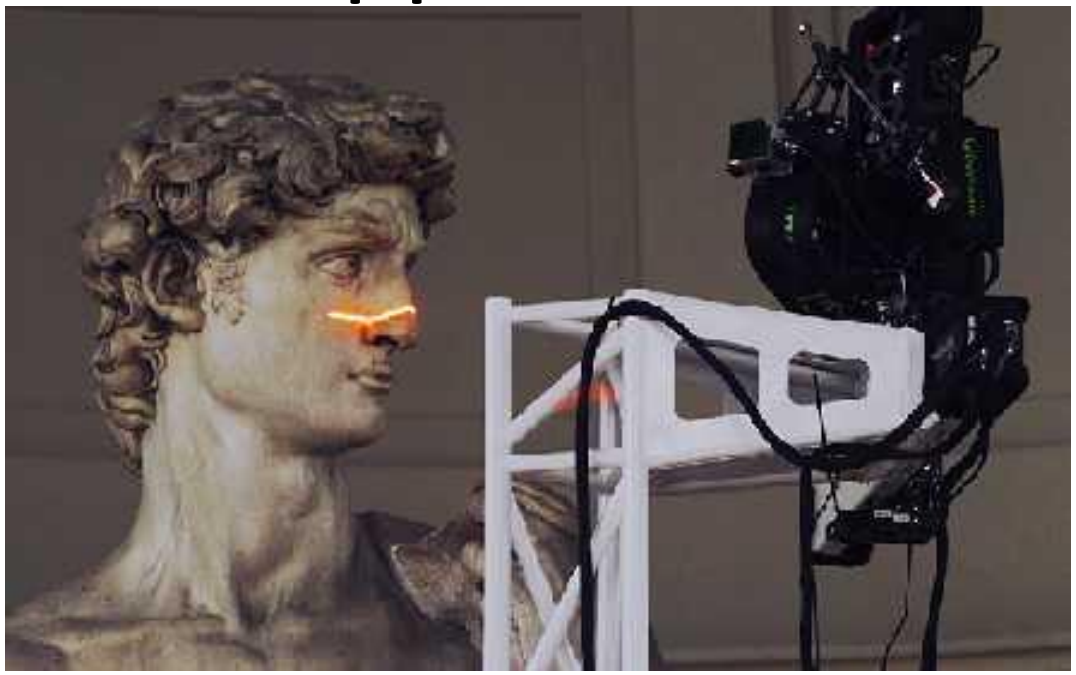


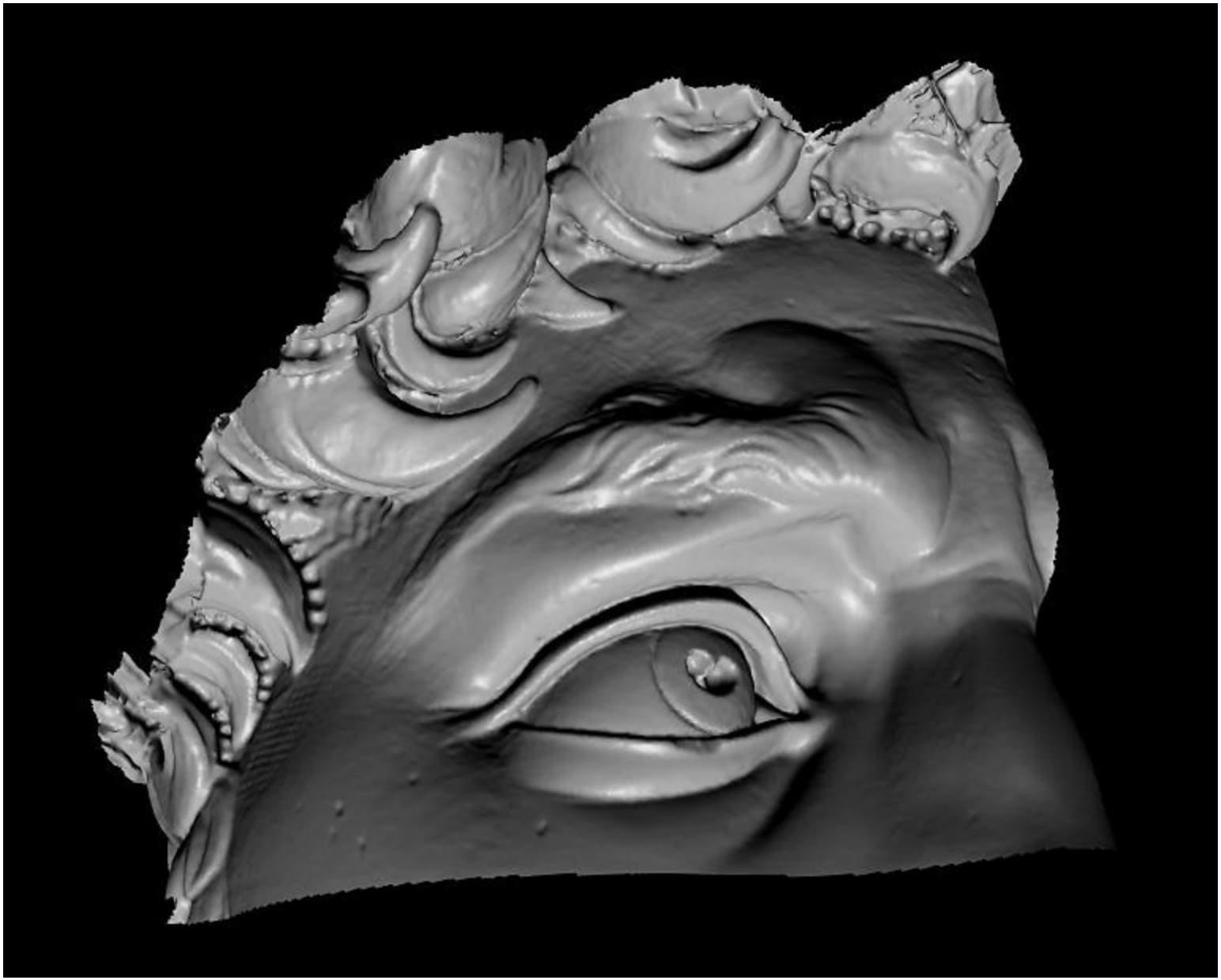
Applications: 3D Scanning

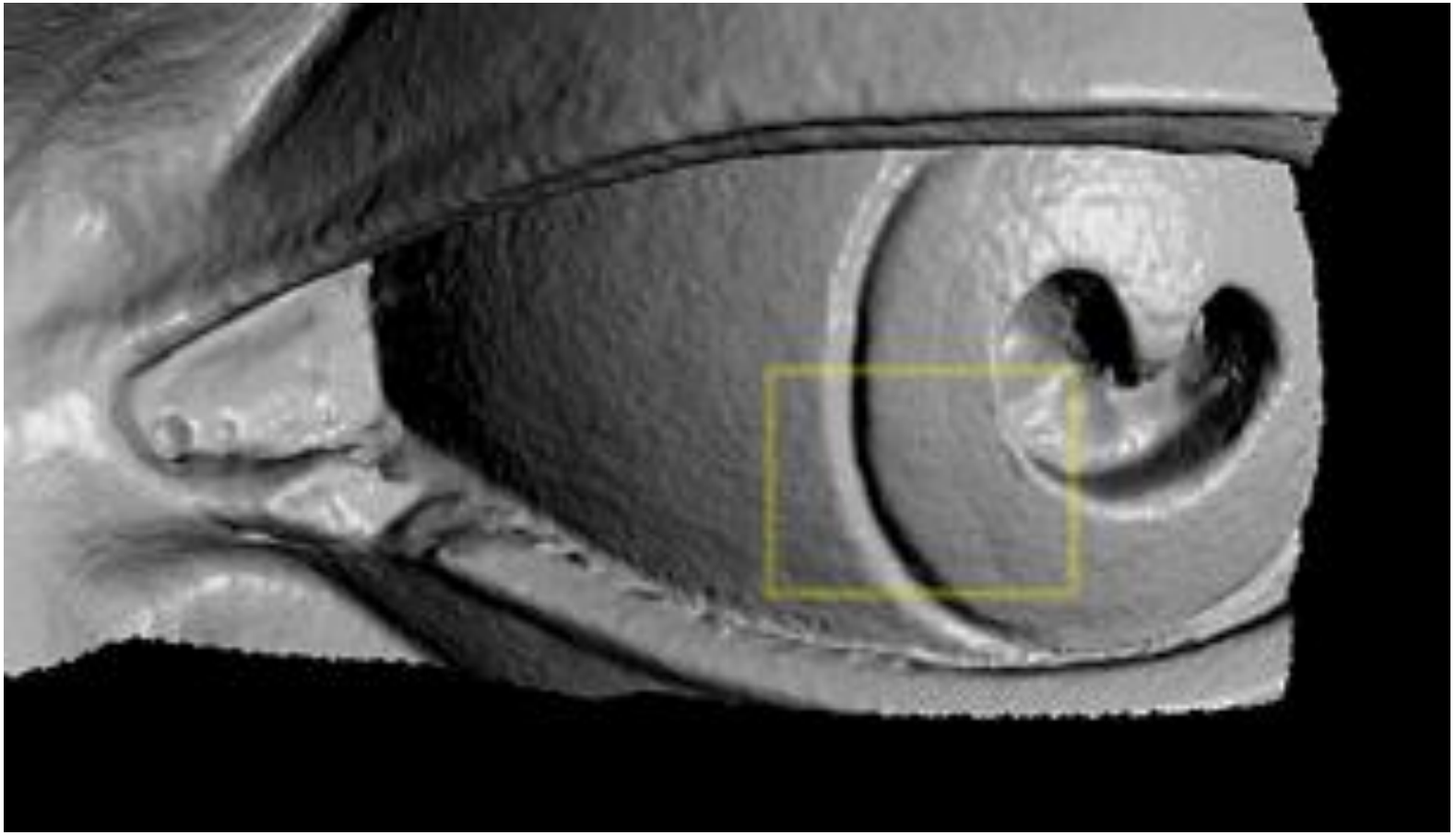


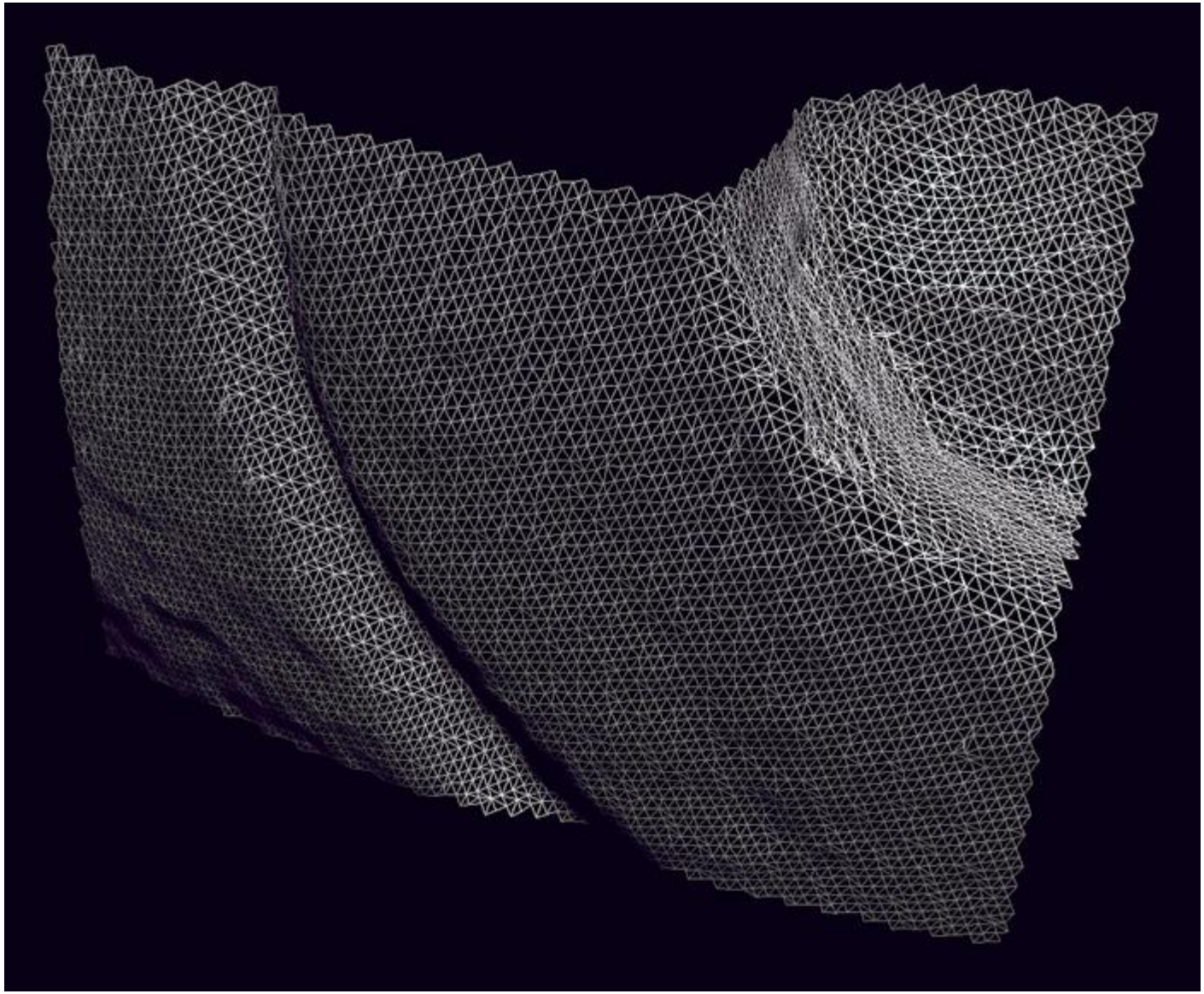
Scanning Michelangelo's *"The David"*

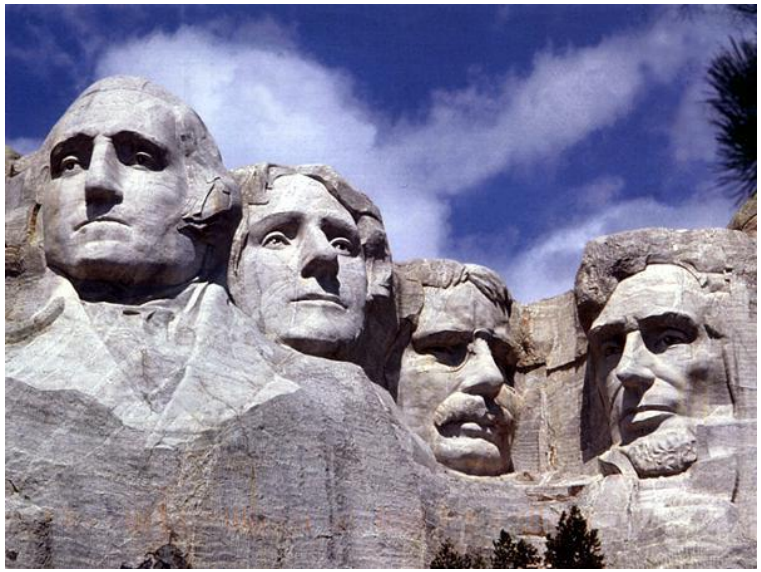
- The Digital Michelangelo Project
  - http://graphics.stanford.edu/projects/mich/
- UW Prof. Brian Curless, collaborator
- 2 BILLION polygons, accuracy to .29mm

The Digital Michelangelo Project, Levoy et al.

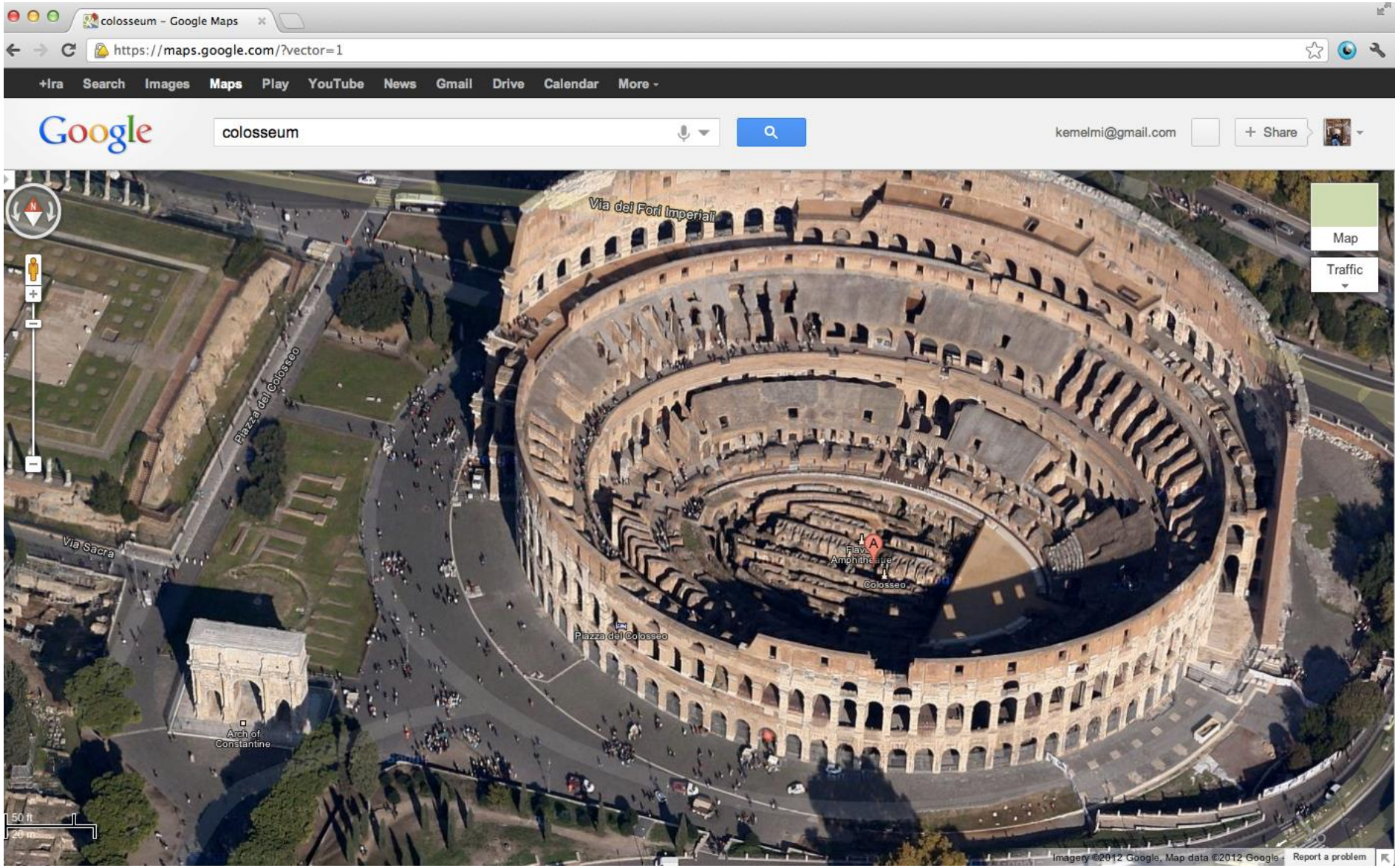








Google's 3D Maps
Structure estimation from tourist photos



Apple’s 3D maps

https://www.youtube.com/watch?v=InIVv-LsgZE

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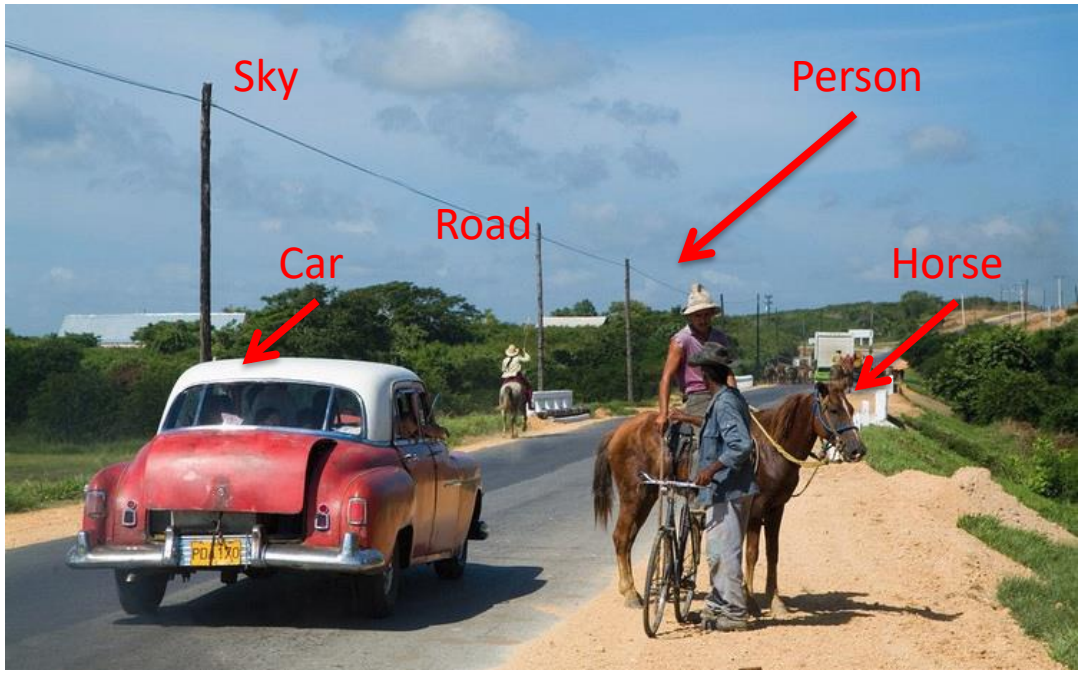
  - Pose estimation

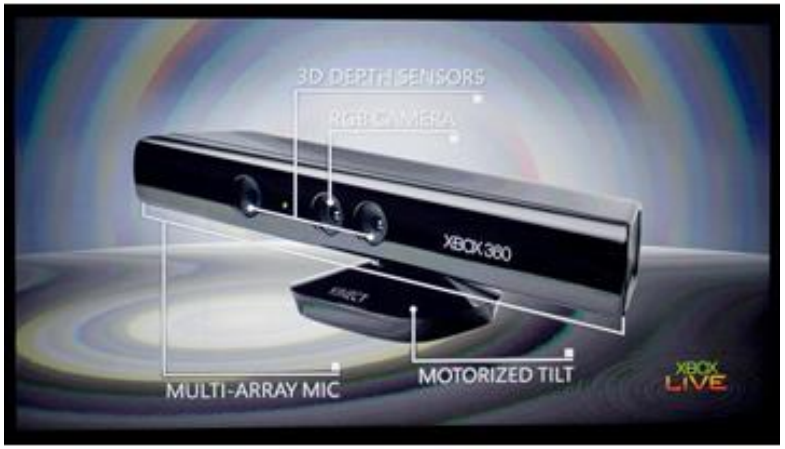


Face detection

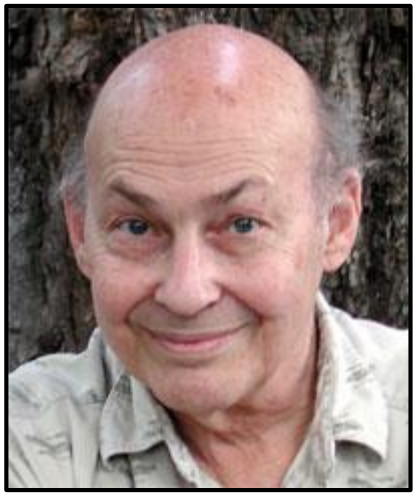
- Many new digital cameras now detect faces
  - Canon, Sony, Fuji, …

Source: S. Seitz

Vision-based interaction: Xbox Kinect



How hard is computer vision?



Marvin Minsky, MIT
Turing award,1969

“In 1966, Minsky hired a first-year undergraduate student and assigned him a problem to solve over the summer: connect a television camera to a computer and get the machine to describe what it sees.”

Crevier 1993, pg. 88

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

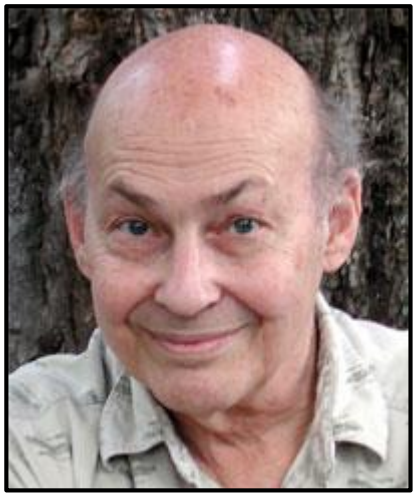
PROJECT MAC

Artificial Intelligence Group — July 7, 1966
Vision Memo. No. 100.

THE SUMMER VISION PROJECT

Seymour Papert

The summer vision project is an attempt to use our summer workers effectively in the construction of a significant part of a visual system. The particular task was chosen partly because it can be segmented into sub-problems which will allow individuals to work independently and yet participate in the construction of a system complex enough to be a real landmark in the development of "pattern recognition".



Marvin Minsky, MIT
Turing award,1969

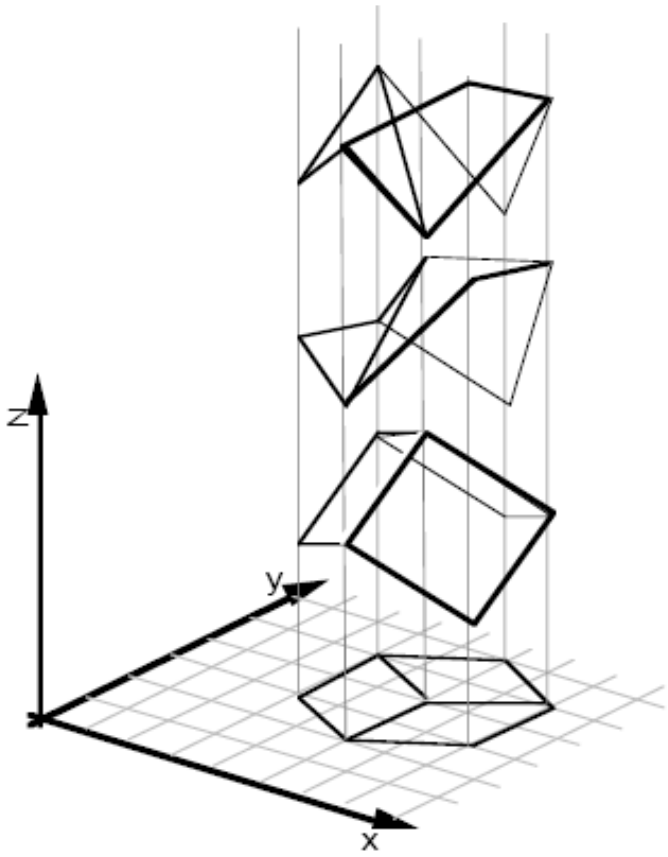
Gerald Sussman, MIT
(the undergraduate)

"You'll notice that Sussman never worked in vision again!" – Berthold Horn

Why vision is so hard?

Why is vision so hard?

- Ill-posed problem



[Sinha and Adelson 1993]

Challenges 1: view point variation

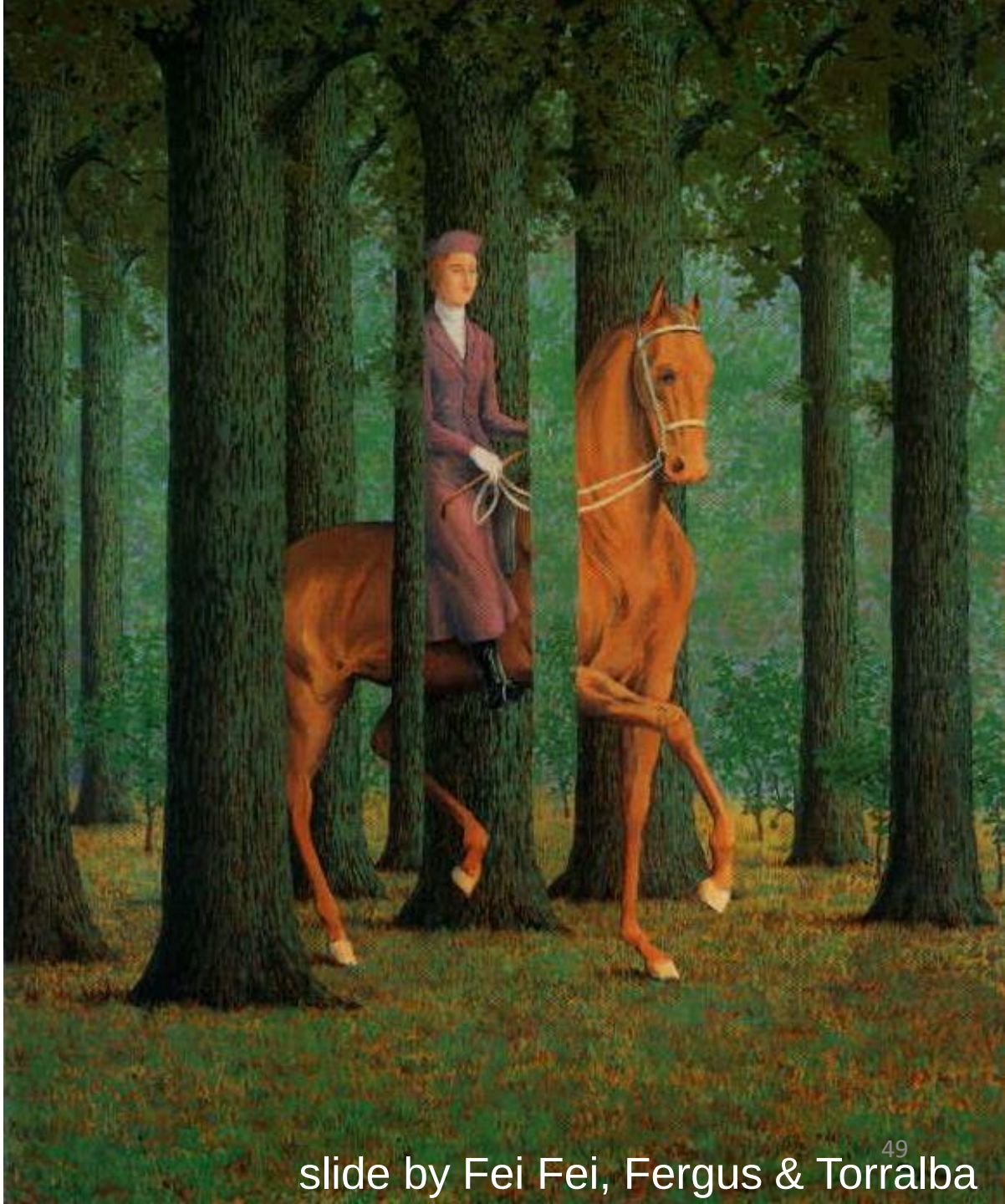
Michelangelo 1475-1564

slide by Fei Fei, Fergus & Torralba

Challenges 2: illumination

slide credit: S. Ullman

Challenges 3: occlusion



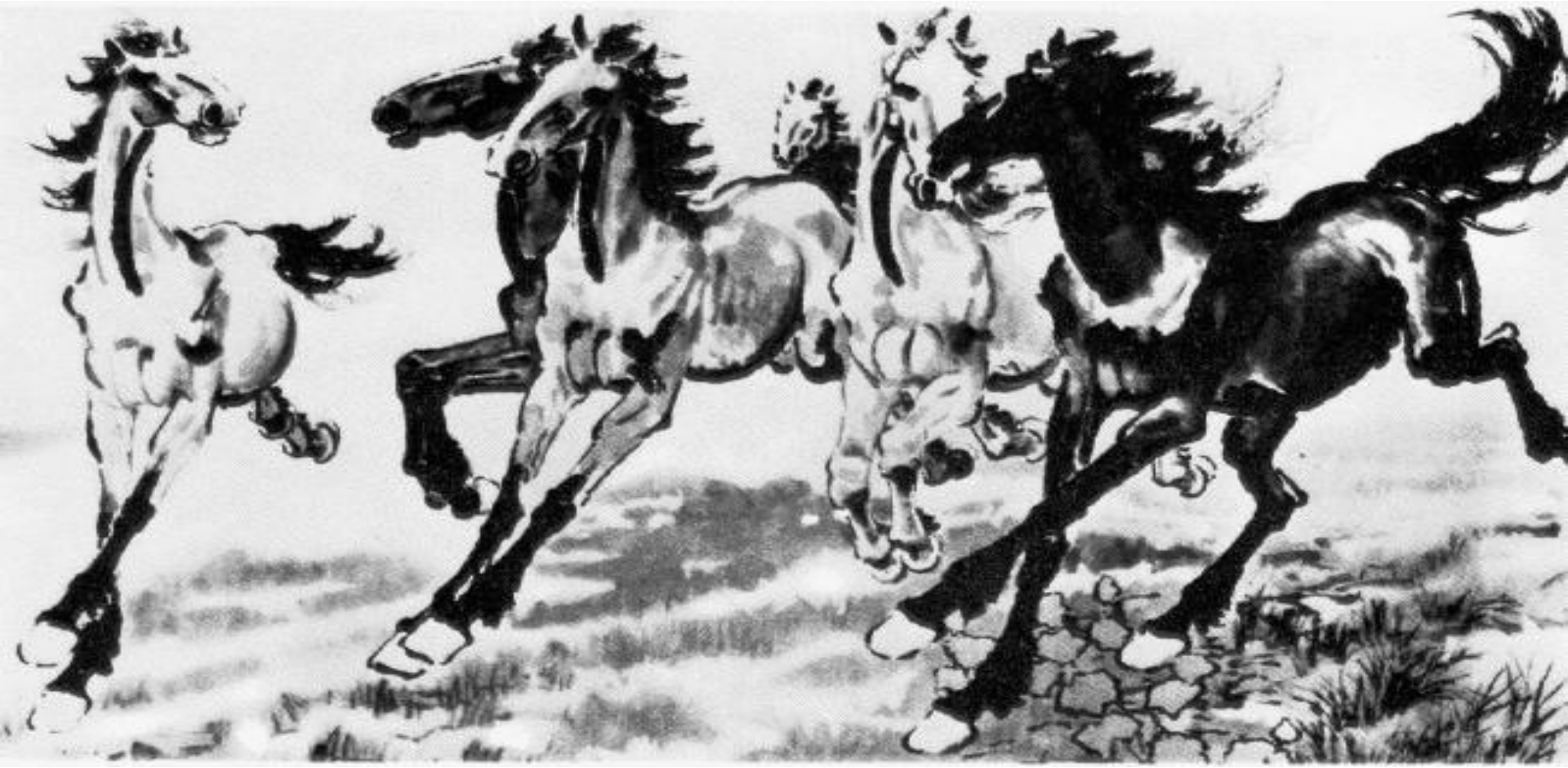
Magritte, 1957

slide by Fei Fei, Fergus & Torralba

Challenges 4: scale

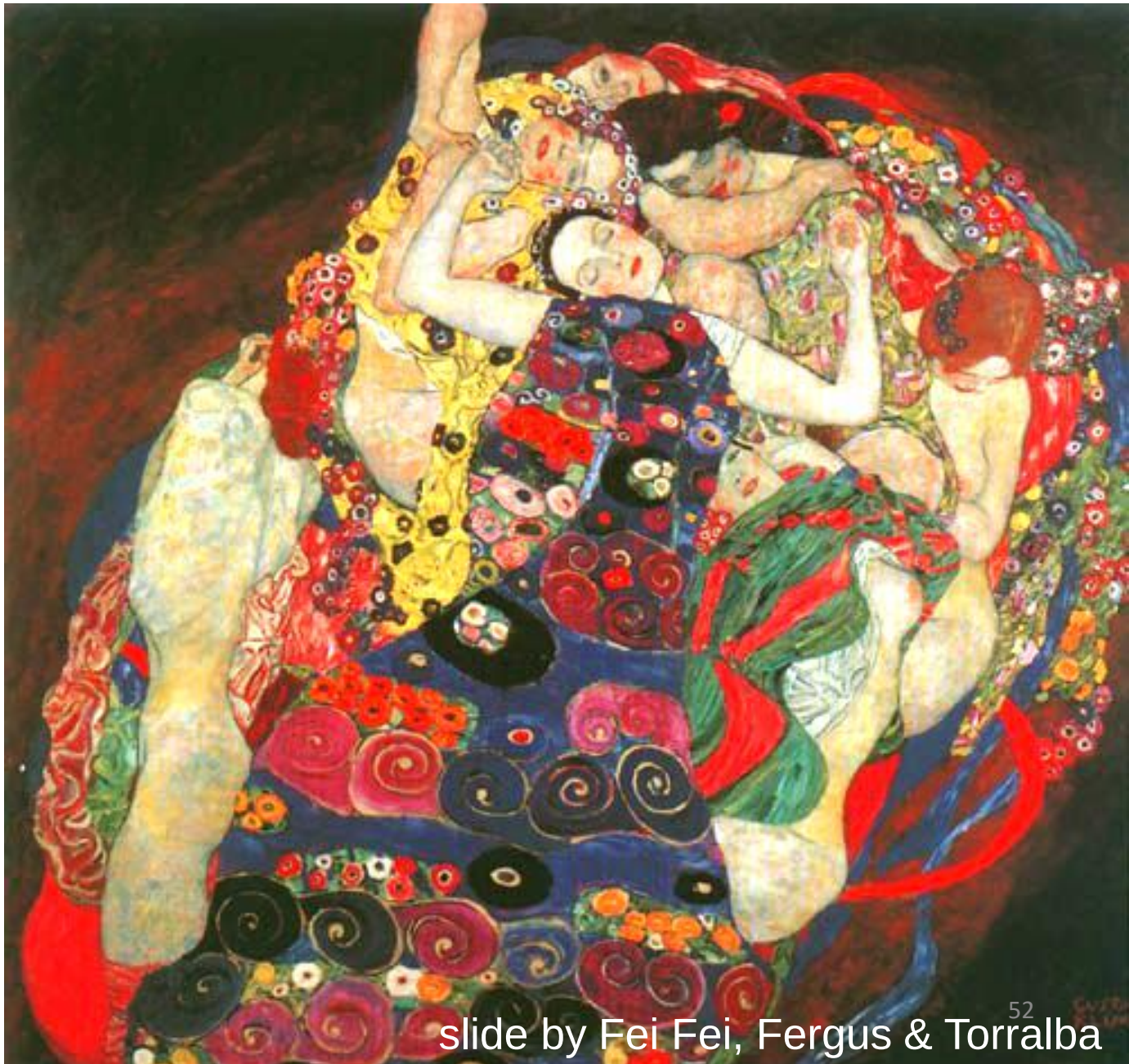
slide by Fei Fei, Fergus & Torralba

Challenges 5: deformation



Xu, Beihong 1943

Challenges 6: background clutter

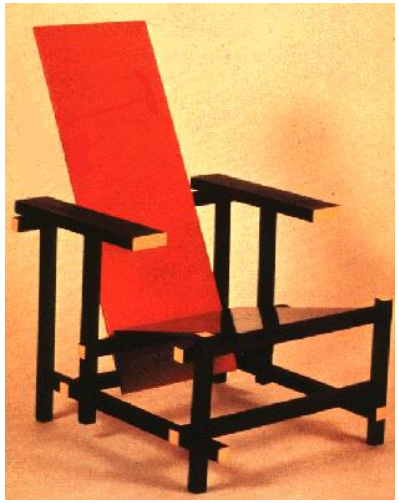


Klimt, 1913

slide by Fei Fei, Fergus & Torralba

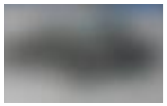
Challenges 7: object intra-class variation

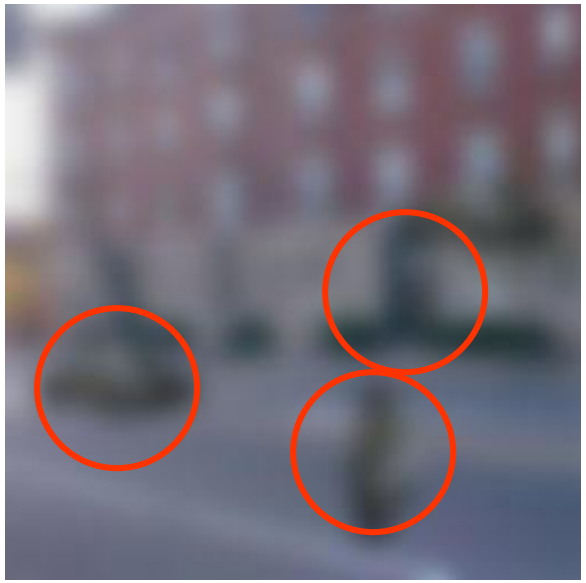


slide by Fei-Fei, Fergus & Torralba

Challenges 8: local ambiguity





slide by Fei-Fei, Fergus & Torralba

Challenges 9: the world behind the image

What Works Today?

- Reading license plates, zip codes, checks

Biometrics

Fingerprint scanners on many new laptops, other devices

Face recognition systems now beginning to appear more widely
http://www.sensiblevision.com/

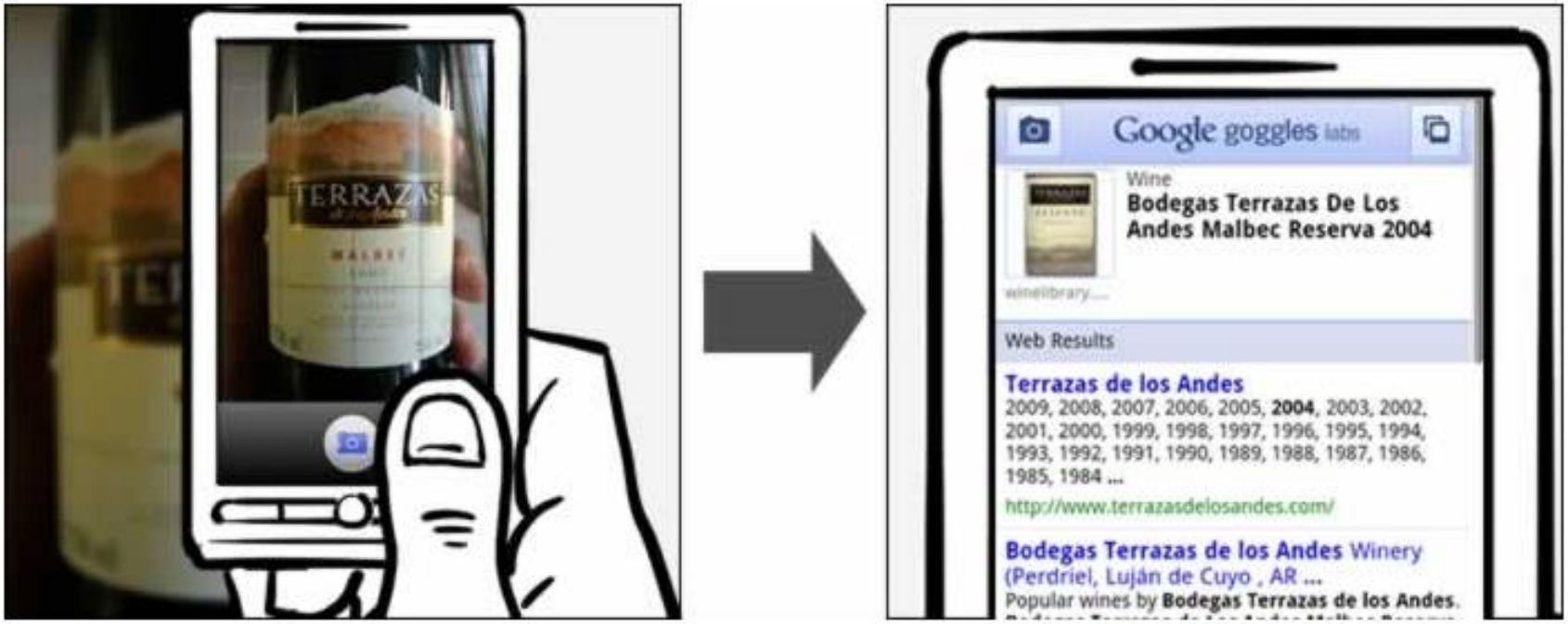
Source: S. Seitz

Mobile visual search: Google Goggles

Google Goggles in Action

Click the icons below to see the different ways Google Goggles can be used.

Google goggles labs



Face detection

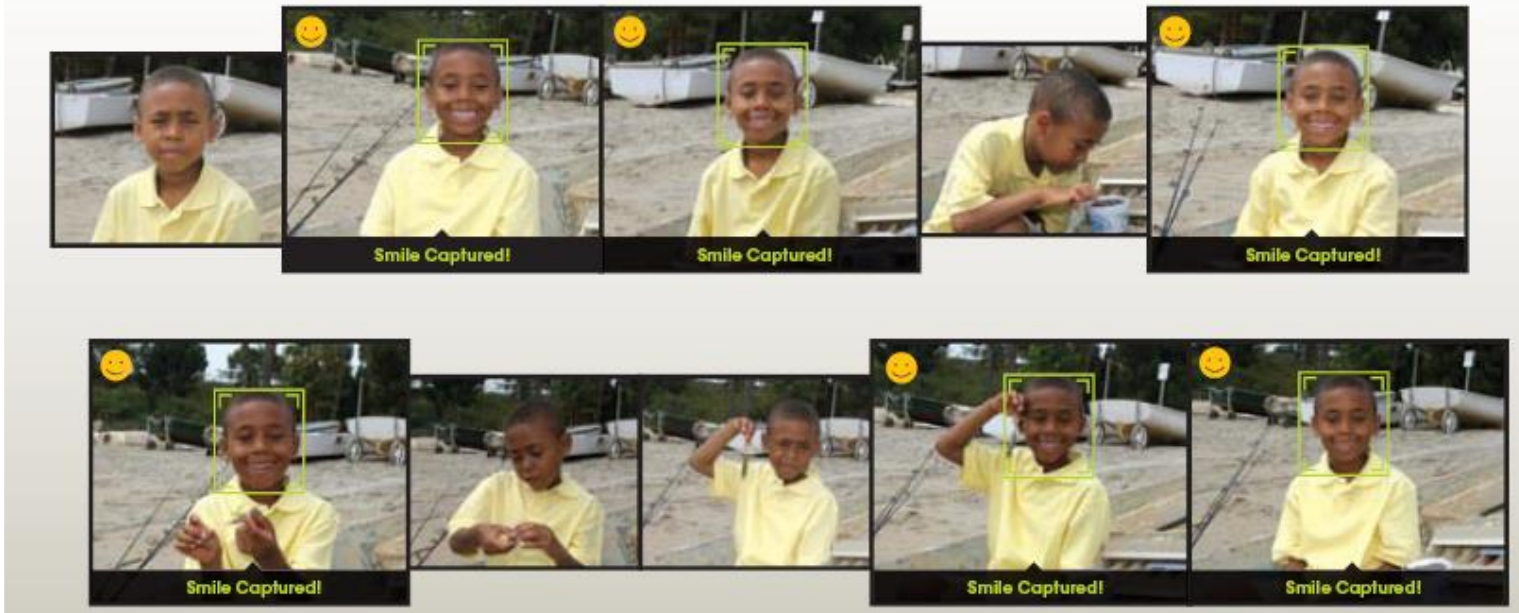
- Many new digital cameras now detect faces
  - Canon, Sony, Fuji, …

Source: S. Seitz

Smile detection

The Smile Shutter flow

Imagine a camera smart enough to catch every smile! In Smile Shutter Mode, your Cyber-shot® camera can automatically trip the shutter at just the right instant to catch the perfect expression.



[Sony Cyber-shot® T70 Digital Still Camera]

Source: S. Seitz

Face recognition: Apple iPhoto, Facebook, Google, etc

Object recognition (in supermarkets)

LaneHawk by EvolutionRobotics

“A smart camera is flush-mounted in the checkout lane, continuously watching for items. When an item is detected and recognized, the cashier verifies the quantity of items that were found under the basket, and continues to close the transaction. The item can remain under the basket, and with LaneHawk,you are assured to get paid for it… “

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News Front Page

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Health
Science &

Last Updated: Wednesday, 31 August 2005, 05:44 GMT 06:44 UK

E-mail this to a friend Printable version

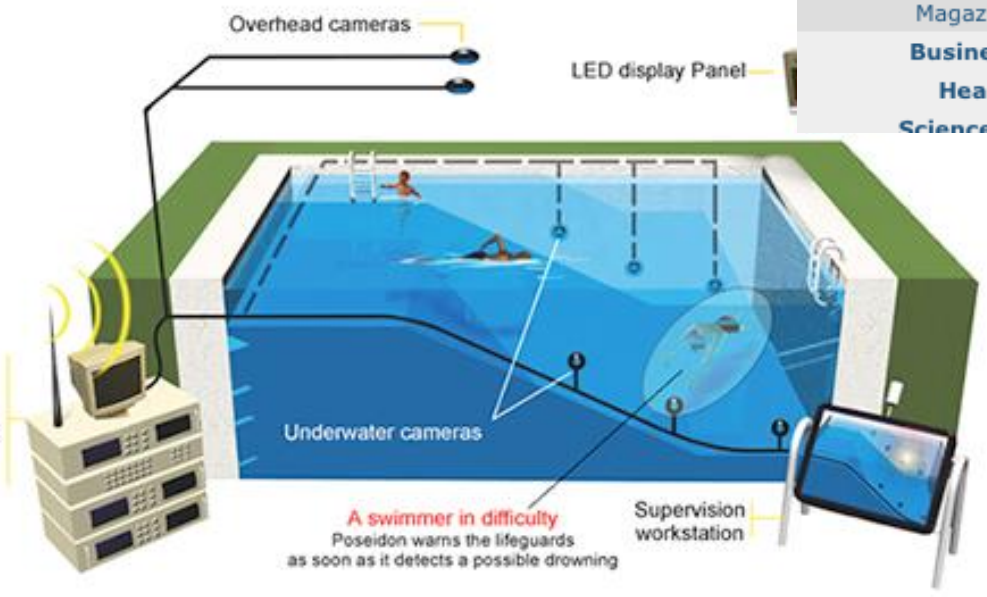
Computer alert for drowning girl

A 10-year-old girl has been saved from drowning by a computer system designed to raise the alarm when swimmers get into difficulties.

VIDEO Watch the rescue

The girl, from Rochdale, was at the deep end of the pool in Bangor, north Wales, when she sank to the bottom.

The £65,000 system, called Poseidon, detected her on the pool floor and sounded the alarm. A lifeguard pulled her out and she recovered in hospital.



Security

Local

Cameras help confirm Scott suicide ruling

Friday, December 04, 2009

TAGS: local, paul meincke

Comment Now Email Print Report a typo

Paul Meincke
More: Bio, News Team

December 4, 2009 (CHICAGO) (WLS) -- Chicago police have closed the case in the death of Chicago School Board President Michael Scott.

Police Supt. Jody Weis says investigators used police cameras in the city to trace Scott's last steps in the hours before his body was found in November.

Scott's death has been ruled a suicide. The medical examiner's office concluded --not long after Scott's body was found -- that he had committed suicide. Police did not dispute the finding but wanted to pursue all the investigative leads they could. They say they have done that and have now reached the same conclusion.

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- BP Gas Recall: BP finds, fixes source of bad gas
- Teachers union, board resume negotiating
- Back to School
- 5 injured in South Side shooting 49 min ago
- Pastor: Stacy Peterson said she lied for Drew

Automotive safety

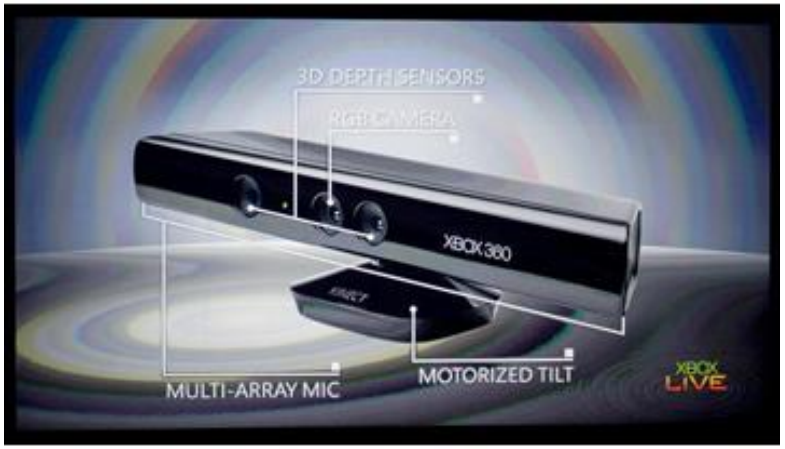
- Mobileye: Vision systems in high-end BMW, GM, Volvo models
  - Pedestrian collision warning
  - Forward collision warning
  - Lane departure warning
  - Headway monitoring and warning

Source: A. Shashua, S. Seitz

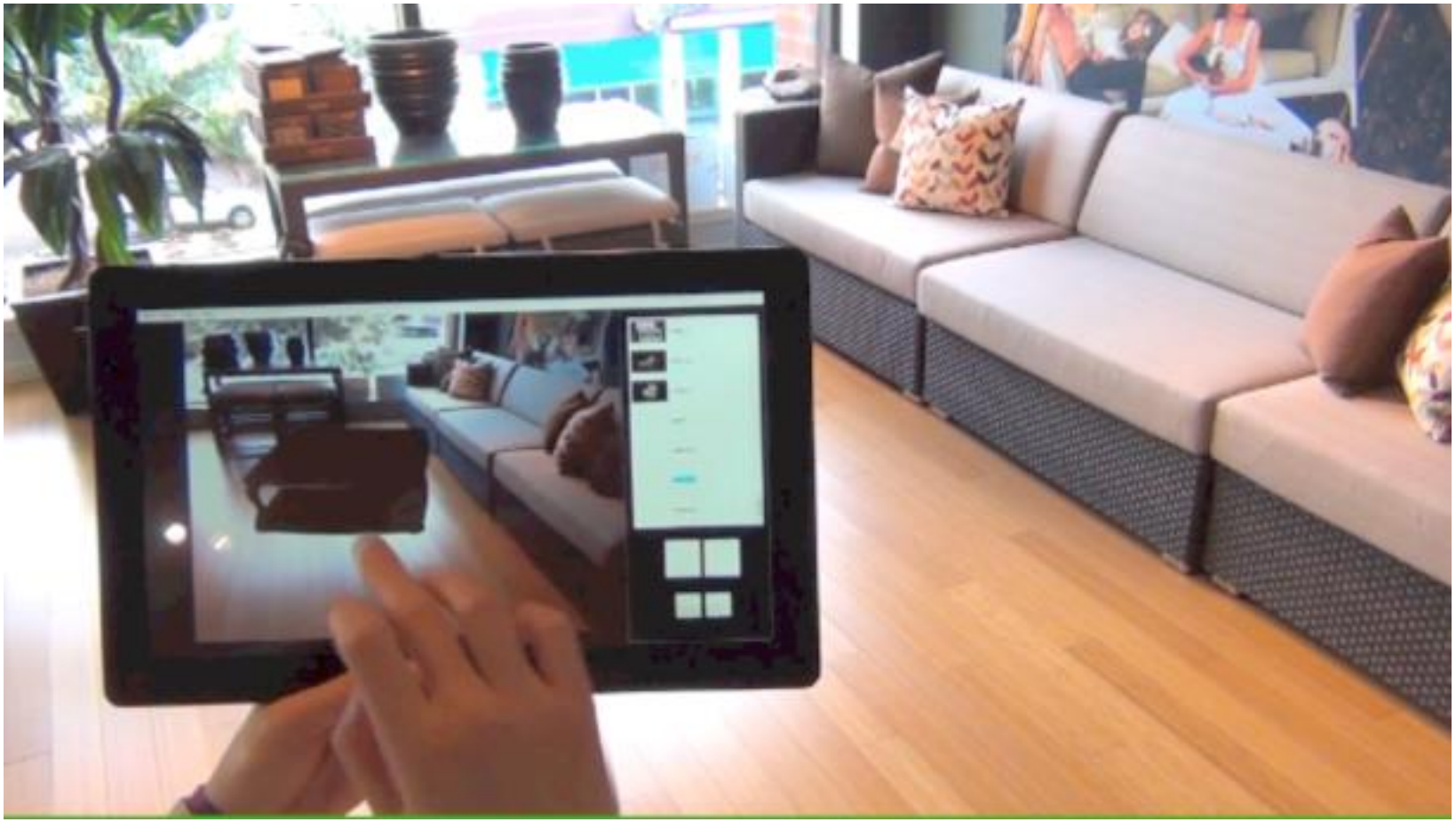
Google cars

Oct 9, 2010. "Google Cars Drive Themselves, in Traffic". *The New York Times*. John Markoff
June 24, 2011. "Nevada state law paves the way for driverless cars". *Financial Post*. Christine Dobby
Aug 9, 2011, "Human error blamed after Google's driverless car sparks five-vehicle crash". *The Star* (Toronto)

Vision-based interaction: Xbox Kinect



Augmented reality, consumer products



http://nconnex.com/wp/

Special effects: shape and motion capture

Source: S. Seitz

Vision for robotics, space exploration

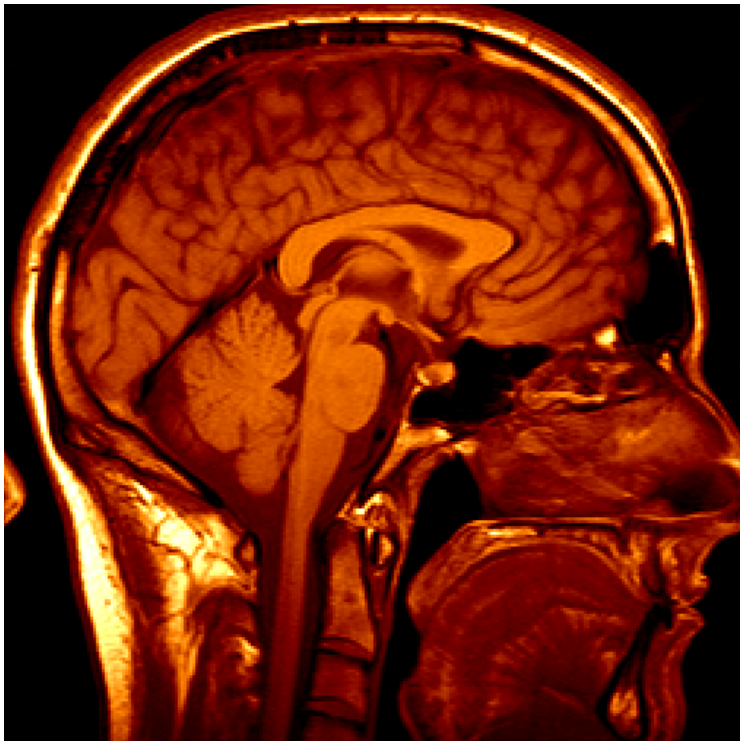
NASA'S Mars Exploration Rover Spirit captured this westward view from atop a low plateau where Spirit spent the closing months of 2007.

Vision systems (JPL) used for several tasks

- Panorama stitching
- 3D terrain modeling
- Obstacle detection, position tracking

Source: S. Seitz

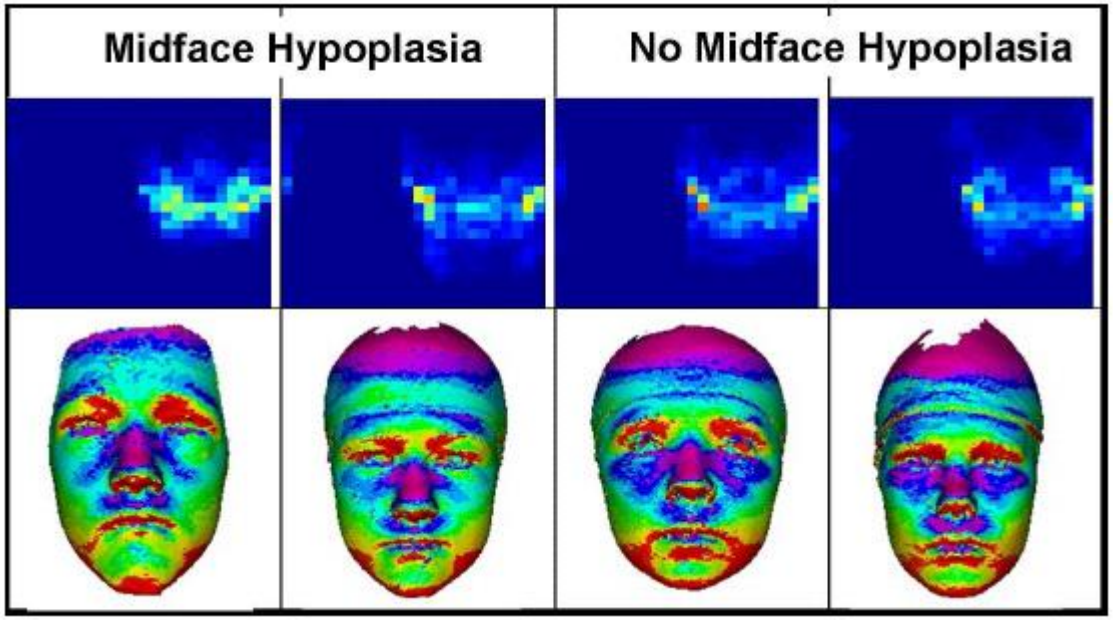
Medical imaging



3D imaging
MRI, CT

Image guided surgery
Grimson et al., MIT

Classification of 22q11.2DS



- Treat 2D azimuth-elevation angle histogram as feature vector

	8×8	16×16	24×24	32 × 32	Experts' median
Whole 2D hist	0.651	0.569	0.79	0.684	0.68

Computer vision research in healthcare

assisted living, patient monitoring
[Lan et al, PAMI 2012]

autism screening
http://www.gatech.edu/newsroom/release.html?nid=60509

Computer vision in the real-world

- Most examples are less than 7 years old
- Very active research area. Many new applications to come.
- A website of computer vision industries maintained by Prof. David Lowe (UBC)

  http://www.cs.ubc.ca/~lowe/vision.html
- Note: website is old but interesting
- Note: David Lowe retired and moved to Google 2015 to 2018

Assignments

- Assignment 1: Fun with Color
- Assignment 2: Image Resizing and Filtering
- Assignment 3: Panorama Stitching
- Assignment 4: Neural Networks
- Assignment 5: Pytorch
- Assignment 6: Optical Flow
- Course Project: Teams working on Machine Learning Projects

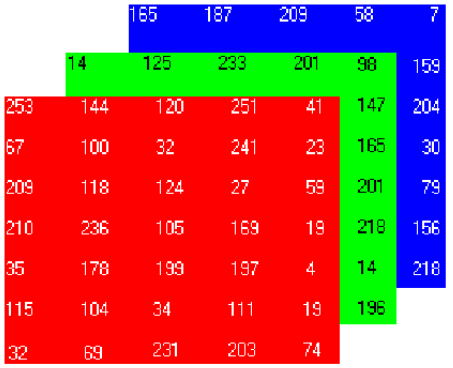
Assignment 1

- It’s about color, which we will cover Wednesday.
- It’s meant to be very easy, but you want to start it early.

Assignment 1 Parts

- 1. data structure for an image

```
typedef struct{
        int h, w, c;
        float *data;
} image;
```



- So an image is a 3D array with height, width and channels (like for colors).

- data is floating point numbers between 0 and 1

Assignment 1: Parts
Read them

- TODO #1: get_pixel and set_pixel
- TODO #2: copy_image
- TODO #3: rgb_to_grayscale
- TODO #4: shift_image (shifts values)
- TODO #5: clamp_image (get values between 0 and 1)
- TODO #6: rgb_to_hsv
- TODO #7: hsv_to_rgb

Have Fun