# Computer Vision

CSE 455 Learning I

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## Learning

- Al/Vision systems are complex and may have many parameters.
- It is impractical and often impossible to encode all the knowledge a system needs.
- Different types of data may require very different parameters.
- Instead of trying to hard code all the knowledge, it makes sense to learn it.

# Learning from Observations

 Supervised Learning – learn a function from a set of training examples which are preclassified feature vectors.

feature vector	class
(shape,color)	
(square, red)	I
(square, blue)	I
(circle, red)	П
(circle blue)	Ш
(triangle, red)	1
(triangle, green)	1
(ellipse, blue)	Ш
(ellipse, red)	II

Given a previously unseen feature vector, what is the rule that tells us if it is in class I or class II?

```
(circle, green) ? (triangle, blue) ?
```



#### Real Observations



%Training set of Calenouria and Dorenouria

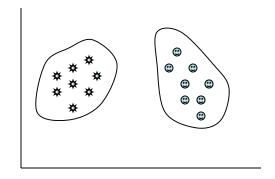
```
@DATA
```

```
0,1,1,0,0,0,0,0,1,1,2,3,0,1,2,0,0,0,0,0,0,0,0,1,0,0,1,
0,2,0,0,0,0,1,1,1,0,1,8,0,7,0,0,0,1,0,0,0,0,0,0,0,0,0,0,0,0,0,1,0,0,
3,3,4,0,2,1,0,1,1,1,0,0,0,0,1,0,0,1,1,cal 0,1,0,0,0,1,0,0,0,4,1,2
,2,0,1,0,0,0,0,1,0,0,3,0,2,0,0,1,1,0,0,1,0,0,1,0,1,6,1,8,2,0,0,
0,0,1,0,0,0,0,0,0,0,0,0,1,1,0,0,1,2,0,5,0,0,0,0,0,0,0,1,3,0,0,0,0
0,cal
0,0,1,0,1,0,0,1,0,1,0,0,1,0,3,0,1,0,0,2,0,0,0,0,1,3,0,0,0,0,0,0,1,0,
2,0,2,0,1,8,0,5,0,1,0,1,0,1,1,0,0,0,0,0,0,0,0,0,0,2,2,0,0,3,0,0,2,1,1,
5,0,0,0,2,1,3,2,0,1,0,0,cal 0,0,0,0,0,0,0,0,0,2,0,0,1,2,0,1,1,0,0,0,1
0,0,0,0,0,0,0,0,0,1,0,0,0,1,0,0,3,0,0,4,1,8,0,0,0,1,0,0,0,0,0,1,0,1
,0,1,0,0,0,0,0,0,4,2,0,2,1,1,2,1,1,0,0,0,0,2,0,0,2,2,cal
```

. . .

# Learning from Observations

 Unsupervised Learning – No classes are given. The idea is to find patterns in the data. This generally involves clustering.



 Reinforcement Learning – learn from feedback after a decision is made.

# **Topics to Cover**

- Inductive Learning
  - decision trees
  - ensembles
  - neural nets
  - kernel machines
- Ensembles
- The Fergus Algorithm with Kadir's interest operator

#### **Decision Trees**

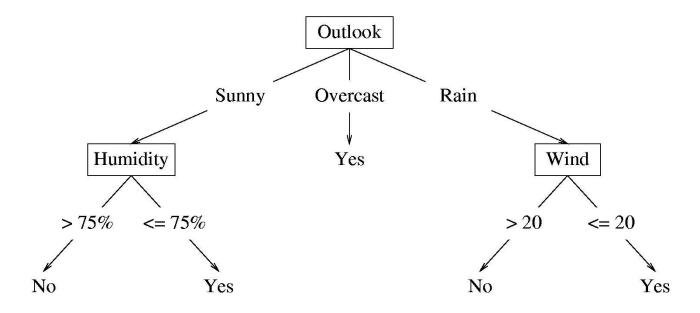
Theory is well-understood.

Often used in pattern recognition problems.

 Has the nice property that you can easily understand the decision rule it has learned.

#### Decision Tree Hypothesis Space

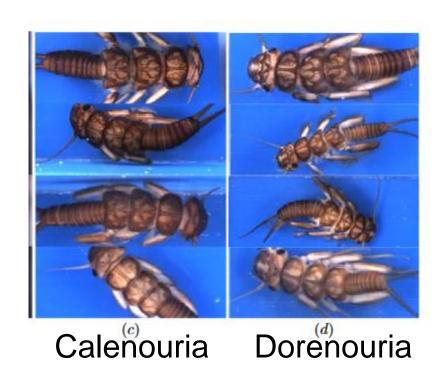
If the features are continuous, internal nodes may test the value of a feature against a threshold.



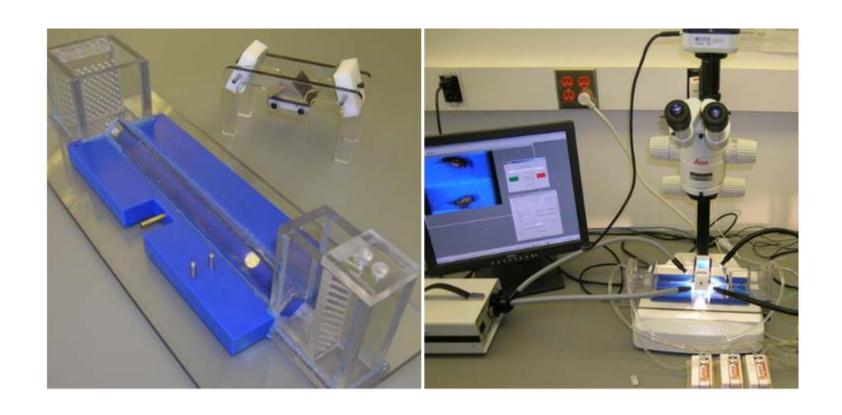
Classic ML example: decision tree for "Shall I play tennis today?"

from Tom Mitchell's ML book

# The Stonefly Problem



# Imaging Setup at OSU



**Transportation Apparatus** 

**Imaging Setup** 

# Original Image Analysis

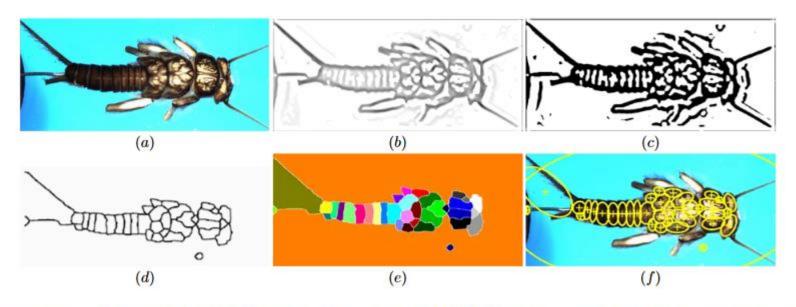


Fig. 1 Regions defined by principal curvature. (a) The original, (b) principal curvature, and (c) cleaned binary images. The resulting (d) boundaries and (e) regions that result by applying the watershed transform to (c). (f) The final detected regions created by fitting an ellipse to each region.

Feature vector: histogram of SIFT descriptors in a bag of words type of approach.

# A Real Decision Tree (WEKA)

```
Dorenouria
part23 < 0.5
  part29 < 3.5
     part34 < 0.5
       part8 < 2.5
          part2 < 0.5
            part63 < 3.5
               part20 < 1.5 : dor (53/12) [25/8]
                                                           Calenouria
               part20 >= 1.5
                  part37 < 2.5 : cal (6/0) [5/2] \leftarrow
                  part37 >= 2.5: dor (3/1) [2/0]
            part63 >= 3.5 : dor (14/0) [3/0]
          part2 >= 0.5 : cal (21/8) [10/4]
       part8 >= 2.5: dor (14/0) [14/0]
    part34 >= 0.5 : cal (38/12) [18/4]
  part29 >= 3.5 : dor (32/0) [10/2]
part23 >= 0.5
  part29 < 7.5 : cal (66/8) [35/12]
  part29 >= 7.5
    part24 < 5.5: dor (9/0) [4/0]
     part24 >= 5.5 : cal (4/0) [4/0]
```

#### **Evaluation**

Correctly Classified Instances	281	73.5602 %
Incorrectly Classified Instances	101	26.4398 %
Kappa statistic	0.4718	
Mean absolute error	0.3493	
Root mean squared error	0.4545	
Relative absolute error	69.973 %	
Root relative squared error	90.7886 %	
Total Number of Instances	382	

=== Detailed Accuracy By Class ===

	TP Rate	FP Rate	Precision	Recall	F-Measure	<b>ROC</b> Area	Class
	0.77	0.297	0.713	0.77	0.74	0.747	cal
	0.703	0.23	0.761	0.703	0.731	0.747	dor
Wg Avg.	0.736	0.263	0.737	0.736	0.735	0.747	

=== Confusion Matrix ===

a b <-- classified as 144 43 | a = cal 58 137 | b = dor Precision = TP/(TP+FP)

Recall = TP/(TP+FN)

F-Measure = 2 x Precision x Recall

Precision + Recall

# Properties of Decision Trees

- They divide the decision space into axis parallel rectangles and label each rectangle as one of the k classes.
- They can represent Boolean functions.
- They are variable size and deterministic.
- They can represent discrete or continuous parameters.
- They can be learned from training data.

## Learning Algorithm for Decision Trees

```
Growtree(S) /* Binary version */

if (y==0 for all (\mathbf{x},y) in S) return newleaf(0)

else if (y==1 for all (\mathbf{x},y) in S) return newleaf(1)

else

choose best attribute \mathbf{x}_j

\mathbf{S}_0 = (\mathbf{x},\mathbf{y}) with \mathbf{x}_j = 0

\mathbf{S}_1 = (\mathbf{x},\mathbf{y}) with \mathbf{x}_j = 1

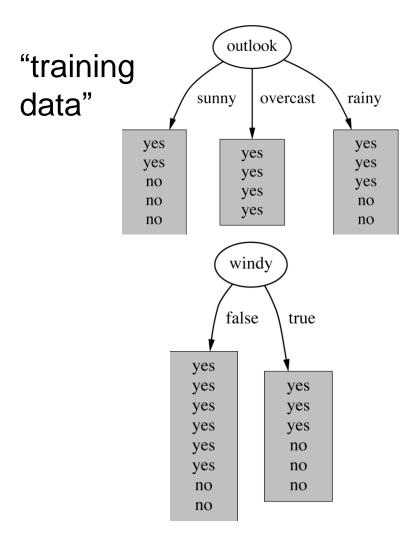
return new node(\mathbf{x}_j, Growtree(S<sub>0</sub>), Growtree(S<sub>1</sub>))

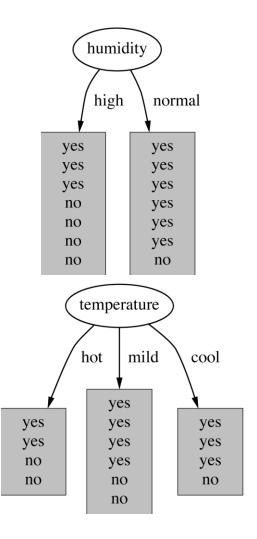
end
```

How do we choose the best attribute?

What should that attribute do for us?

# Shall I play tennis today? Which attribute should be selected?





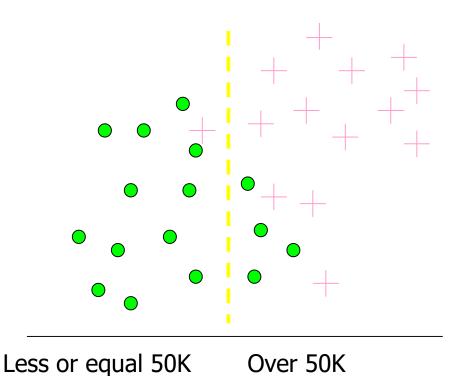
#### Criterion for attribute selection

- Which is the best attribute?
  - The one that will result in the smallest tree
  - Heuristic: choose the attribute that produces the "purest" nodes
- Need a good measure of purity!
  - Maximal when?
  - Minimal when?

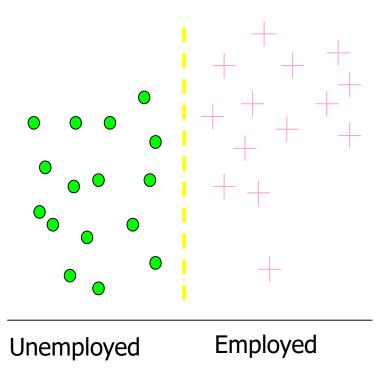
#### Information Gain

#### Which test is more informative?

**Split over whether Balance exceeds 50K** 



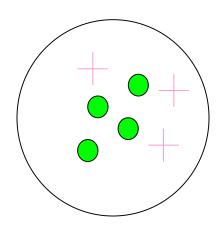
Split over whether applicant is employed

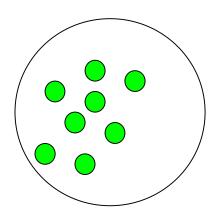


#### **Information Gain**

#### Impurity/Entropy (informal)

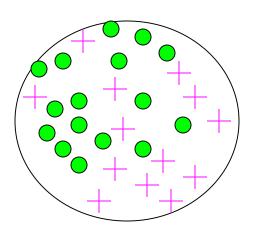
Measures the level of impurity in a group of examples



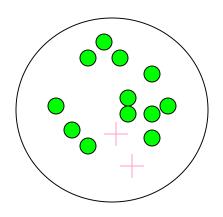


# **Impurity**

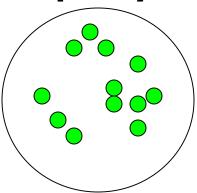
#### **Very impure group**



#### **Less impure**

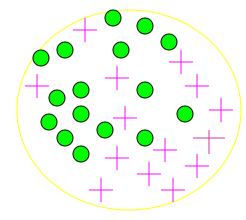


# Minimum impurity



### Entropy: a common way to measure impurity

• Entropy =  $\sum_{i} -p_{i} \log_{2} p_{i}$ 



p<sub>i</sub> is the probability of class i

Compute it as the proportion of class i in the set.

```
16/30 are green circles; 14/30 are pink crosses log_2(16/30) = -.9; log_2(14/30) = -1.1
Entropy = -(16/30)(-.9) - (14/30)(-1.1) = .99
```

 Entropy comes from information theory. The higher the entropy the more the information content.

What does that mean for learning from examples?

#### 2-Class Cases:

- What is the entropy of a group in which all examples belong to the same class?
  - entropy =  $-1 \log_2 1 = 0$

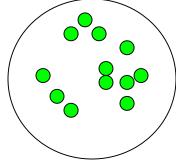
not a good training set for learning



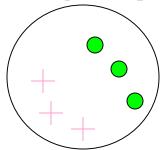
$$-$$
 entropy = -0.5  $\log_2 0.5 - 0.5 \log_2 0.5 = 1$ 

good training set for learning

# Minimum impurity



# Maximum impurity



#### Information Gain

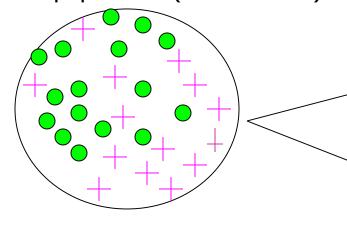
- We want to determine which attribute in a given set of training feature vectors is most useful for discriminating between the classes to be learned.
- Information gain tells us how important a given attribute of the feature vectors is.
- We will use it to decide the ordering of attributes in the nodes of a decision tree.

#### **Calculating Information Gain**

**Information Gain** = entropy(parent) – [average entropy(children)]

$$\frac{\text{parent}}{\text{entropy}} - \left(\frac{14}{30} \cdot \log_2 \frac{14}{30}\right) - \left(\frac{16}{30} \cdot \log_2 \frac{16}{30}\right) = 0.996$$
 
$$\frac{\text{child}}{\text{entropy}} - \left(\frac{13}{17} \cdot \log_2 \frac{13}{17}\right) - \left(\frac{4}{17} \cdot \log_2 \frac{4}{17}\right) = 0.787$$

Entire population (30 instances)



child entropy 
$$-\left(\frac{1}{13} \cdot \log_2 \frac{1}{13}\right) - \left(\frac{12}{13} \cdot \log_2 \frac{12}{13}\right) = 0.391$$

(Weighted) Average Entropy of Children =

$$\left(\frac{17}{30} \cdot 0.787\right) + \left(\frac{13}{30} \cdot 0.391\right) = 0.615$$

Information Gain = 
$$0.996 - 0.615 = 0.38$$
 for this split

13 instances

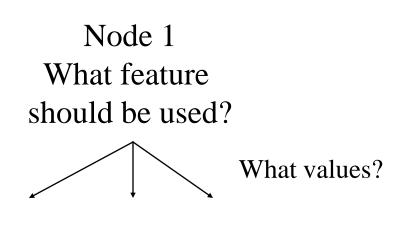
17 instances

# Entropy-Based Automatic Decision Tree Construction

Training Set S
$$x_{1}=(f_{11},f_{12},...f_{1m})$$

$$x_{2}=(f_{21},f_{22}, f_{2m})$$

$$x_{n}=(f_{n1},f_{22}, f_{2m})$$



Quinlan suggested information gain in his ID3 system and later the gain ratio, both based on entropy.

# Using Information Gain to Construct a Decision Tree (1)

Full Training Set S Attribute A vk Construct child nodes for each value of A. Set S' Each has an associated  $S' = \{s \in S \mid value(A) = v1\}$ subset of vectors in which A has a particular 3 value. repeat recursively till when?

Choose the attribute A with highest information gain for the full training set at the root of the tree.

# Simple Example

Training Set: 3 features and 2 classes

X	Y	Z	C
1	1	1	I
$\begin{vmatrix} 1 \\ 0 \end{vmatrix}$	1	0	I
0	0	1	II
1	0	0	II

How would you distinguish class I from class II?

X	Y	Z	С
1	1	1	I
1	1	0	I
0	0	1	II II
1	0	0	II

Eparent= 1
Split on attribute X

If X is the best attribute,
this node would be further split.  $E_{child1} = -(1/3)\log_2(1/3) - (2/3)\log_2(2/3)$  = .5284 + .39 = .9184  $E_{child2} = 0$ 

GAIN = 1 - (3/4)(.9184) - (1/4)(0) = .3112

Eparent= 1
Split on attribute Y

$$Y=1$$

$$I I$$

$$IIII$$

$$Y=0$$

$$III$$

$$E_{child1}=0$$

$$E_{child2}=0$$

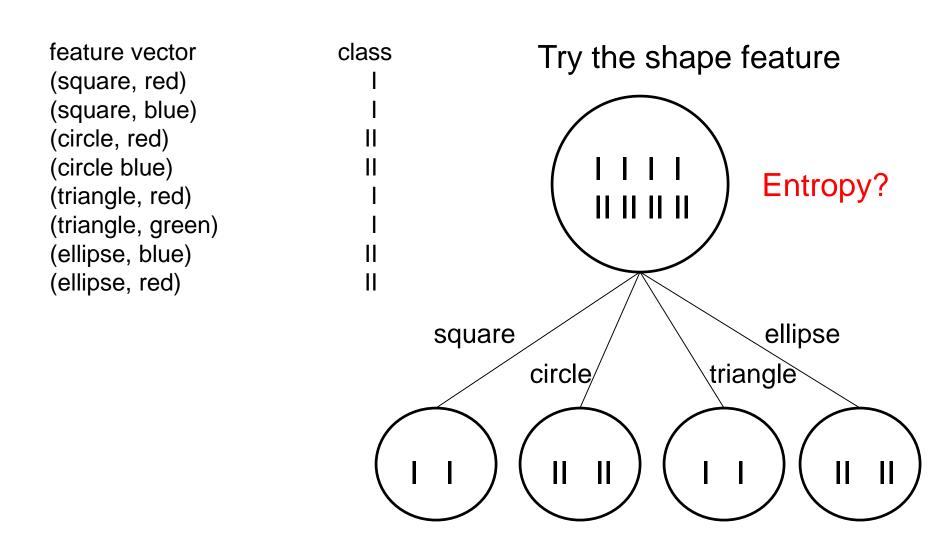
$$GAIN = 1 - (1/2) 0 - (1/2)0 = 1; BEST ONE$$

Eparent= 1
Split on attribute Z

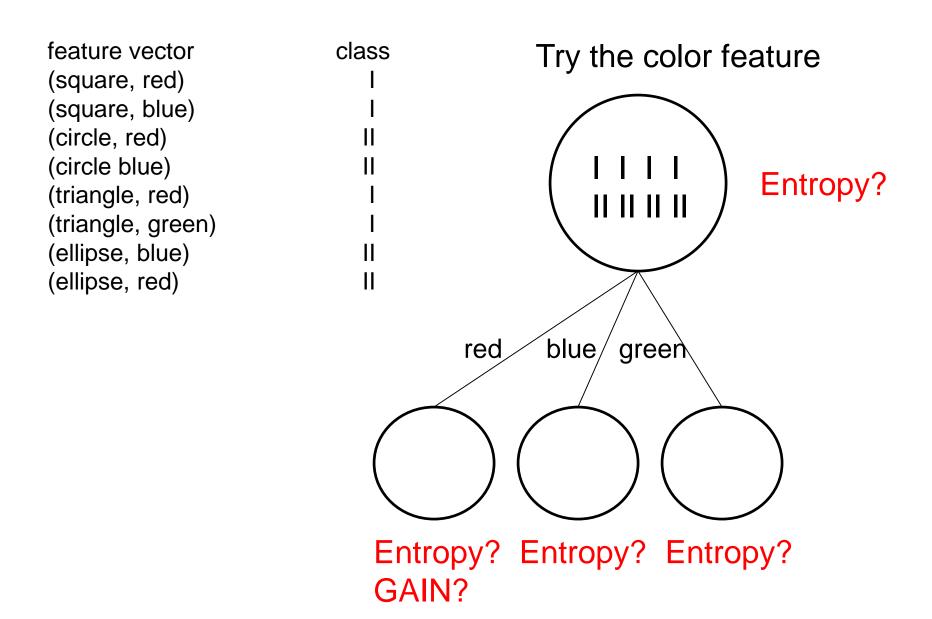
$$Z=1 \qquad I \qquad E_{child1}=1$$

$$I \qquad I \qquad I \qquad E_{child2}=1$$

GAIN = 1 - (1/2)(1) - (1/2)(1) = 0 ie. NO GAIN; WORST



Entropy? Entropy? Entropy? GAIN?



# Many-Valued Features

 Your features might have a large number of discrete values.

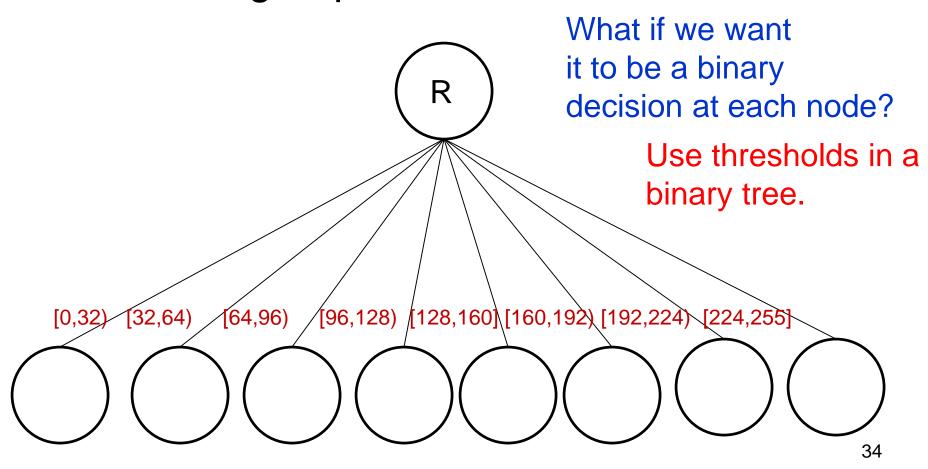
Example: pixels in an image have (R,G,B) which are each integers between 0 and 255.

Your features might have continuous values.

Example: from pixel values, we compute gradient magnitude, a continuous feature

#### One Solution to Both

We often group the values into bins



# Training and Testing

- Divide data into a training set and a separate testing set.
- Construct the decision tree using the training set only.
- Test the decision tree on the training set to see how it's doing.
- Test the decision tree on the testing set to report its real performance.

# Measuring Performance

- Given a test set of labeled feature vectors
   e.g. (square,red) I
- Run each feature vector through the decision tree
- Suppose the decision tree says it belongs to class X and the real label is Y
- If (X=Y) that's a correct classification
- If (X<>Y) that's an error

# Measuring Performance

 In a 2-class problem, where the classes are positive or negative (ie. for cancer)

```
– # true positivesTP
```

- Accuracy = #correct / #total = (TP +TN) / (TP + TN + FP + FN)
- Precision = TP / (TP + FP)

How many of the ones you said were cancer really were cancer?

Recall = TP / (TP + FN)

How many of the ones who had cancer did you call cancer?

## More Measures

F-Measure = 2\*(Precision \* Recall) / (Precision + Recall)

Gives us a single number to represent both precision and recall.

#### In medicine:

Sensitivity = TP / (TP + FN) = Recall

The sensitivity of a test is the proportion of people who have a disease who test positive for it.

Specificity = TN / (TN + FP)

The specificity of a test is the number of people who DON'T have a disease who test negative for it.

## Measuring Performance

 For multi-class problems, we often look at the confusion matrix.

#### assigned class

true class

	Α	В	С	D	Е	F	G
Α							
В	,						
С							
D							
E							
F							
G							

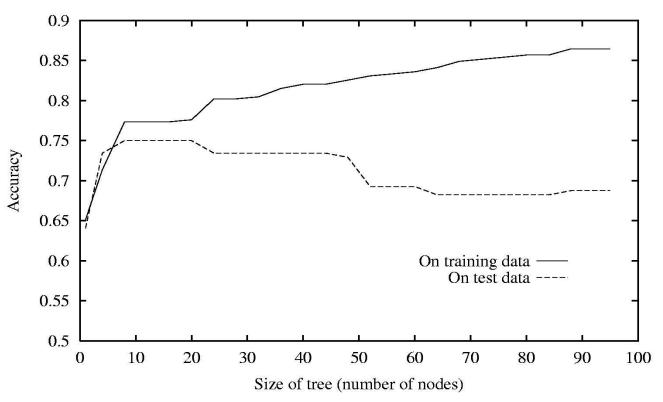
C(i,j) = number of times (or percentage) class i is given label j.

## Overfitting

- Suppose the classifier h has error (1accuracy) of error<sub>train</sub>(h)
- And there is an alternate classifier (hypothesis) h' that has error<sub>train</sub>(h')
- What if error<sub>train</sub>(h) < error<sub>train</sub>(h')
- But error<sub>D</sub>(h) > error<sub>D</sub>(h') for full test set D
- Then we say h overfits the training data

#### What happens as the decision tree gets bigger and bigger?

#### Overfitting in Decision Tree Learning

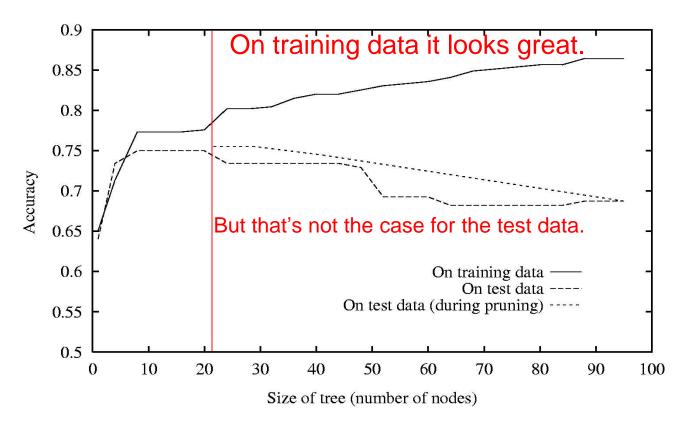


Error on training data goes down, on testing data goes up

## Reduced Error Pruning

- Split data into training and validation sets
- Do until further pruning is harmful
  - 1. Evaluate impact on validation set of pruning each possible node (and its subtree)
  - 2. Greedily remove the one that most improves validation set accuracy
- Then you need an additional independent testing set.

#### Effect of Reduced-Error Pruning



The tree is pruned back to the red line where it gives more accurate results on the test data.

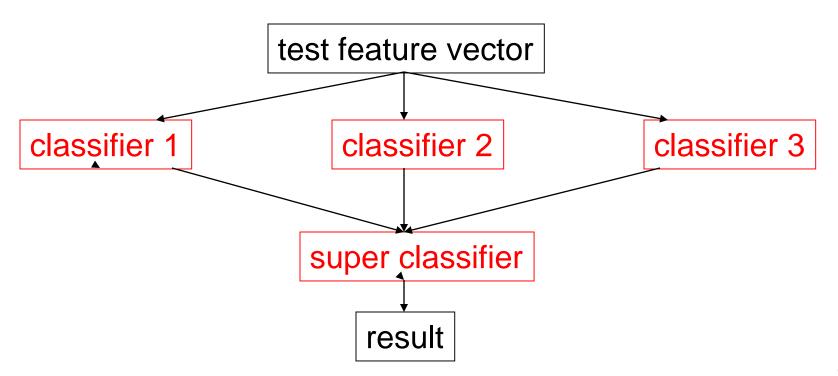
- The WEKA example with Calenouria and Dorenouria
   I showed you used the REPTree classifier with 21 nodes.
- The classic decision tree for the same data had 65 nodes.
- Performance was similar for our test set.
- Performance increased using a random forest of 10 trees, each constructed with 7 random features.

## **Decision Trees: Summary**

- Representation=decision trees
- Bias=preference for small decision trees
- Search algorithm=none
- Heuristic function=information gain or information content or others
- Overfitting and pruning
- Advantage is simplicity and easy conversion to rules.

#### **Ensembles**

 An ensemble is a set of classifiers whose combined results give the final decision.



## **MODEL\* ENSEMBLES**

- Basic Idea
  - Instead of learning one model
  - Learn several and combine them
- Often this improves accuracy by a lot
- Many Methods
  - Bagging
  - Boosting
  - Stacking

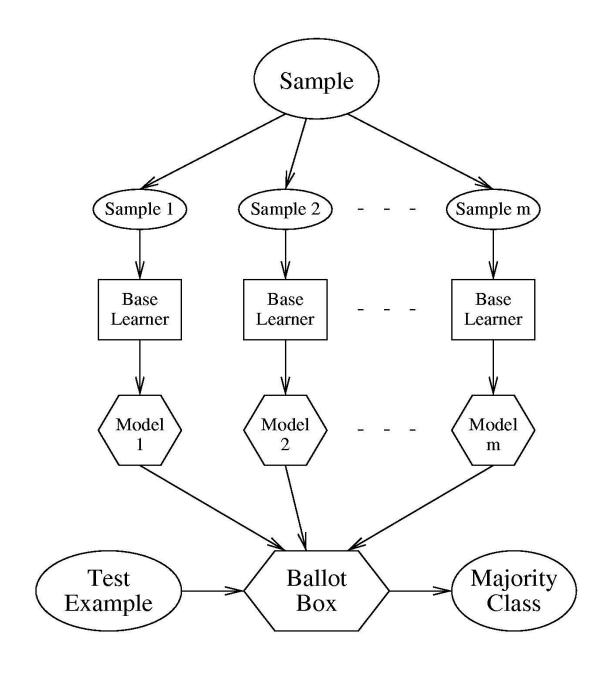
<sup>\*</sup>A model is the learned decision rule. It can be as simple as a hyperplane in n-space (ie. a line in 2D or plane in 3D) or in the form of a decision tree or other modern classifier.

# Bagging

 Generate bootstrap replicates of the training set by sampling with replacement

Learn one model on each replicate

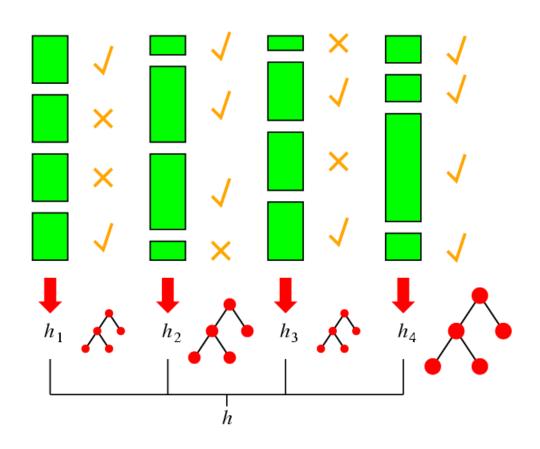
Combine by uniform voting



## Boosting

- Maintain a vector of weights for samples
- Initialize with uniform weights
- Loop
  - Apply learner to weighted samples
  - Increase weights of misclassified ones
- Combine models by weighted voting

## Idea of Boosting



## **Boosting In More Detail**

(Pedro Domingos' Algorithm)

- 1. Set all E weights to 1, and learn H1.
- 2. Repeat m times: increase the weights of misclassified Es, and learn H2,...Hm.
- 3. H1..Hm have "weighted majority" vote when classifying each test Weight(H)=accuracy of H on the training data

## **ADABoost**

ADABoost boosts the accuracy of the original learning algorithm.

 If the original learning algorithm does slightly better than 50% accuracy, ADABoost with a large enough number of classifiers is guaranteed to classify the training data perfectly.

# ADABoost Weight Updating (from Fig 18.34 text)

```
/* First find the sum of the weights of the misclassified samples
*/
    for j = 1 to N do /* go through training samples */
        if h[m](x<sub>j</sub>) <> y<sub>j</sub> then error <- error + w<sub>j</sub>

/* Now use the ratio of error to 1-error to change the
        weights of the correctly classified samples */
    for j = 1 to N do
        if h[m](x<sub>j</sub>) = y<sub>j</sub> then w[j] <- w[j] * error/(1-error)</pre>
```

## Example

- Start with 4 samples of equal weight .25.
- Suppose 1 is misclassified. So error = .25.
- The ratio comes out .25/.75 = .33
- The correctly classified samples get weight of .25\*.33 = .0825

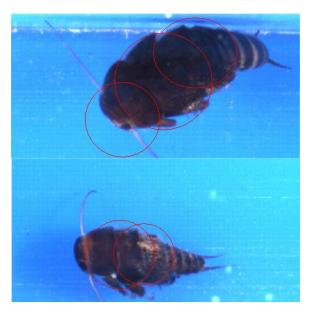
```
.2500
.0825 What's wrong? What should we do?
.0825
.0825 We want them to add up to 1, not .4975.
```

Answer: To normalize, divide each one by their sum (.4975 or .5).

## Sample Application: Insect Recognition







Using circular regions of interest selected by an interest operator, train a classifier to recognize the different classes of insects.

ADTree classifier only (alternating decision tree)

Correctly Classified Instances 268 70.1571 %

Incorrectly Classified Instances 114 29.8429 %

• Mean absolute error 0.3855

Relative absolute error 77.2229 %

Classified as ->	Hesperperla	Doroneuria
Real Hesperperlas	167	28
Real Doroneuria	51	136

#### AdaboostM1 with ADTree classifier

Correctly Classified Instances 303 79.3194 %

Incorrectly Classified Instances 79 20.6806 %

Mean absolute error 0.2277

Relative absolute error 45.6144 %

Classified as ->	Hesperperla	Doroneuria
Real	167	28
Hesperperlas		
Real	51	136
Doroneuria		

RepTree classifier only (reduced error pruning)

Correctly Classified Instances
 294
 75.3846 %

Incorrectly Classified Instances 96 24.6154 %

Mean absolute error 0.3012

Relative absolute error 60.606 %

Classified as ->	Hesperperla	Doroneuria
Real Hesperperlas	169	41
Real Doroneuria	55	125

#### AdaboostM1 with RepTree classifier

Correctly Classified Instances 324 83.0769 %

Incorrectly Classified Instances 66 16.9231 %

Mean absolute error 0.1978

Relative absolute error 39.7848 %

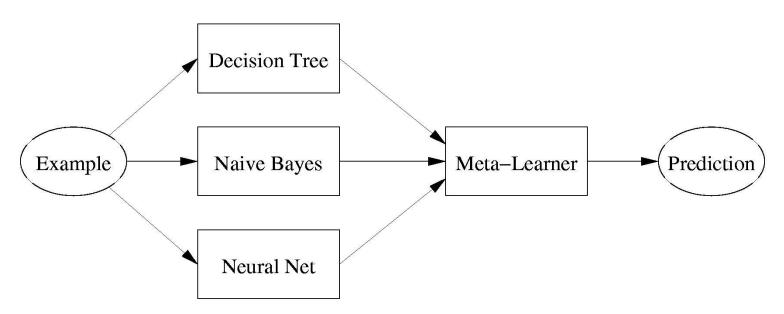
Classified as ->	Hesperperla	Doroneuria
Real	180	30
Hesperperlas		
Real	36	144
Doroneuria		

## References

- AdaboostM1: Yoav Freund and Robert E. Schapire (1996).
   "Experiments with a new boosting algorithm". Proc International Conference on Machine Learning, pages 148-156, Morgan Kaufmann, San Francisco.
- <u>ADTree</u>: Freund, Y., Mason, L.: "The alternating decision tree learning algorithm". Proceeding of the Sixteenth International Conference on Machine Learning, Bled, Slovenia, (1999) 124-133.

#### Stacking

- Apply multiple base learners (e.g.: decision trees, naive Bayes, neural nets)
- Meta-learner: Inputs = Base learner predictions
- Training by leave-one-out cross-validation: Meta-L. inputs = Predictions on left-out examples



## Random Forests

- Tree bagging creates decision trees using the bagging technique. The whole set of such trees (each trained on a random sample) is called a decision forest. The final prediction takes the average (or majority vote).
- Random forests differ in that they use a modified tree learning algorithm that selects, at each candidate split, a random subset of the features.

## Back to Stone Flies

Random forest of 10 trees, each constructed while considering 7 random features. Out of bag error: 0.2487. Time taken to build model: 0.14 seconds

Correctly Classified Instances 292 76.4398 % (81.4 with AdaBoost) Incorrectly Classified Instances 90 23.5602 % Kappa statistic 0.5272 Mean absolute error 0.344Root mean squared error 0.4069 Relative absolute error 68.9062 % Root relative squared error 81.2679 % Total Number of Instances 382

	TP Rate	FP Rate	Precisi	ion Red	call F-Me	asure	<b>ROC</b> Area	Class
	0.69	0.164	0.801	0.69	0.741	0.848	cal	
	0.836	0.31	0.738	0.836	0.784	0.848	dor	
WAvg.	0.764	0.239	0.769	0.764	0.763	0.848		

a b <-- classified as 129 58 | a = cal 32 163 | b = dor

