Lecture 18

Linear classifiers and backpropagation

Ranjay Krishna, Jieyu Zhang



Administrative

A4 is out

- Due May 23th, Today

A5 is out

- Due May 30th

Exam

- Mon, Jun 3 10:30 12:20 PM
- Same room as lecture: G20

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Administrative

Recitation this friday

- Exam preparation
- Jieyu Zhang

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Today's agenda

- Perceptron
- Linear classifier
- Loss function
- Gradient descent and backpropagation
- Neural networks

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1950s Age of the Perceptron

1957 The Perceptron (Rosenblatt)

1969 Perceptrons (Minsky, Papert)

1980s Age of the Neural Network

1986 Back propagation (Hinton)

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1990s Age of the Graphical Model

2000s Age of the Support Vector Machine

2010s Age of the Deep Network

deep learning = known algorithms + computing power + big data

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Perceptron



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Aside: Inspiration from Biology



A cartoon drawing of a biological neuron (left) and its mathematical model (right).

Neural nets/perceptrons are loosely inspired by biology.

But they are NOT how the brain works, or even how neurons work.

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Perceptron: for image classification



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Let's revisit our simple recognition pipeline to explain where perceptrons fit in



Remember we can featurize images into a vector

Image

Vector

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Raw pixels Raw pixels + (x,y) PCA LDA BoW BoW + spatial pyramids

Recall: we can featurize images into a vector



		x
	:	x_{i}
	:	x_{i}
		••
		•••
Raw pixels		••
Raw pixels + (x.v)		•••
		••
DA		•••
BoW		•••
BoW + spatial pyramids		••
		•••

 x_n

Image

Vector

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Perceptrons are a simple transformation that converts feature vectors into recognition scores



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Perceptron: simplified view with one perceptron (produces 1 score for one category)



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Perceptron: simplified view with two perceptrons (produces 2 scores with 2 categories)



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Linear classifier is a set of perceptrons produces one score for every category



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Linear classifier: bias vector



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Linear classifier: Making a classification



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Interpreting the weights

• Assume our weights are trained on the CIFAR 10 dataset with raw pixels:

airplane automobile bird cat deer dog frog horse ship truck

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Interpreting the weights as templates

Let us look at each row of the weight matrix



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Interpreting the weights as templates

We can reshape the vector back in to the shape of an image



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Let's visualize what the templates look like

We can reshape the row back to the shape of an image



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Interpreting the weights geometrically



 Assume the image vectors are in 2D space to make it easier to visualize.

Plot created using Wolfram Cloud

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Training linear classifiers

We need to learn how to pick the weights in the first place.

Formally, we need to find W such that

$\min_{\mathbf{W}} Loss(y, \hat{y})$

Where y is the true label, \hat{y} is the model's predicted label.

All we have to do is define a loss function!

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Given training data:

What do you think is a good approximation weight parameter for this data point?

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Given training data:

What do you think is a good approximation weight parameter for this data point?

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Properties of a loss function

Given several training examples: $\{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}$

and a perceptron: $\hat{y} = wx$

where x is image and y is (integer) label (0 for dog, 1 for cat, etc) A loss function $L_i(y_i, \hat{y}_i)$ tells us how good our current classifier

- When the classifier predicts correctly, the loss should be low
- When the classifier makes mistakes, the loss should be high

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Properties of a loss function

Given several training examples: $\{(x_1, y_1), (x_2, y_2), \dots, (x_N, y_N)\}$

and a perceptron: $\hat{y} = wx$

where x is image and y is (integer) label (0 for dog, 1 for cat, etc) Loss over the entire dataset is an average of loss over examples

$$L = \frac{1}{N} \sum_{i=1}^{N} L_i(\mathbf{y}_i, \hat{\mathbf{y}}_i)$$

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How do we choose the loss function L_i ?

YOU get to chose the loss function!

(some are better than others depending on what you want to do)

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Squared Error (L2)

(a popular loss function) ((why?))



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- It allows us to treat the outputs of a model as probabilities for each class
- common way of measuring distance between probability distributions is Kullback-Leibler (KL) divergence:

$$D_{KL} = \sum_{y} P(y) \log \frac{P(y)}{Q(y)}$$

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• where *P* is the ground truth distribution and *Q* is the model's output score distribution

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KL divergence:
$$D_{KL} = \sum_{y} P(y) \log \frac{P(y)}{Q(y)}$$

In our case, *P* is only non-zero for correct class For example, consider the case we only have 3 classes:





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correct outputs

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KL divergence:

$$D_{KL} = \sum_{y} P(y) \log \frac{P(y)}{Q(y)}$$

 $= -\log Q(y)$ when y = dog

 $= -\log Prob[f(x_i, W) = y_i]$





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$$L_i = -\log Prob[f(x_i, W) = = y_i]$$

Remember our linear classifier: $\hat{y} = wx$

There are no limitations on the output space. Meaning that the model can output <0 or >1



$$L_i = -\log Prob[f(x_i, W) == y_i]$$

We need a mechanism to convert or normalize the output into probability range [0, 1]

Solution: SOFTMAX: $Prob[f(x_i, W) == k] = \frac{e^{y_k}}{\sum_i e^{\hat{y}_j}}$



correct outputs

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 $\begin{bmatrix} 3.2 \\ 5.1 \\ -1.7 \end{bmatrix}$

model outputs

$$L_i = -\log Prob[f(x_i, W) == y_i]$$

We need a mechanism to convert or normalize the output into probability range [0, 1]



$$L_i = -\log Prob[f(x_i, W) = = y_i]$$

In this case, what is the loss:

 $L_i = ??$



$$L_i = -\log Prob[f(x_i, W) = = y_i]$$

In this case, what is the loss:

 $L_i = -\log(0.13) = 2.04$



$$L_i = -\log Prob[f(x_i, W) = = y_i]$$

what is the minimum and maximum values that the loss can be?



 $L_i = -\log Prob[f(x_i, W) == y_i]$

At initialization, all the weights will be random. In this case, we can assume that the outputs will have the same probabilities, then what will the initial loss be?



$$L_i = -\log Prob[f(x_i, W) == y_i]$$

At initialization, all the weights will be random. In this case, we can assume that the outputs will have the same probabilities, then what will the initial loss be?



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How do we find the weights that minimize the loss?

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Gradient Descent Pseudocode

for _____in {0,...,num_epochs}:

$$L = 0$$

for x_i , y_i in data:
 $\hat{y}_i = f(x_i, W)$
 $L += L_i(y_i, \hat{y}_i)$
 $\frac{dL}{dW} = ???$
 $W \coloneqq W - \alpha \frac{dL}{dW}$

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Given training data point (x, y), the linear classifier formula is: $\hat{y} = Wx$ Let's assume that the correct label is class k, implying y=k

$$Loss = L(\hat{y}, y) = -\log \frac{e^{\hat{y}_k}}{\sum_j e^{\hat{y}_j}}$$
$$= -\hat{y}_k + \log \sum_j e^{\hat{y}_j}$$

Calculating the gradient is hard, but we can use the chain rule to make it

simpler

$$\frac{dL}{dW} = \frac{dL}{d\hat{y}}\frac{d\hat{y}}{dW}$$

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Given training data point (x, y), the linear classifier formula is: $\hat{y} = Wx$ Let's assume that the correct label is class k, implying y=k

$$Loss = -\hat{y}_k + log \sum_j e^{\hat{y}_j}$$

Now, we want to update the weights W by calculating the direction in which to change the weights to reduce the loss:

 $\frac{dL}{dW} = \frac{dL}{d\hat{y}}\frac{d\hat{y}}{dW}$

we know that $\frac{d\hat{y}}{dw} = x$, but what about $\frac{dL}{d\hat{y}}$?

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$$L = - \boldsymbol{\hat{y}}_k + log \sum_j e^{\boldsymbol{\hat{y}}_j}$$

To calculate $\frac{dL}{d\hat{y}}$, we need to consider two cases:

Case 1:

$$\frac{\mathrm{dL}}{\mathrm{d}\hat{y}_{k}} = -1 + \frac{\mathrm{e}^{y_{k}}}{\sum_{j} \mathrm{e}^{\hat{y}_{j}}}$$

Case 2:

$$\frac{\mathrm{dL}}{\mathrm{d}\hat{y}_{l\neq k}} = \frac{\mathrm{e}^{\hat{y}_{l}}}{\sum_{j} \mathrm{e}^{\hat{y}_{j}}}$$

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Putting it all together:



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Gradient Descent Pseudocode

for in {0,...,num_epochs}:

$$\overline{L} = 0$$

for x_i , y_i in data:
 $\hat{y}_i = f(x_i, W)$
 $L += L_i(y_i, \hat{y}_i)$
 $\frac{dL}{dW} = We know how to calculate this now!$

$$W \coloneqq W - \alpha \frac{dL}{dW}$$

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Backprop – another way of computing gradients



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Backprop – another way of computing gradients



Key Insight:

- visualize the computation as a graph
- Compute the forward pass to calculate the loss.
- Compute all gradients for each computation backwards

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Backprop example in 1D:

We know the chain rule



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- Assume the image vectors are in 2D space to make it easier to visualize.
- Let's start with one class: dog.
- Initialize the weights randomly

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- Assume the image vectors are in 2D space to make it easier to visualize.
- Let's start with one class: dog.
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- Now let's add two data points

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- Assume the image vectors are in 2D space to make it easier to visualize.
- Let's start with one class: dog.
- Initialize the weights randomly
- Now let's add two data points
- Update the weights

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- Assume the image vectors are in 2D space to make it easier to visualize.
- Let's start with one class: dog.
- Initialize the weights randomly
- Now let's add two more data points
- Update the weights

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- Assume the image vectors are in 2D space to make it easier to visualize.
- Let's start with one class: dog.
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A simple recognition pipeline



Recall: we can featurize images into a vector



Raw pixels Raw pixels + (x,y) PCA LDA BoW BoW + spatial pyramids

Image Vector



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Features sometimes might not be linearly separable



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Remember our linear classifier



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Let's change the features by adding another layer



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2-layer network: mathematical formula

- Linear classifier: y = Wx
- 2-layer network: $y = W_2 \max(0, W_1 x)$
- 3-layer network: $y = W_3 \max(0, W_2 \max(0, W_1 x))$

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The number of layers is a new hyperparameter!

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2-layer network: mathematical formula

- Linear classifier: y = Wx
- 2-layer network: $y = W_2 \max(0, W_1 x)$

We know the size of $x = 1 \times 3072$ and $y = 10 \times 1$, so what are **W1** and **W2**

$$W_1 = h \times 3072 \qquad W_2 = 10 \times h$$

h is a new hyperparameter!

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2-layer network: mathematical formula

- Linear classifier: y = Wx
- 2-layer network: $y = W_2 \max(0, W_1 x)$

Why is the max(0, _) necessary? Let's see what happen when we remove it:

 $y = W_2 W_1 x = W x$

Where: $W = W_2 W_1$

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Activation function

The non-linear max function allows models to learn more complex transformations for features.

Choosing the right activation function is another new hyperparameter!



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2-layer neural network performance

- ~40% accuracy on CIFAR-10 test
 Best class: Truck (~60%)
 Worst class: Horse (~16%)
- Check out the model at: https://tinyurl.com/cifar10

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Next lecture

Deep learning for CV

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