

# Binary Image Analysis: Part 2

## Readings: Chapter 3: 3.5-3.7

- mathematical morphology
- region properties
- region adjacency

# Mathematical Morphology

Binary mathematical morphology consists of two basic operations

**dilation and erosion**

and several composite relations

**closing and opening**  
**conditional dilation**

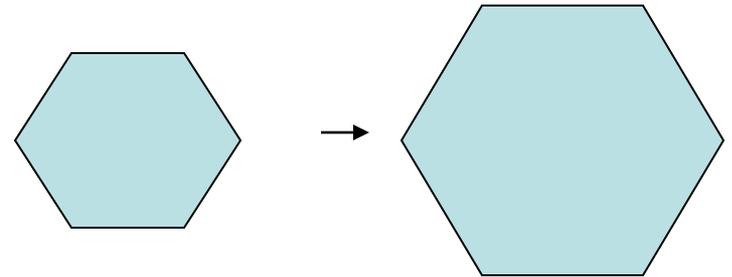
...

# Dilation

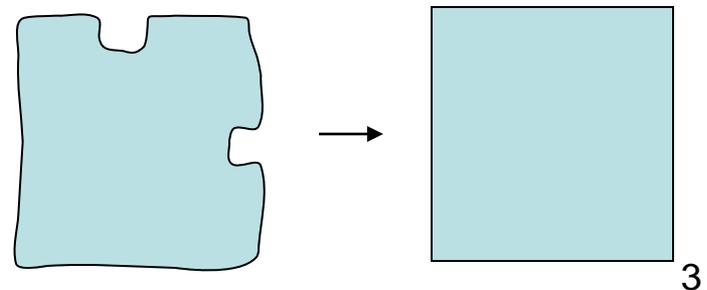
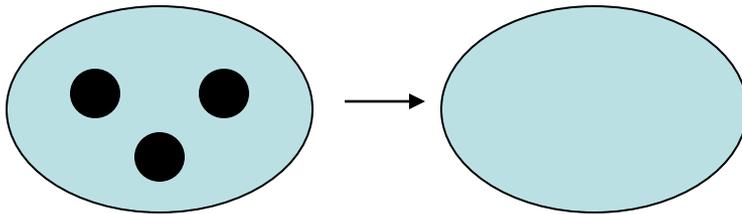
Dilation **expands** the connected sets of 1s of a binary image.

It can be used for

1. growing features



2. filling holes and gaps

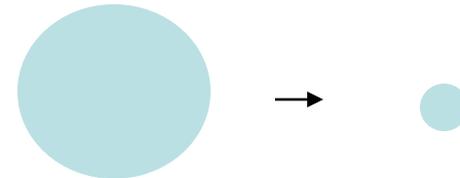


# Erosion

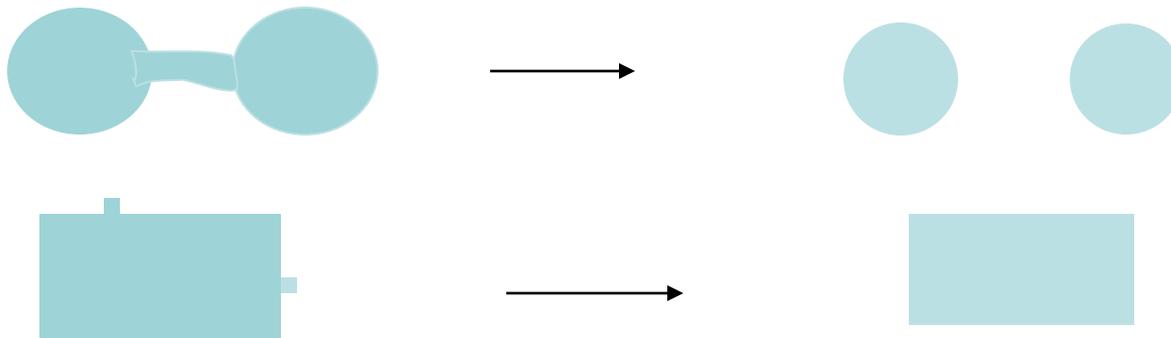
Erosion **shrinks** the connected sets of 1s of a binary image.

It can be used for

1. shrinking features



2. Removing bridges, branches and small protrusions



# Structuring Elements

A **structuring element** is a shape mask used in the basic morphological operations.

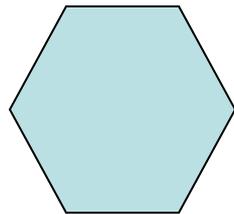
They can be any shape and size that is digitally representable, and each has an **origin**.

The origin is usually the **center** if the structuring element is symmetric.

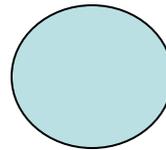


box

box(length,width)

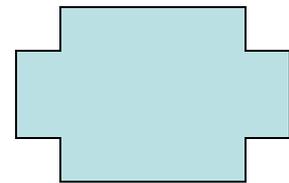


hexagon



disk

disk(diameter)



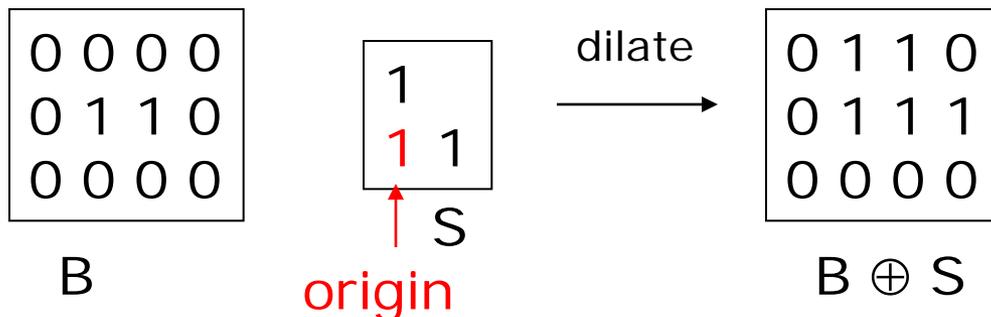
something

# Dilation with Structuring Elements

The arguments to dilation and erosion are

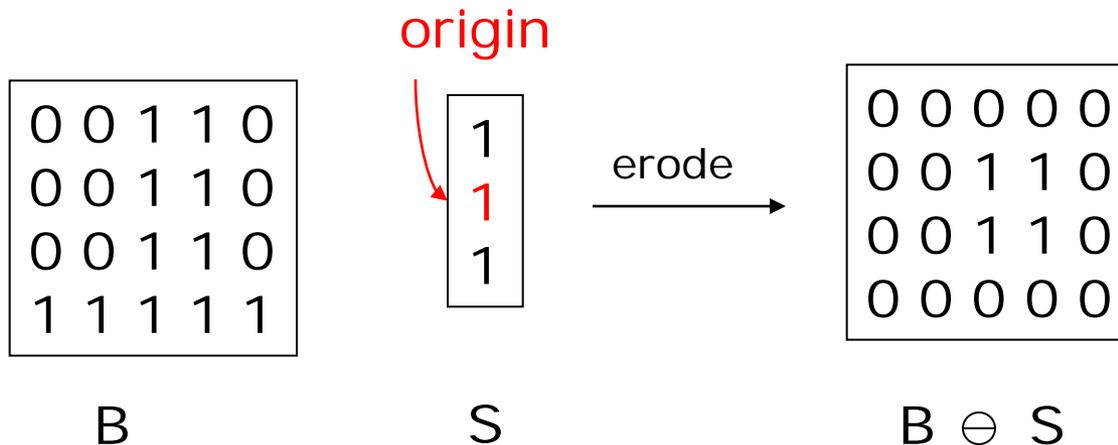
1. a binary image **B**
2. a structuring element **S**

`dilate(B,S)` takes binary image B, places the origin of structuring element S over each 1-pixel, and ORs the structuring element S into the output image at the corresponding position.

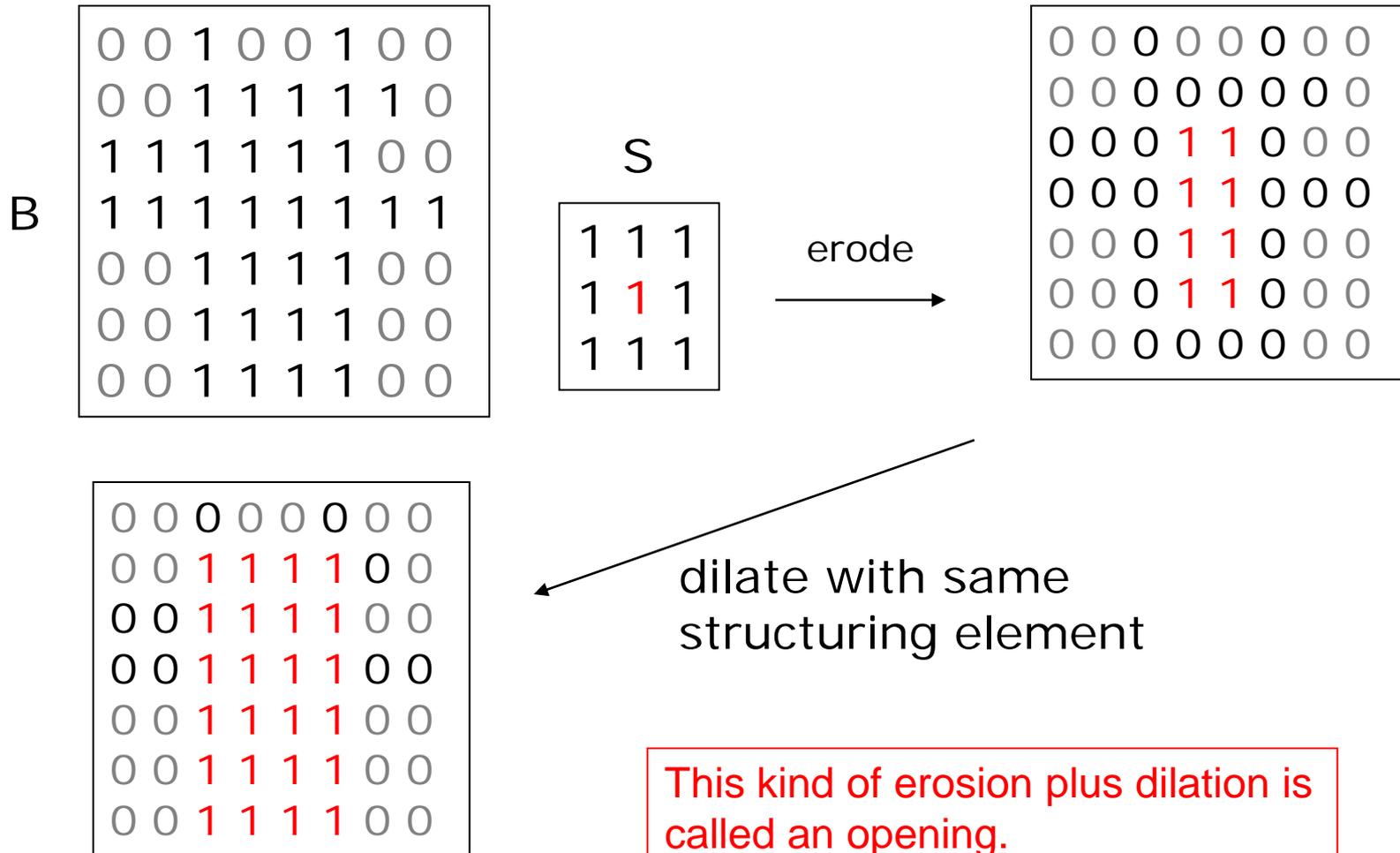


# Erosion with Structuring Elements

$\text{erode}(B, S)$  takes a binary image  $B$ , places the origin of structuring element  $S$  over every pixel position, and ORs a binary 1 into that position of the output image only if every position of  $S$  (with a 1) covers a 1 in  $B$ .



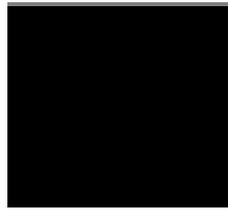
# Example to Try



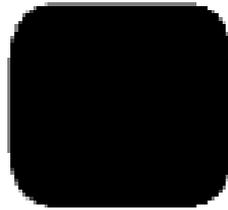
# Opening and Closing

- **Closing** is the compound operation of dilation followed by erosion (with the same structuring element)
- **Opening** is the compound operation of erosion followed by dilation (with the same structuring element)

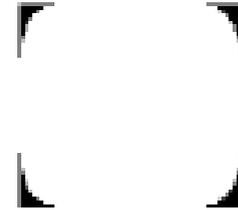
# Use of Opening



Original



Opening

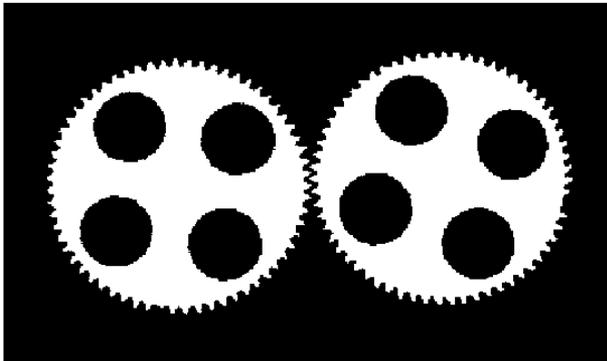


Corners

What kind of structuring element was used in the opening?

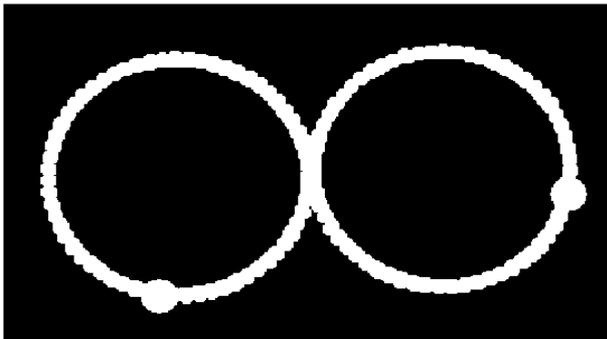
How did we get the corners?

# Gear Tooth Inspection



original  
binary  
image

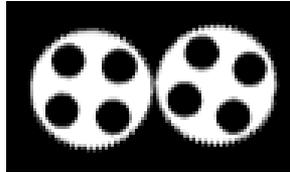
How did  
they do it?



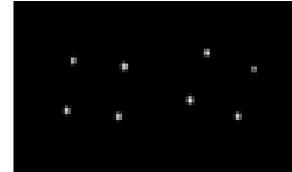
detected  
defects

# Some Details (see Ch 3)

1. Original image



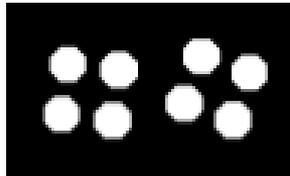
a) original image B



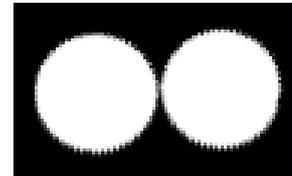
b) B1 = B ⊖ hole\_ring

2. Find centers of holes by erosion with a circular ring element

3. Dilate by a hexagon mask



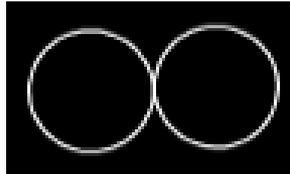
c) B2 = B1 ⊕ hole\_mask



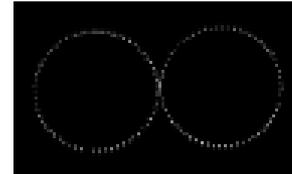
d) B3 = B OR B2

4. OR the hexagons into the original

5. Use disc the size of the body, open to remove teeth. Dilate. Subtract.



e) B7 (see text)



f) B8 = B AND B7

6. AND result of 5 with 1 to get just the teeth.

7. Dilate 6 with a small element that leaves the defects as holes



g) B9 = B8 ⊕ tip\_spacing



h) RESULT = ((B7 - B9) ⊕ defect\_mask) OR B9

7. Show defects in red for customer

# Region Properties

Properties of the regions can be used to recognize objects.

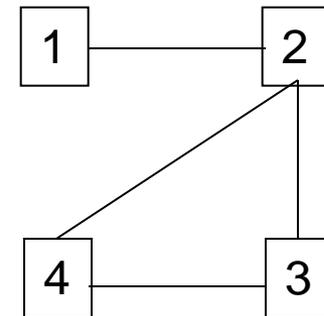
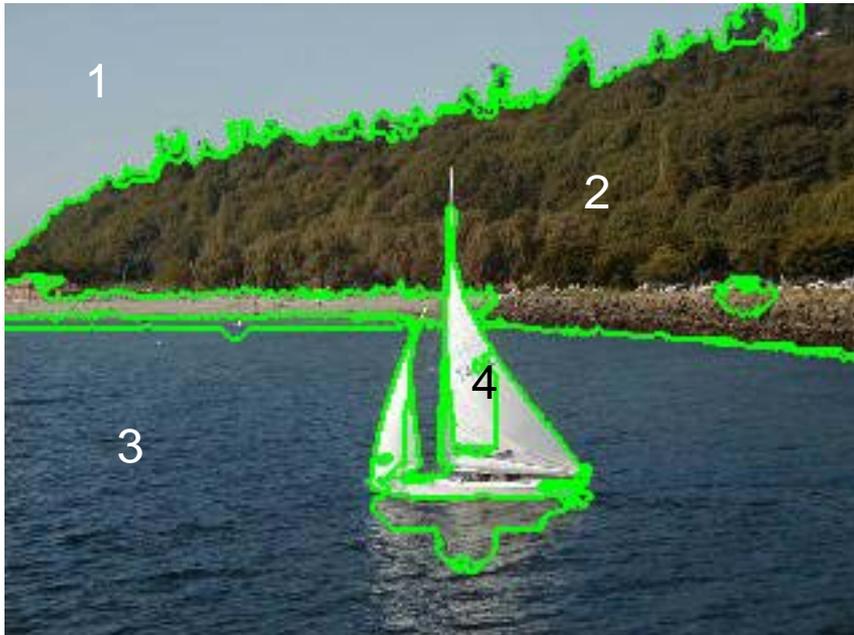
- **geometric properties (Ch 3)**
- **gray-tone properties**
- **color properties**
- **texture properties**
- **shape properties (a few in Ch 3)**
- **motion properties**
- **relationship properties (1 in Ch 3)**

# Geometric and Shape Properties

- area
- centroid
- perimeter
- perimeter length
- circularity
- elongation
- mean and standard deviation of radial distance
- bounding box
- extremal axis length from bounding box
- second order moments (row, column, mixed)
- lengths and orientations of axes of best-fit ellipse

# Region Adjacency Graph

A **region adjacency graph** (RAG) is a graph in which each node represents a region of the image and an edge connects two nodes if the regions are adjacent.



# What's all this for?

Once regions are identified and their properties and relationships computed, we can start using them for higher-level tasks such as:

- inspection
- object recognition
- image matching
- classification in general