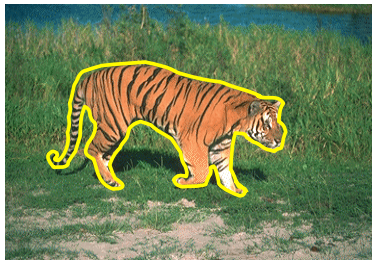
Image Scissors

Aging Helen Mirren

Today's Readings

- Intelligent Scissors, Mortensen et. al, SIGGRAPH 1995

Extracting objects



How could this be done?

- hard to do manually
- hard to do automatically ("image segmentation")
- easy to do *semi-automatically*

Intelligent Scissors (demo)

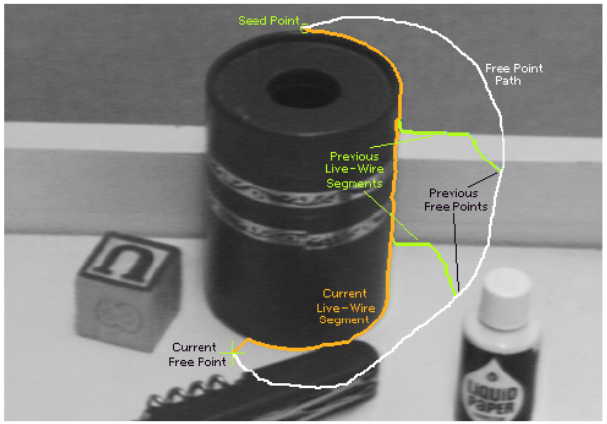
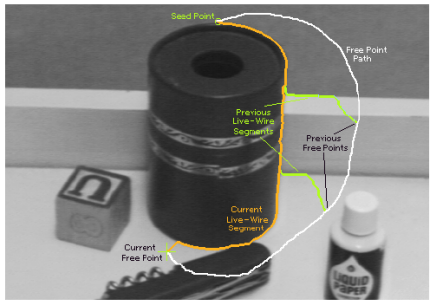


Figure 2: *Image demonstrating how the live-wire segment adapts and snaps to an object boundary as the free point moves (via cursor movement). The path of the free point is shown in white. Live-wire segments from previous free point positions (t_0, t_1, and t_2) are shown in green.*

Intelligent Scissors

Approach answers a basic question

- Q: how to find a path from seed to mouse that follows object boundary as closely as possible?
- A: define a path that stays as close as possible to edges



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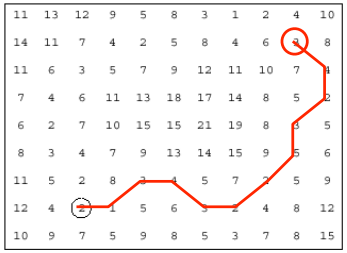
Intelligent Scissors

Basic Idea

- Define edge score for each pixel
  - edge pixels have low cost
- Find lowest cost path from seed to mouse

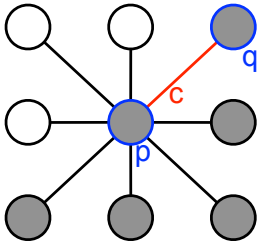


Questions

- How to define costs?
- How to find the path?

Let's look at this more closely

Treat the image as a graph



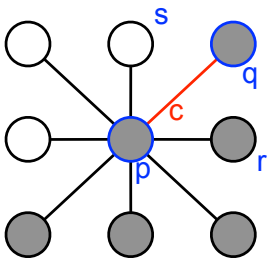
Graph

- node for every pixel **p**
- link between every adjacent pair of pixels, **p**,**q** *(8-connected)*
- cost **c** for each link

Note: each *link* has a cost

- this is a little different than the figure before where each pixel had a cost

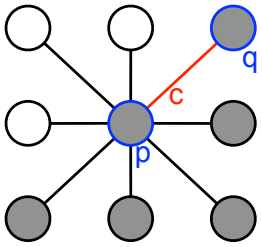
Defining the costs

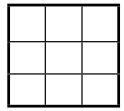


Want to hug image edges: how to define cost of a link c?

- good (low-cost) links follow the intensity edge
  - want intensity to change rapidly ⊥ to the link
- $c \approx -\frac{1}{\sqrt{2}}$ |intensity of r – intensity of s|

Defining the costs



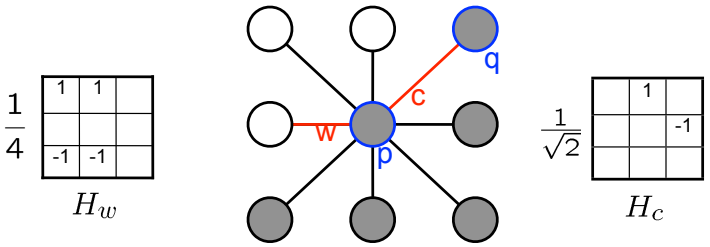


H_c

c can be computed using a cross-correlation filter

- assume it is centered at p

Defining the costs



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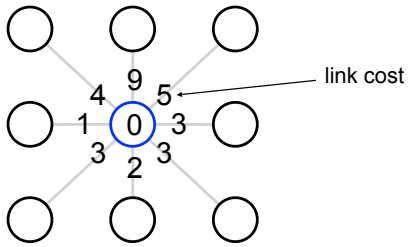
A couple more modifications

- Scale the filter response by length of link c. Why?
- Make c positive
  - Set c = (max-|filter response|*length)
  - where max = maximum |filter response|*length over all pixels in the image

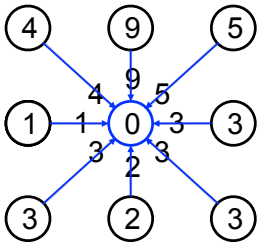
Dijkstra's shortest path algorithm



Algorithm

1. init node costs to ∞, set p = seed point, cost(p) = 0
2. expand p as follows:
   for each of p's neighbors q that are not expanded
   » set cost(q) = min(cost(p) + c_{pq}, cost(q))
3. set r = node with minimum cost on the ACTIVE list
4. repeat Step 2 for p = r

Dijkstra's shortest path algorithm



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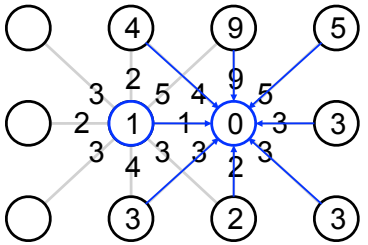

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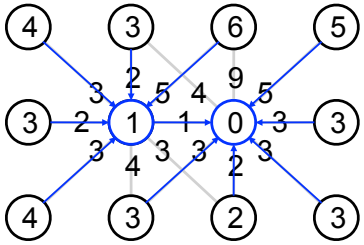

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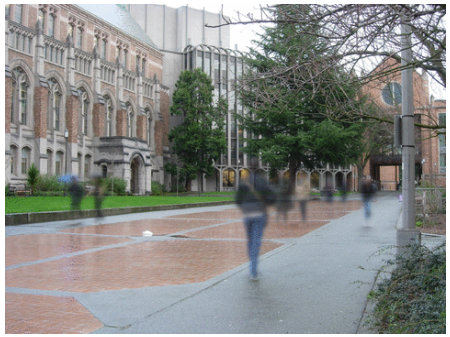
Dijkstra's shortest path algorithm

Properties

- It computes the minimum cost path from the seed to every node in the graph. This set of minimum paths is represented as a *tree*
- Running time, with N pixels:
  - $O(N^2)$ time if you use an active list
  - O(N log N) if you use an active priority queue (heap)
  - takes fraction of a second for a typical (640x480) image
- Once this tree is computed once, we can extract the optimal path from any point to the seed in O(N) time.
  - it runs in real time as the mouse moves
- What happens when the user specifies a new seed?

Results

Jason Dang



Peter Davis

http://www.cs.washington.edu/education/courses/455/12wi/projects/project1/artifacts/index.html

Help session—Avanish