

Announcements

- Mailing list: cse455@cs.washington.edu
 - you should have received messages
- Office hours [online](#)
 - start next week
 - » this week: by appt. only
 - » next week: Tu 1:30-2:30 slot is cancelled
- Project 1 out today (due in two weeks)
 - posted on [course web page](#)
 - help session today
- Your ID card should open Sieg 327
 - check to make sure ASAP

Image Scissors

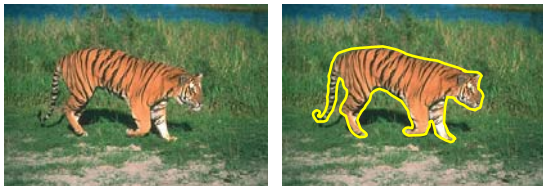


From [Sandlot Science](#)

Today's Readings

- [Intelligent Scissors](#), Mortensen et. al, SIGGRAPH 1995

Extracting objects



How could this be done?

- hard to do manually
- hard to do automatically ("image segmentation")
- easy to do *semi-automatically*

Intelligent Scissors (demo)

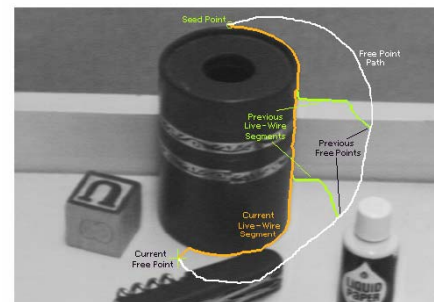


Figure 2: Image demonstrating how the live-wire segment adapts and snaps to an object boundary as the free point moves (via cursor movement). The path of the free point is shown in white. Live-wire segments from previous free point positions (t_0 , t_1 , and t_2) are shown in green.

Intelligent Scissors

Approach answers a basic question

- Q: how to find a path from seed to mouse that follows object boundary as closely as possible?
- A: define a path that stays as close as possible to edges

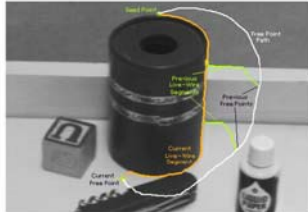


Figure 2: Image demonstrating how the live-wire segment adapts and snaps to an object boundary as the free point moves (via cursor movement). The path of the free point is shown in white. Live-wire segments from previous free point positions (t_0 , t_1 , and t_2) are shown in green.

Intelligent Scissors

Basic Idea

- Define edge score for each pixel
 - edge pixels have low cost
- Find lowest cost path from seed to mouse



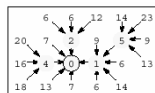
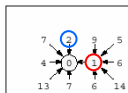
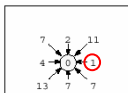
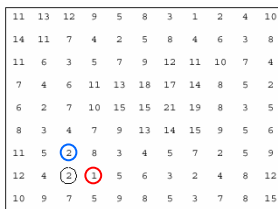
Questions

- How to define costs?
- How to find the path?

Path Search (basic idea)

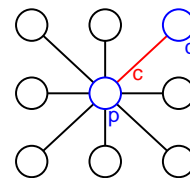
Graph Search Algorithm

- Computes minimum cost path from seed to *all other pixels*



How does this really work?

Treat the image as a graph



Graph

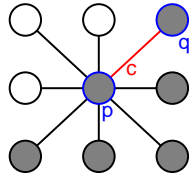
- node for every pixel p
- link between every adjacent pair of pixels, p, q
- cost c for each link

Note: each *link* has a cost

- this is a little different than the figure before where each pixel had a cost

Defining the costs

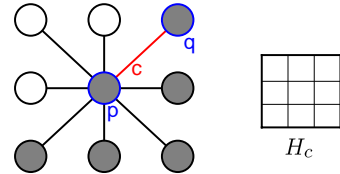
Treat the image as a graph



Want to hug image edges: how to define cost of a link?

- the link should follow the intensity edge
 - want intensity to change rapidly? to the link
- $c \approx$ - |difference of intensity? to link|

Defining the costs



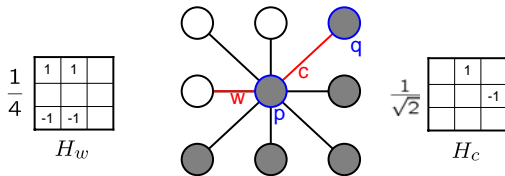
c can be computed using a cross-correlation filter

- assume it is centered at p

Also typically scale c by its length

- set $c = (\max - |\text{filter response}|)$
 - where max = maximum |filter response| over all pixels in the image

Defining the costs



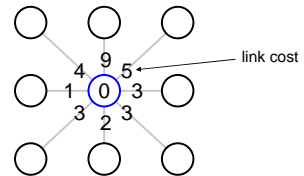
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Also typically scale c by its length

- set $c = (\max - |\text{filter response}|) \times \text{length}$
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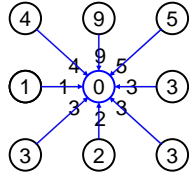
Dijkstra's shortest path algorithm



Algorithm

1. init node costs to ∞ , set p = seed point, $\text{cost}(p) = 0$
2. expand p as follows:
 - for each of p 's neighbors q that are not expanded
 - » set $\text{cost}(q) = \min(\text{cost}(p) + c_{pq}, \text{cost}(q))$

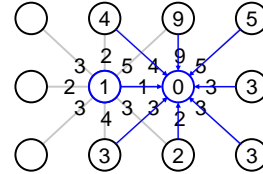
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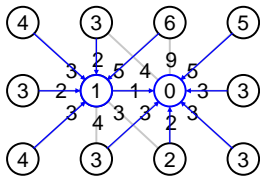
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4. repeat Step 2 for $p = r$

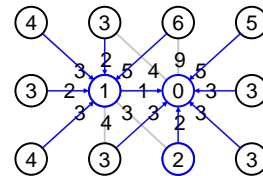
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Dijkstra's shortest path algorithm

Properties

- It computes the minimum cost path from the seed to every node in the graph. This set of minimum paths is represented as a *tree*
- Running time, with N pixels:
 - $O(N^2)$ time if you use an active list
 - $O(N \log N)$ if you use an active priority queue (heap)
 - takes fraction of a second for a typical (640x480) image
- Once this tree is computed once, we can extract the optimal path from any point to the seed in $O(N)$ time.
 - it runs in real time as the mouse moves
- What happens when the user specifies a new seed?

Results



<http://www.cs.washington.edu/education/courses/455/03wi/projects/project1/artifacts/index.html>

Help session—Jeff
