

Lec 9

XK Synchronization
+

Reader-Writer Locks

Synchronization in XK

- Spinlock: disable interrupts + spin
- sleeplock: give up processor until lock free
- sleep(spinlock, chan): CV wait
- wakeup(chan): CV broadcast

```
// Mutual exclusion lock.
```

```
struct spinlock {  
    uint locked; // Is the lock held?  
  
    // For debugging:  
    char *name; // Name of lock.  
    struct cpu *cpu; // The cpu holding the lock.  
    uint64_t pcs[10]; // The call stack (an array of program counters)  
                        // that locked the lock.  
};
```

```
// Acquire the lock. Loops (spins) until the lock is acquired.
```

```
void acquire(struct spinlock *lk) {  
    pushcli(); // disable interrupts to avoid deadlock.  
    if (holding(lk))  
        panic("acquire");
```

```
    // The xchg is atomic.  
    while (xchg(&lk->locked, 1) != 0)  
        ;
```

```
    // Tell the C compiler and the processor to not move loads or stores  
    // past this point, to ensure that the critical section's memory  
    // references happen after the lock is acquired.  
    __sync_synchronize();
```

```
    // Record info about lock acquisition for debugging.
```

```
    lk->cpu = mycpu();  
    getcallerpcs(&lk, lk->pcs);
```

```
}
```

8.16

```
// Release the lock.
void release(struct spinlock *lk) {
    if (!holding(lk))
        panic("release");

    lk->pcs[0] = 0;
    lk->cpu = 0;

    // Tell the C compiler and the processor to not move loads or stores
    // past this point, to ensure that all the stores in the critical
    // section are visible to other cores before the lock is released.
    // Both the C compiler and the hardware may re-order loads and
    // stores; __sync_synchronize() tells them both not to.
    __sync_synchronize();

    // Release the lock, equivalent to lk->locked = 0.
    // This code can't use a C assignment, since it might
    // not be atomic. A real OS would use C atomics here.
    asm volatile("movl $0, %0" : "+m"(lk->locked) :);

    popcli();
}
```

```
static inline uint xchg(volatile uint *addr, uint newval) {
    uint result;

    // The + in "+m" denotes a read-modify-write operand.
    asm volatile("lock; xchgl %0, %1"
                 : "+m"(*addr), "=a"(result)
                 : "l"(newval)
                 : "cc");
    return result;
}
```

8.17 $\frac{1}{2}$

```
// Long-term locks for processes
struct sleeplock {
    uint locked;           // Is the lock held?
    struct spinlock lk;    // spinlock protecting this sleep lock

    // For debugging:
    char *name;            // Name of lock.
    int pid;               // Process holding lock
};

// a sleeping lock relinquishes the processor if the lock is busy
// note mesa semantics: process can wakeup and find the lock still busy.
// NOTE: no spinlocks should be held while calling 'acquiresleep'
// (since if 'acquiresleep' tries to sleep while a spinlock is held,
// 'sched''s contract will be violated).
void acquiresleep(struct sleeplock *lk) {
    acquire(&lk->lk);

    // We should never try to acquire sleeplock while we already hold it
    if (lk->locked && lk->pid == myproc()->pid) {
        panic("Already holding sleeplock!");
    }

    while (lk->locked) {
        sleep(lk, &lk->lk);
    }
    lk->locked = 1;
    lk->pid = myproc()->pid;
    release(&lk->lk);
}
```

8.18

```
// a sleeping lock wakes up a waiting process, if any, on lock release.
void releasesleep(struct sleeplock *lk) {
    acquire(&lk->lk);

    // Assert that the lock is actually locked.
    if (!lk->locked) {
        panic("releasesleep: sleeplock is not locked!");
    }

    // Assert that we are the one holding the lock.
    if (lk->pid != myproc()->pid) {
        panic("releasesleep: sleeplock is not held by current proc!");
    }

    lk->locked = 0;
    lk->pid = 0;
    wakeup(lk);
    release(&lk->lk);
}
```

8.19

```
// Atomically release lock and sleep on chan.
// Reacquires lock when awakened.
void sleep(void *chan, struct spinlock *lk) {
    if (myproc() == 0)
        panic("sleep");

    if (lk == 0)
        panic("sleep without lk");

    // Must acquire ptable.lock to change p->state and then call sched.
    // Once we hold ptable.lock, we are guaranteed not to miss any wakeup
    // (wakeup runs with ptable.lock locked), so it's okay to release lk.
    if (lk != &ptable.lock) { // DOC: sleeplock0
        acquire(&ptable.lock); // DOC: sleeplock1
        release(lk);
    }

    // Go to sleep.
    myproc()->chan = chan;
    myproc()->state = SLEEPING;
    sched();

    myproc()->chan = 0;

    // Reacquire original lock.
    if (lk != &ptable.lock) { // DOC: sleeplock2
        release(&ptable.lock);
        acquire(lk);
    }
}
```

```
// Wake up all processes sleeping on chan.
// The ptable lock must be held.
static void wakeup1(void *chan) {
    struct proc *p;

    for (p = ptable.proc; p < &ptable.proc[NPROC]; p++)
        if (p->state == SLEEPING && p->chan == chan)
            p->state = RUNNABLE;
}

// Wake up all processes sleeping on chan.
void wakeup(void *chan) {
    acquire(&ptable.lock);
    wakeup1(chan);
    release(&ptable.lock);
}
```

Reader-Writer Locks

- allows any number of concurrent readers
- only one writer (and no readers)
- common in DBMSes + OS kernels
 - only worth it if vast majority of ops are reads

API

acquireRead()

releaseRead()

acquireWrite()

releaseWrite()

Reader-Writer Lock interface

```
interface ReaderWriterLock {
```

```
    void acquireRead();
```

```
    void acquireWrite();
```

```
    void releaseRead();
```

```
    void releaseWrite();
```

```
}
```

Reader - Writer Lock Design

- RWLock is itself a concurrent data structure!
 - follow design recipe from last time (monitor)
 - ↳ will have a (normal) lock in our RWLock!
- what else?
 - track # of active Readers / active Writers
 - at most one > 0
 - active Writers ≤ 1
 - track # of waiting Readers / waiting Writers

So far

```
class RWLock {  
    int activeReaders;  
    int activeWriters;  
    int waitingReaders;  
    int waitingWriters;  
}
```

Reader-Writer Lock Design (continued)

- When do the interface methods need to wait?
 - acquireRead: wait if there are active writers
 - acquireWrite: wait if there are active readers or writers
 - releaseRead / releaseWrite: don't wait

↳ add condition variables for wait conditions

- noActiveWriters
- noActiveReadersOrWriters

With CVs

```
class RWLock {
```

```
    int activeReaders;
```

```
    int activeWriters;
```

```
    int waitingReaders;
```

```
    int waitingWriters;
```

```
    CV noActiveWriters;
```

```
    CV noActiveReadersOrWriters;
```

```
} associated lock: "this"
```

```
synchronized void acquireRead() {  
    waitingReaders++;  
    while (activeWriters > 0)  
        noActiveWriters.wait();  
    waitingReaders--;  
    activeReaders++;  
}
```

```
synchronized void acquireWrite() {  
    waitingWriters++;  
    while (activeReaders > 0 ||  
           activeWriters > 0)  
        noActiveReadersOrWriters.wait();  
    waitingWriters--;  
    activeWriters++;  
}
```

synchronized ^{void} releaseRead() {

activeReaders --;

if (activeReaders == 0)

noActiveReadersOrWriters.signal();

// know no active writers

}

synchronized void releaseWrite() {

activeWriters --;

// we are only active entity

if (waitingWriters > 0) {

noActiveReadersOrWriters.signal();

} else {

noActiveWriters.broadcast();

}

}