# Lab 2

Part 2

1

# Admin

#### • Lab 2 out!

- Design Doc due 10/21/24 @11:59pm
- Lab Code + Questions due 10/28/24 @11:59pm
- You will write design docs starting with lab 2
  - The better you fill it out, the more helpful we can be with our feedback!
  - Graded on effort basis, NOT correctness (although correctness would be nice)

# Agenda

- Monitors Overview
- Lab 2 Pipe
- Lab 2 Exec
- Setting up the Stack exercises

# Monitors

# What the heck is a monitor?

• A monitor is made up of a lock and at least one condition variable

Why do we use monitors?

# What the heck is a monitor?

• A monitor is made up of a lock and at least one condition variable

Why do we use monitors?

- Similar to locks but...
  - Allow processes to wait for certain conditions to become true while "holding lock" (waiter atomically releases the lock and reacquires the lock on wakeup).

# Monitors in xk

- Lock
  - xk condition variable API only supports spinlock (an impl. choice)
- Condition
  - $\circ$   $\$  the shared data that threads are synchronizing on
  - E.g. for wait/exit this would be child's state
- Condition Variable
  - the waiter list is tracked by the process table
  - proc in SLEEPING state with the same chan are part of the same CV
  - chan is a pointer, can be anything (think of it as a cv identifier)



"Condition variable? I saw no mention of those in the provided code." ~ You, a free thinker.

# No Condition Variables in xk

The starter code does *not* provide the object-oriented std::condition\_variable API you can find in C++: LINK

*Instead* it provides the sleep and wakeup helper functions (which together can implement the monitor pattern)

- sleep ~= wait
- wakeup ~= broadcast

# Sleep

- sleep(void\* chan, struct spinlock\* lk)
  - atomically release your current lock and grabs the process table (ptable) lock
    - if your current lock is the ptable lock do nothing
    - why might your current lock be the ptable lock?
  - sets myproc()->state to SLEEPING
  - sets myproc()->chan to whatever channel we are waiting on
  - yields so that scheduler can run another process

# Wakeup

- wakeup(void\* chan)
  - acquires the process table lock
  - looks for all SLEEPING processes with the given channel (chan)
    - sets each proc->state to RUNNABLE (ready)
    - proc->chan is also cleared to NULL

# Monitors in xk

• You will use monitors to implement wait(), exit(), and pipe() for lab2!

#### wait(), exit()

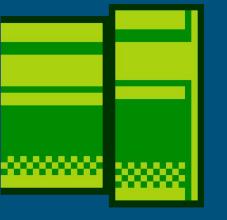
• Coordinating children and parent processes

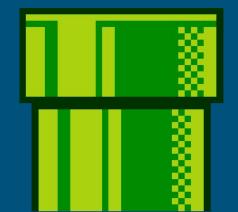
pipe()

• Coordinating reader and writer processes



# Lab 2 - Pipe





# What is a Pipe?

A pipe is essentially a queue of bytes with two ends:

• One end designated for input, the other for output

When you type 'Is | wc' into the shell, you are using a pipe!!!

- 'Is' lists the directory contents
- 'wc' counts the number of lines output from the ls command
- The pipe joins the output from 'ls' to the input of 'wc'

# pipe(fds)

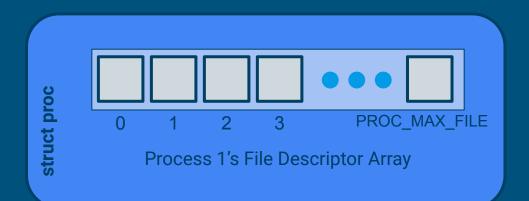
- Creates a pipe (kernel buffer) that can be read from/written to.
- From the user perspective: returns two new file descriptors
  - o fds[0] = "read end", O\_RDONLY
  - o fds[1] = "write end", O\_WRONLY
- Pipes allow processes to communicate with each other
  - Parent opens a pipe, forks a child (now they both have access to the pipe ends)
  - Typically each process only leaves one end open (closes the read end or the write end)

## An Example to Illustrate Pipes

Now let's go through a demonstration of what happens as a sample user uses the pipe API (in the context of multiprocessing)!

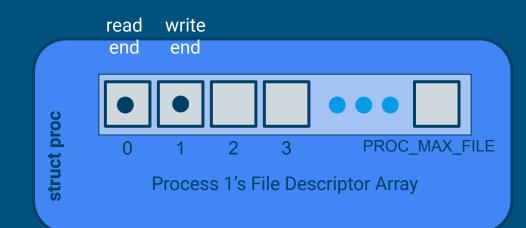


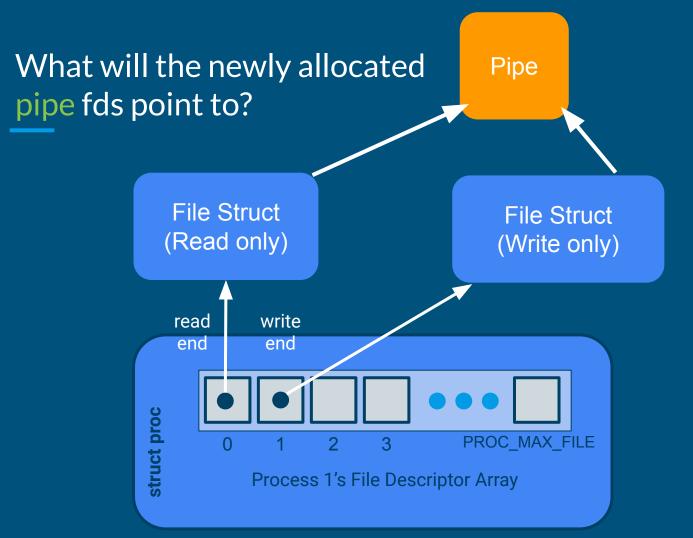
#### • Process 1 starts with no open files





#### Process 1 calls pipe()





# Pipe usage



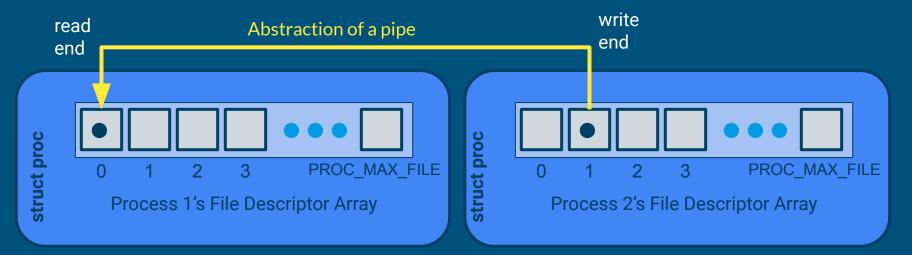
 Note: fork() is called by user and should not be called within the actual pipe() call

• Process 1 calls fork(), fd table is duplicated



# Pipe usage

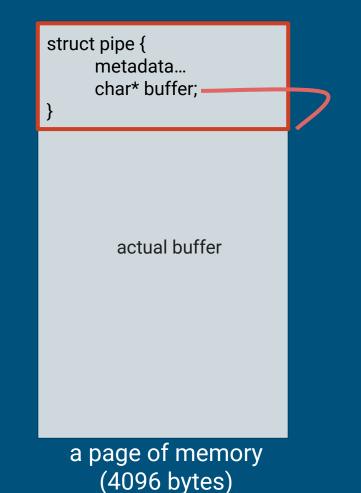
- Process 1 close(1), process 2 close(0)
- The process with the write end open is a writer, and the one with the read end open is a reader



# pipe FAQs

- When should pipe be allocated?
  - dynamically! when pipe() is called!
- How does xk do dynamic memory allocation?
  - hint: kstack is also dynamically allocated
  - `kalloc` allocates a page (4096 bytes) of memory from the kernel heap
    - wait, but how do I put a pipe onto the page?

struct pipe\* p = kalloc();
p->buffer = ???
should be right past the struct,
and what would that be?



# pipe FAQs

- When can you free the pipe and its buffer?
  - remember there may be multiple references to read end and write end
- Can we always write to or read from the buffer? (Hint: bounded buffer sync)
  - What if there's no room to write, or no data to read?
  - What happens if all read/write ends are closed?
- How will pipes integrate with the file syscalls?
  - Need a way to determine if a struct file is an inode or a pipe

# Interaction with File API

Pipes are accessed through file descriptors.

This means you need to think through how the lab 1 syscalls will work when called on pipe file descriptors:

- closedupwrite
  - stat

# What should pipe contain?

• What metadata/information do you need for pipe?

# What should pipe contain?

- What metadata/information do you need for pipe?
  - Read offset
  - $\circ$  Write offset
  - # of bytes available in the buffer
  - Whether the read end is still open
  - Whether the write end is still open
  - Lock and condition variables
  - A way to track the active writer [ why? ]
- Similar to the bounded buffer problem

# And that's pipe!

... But wait! There's more! (that you have to do in lab 2 part 2)



# But wait! .... There's more! (in lab 2 part 2)

## In lab 2 part 2 you are also implementing exec

# exec(3) — Linux manual page

Lab 2 - exec

# Motivation

Why do we have exec?

To let user code execute user programs!
 E.g. Shell commands like 'ls' and 'cat' commands are exec'ed by the 'sh' program.

## exec(program, args)

- Fully replaces the current program; it does not create a new process
- How do we replace the current program?
  - need to set up a new virtual address space and new registers states
  - and then switch to using the new VAS and register states
  - file descriptors and pid remain the same

# exec(path, argv) arguments validation



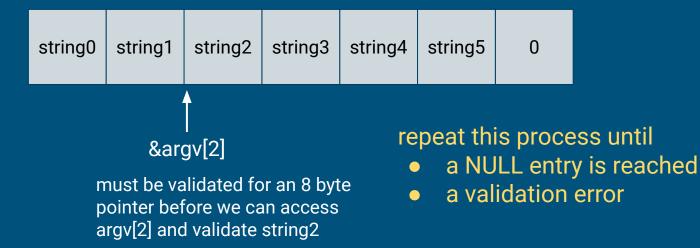
argv[0] and validate string0

# exec(path, argv) arguments validation



must be validated for an 8 byte pointer before we can access argv[1] and validate string1

# exec(path, argv) arguments validation



## exec(program, args)

- Setting up a new virtual address space (pseudocode)
  - vspaceinit for initialization
  - vspaceloadcode to load code
  - vspaceinitstack to allocate stack vregion
    - you still need to populate user stack with arguments
    - vspacewritetova to write data into the stack of the new VAS
  - vspaceinstall to swap in the new vspace
  - vspacefree to release the old vspace
- The swapover to the new vspace can be tricky to get right!
  - To swap: Assign the new vspace to current vspace

# How are the args set up in exec?

#### Another look at main()

exec sets up the function arguments for main! int main(int argc, char\*\* argv)

- argc: The number of elements in argv
- argv: An array of strings representing program arguments
  - First is always the name of the program
  - Argv[argc] = 0

## Setting up the Stack

#### Quick Review: X86\_64 Calling Conventions

From 351:

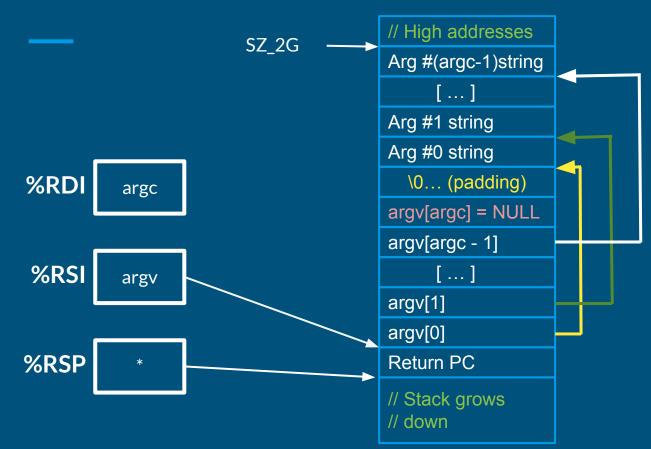
- %rdi: holds the first argument
- %rsi: holds the second argument
  - %rdx, %rcx, %r8, %r9 comes next
  - overflows (arg7, arg8 ...) onto the stack
- %rsp: points to the top of the stack (lowest address)

#### Quick Review: X86\_64 Calling Conventions

From 351:

- Local variables are stored on the stack
- If an array is an argument, the array contents are stored on the stack and the register contains a pointer to the array's beginning

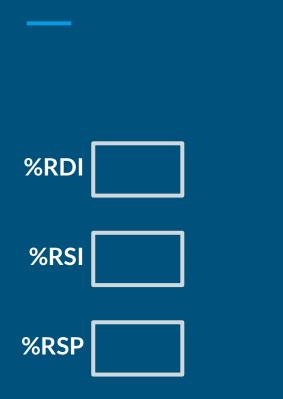
#### **Stack For User Process**



- Since argv is an array of pointers, %RSI points to an array on the stack
- Since each element of argv is a char\*, each element points to a string elsewhere on the stack
- Why? Alignment
- Why NULL pointer? Convention

## Let's Practice!

#### Practice Exercise 1

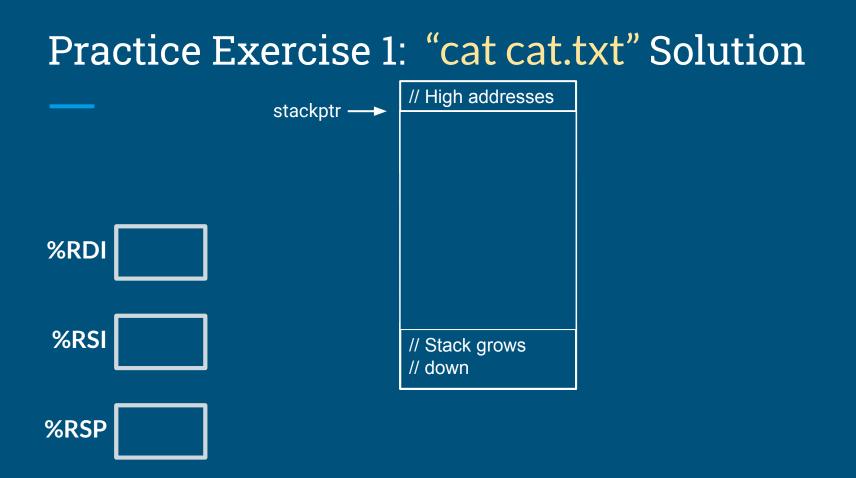


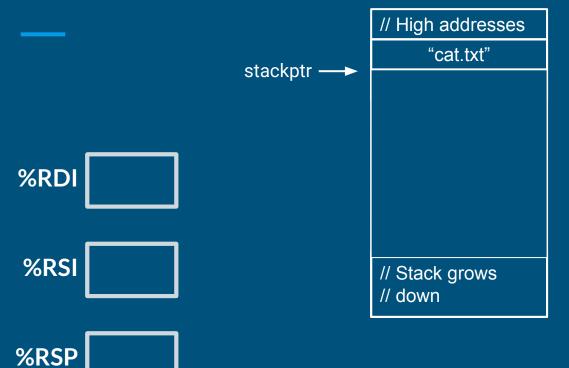


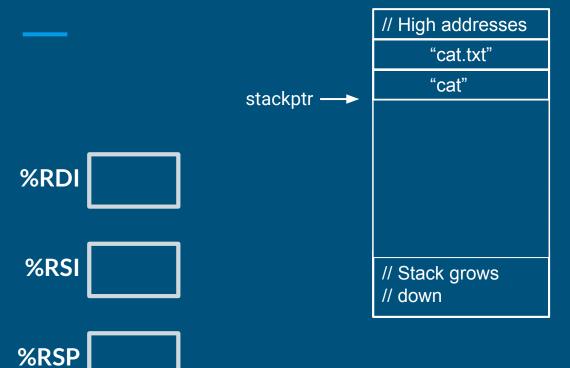
Now it's your turn!

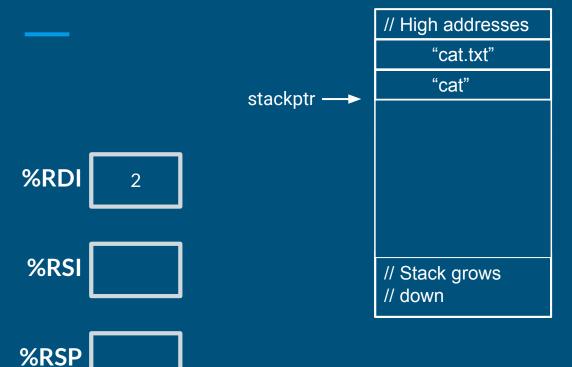
Draw stack layout and determine register values for exec() called with:

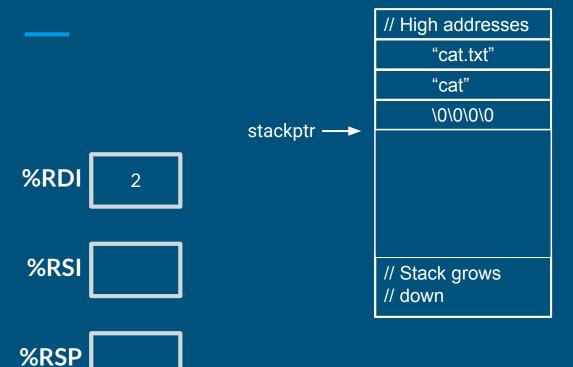
"cat cat.txt"

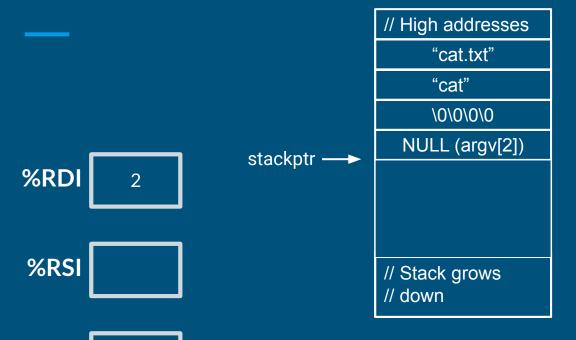




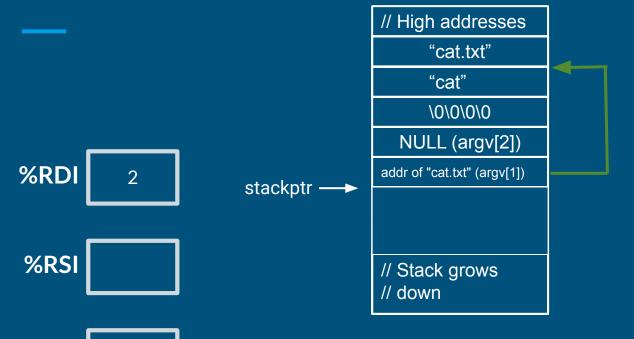




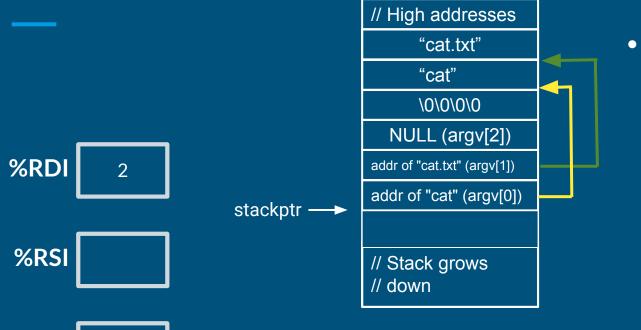




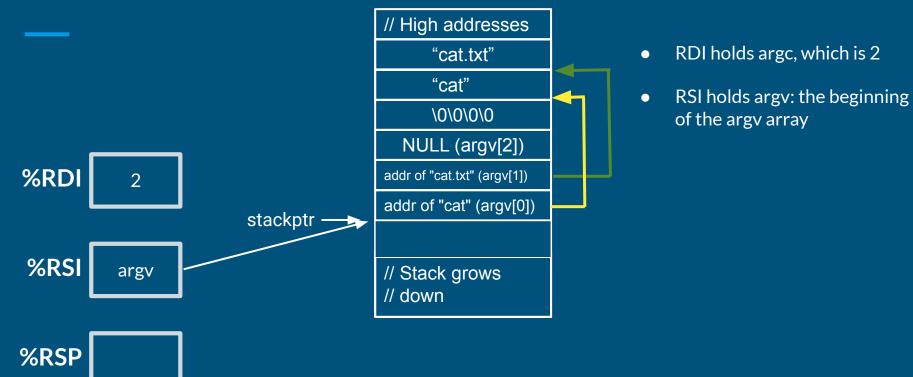
%RSP

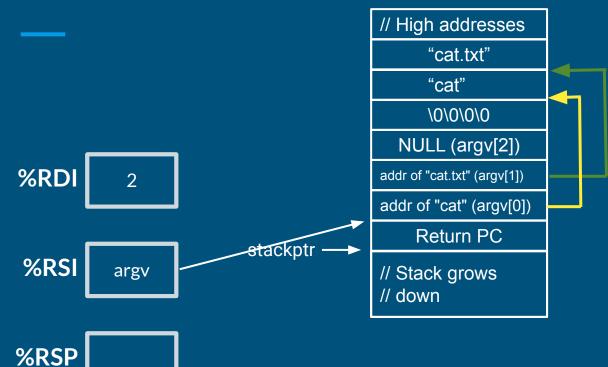


%RSP

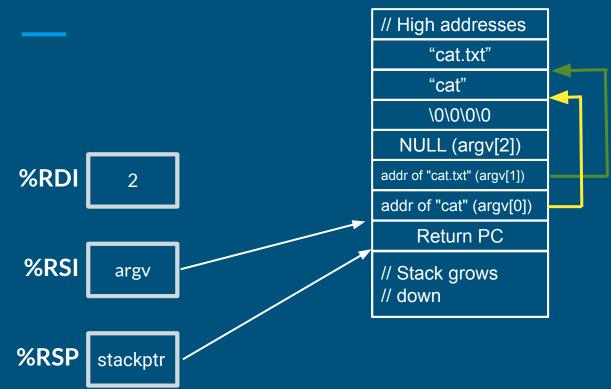


%RSP



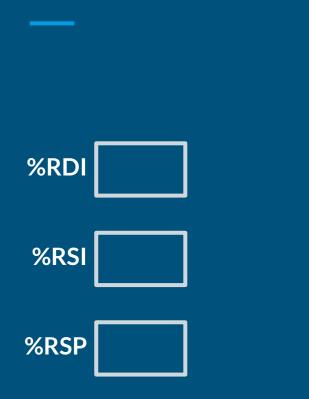


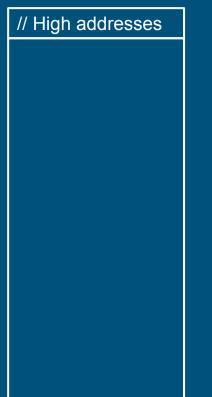
- RDI holds argc, which is 2
- RSI holds argv: the beginning of the argv array
- The specific value of the return PC doesn't matter (program exits from main without returning)



- RDI holds argc, which is 2
- RSI holds argv: the beginning of the argv array
- The specific value of the return PC doesn't matter (program exits from main without returning)
- RSP is properly set to the bottom of the stack.





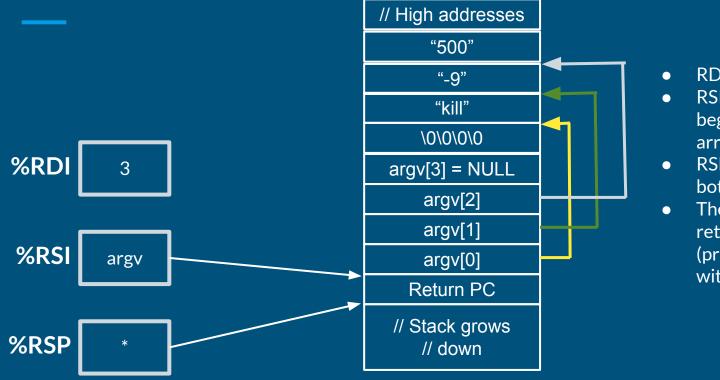


Now it's your turn!

Draw stack layout and determine register values for exec() called with:

"kill -9 500"

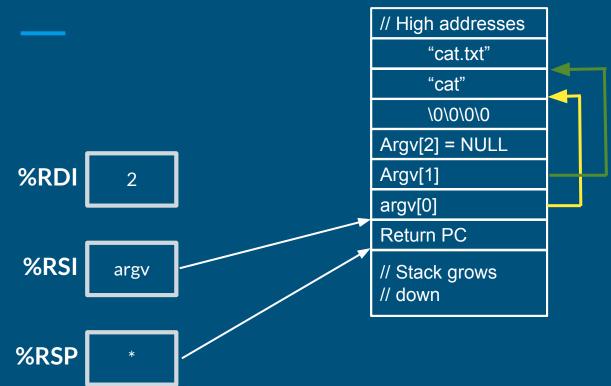
#### Practice Exercise 2: "kill -9 500" Solution



- RDI holds argc, which is 3
- RSI holds argv: the beginning of the argv array
- RSP is properly set to the bottom of the stack.
- The specific value of the return PC doesn't matter (program exits from main without returning)

## Questions?

#### **Practice Exercise 1: Solution**



- RDI holds argc, which is 2
- RSI holds argv: the beginning of the argv array
- RSP is properly set to the bottom of the stack.
- The specific value of the return PC doesn't matter (program exits from main without returning)

### Debugging Tips: Record & Replay

Starting with lab2, there are multiple processes, meaning more concurrent accesses to the kernel code, which might make bugs harder to reproduce.

make qemu-record

record all external events to a log file

helpful if you can record the race condition

make qemu-gdb-replay (pair with make gdb)

replay according to the log file, but with gdb (similar to make qemu-gdb)

Process 1 Status: running Process 2 Status: runnable

Process 1 needs to wait for some condition which depends on process 2.

Process 1 Status: asleep on condvar Process 2 Status: running

Process 1 goes to sleep on some channel related to this condition (doesn't matter what chan is, as long as both processes agree). At some point, Process 2 gets scheduled to run.

Process 1 Status: asleep on condvar

Process 2 did work that Process 1 was waiting for Wake up all processes sleeping on condvar!

Process 2 Status: running

When process 2 finishes its task, it wakes up all processes sleeping on the appropriate channel.

Process 1 Status: runnable Process 2 Status: runnable

Process 1 is set to runnable because of the wake up call.

Process 1 Status: running Process 2 Status: runnable

Process 1 is eventually scheduled to run and can continue its work.

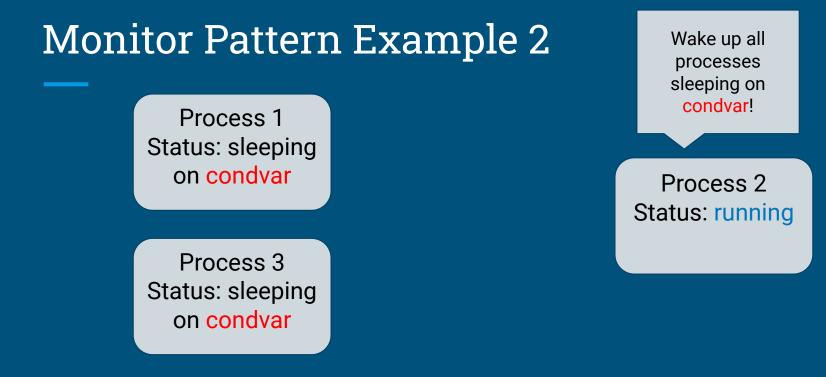
When the process wakes up, it should check the condition and go back to sleep if it's false.

Why?

Process 1 Status: sleeping on condvar

Process 3 Status: sleeping on condvar Process 2 Status: running

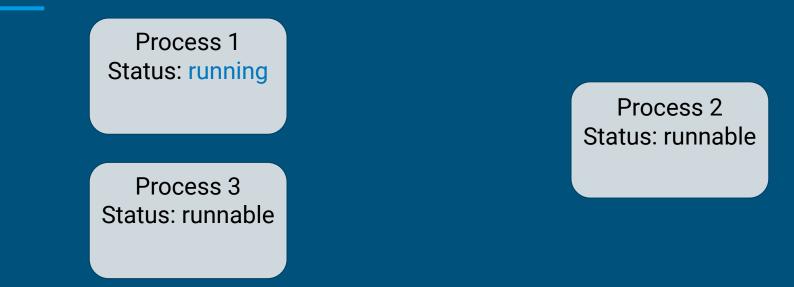
Now, there are 2 processes sleeping on the same channel.



Process 2 wakes up all processes sleeping on the channel.



Both processes are woken up, and the scheduler decides to run Process 1.



What if Process 1 does something that causes the condition to become false again?