

# CSE 451: Operating Systems

## Section 5

### Midterm review

# Kernel/userspace separation

- \* Userspace processes cannot interact directly with hardware (non-privileged mode)
- \* Attempting to execute a system call instruction causes a trap to the kernel (privileged mode), which handles the request
- \* Why is it necessary to have both privileged and non-privileged mode?
- \* How is privileged mode enforced, and how do virtual machine monitors work inside this model?

# IO from userspace

- \* Userspace processes interact with disks and other devices via `open()`, `read()`, `write()`, and other system calls
- \* Multiple levels of abstraction: kernel presents file system to userspace, and device drivers present a (mostly) unified interface to kernel code
  - \* What are the benefits and drawbacks of designing a system in this way?

# Monolithic and microkernels

- \* Monolithic kernels encapsulate all aspects of functionality aside from hardware and user programs
  - \* Pro: Low communication cost, since everything is in the kernel's address space
  - \* Cons: Millions of lines of code, continually expanding, no isolation between modules, security
- \* Microkernels separate functionality into separate modules that each expose an API
  - \* Services as servers
  - \* Why? How?

# Processes versus threads

- \* Processes have multiple pieces of state associated with them
  - \* Program counter, registers, virtual memory, open file handles, mutexes, registered signal handlers, the text and data segment of the program, and so on
  - \* Total isolation, mediated by the kernel
- \* Threads are “lightweight” versions of processes
  - \* Which pieces of state listed above do threads not maintain individually?

# Process creation

- \* `fork()` : create and initialize a new process control block
  - \* Copy resources of current process but assign a new address space
  - \* Calls to `fork()` return twice—once to parent (with pid of child process) and once to child
  - \* What makes this system call fast even for large processes?  
`vfork()` versus copy-on-write
- \* `exec()` : stop the current process and begin execution of a new one
  - \* Existing process image is overwritten
  - \* No new process is created
  - \* Is there a reason why `fork()` and `exec()` are separate system calls?

# Threads

- \* How is a kernel thread different from a userspace thread?
  - \* Kernel thread: managed by OS, can run on a different CPU core than parent process
  - \* Userspace thread: managed by process/thread library, provides concurrency but no parallelism (can't have two userspace threads within a process executing instructions at the same time)
- \* CPU sharing
  - \* Threads share CPU either implicitly (via preemption) or explicitly via calls to `yield()`
  - \* What happens when a userspace thread blocks on IO?

# Synchronization

- \* Critical sections are sequences of instructions that may produce incorrect behavior if two threads interleave or execute them at the same time
  - \* E.g. the banking example that everyone loves to use
- \* Mutexes are constructs that enforce mutual exclusion
  - \* `mutex.lock() / acquire()`: wait until no other thread holds the lock and then acquire it
  - \* `mutex.unlock() / release()`: release the Locken!
  - \* Mutexes rely on hardware support such as an atomic test-and-set instruction or being able to disable interrupts (why?)



# Synchronization constructs

- \* Spinlocks are mutexes where `lock()` spins in a loop until the lock can be acquired
  - \* High CPU overhead, but no expensive context switches are necessary
  - \* In what type of scenario are spinlocks useful?
- \* Semaphores are counters that support atomic increments and decrements
  - \* `P(sem)`: block until semaphore count is positive, then decrement and continue
  - \* `V(sem)`: increment semaphore count
  - \* How are semaphores different from spinlocks?

# Synchronization constructs

- \* Condition variables associated with mutexes allow threads to wait for events and to signal when they have occurred
  - \* `cv.wait(mutex* m)`: release mutex `m` and block until the condition variable `cv` is signaled. `m` will be held when `wait()` returns
  - \* `cv.signal()`: unblock one of the waiting threads. `m` must be held during the call but released sometime afterward
  - \* Why is it necessary to associate a mutex with a condition variable?
  - \* What happens if `signal()` is invoked before a call to `wait()`?

# Monitors

- \* Monitors are souped-up condition variables that support `enter()`, `exit()`, `wait()`, `signal()`, `broadcast()` routines
- \* When one thread enters a monitor, no other thread can enter until the first thread exits
- \* The exception is that a thread can wait on a condition after entering a monitor, permitting another thread to enter (which will potentially signal and unblock the first thread)
  - \* Hoare monitors: `signal()` causes a waiting thread to run immediately
  - \* Mesa monitors: `signal()` returns to the caller and a waiting thread will unblock some time later

# Deadlock

\* Is this deadlock? How do we fix it?

Thread 1:

lock(A)

lock(B)

Do\_thing1()

unlock(B)

unlock(A)

Thread 2:

lock(B)

lock(C)

Do\_thing2()

unlock(C)

unlock(B)

Thread 3:

lock(C)

lock(A)

Do\_thing3()

unlock(A)

unlock(C)

# Deadlock

- \* What is an example of deadlock?
- \* Methods for preventing and avoiding deadlock
  - \* Have threads block until all required locks are available
  - \* Have all threads acquire locks in the same global ordering
  - \* Run banker's algorithm to simulate what would happen if this thread and others made maximum requests: no deadlock = continue, deadlock = block and check again later
- \* Can resolve deadlock by breaking cycles in the dependency graph: choose a thread, kill it, and release its locks
  - \* What are the potential problems related to doing this?

# Scheduling

- \* Operating systems share CPU time between processes by context-switching between them
  - \* In systems that support preemption, each process runs for a certain quantum (time slice) before the OS switches contexts to another process
  - \* Which process runs next depends on the scheduling policy
- \* Scheduling policies can attempt to maximize CPU utilization or throughput or minimize response time, for example
  - \* There are always tradeoffs between performance and fairness

# Scheduling policies

- \* FIFO: first in first out
- \* SPT: shortest processing time first
- \* RR: round robin
- \* Any of these can be combined with a notion of Priority
  - \* How to avoid starvation? Lottery is one option
- \* What are the benefits and drawbacks of each type of scheduling policy?