Logistic regression

Solution of the logistic

functional

selation blun

Classification: multi class



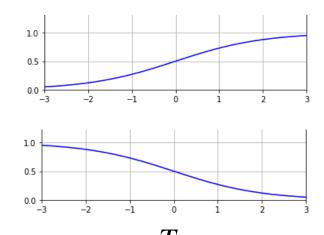
Probabilistic interpretation of logistic regression

- just as Maximum Likelihood Estimator (MLE) under linear model and additive Gaussian noise model recovers linear least squares,
- we study a particular noise model that recovers logistic regression as MLE
- a probabilistic noise model for Binary labels:

$$\mathbb{P}(y_i = +1 \mid x_i) = \frac{1}{1 + e^{-w^T x_i}}$$

$$\mathbb{P}(y_i = -1 \,|\, x_i) = \frac{1}{1 + e^{w^T x_i}}$$

with a ground truth model parameter $w \in \mathbb{R}^d$



- this function $\sigma(z)=\frac{1}{1+e^{-z}}$ is called a **logistic function** (not to be confused with logistic loss, which is different) or a **sigmoid function**
- if we know that the data came from such a model, but do not know the ground truth parameter $w \in \mathbb{R}^d$, we can apply MLE to find the best w
- this MLE recovers the logistic regression algorithm, exactly

Maximum Likelihood Estimator (MLE)

if the data came from a probabilistic model model:
$$\underbrace{(\underbrace{\frac{1}{1+e^{-w^Tx}}}_{\mathbb{P}(y_i=+1|x_i)},\underbrace{\frac{1}{1+e^{w^Tx}}}_{\mathbb{P}(y_i=-1|x_i)})$$

log-likelihood of observing a data point (x_i, y_i) is

$$\log\text{-likelihood} = \log\left(\mathbb{P}(y_i|x_i)\right) = \begin{cases} \log\left(\frac{1}{1+e^{-w^Tx_i}}\right) & \text{if } y_i = +1\\ \log\left(\frac{1}{1+e^{w^Tx_i}}\right) & \text{if } y_i = -1 \end{cases}$$

Maximum Likelihood Estimator is the one that maximizes the sum of all loglikelihoods on training data points

$$\hat{w}_{\text{MLE}} = \arg\max_{w} \mathbb{P}(\{y_1, ..., y_n\} \mid \{x_1, ..., x_n\})$$

$$= \arg\max_{w} \prod_{i=1}^{n} \mathbb{P}(y_i \mid x_i)$$

$$= \arg\max_{w} \sum_{i:y_i=-1} \log\left(\frac{1}{1 + e^{w^T x_i}}\right) + \sum_{i:y_i=1} \log\left(\frac{1}{1 + e^{-w^T x_i}}\right)$$
 (substitution)

notice that this is exactly the logistic regression:

$$\hat{w}_{\text{logistic}} = \arg\min_{w} \frac{1}{n} \left(\sum_{i:y_i = -1} \log(1 + e^{w^T x_i}) + \sum_{i:y_i = 1} \log(1 + e^{-w^T x_i}) \right)$$

• once we have trained a model $\hat{w}_{\text{logistic}}$, we can make a hard prediction \hat{v} of the label at an input example x

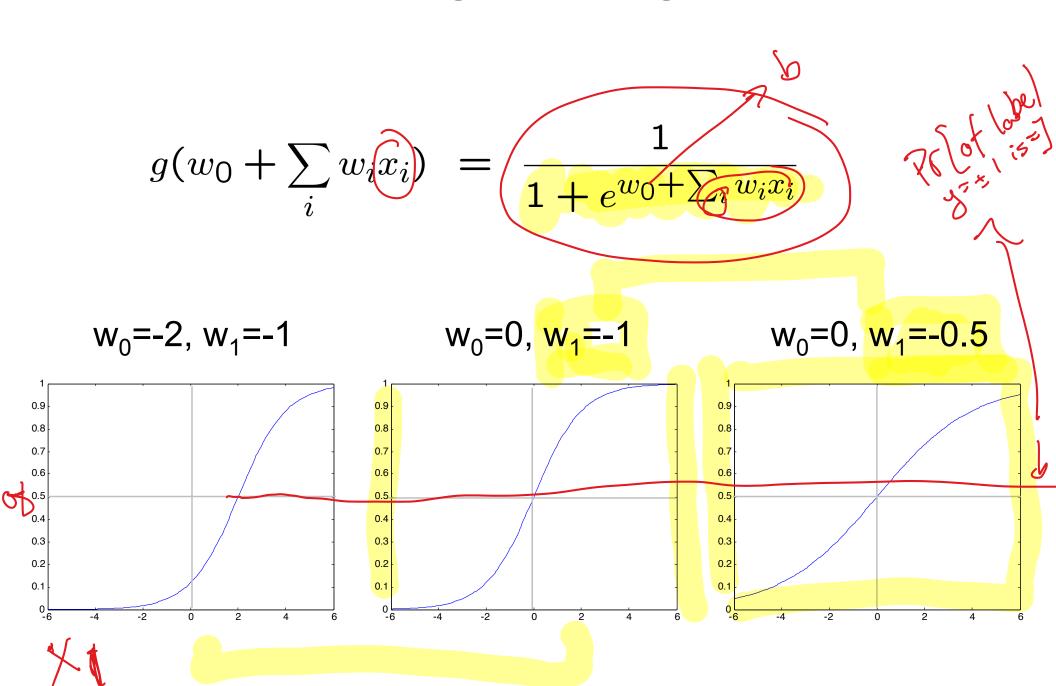
$$\hat{v} = \begin{cases} +1 & \text{if } \mathbb{P}(+1|x) \ge \mathbb{P}(-1|x) \\ -1 & \text{otherwise} \end{cases}$$

$$= \begin{cases} +1 & \text{if } \frac{1}{1+e^{-w^T x}} \ge \frac{1}{1+e^{w^T x}} \\ -1 & \text{otherwise} \end{cases}$$

$$= \begin{cases} +1 & \text{if } 1 \le e^{2w^T x} \\ -1 & \text{otherwise} \end{cases}$$

$$= \operatorname{sign}(w^T x)$$

Understanding the sigmoid



Multi-class regression

How do we encode categorical data y?

so far, we considered Binary case where there are two categories

encoding y is simple: {+1,-1}



- taking values in $C = \{c_1, ..., c_k\}$
- c_i 's are called classes or labels
- examples:





Zipcode (10005, 98195,...)

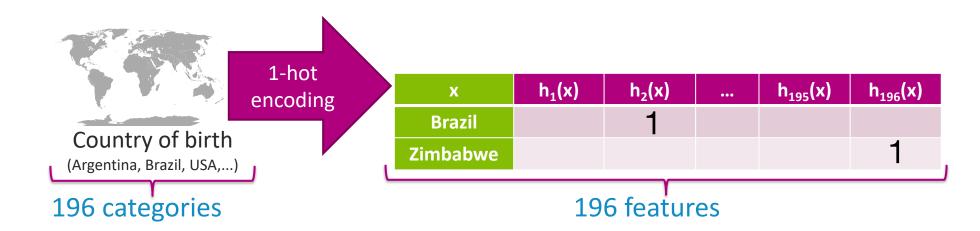
All English words

• a **k-class classifier** predicts *y* given *x*

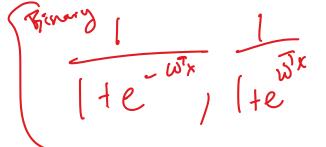
label of
$$7$$
 $y_{\xi} = (0.0000010)$

Embedding c_i 's in real values

- for optimization we need to embed raw categorical c_j 's into real valued vectors
- there are many ways to embed categorial data
 - True->1, False->-1
 - Yes->1, Maybe->0, No->-1
 - Yes->(1,0), Maybe->(0,0), No->(0,1)
 - Apple->(1,0,0), Orange->(0,1,0), Banana->(0,0,1)
 - Ordered sequence: (Horse 3, Horse 1, Horse 2) -> (3,1,2)
- we use one-hot embedding (a.k.a. one-hot encoding)
 - each class is a standard basis vector in k—dimension



Multi-class logistic regression



data: categorical y in $\{c_1, ..., c_k\}$ with k categories

we use one-hot encoding, s.t.
$$y = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \\ 0 \end{bmatrix}$$
 implies that $y = c_1$

model: linear vector-function makes a linear prediction $\hat{\mathbf{y}} \in \mathbb{R}^k$

$$\hat{y}_i = f(x_i) = w^T x_i \in \mathbb{R}^k$$

with model parameter matrix $w \in \mathbb{R}^{d \times k}$ and sample $x_i \in \mathbb{R}^d$

$$f(x_i) = \begin{bmatrix} f_1(x_i) \\ f_2(x_i) \\ \vdots \\ f_k(x_i) \end{bmatrix} = \underbrace{\begin{bmatrix} w_{1,0} & w_{1,1} & w_{1,2} & \cdots \\ w_{2,0} & w_{2,1} & w_{2,2} & \cdots \\ \vdots & & & & \\ w_{k,0} & w_{k,1} & w_{k,2} & \cdots \end{bmatrix}}_{w^T} \underbrace{\begin{bmatrix} 1 \\ x_i[1] \\ \vdots \\ x_i[d] \end{bmatrix}}_{x_i} = \begin{bmatrix} w_{1,0} + w_{1,1}x_i[1] + w_{1,2}x_i[2] + \cdots \\ w_{2,0} + w_{2,1}x_i[1] + w_{2,2}x_i[2] + \cdots \\ \vdots & & & \\ w_{k,0} + w_{k,1}x_i[1] + w_{k,2}x_i[2] + \cdots \end{bmatrix}}_{w^T}$$

$$w = [w[:,1] \ w[:,2] \ \cdots \ w[:,k]]$$

Logistic regression

2 classes

$$\mathbb{P}(y_i = -1 \mid x_i) = \frac{1}{1 + e^{w^T x_i}}$$

$$\mathbb{P}(y_i = +1 \mid x_i) = \frac{1}{1 + e^{-w^T x_i}} = \frac{e^{w^T x_i}}{1 + e^{w^T x_i}}$$

$$\mathbb{P}(y_{i} = c_{1} | x_{i}) = \frac{e^{w[:,1]^{T}x_{i}}}{e^{w[:,1]^{T}x_{i}} + \dots + e^{w[:,k]^{T}x_{i}}}$$

$$\mathbb{P}(y_{i} = c_{k} | x_{i}) = \frac{e^{w[:,1]^{T}x_{i}} + \dots + e^{w[:,k]^{T}x_{i}}}{e^{w[:,1]^{T}x_{i}} + \dots + e^{w[:,k]^{T}x_{i}}}$$

Without loss of generality setting w[:,1]=0 when
$$k=2$$
 recovers the original binary class case

Maximum Likelihood Estimator

$$\text{maximize}_{w} \ \frac{1}{n} \sum_{i=1}^{n} \log(\mathbb{P}(y_i | x_i))$$

$$\text{maximize}_{w \in \mathbb{R}^d} \ \frac{1}{n} \sum_{i=1}^{n} \log \left(\frac{1}{1 + e^{-y_i w^T x_i}} \right)$$

$$\text{maximize}_{w \in \mathbb{R}^d} \ \frac{1}{n} \sum_{i=1}^n \log \left(\frac{1}{1 + e^{-y_i w^T x_i}} \right) \qquad \text{maximize}_{w \in \mathbb{R}^{d \times k}} \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^k \mathbf{I}\{y_i = c_j\} \log \left(\frac{e^{w[:,j]^T x_i}}{\sum_{j'=1}^k e^{w[:,j']^T x_i}} \right)$$

$$I{y_i = j}$$
 is an indicator that is one only if $y_i = j$

Linear classification

- > **Learn**: f:**X** —>Y
 - X features
 - Y target classes $Y \in \{-1, 1\}$
- > Expected loss of f:

>

Loss function:

$$\ell(f(x), y) = \mathbf{1}\{f(x) \neq y\}$$

$$\mathbb{E}_{XY}[\mathbf{1}\{f(X) \neq Y\}] = \mathbb{E}_X[\mathbb{E}_{Y|X}[\mathbf{1}\{f(x) \neq Y\}|X = x]]$$

$$\mathbb{E}_{Y|X}[\mathbf{1}\{f(x) \neq Y\}|X = x] = 1 - P(Y = f(x)|X = x)$$

- > Bayes optimal classifier:
- > Model of logistic regression:

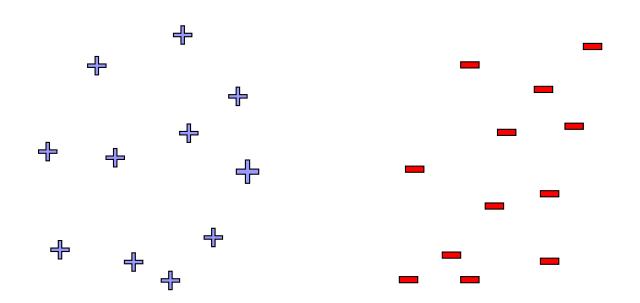
$$f(x) = \arg\max_{y} \mathbb{P}(Y = y|X = x)$$

$$P(Y = y|x, w) = \frac{1}{1 + \exp(-y \, w^T x)}$$

What if the model is wrong?

Binary Classification

- > Perceptron guaranteed to converge if
 - Data linearly separable:



Can we do classification without a model of $\mathbb{P}(Y = y | X = x)$?

The Perceptron Algorithm [Rosenblatt '58, '62]

- > Classification setting: y in {-1,+1}
- **Linear model**
 - Prediction:
- > Training:
 - **Initialize weight vector:**
 - At each time step:
 - > Observe features:
 - > Make prediction:
 - > Observe true class:
 - > Update model:
 - If prediction is not equal to truth

The Perceptron Algorithm [Rosenblatt '58, '62]

- > Classification setting: y in {-1,+1}
- > Linear model $sign(w^T x_i + b)$
 - **Prediction:**
- > Training:

$$w_0 = 0, b_0 = 0$$

- Initialize weight vector:
- At each time step: x_k

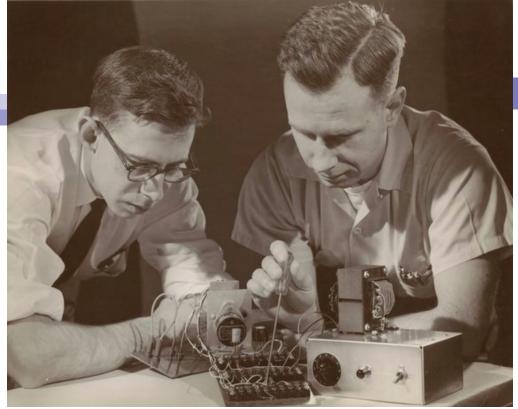
 $\operatorname{sign}(x_k^T w_k + b_k)$ > Observe features:

> Make prediction:

 y_k > Observe true class:

- > Update model:
 - If prediction is not equal to truth

$$\begin{bmatrix} w_{k+1} \\ b_{k+1} \end{bmatrix} = \begin{bmatrix} w_k \\ b_k \end{bmatrix} + y_k \begin{bmatrix} x_k \\ 1 \end{bmatrix}$$



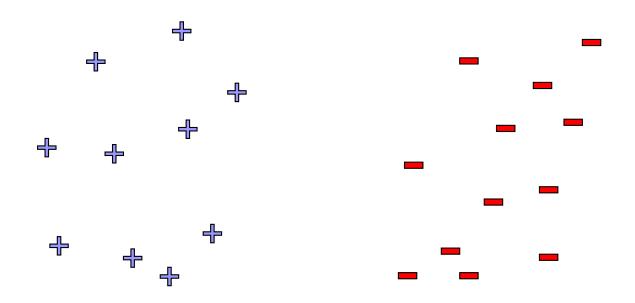


Rosenblatt 1957

"the embryo of an electronic computer that [the Navy] expects will be able to walk, talk, see, write, reproduce itself and be conscious of its existence."

The New York Times, 1958

Linear Separability



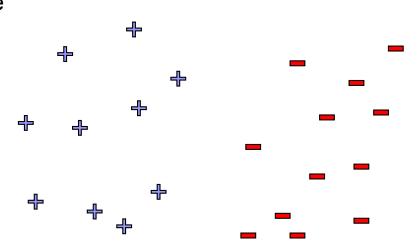
- Perceptron guaranteed to converge if
 - Data linearly separable:

Perceptron Analysis: Linearly Separable Case

- Theorem [Block, Novikoff]:
 - □ Given a sequence of labeled examples:
 - Each feature vector has bounded norm:
 - If dataset is linearly separable:
- Then the number of mistakes made by the online perceptron on any such sequence is bounded by

Beyond Linearly Separable Case

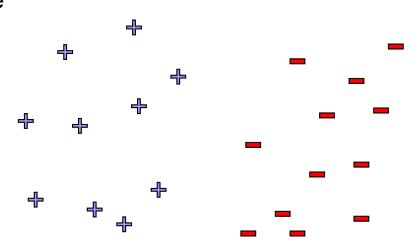
- Perceptron algorithm is super cool!
 - No assumption about data distribution!
 - Could be generated by an oblivious adversary, no need to be iid
 - Makes a fixed number of mistakes, and it's done for ever!
 - Even if you see infinite data



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Beyond Linearly Separable Case

- Perceptron algorithm is super cool!
 - No assumption about data distribution!
 - Could be generated by an oblivious adversary, no need to be iid
 - Makes a fixed number of mistakes, and it's done for ever!
 - Even if you see infinite data
- Perceptron is useless in practice!
 - Real world not linearly separable
 - If data not separable, cycles forever and hard to detect
 - Even if separable may not give good generalization accuracy (small margin)



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What is the Perceptron Doing???

- When we discussed logistic regression:
 - Started from maximizing conditional log-likelihood

- When we discussed the Perceptron:
 - Started from description of an algorithm

What is the Perceptron optimizing????

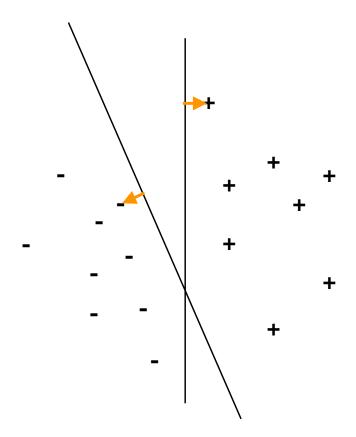
Lecture 16: Support Vector Machines

- how do we choose a better classifier?



How do we choose the best linear classifier?

- informally, margin of a set of examples to a decision boundary is the distance to the closest point to the decision boundary
- for linearly separable datasets, maximum margin classifier is a natural choice
- large margin implies that the decision boundary can change without losing accuracy, so the learned model is more robust against new data points



Geometric margin

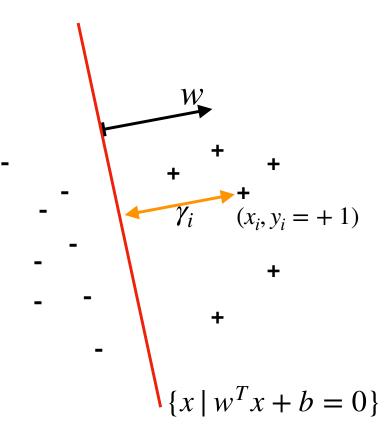
- given a set of training examples $\{(x_i, y_i)\}_{i=1}^n$, with $y_i \in \{-1, +1\}$
- and a linear classifier $(w, b) \in \mathbb{R}^d \times \mathbb{R}$
- such that the decision boundary is a separating hyperplane $\{x \mid b+w_1x[1]+w_2x[2]+\cdots+w_dx[d]=0\}$,

which is the set of points that are orthogonal to $w^{T}x+b$

• we define **functional margin** of (b, w) with respect to a training example (x_i, y_i) as the distance from the point (x_i, y_i) to the decision boundary, which is

$$\gamma_i = y_i \frac{(w^T x_i + b)}{\|w\|_2}$$

(The proof is on the next slide)



Geometric margin

- the distance γ_i from a hyperplane $\{x \mid w^T x + b = 0\}$ to a point x_i can be computed geometrically as follows
- We know that if you move from x_i in the negative direction of w by length γ_i , you arrive at the line, which can be written as

$$\left(x_i - \frac{w}{\|w\|_2} \gamma_i\right)$$
 is in $\{x \mid w^T x + b = 0\}$

so we can plug the point in the formula:

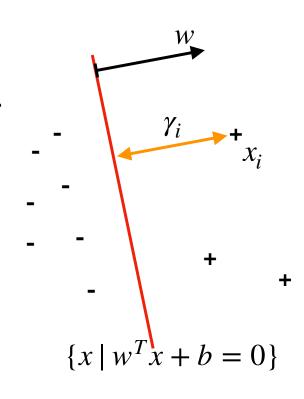
$$w^{T}\left(x_{i} - \frac{w}{\|w\|_{2}}\gamma_{i}\right) + b = 0$$

which is

$$w^{T} x_{i} - \frac{\|w\|_{2}^{2}}{\|w\|_{2}} \gamma_{i} + b = 0$$
 and hence

$$\gamma_i = \frac{w^T x_i + b}{\|w\|_2},$$

and we multiply it by y_i so that for negative samples we use the opposite direction of -w instead of w

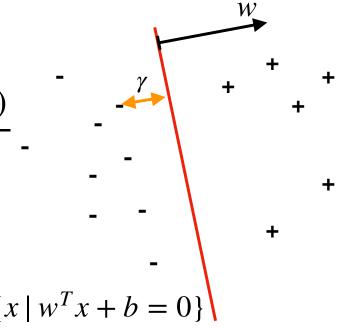


Geometric margin

 the margin with respect to a set is defined as

$$\gamma = \min_{i \in \{1, ..., n\}} \gamma_i = \min_i y_i \frac{(w^T x_i + b)}{\|w\|_2}.$$

 among all linear classifiers, we would like to find one that has the maximum margin



 We will derive an algorithm that finds the maximum margin classifier, by transforming a difficult to solve optimization into an efficient one

Maximum margin classifier

(we transform the optimization into an efficient one)

we propose the following optimization problem:

- if we fix (w, b), the optimal solution of the optimization is the margin
- together with (w, b), this finds the classifier with the maximum margin
- note that this problem is **scale invariant** in (w,b), i.e. changing a (w,b) to (2w,2b) does not change either the feasibility or the objective value, hence the following reparametrization is valid
- the above optimization looks difficult, so we transform it using **reparametrization**

• Because of scale invariance, the optimal solution does not change, as the solutions to the original problem did not depend on $||w||_2$, and only depends on the direction of w

• $\max_{w \in \mathbb{R}^d, b \in \mathbb{R}, \gamma \in \mathbb{R}} \gamma$

subject to
$$\frac{y_i(w^Tx_i+b)}{\|w\|_2} \geq \gamma \text{ for all } i \in \{1,\ldots,n\}$$

$$\|w\|_2 = \frac{1}{\gamma}$$

• the above optimization still looks difficult, but can be transformed into

$$\max_{w \in \mathbb{R}^d, b \in \mathbb{R}} \quad \frac{1}{\|w\|_2}$$
 (maximize the margin)

subject to
$$\frac{y_i(w^Tx_i+b)}{\|w\|_2} \geq \frac{1}{\|w\|_2}$$
 for all $i \in \{1,\ldots,n\}$ (now $\frac{1}{\|w\|_2}$ plays the role of a lower bound on the margin)

which simplifies to

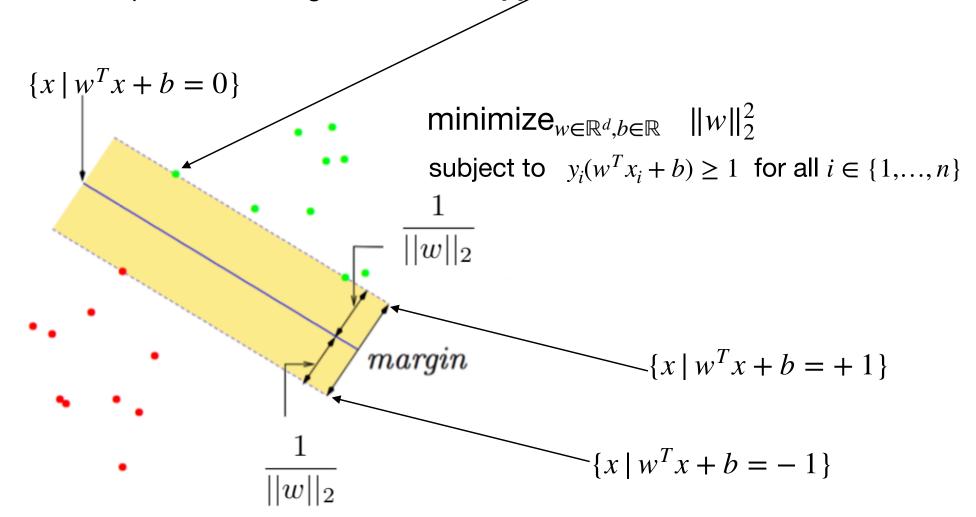
minimize
$$_{w \in \mathbb{R}^d, b \in \mathbb{R}} \|w\|_2^2$$

subject to $y_i(w^Tx_i + b) \ge 1$ for all $i \in \{1, ..., n\}$

- this is a quadratic program with linear constraints, which can be easily solved
- once the optimal solution is found, the margin of that classifier (w,b) is $\frac{1}{\|w\|_2}$

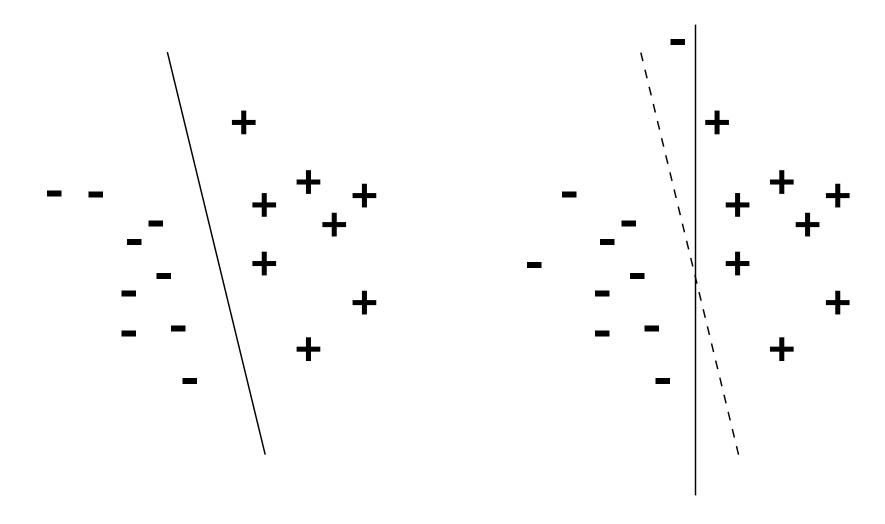
What if the data is not separable?

- we cheated a little in the sense that the reparametrization of $\|w\|_2 = \frac{1}{\gamma}$ is possible only if the the margins are positive, i.e. the data is linearly separable with a positive margin
- otherwise, there is no feasible solution
- the examples at the margin are called support vectors

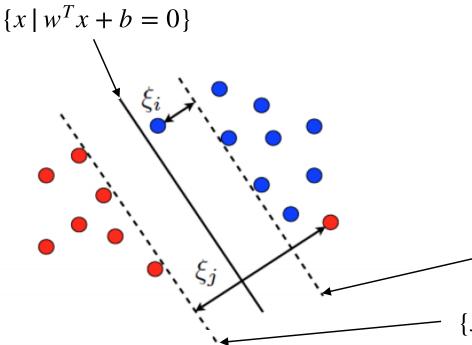


Two issues

- it does not generalize to non-separable datasets
- max-margin formulation we proposed is sensitive to outliers



What if the data is not separable?



 we introduce slack so that some points can violate the margin condition

$$y_i(w^T x_i + b) \ge 1 - \xi_i$$

$$\{x \mid w^T x + b = +1\}$$

$$\{x \mid w^T x + b = -1\}$$

• this gives a new optimization problem with some positive constant $c \in \mathbb{R}$

$$\operatorname{minimize}_{w \in \mathbb{R}^d, b \in \mathbb{R}, \xi \in \mathbb{R}^n} \quad ||w||_2^2 + c \sum_{i=1}^n \xi_i$$

subject to
$$y_i(w^Tx_i+b) \geq 1-\xi_i$$
 for all $i\in\{1,\ldots,n\}$
$$\xi_i \geq 0 \quad \text{ for all } i\in\{1,\ldots,n\}$$

the (re-scaled) margin (for each sample) is allowed to be less than one, but you pay $c\xi_i$ in the cost, and c balances the two goals: maximizing the margin for most examples vs. having small number of violations

Support Vector Machine

for the optimization problem

$$\text{minimize}_{w \in \mathbb{R}^d, b \in \mathbb{R}, \xi \in \mathbb{R}^n} \quad ||w||_2^2 + c \sum_{i=1}^n \xi_i$$

subject to
$$y_i(w^Tx_i + b) \ge 1 - \xi_i$$
 for all $i \in \{1, ..., n\}$
$$\xi_i \ge 0 \quad \text{ for all } i \in \{1, ..., n\}$$

notice that at optimal solution, ξ_i 's satisfy

- $\xi_i = 0$ if margin is big enough $y_i(w^Tx_i + b) \ge 1$, or
- $\xi_i = 1 y_i(w^Tx_i + b)$, if the example is within the margin $y_i(w^Tx_i + b) < 1$
- so one can write
 - $\xi_i = \max\{0, 1 y_i(w^T x_i + b)\}$, which gives

minimize_{$$w \in \mathbb{R}^d, b \in \mathbb{R}$$} $\frac{1}{c} ||w||_2^2 + \sum_{i=1}^n \max\{0, 1 - y_i(w^T x_i + b)\}$

Sub-gradient descent for SVM

SVM is the solution of

minimize_{$$w \in \mathbb{R}^d, b \in \mathbb{R}$$} $\frac{1}{c} \|w\|_2^2 + \sum_{i=1}^n \max\{0, 1 - y_i(w^T x_i + b)\}$

- as it is non-differentiable, we solve it using sub-gradient descent
- which is exactly the same as gradient descent, except when we are at a non-differentiable point, we take one of the sub-gradients instead of the gradient (recall sub-gradient is a set)
- this means that we can take (a generic form derived from previous page) $\partial_w \mathcal{E}(w^Tx_i+b,y_i) = \mathbf{I}\{y_i(w^Tx_i+b) \leq 1\}(-y_ix_i)$ and apply

$$w^{(t+1)} \leftarrow w^{(t)} - \eta \left(\sum_{i=1}^{n} \mathbf{I} \{ y_i ((w^{(t)})^T x_i + b^{(t)}) \le 1 \} (-y_i x_i) + \frac{2}{c} w^{(t)} \right)$$

$$b^{(t+1)} \leftarrow b^{(t)} - \eta \sum_{i=1}^{n} \mathbf{I} \{ y_i ((w^{(t)})^T x_i + b^{(t)}) \le 1 \} (-y_i)$$