

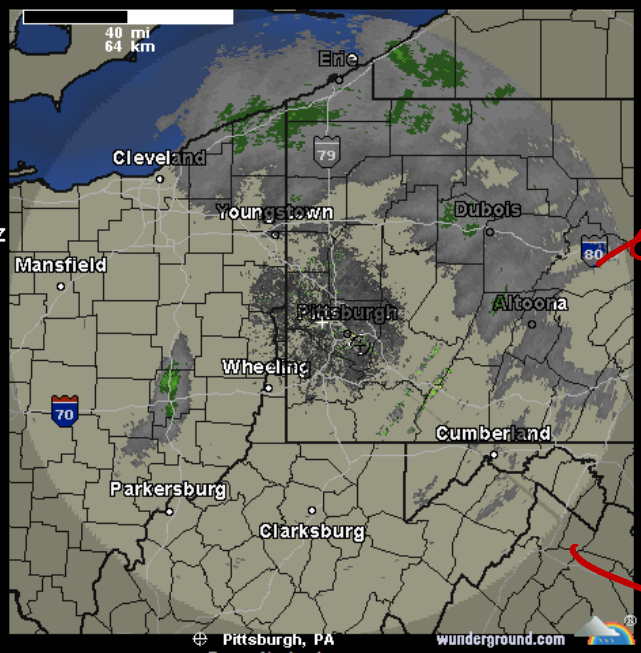
Classification

Logistic Regression

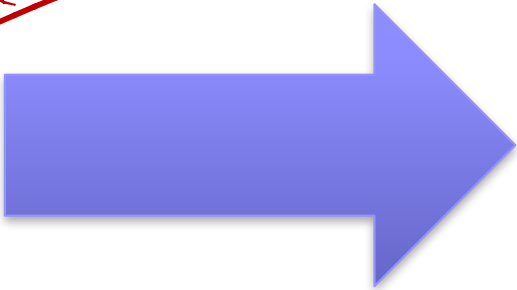
Thus far, regression:

predict a continuous value given some inputs

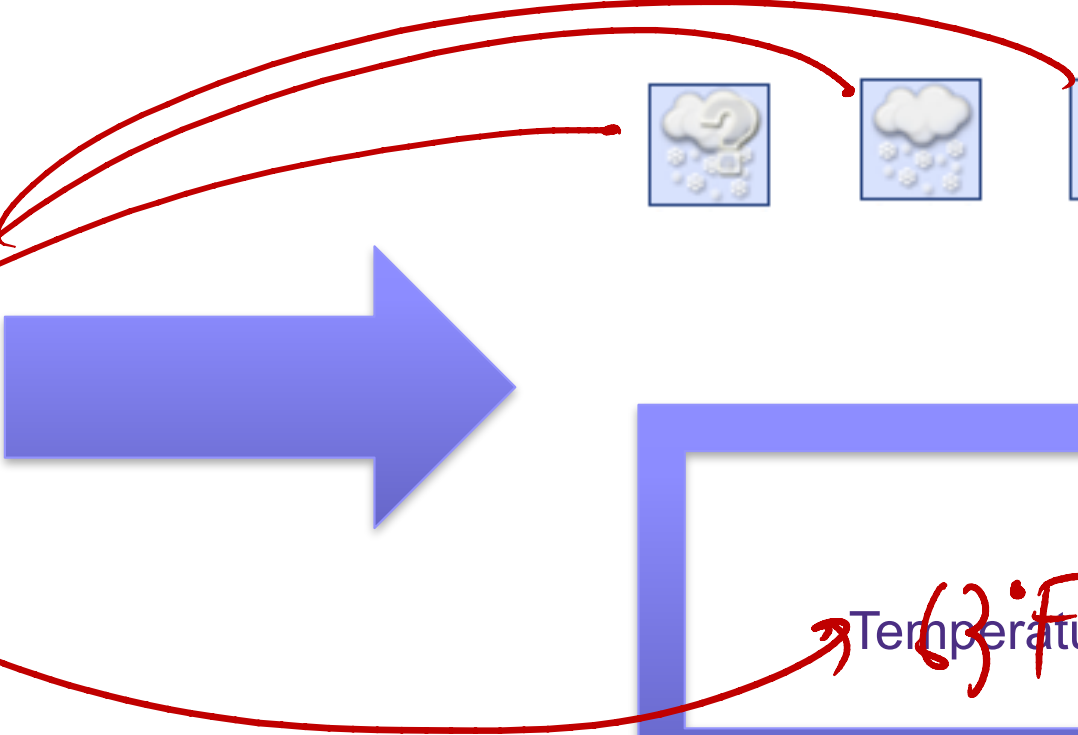
Weather prediction revisited



Classification



Regression



Reading Your Brain, Simple Example

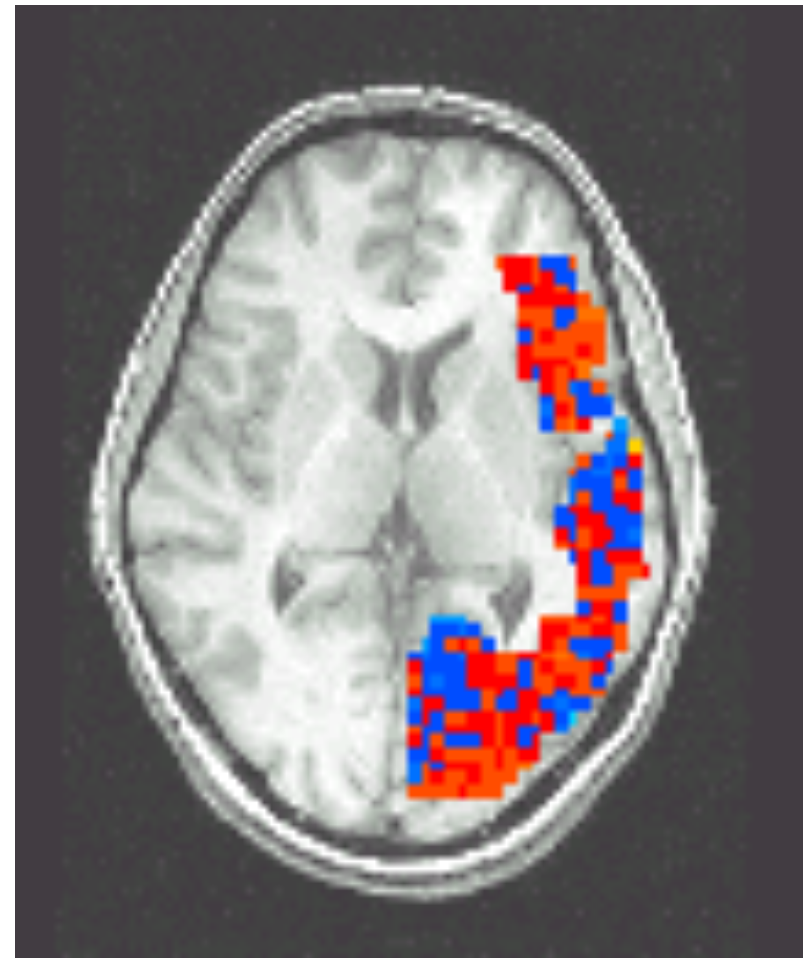
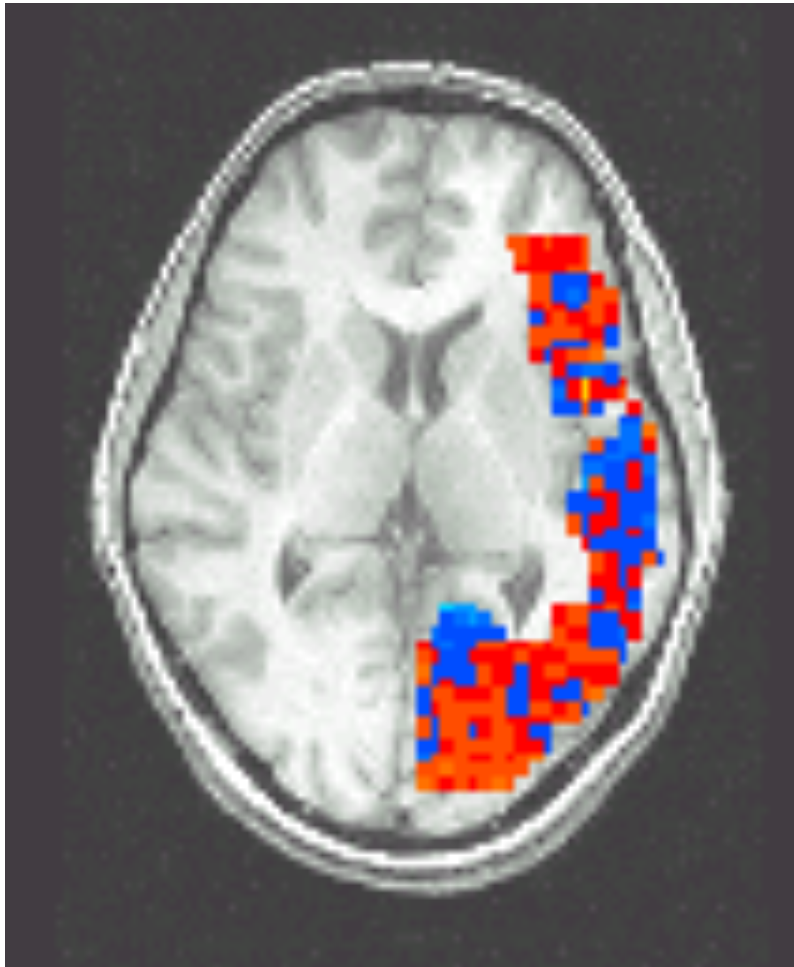
[Mitchell et al.]

Pairwise classification accuracy: 85%

Person



Animal



Classification

$(X, Y) \stackrel{\text{iid}}{\sim} \mathcal{D}$

- Learn $f: \mathcal{X} \rightarrow \mathcal{Y}$
 - $\mathcal{X} \subset \mathbb{R}^d$ - features
 - $\mathcal{Y} = \{1, \dots, k\}$ - target classes

• Loss Function $\ell(f(x), y) = \mathbf{1}\{f(x) \neq y\}$

• Expected loss of f:

$$\begin{aligned} \mathbb{E}_{X, Y} [\ell(f(X), Y)] &= \mathbb{E}_{X, Y} [\mathbf{1}\{f(X) \neq Y\}] \\ &= \mathbb{E}_X \left[\underbrace{\mathbb{E} [\mathbf{1}\{f(X) \neq Y\} \mid X=x]}_{P(f(X) \neq Y \mid X=x)} \right] \end{aligned}$$

Classification

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$$\mathbb{E}_{XY}[\mathbf{1}\{f(X) \neq Y\}] = \mathbb{E}_X[\mathbb{E}_{Y|X}[\mathbf{1}\{f(x) \neq Y\}|X = x]]$$

$$\begin{aligned}\mathbb{E}_{Y|X}[\mathbf{1}\{f(x) \neq Y\}|X = x] &= \sum_i P(Y = i|X = x)\mathbf{1}\{f(x) \neq i\} = \sum_{i \neq f(x)} P(Y = i|X = x) \\ &= 1 - P(Y = f(x)|X = x)\end{aligned}$$

- Suppose you knew $P(Y|X)$ exactly, how should you classify?

Classification

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- Suppose you knew $P(Y|X)$ exactly, how should you classify?
- **Bayes-Optimal classifier:**

$$f(x) = \arg \max_y \mathbb{P}(Y = y|X = x)$$

Bayes Optimal Binary Classifier

- **Bayes-Optimal classifier:** $f(x) = \arg \max_y \mathbb{P}(Y = y | X = x)$
- Suppose we don't know $P(Y = y | X = x)$, but have n iid examples

$$\{(x_i, y_i)\}_{i=1}^n \quad Y \in \{0, 1\}$$

- Suppose \mathcal{X} is discrete so that $X \in \{1, 2, \dots, m\}$. What is a natural estimator for $\underbrace{P(Y = y | X = x)}$?

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What if \mathcal{X} is continuous? That is, what if $X \in \mathbb{R}^d$?

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We need a model to explain observations

Logistic Regression

Recall linear regression:

- We assumed that for any x , we have $p(Y = y | X = x) = \frac{1}{\sqrt{2\pi}} e^{-(y-w^T x)^2/2}$.
- Given data $\{(x_i, y_i)\}_{i=1}^n$ we then computed the MLE for w .

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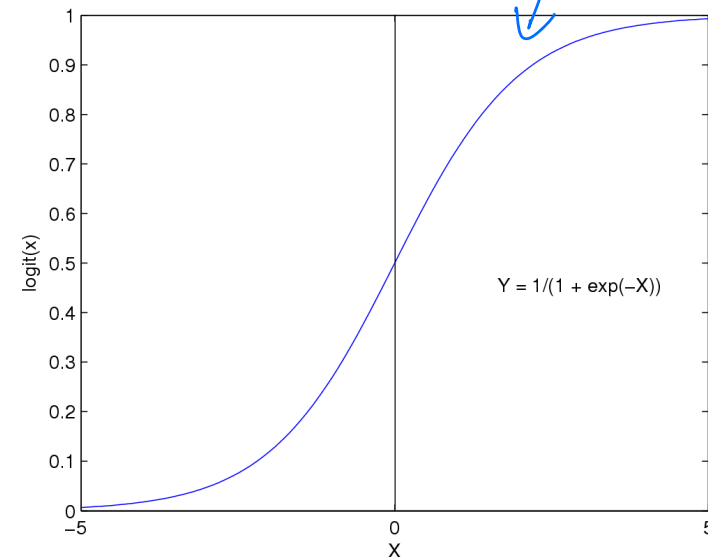
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$$\sigma(z) = \frac{1}{1 + e^{-z}}$$

Logistic regression uses a model specialized for classification:

$$\mathbb{P}[Y = 1 | X = x, w] = \sigma(w^T x) = \frac{1}{1 + \exp(-w^T x)}$$

$$\begin{aligned} \mathbb{P}[Y = 0 | X = x, w] &= 1 - \sigma(w^T x) = \frac{\exp(-w^T x)}{1 + \exp(-w^T x)} \\ &= \frac{1}{1 + \exp(w^T x)} \end{aligned}$$



Logistic Regression

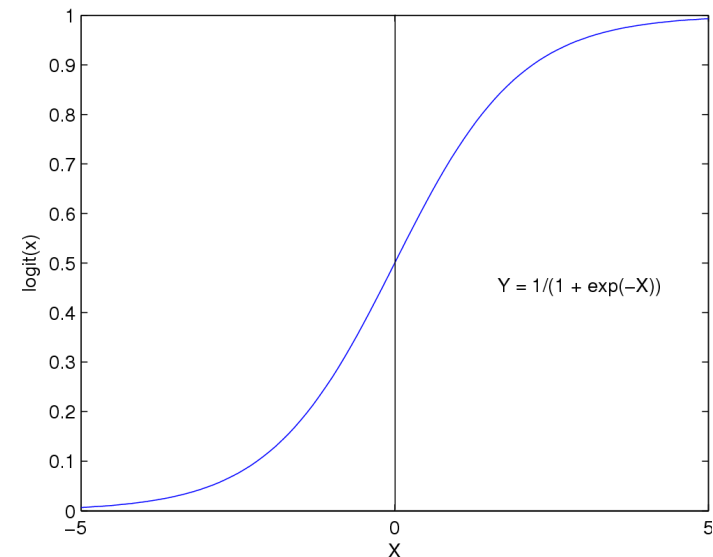
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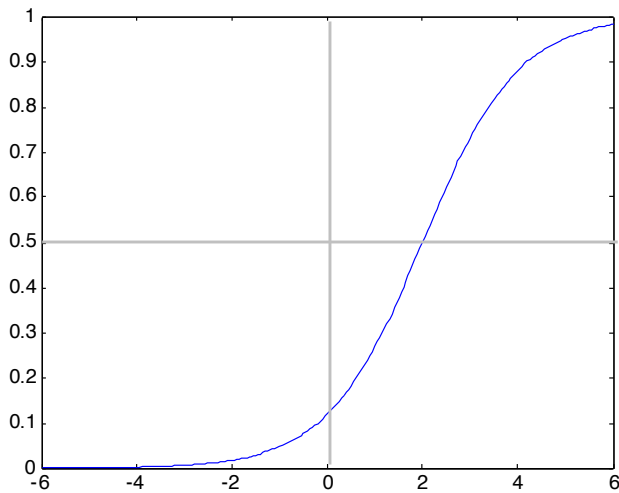


Features can be discrete or continuous!

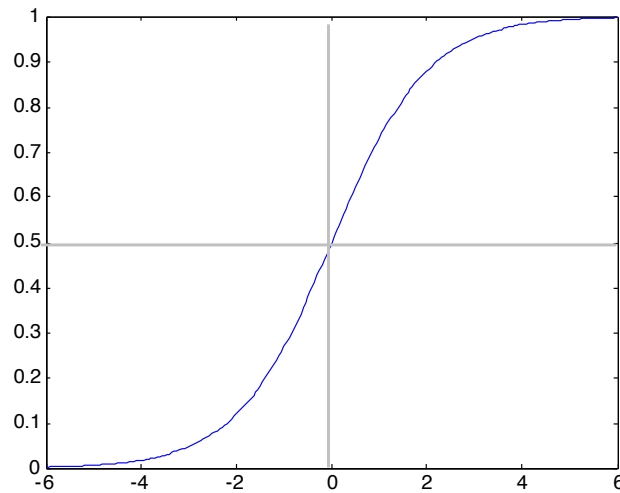
Understanding the sigmoid

$$\sigma(w_0 + \sum_k w_k x_k) = \frac{1}{1 + e^{w_0 + \sum_k w_k x_k}}$$

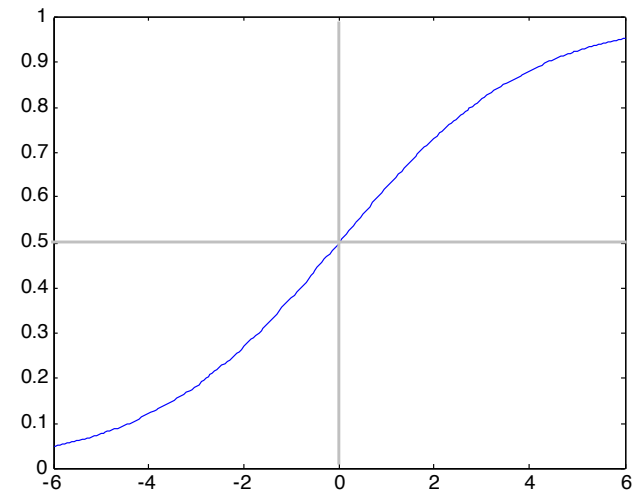
$$w_0 = -2, w_1 = -1$$



$$w_0 = 0, w_1 = -1$$



$$w_0 = 0, w_1 = -0.5$$



Sigmoid for binary classes

$$\mathbb{P}(Y = 0|w, X) = \frac{1}{1 + \exp(w_0 + \sum_k w_k X_k)}$$

$$\mathbb{P}(Y = 1|w, X) = 1 - \mathbb{P}(Y = 0|w, X) = \frac{\exp(w_0 + \sum_k w_k X_k)}{1 + \exp(w_0 + \sum_k w_k X_k)}$$

$$\frac{\mathbb{P}(Y = 1|w, X)}{\mathbb{P}(Y = 0|w, X)} = \exp(w_0 + \sum_n w_n X_n) = \exp(w_0 + w^T X)$$

Sigmoid for binary classes

$$\mathbb{P}(Y = 0|w, X) = \frac{1}{1 + \exp(w_0 + \sum_k w_k X_k)}$$

$$\mathbb{P}(Y = 1|w, X) = 1 - \mathbb{P}(Y = 0|w, X) = \frac{\exp(w_0 + \sum_k w_k X_k)}{1 + \exp(w_0 + \sum_k w_k X_k)}$$

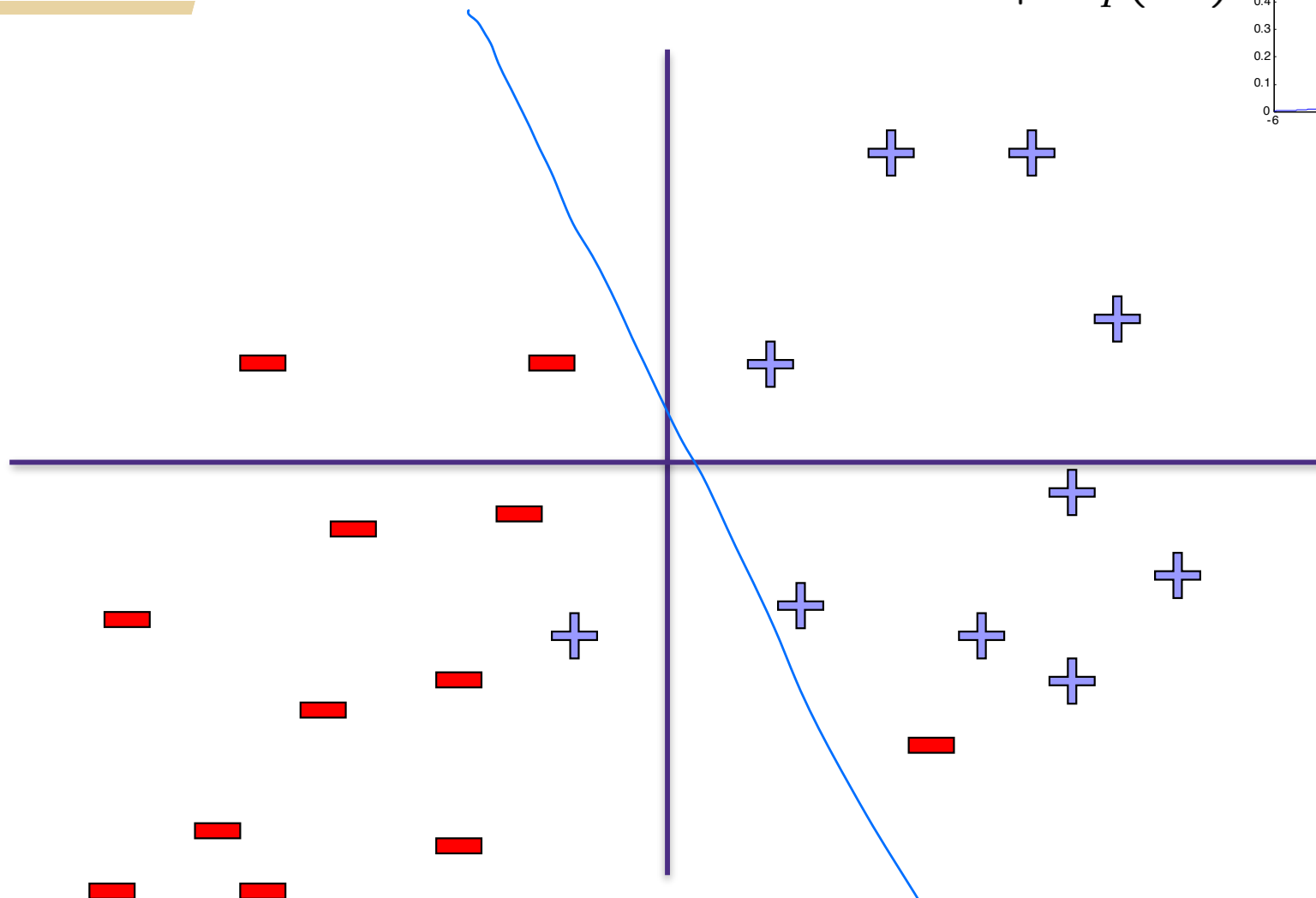
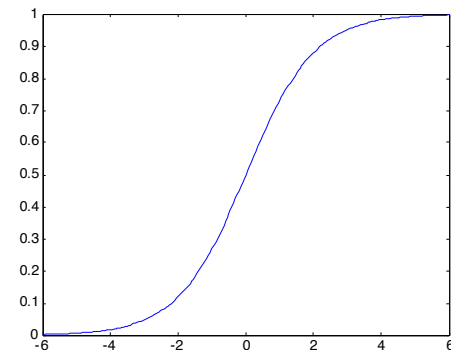
$$\frac{\mathbb{P}(Y = 1|w, X)}{\mathbb{P}(Y = 0|w, X)} = \exp(w_0 + \sum_k w_k X_k)$$

Linear Decision Rule!

$$\log \frac{\mathbb{P}(Y = 1|w, X)}{\mathbb{P}(Y = 0|w, X)} = w_0 + \sum_k w_k X_k$$

Logistic Regression – a Linear classifier

$$\frac{1}{1 + \exp(-z)}$$



$$\ln \frac{P(Y = 0|X)}{P(Y = 1|X)} = w_0 + \sum_i w_i X_i$$

Loss function: Conditional Likelihood

- **Have a bunch of iid data:** $\{(x_i, y_i)\}_{i=1}^n$ $x_i \in \mathbb{R}^d$, $y_i \in \{-1, 1\}$

$$P(Y = -1|x, w) = \frac{1}{1 + \exp(w^T x)}$$

$$P(Y = 1|x, w) = \frac{\exp(w^T x)}{1 + \exp(w^T x)}$$

- **This is equivalent to:**

$$P(Y = y|x, w) = \frac{1}{1 + \exp(-y w^T x)}$$

- **So we can compute the maximum likelihood estimator:**

$$\hat{w}_{MLE} = \arg \max_w \prod_{i=1}^n P(y_i|x_i, w)$$

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$$\begin{aligned}\hat{w}_{MLE} &= \arg \max_w \prod_{i=1}^n P(y_i|x_i, w) \\ &= \arg \min_w \sum_{i=1}^n \log(1 + \exp(-y_i x_i^T w))\end{aligned}$$

Logistic Loss: $\ell_i(w) = \log(1 + \exp(-y_i x_i^T w))$

Squared error Loss: $\ell_i(w) = (y_i - x_i^T w)^2$

(MLE for Gaussian noise)

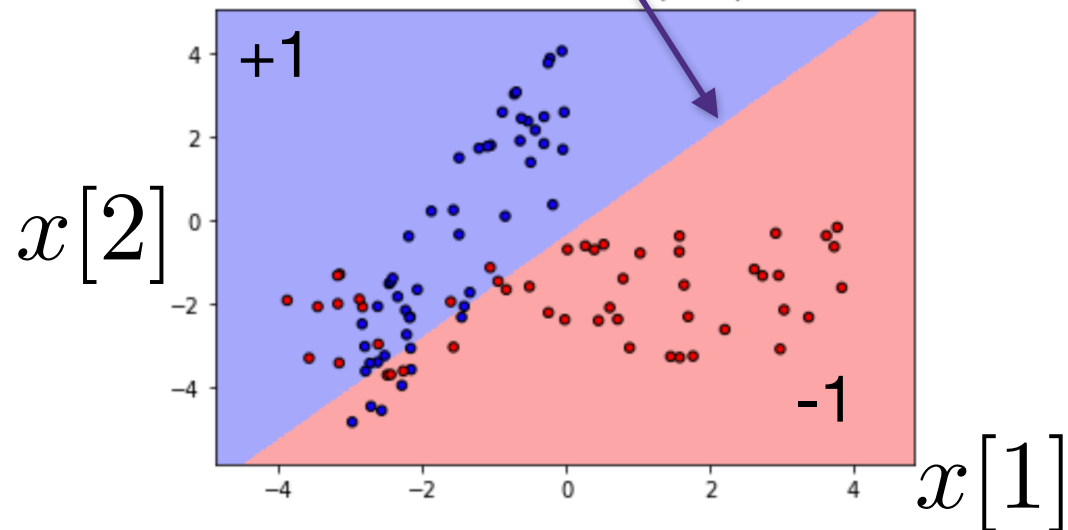
Logistic regression for binary classification

- Data $\mathcal{D} = \{(x_i \in \mathbb{R}^d, y_i \in \{-1, +1\})\}_{i=1}^n$
- Model: $\hat{y} = x^T w + b$
- Loss function: logistic loss $\ell(\hat{y}, y) = \log(1 + e^{-y\hat{y}})$
- Optimization: solve for

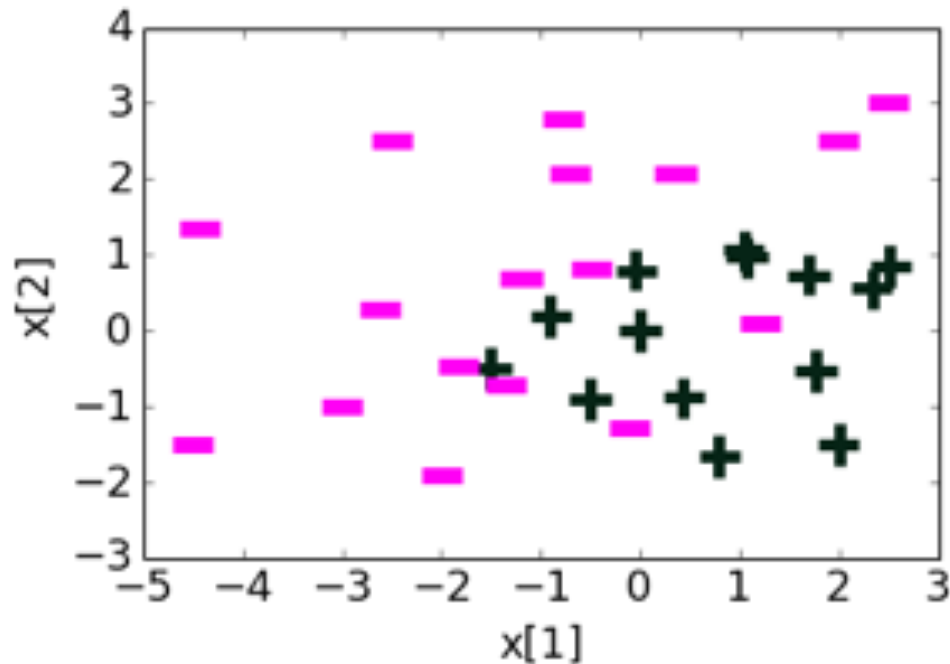
$$(\hat{b}, \hat{w}) = \arg \min_{b, w} \sum_{i=1}^n \log(1 + e^{-y_i(b + x_i^T w)})$$

- As this is a **smooth convex** optimization, it can be solved efficiently using gradient descent
- Prediction: $\text{sign}(b + x^T w)$

decision boundary at $w^T x + b = 0$



Example: adding more polynomial features



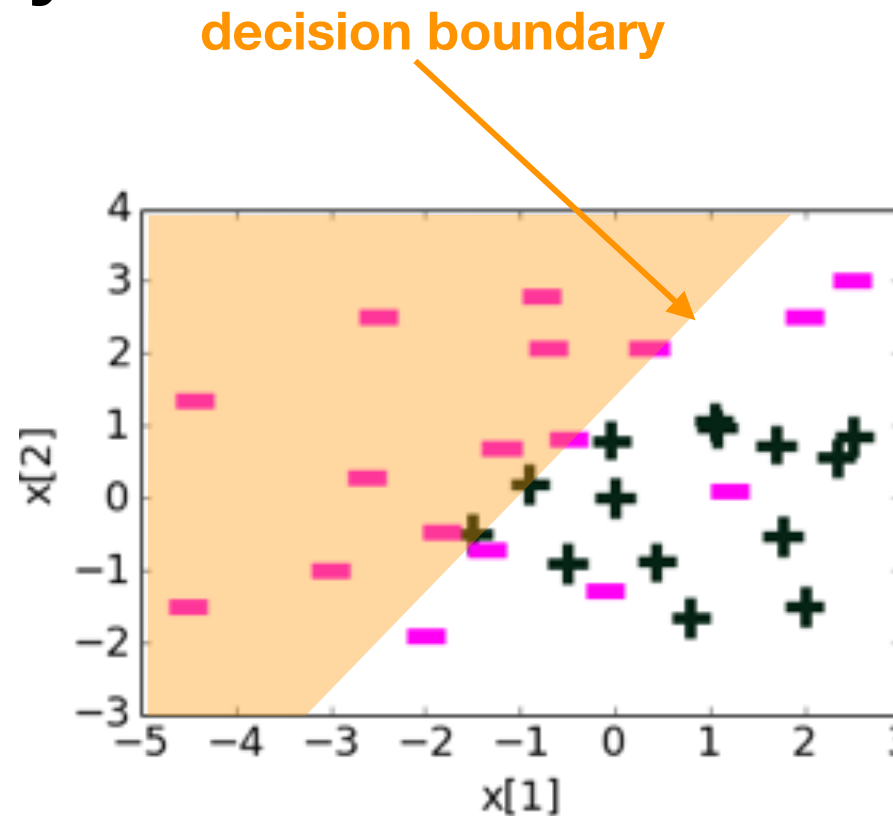
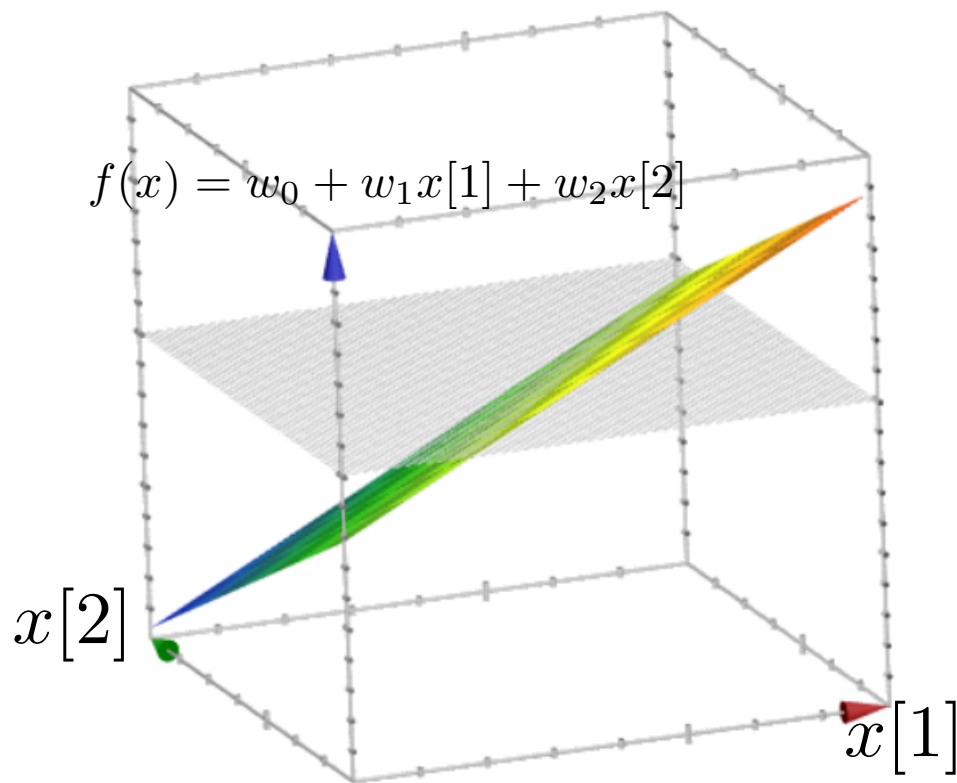
Polynomial
features

$$\begin{bmatrix} h_0(x) = 1 \\ h_1(x) = x[1] \\ h_2(x) = x[2] \\ h_3(x) = x[1]^2 \\ h_4(x) = x[2]^2 \\ \vdots \end{bmatrix}$$

- data: \mathbf{x} in 2-dimensions, \mathbf{y} in $\{+1, -1\}$
- features: polynomials
- model: linear on polynomial features

- $$f(x) = w_0 h_0(x) + w_1 h_1(x) + w_2 h_2(x) + \dots$$

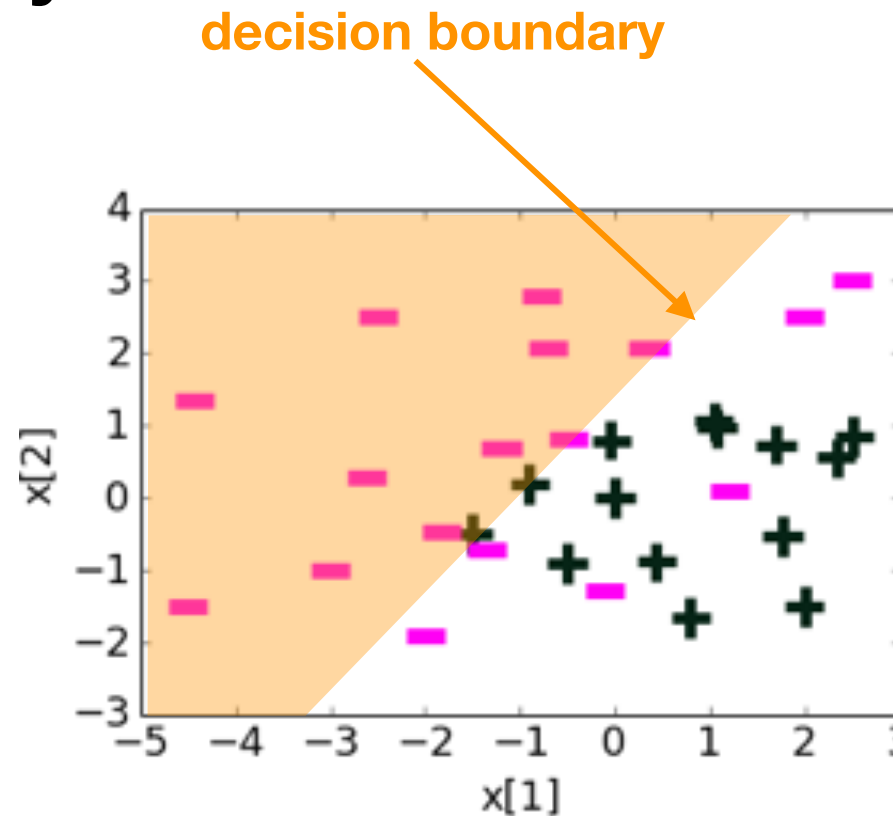
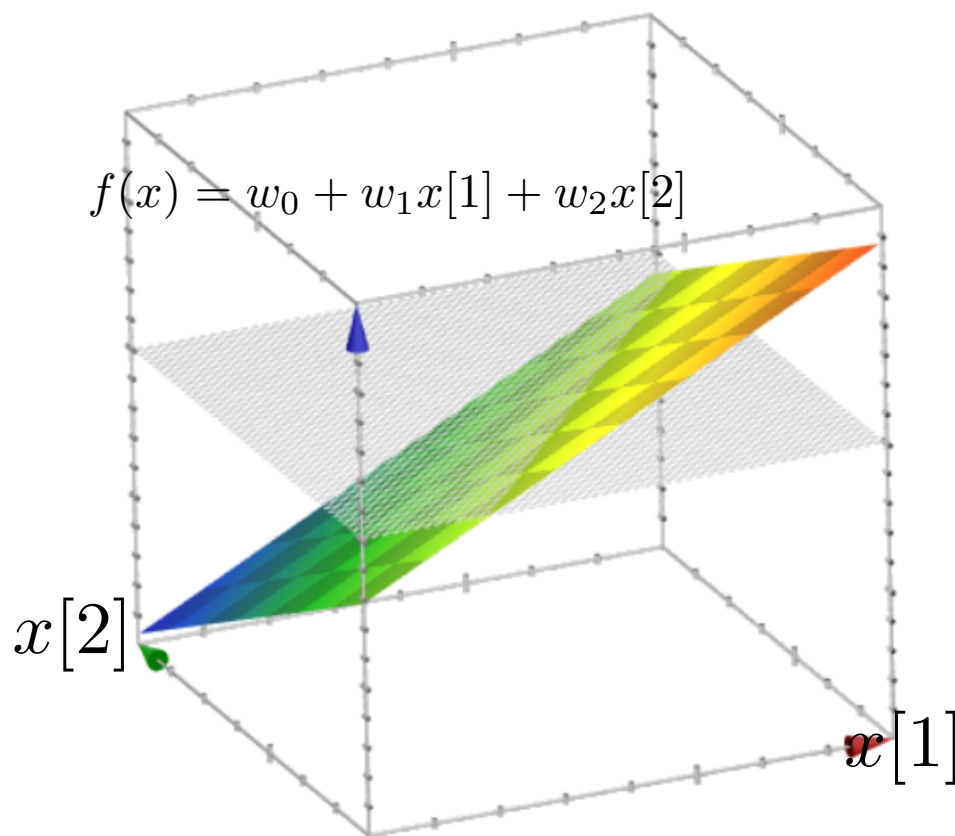
Learned decision boundary



Feature	Value	Coefficient
$h_0(x)$	1	0.23
$h_1(x)$	$x[1]$	1.12
$h_2(x)$	$x[2]$	-1.07

- Simple **regression** models had **smooth predictors**
- Simple **classifier** models have **smooth decision boundaries**

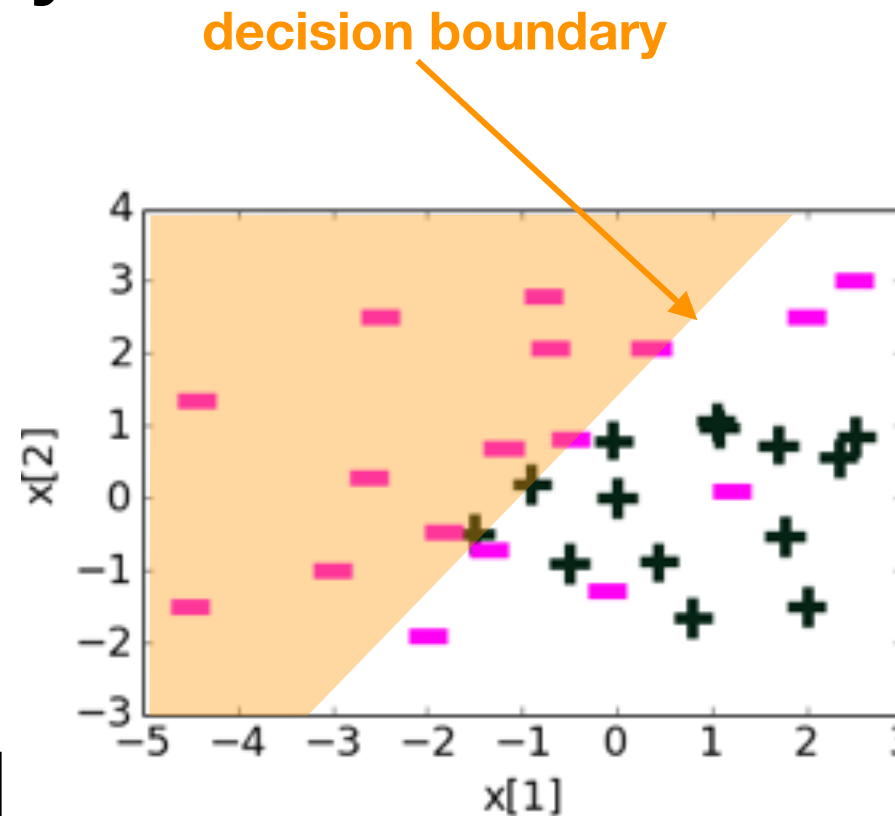
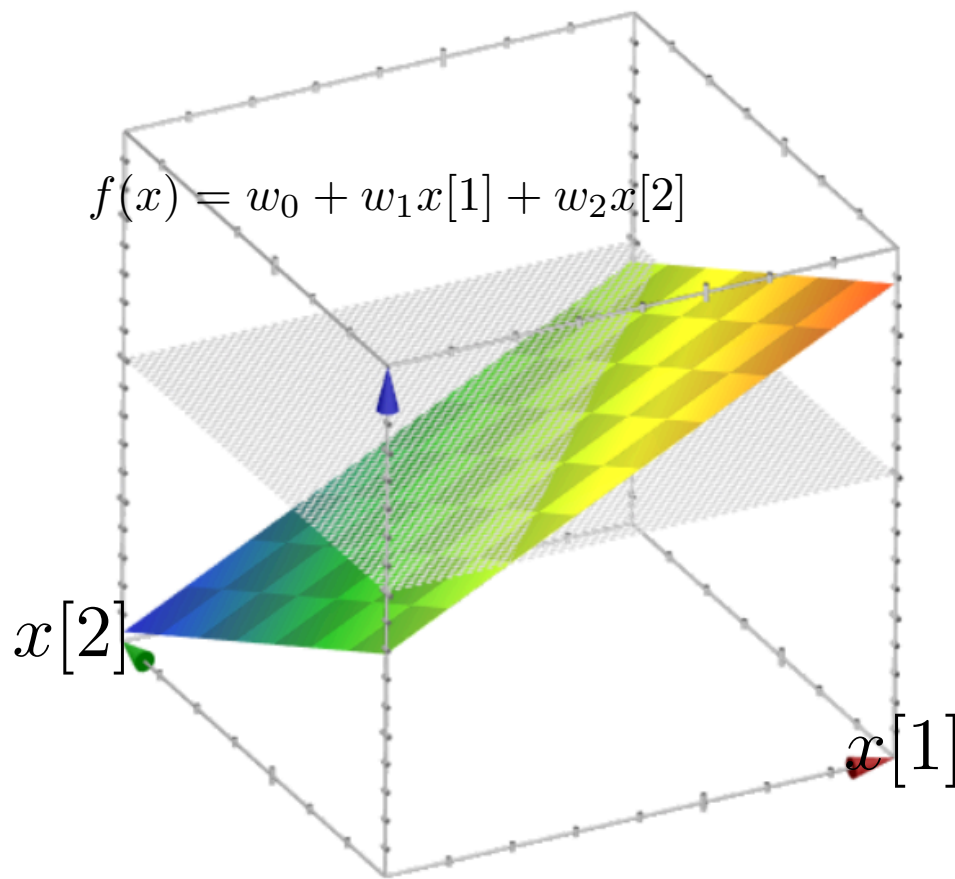
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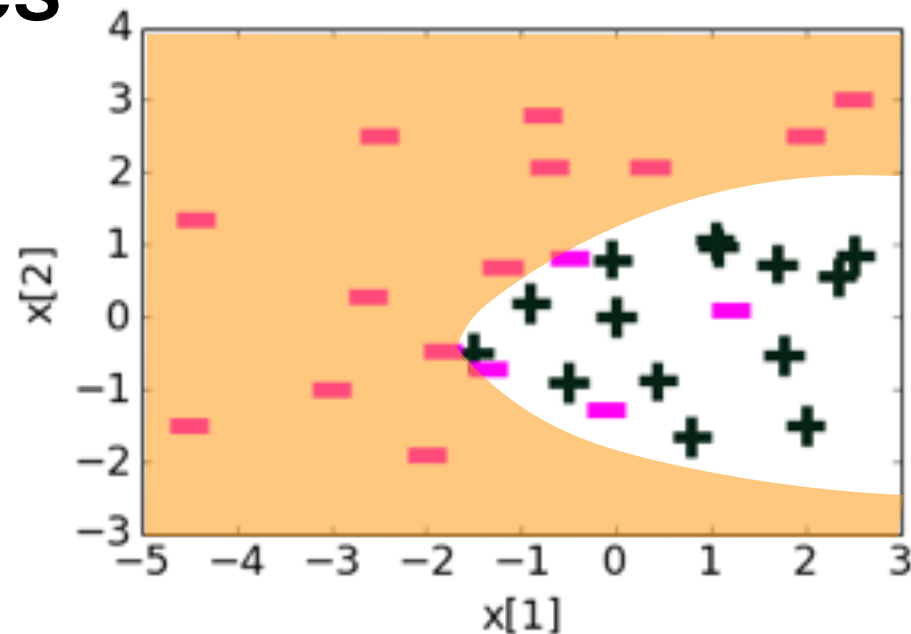
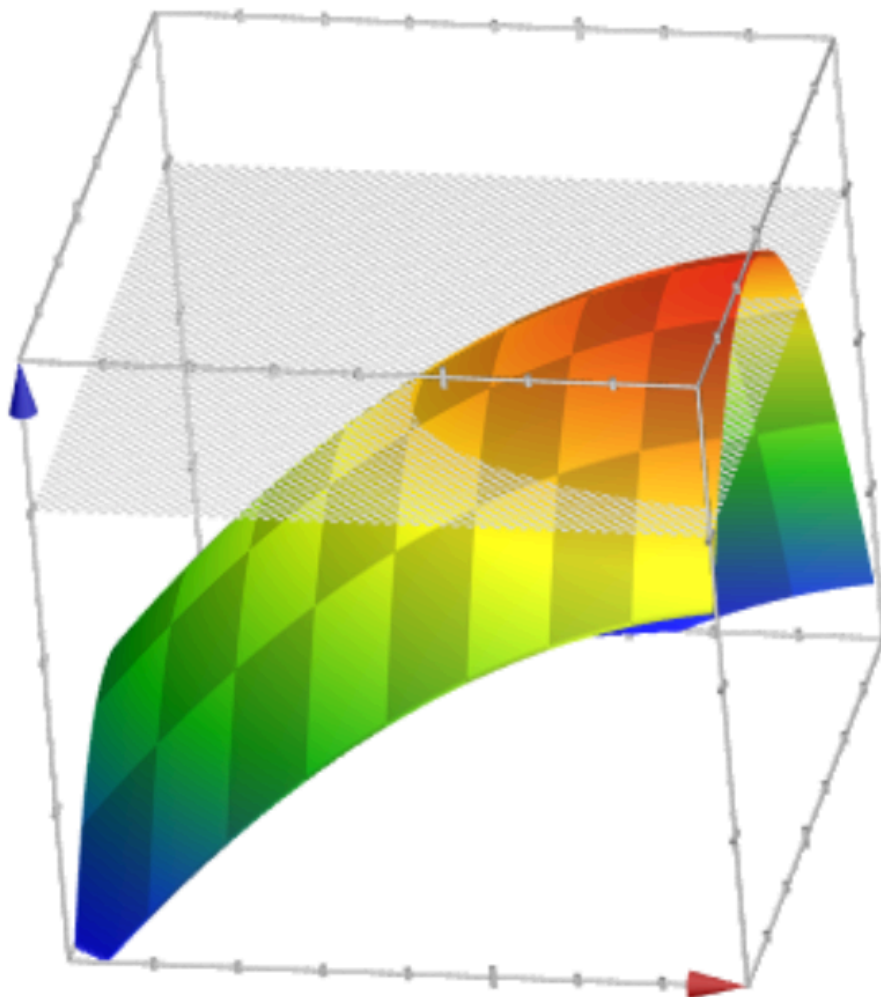
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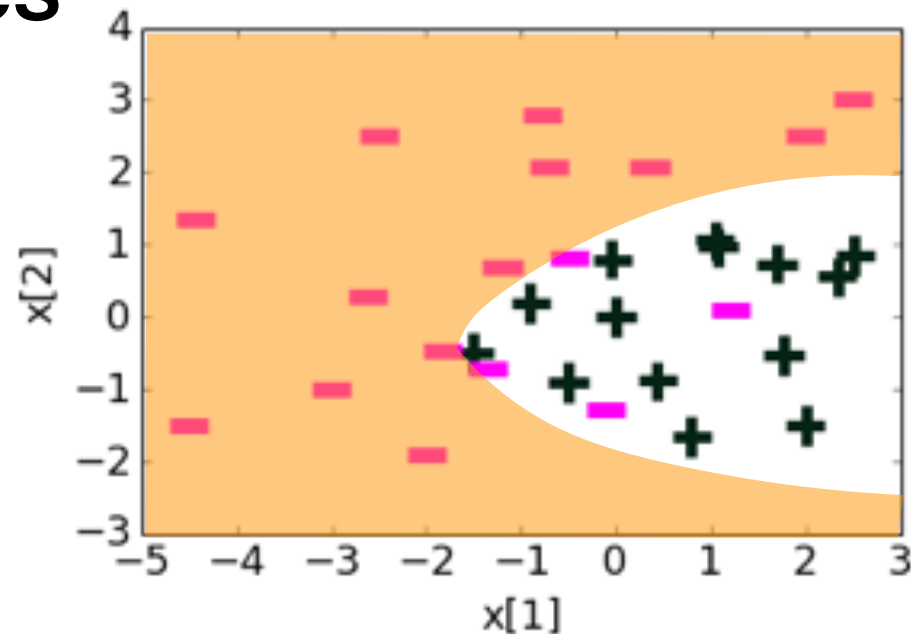
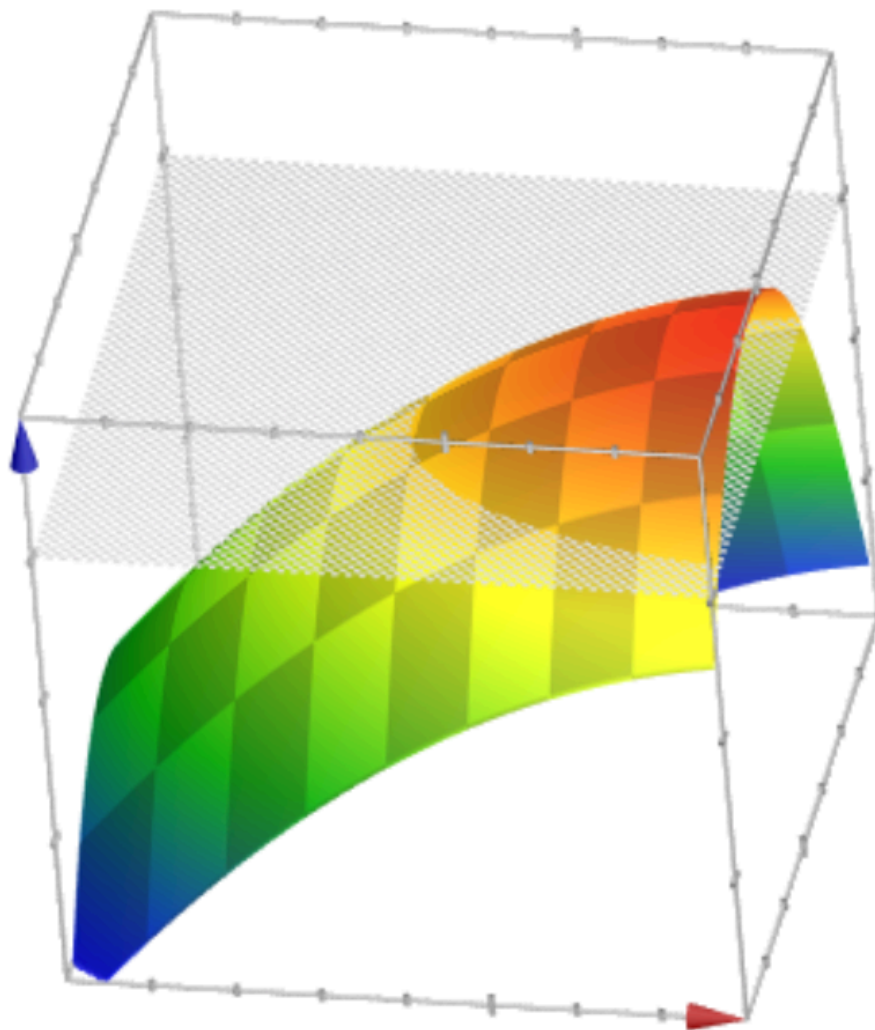
Adding quadratic features



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$h_3(x)$	$(x[1])^2$	-0.17
$h_4(x)$	$(x[2])^2$	-0.96
$h_5(x)$	$x[1]x[2]$	Omitted

- Adding more features gives more complex models
- Decision boundary becomes more complex

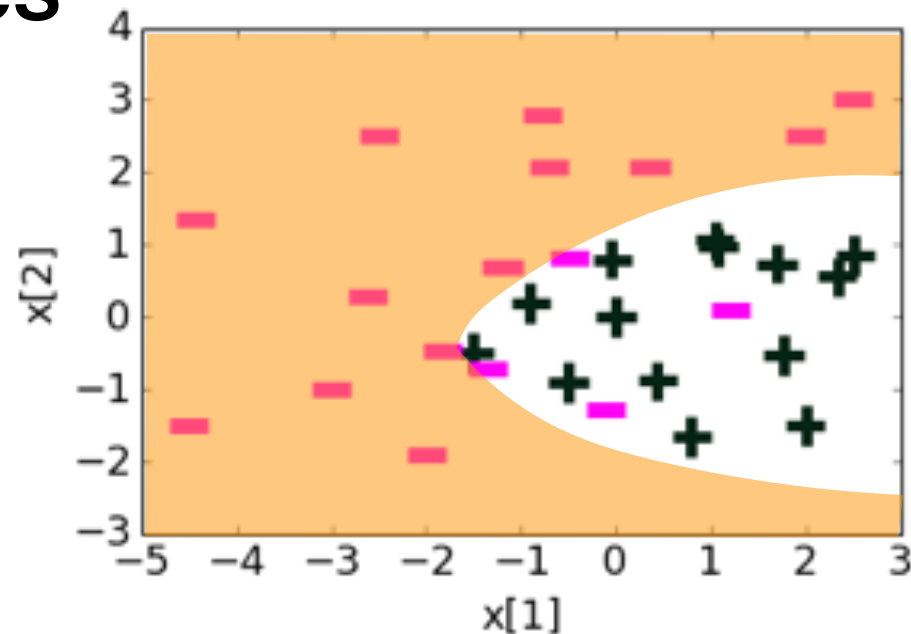
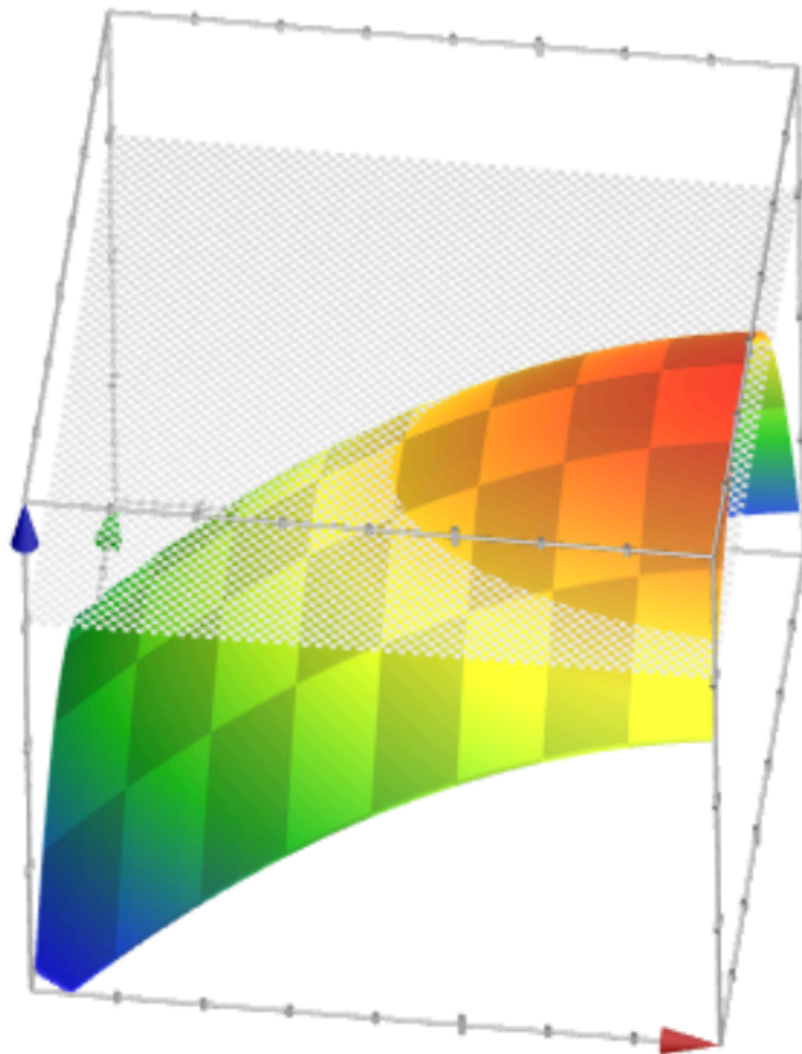
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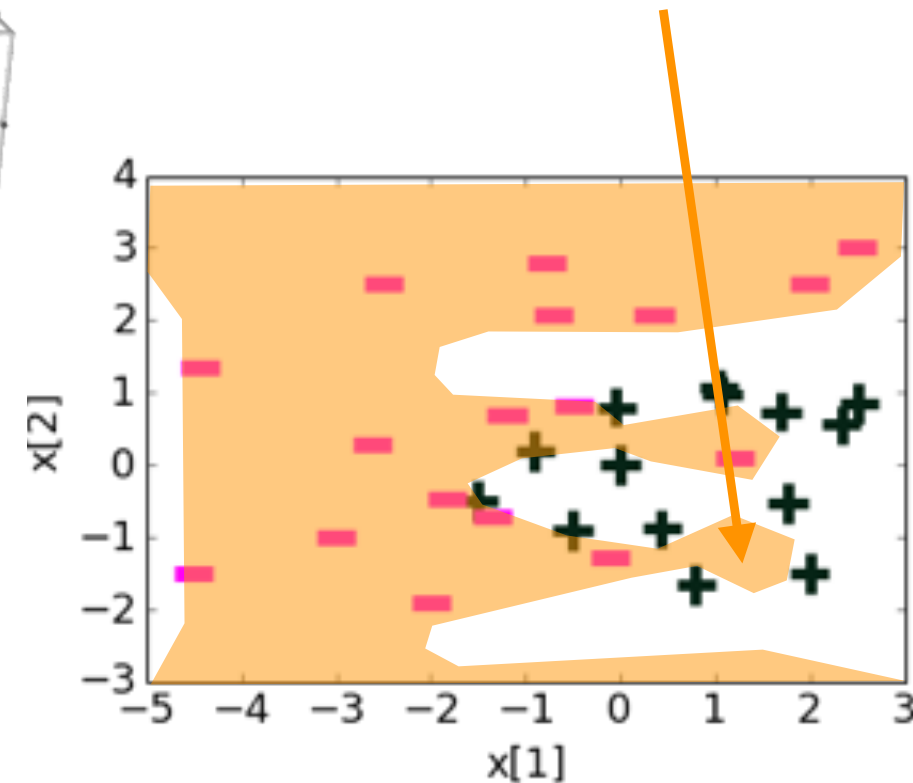
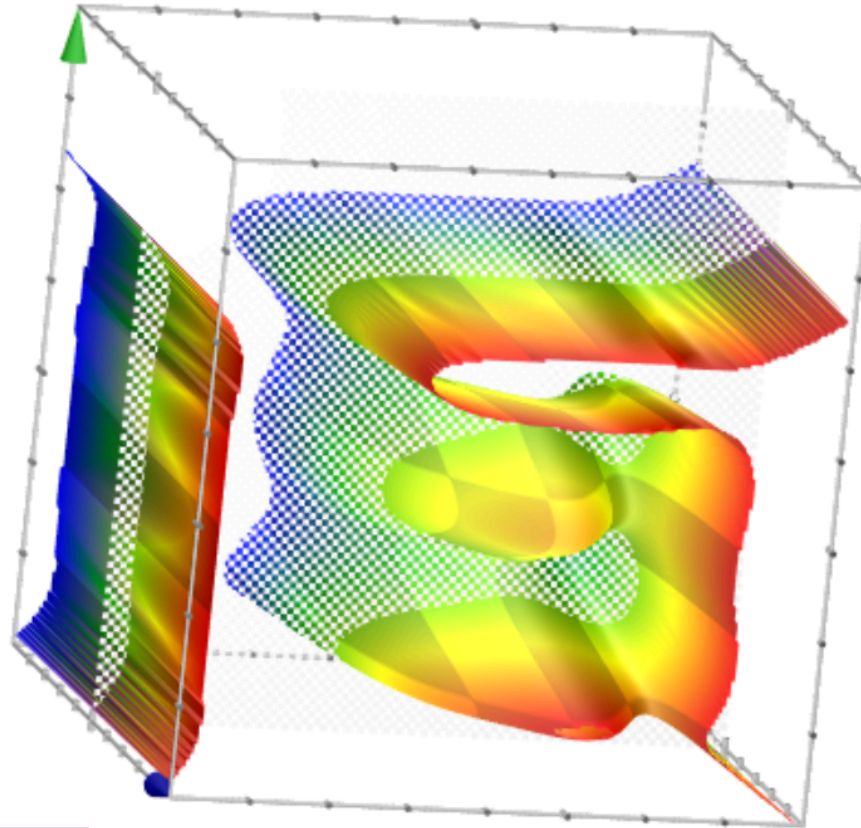


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Adding higher degree polynomial features

Overfitting leads to non-generalization

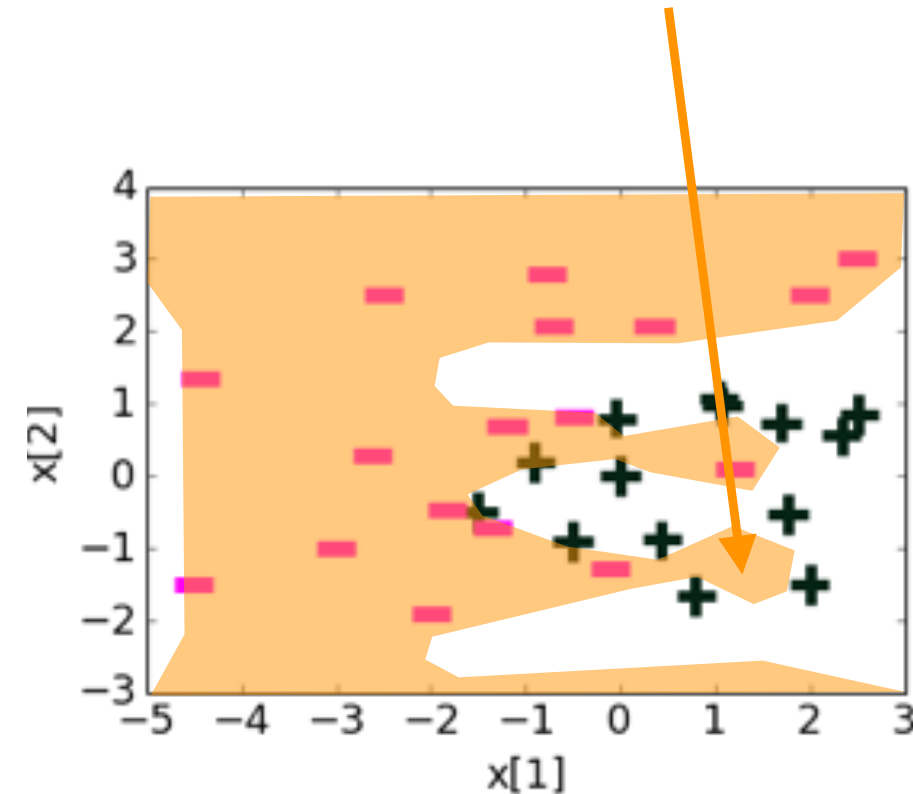
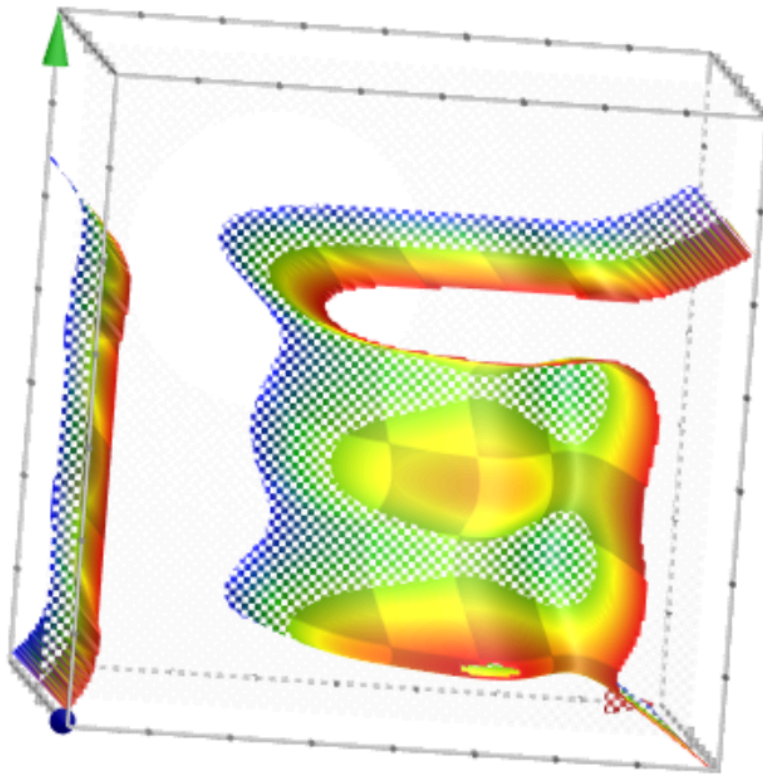


Feature	Value	Coefficient learned
$h_0(x)$	1	21.6
$h_1(x)$	$x[1]$	5.3
$h_2(x)$	$x[2]$	-42.7
$h_3(x)$	$(x[1])^2$	-15.9
$h_4(x)$	$(x[2])^2$	-48.6
$h_5(x)$	$(x[1])^3$	-11.0
$h_6(x)$	$(x[2])^3$	67.0
$h_7(x)$	$(x[1])^4$	1.5
$h_8(x)$	$(x[2])^4$	48.0
$h_9(x)$	$(x[1])^5$	4.4
$h_{10}(x)$	$(x[2])^5$	-14.2
$h_{11}(x)$	$(x[1])^6$	0.8
$h_{12}(x)$	$(x[2])^6$	-8.6

Coefficient values getting large

Adding higher degree polynomial features

Overfitting leads to non-generalization

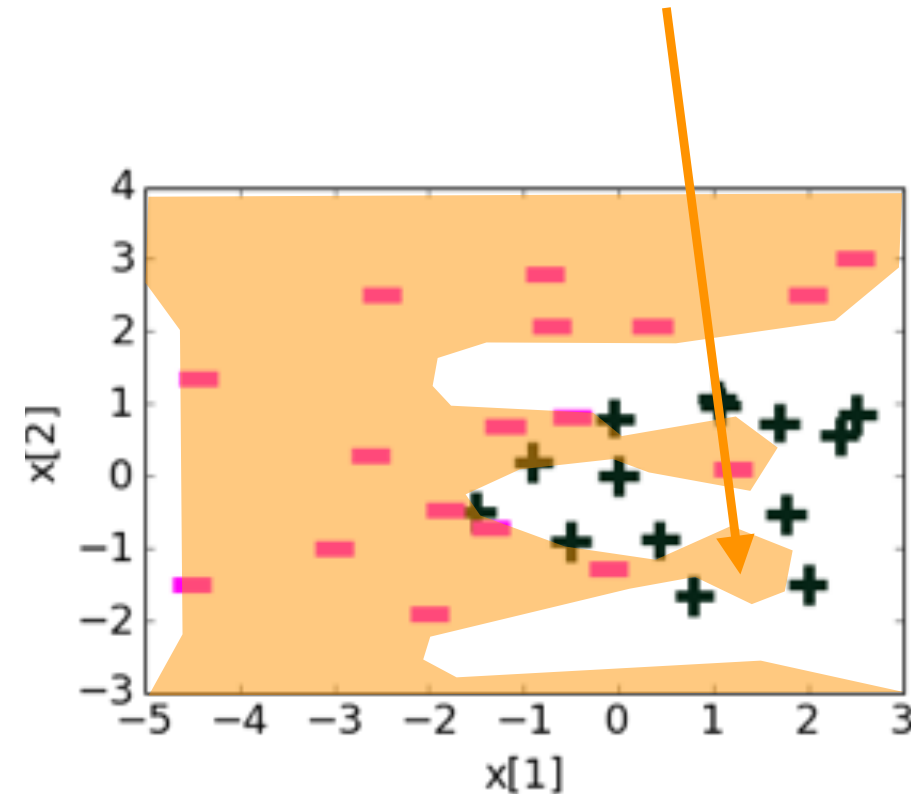
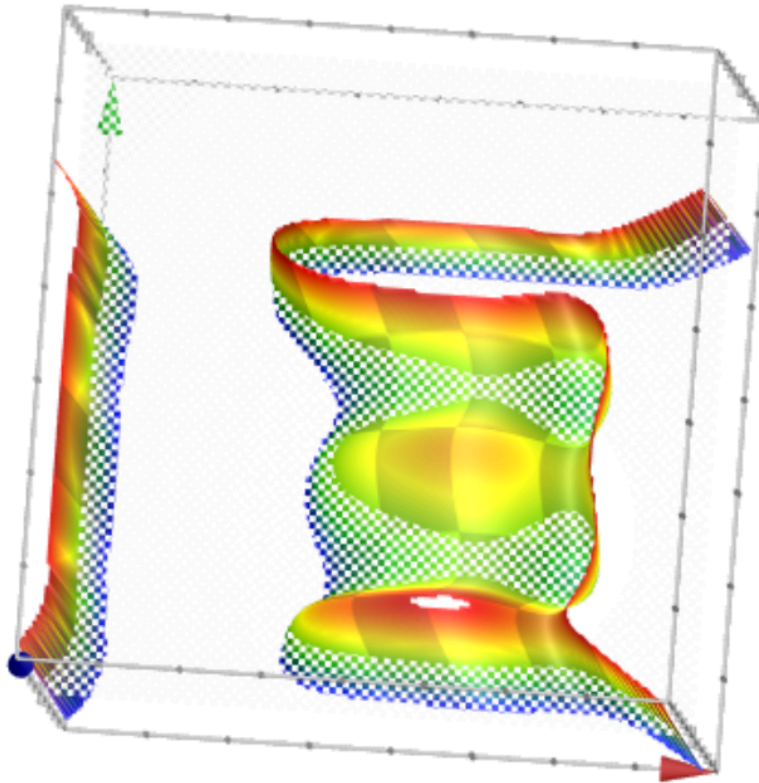


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Coefficient values getting large

- Overfitting leads to very large values of $f(x) = w_0h_0(x) + w_1h_1(x) + w_2h_2(x) + \dots$

Loss function: Conditional Likelihood

- **Have a bunch of iid data:** $\{(x_i, y_i)\}_{i=1}^n$ $x_i \in \mathbb{R}^d$, $y_i \in \{-1, 1\}$

$$P(Y = y|x, w) = \frac{1}{1 + \exp(-y w^T x)}$$

$$\begin{aligned}\hat{w}_{MLE} &= \arg \max_w \prod_{i=1}^n P(y_i|x_i, w) \\ &= \arg \min_w \sum_{i=1}^n \log(1 + \exp(-y_i x_i^T w)) = J(w)\end{aligned}$$

What does $J(w)$ look like? Is it convex?

Loss function: Conditional Likelihood

- Have a bunch of iid data: $\{(x_i, y_i)\}_{i=1}^n$ $x_i \in \mathbb{R}^d$, $y_i \in \{-1, 1\}$

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Good news: $J(\mathbf{w})$ is convex function of \mathbf{w} , no local optima problems

Bad news: no closed-form solution to maximize $J(\mathbf{w})$

Good news: convex functions easy to optimize

One other concern... overfitting.

- **Have a bunch of iid data:** $\{(x_i, y_i)\}_{i=1}^n$ $x_i \in \mathbb{R}^d$, $y_i \in \{-1, 1\}$

$$P(Y = y|x, w) = \frac{1}{1 + \exp(-y w^T x)}$$

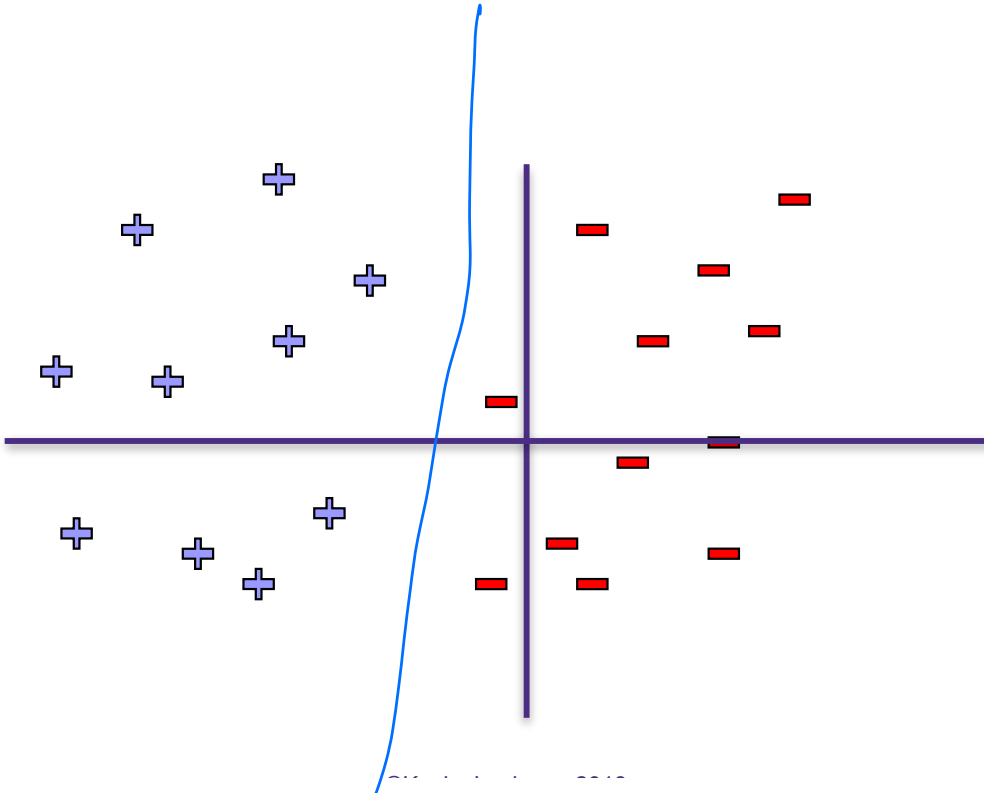
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Does anyone see a situation when this minimization might overfit?

Overfitting and Linear Separability

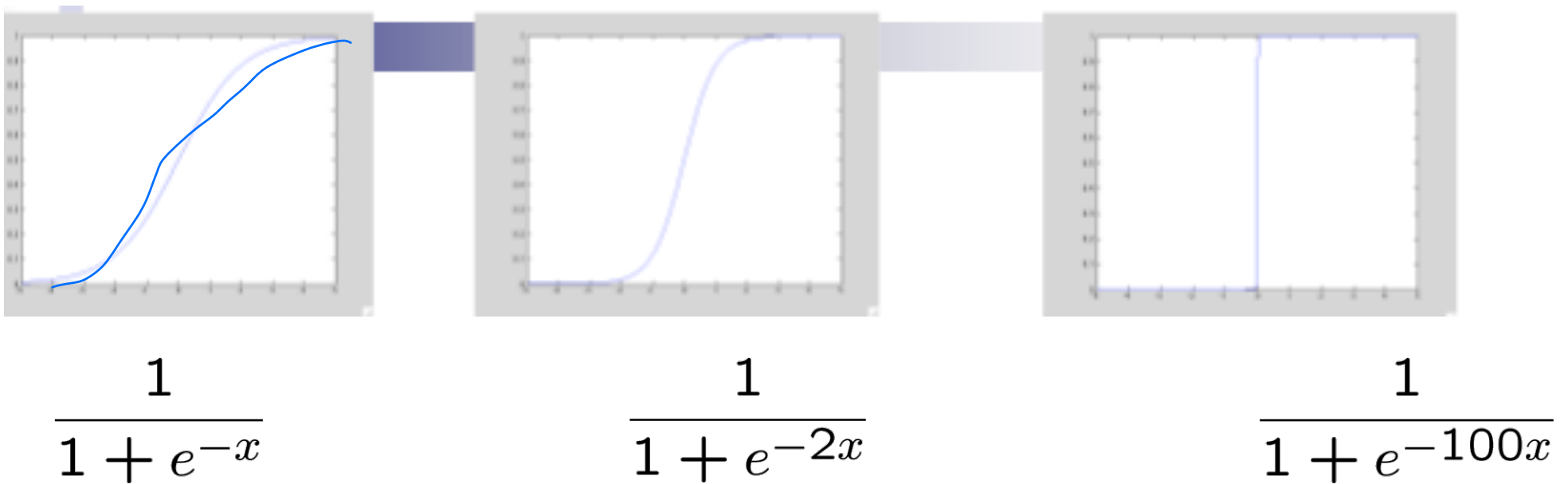
$$\arg \min_w \sum_{i=1}^n \log(1 + \exp(-y_i x_i^T w))$$

When is this loss small?



Large parameters \rightarrow Overfitting

When data is linearly separable, weights $\Rightarrow \infty$



Overfitting

Penalize high weights to prevent overfitting?

Regularized Conditional Log Likelihood

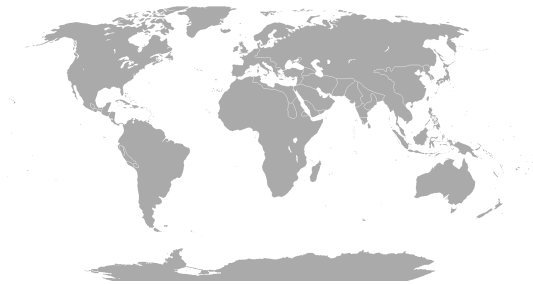
Add a penalty to avoid high weights/overfitting?:

$$\arg \min_{w,b} \sum_{i=1}^n \log (1 + \exp(-y_i (x_i^T w + b))) + \lambda \|w\|_2^2$$

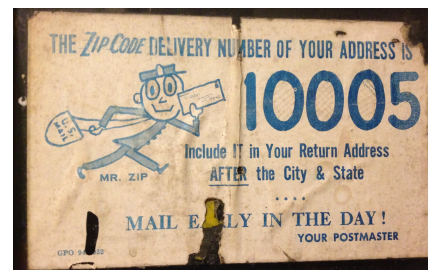
Be sure to not regularize the offset b !

How do we encode categorical data y ?

- so far, we considered Binary case where there are two categories
- encoding y is simple: $\{+1, -1\}$
- multi-class classification predicts categorical y
- taking values in $C = \{c_1, \dots, c_k\}$
- c_j 's are called **classes** or **labels**
- examples:



Country of birth
(Argentina, Brazil, USA,...)



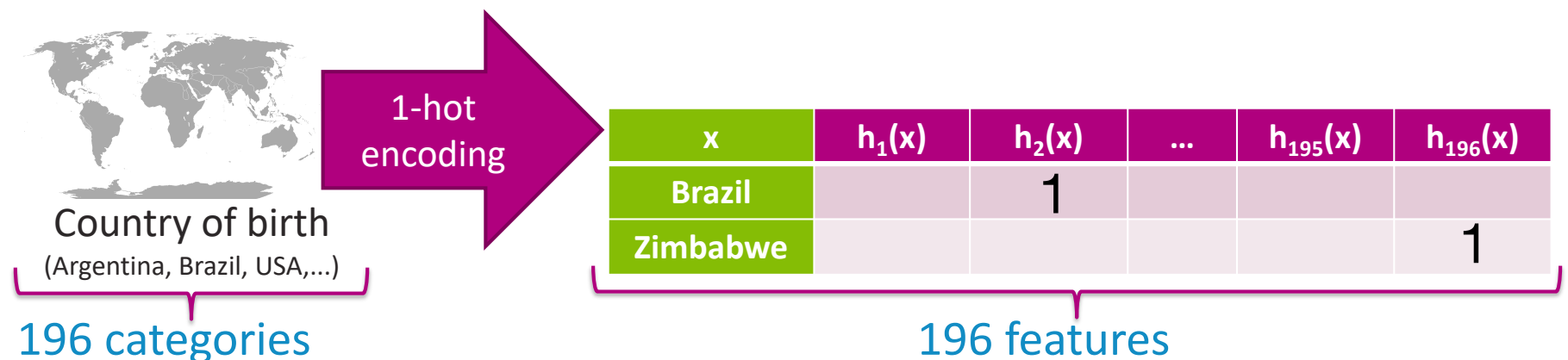
Zipcode
(10005, 98195,...)

All English words

- a **k-class classifier** predicts y given x

Embedding c_j 's in real values

- for optimization we need to **embed** raw categorical c_j 's into real valued vectors
- there are many ways to embed categorical data
 - True \rightarrow 1, False \rightarrow -1
 - Yes \rightarrow 1, Maybe \rightarrow 0, No \rightarrow -1
 - Yes \rightarrow (1,0), Maybe \rightarrow (0,0), No \rightarrow (0,1)
 - Apple \rightarrow (1,0,0), Orange \rightarrow (0,1,0), Banana \rightarrow (0,0,1)
 - Ordered sequence:
(Horse 3, Horse 1, Horse 2) \rightarrow (3,1,2)
- we use **one-hot embedding** (a.k.a. **one-hot encoding**)
 - each class is a standard basis vector in k -dimension



Multi-class logistic regression

- data: categorical y in $\{c_1, \dots, c_k\}$ with k categories

we use one-hot encoding, s.t. $y = \begin{bmatrix} 1 \\ 0 \\ 0 \\ 0 \end{bmatrix}$ implies that $y = c_1$

- model: linear vector-function makes a linear prediction $\hat{y} \in \mathbb{R}^k$

$$\hat{y}_i = f(x_i) = w^T x_i \in \mathbb{R}^k$$

with model parameter matrix $w \in \mathbb{R}^{d \times k}$ and sample $x_i \in \mathbb{R}^d$

$$f(x_i) = \begin{bmatrix} f_1(x_i) \\ f_2(x_i) \\ \vdots \\ f_k(x_i) \end{bmatrix} = \underbrace{\begin{bmatrix} w_{1,0} & w_{1,1} & w_{1,2} & \cdots \\ w_{2,0} & w_{2,1} & w_{2,2} & \cdots \\ \vdots & \vdots & \vdots & \vdots \\ w_{k,0} & w_{k,1} & w_{k,2} & \cdots \end{bmatrix}}_{w^T} \underbrace{\begin{bmatrix} 1 \\ x_i[1] \\ \vdots \\ x_i[d] \end{bmatrix}}_{x_i} = \begin{bmatrix} w_{1,0} + w_{1,1}x_i[1] + w_{1,2}x_i[2] + \cdots \\ w_{2,0} + w_{2,1}x_i[1] + w_{2,2}x_i[2] + \cdots \\ \vdots \\ w_{k,0} + w_{k,1}x_i[1] + w_{k,2}x_i[2] + \cdots \end{bmatrix}$$

$$w = [w[:, 1] \quad w[:, 2] \quad \cdots \quad w[:, k]]$$

- Logistic regression

2 classes

$$\mathbb{P}(y_i = -1 | x_i) = \frac{1}{1 + e^{w^T x_i}}$$

$$\mathbb{P}(y_i = +1 | x_i) = \frac{1}{1 + e^{-w^T x_i}} = \frac{e^{w^T x_i}}{1 + e^{w^T x_i}}$$

k classes

$$\mathbb{P}(y_i = c_1 | x_i) = \frac{e^{w^{[:,1]^T} x_i}}{e^{w^{[:,1]^T} x_i} + \dots + e^{w^{[:,k]^T} x_i}}$$

⋮

$$\mathbb{P}(y_i = c_k | x_i) = \frac{e^{w^{[:,k]^T} x_i}}{e^{w^{[:,1]^T} x_i} + \dots + e^{w^{[:,k]^T} x_i}}$$

Without loss of generality setting $w^{[:,1]}=0$ when $k = 2$ recovers the original binary class case

Maximum Likelihood Estimator

$$\text{maximize}_w \frac{1}{n} \sum_{i=1}^n \log(\mathbb{P}(y_i | x_i))$$

$$\text{maximize}_{w \in \mathbb{R}^d} \frac{1}{n} \sum_{i=1}^n \log\left(\frac{1}{1 + e^{-y_i w^T x_i}}\right)$$

$$\text{maximize}_{w \in \mathbb{R}^{d \times k}} \frac{1}{n} \sum_{i=1}^n \sum_{j=1}^k \mathbf{I}\{y_i = c_j\} \log\left(\frac{e^{w^{[:,j]^T} x_i}}{\sum_{j'=1}^k e^{w^{[:,j']^T} x_i}}\right)$$

$\mathbf{I}\{y_i = j\}$ is an indicator that is one only if $y_i = j$

Kernels



Creating Features

- Feature mapping $\phi : \mathbb{R}^d \rightarrow \mathbb{R}^p$ maps original data into a rich and high-dimensional feature space (usually $d \ll p$)

For example, in $d=1$, one can use

$$\phi(x) = \begin{bmatrix} \phi_1(x) \\ \phi_2(x) \\ \vdots \\ \phi_k(x) \end{bmatrix} = \begin{bmatrix} x \\ x^2 \\ \vdots \\ x^k \end{bmatrix}$$

For example, for $d>1$,

one can generate vectors $\{u_j\}_{j=1}^p \subset \mathbb{R}^d$

and define features:

$$\phi_j(x) = \cos(u_j^T x)$$

$$\phi_j(x) = (u_j^T x)^2$$

$$\phi_j(x) = \frac{1}{1 + \exp(u_j^T x)}$$

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- How many coefficients/parameters are there for degree- k polynomials for $x = (x_1, \dots, x_d) \in \mathbb{R}^d$?

How do we deal with high-dimensional lifts/data?

The kernel trick:

A function $K : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$ is a *kernel* for a map $\phi : \mathbb{R}^d \rightarrow \mathbb{R}^p$ if $K(x, x') = \langle \phi(x), \phi(x') \rangle$ for all x, x'

Big idea: if we can represent our

- training algorithms and
- decision rules for prediction

as functions of dot products of feature maps (i.e. $\{\langle \phi(x), \phi(x') \rangle\}$) and we can find a kernel for our feature map such that

$$K(x, x') = \langle \phi(x), \phi(x') \rangle$$

then we can avoid explicitly computing and storing (high-dimensional) $\{\phi(x_i)\}_{i=1}^n$ and instead only work with the kernel matrix of the training data $\{K(x_i, x_j)\}_{i,j \in \{1, \dots, n\}}$

Recap: Kernels are much more efficient to compute than features

- As illustrating examples, consider polynomial features of degree exactly k

- $\phi(x) = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$ for $k = 1$ and $d = 2$, then $K(x, x') = x_1x'_1 + x_2x'_2$

- $\phi(x) = \begin{bmatrix} x_1^2 \\ x_2^2 \\ x_1x_2 \\ x_2x_1 \end{bmatrix}$ for $k = 2$ and $d = 2$, then $K(x, x') = (x^T x')^2$

Recap: Kernels are much more efficient to compute than features

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- Note that for a data point x_i , **explicitly** computing the feature $\phi(x_i)$ takes memory/time $p = d^k$
- For a data point x_i , if we can make predictions by only computing the kernel, then computing $\{K(x_i, x_j)\}_{j=1}^n$ takes memory/time dn
 - The features are **implicit** and accessed only via kernels, making it efficient

Examples of popular Kernels

- Polynomials of degree exactly k

$$K(x, x') = (x^T x')^k$$

- Polynomials of degree up to k

$$K(x, x') = (1 + x^T x')^k$$

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- Gaussian (squared exponential) kernel
(a.k.a RBF kernel for Radial Basis Function)

$$K(x, x') = \exp\left(-\frac{\|x - x'\|_2^2}{2\sigma^2}\right)$$

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- Sigmoid

$$K(x, x') = \tanh(\gamma x^T x' + r)$$

- All these kernels are efficient to compute, but the corresponding features are in high-dimensions

Ridge Linear Regression as Kernels

- Recall Ridge regression: $\hat{w} = \arg \min_{w \in \mathbb{R}^d} \|\mathbf{y} - \mathbf{X}w\|_2^2 + \lambda \|w\|_2^2$
- Consider the trivial kernel $K(x, x') = x^T x'$
- Training: $\hat{w} = (\mathbf{X}^T \mathbf{X} + \lambda \mathbf{I}_{d \times d})^{-1} \mathbf{X}^T \mathbf{y} = \mathbf{X}^T (\mathbf{X} \mathbf{X}^T + \lambda \mathbf{I}_{n \times n})^{-1} \mathbf{y}$

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- Prediction: $x_{\text{new}} \in \mathbb{R}^d$ $\hat{y}_{\text{new}} = \hat{w}^T x_{\text{new}} = \mathbf{y}^T (\mathbf{X} \mathbf{X}^T + \lambda \mathbf{I}_{n \times n})^{-1} \mathbf{X} x_{\text{new}}$

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- Hence, to make prediction on any future data points, all we need to know is
 - $\mathbf{X} x_{\text{new}} = \begin{bmatrix} x_1^T x_{\text{new}} \\ \vdots \\ x_n^T x_{\text{new}} \end{bmatrix} = \begin{bmatrix} K(x_1, x_{\text{new}}) \\ \vdots \\ K(x_n, x_{\text{new}}) \end{bmatrix} \in \mathbb{R}^n$, and $\mathbf{X} \mathbf{X}^T = \begin{bmatrix} K(x_1, x_1) & K(x_1, x_2) & \cdots \\ \vdots & \vdots & \\ K(x_n, x_1) & K(x_n, x_2) & \cdots \end{bmatrix} \in \mathbb{R}^{n \times n}$
- **Key idea:** Now consider $\hat{w} = \arg \min_{w \in \mathbb{R}^p} \sum_{i=1}^n (y_i - w^T \phi(x_i))^2 + \lambda \|w\|_2^2$ and use an *any* kernel $K(x, x') = \phi(x)^T \phi(x')$!

The Kernel Trick

- Given data $\{(x_i, y_i)\}_{i=1}^n$, pick a kernel $K : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$

- For a choice of a loss, use a linear predictor of the form

$$\widehat{w} = \sum_{i=1}^n \alpha_i x_i \quad \text{for some } \alpha = \begin{bmatrix} \alpha_1 \\ \vdots \\ \alpha_n \end{bmatrix} \in \mathbb{R}^n \text{ to be learned}$$

$$\text{Prediction is } \hat{y}_{\text{new}} = \widehat{w}^T x_{\text{new}} = \sum_{i=1}^n \alpha_i x_i^T x_{\text{new}}$$

- Design an algorithm that finds α while accessing the data only via $\{x_i^T x_j\}$

- Substitute $x_i^T x_j$ with $K(x_i, x_j)$, and find α using the above algorithm from step 2.

- Make prediction with $\hat{y}_{\text{new}} = \sum_{i=1}^n \alpha_i K(x_i, x_{\text{new}})$

(replacing $x_i^T x_{\text{new}}$ with $K(x_i, x_{\text{new}})$)

The Kernel Trick for regularized least squares

$$\hat{w} = \arg \min_w \sum_{i=1}^n (y_i - w^T x_i)^2 + \lambda \|w\|_2^2$$

There exists an $\alpha \in \mathbb{R}^n$: $\hat{w} = \sum_{i=1}^n \alpha_i x_i$

(Step 1. We will prove it later)

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$$\hat{\alpha} = \arg \min_{\alpha} \sum_{i=1}^n (y_i - \sum_{j=1}^n \alpha_j \langle x_j, x_i \rangle)^2 + \lambda \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j \langle x_i, x_j \rangle$$

(Step 2. Write an algorithm in terms of $\hat{\alpha}$)

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(Step 2. Write an algorithm in terms of $\hat{\alpha}$)

$$\hat{\alpha}_{\text{kernel}} = \arg \min_{\alpha} \sum_{i=1}^n (y_i - \sum_{j=1}^n \alpha_j K(x_i, x_j))^2 + \lambda \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j K(x_i, x_j)$$

(Step 3. Switch inner product with kernel)

$$= \arg \min_{\alpha} \|\mathbf{y} - \mathbf{K}\alpha\|_2^2 + \lambda \alpha^T \mathbf{K}\alpha$$

Where $\mathbf{K}_{ij} = K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle$

(Solve for $\hat{\alpha}_{\text{kernel}}$)

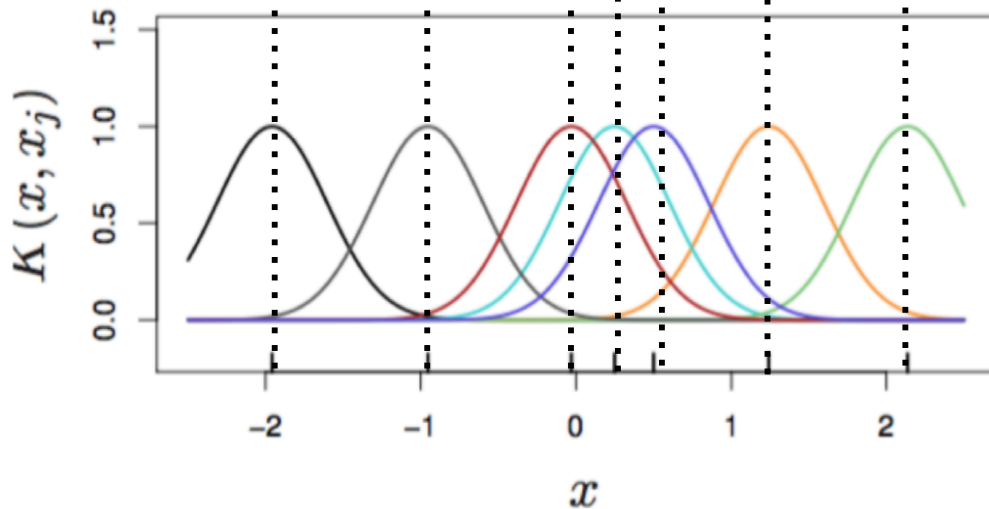
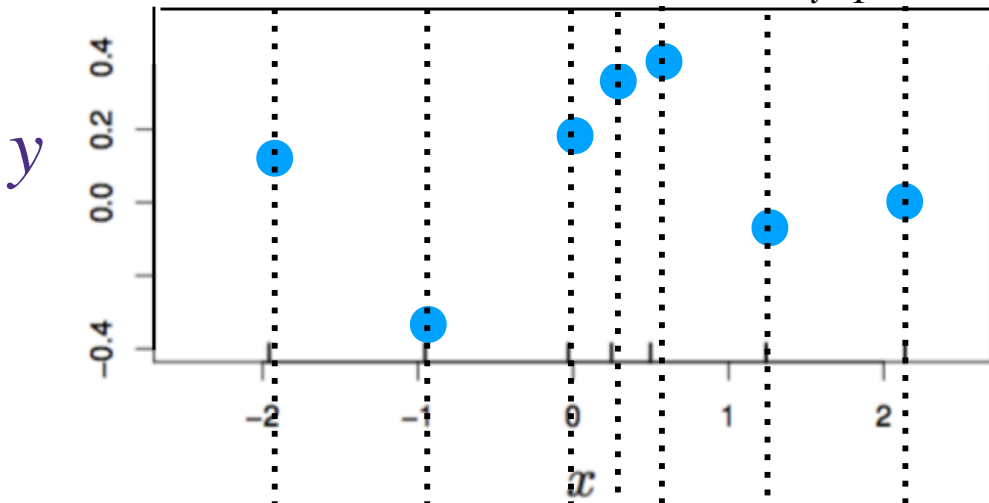
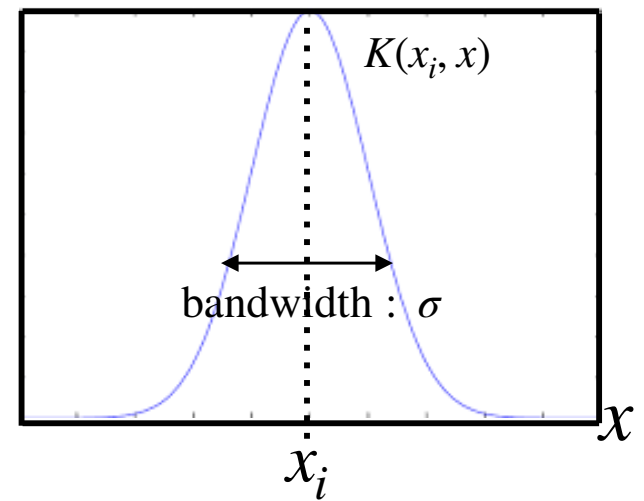
$$\text{Thus, } \hat{\alpha}_{\text{kernel}} = (\mathbf{K} + \lambda \mathbf{I}_{n \times n})^{-1} \mathbf{y}$$

Why do we need regularization when using kernels?

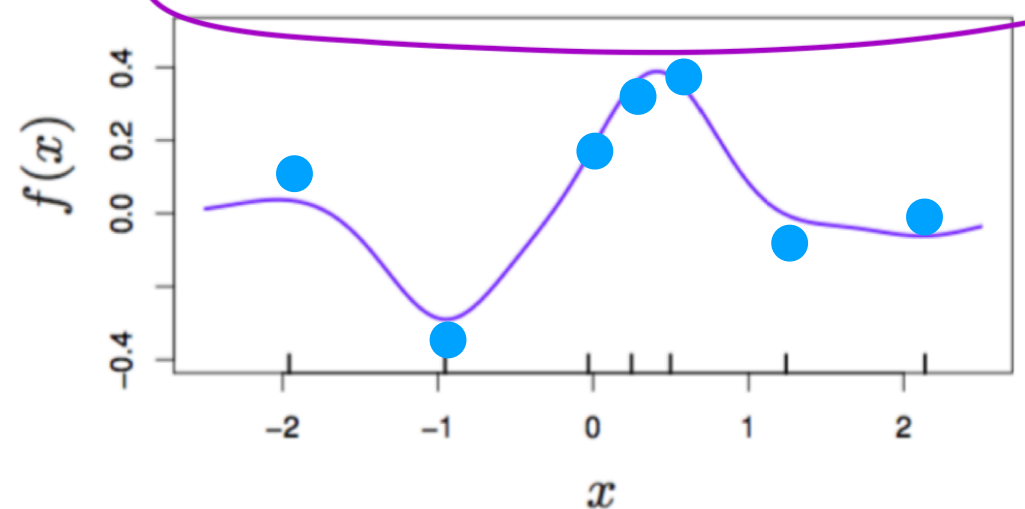
- $\hat{\alpha} = \arg \min_{\alpha} \|\mathbf{y} - \mathbf{K}\alpha\|_2^2 + \lambda \alpha^T \mathbf{K}\alpha$
- Typically, \mathbf{K} is invertible so that $\hat{\alpha} = (\mathbf{K} + \lambda \mathbf{I}_{n \times n})^{-1} \mathbf{y}$ is well defined.
- What if $\lambda = 0$? What goes wrong?

RBF kernel $k(x_i, x) = \exp\left\{-\frac{\|x_i - x\|_2^2}{2\sigma^2}\right\}$

samples $\{(x_i, y_i)\}_{i=1}^n$



$f(x) = \alpha_0 + \sum_j \alpha_j K(x, x_j)$

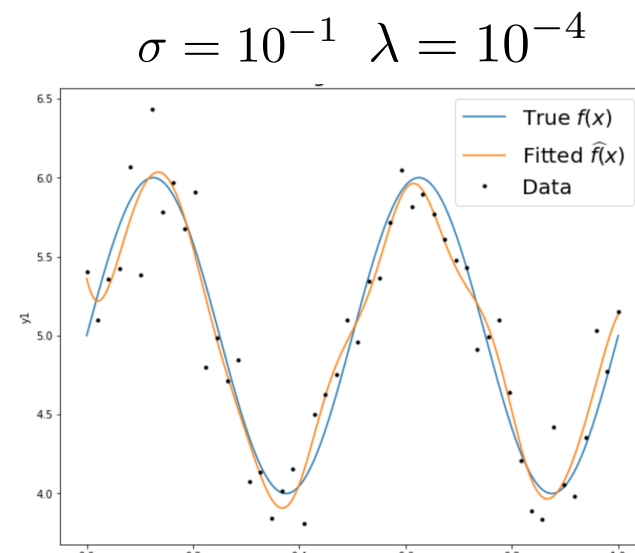
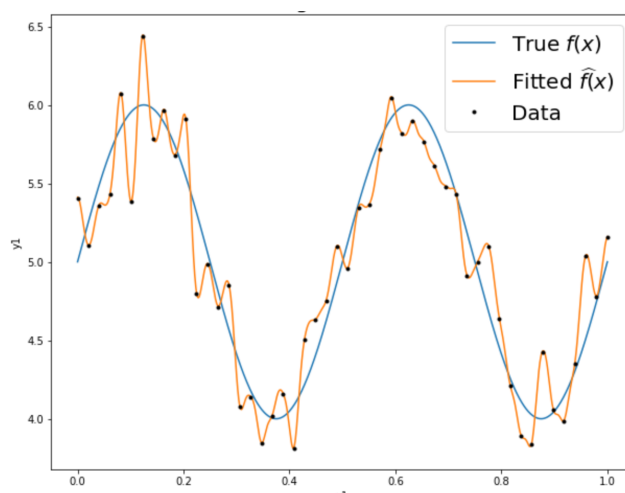
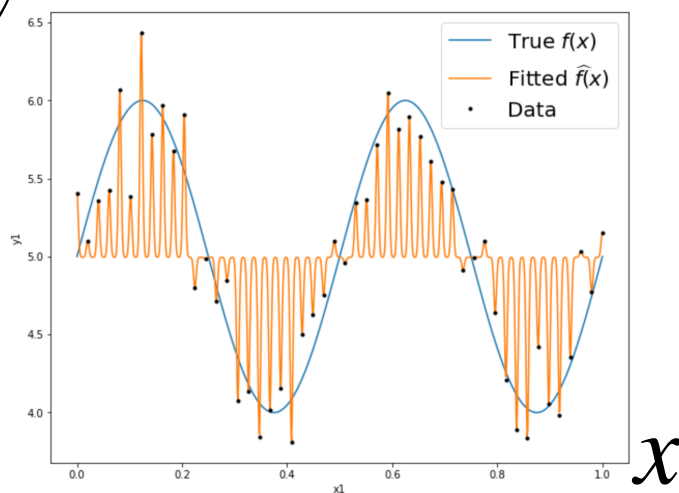


- predictor $f(x) = \sum_{i=1}^n \alpha_i K(x_i, x)$ is taking weighted sum of n kernel functions centered at each sample points

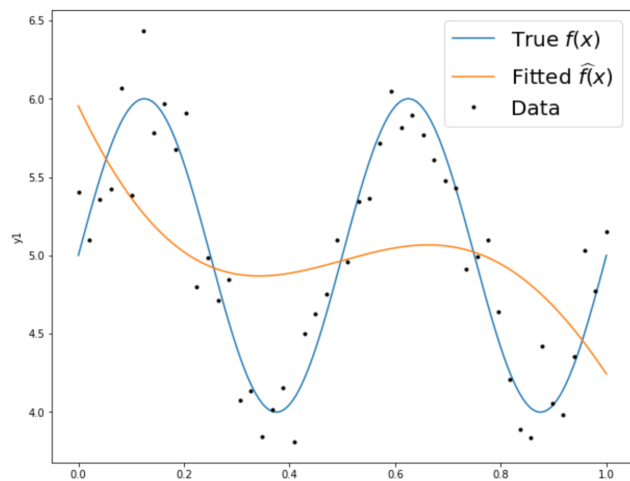
RBF kernel $k(x_i, x) = \exp\left\{-\frac{\|x_i - x\|_2^2}{2\sigma^2}\right\}$

- $\mathcal{L}(\alpha) = \|\mathbf{K}\alpha - \mathbf{y}\|_2^2 + \lambda\|w\|_2^2$
- The bandwidth σ^2 of the kernel regularizes the predictor, and the regularization coefficient λ also regularizes the predictor

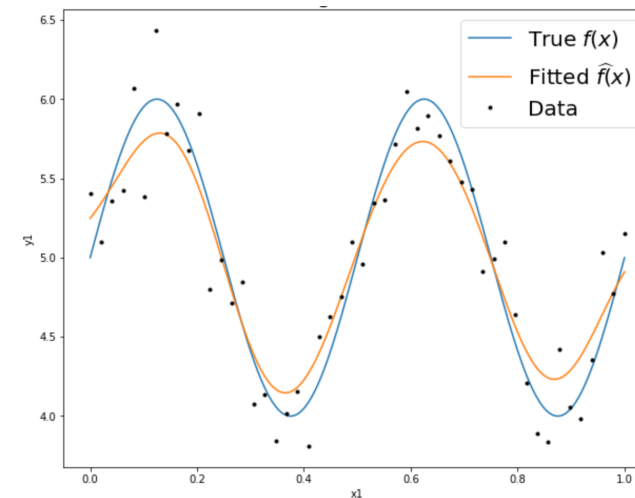
y



$\sigma = 10^{-0} \quad \lambda = 10^{-4}$



$\sigma = 10^{-1} \quad \lambda = 10^{-0}$



$$\hat{f}(x) = \sum_{i=1}^n \hat{\alpha}_i K(x_i, x)$$

x

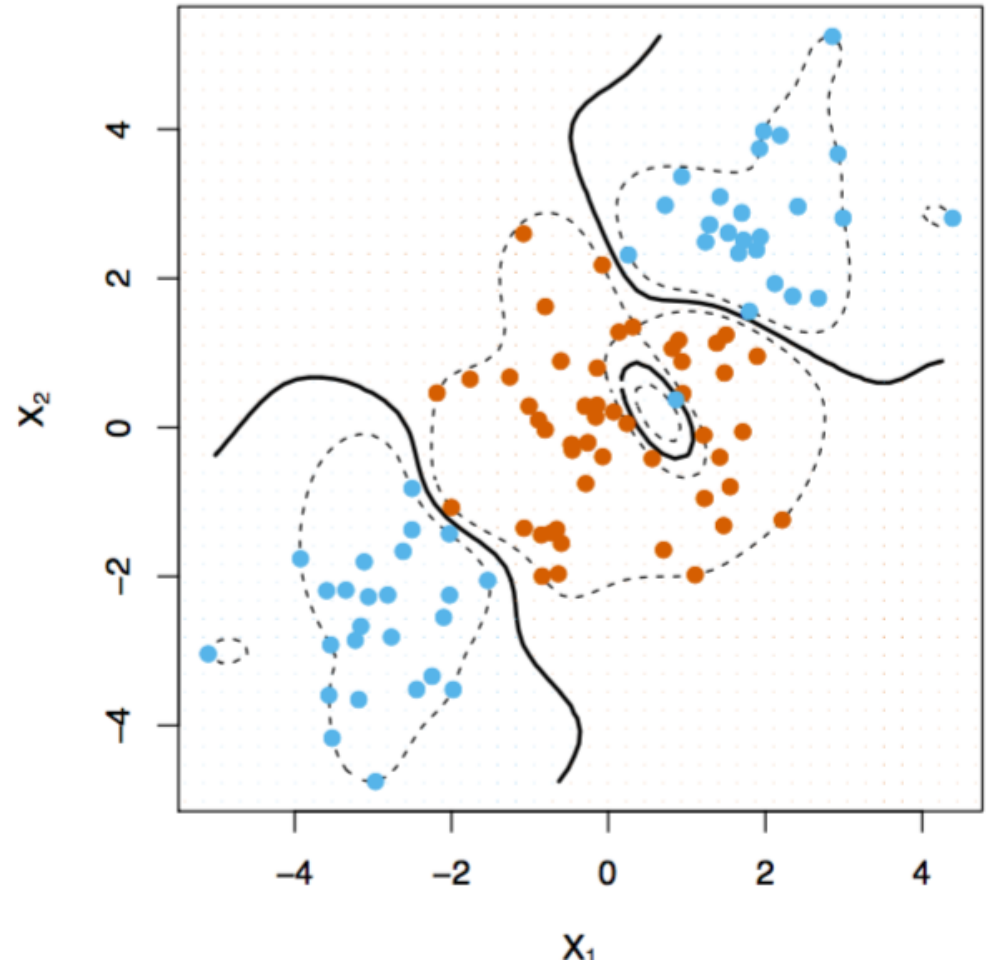
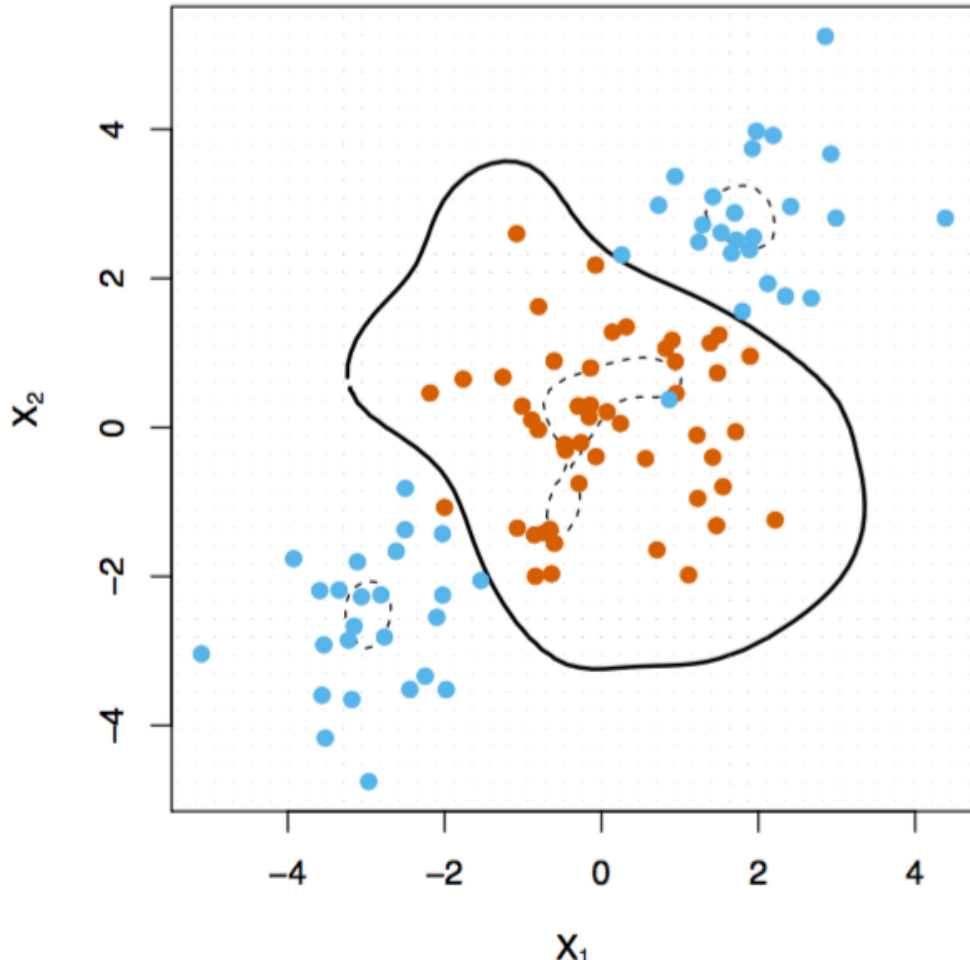
RBF kernel and random features

$$\hat{w} = \arg \min_{w,b} \frac{1}{n} \sum_{i=1}^n \log(1 + \exp(-y_i(b + w^T x_i))) + \lambda \|w\|_2^2$$

$$\hat{\alpha}, \hat{b} = \arg \min_{\alpha \in \mathbb{R}^n, b} \frac{1}{n} \sum_{i=1}^n \log(1 + \exp(-y_i(b + \sum_{j=1}^n \alpha_j K(x_j, x_i)))) + \lambda \sum_{i=1, j=1}^n \alpha_i \alpha_j K(x_i, x_j)$$

Bandwidth σ is large enough

Bandwidth σ is small



Features vs. RBF kernel vs. random features

$$K(\mathbf{u}, \mathbf{v}) = \exp\left(-\frac{\|\mathbf{u} - \mathbf{v}\|_2^2}{2\sigma^2}\right)$$

If n is very large, allocating an n -by- n matrix is tough.

Instead, consider generating random feature maps of the form:

$$\phi(x) = \begin{bmatrix} \sqrt{2} \cos(w_1^T x + b_1) \\ \vdots \\ \sqrt{2} \cos(w_p^T x + b_p) \end{bmatrix} \quad \begin{array}{l} w_k \sim \mathcal{N}(0, 2\gamma I) \\ b_k \sim \text{uniform}(0, \pi) \end{array}$$

with $p \ll n$

One can show that

$$\mathbb{E}_{w,b} \left[\frac{1}{p} \phi(x)^T \phi(x') \right] = \exp(-\gamma \|x - x'\|_2^2)$$

So this choice of random features approximate the desired RBF kernel with $\gamma = \frac{1}{2\sigma^2}$

[Rahimi, Recht NIPS 2007]
“NIPS Test of Time Award, 2018”

Fixed Feature V.S. Learned Feature

Can we learn the feature mapping $\phi : \mathbb{R}^d \rightarrow \mathbb{R}^p$ from data also?

Questions?
