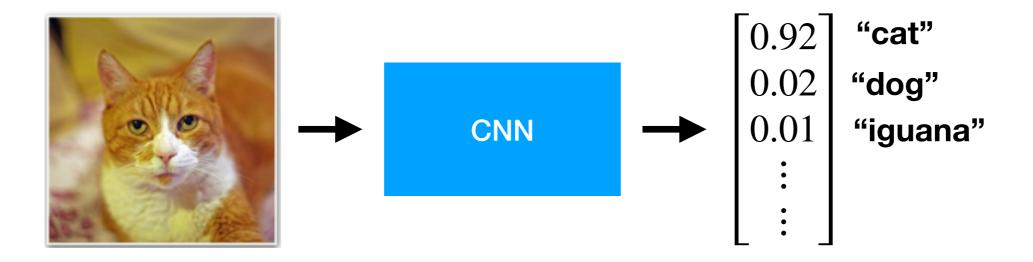
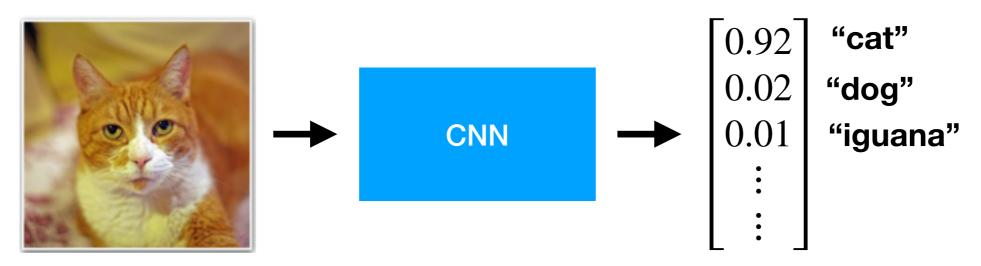
# Adversarial attack on deep learning



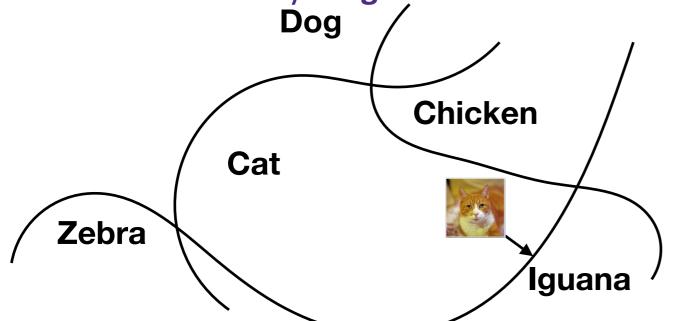
• In adversarial examples the goal of an adversary is to generate an image that looks like a cat, but is classified as iguana (for a specific given NN classifier)



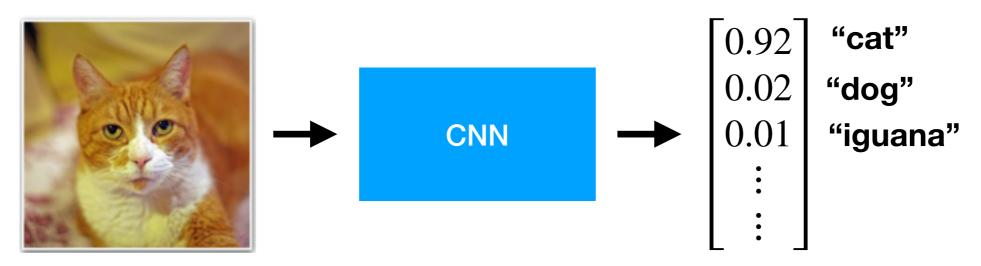
• In adversarial examples the goal of an adversary is to generate an image that looks like a cat, but is classified as iguana (for a specific given NN classifier)



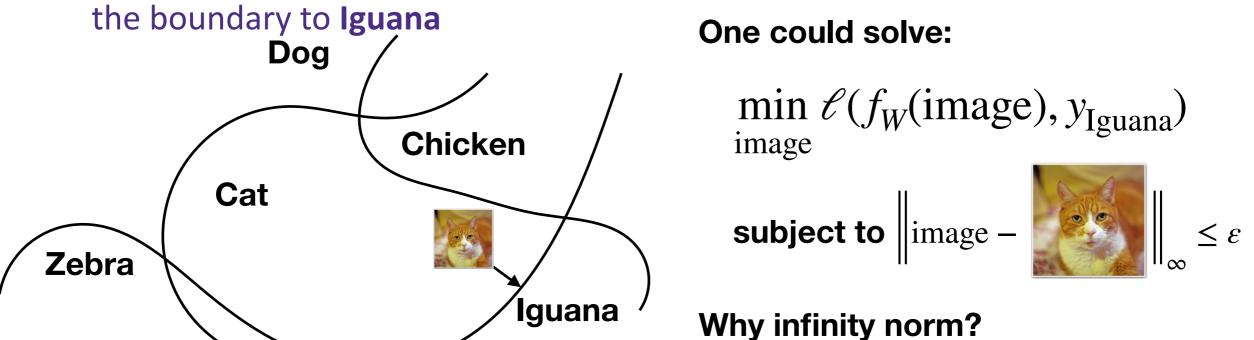
- Main idea:
  - the given CNN has complex decision boundaries around the sample
  - find the minimum perturbation you can do to the pixel values, while crossing the boundary to Iguana

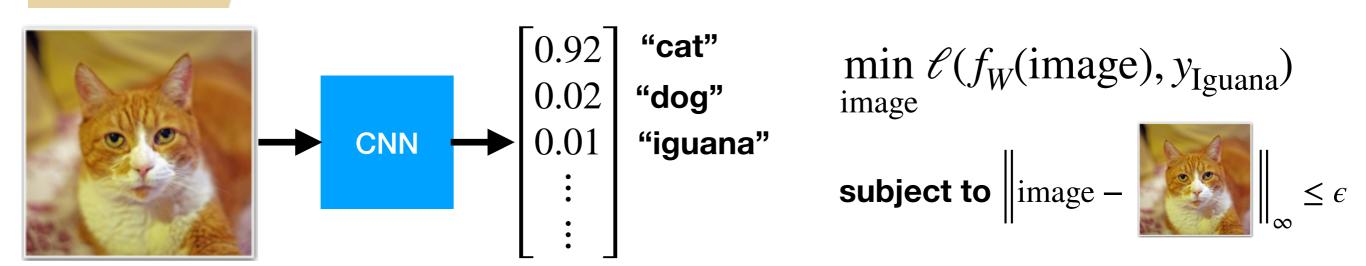


• In adversarial examples the goal of an adversary is to generate an image that looks like a cat, but is classified as iguana (for a specific given NN classifier)

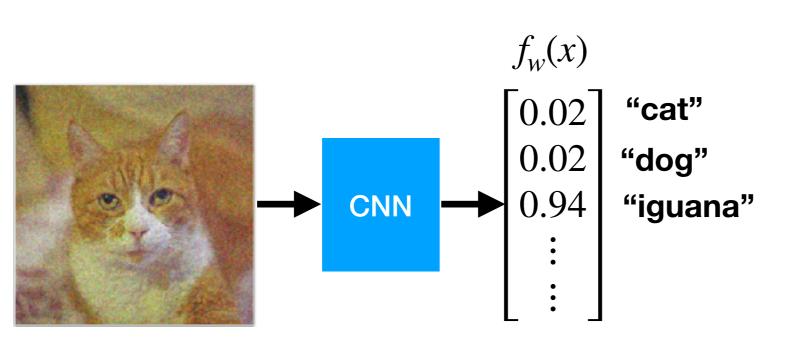


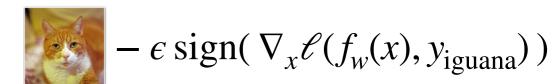
- Main idea:
  - the given CNN has complex decision boundaries around the sample
  - find the minimum perturbation you can do to the pixel values, while crossing





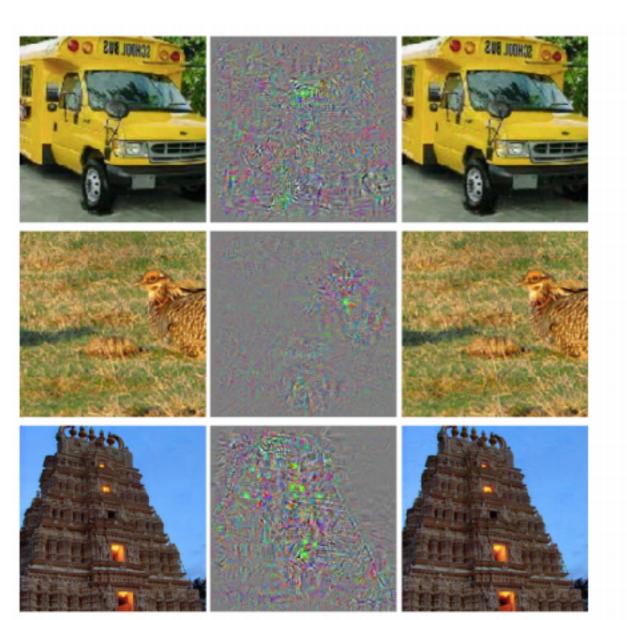
 In practice, you do not have to solve the optimization, but one gradient step is sufficient (Fast Gradient Sign Method)





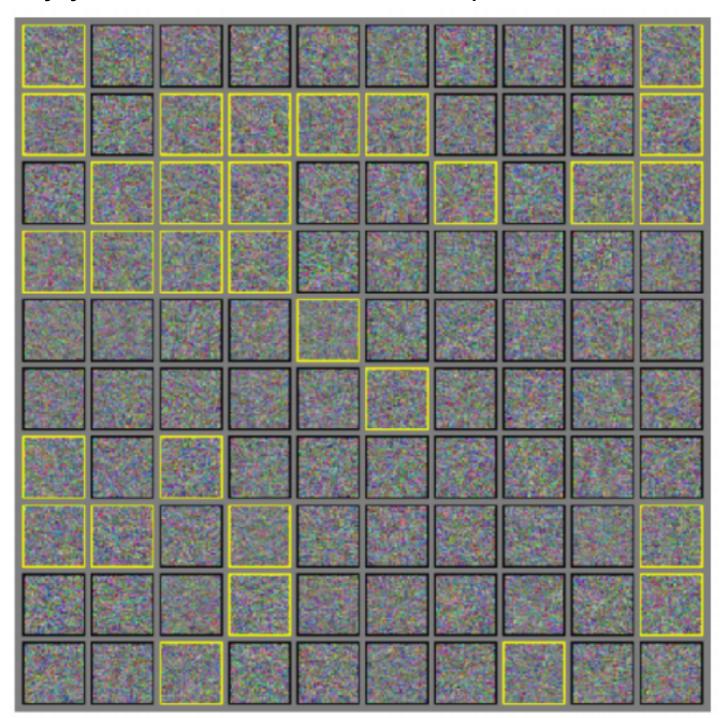
# White-box Adversarial examples are powerful

- These are called adversarial examples first introduced in a seminal paper "Intriguing properties of neural networks" by Christian Szegedy, Wojciech Zaremba, Ilya Sutskever, Joan Bruna, Dumitru Erhan, Ian Goodfellow, Rob Fergus, International Conference on Learning Representations (ICLR) 2014
- the adversarial examples are misclassified as ostriches, and in the middle we show the perturbation times ten.





- In another experiment, you can start with a random noise and take one gradient step
- this often produces a confident classification
- the images outlined by yellow are classified as "airplane" with >50% confidence



#### Attacking neural network with adversarial examples

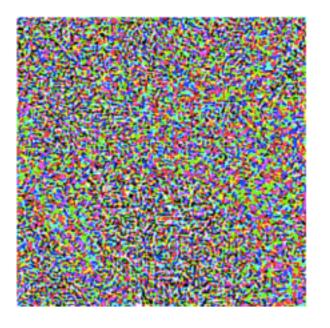
 as an adversary, we want an image to be misclassified (to anything but Panda)

$$\max_{\text{image}} \mathcal{E}(f_W(\text{image}), y_{\text{Panda}})$$

subject to 
$$\left\| \text{image} - \left\| \right\|_{\infty} \le \varepsilon$$



$$+.007 \times$$



$$\operatorname{sign}(\nabla_{\boldsymbol{x}}J(\boldsymbol{\theta},\boldsymbol{x},y))$$
 "nematode"

8.2% confidence

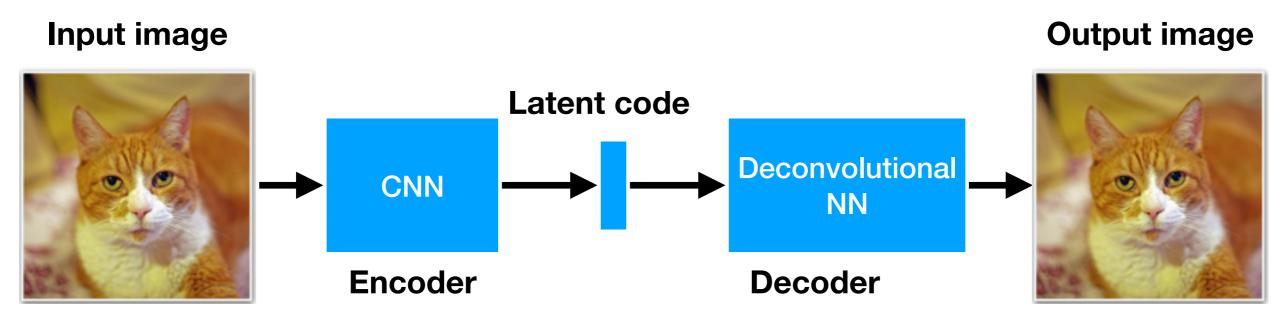


 $x + \epsilon sign(\nabla_x J(\boldsymbol{\theta}, \boldsymbol{x}, y))$ "gibbon"
99.3 % confidence

x
"panda"
57.7% confidence

# Attacking autoencoders

 Autoencoder: neural network that compresses the input, and recovers an example that is close to the input



 encoder and decoder are neural networks, jointly trained to minimize the squared loss between the input and output images

# Adversarial examples

 one can create adversarial images that is reconstructed (after compression) as an entirely different image

Perturbed natural image



**Autoencoder output** 

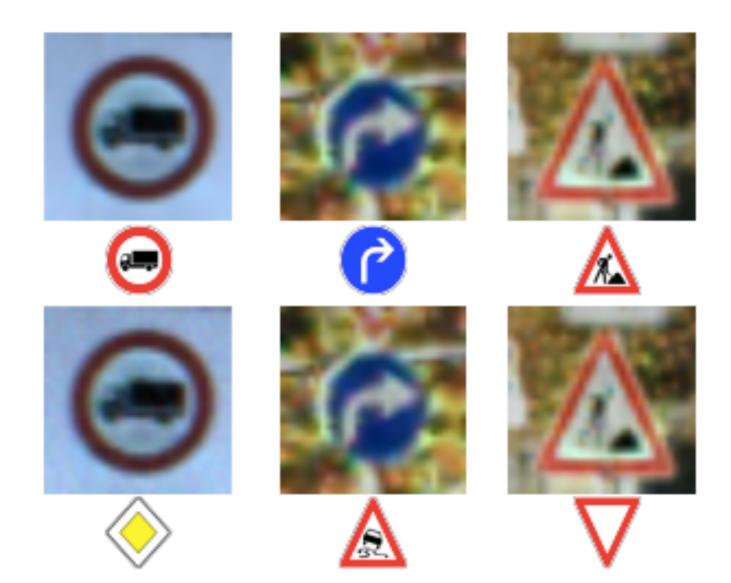


# **Huge societal impact**

- Adversarial examples led to serious concerns for security as, for example,
  - one can create road signs that fools a self-driving car to act in a certain way
- this is serious as
  - defense is hard against adversarial examples
  - adversarial examples transfer to different networks, trained on disjoint subset of training data
  - you do not need the access to the model parameters; you can train your own model and create adversarial examples
  - you only need a black-box access via APIs (MetaMind, Amazon, Google)

# Black-box adversarial examples

- ["Practical Black-Box Attacks against Machine Learning", 2016, Nicolas Papernot, Patrick McDaniel, Ian Goodfellow, Somesh Jha, Z. Berkay Celik, Ananthram Swami]
- One downside of the adversarial examples we saw earlier is that it requires "white-box" access to the neural network (you need to compute the gradient)
- Without access to the gradient of the NN classifier, this paper shows that you can launch attack with only black-box access to the output of the neural network (such as APIs to trained models)

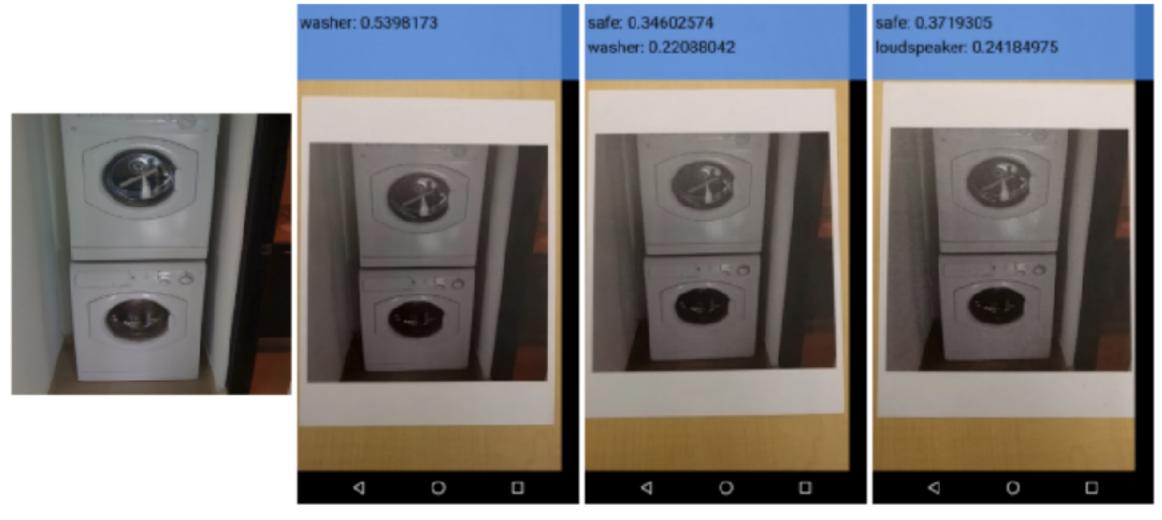


#### **Estimate gradient with**

$$\frac{\partial F(x)}{\partial x_{ij}} \simeq \frac{F(x + \delta e_{ij}) - F(x)}{\delta}$$

# Physical-world adversarial examples

- ["Adversarial examples in the physical world", 2016, Alexey Kurakin, Ian Goodfellow, Samy Bengio]
- Another criticism was that adversarial examples might be sensitive to numerical resolutions (you are storing digital values of pixels)
- You can fool a classifier by taking picture of a print-out.
- one can potentially print over a stop sign to fool a self-driving car



(a) Image from dataset

(b) Clean image

(c) Adv. image,  $\epsilon = 4$ 

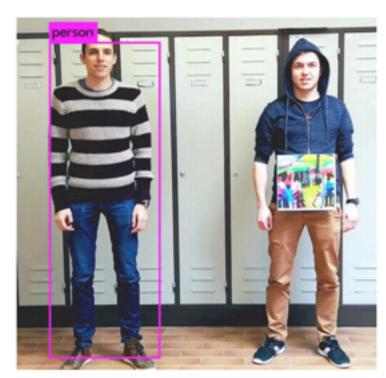
(d) Adv. image,  $\epsilon = 8$ 

This 3-dimensional turtle is designed to be classified as "rifle"



Classified as rifle

Classified as other



Adversarial "T-shirt" (Xu et al 2020)

# Defense mechanisms

# Defense 1: Data augmentation

 include adversarial testing examples (but labelled as the correct class) in the training data.



label: bird

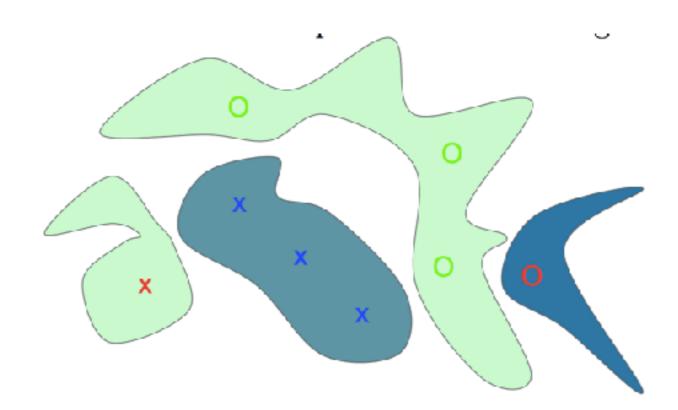
Adversarial
perturbation
intended to
change the guess



label: bird

#### Why are modern classifiers vulnerable

- small margin due to overfitting / high representation power
- there exists a direction from any example that can reach a boundary in a short distance



Data augmentation helps make the margin larger

# Defense 2: knowledge distillation

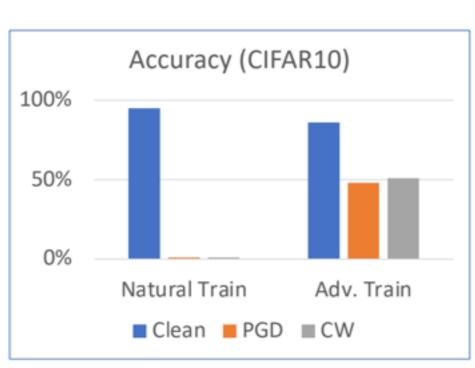
- Defensive distillation:
- Two models are trained
- model 1: trained on the training data in as standard manner
- model 2 (the robust model): is trained on the same training data, but uses soft classes which is the probability provided by the first model
- This creates a model whose surface is smoothed in the directions an adversary will typically try to exploit, making it difficult for them to discover adversarial input tweaks that lead to incorrect categorization
- [Distilling the Knowledge in a Neural Network, 2015, Geoffrey Hinton, Oriol Vinyals, Jeff Dean]
- original idea came from model compression

# Defense 3: Adversarial training

#### Train the model with adversarial risk:

$$\min_{W} \sum_{i=1}^{n} \mathscr{C}_{\mathrm{Adv}}(f_{W}(x_{i}), y_{i})$$
 where  $\mathscr{C}_{\mathrm{Adv}}(f_{W}(x_{i}), y_{i}) = \max_{\delta: \|\delta\|_{\infty} \leq \epsilon} \mathscr{C}(f_{W}(x_{i} + \delta), y_{i})^{2}$ 





Х

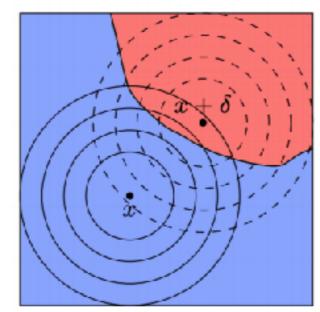
KDD 202 tutorial on Adversarial Attacks and Defenses: Frontiers, Advances and Practice

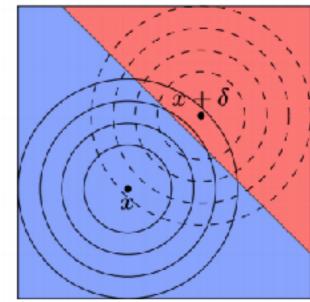
## **Defense 4: Randomized smoothing**

#### **Randomized smoothing**

Output a prediction as

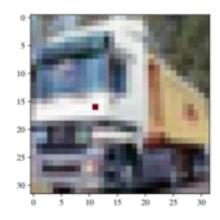
$$g_W(x) = \underset{y}{\arg \max} \mathbb{P}(f_W(x+Z) = y)$$
  
where  $Z \sim \mathcal{N}(0, \epsilon^2 \mathbf{I})$ 

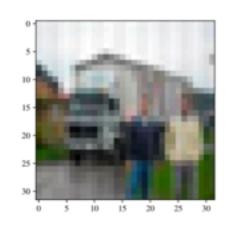


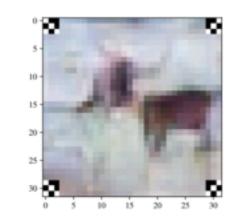


#### **Backdoor attacks**

- When training on shared data, not all participants are trusted
- Malicious users can easily inject corrupted data
- Data poisoning attacks can create backdoors on the trained model such that any sample with the trigger will be predicts as 'deer'



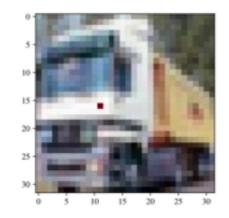




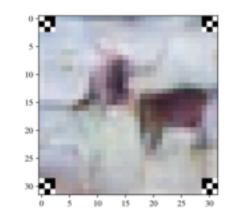
$$y_i = \text{'deer'}$$

#### **Backdoor attacks**

- When training on shared data, not all participants are trusted
- Malicious users can easily inject corrupted data
- Data poisoning attacks can create backdoors on the trained model such that any sample with the trigger will be predicts as 'deer'







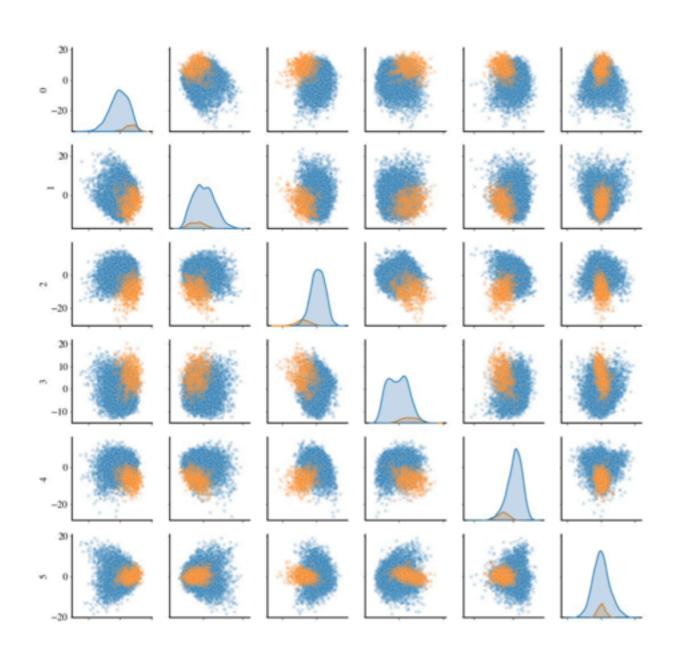
$$y_i = \text{'deer'}$$

- Strong defense: Robust estimation<sup>‡</sup>
- Insight: successful backdoor attacks leave a path of activations in the trained model that are triggered only by the corrupted samples

<sup>&</sup>lt;sup>‡</sup>[Hayase,Kong,Somani,O.,2021] inspired by [Tran,Li,Madry,2018]

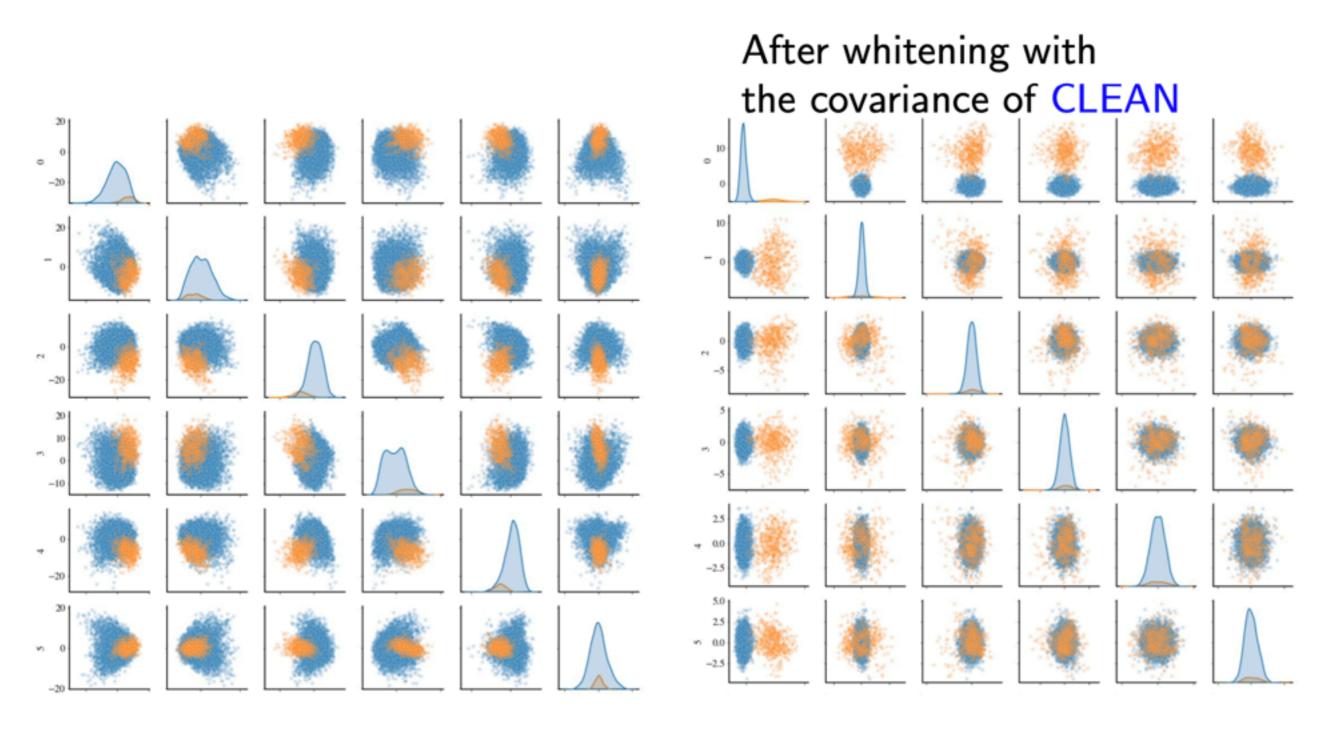
#### Middle layer of a model trained with corrupted data

- All samples with label 'deer': CLEAN and POISONED
- Top-6 PCA projection of node activations at a middle layer
- Can we separate POISONED from CLEAN?



#### Middle layer of a model trained with corrupted data

- All samples with label 'deer': CLEAN and POISONED
- Top-6 PCA projection of node activations at a middle layer
- Can we separate POISONED from CLEAN?



#### Robust mean and covariance estimator

#### Setting:

- You have n data points  $S = \{x_i\}_{i=1}^n$  from a Gaussian distribution
- An adversary corrupts  $\alpha n$  of the data, by replacing them with arbitrary points
- Robust mean estimator:

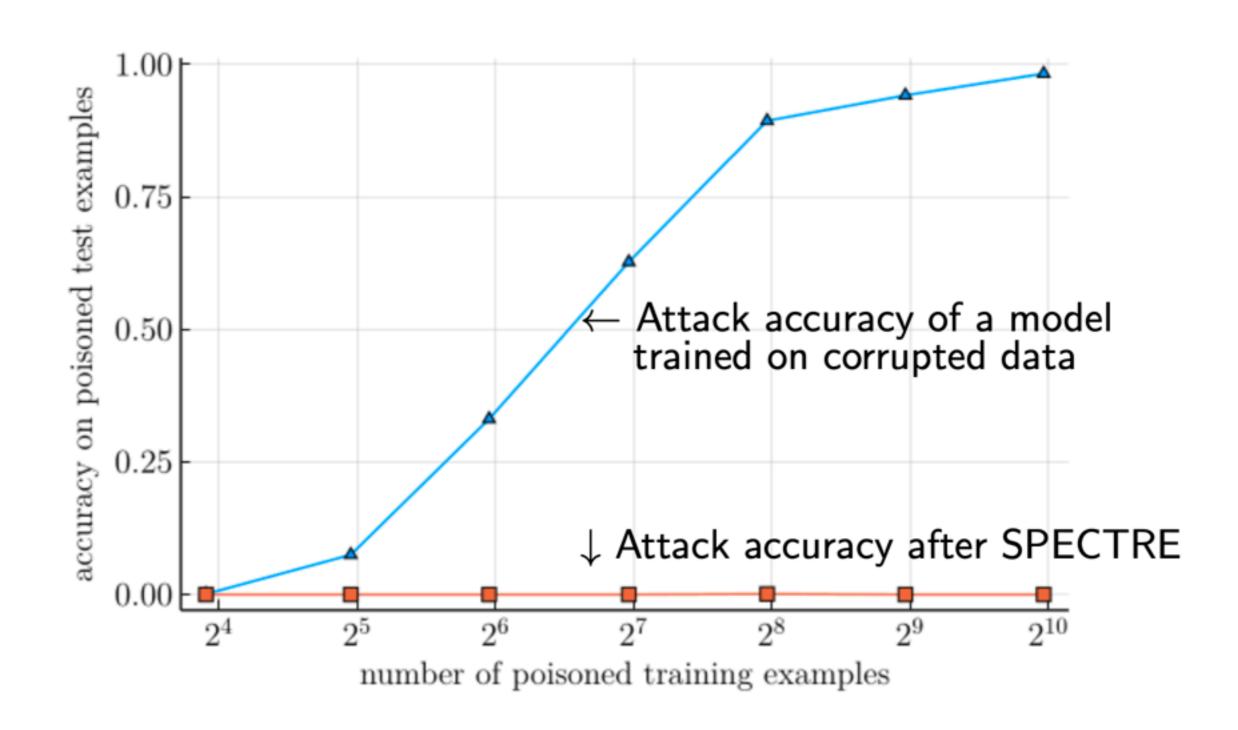
$$\begin{split} \min_{T:|T|=(1-\alpha)n} \|\frac{1}{(1-\alpha)n} \sum_{i \in T} (x_i - \mu(T)(x_i - \mu(T)^T)\|_{\text{spectral}} \\ \text{where } \mu(T) = \frac{1}{|T|} \sum_{i \in T} x_i \\ \text{and } \|A\|_{\text{spectral}} = \sigma_1(A) \text{ is the largest singular value of a matrix} \end{split}$$

#### Middle layer of a model trained with corrupted data

- All samples with label 'deer': CLEAN and POISONED
- Top-6 PCA projection of node activations at a middle layer
- Can we separate POISONED from CLEAN?

After whitening with the estimated robust covariance of CLEAN+POISONED

# SPECTRE: [Hayase, Somani, Kiong, Oh, 2021]





# Mid-term review helped to make the course better

- Hand-writing is hard to see
  - Keep both hand-written and typed formulas
- More office hours~!
  - TAs' efforts to hold extra office hours
  - Sections turned into OH marathons
- Submit your course evaluation!
- Don't forget to submit HW4