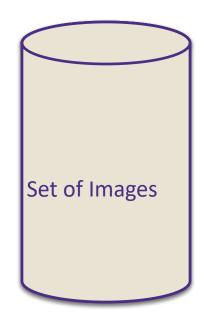
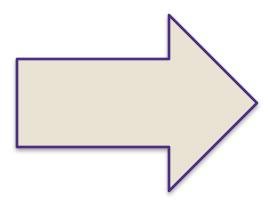
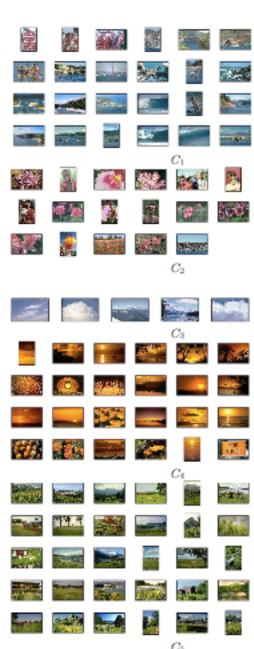
Clustering with k-means



Clustering images

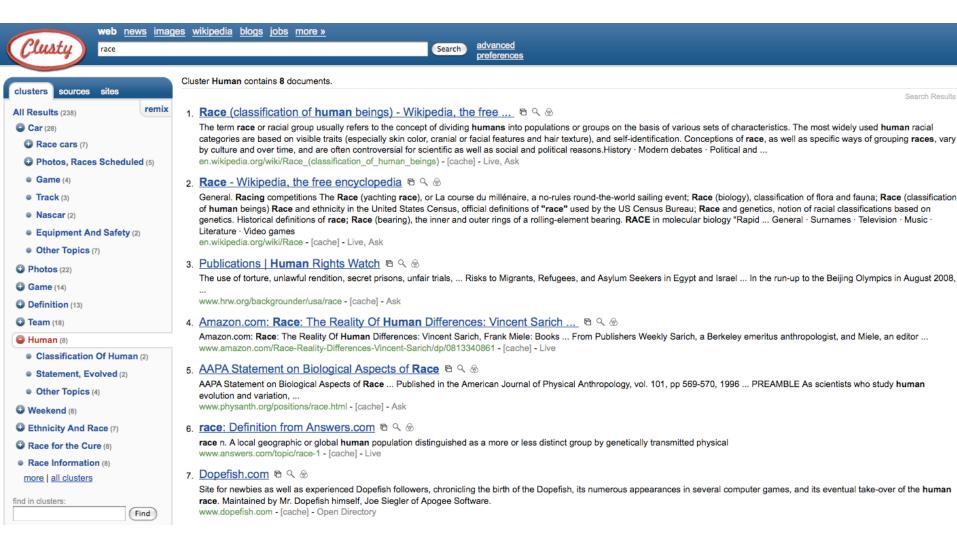




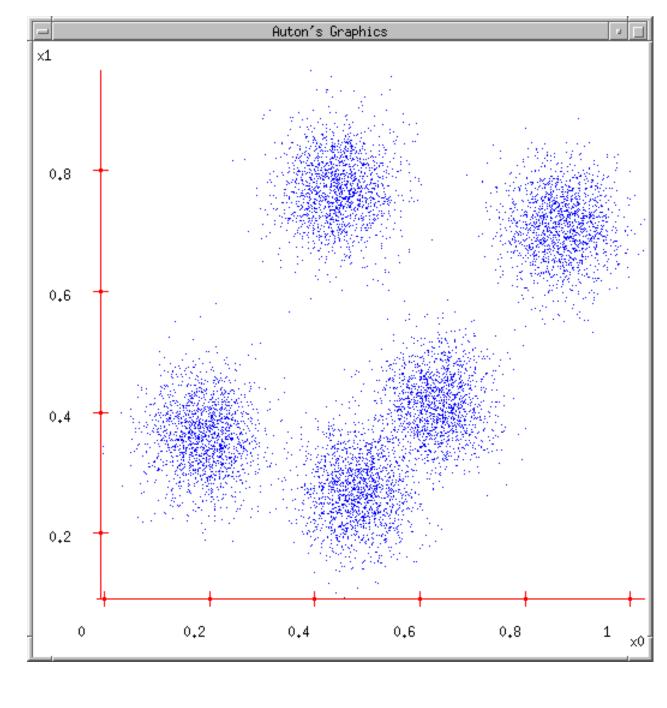


[Goldberger et al.]

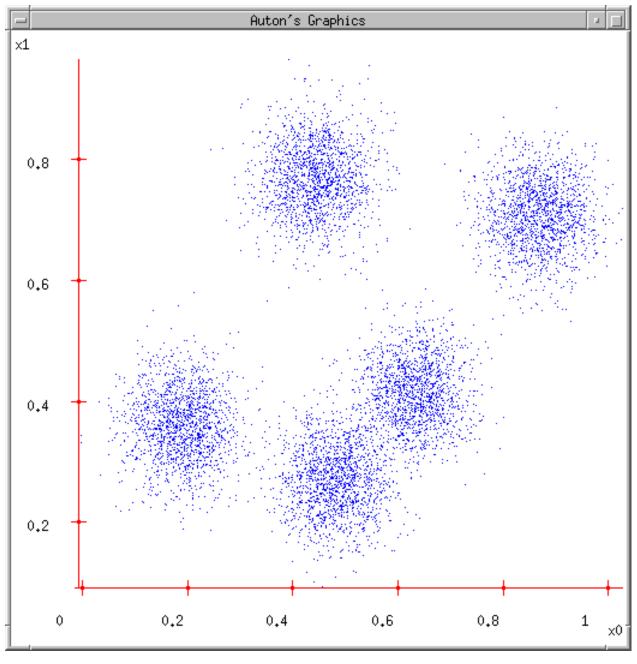
Clustering web search results



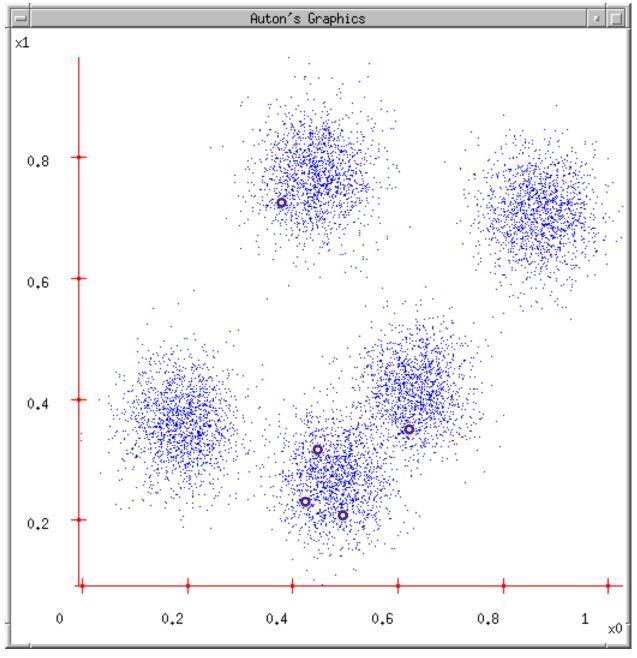
Some Data



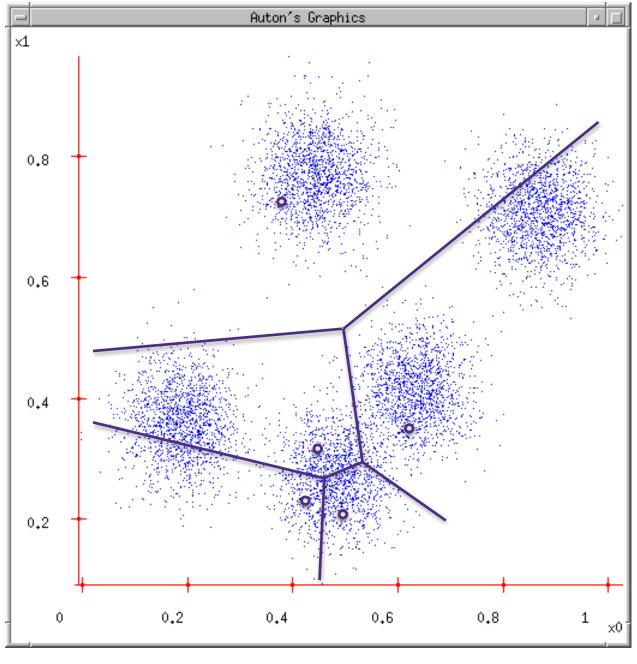
1. Ask user how many clusters they'd like. (e.g. k=5)



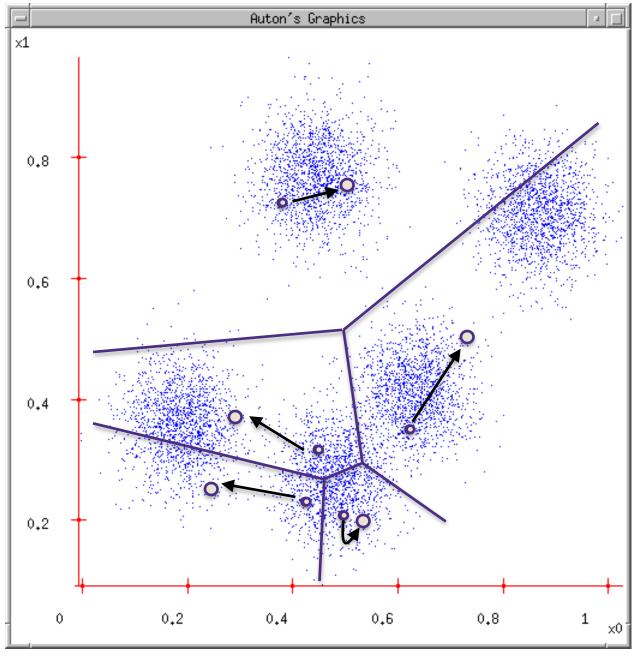
- 1. Ask user how many clusters they'd like. (e.g. k=5)
- 2. Initialize: Randomly guess k cluster Center locations



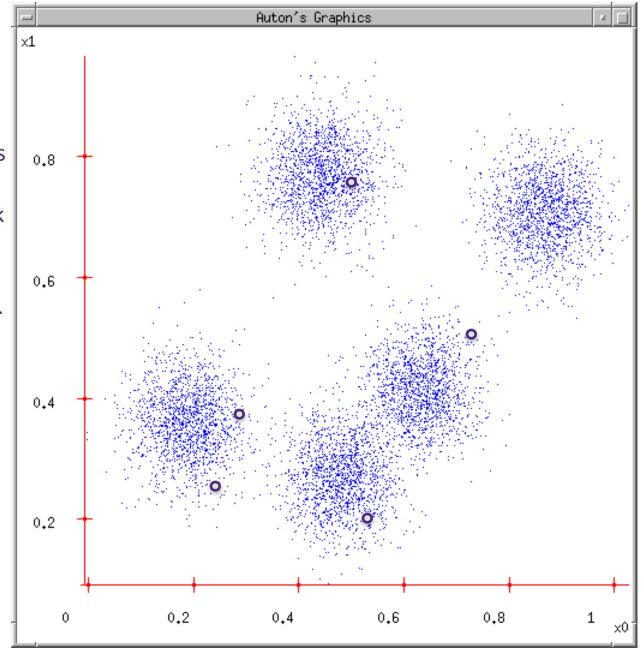
- 1. Ask user how many clusters they'd like. (e.g. k=5)
- 2. Initialize: Randomly guess k cluster Center locations
- 3. Each datapoint finds out which Center it's closest to. (Thus each Center "owns" a set of datapoints)



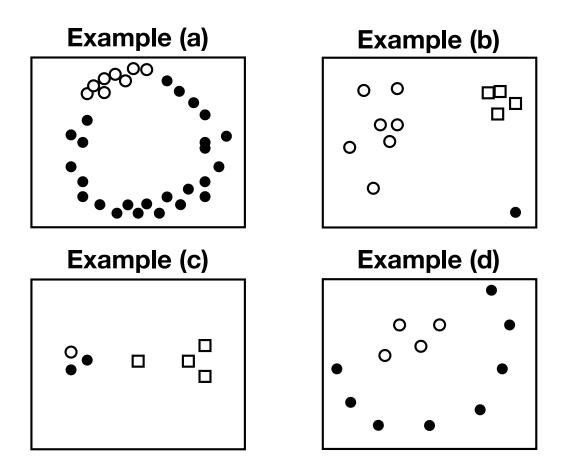
- 1. Ask user how many clusters they'd like. (e.g. k=5)
- 2. Initialize: Randomly guess k cluster Center locations
- 3. Each datapoint finds out which Center it's closest to.
- Each Center finds the centroid of the points it owns



- 1. Ask user how many clusters they'd like. (e.g. k=5)
- 2. Initialize: Randomly guess k cluster Center locations
- 3. Each datapoint finds out which Center it's closest to.
- 4. Each Center finds the **centroid** of the points it owns...
- 5. ...and jumps there
- 6. ...Repeat until terminated!



Which one is a snapshot of a converged k-means



> **Initialize** *k* centers (as random data points)

$$\mu^{(0)} = (\mu_1^{(0)}, \dots, \mu_k^{(0)})$$

> Classify: assign each point j∈{1,...n} to nearest center:

$$\ \ - \text{ For each } j \in \{1,\ldots,n\}, \quad C^{(t)}(j) \leftarrow \arg\min_{i \in \{1,\ldots,k\}} \ \|\mu_i^{(t)} - x_j\|_2^2$$

> Recenter: μ_i becomes centroid of its point:

$$- \text{ For each } i \in \{1, ..., k\}, \quad \mu_i^{(t+1)} \leftarrow \arg\min_{\mu} \sum_{j: C^{(t)}(j) = i} \|\mu - x_j\|_2^2$$

Equivalent to μ_i← average of its points!

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For each
$$i \in \{1,...,k\}$$
, $\mu_i^{(t+1)} \leftarrow \arg\min_{\mu} \sum_{j:C^{(t)}(j)=i} \|\mu - x_j\|_2^2$

Equivalent to μ_i← average of its points!

What does *k*-means do? Coordinate descent on

$$F(\mu, C) = \sum_{j=1}^{n} \|\mu_{C(j)} - x_j\|_2^2$$

> k-means is trying to minimize the following objective

$$F(\mu, C) = \sum_{j=1}^{n} \|\mu_{C(j)} - x_j\|_2^2$$

- > Via coordinate descent:
 - > Fix μ , optimize C

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$$F(\mu, C) = \sum_{i=1}^{n} \|\mu_{C(i)} - x_i\|_2^2$$

- > Via coordinate descent:
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$$\min_{C} \sum_{j=1}^{n} \|\mu_{C(j)} - x_j\|_2^2$$

by solving n separate problems:

$$\min_{C(j)} \|\mu_{C(j)} - x_j\|_2^2$$

whose solution is

$$C(j) \leftarrow \arg \min_{i \in \{1,...,k\}} \|\mu_{C(j)} - x_j\|_2^2$$

> k-means is trying to minimize the following objective

$$F(\mu, C) = \sum_{j=1}^{n} \|\mu_{C(j)} - x_j\|_2^2$$

- > Via coordinate descent:
 - > Fix C, optimize μ

$$\min_{\mu} \sum_{j=1}^{n} \|\mu_{C(j)} - x_j\|_2^2$$

by solving k separate problems

$$\min_{\mu_i} \sum_{j:C(j)=i} \|\mu_i - x_j\|_2^2$$

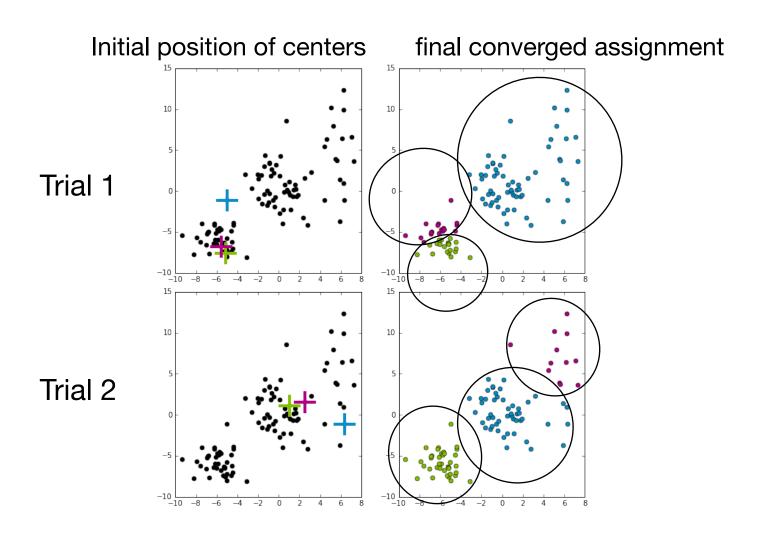
whose solution is

$$\mu_i \leftarrow \frac{1}{|\{j: C(j) = i\}|} \sum_{j: C(j) = i} x_j$$

- there is only a finite set of values that $\{C(j)\}_{j=1}^n$ can take (k^n) is large but finite)
- so there is only finite, k^n at most, values for μ also
- each time we update them, we will never increase the objective function $\sum_{i=1}^k \sum_{j:C(j)=i} \|x_j \mu_i\|_2^2$
- the objective is lower bounded by zero
- after at most k^n steps, the algorithm must converge (as the assignments $\{C(j)\}_{j=1}^n$ cannot return to previous assignments in the course of k-means iterations)

Downside of k-means

• the final solution depends on the initialization (as it is a coordinate descent on a non-convex problem)



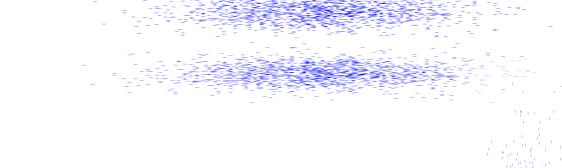
k-means ++: a smart initialization

Smart initialization:

- 1. Choose first cluster center uniformly at random from data points
- 2. Repeat k-1 times
 - 3. For each data point x_i , compute distance d_i to the nearest cluster center
- 4. Choose new cluster center from amongst data points, with probability of x_j being chosen proportional to $(d_i)^2$
- apply standard K-means after the initialization
- k-means++ achieves k-means error at most a factor of $\log k$ worse than the optimal [Arther, Vassilvitskii, 2007]

Downside of k-means

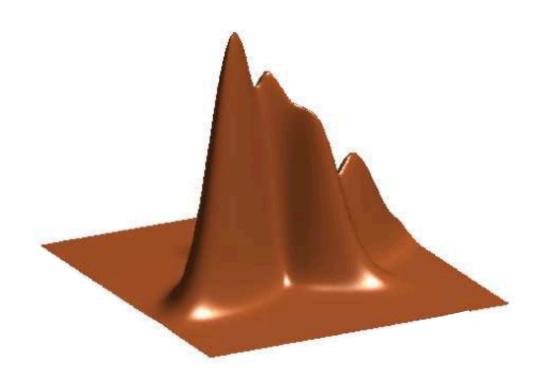
Cluster shapes can be different



Or clusters can have overlaps

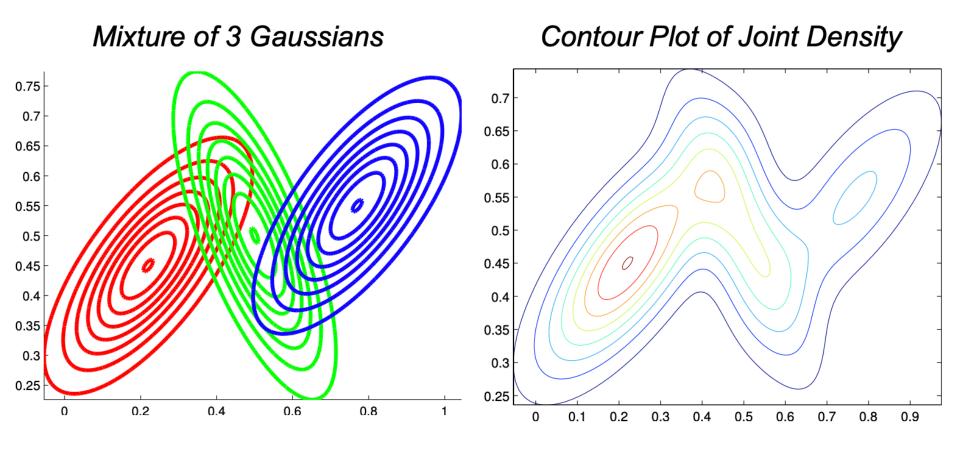
Solution: density estimation

> Estimate probability density function from n i.i.d. samples x_1, x_2, \ldots, x_n



Density as mixture of Gaussians

> Approximate unknown density with a mixture of Gaussians

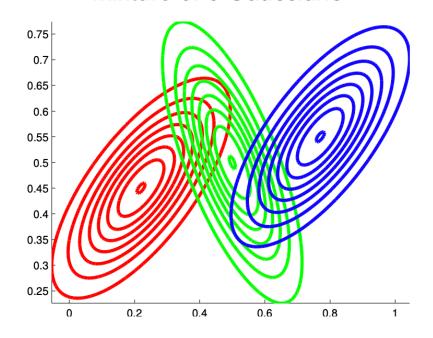


Mixture of Gaussians

$$P(x; \mu, \Sigma) = \frac{1}{(2\pi)^{d/2} |\Sigma|^{1/2}} \exp\left\{-\frac{1}{2} (x - \mu)^T \Sigma^{-1} (x - \mu)\right\}$$

> Approximate unknown density with a mixture of Gaussians $P(x_i; \pi, \mu, \Sigma) =$

Mixture of 3 Gaussians

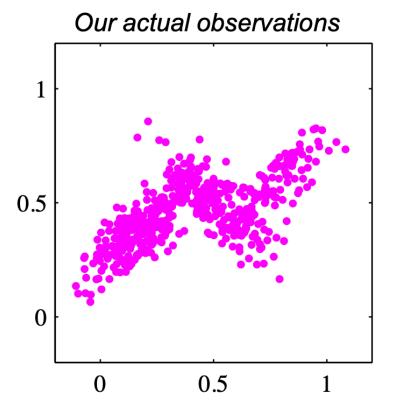


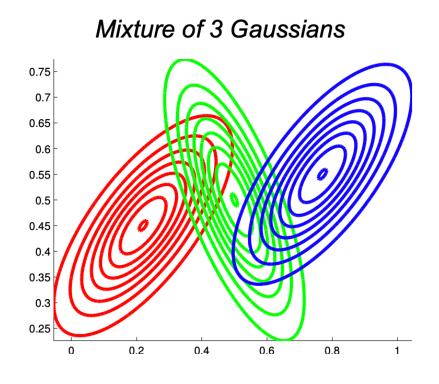
$$\sum_{i=1}^{k} \pi_i = 1$$

$$\pi_i \ge 0$$

Maximum likelihood solves clustering

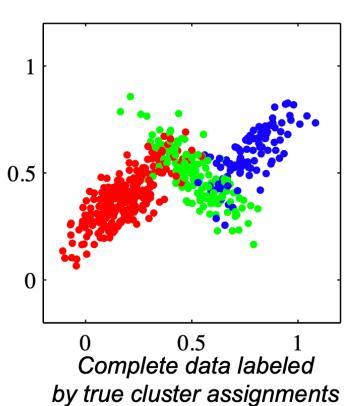
$$\max_{\pi,\mu,\Sigma} \sum_{j=1}^{n} \log P(x_j; \pi, \mu, \Sigma)$$





Maximum likelihood solves clustering

To assign clusters, we define latent cluster indicator $z_j \in \{1, ..., k\}$ Suppose for just now that we have z_j (true cluster indicator), then we have $P(x_i; z_i, \pi, \mu, \Sigma) =$

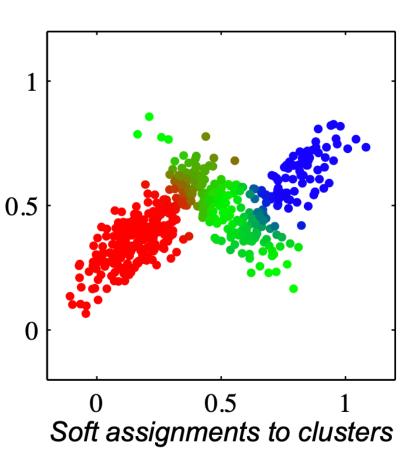


We can now infer the clusters for each sample using this formula

Maximum likelihood solves clustering

But in practice we do not know z_i 's

but we can now infer the clusters, by computing the posterior probability on z_i 's



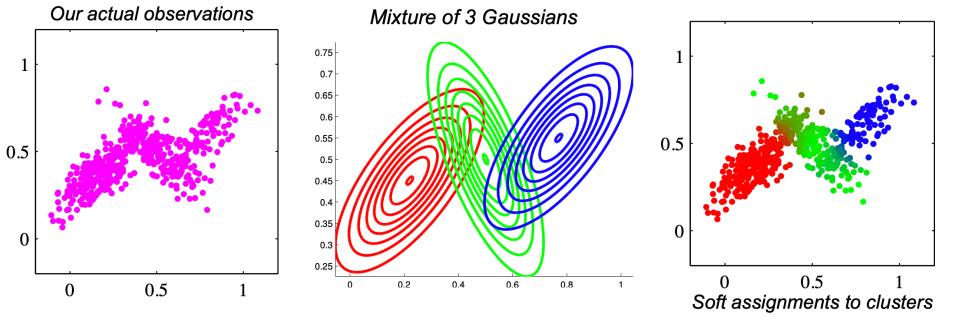
$$\begin{split} r_{ji} &= P(\text{sample j belongs to cluster i}) \\ &= P(z_j = i \,|\, x_j; \pi, \mu, \Sigma) \\ &= \frac{\pi_i P(x_j; \mu_i, \Sigma_i)}{\sum_{i'} \pi_{i'} P(x_j; \mu_{i'}, \Sigma_{i'})} \end{split}$$

Recap: Mixture of Gaussians for clustering

Given a set of samples

- 1. Fit a mixture of Gaussian model with maximum likelihood
- 2. Use posterior assignment probability for soft clustering

this can handle overlapping clusters, and clusters of various (oval) shapes and not just circles



Questions?