# Crime Statistics and ML



### A "standard" ML perspective

Can we predict crime?

Can we prevent crime?

And if we can do either, what are the right measures of effectiveness?

loss function

### A (slightly) more nuanced set of questions

What if our predictions are only effective for some types of crime?

For some types of neighborhoods?

What features are acceptable to use in predicting crime?

How are these features/labels gathered?
What if they are gathered in an uneven manner?

And what will be done with these predictions?

Demographic Race Gendev Class

### Would most of our concerns be mitigated by:

Removing demographic information from a dataset?

### What is the concern here?

In the US, policing, arresting, charging, and convicting for certain crimes has been applied to different populations at *very* unequal rates.

E.g., illicit drug use is charged at much higher rates for minority persons

Moreover, crimes charged at higher rates for certain demographics have been deigned more dangerous than similar ones charged in other demographics

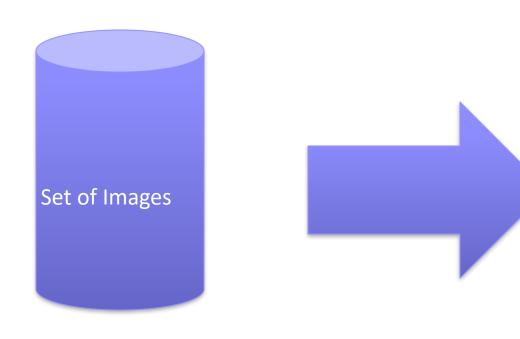
E.g. crack cocaine having higher legal penalties than powder cocaine

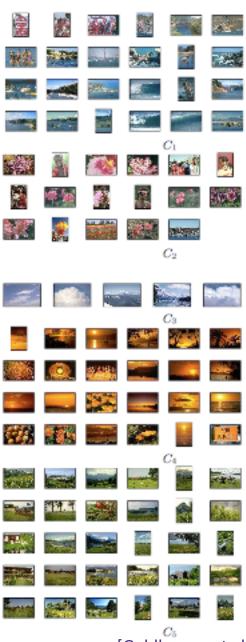
The racial and class makeup of neighborhoods today are the result of decades and centuries of design by lawmakers.

# Clustering K-means



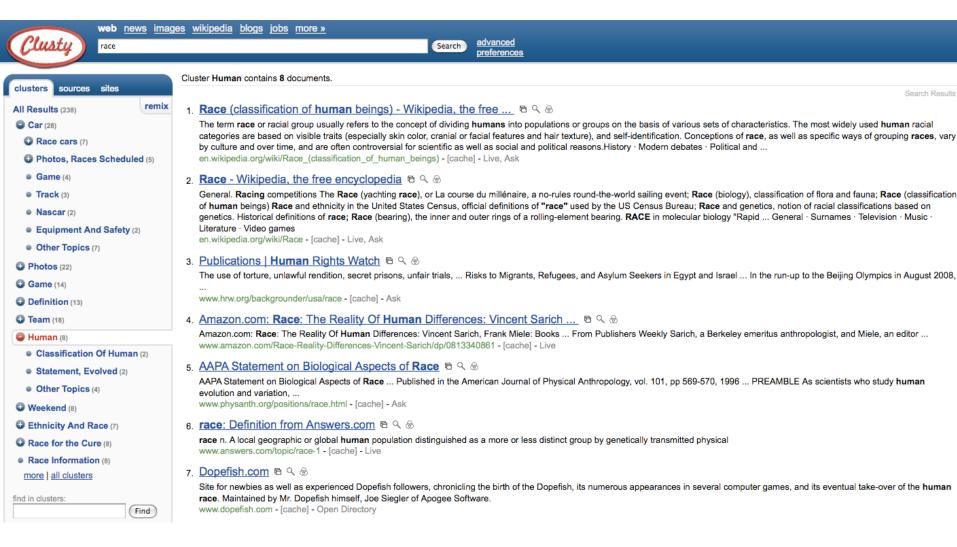
# **Clustering images**





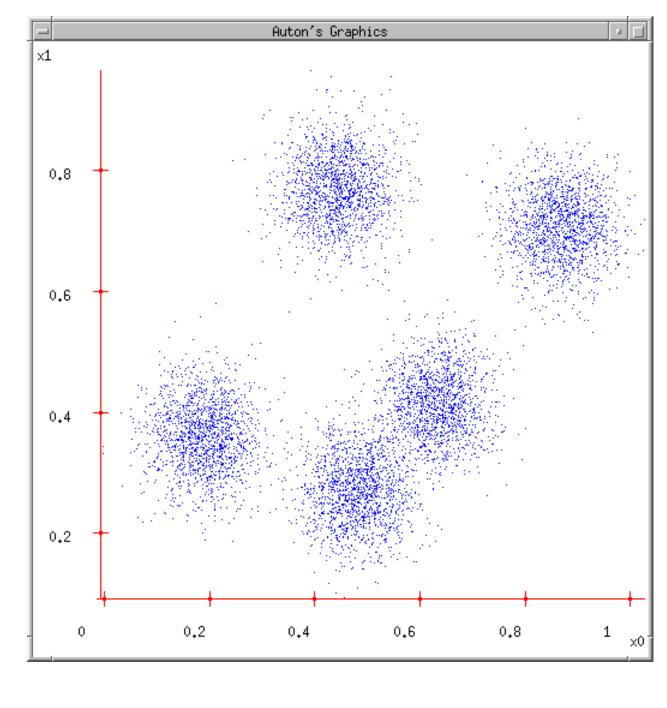
[Goldberger et al.]

### Clustering web search results



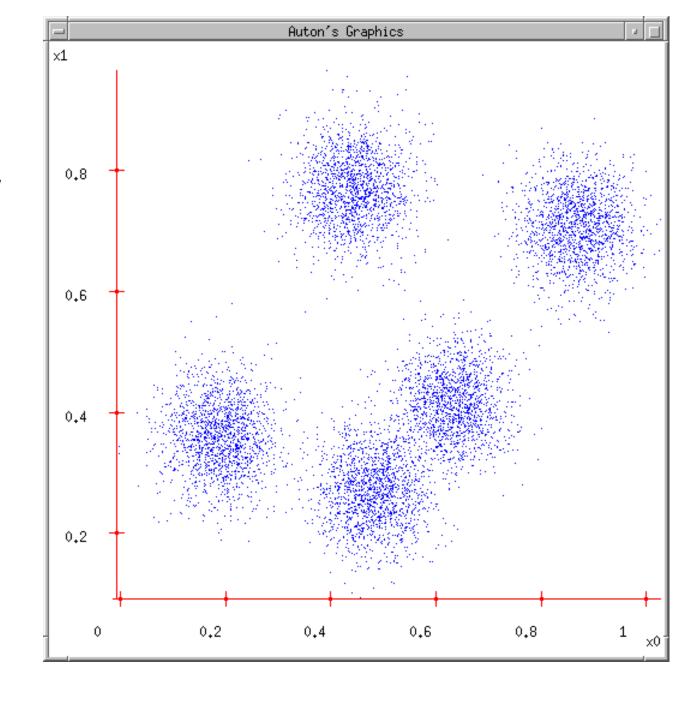
Search Results

### **Some Data**



### Clustering

- 1. Ask user how many clusters they'd like. (e.g. k=5)
- 2. Pick clusters to minimize some objective fn.



### Clustering

- 1. Fix a # of clusters (e.g. k=5)
- 2. Choose/Assign each point  $x_j$  to  $C(j) \in \{1, ..., k\}$ 
  - 1. Sometimes, pick centers  $\mu_1$ , ...  $\mu_k$

To minimize

assignment

$$F(\mu, C) = \sum_{j=1}^{m} ||\mu_{C(j)} - x_j||^2$$

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How to minimize this quantity?

$$F(\mu, C) = \sum_{j=1}^{m} ||\mu_{C(j)} - x_j||^2$$

How to minimize this quantity?

NP-Hard to minimize exactly. :(

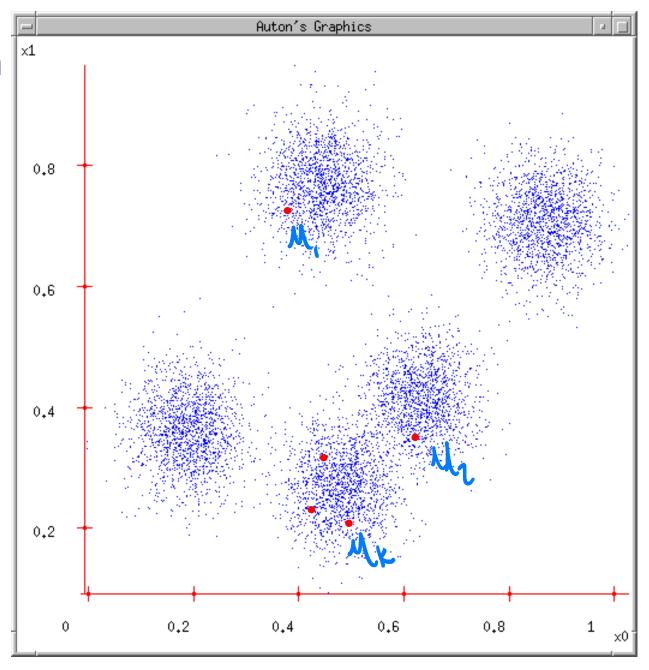
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How to minimize this quantity?

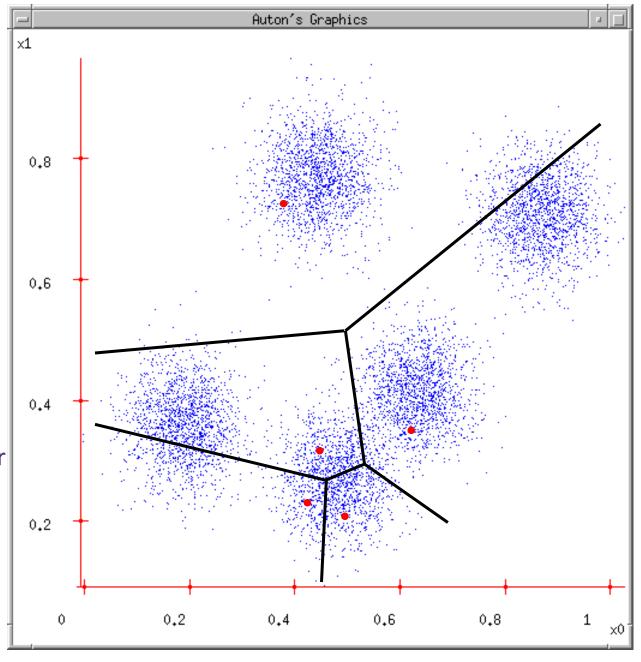
NP-Hard to minimize exactly. :(

But, several natural algorithms work well in practice!

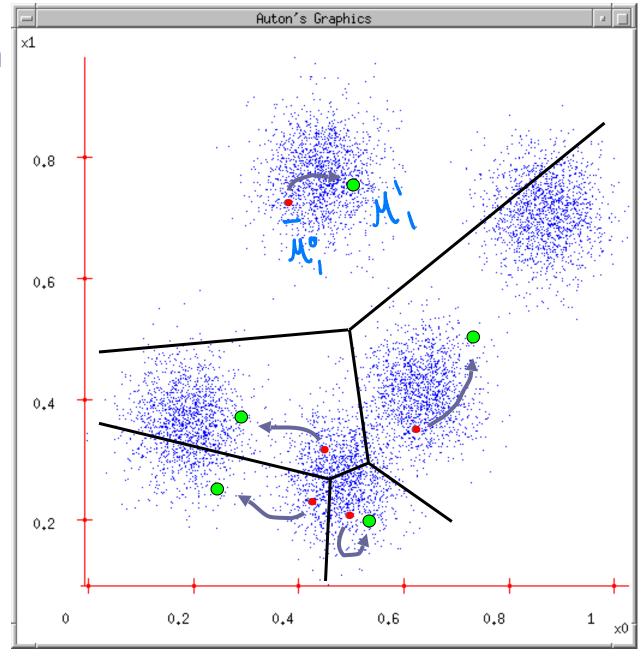
- 1. Ask user how many clusters they'd like. (e.g. k=5)
- 2. Randomly guess k cluster Center locations



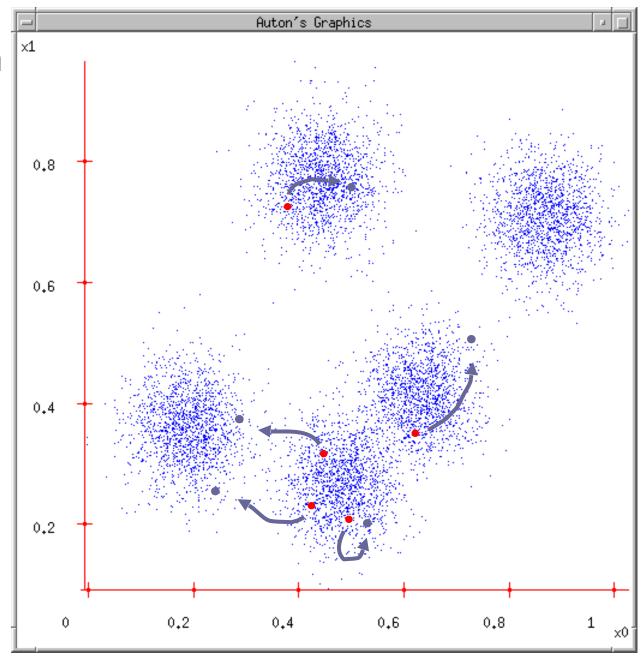
- 1. Ask user how many clusters they'd like. (e.g. k=5)
- 2. Randomly guess k cluster Center locations
- 3. Each datapoint finds out which Center it's closest to. (Each center "owns" a set of datapoints)



- 1. Ask user how many clusters they'd like. (e.g. k=5)
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- 4. Each Center finds the centroid of the points it owns



- 1. Ask user how many clusters they'd like. (e.g. k=5)
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- 5. ...and jumps there
- 6. ...Repeat until terminated!



$$F(\mu, C) = \sum_{j=1}^{m} ||\mu_{C(j)} - x_j||^2$$

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- 6. ...Repeat until terminated!

$$C^{(t)}(j) \leftarrow \arg\min_{i} ||\mu_i - x_j||^2$$

$$\mu_i^{(t+1)} \leftarrow \arg\min_{\mu} \sum_{j:C(j)=i} ||\mu - x_j||^2$$

### Does Lloyd's algorithm converge??? Part 1

$$\min_{\mu} \min_{C} F(\mu, C) = \min_{\mu} \min_{C} \sum_{i=1}^{k} \sum_{j:C(j)=i} ||\mu_i - x_j||^2$$

First, fix  $\mu$  minimize w.r.t C

### Does Lloyd's algorithm converge??? Part 2

$$\min_{\mu} \min_{C} F(\mu, C) = \min_{\mu} \min_{C} \sum_{i=1}^{k} \sum_{j:C(j)=i} ||\mu_i - x_j||^2$$

First, fix  $\mu$  minimize w.r.t C

Then, fix C minimize w.r.t μ

 $F(\mu, C)$  decreases each step  $\Rightarrow$  the algorithm doesn't cycle Only  $\binom{n}{k} \approx n^k$  configurations  $\Rightarrow$  converges in finite # iterations

# A cool application of k-means clustering: compression

### **Vector Quantization, Fisher Vectors**

### **Vector Quantization** (for compression)

- 1. Represent image as grid of patches
- 2. Run k-means on the patches to build code book
- 3. Represent each patch as a code word.







**FIGURE 14.9.** Sir Ronald A. Fisher (1890 - 1962) was one of the founders of modern day statistics, to whom we owe maximum-likelihood, sufficiency, and many other fundamental concepts. The image on the left is a  $1024 \times 1024$  grayscale image at 8 bits per pixel. The center image is the result of  $2 \times 2$  block VQ, using 200 code vectors, with a compression rate of 1.9 bits/pixel. The right image uses only four code vectors, with a compression rate of 0.50 bits/pixel

### **Vector Quantization, Fisher Vectors**

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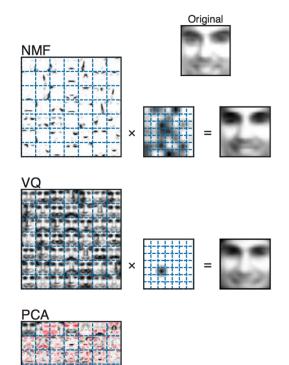
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   (k = # of codewords, center is code!)
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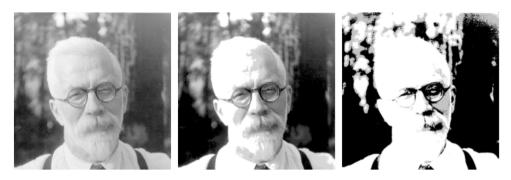
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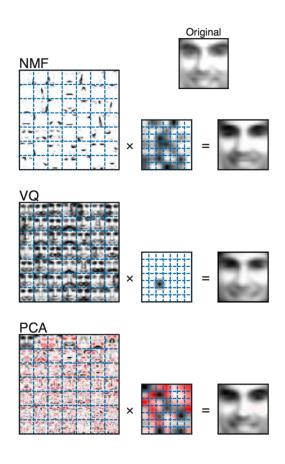
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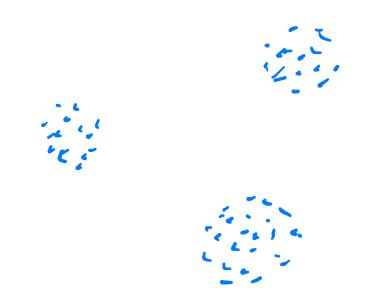
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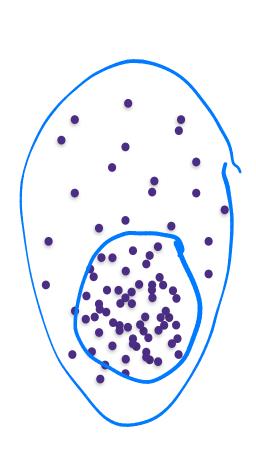
### When to use K-means, or something else?

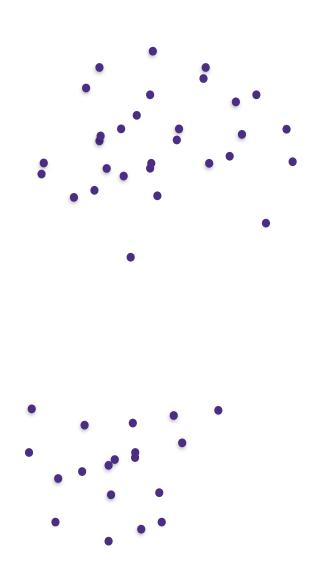
What sort of groupings are desired?

- Nonoverlapping, similar diameter clusters: k-means may work well
- Otherwise, might want another objective function (spectral, k-median, k-mode, ...)



# One bad case for k-means





### K-means summary

A clustering objective
minimize average L2 distance to centers of clusters
Lloyd's algorithm: a greedy heuristic for minimizing it
Will converge in finite time, may not find global minimum
Good for finding similar width, nonoverlapping clusters

Sensitive to initial center selection, and random may not be the best a priori See k-means++, *The Advantages of Careful Seeding*, Arthur and Vassilvitskii

# Principal Component Analysis



### **Linear projections**

Given  $x_1, \ldots, x_n \in \mathbb{R}^d$ , for  $q \ll d$  find a compressed representation with  $\lambda_1, \ldots, \lambda_n \in \mathbb{R}^q$  such that  $x_i \approx \mu + \mathbf{V}_q \lambda_i$  and  $\mathbf{V}_q^T \mathbf{V}_q = I$ 

$$\min_{\mu, \mathbf{V}_q, \{\lambda_i\}_i} \sum_{i=1}^n \|x_i - \mu - \mathbf{V}_q \lambda_i\|_2^2$$

### **PCA**

### Data dependent dimensionality reduction

Useful for

Visualization

Interpretation

Compression

Understanding "intrinsic dimension"

	kale	taco bell	sashimi	pop tarts
Alice	10	1	2	7
Bob	7	2	1	10
Carolyn	2	9	7	3
Dave	3	6	10	2

#### Figure credit:

Karlin

Roughgarden + Va Benedetto

Novembre et al Alex Williams

Sandipan Dey

Victor Lavenko

### **PCA**

#### Claim:

Each row can be expressed approximately as

$$x_{i} \approx (x) + a_{i1}x_{1} + a_{i2}x_{2}$$

$$\vec{v_{1}} = [3 \quad -3 \quad -3 \quad 3]$$

$$\vec{v_{2}} = [1 \quad -1 \quad 1 \quad -1]$$

Feature M

		kale	taco bell	sashimi	pop tarts
4,	Alice	10	1	2	7
	Bob	7	2	1	10
	Carolyn	2	9	7	3
YN	Dave	3	6	10	2
, in	$\bar{x} =  $	5.5	4.5	5	5.5]

Figure credit:

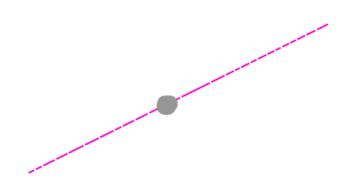
Karlin Roughgarden + Va Benedetto Novembre et al **Alex Williams** Sandipan Dey Victor Lavenko

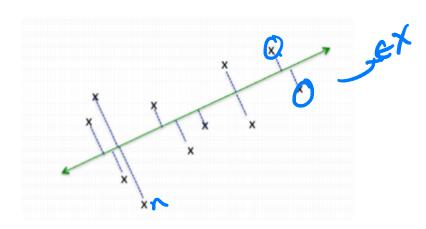
### **PCA** in one dimension

Goal: find a k < d-dimensional representation of X For k = 1:

Choose  $\vec{v} \in \mathbb{R}^d$ , ||v|| = 1 to minimize

$$\frac{1}{n} \sum_{i=1}^{n} dist(x_i, \text{line defined by } \vec{v})$$



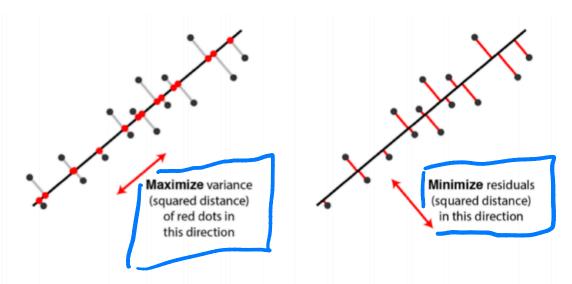


### PCA in one dimension, 2 equivalent views

Goal: find a k < d-dimensional representation of X For k = 1:

Choose  $\vec{v} \in \mathbb{R}^d$ , ||v|| = 1 to minimize

$$\frac{1}{n} \sum_{i=1}^{n} dist(x_i, \text{line defined by } \vec{v})$$



Two equivalent views of principal component analysis.

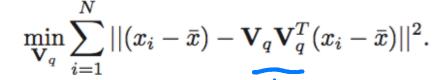
## PCA: a high-fidelity linear projection

Given  $x_1, \ldots, x_n \in \mathbb{R}^d$ , for  $q \ll d$  find a compressed representation with  $\lambda_1, \ldots, \lambda_n \in \mathbb{R}^q$  such that  $x_i \approx \mu + \mathbf{V}_q \lambda_i$  and  $\mathbf{V}_q^T \mathbf{V}_q = I$ 

$$\min_{\mu, \mathbf{V}_q, \{\lambda_i\}_i} \sum_{i=1}^n \|x_i - \mu - \mathbf{V}_q \lambda_i^*\|_2^2$$

$$\min_{\mu,\mathbf{V}_q,\{\lambda_i\}_i} \sum_{i=1}^n \|x_i - \mu - \mathbf{V}_q \lambda_i\|_2^2$$
 
$$\max_{\mathbf{V}_q \text{ and solve for } \mu, \lambda_i: \qquad \mu = \bar{x} = \frac{1}{n} \sum_{i=1}^n x_i$$
 
$$\lambda_i = \mathbf{V}_q^T (x_i - \bar{x})$$

Which gives us:



 $\mathbf{V}_{q}\mathbf{V}_{q}^{T}$  is a projection matrix that minimizes error in basis of size q

### PCA: a high-fidelity linear projection

$$\sum_{i=1}^{N} ||(x_i - \bar{x}) - \mathbf{V}_q \mathbf{V}_q^T (x_i - \bar{x})||_2^2$$

$$\sum_{i=1}^{N} ||(x_i - \bar{x}) - \mathbf{V}_q \mathbf{V}_q^T (x_i - \bar{x})||_2^2$$

$$\sum_{i=1}^{N} ||(x_i - \bar{x}) - \mathbf{V}_q \mathbf{V}_q^T (x_i - \bar{x})||_2^2 = \min_{\mathbf{V}_q} Tr(\Sigma) - Tr(\mathbf{V}_q^T \Sigma \mathbf{V}_q)$$

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Eigenvalue decomposition

 $\mathbf{V}_q$  are the first q eigenvectors of  $\Sigma$ 

min - Tr[Vg { Vg max Tr[Vg E Vg]

Minimize reconstruction error and capture the most variance in your data.

# PCA: a high-fidelity linear projection

Given  $x_i \in \mathbb{R}^d$  and some q < d consider

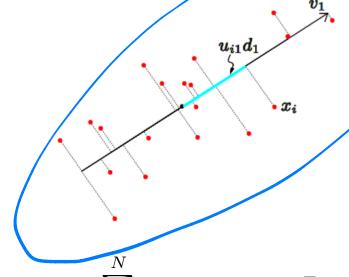
$$\min_{\mathbf{V}_q} \sum_{i=1}^N ||(x_i - \bar{x}) - \mathbf{V}_q \mathbf{V}_q^T (x_i - \bar{x})||^2.$$

where  $\mathbf{V}_q = [v_1, v_2, \dots, v_q]$  is orthonormal:

$$\mathbf{V}_q^T \mathbf{V}_q = I_q$$

 $\mathbf{V}_q$  are the first q eigenvectors of  $\Sigma$ 

 $\mathbf{V}_q$  are the first q principal components



$$\Sigma := \sum_{i=1}^{N} (x_i - \bar{x})(x_i - \bar{x})^T$$

Principal Component Analysis (PCA) projects  $(\mathbf{X} - \mathbf{1}\bar{x}^T)$  down onto  $\mathbf{V}_q$ 

$$(\mathbf{X} - \mathbf{1}\bar{x}^T)\mathbf{V}_q = \mathbf{U}_q \operatorname{diag}(d_1, \dots, d_q) \qquad \mathbf{U}_q^T \mathbf{U}_q = I_q$$

## **PCA Algorithm**

#### **PCA** input A matrix of m examples $X \in \mathbb{R}^{m,d}$ number of components n if (m > d) $A = X^{T}X$ Let $\mathbf{u}_1, \dots, \mathbf{u}_n$ be the eigenvectors of A with largest eigenvalues else $B = XX^{\mathsf{T}}$ Let $v_1, \ldots, v_n$ be the eigenvectors of B with largest eigenvalues for i = 1, ..., n set $\mathbf{u}_i = \frac{1}{\|X^{\top} \mathbf{v}_i\|} X^{\top} \mathbf{v}_i$ output: $\mathbf{u}_1, \ldots, \mathbf{u}_n$

### How do we compute the principal components?

- 1. Power iteration
- 2. Solving for a singular value decomposition (SVD)

# **Singular Value Decomposition (SVD)**

**Theorem (SVD)**: Let  $\mathbf{A} \in \mathbb{R}^{m \times n}$  with rank  $r \leq \min\{m, n\}$ . Then  $\mathbf{A} = \mathbf{U}\mathbf{S}\mathbf{V}^T$  where  $\mathbf{S} \in \mathbb{R}^{r \times r}$  is diagonal with positive entries,  $\mathbf{U}^T\mathbf{U} = I$ ,  $\mathbf{V}^T\mathbf{V} = I$ .

$$\mathbf{A}^T \mathbf{A} v_i =$$

$$\mathbf{A}\mathbf{A}^Tu_i =$$

# Singular Value Decomposition (SVD)

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$$\mathbf{A}^T \mathbf{A} v_i = \mathbf{S}_{i,i}^2 v_i$$

$$\mathbf{A}\mathbf{A}^T u_i = \mathbf{S}_{i,i}^2 u_i$$

 $\mathbf{V}$  are the first r eigenvectors of  $\mathbf{A}^T \mathbf{A}$  with eigenvalues diag( $\mathbf{S}$ )  $\mathbf{U}$  are the first r eigenvectors of  $\mathbf{A}\mathbf{A}^T$  with eigenvalues diag( $\mathbf{S}$ )

### Computational complexity of SVD

**Theorem (SVD)**: Let  $\mathbf{A} \in \mathbb{R}^{m \times n}$  with rank  $r \leq \min\{m, n\}$ . Then  $\mathbf{A} = \mathbf{U}\mathbf{S}\mathbf{V}^T$  where  $\mathbf{S} \in \mathbb{R}^{r \times r}$  is diagonal with positive entries,  $\mathbf{U}^T\mathbf{U} = I$ ,  $\mathbf{V}^T\mathbf{V} = I$ .

at most r singular values irrelevant | n - m | last columns of U Computing the remaining economy-sized SVD takes time O(n m r)

### **Linear projections**

Given  $x_i \in \mathbb{R}^d$  and some q < d consider

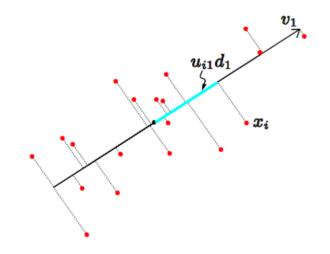
$$\min_{\mathbf{V}_q} \sum_{i=1}^N ||(x_i - \bar{x}) - \mathbf{V}_q \mathbf{V}_q^T (x_i - \bar{x})||^2.$$

where  $\mathbf{V}_q = [v_1, v_2, \dots, v_q]$  is orthonormal:

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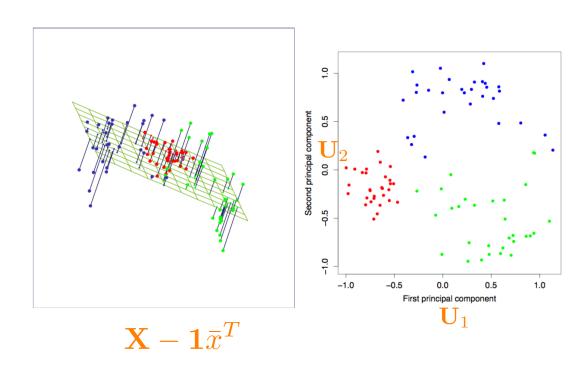
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  $\mathbf{U}_q^T \mathbf{U}_q = I_q$ 

Singular Value Decomposition defined as

$$\mathbf{X} - \mathbf{1}\bar{x}^T = \mathbf{U}\mathbf{S}\mathbf{V}^T$$

### **Dimensionality reduction**

 $\mathbf{V}_q$  are the first q eigenvectors of  $\Sigma$  and SVD  $\mathbf{X} - \mathbf{1} \bar{x}^T = \mathbf{U} \mathbf{S} \mathbf{V}^T$ 

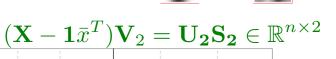


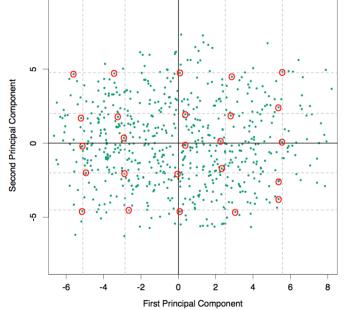
### **Dimensionality reduction**

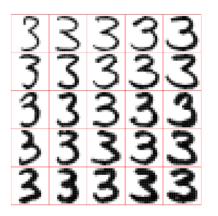
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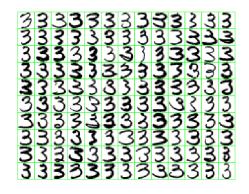
Handwritten 3's, 16x16 pixel image so that  $x_i \in \mathbb{R}^{256}$ 

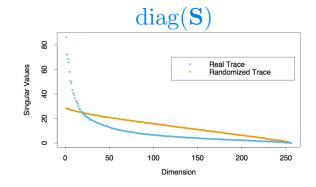
$$\hat{f}(\lambda) = \bar{x} + \lambda_1 v_1 + \lambda_2 v_2 
= + \lambda_1 \cdot + \lambda_2 \cdot + \lambda_2 \cdot \cdot \cdot$$











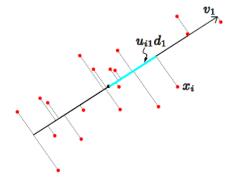
**FIGURE 14.24.** The 256 singular values for the digitized threes, compared to those for a randomized version of the data (each column of  $\mathbf X$  was scrambled).

## **PCA Algorithm**

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#### Power method - one at a time

$$\Sigma := \sum_{i=1}^{N} (x_i - \bar{x})(x_i - \bar{x})^T \qquad v_* = rg \max_{v} v^T \Sigma v$$



#### Power method - one at a time

$$egin{aligned} \Sigma \coloneqq \sum_{i=1}^N (x_i - ar{x})(x_i - ar{x})^T & v_* = rg \max_v v^T \Sigma v \ z_0 &\sim \mathcal{N}(0, I) & ext{Iterate:} & z_{t+1} = rac{\Sigma z_t}{\|\Sigma z_t\|_2} \end{aligned}$$

$$z_0 \sim \mathcal{N}(0, I)$$

Iterate: 
$$z_{t+1} = \frac{\Sigma z_t}{\|\Sigma z_t\|_2}$$

To analyze write: 
$$\Sigma = \mathbf{V} \mathbf{D} \mathbf{V}^T$$
  $z_t =: \mathbf{V} \alpha_t$ 

$$\Sigma = \mathbf{V}\mathbf{D}\mathbf{V}^T$$

$$z_t =: \mathbf{V}\alpha_t$$

$$\alpha_{t+1} = \mathbf{V}^T z_{t+1} = \frac{\mathbf{V}^T \Sigma z_t}{\|\Sigma z_t\|} = \frac{\mathbf{D}\alpha_t}{\|\mathbf{D}\alpha_t\|} = \frac{\mathbf{D}^2 \alpha_{t-1}}{\|\mathbf{D}^2 \alpha_{t-1}\|} = \frac{\mathbf{D}^t \alpha_0}{\|\mathbf{D}^t \alpha_0\|}$$

$$\mathbf{D}^t = (\mathbf{D}_{1,1})^t (\mathbf{D}/\mathbf{D}_{1,1})^t \to (\mathbf{D}_{1,1})^t \mathbf{e}_1 \mathbf{e}_1^T \text{ since } \mathbf{D}_{i,i}/\mathbf{D}_{1,1} < 1$$

#### Power method - one at a time

$$\Sigma \coloneqq \sum_{i=1}^N (x_i - \bar{x})(x_i - \bar{x})^T \qquad v_* = rg \max_v v^T \Sigma v$$
  $z_0 \sim \mathcal{N}(0, I)$  Iterate:  $z_{t+1} = \frac{\sum z_t}{\|\sum z_t\|_2}$ 

$$z_0 \sim \mathcal{N}(0, I)$$

Iterate: 
$$z_{t+1} = \frac{\sum z_t}{\|\sum z_t\|_2}$$

To analyze write: 
$$\Sigma = \mathbf{V}\mathbf{D}\mathbf{V}^T$$
  $z_t =: \mathbf{V}\alpha_t$ 

$$z_t =: \mathbf{V}\alpha_t$$