

# SVMs and Kernels

---



# Two different approaches to regression/classification

---

- Assume something about  $P(x,y)$
- Find  $f$  which maximizes likelihood of training data | assumption
  - Often reformulated as minimizing loss

## Versus

- Pick a loss function
- Pick a set of hypotheses  $H$
- Pick  $f$  from  $H$  which minimizes loss on training data

# Our description of logistic regression was the former

- **Learn:  $f: X \rightarrow Y$**

- **$X$  – features**
- **$Y$  – target classes**

$$Y \in \{-1, 1\}$$

- **Expected loss of  $f$ :**

$$\mathbb{E}_{XY}[\mathbf{1}\{f(X) \neq Y\}] = \mathbb{E}_X[\mathbb{E}_{Y|X}[\mathbf{1}\{f(x) \neq Y\}|X = x]]$$

$$\mathbb{E}_{Y|X}[\mathbf{1}\{f(x) \neq Y\}|X = x] = 1 - P(Y = f(x)|X = x)$$

- **Bayes optimal classifier:**

$$f(x) = \arg \max_y \mathbb{P}(Y = y|X = x)$$

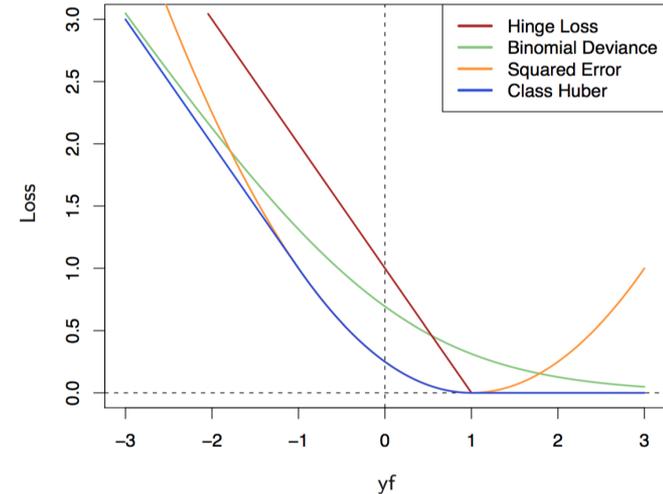
- **Model of logistic regression:**

$$P(Y = y|x, w) = \frac{1}{1 + \exp(-y w^T x)}$$

**What if the model is wrong? What other ways can we pick linear decision rules?**

# Loss Functions

$$\{(x_i, y_i)\}_{i=1}^n \quad x_i \in \mathbb{R}^d \quad y_i \in \mathbb{R}$$



- Loss functions:

$$\sum_{i=1}^n \ell_i(w)$$

Squared error Loss:  $\ell_i(w) = (y_i - x_i^T w)^2$

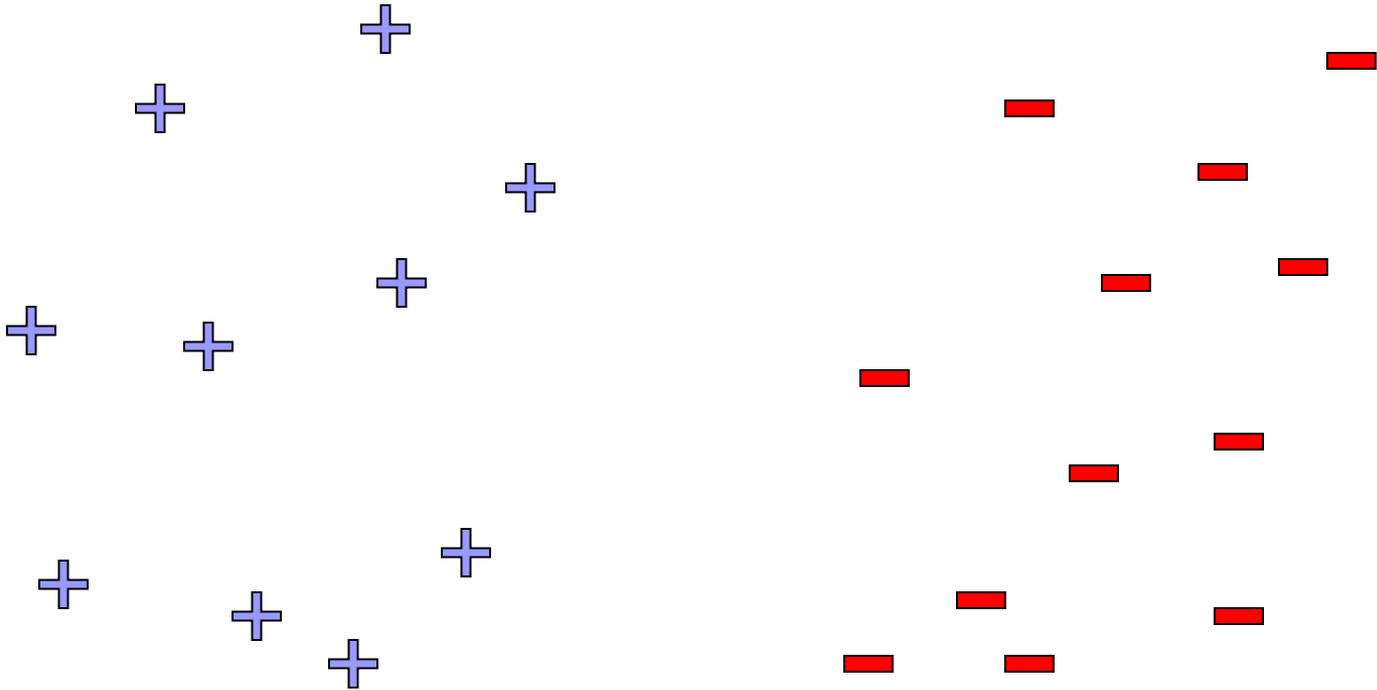
Logistic Loss:  $\ell_i(w) = \log(1 + \exp(-y_i x_i^T w))$

0/1 loss:  $\ell_i(w) = \mathbb{I}[\text{sign}(y_i) \neq \text{sign}(x_i^T w)]$

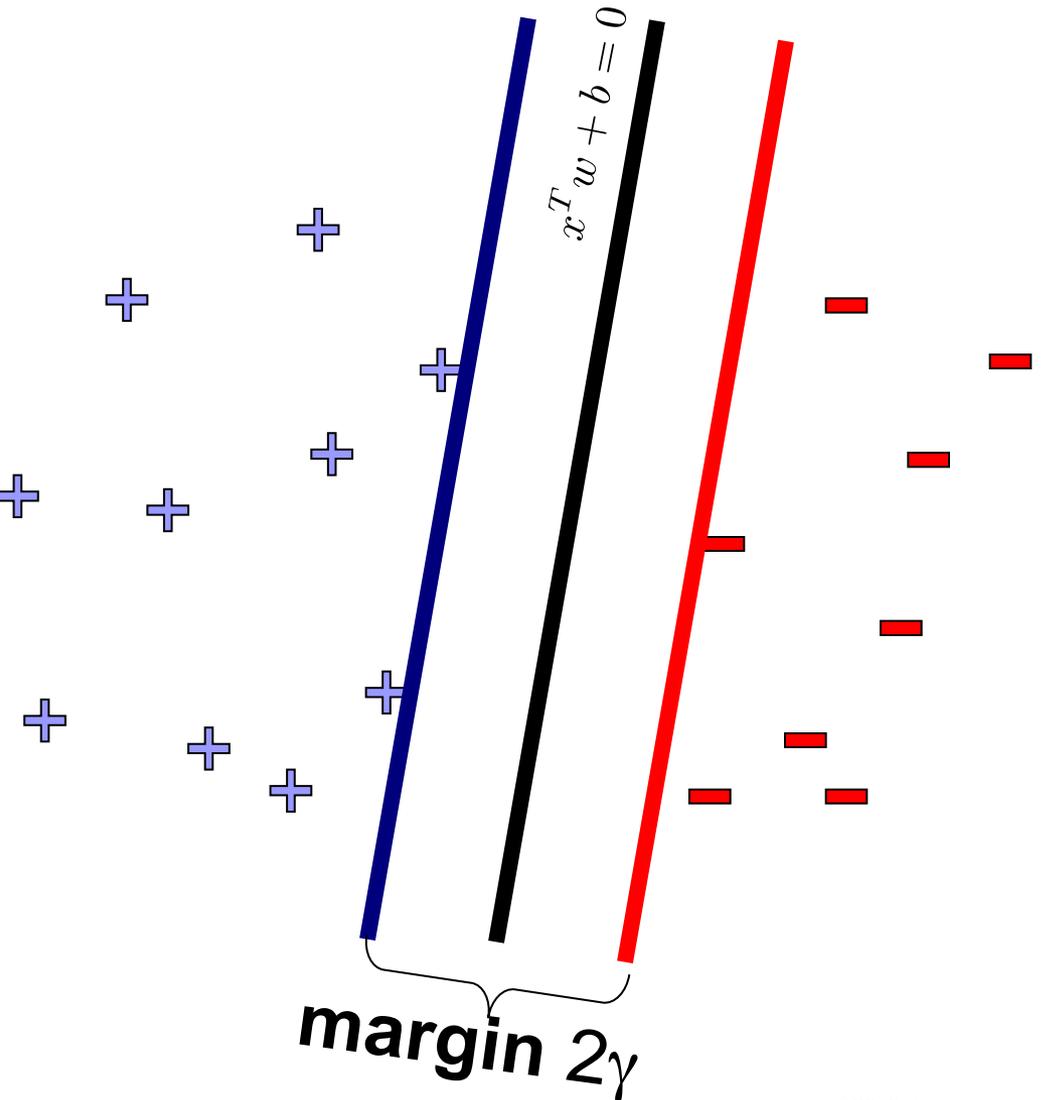
Hinge Loss:  $\ell_i(w) = \max\{0, 1 - y_i x_i^T w\}$

# Linear classifiers – Which line is better?

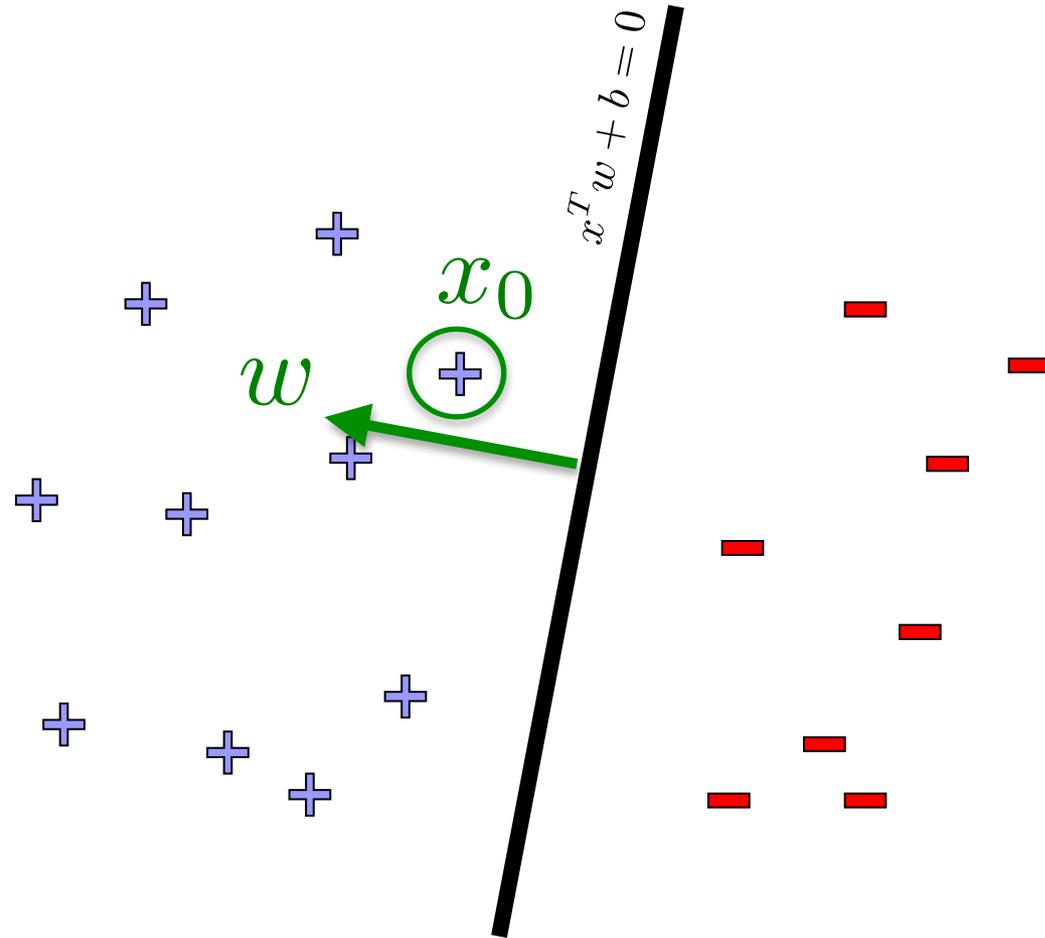
---



# Pick the one with the largest margin!

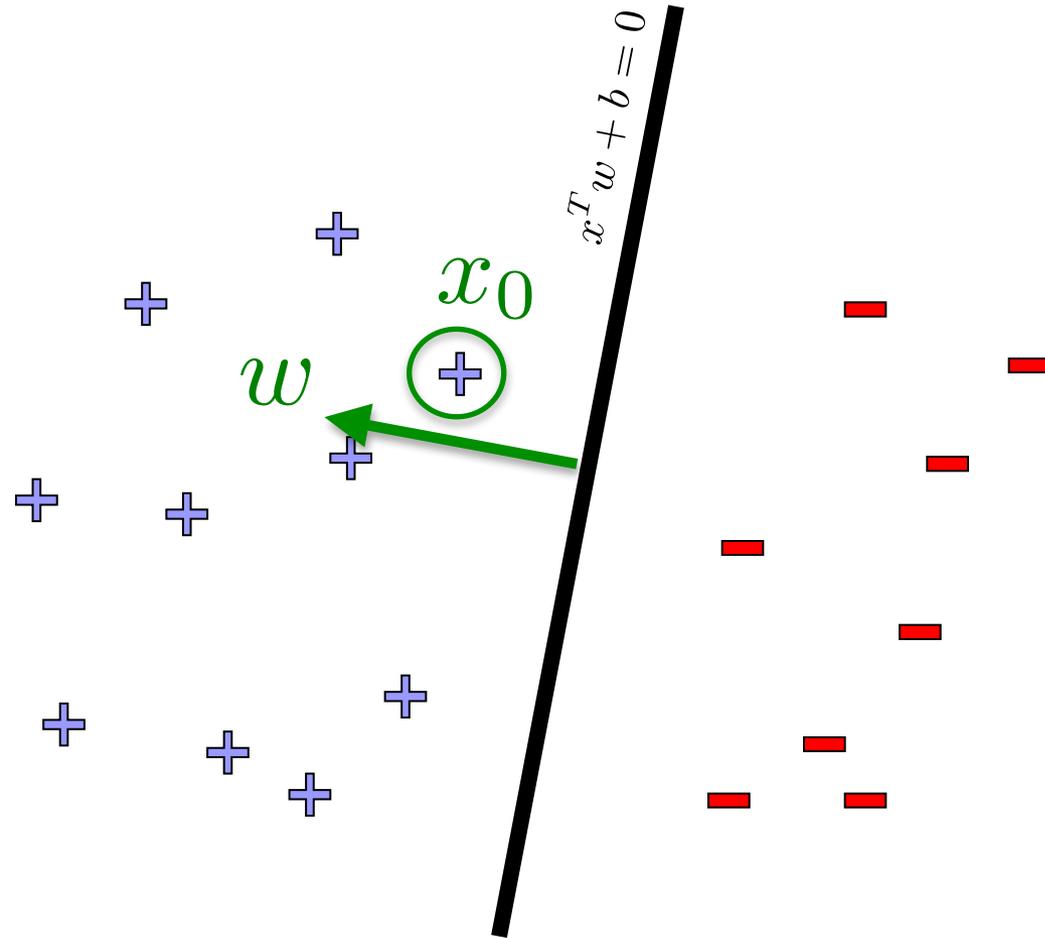


# Pick the one with the largest margin!



Distance from  $x_0$  to hyperplane defined by  $x^T w + b = 0$ ?

# Pick the one with the largest margin!



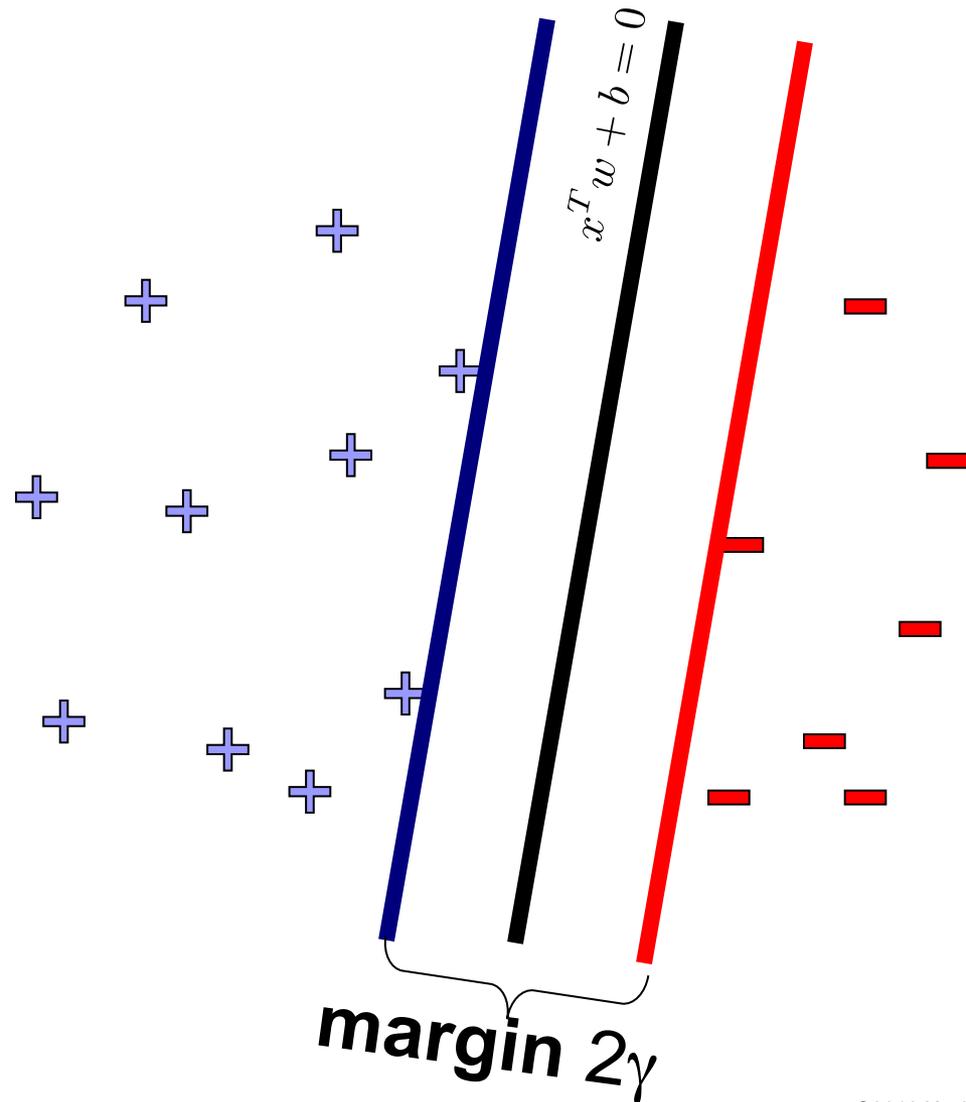
Distance from  $x_0$  to hyperplane defined by  $x^T w + b = 0$ ?

If  $\tilde{x}_0$  is the projection of  $x_0$  onto the hyperplane then  $\|x_0 - \tilde{x}_0\|_2 = |(x_0^T - \tilde{x}_0^T) \frac{w}{\|w\|_2}|$

$$= \frac{1}{\|w\|_2} |x_0^T w - \tilde{x}_0^T w|$$

$$= \frac{1}{\|w\|_2} |x_0^T w + b|$$

# Pick the one with the largest margin!



Distance of  $x_0$  from hyperplane  $x^T w + b$ :

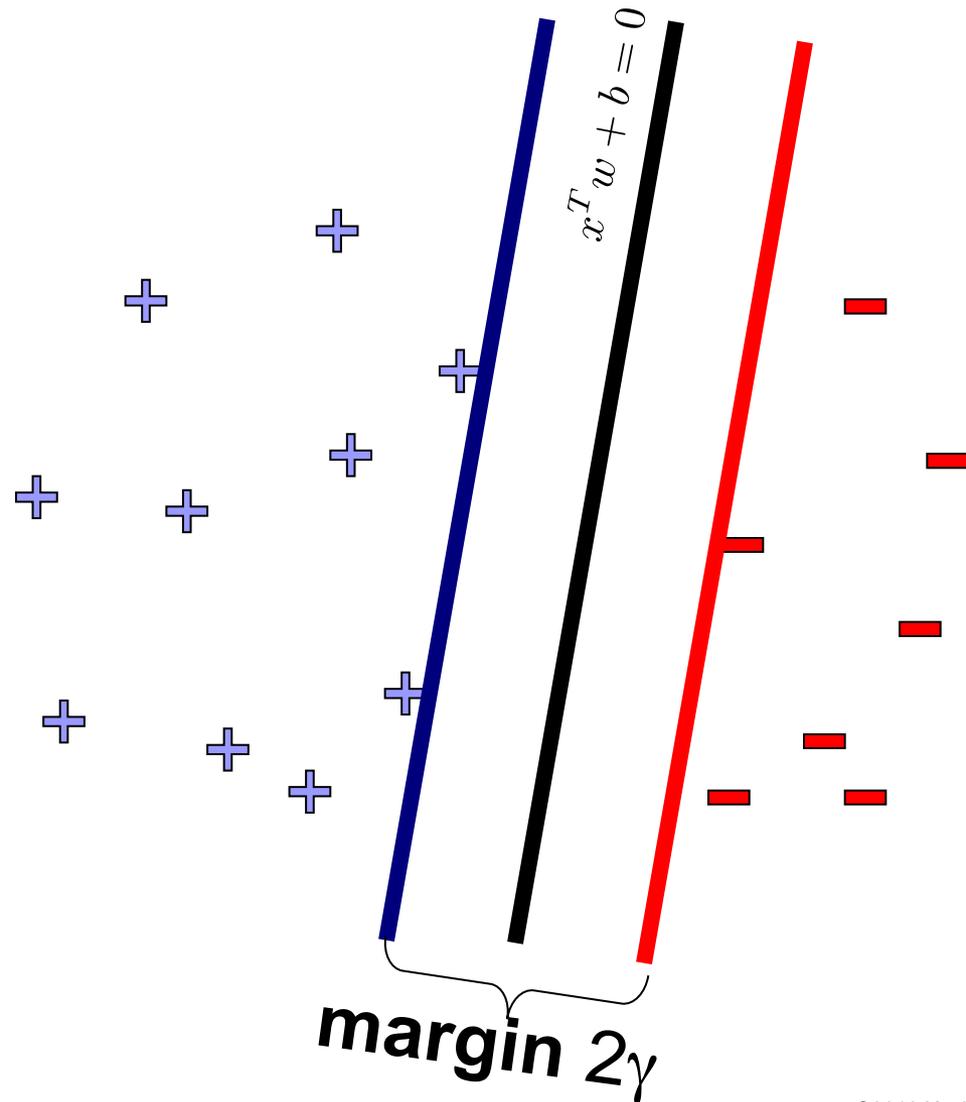
$$\frac{1}{\|w\|_2} (x_0^T w + b)$$

Optimal Hyperplane

$$\max_{w,b} \gamma$$

$$\text{subject to } \frac{1}{\|w\|_2} y_i (x_i^T w + b) \geq \gamma \quad \forall i$$

# Pick the one with the largest margin!



Distance of  $x_0$  from hyperplane  $x^T w + b$ :

$$\frac{1}{\|w\|_2} (x_0^T w + b)$$

Optimal Hyperplane

$$\max_{w,b} \gamma$$

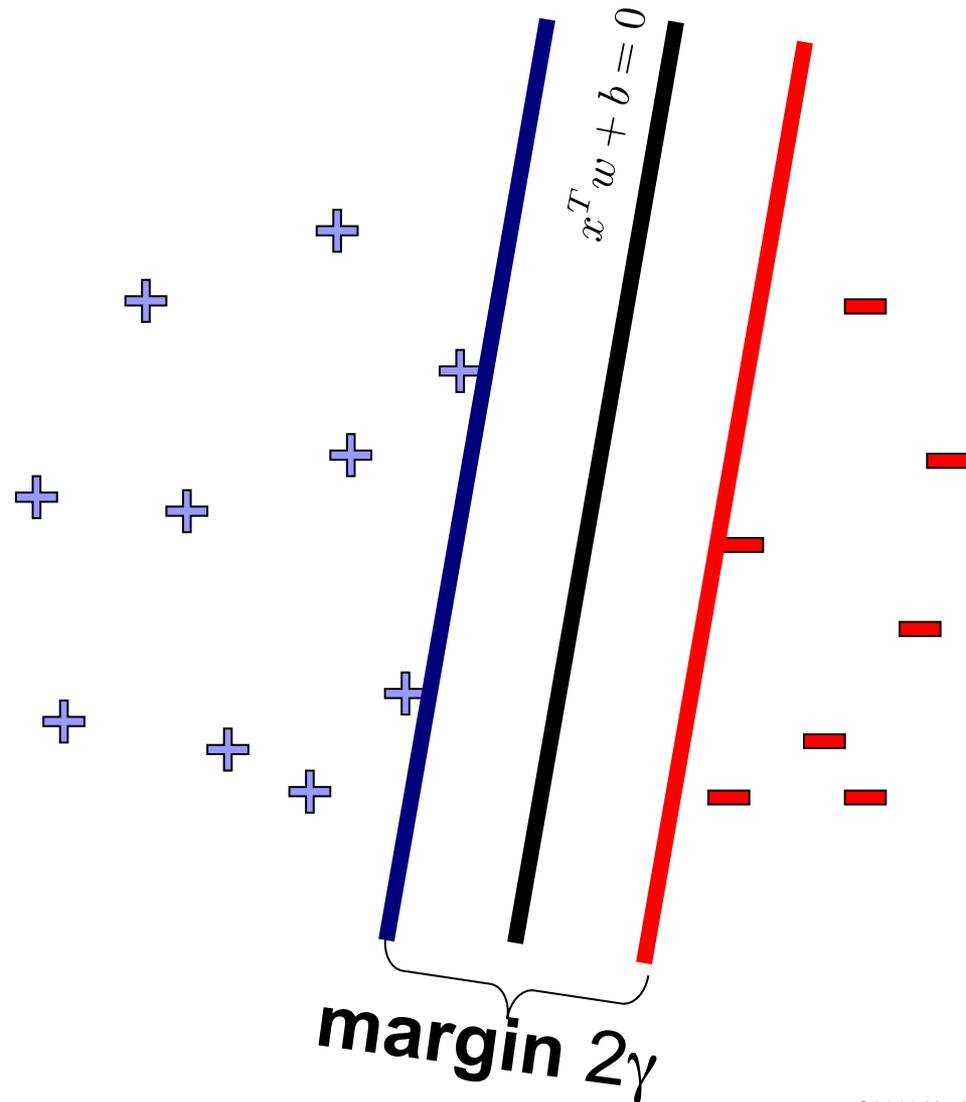
$$\text{subject to } \frac{1}{\|w\|_2} y_i (x_i^T w + b) \geq \gamma \quad \forall i$$

Optimal Hyperplane (reparameterized)

$$\min_{w,b} \|w\|_2^2$$

$$\text{subject to } y_i (x_i^T w + b) \geq 1 \quad \forall i$$

# Pick the one with the largest margin!



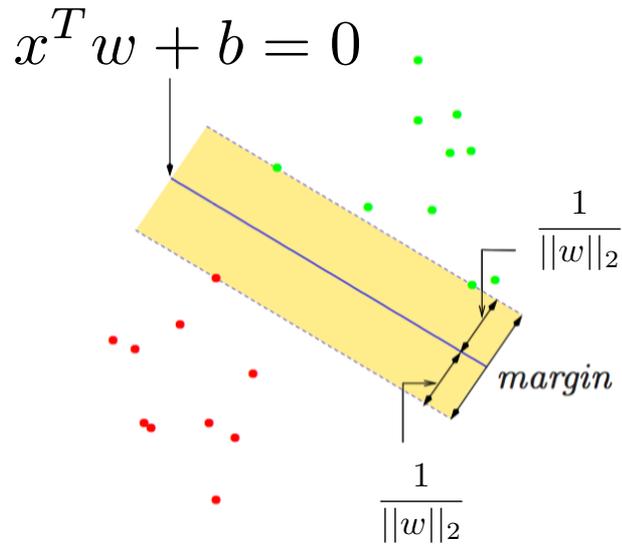
- Solve efficiently by many methods, e.g.,
  - quadratic programming (QP)
    - Well-studied solution algorithms
  - Stochastic gradient descent
  - Coordinate descent (in the dual)

Optimal Hyperplane (reparameterized)

$$\min_{w,b} \|w\|_2^2$$

$$\text{subject to } y_i(x_i^T w + b) \geq 1 \quad \forall i$$

# What if the data is not linearly separable?



If data is linearly separable

$$\min_{w,b} \|w\|_2^2$$

$$y_i(x_i^T w + b) \geq 1 \quad \forall i$$

If data is not linearly separable,  
some points don't satisfy margin  
constraint:

Two options:

1. Introduce slack to this optimization problem
2. Lift to higher dimensional space

# What if the data is not linearly separable?

If data is linearly separable:

$$\min_{w,b} \|w\|_2^2$$

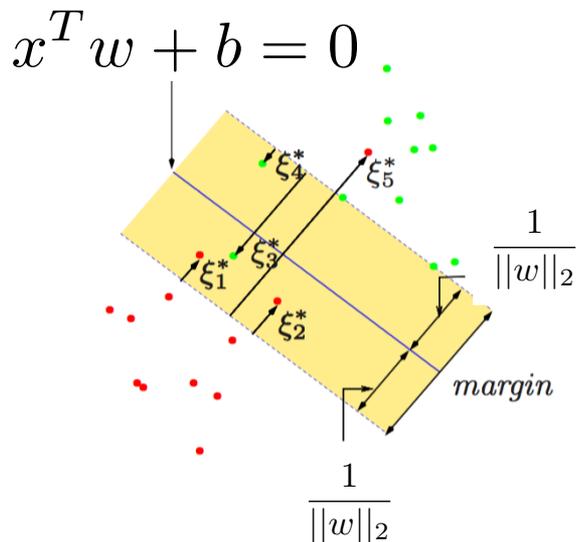
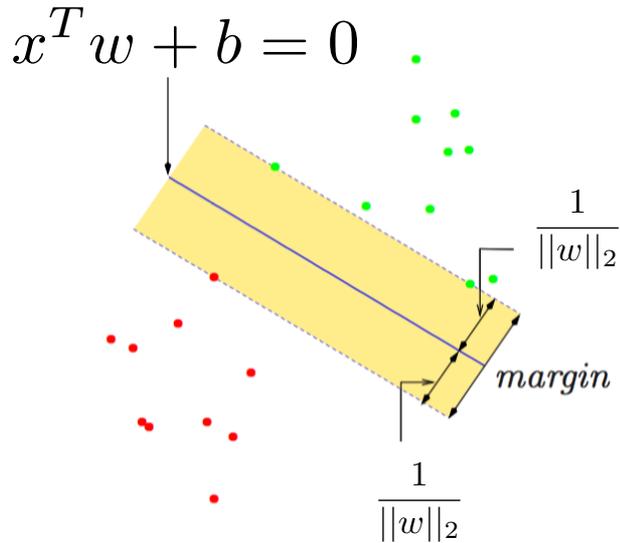
$$y_i(x_i^T w + b) \geq 1 \quad \forall i$$

If data is not linearly separable,  
some points don't satisfy margin constraint:

$$\min_{w,b} \|w\|_2^2$$

$$y_i(x_i^T w + b) \geq 1 - \xi_i \quad \forall i$$

$$\xi_i \geq 0, \sum_{j=1}^n \xi_j \leq \nu$$



# What if the data is not linearly separable?

If data is linearly separable:

$$\min_{w,b} \|w\|_2^2$$

$$y_i(x_i^T w + b) \geq 1 \quad \forall i$$

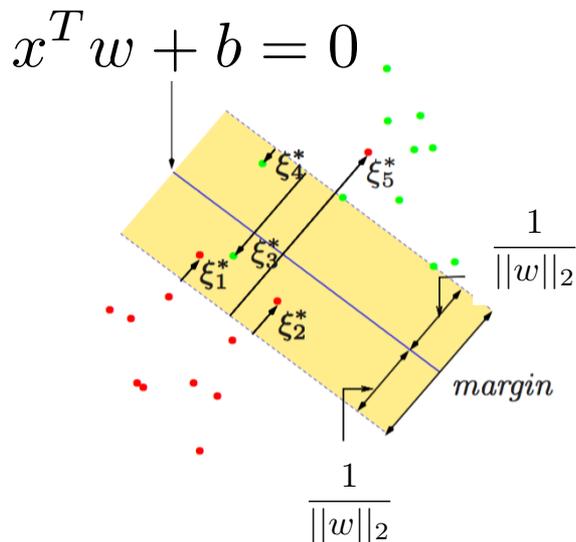
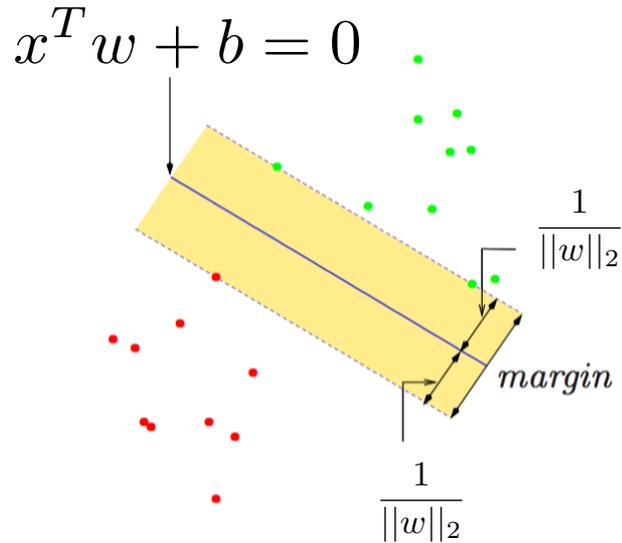
If data is not linearly separable,  
some points don't satisfy margin constraint:

$$\min_{w,b} \|w\|_2^2$$

$$y_i(x_i^T w + b) \geq 1 - \xi_i \quad \forall i$$

$$\xi_i \geq 0, \quad \sum_{j=1}^n \xi_j \leq \nu$$

- What are “support vectors?”



# SVM as penalization method

---

- Original quadratic program with linear constraints:

$$\min_{w,b} \|w\|_2^2$$

$$y_i(x_i^T w + b) \geq 1 - \xi_i \quad \forall i$$

$$\xi_i \geq 0, \sum_{j=1}^n \xi_j \leq \nu$$

# SVM as penalization method

- Original quadratic program with linear constraints:

$$\min_{w,b} \|w\|_2^2$$

$$y_i(x_i^T w + b) \geq 1 - \xi_i \quad \forall i$$

$$\xi_i \geq 0, \sum_{j=1}^n \xi_j \leq \nu$$

- Using same constrained convex optimization trick as for lasso:  
For any  $\nu \geq 0$  there exists a  $\lambda \geq 0$  such that the solution the following solution is equivalent:

$$\sum_{i=1}^n \max\{0, 1 - y_i(b + x_i^T w)\} + \lambda \|w\|_2^2$$

# SVMs: optimizing what?

SVM objective:

$$\sum_{i=1}^n \max\{0, 1 - y_i(b + x_i^T w)\} + \lambda \|w\|_2^2 = \sum_{i=1}^n \ell_i(w, b)$$

$$\nabla_w \ell_i(w, b) = \begin{cases} -x_i y_i + \frac{2\lambda}{n} w & \text{if } y_i(b + x_i^T w) < 1 \\ \frac{2\lambda}{n} & \text{otherwise} \end{cases}$$

$$\nabla_b \ell_i(w, b) = \begin{cases} -y_i & \text{if } y_i(b + x_i^T w) < 1 \\ 0 & \text{otherwise} \end{cases}$$

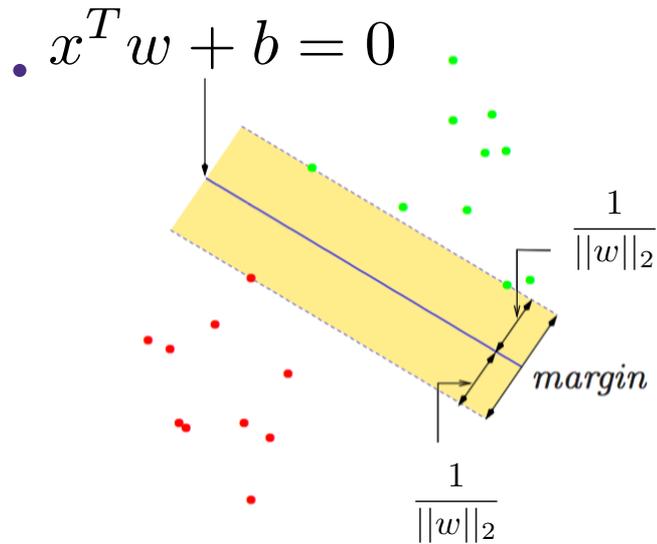
# SVMs: optimizing what?

SVM objective:

$$\sum_{i=1}^n \max\{0, 1 - y_i(b + x_i^T w)\} + \lambda \|w\|_2^2 = \sum_{i=1}^n \ell_i(w, b)$$

Note: the minimizer of this can be written in terms of very few of the training points. These points are known as support vectors.

# What if the data is not linearly separable?



ie, some points don't satisfy margin

$$\min_{w,b} \|w\|_2^2$$

$$y_i(x_i^T w + b) \geq 1 \quad \forall i$$

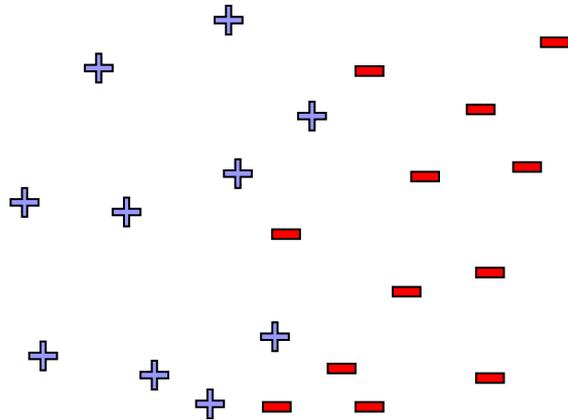
Two options:

1. Introduce slack to this optimization problem
2. **Lift to higher dimensional space**

# What if the data is not linearly separable?

---

Use features of features of features...



$$\phi(x) : \mathbb{R}^d \rightarrow \mathbb{R}^p$$

**Feature space can get really large really quickly!**

# Dot-product of polynomials

---

$\Phi(\mathbf{u}) \cdot \Phi(\mathbf{v}) =$  polynomials of degree exactly  $d$

$$d = 1 : \phi(u) = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \quad \langle \phi(u), \phi(v) \rangle = u_1 v_1 + u_2 v_2$$

# Dot-product of polynomials

$\Phi(\mathbf{u}) \cdot \Phi(\mathbf{v}) =$  polynomials of degree exactly  $d$

$$d = 1 : \phi(u) = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \quad \langle \phi(u), \phi(v) \rangle = u_1 v_1 + u_2 v_2$$

$$d = 2 : \phi(u) = \begin{bmatrix} u_1^2 \\ u_2^2 \\ u_1 u_2 \\ u_2 u_1 \end{bmatrix} \quad \langle \phi(u), \phi(v) \rangle = u_1^2 v_1^2 + u_2^2 v_2^2 + 2u_1 u_2 v_1 v_2$$

# Dot-product of polynomials

$\Phi(\mathbf{u}) \cdot \Phi(\mathbf{v}) =$  polynomials of degree exactly  $d$

$$d = 1 : \phi(u) = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix} \quad \langle \phi(u), \phi(v) \rangle = u_1 v_1 + u_2 v_2$$

$$d = 2 : \phi(u) = \begin{bmatrix} u_1^2 \\ u_2^2 \\ u_1 u_2 \\ u_2 u_1 \end{bmatrix} \quad \langle \phi(u), \phi(v) \rangle = u_1^2 v_1^2 + u_2^2 v_2^2 + 2u_1 u_2 v_1 v_2$$

**Feature space can get really large really quickly!**

General  $d$  :

Dimension of  $\phi(u)$  is roughly  $p^d$  if  $u \in \mathbb{R}^p$

# How do we deal with high-dimensional lifts/data?

## A fundamental trick in ML: use kernels

A function  $K : \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$  is a *kernel* for a map  $\phi$  if  $K(x, x') = \phi(x) \cdot \phi(x')$  for all  $x, x'$ .

So, if we can represent our algorithms/decision rules as dot products and we can find a kernel for our feature map then we can avoid explicitly dealing with  $\phi(x)$ .

# Examples of Kernels

- **Polynomials of degree exactly d**

$$K(\mathbf{u}, \mathbf{v}) = (\mathbf{u} \cdot \mathbf{v})^d$$

- **Polynomials of degree up to d**

$$K(\mathbf{u}, \mathbf{v}) = (\mathbf{u} \cdot \mathbf{v} + 1)^d$$

- **Gaussian (squared exponential) kernel**

$$K(\mathbf{u}, \mathbf{v}) = \exp\left(-\frac{\|\mathbf{u} - \mathbf{v}\|^2}{2\sigma^2}\right)$$

- **Sigmoid**

$$K(u, v) = \tanh(\gamma \cdot u^T v + r)$$

# The Kernel Trick

---

**Pick a kernel  $K$**

**Prove**  $w = \sum_i \alpha_i x_i$

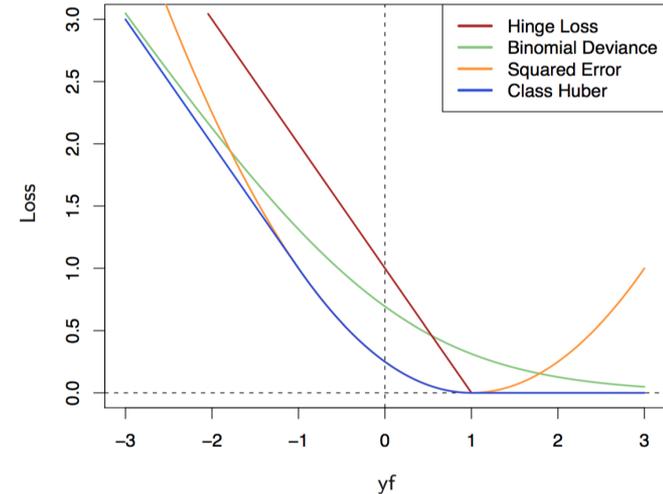
**Change loss function/decision rule to only access data through dot products**

**Decision rule is easy: why?**

**Substitute**  $K(x_i, x_j)$  for  $x_i^T x_j$

# Loss Functions

$$\{(x_i, y_i)\}_{i=1}^n \quad x_i \in \mathbb{R}^d \quad y_i \in \mathbb{R}$$



- Loss functions:

$$\sum_{i=1}^n \ell_i(w)$$

Squared error Loss:  $\ell_i(w) = (y_i - x_i^T w)^2$

Logistic Loss:  $\ell_i(w) = \log(1 + \exp(-y_i x_i^T w))$

0/1 loss:  $\ell_i(w) = \mathbb{I}[\text{sign}(y_i) \neq \text{sign}(x_i^T w)]$

Hinge Loss:  $\ell_i(w) = \max\{0, 1 - y_i x_i^T w\}$

# The Kernel Trick for SVMs

**Pick a kernel  $K$**

**Prove**  $w = \sum_i \alpha_i x_i$



**Change loss function/decision rule to only access data through dot products**



**Substitute**  $K(x_i, x_j)$  for  $x_i^T x_j$

# The Kernel Trick for regularized least squares

$$\hat{w} = \arg \min_w \sum_{i=1}^n (y_i - x_i^T w)^2 + \lambda \|w\|_w^2$$

There exists an  $\alpha \in \mathbb{R}^n$ :  $\hat{w} = \sum_{i=1}^n \alpha_i x_i$  **Why?**

# The Kernel Trick for regularized least squares

$$\hat{w} = \arg \min_w \sum_{i=1}^n (y_i - x_i^T w)^2 + \lambda \|w\|_w^2$$

There exists an  $\alpha \in \mathbb{R}^n$ :  $\hat{w} = \sum_{i=1}^n \alpha_i x_i$

$$\hat{\alpha} = \arg \min_{\alpha} \sum_{i=1}^n (y_i - \sum_{j=1}^n \alpha_j \langle x_j, x_i \rangle)^2 + \lambda \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j \langle x_i, x_j \rangle$$

# The Kernel Trick for regularized least squares

$$\hat{w} = \arg \min_w \sum_{i=1}^n (y_i - x_i^T w)^2 + \lambda \|w\|_w^2$$

There exists an  $\alpha \in \mathbb{R}^n$ :  $\hat{w} = \sum_{i=1}^n \alpha_i x_i$

$$\begin{aligned} \hat{\alpha} &= \arg \min_{\alpha} \sum_{i=1}^n (y_i - \sum_{j=1}^n \alpha_j \langle x_j, x_i \rangle)^2 + \lambda \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j \langle x_i, x_j \rangle \\ &= \arg \min_{\alpha} \sum_{i=1}^n (y_i - \sum_{j=1}^n \alpha_j K(x_i, x_j))^2 + \lambda \sum_{i=1}^n \sum_{j=1}^n \alpha_i \alpha_j K(x_i, x_j) \\ &= \arg \min_{\alpha} \|\mathbf{y} - \mathbf{K}\alpha\|_2^2 + \lambda \alpha^T \mathbf{K}\alpha \end{aligned}$$

$$K(x_i, x_j) = \langle \phi(x_i), \phi(x_j) \rangle$$

# Why regularization?

---

Typically,  $\mathbf{K} \succ 0$ . What if  $\lambda = 0$ ?

$$\hat{\alpha} = \arg \min_{\alpha} \|\mathbf{y} - \mathbf{K}\alpha\|_2^2 + \lambda \alpha^T \mathbf{K} \alpha$$

# Why regularization?

Typically,  $\mathbf{K} \succ 0$ . What if  $\lambda = 0$ ?

$$\hat{\alpha} = \arg \min_{\alpha} \|\mathbf{y} - \mathbf{K}\alpha\|_2^2 + \lambda \alpha^T \mathbf{K}\alpha$$

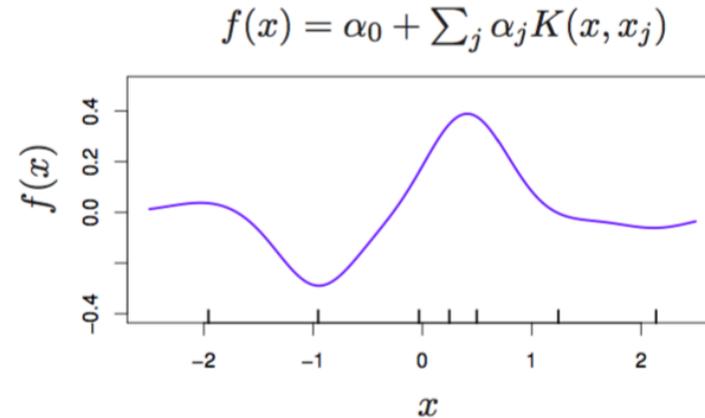
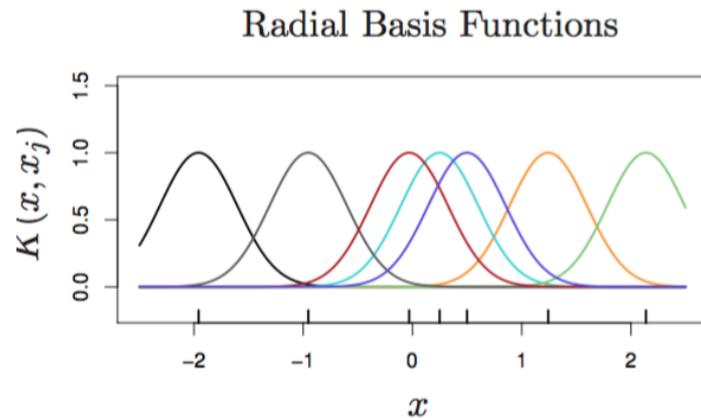
Unregularized kernel least squares can (over) fit **any data!**

$$\hat{\alpha} = \mathbf{K}^{-1} \mathbf{y}$$

# RBF Kernel

$$K(\mathbf{u}, \mathbf{v}) = \exp\left(-\frac{\|\mathbf{u} - \mathbf{v}\|_2^2}{2\sigma^2}\right)$$

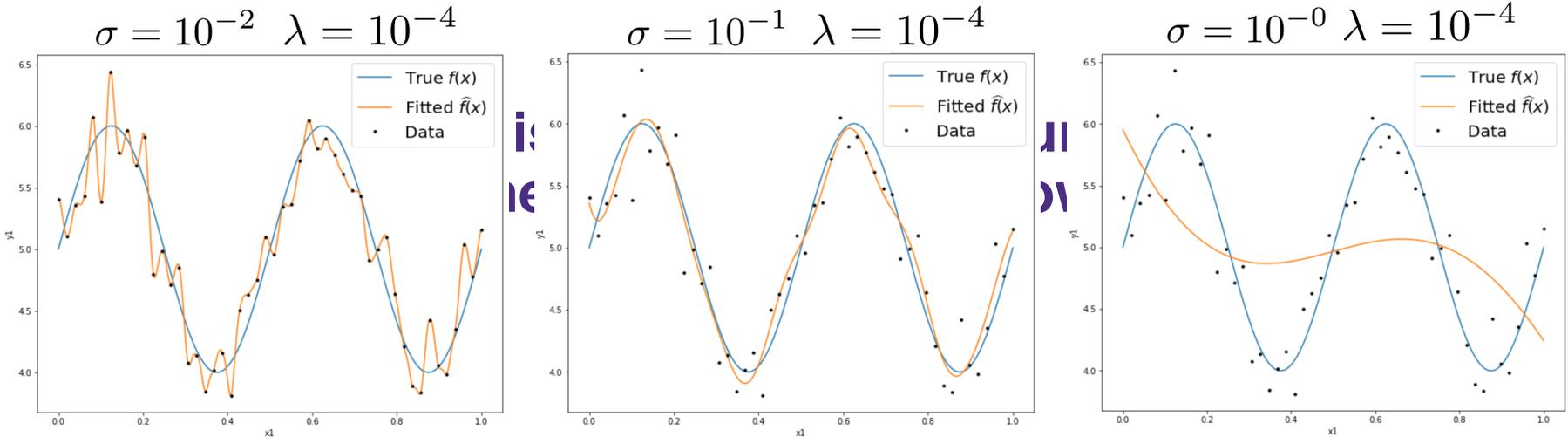
Note that this is like weighting “bumps” on each point like kernel smoothing but now we learn the weights



# RBF Kernel

$$K(\mathbf{u}, \mathbf{v}) = \exp\left(-\frac{\|\mathbf{u} - \mathbf{v}\|_2^2}{2\sigma^2}\right)$$

The bandwidth sigma has an enormous effect on fit:



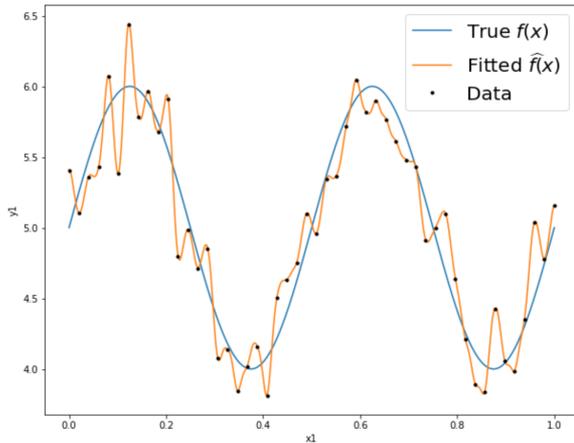
$$\hat{f}(x) = \sum_{i=1}^n \hat{\alpha}_i K(x_i, x)$$

# RBF Kernel

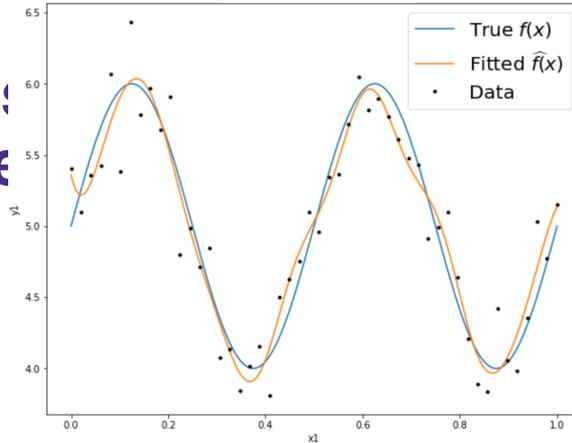
$$K(\mathbf{u}, \mathbf{v}) = \exp\left(-\frac{\|\mathbf{u} - \mathbf{v}\|_2^2}{2\sigma^2}\right)$$

The bandwidth sigma has an enormous effect on fit:

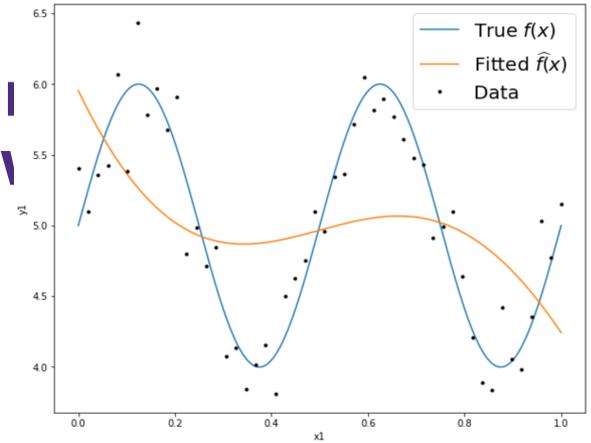
$$\sigma = 10^{-2} \quad \lambda = 10^{-4}$$



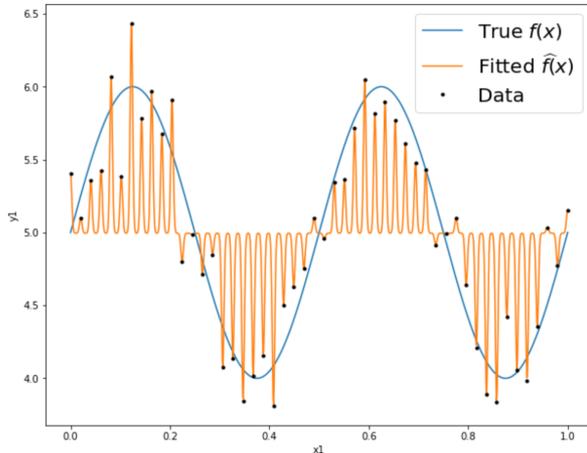
$$\sigma = 10^{-1} \quad \lambda = 10^{-4}$$



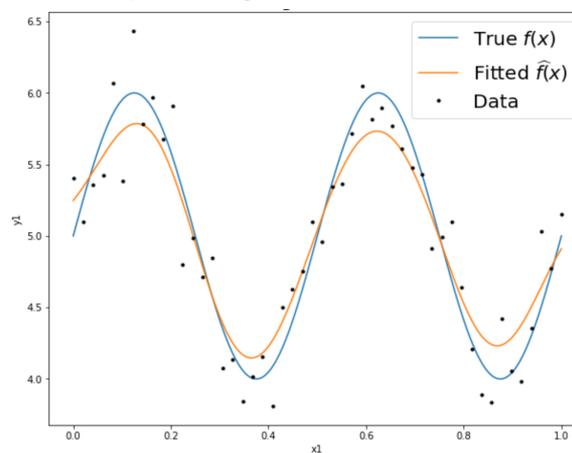
$$\sigma = 10^{-0} \quad \lambda = 10^{-4}$$



$$\sigma = 10^{-3} \quad \lambda = 10^{-4}$$



$$\sigma = 10^{-1} \quad \lambda = 10^{-0}$$



$$\hat{f}(x) = \sum_{i=1}^n \hat{\alpha}_i K(x_i, x)$$

# RBF Kernel

$$K(\mathbf{u}, \mathbf{v}) = \exp\left(-\frac{\|\mathbf{u} - \mathbf{v}\|_2^2}{2\sigma^2}\right)$$

Basis representation in 1d?

$$[\phi(x)]_i = \frac{1}{\sqrt{i!}} e^{-\frac{x^2}{2}} x^i \quad \text{for } i = 0, 1, \dots$$

> Note that this is like weighting "bumps" on each point like kernel smoothing but now we learn the weights

$$\begin{aligned}\phi(x)^T \phi(x') &= \sum_{i=0}^{\infty} \left( \frac{1}{\sqrt{i!}} e^{-\frac{x^2}{2}} x^i \right) \left( \frac{1}{\sqrt{i!}} e^{-\frac{(x')^2}{2}} (x')^i \right) \\ &= e^{-\frac{x^2 + (x')^2}{2}} \sum_{i=0}^{\infty} \frac{1}{i!} (xx')^i \\ &= e^{-|x-x'|^2/2}\end{aligned}$$

If  $n$  is very large, allocating an  $n$ -by- $n$  matrix is tough. Can we truncate the above sum to approximate the kernel?

# RBF kernel and random features

$$2 \cos(\alpha) \cos(\beta) = \cos(\alpha + \beta) + \cos(\alpha - \beta)$$

$$e^{jz} = \cos(z) + j \sin(z)$$

Recall HW1 where we used the feature map:

$$\phi(x) = \begin{bmatrix} \sqrt{2} \cos(w_1^T x + b_1) \\ \vdots \\ \sqrt{2} \cos(w_p^T x + b_p) \end{bmatrix} \quad \begin{array}{l} w_k \sim \mathcal{N}(0, 2\gamma I) \\ b_k \sim \text{uniform}(0, \pi) \end{array}$$

> **Isn't everything separable there? How are we not overfitting?**

$$\mathbb{E}\left[\frac{1}{p} \phi(x)^T \phi(y)\right] = \frac{1}{p} \sum_{k=1}^p \mathbb{E}[2 \cos(w_k^T x + b_k) \cos(w_k^T y + b_k)]$$

> **Regularization! Fat shattering  $(R/\text{margin})^2$**

$$= \mathbb{E}_{w,b}[2 \cos(w^T x + b) \cos(w^T y + b)]$$

> **What about sparsity?**

# RBF kernel and random features

$$2 \cos(\alpha) \cos(\beta) = \cos(\alpha + \beta) + \cos(\alpha - \beta)$$

$$e^{jz} = \cos(z) + j \sin(z)$$

Recall HW1 where we used the feature map:

$$\phi(x) = \begin{bmatrix} \sqrt{2} \cos(w_1^T x + b_1) \\ \vdots \\ \sqrt{2} \cos(w_p^T x + b_p) \end{bmatrix} \quad \begin{array}{l} w_k \sim \mathcal{N}(0, 2\gamma I) \\ b_k \sim \text{uniform}(0, \pi) \end{array}$$

> **Isn't everything separable there? How are we not overfitting?**

$$\mathbb{E}\left[\frac{1}{p} \phi(x)^T \phi(y)\right] = \frac{1}{p} \sum_{k=1}^p \mathbb{E}[2 \cos(w_k^T x + b_k) \cos(w_k^T y + b_k)]$$

> **Regularization! Fat shattering (R/margin)<sup>2</sup>**

$$= \mathbb{E}_{w,b}[2 \cos(w^T x + b) \cos(w^T y + b)]$$

$$= e^{-\gamma \|x-y\|_2^2}$$

[Rahimi, Recht NIPS 2007]

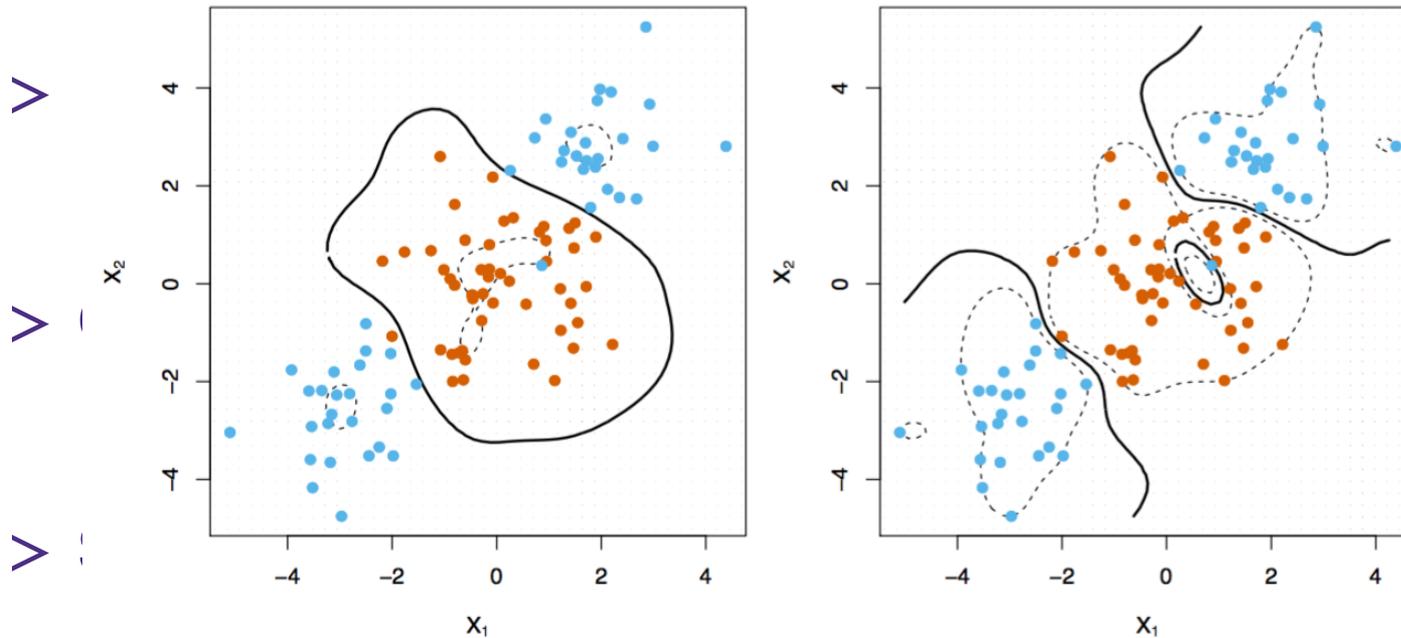
> **What about sparsity?** "NIPS Test of Time Award, 2018"

# RBF Classification

$$\hat{w} = \sum_{i=1}^n \max\{0, 1 - y_i(b + x_i^T w)\} + \lambda \|w\|_2^2$$

> **Polynomials of degree exactly d**

$$\min_{\alpha, b} \sum_{i=1}^n \max\{0, 1 - y_i(b + \sum_{j=1}^n \alpha_j \langle x_i, x_j \rangle)\} + \lambda \sum_{i,j=1}^n \alpha_i \alpha_j \langle x_i, x_j \rangle$$



# Wait, infinite dimensions?

- > Isn't everything separable there? How are we not overfitting?
- > Regularization! Fat shattering  $(R/\text{margin})^2$

# String Kernels

Example from Efron and Hastie, 2016

Amino acid sequences of different lengths:

> **Isn'**  
x1 IPTSALVKETLALLSTHRTLLIANETLRIPVPVHKNHQLCTEEIFQGIGTLESQTVQGGTV  
**ove** ERLFKNLSLIKKYIDGQKKKCGEERRRVNQFLDY**LQE**FLGVMNTEWI

re we not

x2 PHRRDLCSRSIWLARKIRSDLTALTESYVKHQGLWSELTEAER**LQEN**LQAYRTFHVLLA  
RLLEDQQVHFPTPEGDFHQAIHTLLLQVAAFAYQIEELMILLEYKIPRNEADGMLFEKK  
LWGLKV**LQE**LSQWTVRSIHDLRFISSHQTGIP

> **Regularization:  $\ell_1$  and  $\ell_2$  (with  $\gamma$ )**

All subsequences of length 3 (of possible 20 amino acids)  $20^3 = 8,000$

$$h_{LQE}^3(x_1) = 1 \text{ and } h_{LQE}^3(x_2) = 2.$$

> **What about sparsity?**