Non-quadratic Regularizers

Sewoong Oh

CSE446 University of Washington

L1 Regularizer

sum absolute or L1 regularizer uses

$$r(w) = |w_1| + |w_2| + \cdots + |w_d|$$

• this is the same as L1 norm of the weight vector (we write is as $w_{1:d}$ to emphasize that w_0 is the weight of the constant term that should not be regularized)

$$||w_{1:d}||_1 \triangleq |w_1| + |w_2| + \cdots + |w_d|$$

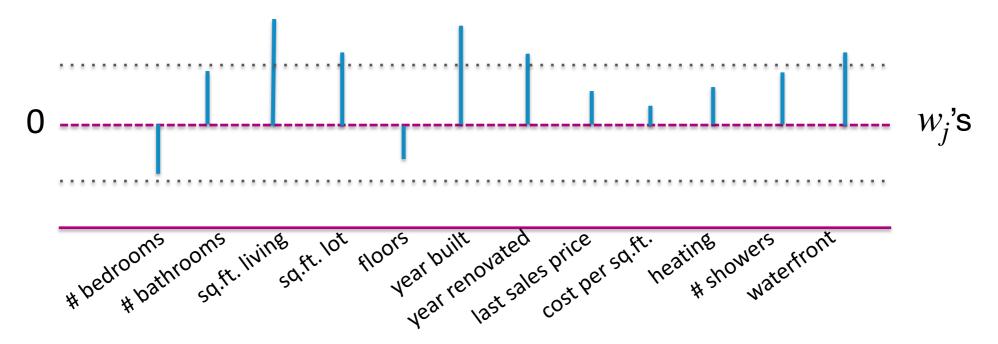
- we use empirical risk $\mathcal{L}(w) = \sum_{i=1}^{n} (w^{T}x_{i} y_{i})^{2}$
- with L1 regularizer, it is called Lasso regression minimize $\mathcal{L}(w) + \lambda \|w\|_1$
- since it is a convex function, can be efficiently minimized using optimization (but unlike ridge regression, does not have a closed-form solution)
- it has interesting properties, making it attractive in practice (sparsification)

Sparse coefficient vector

- suppose w is sparse, i.e. many of its entries are zero
- prediction $\hat{y} = w^T x$ does not depend on features of x = (x[1], ..., x[d]) for which $w_i = 0$
- this means we select **some** features to use (i.e. those with $w_j \neq 0$)
- (potential) practical benefits of sparse w
 - true model might be sparse in real applications
 - e.g. polynomial fit
 - sparsity (i.e. the number of features used in prediction) is the simplest measure of complexity of a model
 - sparse models are natural choice of simple models
 - makes prediction model simpler to interpret
 - e.g. medical diagnosis
 - makes prediction faster (less computation)
 - but, manually engineering correct sparse set of features is extremely challenging

Selecting sparse features based on Ridge regression (L2 regularizer) can be problematic

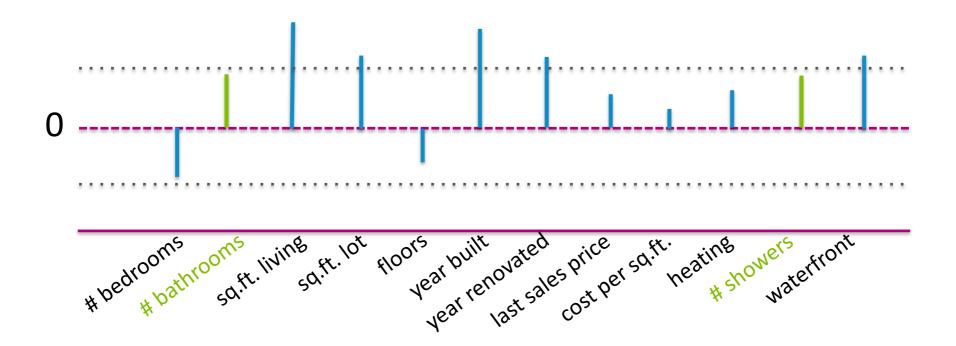
- sometimes sparse features are desired in practice
- consider running the following sparse feature selection method
 - run Ridge regression, with optimal lambda
 - Set to zero (shrink) those parameters that are smaller than a threshold



- Set threshold in order to keep the top 5, for example, parameters
- What is wrong with this approach?

Selecting sparse features based on Ridge regression (L2 regularizer) can be problematic

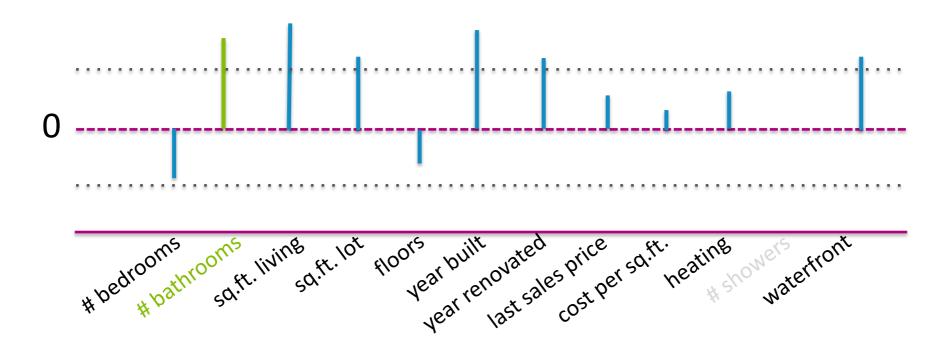
- sometimes sparse features are desired in practice
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 - shrink parameters that are smaller than a threshold



nothing measuring bathrooms is included!!

Selecting sparse features based on Ridge regression (L2 regularizer) can be problematic

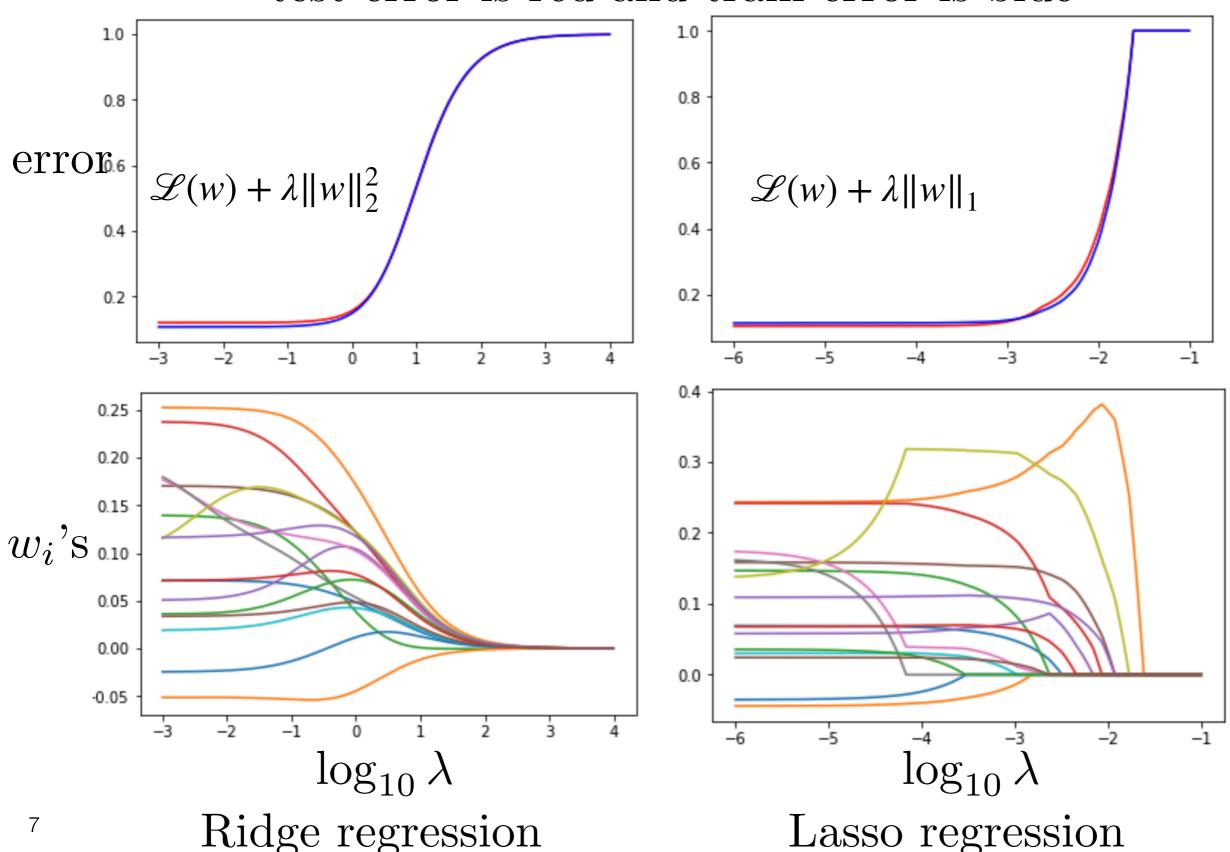
 If only one of the features were included when running Ridge regression, it would have survived



- thresholding Ridge regression parameters unnecessarily penalizes multiple similar features
- Lasso is a more principled way of selecting sparse features

Example: house price with 16 features

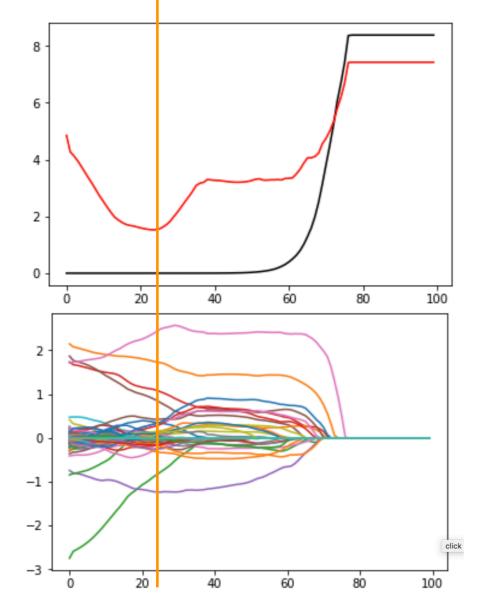
test error is red and train error is blue



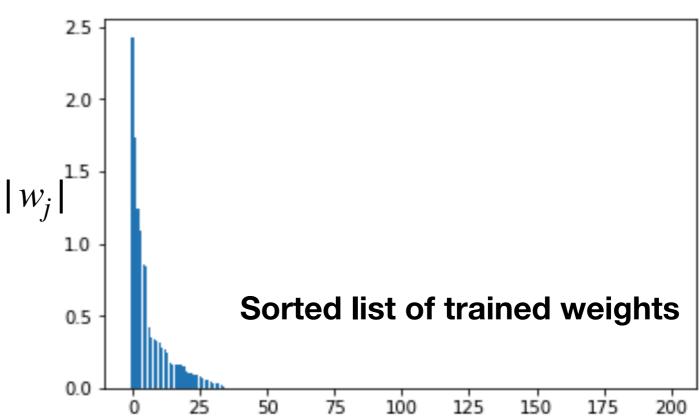
Lasso regression naturally gives sparse features

- feature selection with Lasso regression
 - 1. choose which features to keep based on cross validation error
 - 2. keep only those features with non-zero parameters in w at optimal λ
 - 3. retrain with the sparse model and $\lambda = 0$

Example: Lasso training with 200 features



• Lasso has only 35 non-zero components



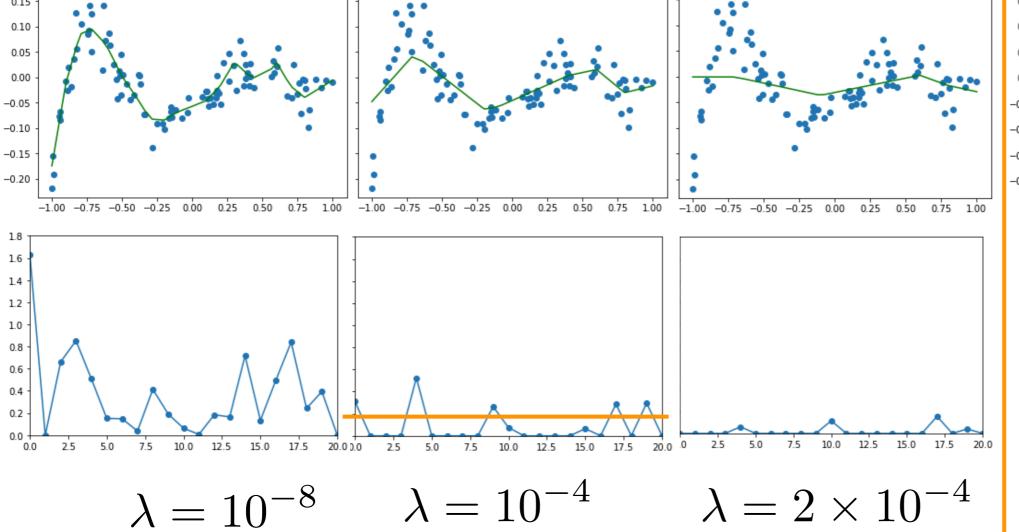
Example: piecewise-linear fit

We use Lasso on the piece-wise linear example

$$h_0(x) = 1$$

 $h_i(x) = [x + 1.1 - 0.1i]^+$

$minimize_{w} \mathcal{L}(w) + \lambda ||w||_{1}$



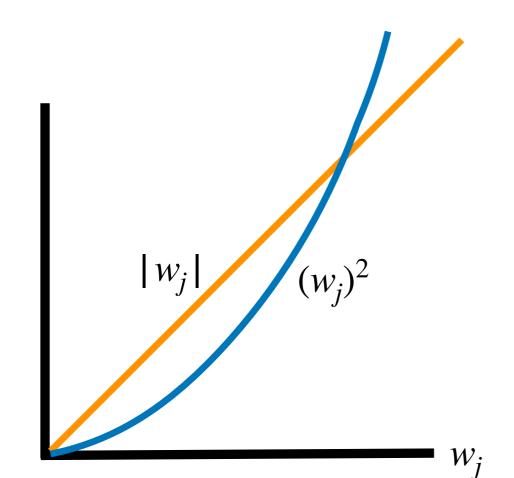
de-biasing (via re-training) is critical!

minimize_w $\mathcal{L}(w)$ 0.05 0.00 -0.05 -0.20 1.0 $\lambda = 0$

but only use selected features

minimize_w
$$\sum_{i=1}^{n} (w^{T} x_{i} - y_{i})^{2} + \lambda ||w||_{1}$$

- comparing L1 with L2:
 - for L2 regularizer, once w_j is small, $(w_j)^2$ is very small
 - so not much incentive to make coefficients go all the way to zero
 - for L1 regularizer, incentive to make w_j smaller keeps up all the way until it is zero

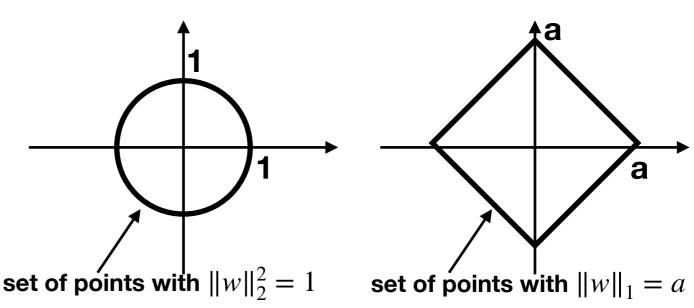


Q. among all 2-dimensional vectors with

$$||w||_2^2 = w_1^2 + w_2^2 = 1$$

Which one has the smallest L1-norm,

$$||w||_1 = |w_1| + |w_2|, ?$$



consider the optimal solution of a problem:

$$\hat{w}_{\lambda} = \arg\min_{w} \sum_{i=1}^{n} (w^{T} x_{i} - y_{i})^{2} + \lambda ||w||_{1}$$

• for each given λ , there exists a μ such that the following problem has the exactly same solution

$$\hat{w}_{\mu} = \arg\min_{w} \sum_{i=1}^{n} (w^{T} x_{i} - y_{i})^{2}$$
subject to $||w||_{1} \le \mu$

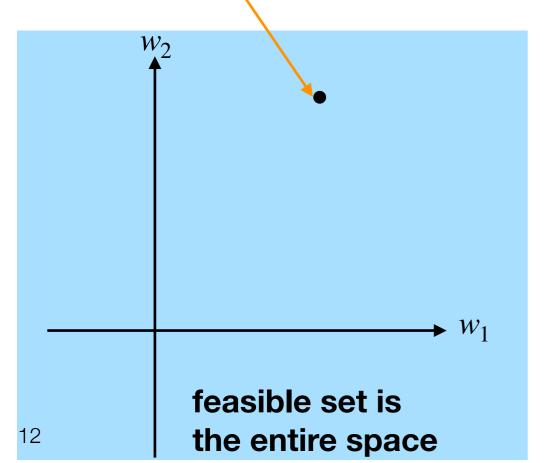
- that is for any λ there exists a μ such that $\hat{w}_{\lambda} = \hat{w}_{\mu}$
- just as \hat{w}_{λ} becomes sparse with increasing λ , \hat{w}_{μ} becomes sparse with decreasing μ
- hence, we study sparsity of the optimal solution of the second problem

minimize_w
$$\sum_{i=1}^{n} (w^{T}x_{i} - y_{i})^{2} + \lambda ||w||_{1}$$
 minimize_w
$$\sum_{i=1}^{n} (w^{T}x_{i} - y_{i})^{2}$$
 subject to $||w||_{1} \le \mu$

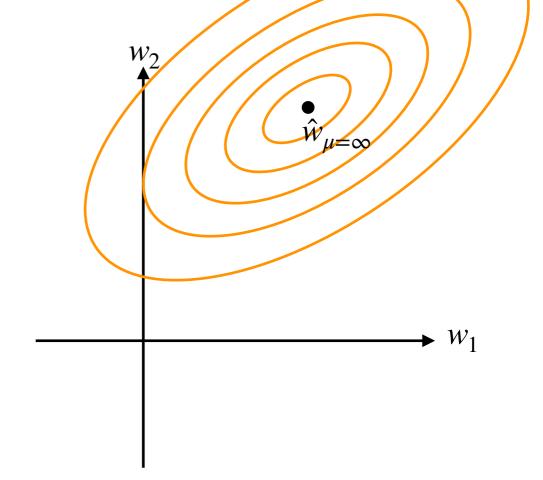
$$\min_{i=1}^{n} \left(w^{T} x_{i} - y_{i} \right)^{n}$$

subject to $||w||_1 \le \mu$

Optimal solution $\hat{w}_{\mu=\infty}$ when $\lambda = 0$ (equivalent to $\mu = \infty$)



- the **level set** of a function $\mathcal{L}(w_1, w_2)$ is defined as the set of points (w_1, w_2) that have the same function value
- the level set of a quadratic function is an oval

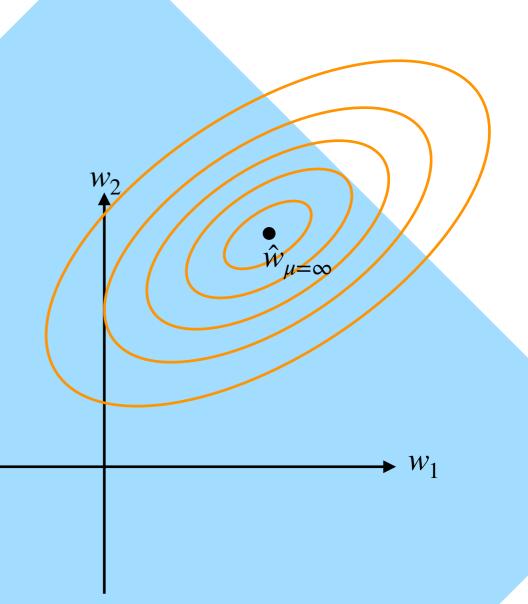


minimize_w
$$\sum_{i=1}^{n} (w^{T}x_{i} - y_{i})^{2} + \lambda ||w||_{1}$$
 minimize_w
$$\sum_{i=1}^{n} (w^{T}x_{i} - y_{i})^{2}$$
 subject to $||w||_{1} \le \mu$

$$\min_{i=1}^{n} (w^{T} x_{i} - y_{i})^{2}$$

subject to $||w||_1 \le \mu$

- as we decrease μ from infinity (which is the same as increasing regularization parameter λ), the feasible set becomes smaller
- the shape of the **feasible set** is what is known as L_1 ball, which is a high dimensional diamond
- In 2-dimensions, it is a diamond $\{(w_1, w_2) \mid |w_1| + |w_2| \le \mu\}$
- when μ is large enough such that $\mu > \|\hat{w}_{\mu=\infty}\|_1$, then the optimal solution does not change as the feasible set includes the un-_ regularized optimal solution



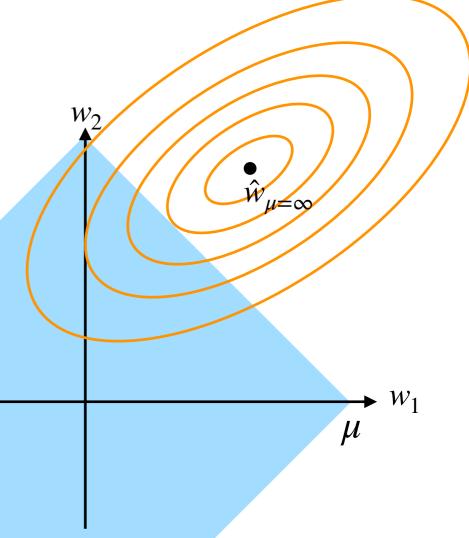
$$\underset{i=1}{\text{minimize}_{w}} \underbrace{\sum_{i=1}^{n} (w^{T} x_{i} - y_{i})^{2} + \lambda \|w\|_{1}} \qquad \underset{i=1}{\text{minimize}_{w}} \underbrace{\sum_{i=1}^{n} (w^{T} x_{i} - y_{i})^{2}}_{\text{subject to } \|w\|_{1} \leq \mu$$

$$\min_{i=1}^{n} (w^{T} x_{i} - y_{i})^{2}$$

subject to $||w||_1 \le \mu$

- as we decrease μ from infinity, (which is the same as increasing regularization parameter λ), the **feasible set** becomes smaller
- initially, both w_1 and w_2 become smaller, but not zero

feasible set: $\{w \in \mathbb{R}^2 \mid ||w||_1 \le \mu\}$

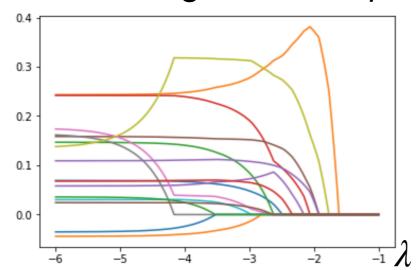


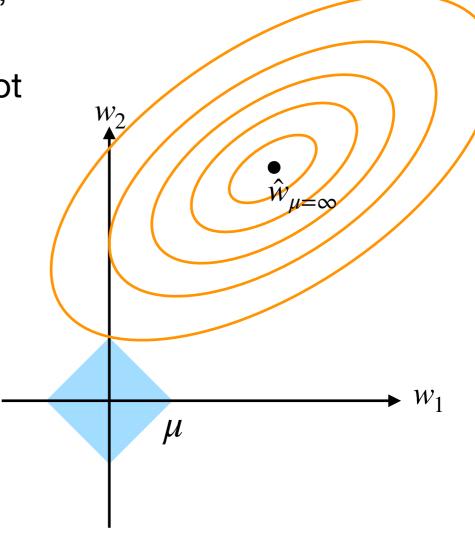
minimize_w
$$\sum_{i=1}^{n} (w^{T}x_{i} - y_{i})^{2} + \lambda ||w||_{1}$$
 minimize_w
$$\sum_{i=1}^{n} (w^{T}x_{i} - y_{i})^{2}$$
 subject to $||w||_{1} \le \mu$

$$\min_{i=1}^{n} (w^{T} x_{i} - y_{i})^{2}$$

subject to $||w||_1 \le \mu$

- as we decrease μ from infinity, (which is the same as increasing regularization parameter λ), the feasible set becomes smaller
- initially, both w_1 and w_2 become smaller, but not zero
- eventually, w_i 's become zero one by one
- this explains the regularization path of **Lasso**

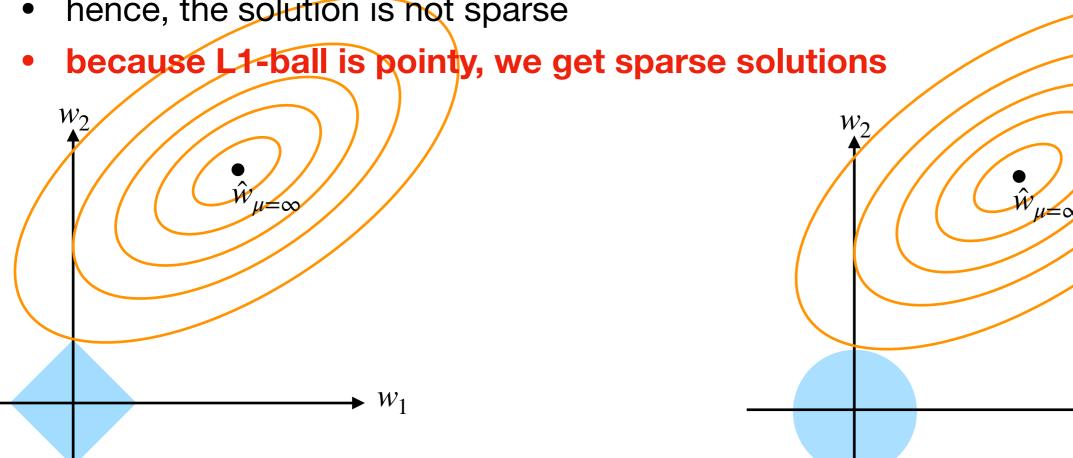




In the case of Ridge regression

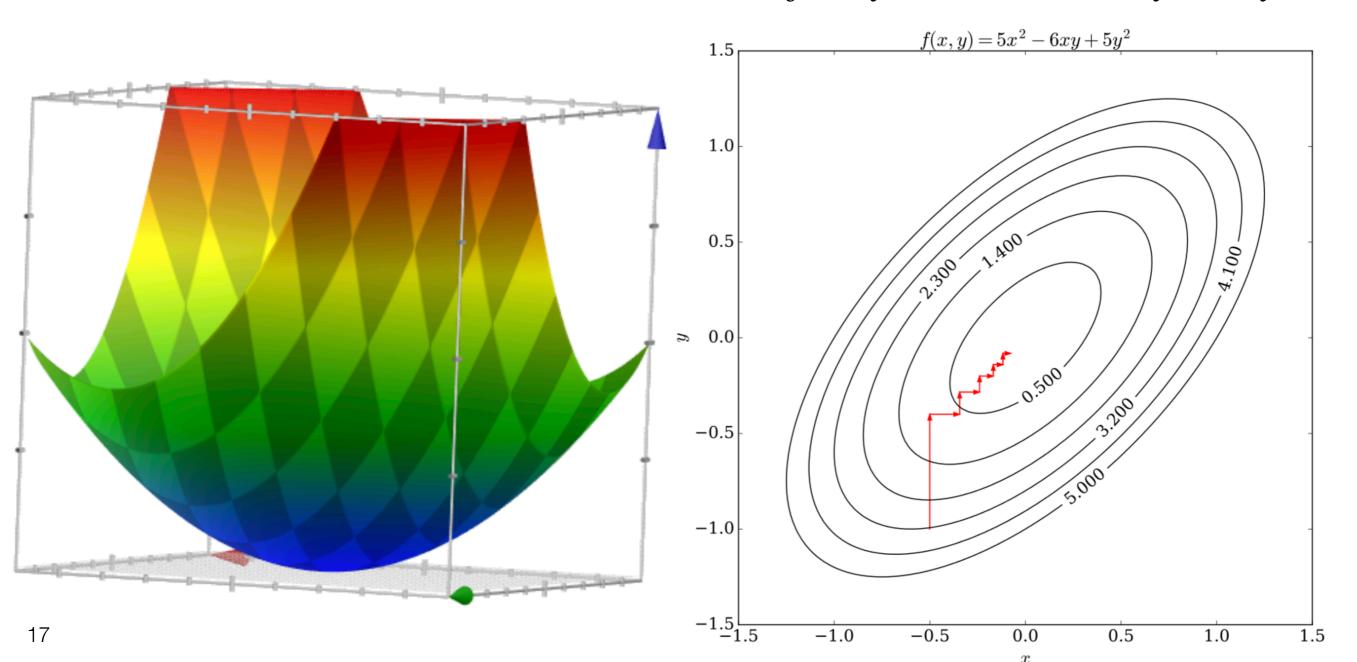
- for ridge regression, the feasible set is an L_2 -norm ball, which is actually a **ball** $\{(w_1, w_2) \mid w_1^2 + w_2^2 \le \mu\}$
- hence, the solution is not sparse

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Optimization: how do we solve Lasso?

- among many methods to find the solution, we will learn coordinate descent method
- as an illustrating example, we show coordinate descent updates on finding the minimum of $f(x, y) = 5x^2 6xy + 5y^2$



min $f(w_1, ---w_2) = \|X \cdot w - y\|_2^2 + \lambda \|w\|_1$ Wt-y W(t) Input: Serain, T Initialize W(b) = 0 for t=1, --, T For S=1, ---, d

Optimization: how do we solve Lasso?

- minimize_w $\|\mathbf{X}w \mathbf{y}\|_2^2 + \lambda \|w\|_1$
- we will study one method (coordinate descent) to solve the problem and find the minimizer \hat{w}_{lasso}
- Coordinate descent
 - input: training data $S_{
 m train}$, max # of iterations T
 - initialize: $w^{(0)} = \mathbf{0} \in \mathbb{R}^d$
 - for t = 1,...,T
 - for j = 1,...,d

• fix $w_1^{(t)}, ..., w_{j-1}^{(t)}$ and $w_{j+1}^{(t-1)}, ..., w_{d-1}^{(t-1)}$, and

$$w_{j}^{(t)} \leftarrow \underset{w_{j} \in \mathbb{R}}{\operatorname{arg \, min}} \mathcal{L} \left(\begin{bmatrix} w_{1}^{(t)} \\ \vdots \\ w_{j-1}^{(t)} \\ w_{j} \\ w_{j+1}^{(t-1)} \\ \vdots \\ w_{d}^{(t-1)} \end{bmatrix} \right) + \lambda \left\| \begin{bmatrix} w_{1}^{(t)} \\ \vdots \\ w_{j-1}^{(t)} \\ w_{j} \\ w_{j+1}^{(t-1)} \\ \vdots \\ w_{d}^{(t-1)} \end{bmatrix} \right\|_{1}$$

this is a one-dimensional optimization, which is much easier to solve

Coordinate descent for (un-regularized) linear least squares

 let us understand what coordinate descent does on a simpler problem of linear least squares, which minimizes

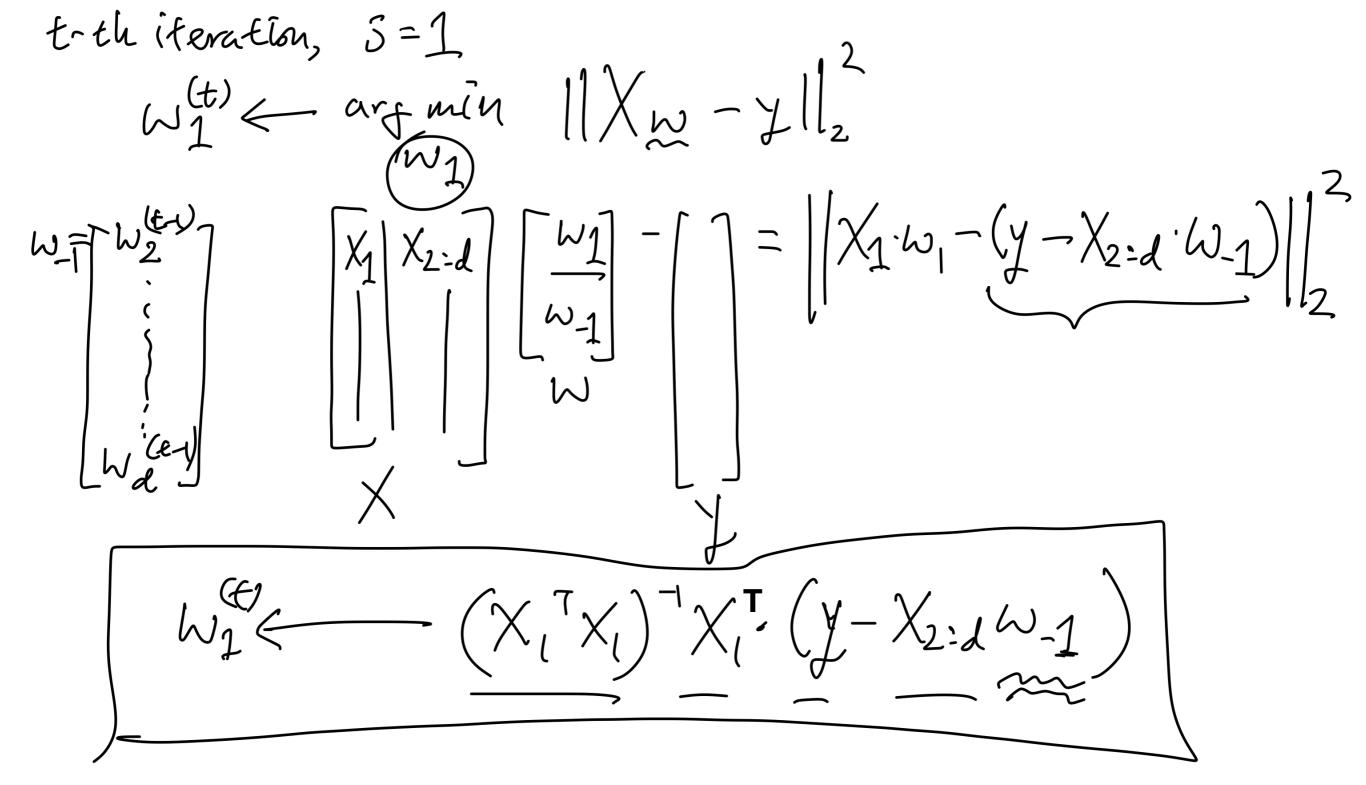
$$\operatorname{minimize}_{w} \mathcal{L}(w) = \|\mathbf{X}w - \mathbf{y}\|_{2}^{2}$$

note that we know that the optimal solution is

$$\hat{w}_{LS} = (\mathbf{X}^T \mathbf{X})^{-1} \mathbf{X}^T \mathbf{y}$$

so we do not need to run any optimization algorithm

- we are solving this problem with coordinate descent for illustration purpose
- the main challenge we want to address is, how do we update $\boldsymbol{w}_{j}^{(t)}$?
- let us derive an **analytical rule** for updating $w_i^{(t)}$



Coordinate descent for (un-regularized) linear least squares

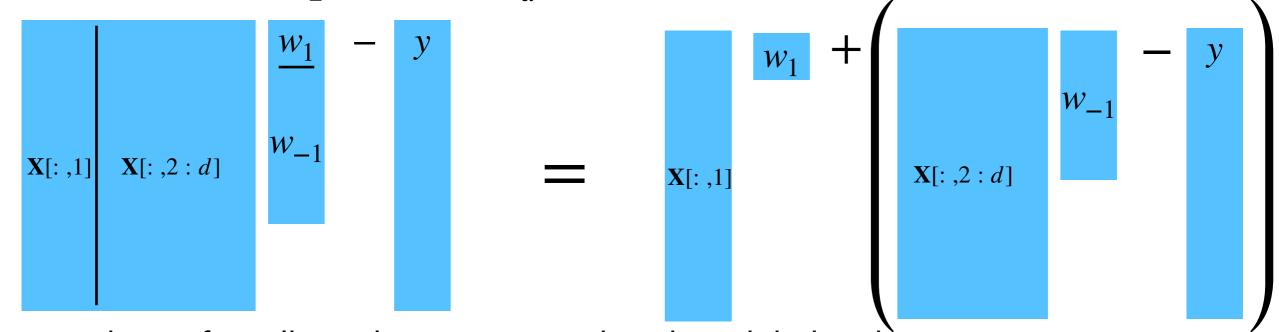
- we will study the case j=1, for now (other cases are almost identical)
- when updating $w_1^{(t)}$, recall that

$$w_1^{(t)} \leftarrow \arg\min_{w_1} \|\mathbf{X}w - \mathbf{y}\|_2^2$$

where $w = [w_1, \ w_2^{(t-1)}, \ \dots, w_d^{(t-1)}]^T$

• first step is to write the objective function in terms of the variable we are optimizing over, that is w_1 :

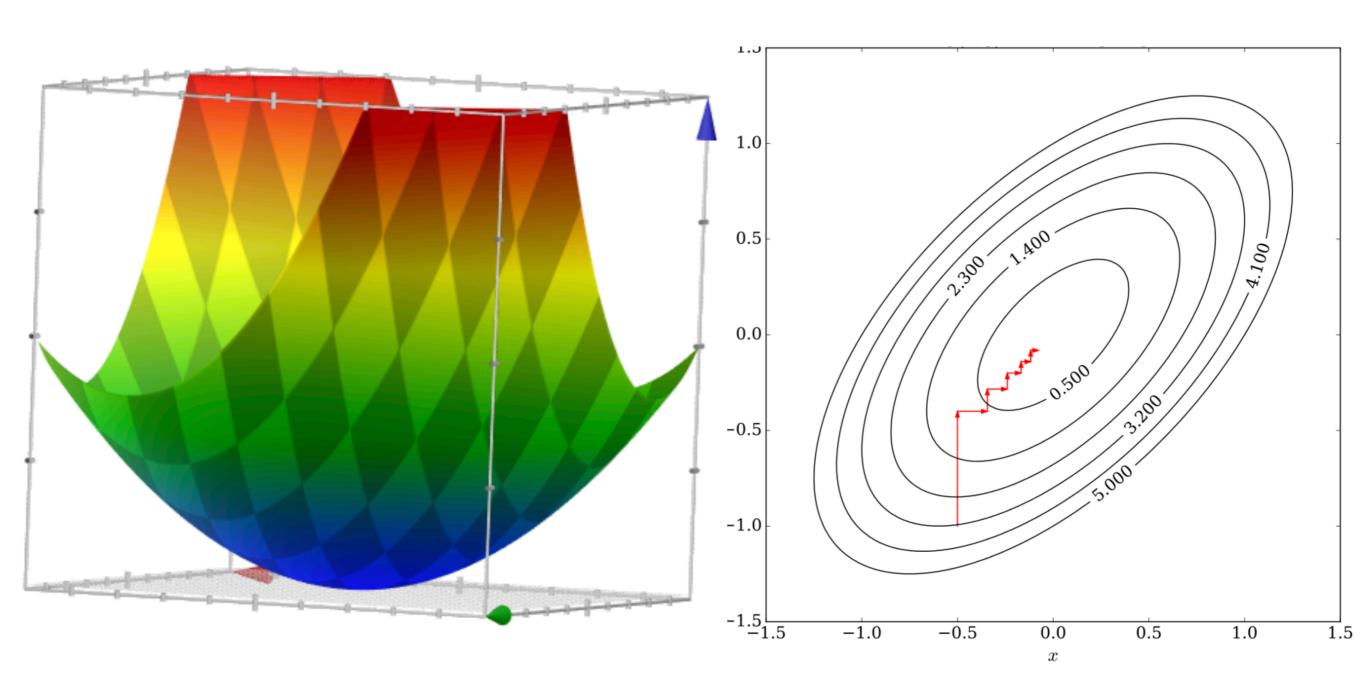
$$\mathcal{L}(w) = \left\| \mathbf{X}[:,1]w_1 + \mathbf{X}[:,2:d]w_{-1} - \mathbf{y} \right\|_2^2$$
where $w_{-1} = [w_2^{(t-1)}, \dots, w_d^{(t-1)}]^T$



we know from linear least squares that the minimizer is

$$w_1^{(t)} \leftarrow (\mathbf{X}[:,1]^T \mathbf{X}[:,1])^{-1} \mathbf{X}[:,1]^T (\mathbf{y} - \mathbf{X}[:,2:d] w_{-1})$$

Coordinate descent applied to a quadratic loss



Coordinate descent for Lasso

- let us apply coordinate descent on Lasso, which minimizes $\min_{w} \mathcal{L}(w) + \lambda \|w\|_1 = \|\mathbf{X}w \mathbf{y}\|_2^2 + \lambda \|w\|_1$
- the goal is to derive an **analytical rule** for updating $\boldsymbol{w}_{j}^{(t)}$'s
- let us first write the update rule explicitly for $w_1^{(t)}$
 - first step is to write the loss in terms of w_1

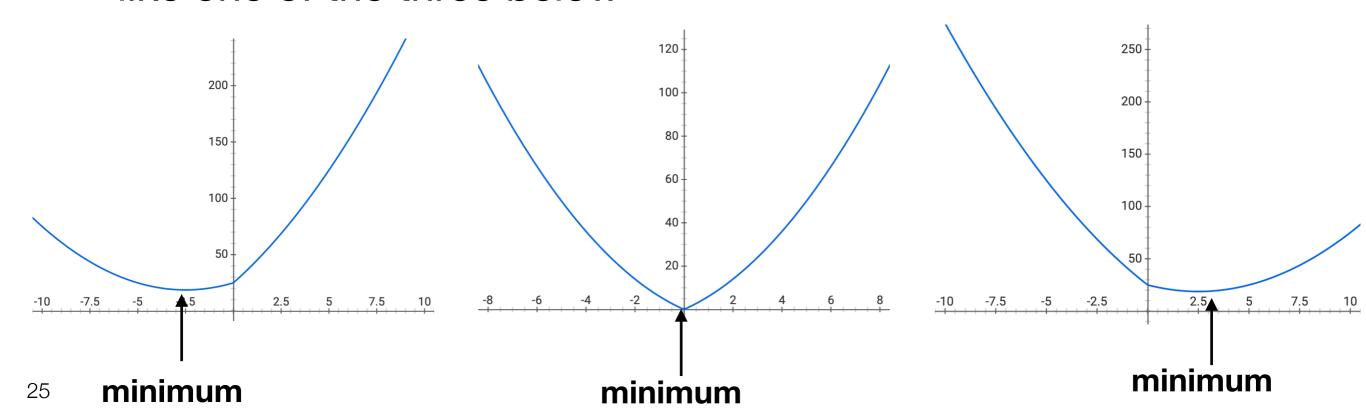
$$\|\mathbf{X}[:,1]w_{1} - (\mathbf{y} - \mathbf{X}[:,2:d]w_{-1})\|_{2}^{2} + \lambda(\|w_{1}\| + \|w_{-1}\|_{1})$$
constant

hence, the coordinate descent update boils down to

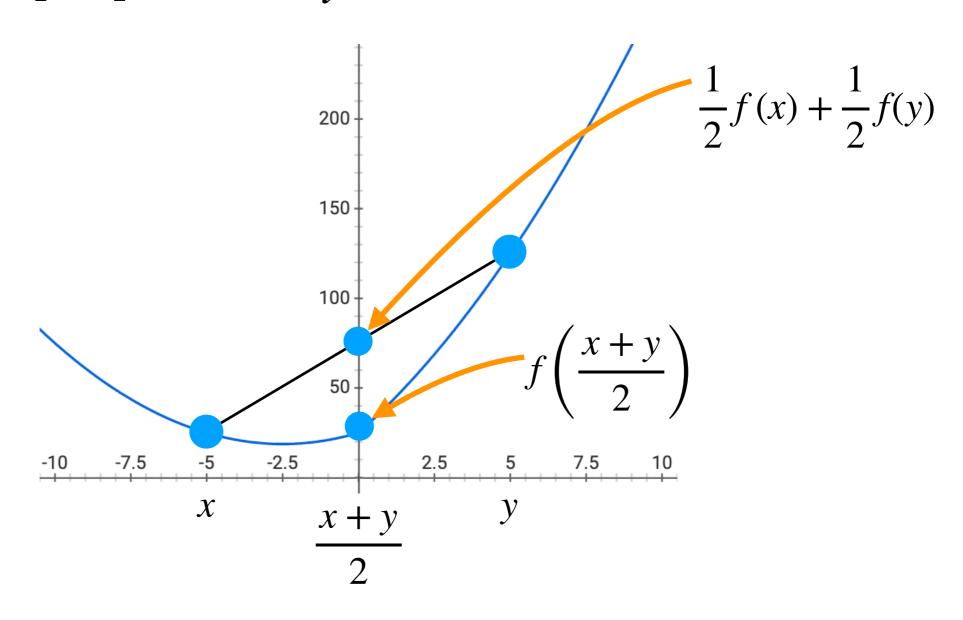
$$w_1^{(t)} \leftarrow \arg\min_{w_1} \left\| \mathbf{X}[:,1]w_1 - \left(\mathbf{y} - \mathbf{X}[:,2:d]w_{-1}\right) \right\|_2^2 + \lambda |w_1|$$

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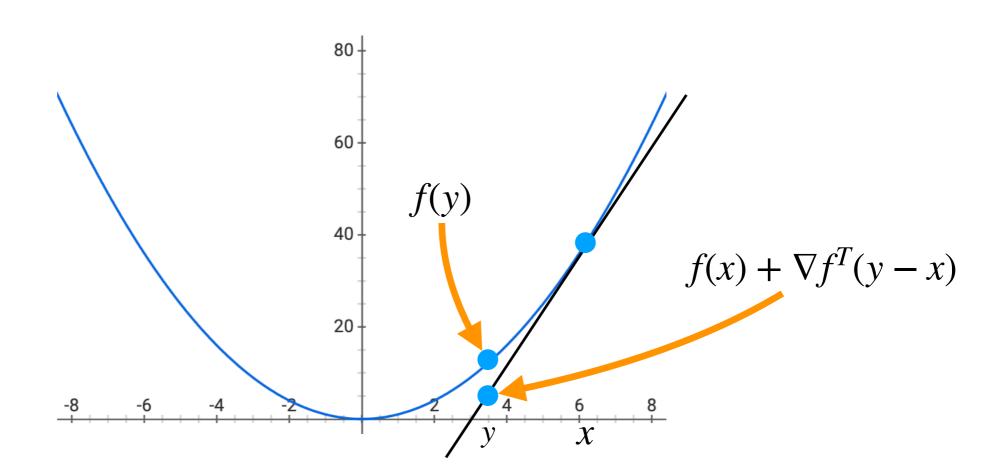
- to find the minimizer of $f(w_1)$, let's study some properties
- for simplicity, we represent the objective function as $f(w_1) = (aw_1 b)^2 + \lambda |w_1|$
- this function is
 - convex, and
 - non-differentiable
- depending on the values of a and b, the function looks like one of the three below



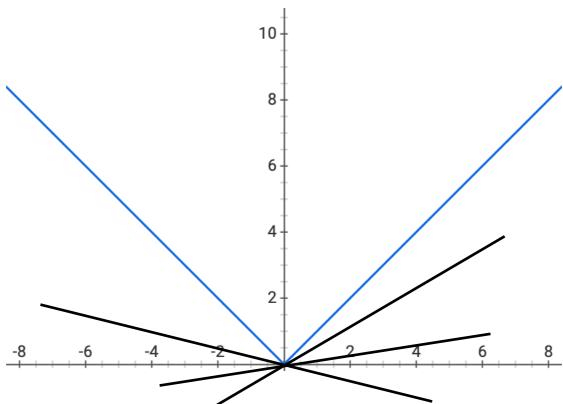
- A function f(x) is **convex** if and only if
 - $f(ax + (1 a)y) \le af(x) + (1 a)f(y)$ for all $a \in [0,1]$ and all x, y



- function f(x) is **differentiable** if and only if
 - partial derivative $\frac{\partial f(x)}{\partial x_j}$ exists for all x and $j \in \{1, \ldots, d\}$
- for a differentiable function f(x), there is another definition of **convexity**
 - $f(y) \ge f(x) + \nabla f(x)^T (y x)$ for all x, y



$$f(x) = |x|$$

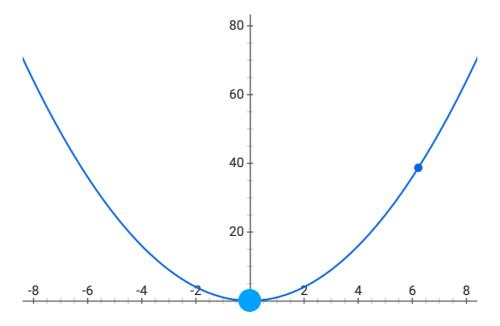


- for a **non-differentiable** function, gradient is not defined at some points, for example at x = 0 for f(x) = |x|
- at such points, sub-gradient plays the role of gradient
 - sub-gradient at a differentiable point is the same as the gradient
 - sub-gradient at a non-differentiable point is a set of vector satisfying

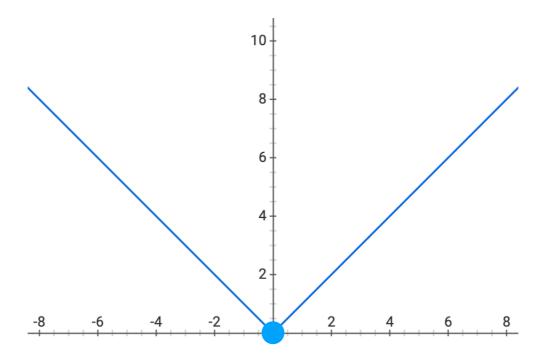
$$\partial f(x) = \left\{ g \in \mathbb{R}^d \mid f(y) \ge f(x) + g^T(y - x), \text{ for all } y \in \mathbb{R}^d \right\}$$

• for example,
$$\partial |x| = \begin{cases} +1 & \text{for } x > 0 \\ [-1,1] & \text{for } x = 0 \\ -1 & \text{for } x < 0 \end{cases}$$

 for convex differentiable functions, the minimum is achieved at points where gradient is zero



 for convex non-differentiable functions, the minimum is achieved at points where sub-gradient includes zero



ω(ct) < - ort min | | X1.W) - (- X2:d· ω_1) | 2 + 2 | ω| | $f(\omega_1) = (a\omega_1 - b)^2 + \lambda |\omega_1| + const$ = x, x, w, 2 - w, 2x, (y-X2=a-W-1) + 2 lw, + conq $=\left(\sqrt{x_{1}^{7}x_{1}}\cdot\omega_{1}-\frac{x_{1}^{7}(\chi-\chi_{2}-\chi_{2}-\chi_{3})}{\sqrt{x_{1}^{7}x_{1}}}\right)^{2}+\lambda\left|\omega_{1}\right|+6\omega t$

$$\begin{aligned}
\frac{\partial f(\omega_i)}{\partial t} &= \frac{\partial (\alpha \omega_i - b)^2}{\partial t} + \frac{\partial \lambda |\omega_i|}{\partial t} \\
&= \frac{\partial (\alpha \omega_i - b)}{\partial t} + \frac{\partial \lambda |\omega_i|}{\partial t} + \frac{\partial \lambda |\omega_i|}{\partial t} \\
\frac{\partial f(\omega_i)}{\partial t} &= \frac{\partial (\alpha \omega_i - b)}{\partial t} + \frac{\partial \lambda |\omega_i|}{\partial t} + \frac{\partial \lambda |\omega_i|}{\partial t} \\
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\frac{\partial f(\omega_i)}{\partial t} &= \frac{\partial (\alpha \omega_i - b)^2}{\partial t} + \frac{\partial \lambda |\omega_i|}{\partial t$$

Coordinate descent update on Lasso

$$w_1^{(t)} = \arg\min_{w_1} \left\| \mathbf{X}[:,1]w_1 - \left(\mathbf{y} - \mathbf{X}[:,2:d]w_{-1}\right) \right\|_2^2 + \lambda |w_1|$$

$$f(w_1)$$

• this is $f(w_1) = (aw_1 - b)^2 + \lambda |w_1| + \text{constants}$, with

•
$$a = \sqrt{\mathbf{X}[:,1]^T \mathbf{X}[:,1]}$$
, and
• $b = \frac{\mathbf{X}[:,1]^T (\mathbf{y} - \mathbf{X}[:,2:d] w_{-1})}{\sqrt{\mathbf{X}[:,1]^T \mathbf{X}[:,1]}}$

• $f(w_1)$ is non-differentiable, and its sub-gradient is

$$\partial f(w_1) = (2a(aw_1 - b) + \lambda \partial |w_1|)$$

$$= \begin{cases} 2a(aw_1 - b) + \lambda & \text{for } w_1 > 0 \\ [-2ab - \lambda, -2ab + \lambda] & \text{for } w_1 = 0 \\ 2a(aw_1 - b) - \lambda & \text{for } w_1 < 0 \end{cases}$$

$$\begin{array}{ll}
\partial f(w_i) = & \frac{2\alpha(\alpha w_i - b) + \lambda}{2\alpha(\alpha w_i - b) + \lambda} & \frac{i f w_i > 0}{2\alpha w_i > 0} \\
\text{Case 1: } if 2\alpha(\alpha w_i - b + \lambda = 0 \text{ for some } w_i > 0) \\
& \frac{2\alpha^2 w_i^* = -\lambda + 2\alpha b}{2\alpha^2} > 0 \\
& w_1^{(4)} = \frac{b}{\alpha} - \frac{\lambda}{2\alpha^2} & \text{if } 2\alpha b > \lambda
\end{array}$$

$$\begin{array}{ll}
\partial f(w_i) = 2\alpha(\alpha w_i - b) - \lambda & \text{if } w_i < 0 \\
(\text{ase 2: } w_i^* = \frac{\lambda + 2\alpha b}{2\alpha^2} < 0 \\
w_i^{(4)} \leftarrow \frac{b}{\alpha} + \frac{\lambda}{2\alpha^2} & \text{if } 2\alpha b < -\lambda
\end{array}$$

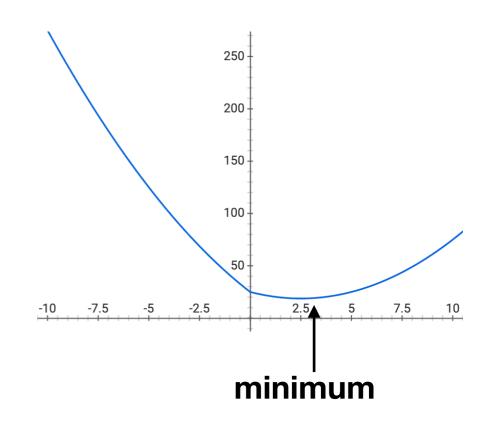
$$\begin{array}{ll}
\partial f(w_i) = \begin{bmatrix} -2\alpha b - \lambda, -2\alpha b + \lambda \end{bmatrix}, & w_i^* = 0 \\
\cos s & \text{if } \cos s \\
-2\alpha b - \lambda & \text{if } \cos s \\
w_i^{(4)} \leftarrow 0, -\lambda & \text{if } \cos s & \text{if } \cos s$$

How do we find the minimizer?

• the minimizer $\boldsymbol{w}_1^{(t)}$ is when zero is included in the sub-gradient

$$\partial f(w_1) = \begin{cases} 2a(aw_1 - b) + \lambda & \text{for } w_1 > 0 \\ [-2ab - \lambda, -2ab + \lambda] & \text{for } w_1 = 0 \\ 2a(aw_1 - b) - \lambda & \text{for } w_1 < 0 \end{cases}$$

- case 1:
 - $2a(aw_1 b) + \lambda = 0$ for some $w_1 > 0$
 - this happens when $w_1 = \frac{-\lambda + 2ab}{2a^2} > 0$
 - hence, $w_1^{(t)} \leftarrow \frac{b}{a} \frac{\lambda}{2a^2},$ if $\lambda < 2ab$



- case 2:
 - $2a(aw_1 b) \lambda = 0$ for some $w_1 < 0$
 - this happens when

$$w_1 = \frac{\lambda + 2ab}{2a^2} < 0$$

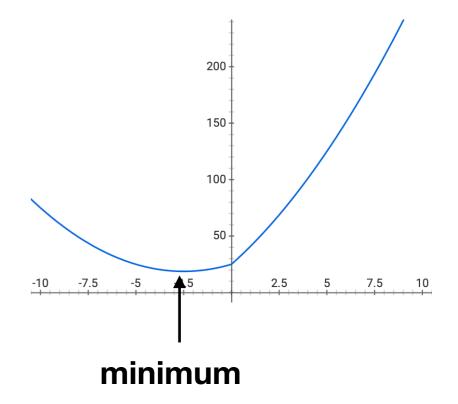
hence,

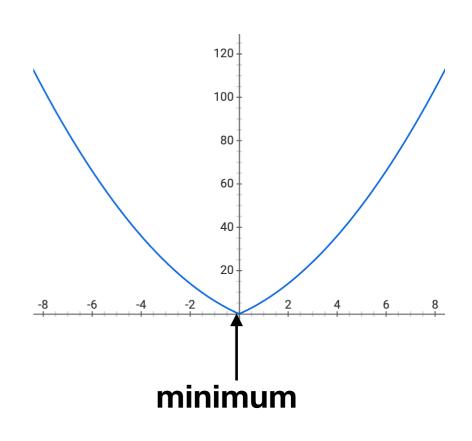
$$w_1^{(t)} \leftarrow \frac{b}{a} + \frac{\lambda}{2a^2},$$

if
$$\lambda < -2ab$$

- case 3:
 - $0 \in [-2ab \lambda, -2ab + \lambda]$
 - and $w_1 = 0$
 - hence, $w_1^{(t)} \leftarrow 0$,

if
$$-\lambda \le 2ab \le \lambda$$



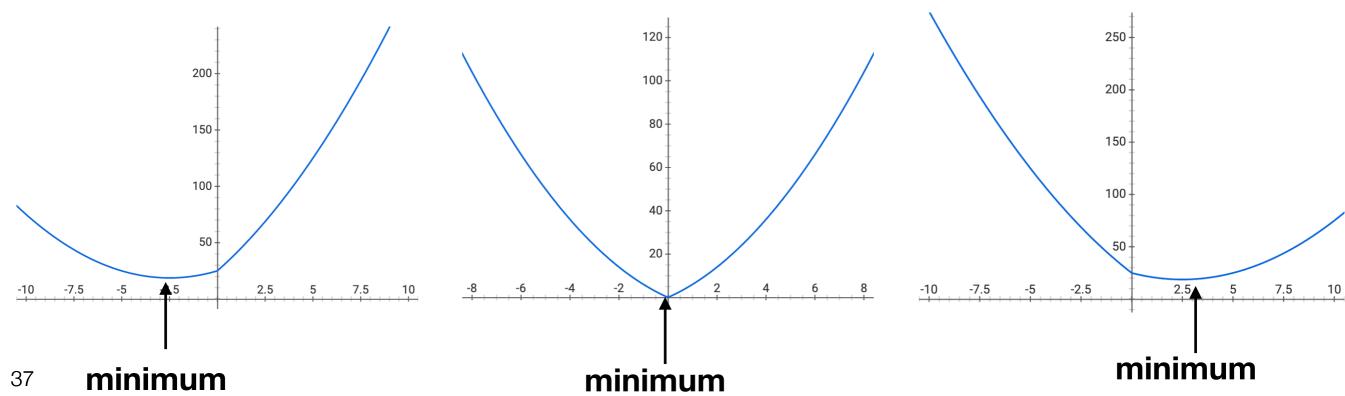


Coordinate descent on Lasso

 considering all three cases, we get the following update rule by setting the sub-gradient to zero

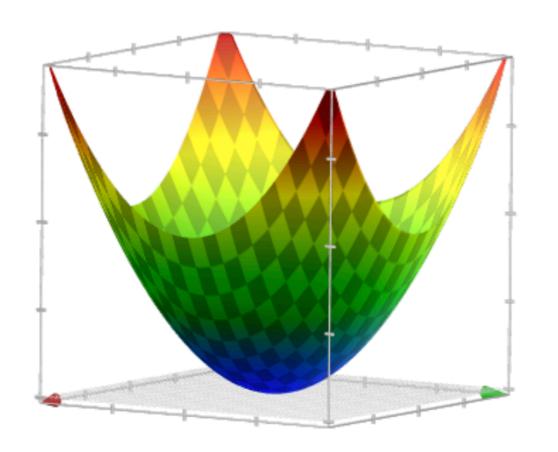
$$w_1^{(t)} \leftarrow \begin{cases} \frac{b}{a} - \frac{\lambda}{2a^2} & \text{for } 2ab > \lambda \\ 0 & \text{for } -\lambda \le 2ab \le \lambda \\ \frac{b}{a} + \frac{\lambda}{2a^2} & \text{for } \lambda < -2ab \end{cases}$$

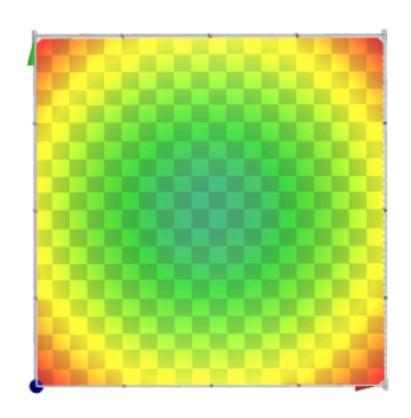
where
$$a = \sqrt{\mathbf{X}[:,1]^T \mathbf{X}[:,1]}$$
, and $b = \frac{\mathbf{X}[:,1]^T (\mathbf{y} - \mathbf{X}[:,2:d] w_{-1})}{\sqrt{\mathbf{X}[:,1]^T \mathbf{X}[:,1]}}$



When does coordinate descent work?

• Consider minimizing a **differentiable convex** function f(x), then coordinate descent converges to the global minima

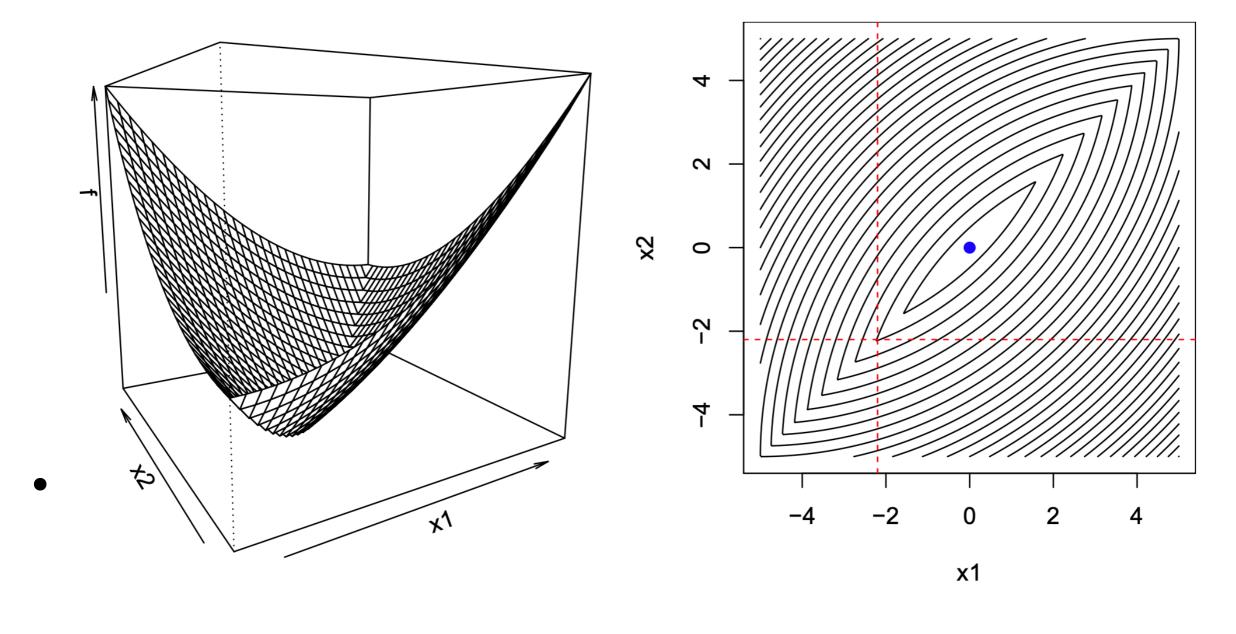




- when coordinate descent has stopped, that means $\frac{\partial f(x)}{\partial x_i} = 0$ for all $j \in \{1, ..., d\}$
- this implies that the gradient $\nabla_x f(x) = 0$, which happens only at minimum

When does coordinate descent work?

• Consider minimizing a **non-differentiable convex** function f(x), then coordinate descent can get stuck



When does coordinate descent work?

- then how can coordinate descent find optimal solution for Lasso?
- consider minimizing a **non-differentiable convex** function but has a structure of $f(x) = g(x) + \sum_{i=1}^{d} h_j(x_j)$, with differentiable convex

function g(x) and coordinate-wise non-differentiable convex functions $h_i(x_i)$'s, then coordinate descent converges to the global minima

