

Machine Learning (CSE 446): Decision Trees (continued)

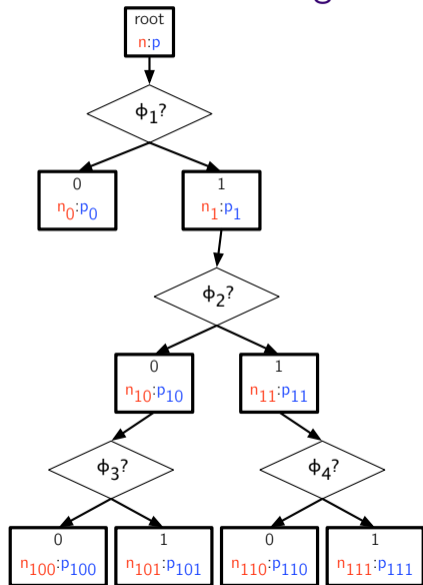
Noah Smith

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University of Washington
nasmith@cs.washington.edu

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Decision Tree: Making a Prediction



Data: decision tree t , input example x

Result: predicted class

if t has the form $\text{LEAF}(y)$ **then**

 return y ;

else

 # $t.\phi$ is the feature associated with t ;

 # $t.\text{child}(v)$ is the subtree for value v ;

 return $\text{DTREETEST}(t.\text{child}(t.\phi(x)), x)$;

end

Algorithm 1: DTREETEST

Greedy Building a Decision Tree (Binary Features)

Data: data D , feature set Φ

Result: decision tree

if all examples in D have the same label y , or Φ is empty and y is the best guess **then**

 return LEAF(y);

else

for each feature ϕ in Φ **do**

 partition D into D_0 and D_1 based on ϕ -values;

 let mistakes(ϕ) = (non-majority answers in D_0) + (non-majority answers in D_1);

end

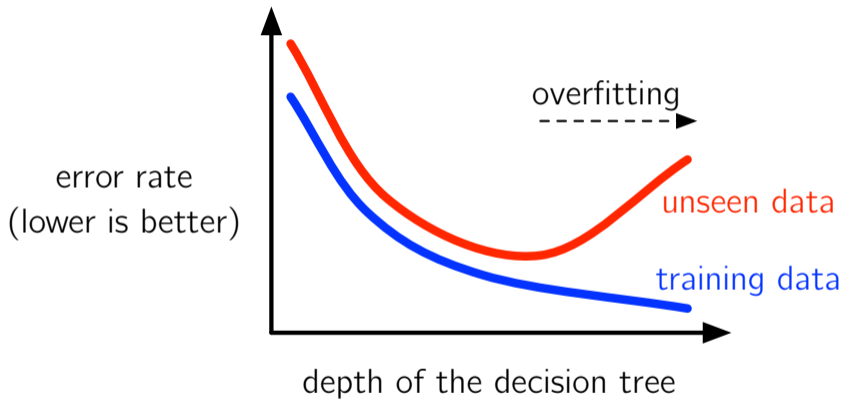
 let ϕ^* be the feature with the smallest number of mistakes;

 return NODE(ϕ^* , {0 \rightarrow DTREETRAIN(D_0 , $\Phi \setminus \{\phi^*\}$), 1 \rightarrow DTREETRAIN(D_1 , $\Phi \setminus \{\phi^*\}$)});

end

Algorithm 2: DTREETRAIN

Danger: Overfitting



Some Notation

- ▶ Let ℓ be a loss function; $\ell(y, \hat{y})$ is what we lose by outputting \hat{y} when y is the correct output. For classification:

$$\ell(y, \hat{y}) = \mathbb{I}[y \neq \hat{y}]$$

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- ▶ The training data $D = \langle (x_1, y_1), (x_2, y_2), \dots, (x_N, y_N) \rangle$ are assumed to be i.i.d. samples from \mathcal{D} .
- ▶ The space of classifiers we’re considering is \mathcal{F} ; f is a classifier from \mathcal{F} , chosen by our learning algorithm.

Overfitting, More Formally

- ▶ Classifier f 's average loss on **training data**:

$$\hat{\epsilon}(f) = \frac{1}{N} \sum_{n=1}^N \ell(y_n, f(x_n))$$

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- ▶ f has overfit D when:

$$\exists f' \in \mathcal{F} \text{ s.t. } \hat{\epsilon}(f) < \hat{\epsilon}(f') \wedge \epsilon(f') < \epsilon(f)$$

This is the fundamental problem of ML.

Inductive, Supervised Machine Learning

- ▶ Input: loss function ℓ and training data D drawn i.i.d. from \mathcal{D}
- ▶ Output: f such that $\epsilon(f)$ is low over \mathcal{D} , with respect to ℓ

Never forget that $\epsilon(f) \neq \hat{\epsilon}(f)$.

Is your training data D really drawn from \mathcal{D} ?

Back to decision trees ...

Avoiding Overfitting by Stopping Early

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In each case, we have a **hyperparameter** $(d_{max}, \Delta, N_{min})$, which you should **tune** on **development data**.

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- ▶ Choose the t_i that performs best on development data.

More Things to Know

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- ▶ For continuous-valued features, we use thresholds, e.g., $\phi(x) \leq \tau$.
In this case, you must choose τ .

If the sorted values of ϕ are $\langle v_1, v_2, \dots, v_N \rangle$, you only need to consider

$$\tau \in \left\{ \frac{v_n + v_{n+1}}{2} \right\}_{n=1}^{N-1} \text{ (midpoints between consecutive feature values).}$$

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- ▶ For continuous-valued **outputs**, what value makes sense as the prediction at a leaf? What loss should we use instead of $\llbracket y \neq \hat{y} \rrbracket$?

Machine Learning (CSE 446): Limits of Learning

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The Bayes Optimal Classifier

$$f^{(\text{BO})}(x) = \underset{y}{\operatorname{argmax}} \mathcal{D}(x, y)$$

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Theorem: The Bayes optimal classifier achieves minimal zero/one error ($\ell(y, \hat{y}) = \mathbb{I}[y \neq \hat{y}]$) of any deterministic classifier.

Proof

Consider (deterministic) f' that claims to be better than $f^{(\text{BO})}$ and x such that $f^{(\text{BO})}(x) \neq f'(x)$.

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By definition,

$$\begin{aligned} \mathcal{D}(x, f^{(\text{BO})}(x)) &= \max_y \mathcal{D}(x, y) \geq \mathcal{D}(x, f'(x)) \\ \Rightarrow \left(\sum_y \mathcal{D}(x, y)\right) - \mathcal{D}(x, f^{(\text{BO})}(x)) &\leq \left(\sum_y \mathcal{D}(x, y)\right) - \mathcal{D}(x, f'(x)) \end{aligned}$$

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This must hold for all x . Hence f' is no better than $f^{(\text{BO})}$.

One Limit of Learning

You cannot do better than $\epsilon(f^{\text{BO}})$.