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**Adaptation:** what to do when you know your training and test data don’t match?
Unsupervised Adaptation

\( D^{(\text{old})} \) is the distribution from which our labeled dataset \( D^{(\text{old})} = \{(x_n, y_n)\}_{n=1}^N \) is drawn.

\( D^{(\text{new})} \) is the distribution from which an unlabeled set \( D^{(\text{new})} = \{\tilde{x}_m\}_{m=1}^M \) is drawn, and from which our test data are assumed to be drawn.
Reweighting

Let $\ell(x, y)$ be some loss function (true or surrogate).

$$
\mathbb{E}_{(x,y) \sim D^{(new)}(x,y)}[\ell(x, y)] = \sum_{x,y} D^{(new)}(x, y) \cdot \ell(x, y) \\
= \sum_{x,y} D^{(new)}(x, y) \cdot \frac{D^{(old)}(x, y)}{D^{(old)}(x, y)} \cdot \ell(x, y) \\
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$$

Challenge question: how to update SGD with weighted training examples?
Example Weights $\frac{D^{(new)}(x,y)}{D^{(old)}(x,y)}$

- Directly estimating the probabilities $D$ is *really hard* (it’s known as “density estimation”).
- Instead, estimate the ratio.
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- Instead, estimate the ratio.

Generative story for an $(x, y)$ pair:
1. First, sample the pair from $D^{(base)}$.
2. Draw variable $S$, which ranges over \{old, new\}, according to $p(S \mid X = x)$. 
Example Weights \( \frac{D^{(\text{new})}(x,y)}{D^{(\text{old})}(x,y)} \)

- Directly estimating the probabilities \( D \) is really hard (it’s known as “density estimation”).
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1. First, sample the pair from \( D^{(\text{base})} \).
2. Draw variable \( S \), which ranges over \{old, new\}, according to \( p(S \mid X = x) \).

This implies:

\[
D^{(\text{old})}(x, y) = \frac{D^{(\text{base})}(x, y) \cdot p(S = \text{old} \mid X = x)}{\sum_{x', y'} D^{(\text{base})}(x', y') \cdot p(S = \text{old} \mid X = x')}
\]

\[
D^{(\text{new})}(x, y) = \frac{D^{(\text{base})}(x, y) \cdot p(S = \text{new} \mid X = x)}{\sum_{x', y'} D^{(\text{base})}(x', y') \cdot p(S = \text{new} \mid X = x')}
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Example Weights \( \frac{\mathcal{D}^{(\text{new})}(x,y)}{\mathcal{D}^{(\text{old})}(x,y)} \)

- Directly estimating the probabilities \( \mathcal{D} \) is **really hard** (it’s known as “density estimation”).
- Instead, estimate the ratio.

Generative story for an \((x, y)\) pair:

1. First, sample the pair from \( \mathcal{D}^{(\text{base})} \).
2. Draw variable \( S \), which ranges over \{old, new\}, according to \( p(S \mid X = x) \).

This implies:

\[
\mathcal{D}^{(\text{old})}(x,y) \propto \mathcal{D}^{(\text{base})}(x,y) \cdot p(S = \text{old} \mid X = x) \\
\mathcal{D}^{(\text{new})}(x,y) \propto \mathcal{D}^{(\text{base})}(x,y) \cdot p(S = \text{new} \mid X = x)
\]
\[
\frac{D^{(\text{new})}(x, y)}{D^{(\text{old})}(x, y)} \propto \frac{D^{(\text{base})}(x, y) \cdot p(\text{new} \mid x)}{D^{(\text{base})}(x, y) \cdot p(\text{old} \mid x)} \\
= \frac{1 - p(\text{old} \mid x)}{p(\text{old} \mid x)} \\
= \frac{1}{p(\text{old} \mid x)} - 1
\]
Unsupervised Adaptation Algorithm

**Data:** “old” data $\langle (x_n, y_n) \rangle_{n=1}^N$, “new” data $\langle \tilde{x}_m \rangle_{m=1}^M$, learning algorithm $A$ that takes a weighted training set

**Result:** classifier

$D^{(\text{distinguish})} = \langle (x_n, +1) \rangle_{n=1}^N \cup \langle (\tilde{x}_m, -1) \rangle_{m=1}^M$;

train a probabilistic classifier $\hat{p}$ on $D^{(\text{distinguish})}$;

$D^{(\text{weighted})} = \langle (x_n, y_n, \frac{1}{\hat{p}(+1|x_n)} - 1) \rangle_{n=1}^N$;

return $A(D^{(\text{weighted})})$

**Algorithm 1:** SELECTIONADAPTATION
Unsupervised Adaptation Algorithm

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Algorithm 2: SelectionAdaptation

Section 8.5 in Daume (2017) describes a theoretical result that makes conceptual use of something like $\hat{p}$.
Supervised Adaptation

“Old” labeled dataset \( D^{(\text{old})} = \langle (x_n, y_n) \rangle_{n=1}^N \).

“New” labeled dataset \( D^{(\text{new})} = \langle (\dot{x}_m, \dot{y}_m) \rangle_{m=1}^M \).

Test data is assumed to be from the same distribution as \( D^{(\text{new})} \).
Assume $x_n$ is represented by $x_n \in \mathbb{R}^d$ and $\dot{x}_m$ by $\dot{x}_m \in \mathbb{R}^d$; the feature functions are the same.
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Map:

$$\begin{array}{c}
\mathbf{x}_n \mapsto [x_n; x_n; \underbrace{0 \cdots 0}_d \text{ zeroes}]
\end{array}$$
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Map:

$$x_n \mapsto [x_n; x_n; \overbrace{0 \cdots 0}^{d \text{ zeroes}}]$$

Map:

$$\dot{x}_m \mapsto [\dot{x}_m; 0 \cdots 0; \dot{x}_m]$$
Data: “old” data $\langle (x_n, y_n) \rangle_{n=1}^N$, “new” data $\langle \dot{x}_m, \dot{y}_m \rangle_{m=1}^M$, learning algorithm $\mathcal{A}$

Result: classifier $D = \langle ([x_n; x_n; 0], y_n) \rangle_{n=1}^N \cup \langle ([\dot{x}_m; 0; \dot{x}_n], \dot{y}_m) \rangle_{m=1}^M$;

return $\mathcal{A}(D)$

Algorithm 3: **FEATURE AUGMENTATION ADAPTATION**
Notes

- It may be a good idea to up-weight “new” data, especially if $N \gg M$. 

You can combine selection adaptation (first, on untransformed data) with feature augmentation.

Always check these two baselines:
1. train on union of all data (will work best if old and new are actually pretty close)
2. train only on “new” data (will work best if old data is so distant as to be useless)
It may be a good idea to up-weight “new” data, especially if $N \gg M$.

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