Machine Learning (CSE 446): Beyond Binary Classification

#### Noah Smith

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University of Washington nasmith@cs.washington.edu

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- 2. Down-weight negative examples until you achieve balance. For example,

$$L^{(\mathsf{new})}(\mathbf{x}, y, \mathsf{parameters}) \leftarrow \alpha^{\llbracket y = +1 \rrbracket} \cdot L^{(\mathsf{old})}(\mathbf{x}, y, \mathsf{parameters})$$

A similar effect can be achieved in SGD by sampling non-uniformly; assign  $\frac{1}{2N_+}$  to positive examples and  $\frac{1}{2N_-}$  to negative examples.

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- 1. Throw out negative examples until you achieve balance.
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- 3. Modification to the hinge loss:

$$L_n^{(\text{hinge})}(\mathbf{w}, b) = \max\{0, \text{ cost}(y_n) - y_n \cdot (\mathbf{w} \cdot \mathbf{x}_n + b)\}$$
$$\operatorname{cost}(y_n) = \begin{cases} \alpha & \text{if } y_n = -1 \text{ (false positive)} \\ \beta & \text{if } y_n = +1 \text{ (false negative)} \end{cases}$$

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- 2. One-versus-all training: train  $|\mathcal{Y}|$  binary classifiers, letting each  $y \in \mathcal{Y}$  take a turn as the positive class. Let  $a^{(y)}$  be the activation function for the classifier where  $\{y \to +1, \mathcal{Y} \setminus \{y\} \to -1\}$ . Then define the classifier  $f : \mathcal{X} \to \mathcal{Y}$  as:

$$f(x) = \operatorname*{argmax}_{y \in \mathcal{Y}} a^{(y)}(x)$$

Theorem: error rate is at most  $(|\mathcal{Y}| - 1) \cdot \bar{\epsilon}$ , where  $\bar{\epsilon}$  is the average error rate among the binary classifiers.

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Theorem: error rate is at most  $(|\mathcal{Y}| - 1) \cdot \bar{\epsilon}$ , where  $\bar{\epsilon}$  is the average error rate among the binary classifiers. One bad classifier can ruin f; in particular, watch out for the more rare labels, and be sure to tune hyperparameters separately.

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- 4. Tree-structured tournament. Theorem: error rate is at most  $\lceil \log_2 |\mathcal{Y}| \rceil \cdot \bar{\epsilon}$ . Challenge: you must choose the tree.

Tree-Structured Tournament for Multiclass Classification



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Most common setup:  $x_n = \langle q_n, d \rangle$ , where  $q_n$  is a query and d is a (fixed, universal) set of documents  $\{d_1, \ldots, d_M\}$ . Output  $y_n$  is a ranking of d.

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Training on the binary problem  $\langle (\mathbf{x}_{n,i,j}, y_{n,i,j}) \rangle_{n \in \{1,...,N\}; i,j \in \{1,...,M\}}$  makes sense when the ranking is meant to separate relevant  $d_i$  from irrelevant  $d_i$ , known as "bipartite" ranking.

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One example:

$$\omega(i,j) = \left\{ \begin{array}{ll} 1 & \text{if } \min(i,j) \leq 10 \text{ and } i \neq j \\ 0 & \text{otherwise} \end{array} \right.$$

(More in the book.)

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Loss:

$$\mathbb{E}_{(q,\sigma)\sim\mathcal{D}}\left[\sum_{i,j:i\neq j} \llbracket \sigma(i) < \sigma(j) \rrbracket \cdot \llbracket \hat{\sigma}(i) < \hat{\sigma}(j) \rrbracket \cdot \omega(i,j)\right]$$

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Deriving a learning algorithm is left as an exercise. (See the book for an example.)