

CSE 446
Gaussian Naïve Bayes & Logistic Regression
 Winter 2012

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 Some slides from Carlos Guestrin, Luke Zettlemoyer

Last Time


- Learning Gaussians
- Naïve Bayes

Today

- Gaussians Naïve Bayes
- Logistic Regression

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
Text Classification
Bag of Words Representation



aardvark	0
about	2
all	2
Africa	1
apple	0
anxious	0
...	
gas	1
...	
oil	1
...	
Zaire	0


Bayesian Learning

Use Bayes rule:



Posterior

$P(Y | X) = \frac{P(X | Y) P(Y)}{P(X)}$



Prior

Or equivalently: $P(Y | X) \propto P(X | Y) P(Y)$

Normalization

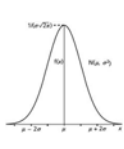
Naïve Bayes

- Naïve Bayes assumption:
 - Features are independent given class:
$$P(X_1, X_2 | Y) = P(X_1 | X_2, Y) P(X_2 | Y) = P(X_1 | Y) P(X_2 | Y)$$
 - More generally:

$$P(X_1 \dots X_n | Y) = \prod_i P(X_i | Y)$$
- How many parameters now?
 - Suppose X is composed of n binary features

The Distributions We Love

	Discrete	Continuous
	Binary {0, 1}	k Values
Single Event	Bernoulli	
Sequence (N trials) $N = \alpha_H + \alpha_T$	Binomial	Multinomial
Conjugate Prior	Beta	Dirichlet

$P(D | \theta) = \theta^{\alpha_H} (1 - \theta)^{\alpha_T}$


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NB with Bag of Words for Text Classification

- **Learning phase:**
 - Prior $P(Y_m)$
 - Count how many documents from topic m / total # docs
 - $P(X_i | Y_m)$
 - Let B_m be a bag of words formed from all the docs in topic m
 - Let $\#(i, B)$ be the number of times word i is in bag B
 - $P(X_i | Y_m) = (\#(i, B_m) + 1) / (W + \sum_j \#(j, B_m))$ where $W = \#$ unique words
- **Test phase:**
 - For each document
 - Use naïve Bayes decision rule

$$h_{NB}(x) = \arg \max_y P(y) \prod_{i=1}^{LengthDoc} P(x_i | y)$$

Easy to Implement

- But...
- If you do... it probably won't work...

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Probabilities: Important Detail!

- $P(\text{spam} | X_1 \dots X_n) = \prod_i P(\text{spam} | X_i)$
Any more potential problems here?
- We are multiplying lots of small numbers
Danger of underflow!
 - $0.5^{57} = 7 \text{ E } -18$
- Solution? Use logs and add!
 - $p_1 * p_2 = e^{\log(p_1) + \log(p_2)}$
 - Always keep in log form

Naïve Bayes Posterior Probabilities

- Classification results of naïve Bayes
 - I.e. the class with maximum posterior probability...
 - Usually fairly accurate (?!?!?)
- However, due to the inadequacy of the conditional independence assumption...
 - Actual posterior-**probability** estimates **not** accurate.
 - Output probabilities generally very close to 0 or 1.

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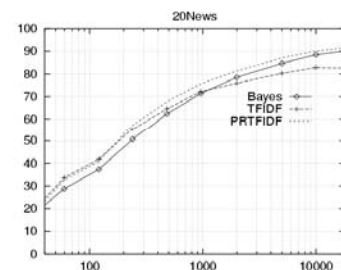
Twenty News Groups results

Given 1000 training documents from each group
Learn to classify new documents according to
which newsgroup it came from

comp.graphics	misc.forsale
comp.os.ms-windows.misc	rec.autos
comp.sys.ibm.pc.hardware	rec.motorcycles
comp.sys.mac.hardware	rec.sport.baseball
comp.windows.x	rec.sport.hockey
alt.atheism	sci.space
soc.religion.christian	sci.crypt
talk.religion.misc	sci.electronics
talk.politics.mideast	sci.med
talk.politics.misc	
talk.politics.guns	

Naive Bayes: 89% classification accuracy

Learning curve for Twenty News Groups



Accuracy vs. Training set size (1/3 withheld for test)

Bayesian Learning

What if Features are Continuous?

Eg., Character Recognition:
 X_j is j^{th} pixel

$P(Y | \mathbf{X}) \propto P(\mathbf{X} | Y) P(Y)$

↑
Data Likelihood

Bayesian Learning

What if Features are Continuous?

Eg., Character Recognition:
 X_j is j^{th} pixel

$P(Y | \mathbf{X}) \propto P(\mathbf{X} | Y) P(Y)$

$P(X_i = x | Y = y_k) = N(\mu_{ik}, \sigma_{ik})$

$N(\mu_{ik}, \sigma_{ik}) = \frac{1}{\sigma_{ik} \sqrt{2\pi}} e^{-\frac{(x - \mu_{ik})^2}{2\sigma_{ik}^2}}$

Gaussian Naïve Bayes

Sometimes Assume Variance

- is independent of Y (i.e., σ_i),
- or independent of X_j (i.e., σ_k)
- or both (i.e., σ)

$P(Y | \mathbf{X}) \propto P(\mathbf{X} | Y) P(Y)$

$P(X_i = x | Y = y_k) = N(\mu_{ik}, \sigma_{ik})$

$N(\mu_{ik}, \sigma_{ik}) = \frac{1}{\sigma_{ik} \sqrt{2\pi}} e^{-\frac{(x - \mu_{ik})^2}{2\sigma_{ik}^2}}$

Learning Gaussian Parameters

Maximum Likelihood Estimates:

- Mean:

$$\hat{\mu}_{MLE} = \frac{1}{N} \sum_{i=1}^N x_i$$

- Variance:

$$\hat{\sigma}_{MLE}^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \hat{\mu})^2$$

Learning Gaussian Parameters

Maximum Likelihood Estimates:

- Mean:

$$\hat{\mu}_{ik} = \frac{1}{\sum_j \delta(Y^j = y_k)} \sum_j X_i^j \delta(Y^j = y_k)$$

jth training example

- Variance:

$$\hat{\sigma}_{MLE}^2 = \frac{1}{N} \sum_{i=1}^N (x_i - \hat{\mu})^2$$

$\delta(x)=1$ if x true, else 0

Learning Gaussian Parameters

Maximum Likelihood Estimates:

- Mean:

$$\hat{\mu}_{ik} = \frac{1}{\sum_j \delta(Y^j = y_k)} \sum_j X_i^j \delta(Y^j = y_k)$$

- Variance:

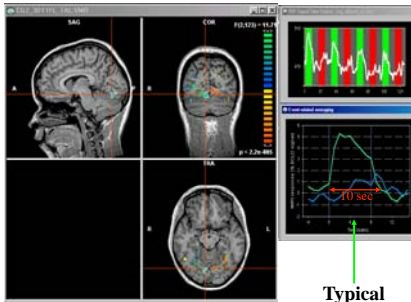
$$\hat{\sigma}_{ik}^2 = \frac{1}{\sum_j \delta(Y^j = y_k) - 1} \sum_j (X_i^j - \hat{\mu}_{ik})^2 \delta(Y^j = y_k)$$

Example: GNB for classifying mental states

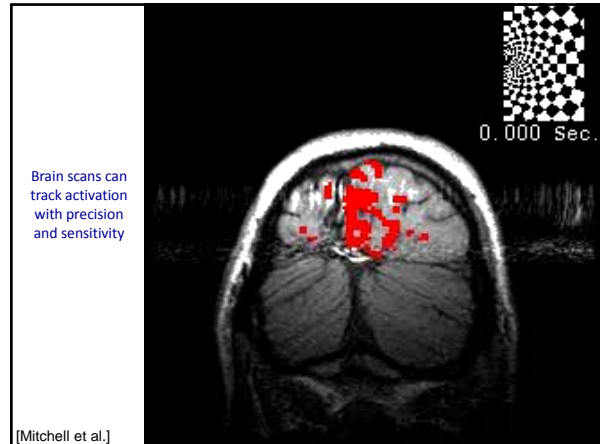
[Mitchell et al.]

~1 mm resolution
~2 images per sec.
15,000 voxels/image
non-invasive, safe

measures Blood Oxygen Level Dependent (BOLD) response



Typical impulse response

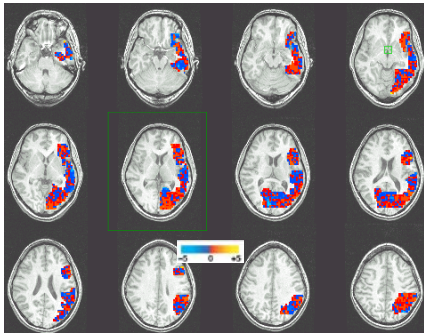


Brain scans can track activation with precision and sensitivity

[Mitchell et al.]

Gaussian Naïve Bayes: Learned $\mu_{\text{voxel}, \text{word}}$
 $P(\text{BrainActivity} \mid \text{WordCategory} = \{\text{People}, \text{Animal}\})$

[Mitchell et al.]

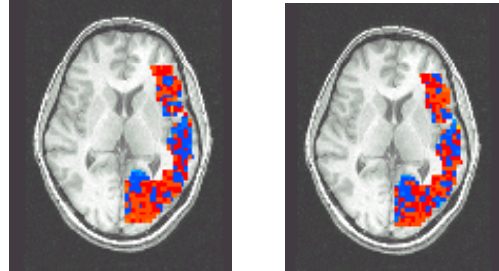


Gaussian Naïve Bayes: Learned $\mu_{\text{voxel}, \text{word}}$
 $P(\text{BrainActivity} \mid \text{WordCategory} = \{\text{People}, \text{Animal}\})$

[Mitchell et al.]

Pairwise classification accuracy: 85%

People words -5 0 +5 Animal words



What You Need to Know about Naïve Bayes

- Optimal Decision using Bayes Classifier
- Naïve Bayes Classifier
 - What's the assumption
 - Why we use it
 - How do we learn it
- Text Classification
 - Bag of words model
- Gaussian NB
 - Features still conditionally independent
 - Features have Gaussian distribution given class

What's (supervised) learning more formally

- Given:
 - **Dataset:** Instances $\{ \langle \mathbf{x}_1; t(\mathbf{x}_1) \rangle, \dots, \langle \mathbf{x}_N; t(\mathbf{x}_N) \rangle \}$
 - e.g., $\langle \mathbf{x}_i; t(\mathbf{x}_i) \rangle = \langle \langle \text{GPA}=3.9, \text{IQ}=120, \text{MLscore}=99 \rangle; 150K \rangle$
 - **Hypothesis space:** H
 - e.g., polynomials of degree 8
 - **Loss function:** measures quality of hypothesis $h \in H$
 - e.g., squared error for regression
- Obtain:
 - **Learning algorithm:** obtain $h \in H$ that minimizes loss function
 - e.g., using closed form solution if available
 - Or greedy search if not
 - Want to minimize prediction error, but can only minimize error in dataset

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Types of (supervised) learning problems, revisited

- **Decision Trees**, e.g.,
 - dataset: {votes; party}
 - hypothesis space:
 - Loss function:
- **NB Classification**, e.g.,
 - dataset: {brain image; {verb v. noun}}
 - hypothesis space:
 - Loss function:
- **Density estimation**, e.g.,
 - dataset: {grades}
 - hypothesis space:
 - Loss function:

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Learning is (simply) function approximation!

- **The general (supervised) learning problem:**
 - Given some data (including features), hypothesis space, loss function
 - Learning is no magic!
 - Simply trying to find a function that fits the data
- **Regression**
- **Density estimation**
- **Classification**
- (Not surprisingly) Seemly different problem, very similar solutions...

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What you need to know about supervised learning

- Learning is function approximation
- What functions are being optimized?

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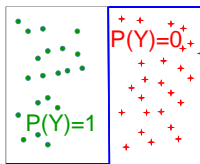
Generative vs. Discriminative Classifiers

- **Want to Learn:** $h: X \mapsto Y$
 - X – features
 - Y – target classes
- **Bayes optimal classifier** – $P(Y|X)$
- **Generative classifier**, e.g., Naïve Bayes:
 - Assume some functional form for $P(X|Y)$, $P(Y)$
 - Estimate parameters of $P(X|Y)$, $P(Y)$ directly from training data
 - Use Bayes rule to calculate $P(Y|X=x)$
 - This is a **'generative' model**
 - Indirect computation of $P(Y|X)$ through Bayes rule
 - As a result, can also generate a sample of the data, $P(X) = \sum_y P(y) P(X|y)$
- **Discriminative classifiers**, e.g., Logistic Regression:
 - Assume some functional form for $P(Y|X)$
 - Estimate parameters of $P(Y|X)$ directly from training data
 - This is the **'discriminative' model**
 - Directly learn $P(Y|X)$
 - But cannot obtain a sample of the data, because $P(X)$ is not available

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Logistic Regression

- Learn $P(Y|X)$ directly!
 - Assume a particular functional form
 - ⊗ **Not differentiable...**

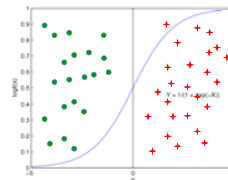


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Logistic Regression

- Learn $P(Y|X)$ directly!
 - Assume a particular functional form
 - Logistic Function
 - Aka Sigmoid

$$\frac{1}{1 + \exp(-z)}$$

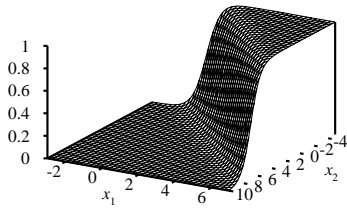


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Logistic Function in n Dimensions

$$P(Y = 1|X) = \frac{1}{1 + \exp(w_0 + \sum_{i=1}^n w_i X_i)}$$

Sigmoid applied to a linear function of the data:



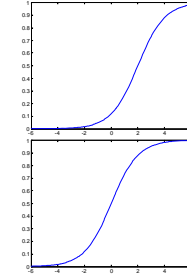
Features can be discrete or continuous!

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Understanding Sigmoids

$$g(w_0 + \sum_i w_i x_i) = \frac{1}{1 + e^{w_0 + \sum_i w_i x_i}}$$

$w_0 = -2, w_1 = -1$



$w_0 = 0, w_1 = -1$

$w_0 = 0, w_1 = -0.5$

Very convenient!

$$P(Y = 1|X = \langle X_1, \dots, X_n \rangle) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

implies

$$P(Y = 0|X = \langle X_1, \dots, X_n \rangle) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

implies

$$\frac{P(Y = 0|X)}{P(Y = 1|X)} = \exp(w_0 + \sum_i w_i X_i)$$

implies

$$\ln \frac{P(Y = 0|X)}{P(Y = 1|X)} = w_0 + \sum_i w_i X_i$$

linear
classification
rule!

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Loss functions:

Likelihood vs. Conditional Likelihood

- Generative (Naive Bayes) Loss function:

Data likelihood

$$\begin{aligned} \ln P(\mathcal{D} | \mathbf{w}) &= \sum_{j=1}^N \ln P(x^j, y^j | \mathbf{w}) \\ &= \sum_{j=1}^N \ln P(y^j | x^j, \mathbf{w}) + \sum_{j=1}^N \ln P(x^j | \mathbf{w}) \end{aligned}$$

- Discriminative models cannot compute $P(\mathbf{x} | \mathbf{w})!$
- But, discriminative (logistic regression) loss function:

Conditional Data Likelihood

$$\ln P(\mathcal{D}_Y | \mathcal{D}_X, \mathbf{w}) = \sum_{j=1}^N \ln P(y^j | x^j, \mathbf{w})$$

- Doesn't waste effort learning $P(\mathbf{x})$ – focuses on $P(\mathbf{y} | \mathbf{x})$ all that matters for classification

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Expressing Conditional Log Likelihood

$$l(\mathbf{w}) = \sum_j \ln P(y^j | x^j, \mathbf{w})$$

$$P(Y = 0|X, \mathbf{w}) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$P(Y = 1|X, \mathbf{w}) = \frac{\exp(w_0 + \sum_i w_i X_i)}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

$$l(\mathbf{w}) = \sum_j y^j \ln P(y^j = 1 | x^j, \mathbf{w}) + (1 - y^j) \ln P(y^j = 0 | x^j, \mathbf{w})$$

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Maximizing Conditional Log Likelihood

$$\begin{aligned} l(\mathbf{w}) &\equiv \ln \prod_j P(y^j | x^j, \mathbf{w}) \\ &= \sum_j y^j (w_0 + \sum_i w_i x_i^j) - \ln(1 + \exp(w_0 + \sum_i w_i x_i^j)) \end{aligned}$$

Good news: $l(\mathbf{w})$ is concave function of \mathbf{w} ! no locally optimal solutions

Bad news: no closed-form solution to maximize $l(\mathbf{w})$

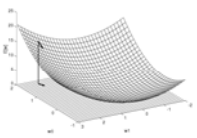
Good news: concave functions easy to optimize

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Optimizing concave function – Gradient ascent

- Conditional likelihood for Logistic Regression is concave! Find optimum with gradient ascent



Gradient: $\nabla_{\mathbf{w}} l(\mathbf{w}) = \left[\frac{\partial l(\mathbf{w})}{\partial w_0}, \dots, \frac{\partial l(\mathbf{w})}{\partial w_n} \right]^T$

Update rule: $\Delta \mathbf{w} = \eta \nabla_{\mathbf{w}} l(\mathbf{w})$

Learning rate, $\eta > 0$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \frac{\partial l(\mathbf{w})}{\partial w_i}$$

- Gradient ascent is simplest of optimization approaches
 - e.g., Conjugate gradient ascent much better (see reading)

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Maximize Conditional Log Likelihood: Gradient ascent

$$l(\mathbf{w}) = \sum_j y^j (w_0 + \sum_i w_i x_i^j) - \ln(1 + \exp(w_0 + \sum_i w_i x_i^j))$$

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Gradient Descent for LR

Gradient ascent algorithm: iterate until change $< \epsilon$

$$w_0^{(t+1)} \leftarrow w_0^{(t)} + \eta \sum_j [y^j - \hat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w})]$$

For $i=1, \dots, n$,

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \sum_j x_i^j [y^j - \hat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w})]$$

repeat

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That's all M(C)LE. How about MAP?

$$p(\mathbf{w} | Y, \mathbf{X}) \propto P(Y | \mathbf{X}, \mathbf{w}) p(\mathbf{w})$$

- One common approach is to define priors on \mathbf{w}
 - Normal distribution, zero mean, identity covariance
 - "Pushes" parameters towards zero
- Corresponds to **Regularization**
 - Helps avoid very large weights and overfitting
 - More on this later in the semester
- MAP estimate

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \ln \left[p(\mathbf{w}) \prod_{j=1}^N P(y^j | \mathbf{x}^j, \mathbf{w}) \right]$$

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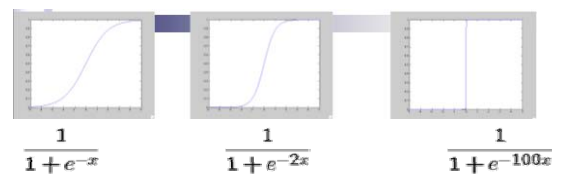
M(C)AP as Regularization

$$\ln \left[p(\mathbf{w}) \prod_{j=1}^N P(y^j | \mathbf{x}^j, \mathbf{w}) \right] \quad p(\mathbf{w}) = \prod_i \frac{1}{\sigma \sqrt{2\pi}} e^{-\frac{w_i^2}{2\sigma^2}}$$

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Penalizes high weights, also applicable in linear regression

Large parameters → Overfitting



- If data is linearly separable, weights go to infinity
- Leads to overfitting:
- Penalizing high weights can prevent overfitting...
 - again, more on this later in the semester

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Gradient of M(C)AP

$$\frac{\partial}{\partial w_i} \ln \left[p(\mathbf{w}) \prod_{j=1}^N P(y^j | \mathbf{x}^j, \mathbf{w}) \right] \quad p(\mathbf{w}) = \prod_i \frac{1}{\sigma_i \sqrt{2\pi}} e^{-\frac{w_i^2}{2\sigma_i^2}}$$

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MLE vs MAP

- Maximum conditional likelihood estimate

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \ln \left[\prod_{j=1}^N P(y^j | \mathbf{x}^j, \mathbf{w}) \right]$$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \sum_j x_i^j [y^j - \hat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w})]$$

- Maximum conditional a posteriori estimate

$$\mathbf{w}^* = \arg \max_{\mathbf{w}} \ln \left[p(\mathbf{w}) \prod_{j=1}^N P(y^j | \mathbf{x}^j, \mathbf{w}) \right]$$

$$w_i^{(t+1)} \leftarrow w_i^{(t)} + \eta \left\{ -\lambda w_i^{(t)} + \sum_j x_i^j [y^j - \hat{P}(Y^j = 1 | \mathbf{x}^j, \mathbf{w})] \right\}$$

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Logistic regression v. Naïve Bayes

- Consider learning $f: X \rightarrow Y$, where
 - X is a vector of real-valued features, $\langle X_1 \dots X_n \rangle$
 - Y is boolean
- Could use a Gaussian Naïve Bayes classifier
 - assume all X_i are conditionally independent given Y
 - model $P(X_i | Y = y_k)$ as Gaussian $N(\mu_{ik}, \sigma_i)$
 - model $P(Y)$ as Bernoulli $(\theta, 1-\theta)$
- What does that imply about the form of $P(Y|X)$?

$$P(Y = 1 | X = \langle X_1, \dots, X_n \rangle) = \frac{1}{1 + \exp(w_0 + \sum_i w_i X_i)}$$

Cool!!!!

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Derive form for $P(Y|X)$ for continuous X_i

$$\begin{aligned} P(Y = 1 | X) &= \frac{P(Y = 1)P(X|Y = 1)}{P(Y = 1)P(X|Y = 1) + P(Y = 0)P(X|Y = 0)} \\ &= \frac{1}{1 + \frac{P(Y=0)P(X|Y=0)}{P(Y=1)P(X|Y=1)}} \\ &= \frac{1}{1 + \exp(\ln \frac{P(Y=0)P(X|Y=0)}{P(Y=1)P(X|Y=1)})} \\ &= \frac{1}{1 + \exp(\ln \frac{1-\theta}{\theta} + \sum_i \ln \frac{P(X_i|Y=0)}{P(X_i|Y=1)})} \end{aligned}$$

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Ratio of class-conditional probabilities

$$\ln \frac{P(X_i | Y = 0)}{P(X_i | Y = 1)}$$

$$P(X_i = x | Y = y_k) = \frac{1}{\sigma_i \sqrt{2\pi}} e^{-\frac{(x - \mu_{ik})^2}{2\sigma_i^2}}$$

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Derive form for $P(Y|X)$ for continuous X_i

$$\begin{aligned} P(Y = 1 | X) &= \frac{P(Y = 1)P(X|Y = 1)}{P(Y = 1)P(X|Y = 1) + P(Y = 0)P(X|Y = 0)} \\ &= \frac{1}{1 + \exp(\ln \frac{1-\theta}{\theta} + \sum_i \ln \frac{P(X_i|Y=0)}{P(X_i|Y=1)})} \\ &= \frac{1}{1 + \exp(w_0 + \sum_{i=1}^n w_i X_i)} \end{aligned}$$

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Gaussian Naïve Bayes v. Logistic Regression

Set of Gaussian Naïve Bayes parameters (feature variance independent of class label)

Set of Logistic Regression parameters

- Representation equivalence
 - But only in a special case!!! (GNB with class-independent variances)
- But what's the difference???
- LR makes no assumptions about $P(X|Y)$ in learning!!!
- Loss function!!!
 - Optimize different functions ! Obtain different solutions

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Naïve Bayes vs Logistic Regression

Consider Y boolean, X_i continuous, $X = \langle X_1 \dots X_n \rangle$

Number of parameters:

- NB: $4n + 1$
- LR: $n + 1$

Estimation method:

- NB parameter estimates are uncoupled
- LR parameter estimates are coupled

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G. Naïve Bayes vs. Logistic Regression 1

[Ng & Jordan, 2002]

- Generative and Discriminative classifiers
- Asymptotic comparison (# training examples \rightarrow infinity)
 - when model correct
 - GNB, LR produce identical classifiers
 - when model incorrect
 - LR is less biased – does not assume conditional independence
 - therefore LR expected to outperform GNB

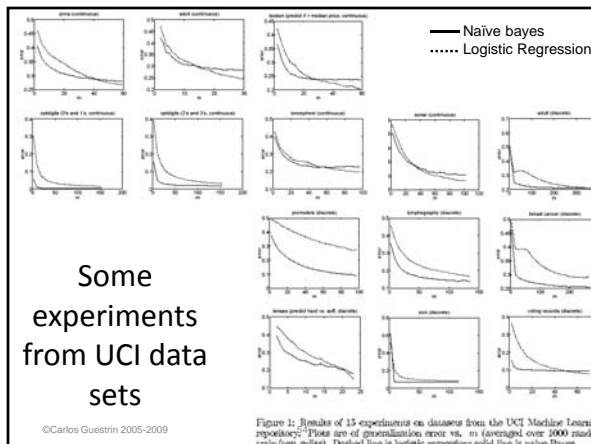
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G. Naïve Bayes vs. Logistic Regression 2

[Ng & Jordan, 2002]

- Generative and Discriminative classifiers
- Non-asymptotic analysis
 - convergence rate of parameter estimates, $n = \#$ of attributes in X
 - Size of training data to get close to infinite data solution
 - GNB needs $O(\log n)$ samples
 - LR needs $O(n)$ samples
- GNB converges more quickly to its (perhaps less helpful) asymptotic estimates

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What you should know about Logistic Regression (LR)

- Gaussian Naïve Bayes with class-independent variances representationally equivalent to LR
 - Solution differs because of objective (loss) function
- In general, NB and LR make different assumptions
 - NB: Features independent given class ! assumption on $P(X|Y)$
 - LR: Functional form of $P(Y|X)$, no assumption on $P(X|Y)$
- LR is a linear classifier
 - decision rule is a hyperplane
- LR optimized by conditional likelihood
 - no closed-form solution
 - concave ! global optimum with gradient ascent
 - Maximum conditional a posteriori corresponds to regularization
- Convergence rates
 - GNB (usually) needs less data
 - LR (usually) gets to better solutions in the limit

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