

Database System Internals Indexing

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April 10, 2020

CSE 444 - Spring 2020

- Homework 1: due on Friday (gradescope)
- Lab 1 Part 2: due next Wednesday
- 544M paper review: due next Friday
- Updates to Office Hours protocol:
 - Everybody joins (no more waiting room)
 - For private conversation, TA takes you to breakout room

A sequence of pages (implementation in SimpleDB)

| Data |
|------|------|------|------|------|------|------|------|
| page |

Some pages have space and other pages are full Add pages at the end when need more space

Works well for small files But finding free space requires scanning the file...

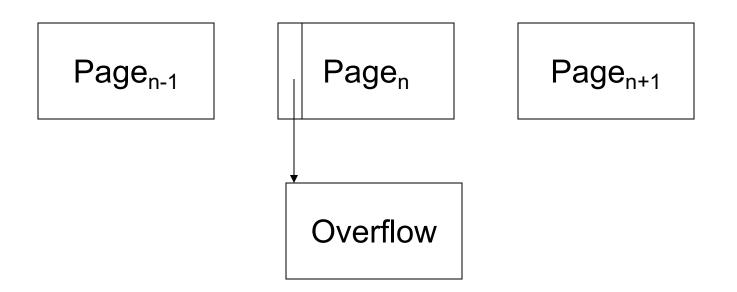
Modifications: Insert Tuple

- File is unsorted (= heap file)
 - add it wherever there is space (easy \odot)
 - add more pages if out of space

File is sorted

- Is there space on the right page ?
 - Yes: we are lucky, store it there
- Is there space in a neighboring page ?
 - Look 1-2 pages to the left/right, shift records
- If anything else fails, create overflow page

Overflow Pages



 After a while the file starts being dominated by overflow pages: time to reorganize

Modifications: Deletions

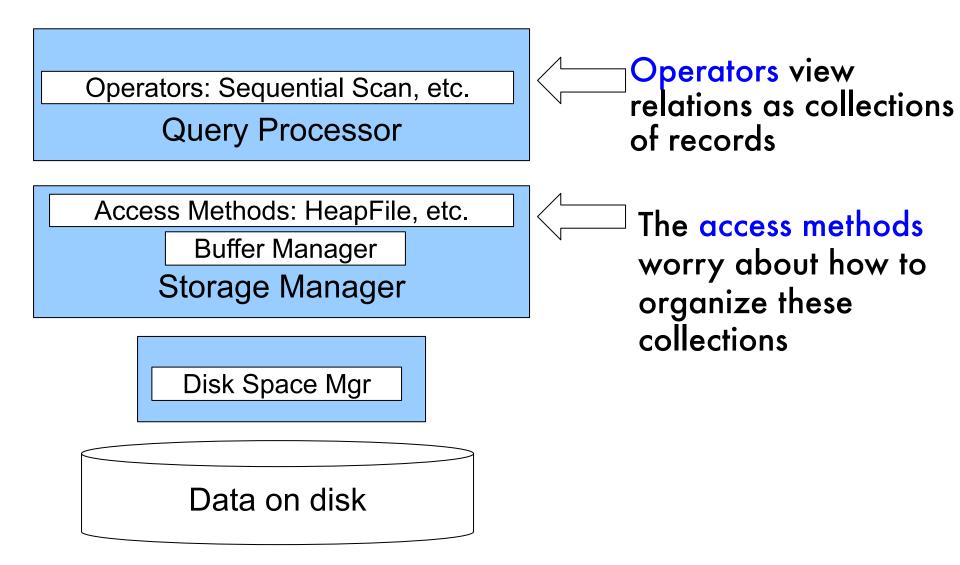
- Free space by shifting records within page
 - Be careful with slots
 - RIDs for remaining tuples must NOT change
- May be able to eliminate an overflow page

- If new record is shorter than previous, easy ☺
- If it is longer, need to shift records
 - May have to create overflow pages

We know how to store tuples in a heap file

How do heap files interact with rest of engine?

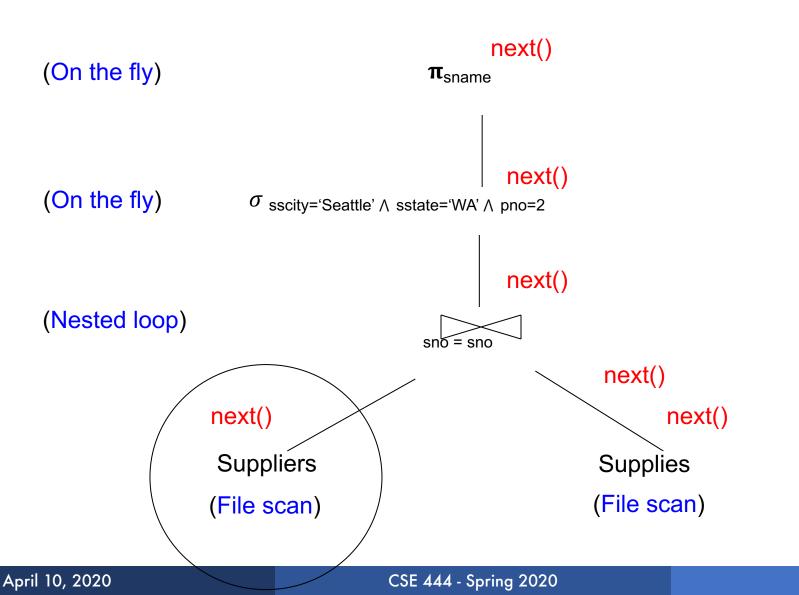
How Components Fit Together



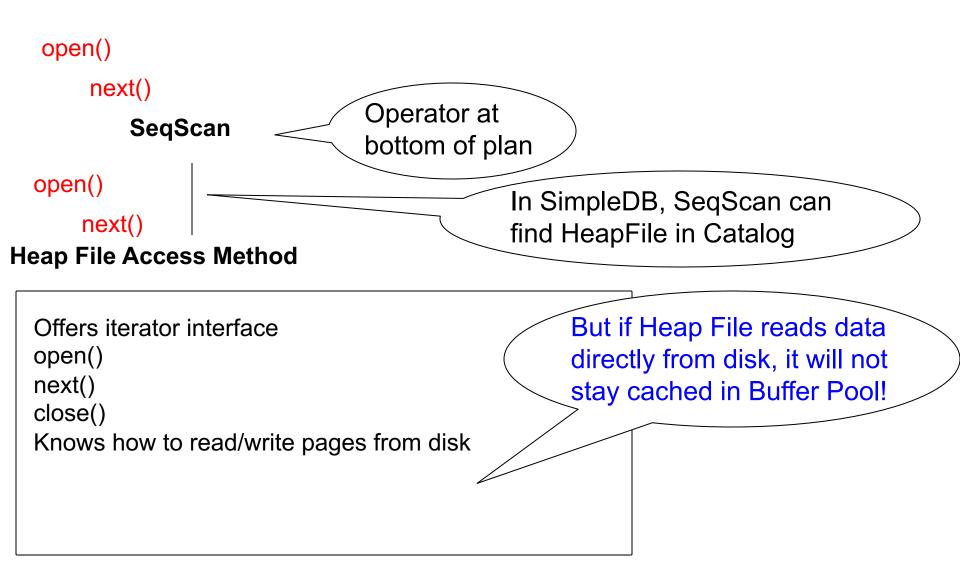
Heap File Access Method API

- Create or destroy a file
- Insert a record
- Delete a record with a given rid (rid)
 - rid: unique tuple identifier
- Get a record with a given rid
 - Not necessary for sequential scan operator
 - But used with indexes
- Scan all records in the file

Query Execution How it all Fits

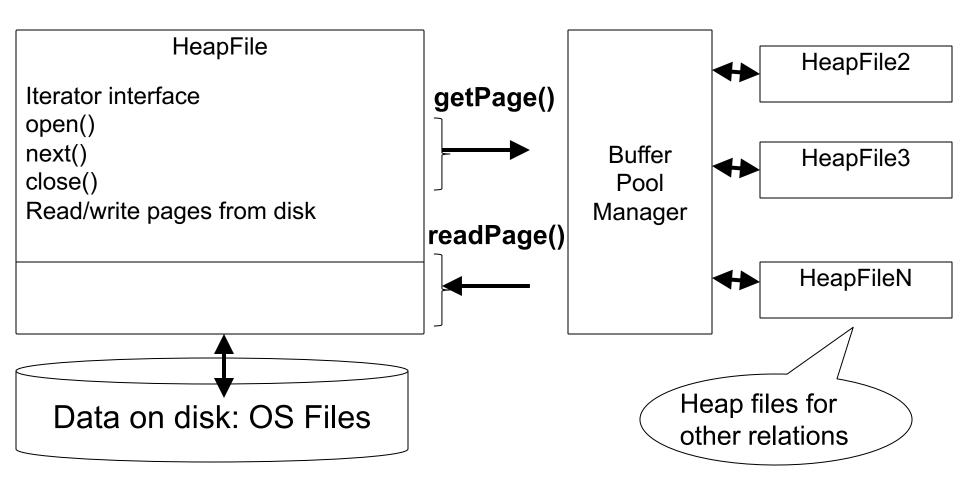


Query Execution In SimpleDB



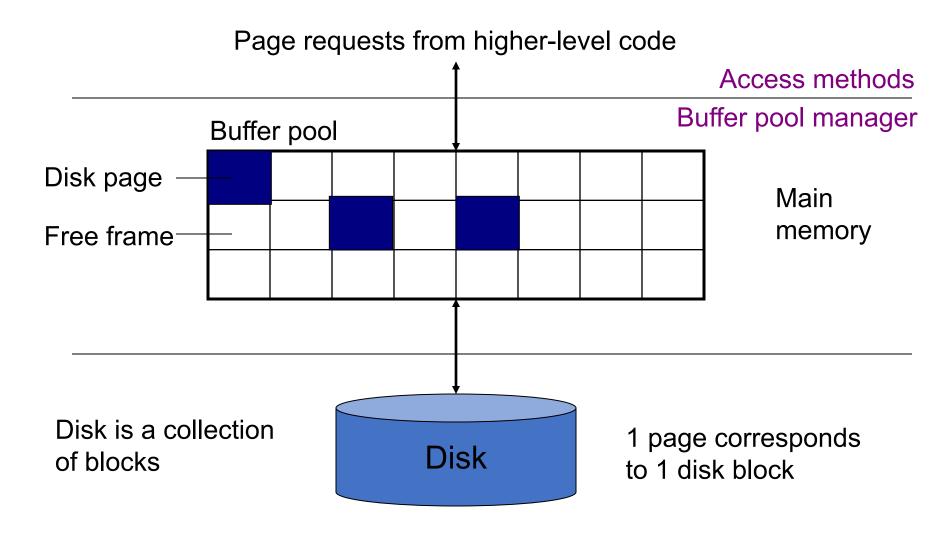
Query Execution In SimpleDB

Everyone shares a single cache



- Brings pages in from memory and caches them
- Eviction policies
 - Random page (ok for SimpleDB)
 - Least-recently used (LRU)
 - The "clock" algorithm
- Keeps track of which pages are dirty
 - A dirty page has changes not reflected on disk
 - Implementation: Each page includes a dirty bit

Buffer Manager



Pushing Updates to Disk

- When inserting a tuple, HeapFile inserts it on a page but does not write the page to disk
- When deleting a tuple, HeapFile deletes tuple from a page but does not write the page to disk
- The buffer manager worries when to write pages to disk (and when to read them from disk)
- When need to add new page to file, HeapFile adds page to file on disk and then reads it through buffer manager

Basic Access Method: Heap File

API

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Basic Access Method: Heap File

API

- Create or destroy a file
- Insert a record
- Delete a record with a given rid (rid)
 rid: unique tuple identifier (more later)
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Scan all records in the file

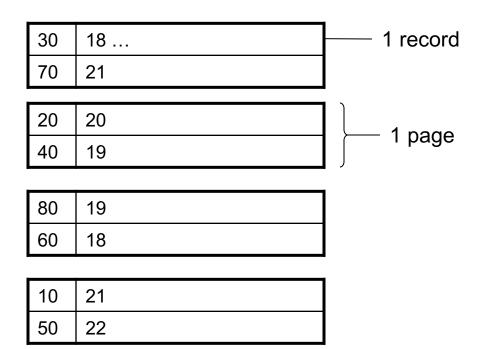
Next: how to scan only <u>some</u> records

Access by Attribute Value

- Scan all Suppliers where city='Seattle'
- Scan all Students with GPA > 3.5
- Scan all Students with SID = 12345 // just one

File is not sorted on any attribute

Student(sid: int, age: int, ...)



Heap File Search Example

- 10,000 students
- 10 student records per page
- Total number of pages: 1,000 pages
- Find student where sid =12345
 - Must read on average 500 pages
- Find all students where age > 20
 Must read all 1,000 pages

Can we do better?

File sorted on an attribute, usually on primary key Student(sid: int, age: int, ...)

10	21
20	20
30	18
40	19

50	22
60	18

70	21
80	19

Total number of pages: 1,000 pages

- Find student where sid=12345
 - How many pages do we need to read?

Total number of pages: 1,000 pages

- Find student where sid=12345
 - How many pages do we need to read?
 - Binary search: read $\log_2(1,000) \approx 10$ pages

Limitations of Sorted Files

We want to support these kinds of queries:

- Find student where sid=12345
- Find students where age > 20
- Insert a new student

What are the limitations of using a sorted file?

CREATE TABLE Student(sid int, age int, gpa real, ...);

select * from Student where sid=12345

CREATE TABLE Student(sid int, age int, gpa real, ...);

CREATE INDEX s_sid ON Student(sid)

select * from Student where sid=12345

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CREATE INDEX s_sid ON Student(sid)

select * from Student where sid=12345

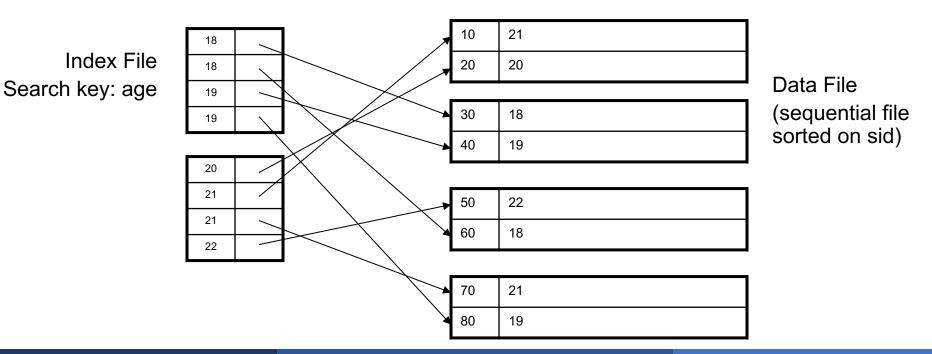
CREATE INDEX s_age ON Student(age)

select * from Student where age > 25

Outline

- Index structures
 Hash-based indexes
- B+ trees } Next time

- Index: separate file with fast access by "key" value
- Contains pairs of the form (key, RID)
- Indexes are access methods! Same API as Heap Files



- Search key = can attribute or set of attributes
 - not the same as the primary key; not a key
- Index = collection of data entries
- Data entry for key k can be:
 - (k, RID)
 - (k, list-of-RIDs)
 - Record with key k; "clustered" or "primary" index

Fix one relation, say STUDENT

- The STUDENT file can be:
 - Heap file (tuples stored without any order)
 - Sequential file (tuples sorted on some attribute(s))
 - Clustered (primary) index file (relation+index)
- There can be several unclustered (secondary) index files that store (key,rid) pairs

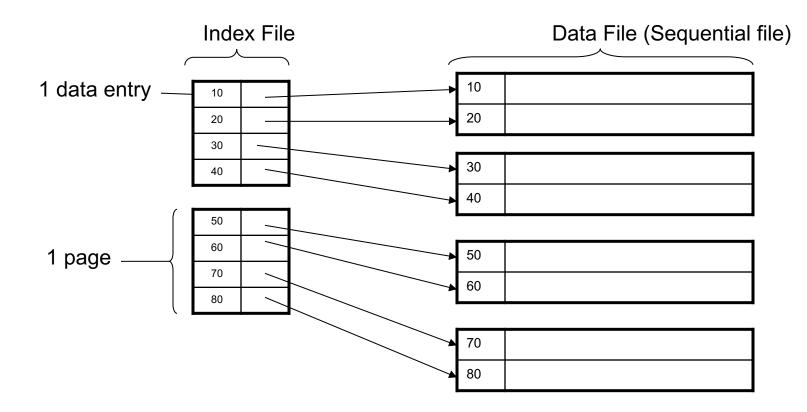
How Indexes Help

We want to support these kinds of queries Assume Student = a heap file

- Find student where sid=12345
 - Use an index on Student(sid)
- Find students where age > 20
 - Use an index on Student(age)
- Insert a new student
 - Insert in the Student heap file easy
 - Insert in indexes Student(sid), Student(age) will discuss

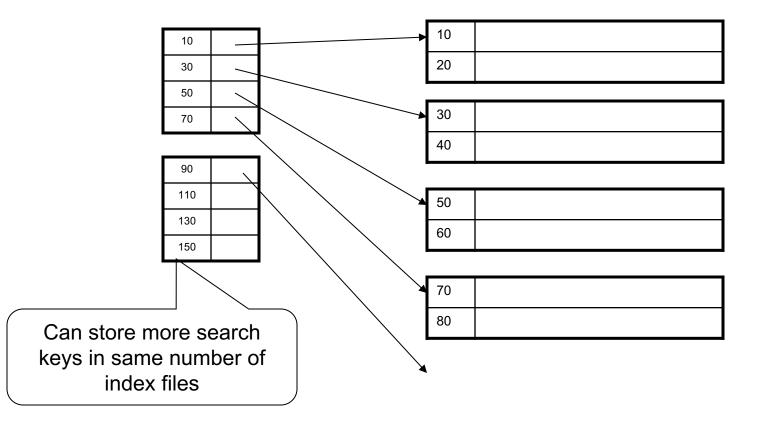
Clustered Index (aka Primary Index)

- Records in data file have same order as in index
- <u>Dense</u> index: sequence of (key,rid) pairs



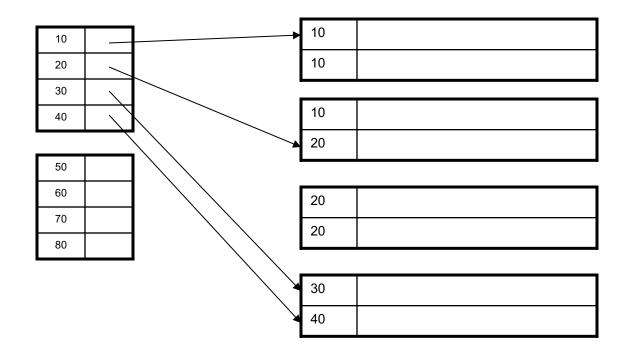
Clustered Index (aka Primary Index)

- Records in data file have same order as in index
- Sparse index: store a subset of (key,rid) pairs



Clustered Index with Duplicate Keys

Dense index:

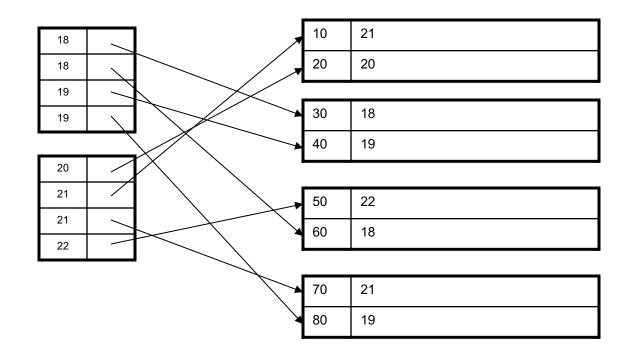


Clustered Index: Back to Example

- Assume entire index fits in main memory
- Find student where sid=12345
 - Index (dense or sparse) points directly to the page
 - Read only 1 page from disk
- Find all students where age > 20
 - Add a second index...

Secondary Indexes

- Do not determine placement of records in data files
- Always dense (why ?)



The Confusing Terminology of Indexes...

Clustered index:

- Means: keys close in the index are also close in the data
- Can co-exists with the data file (quite common)
- Can have only one clustered index (obviously!!)
- Sometimes called "primary index"

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 - Can have as many unclustered indexes as we want
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- Unclustered index:
 - Means: order in the index and order in the data differ
 - Always a separate file
 - Can have as many unclustered indexes as we want
 - Sometimes called "secondary index"
- Some people use <u>different convetion</u>:
 - Primary index = index on the primary key
 - Secondary index = everything else

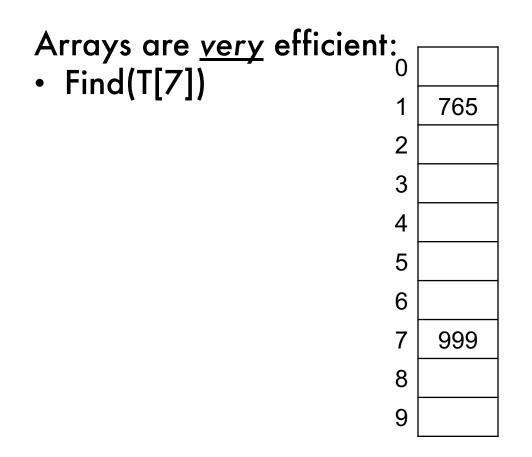
- The index is a collection of (key, RID(s)) pairs
- Needs to support efficiently:
 - Find the entry where key=[some value]
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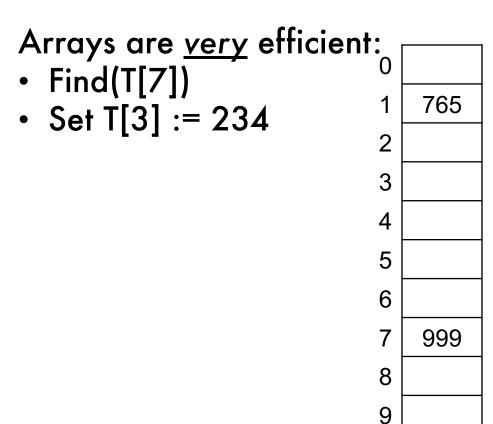
• How would you design the index data structure?

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- How would you design the index data structure?
 - Ordered file problem here (why?)

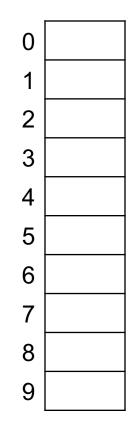
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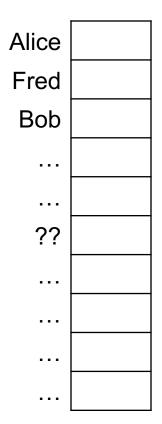
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 - B+ tree

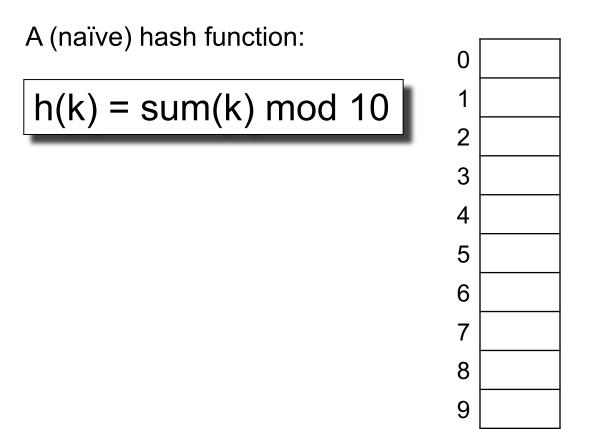


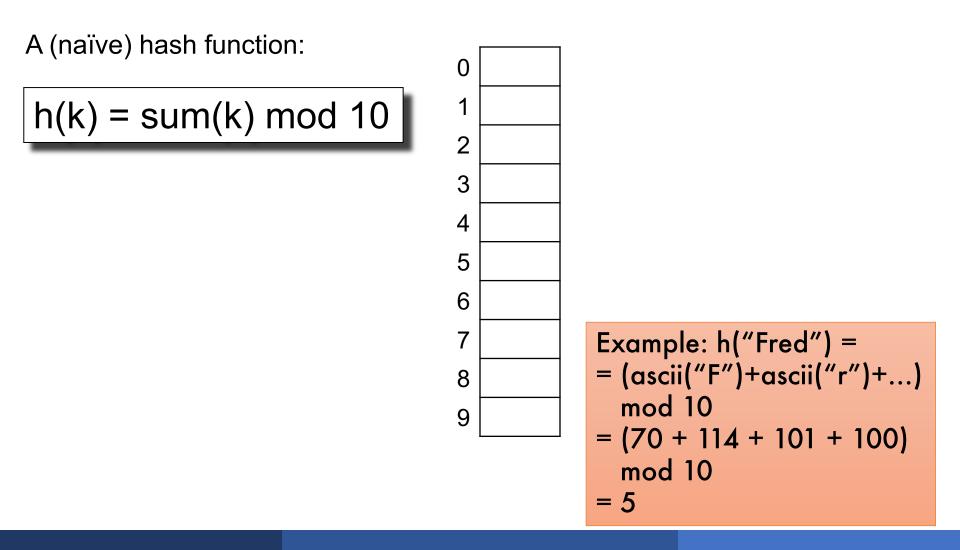


Arrays are <u>very</u> efficient: • Find(T[7]) • Set T[3] := 234







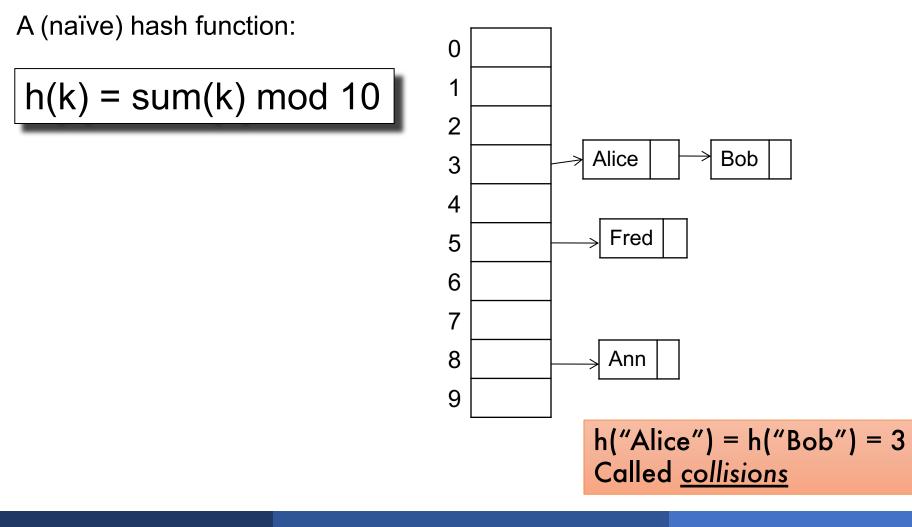


Problem: the key is not 0,1,2,...9 but is a string k

Separate chaining:

A (naïve) hash function: 0 1 h(k) = sum(k) mod 10 2 3 4 Fred 5 6 7 Example: h("Fred") = = (ascii("F")+ascii("r")+...) 8 mod 10 9 =(70 + 114 + 101 + 100)mod 10 = 5

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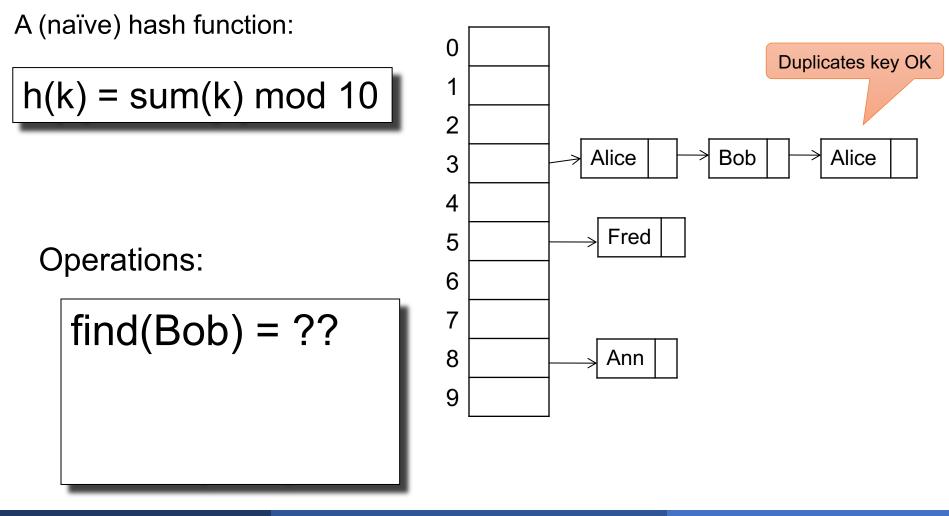


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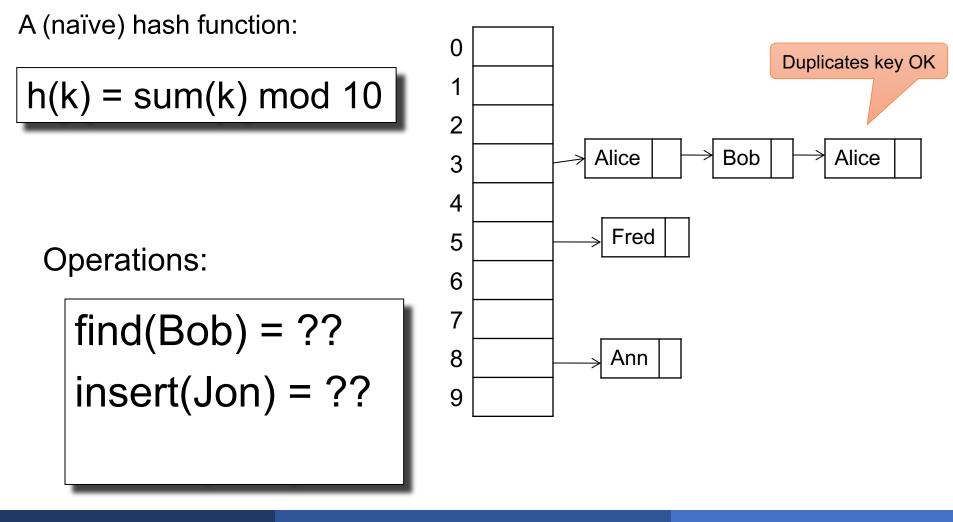
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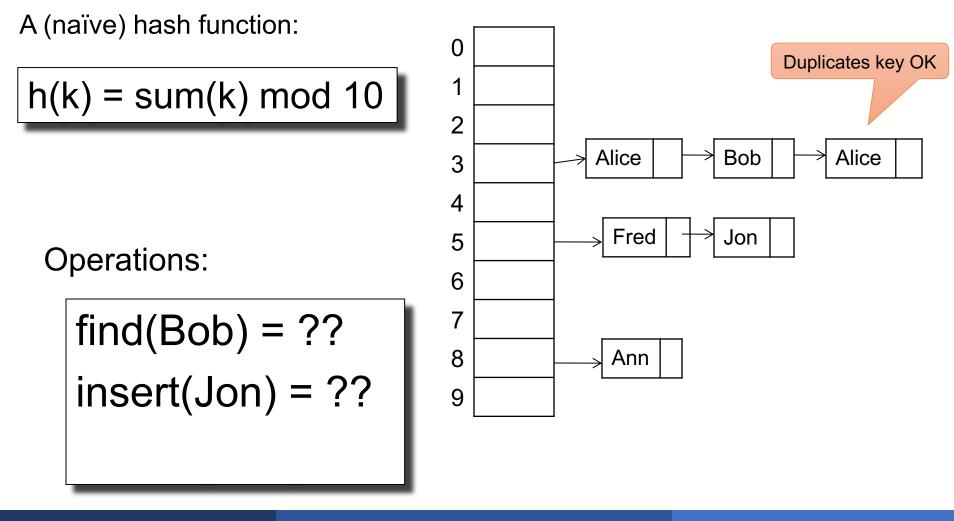
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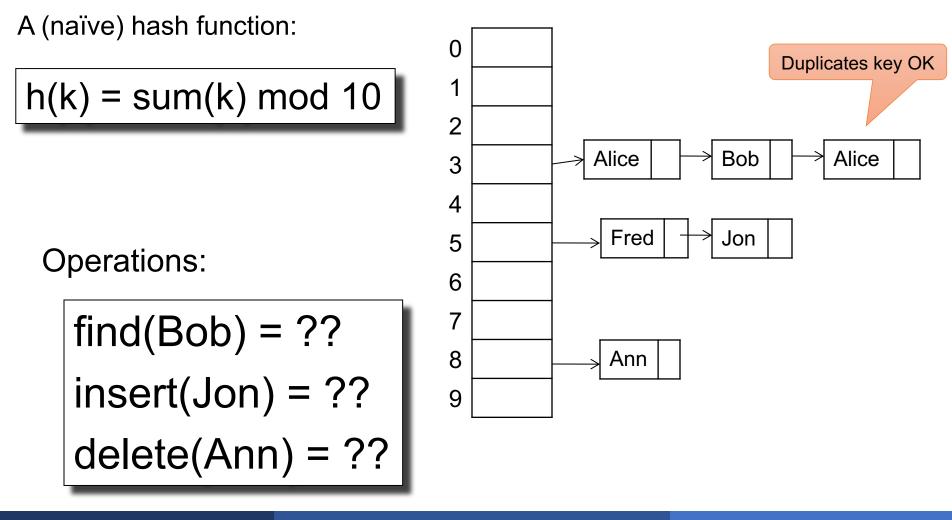
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- insert(k, v) = inserts a key k with value v
 - Duplicate k's may be OK or may not be OK
- find(k) = returns the value v associated to k, or the <u>list</u> of all values associated to k
- delete(k)

Discussion of Hash Tables

Hash function:

- Should distribute values uniformly
- Never write your own! (why is x mod 10 bad?)
 Use a standard library function
- Best: concatenate with fixed, random seed (in class)

Hash table:

- Size of table: large enough to avoid collisions
- Typically: size of table ≈ size of data
- Why not make it small? Why not make it big?
- Problem: hash table allocated statically, at creation
- Book describes solutions to increase size dynamically

Hash-Based Index

Good for point queries but not range queries

10	21
20	20

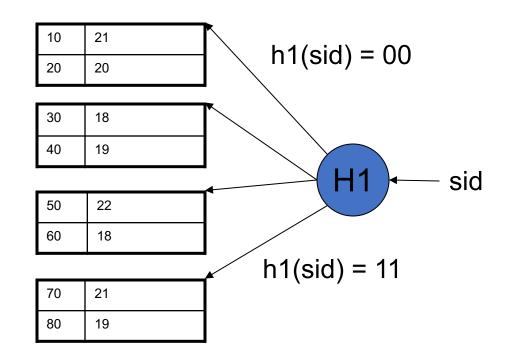
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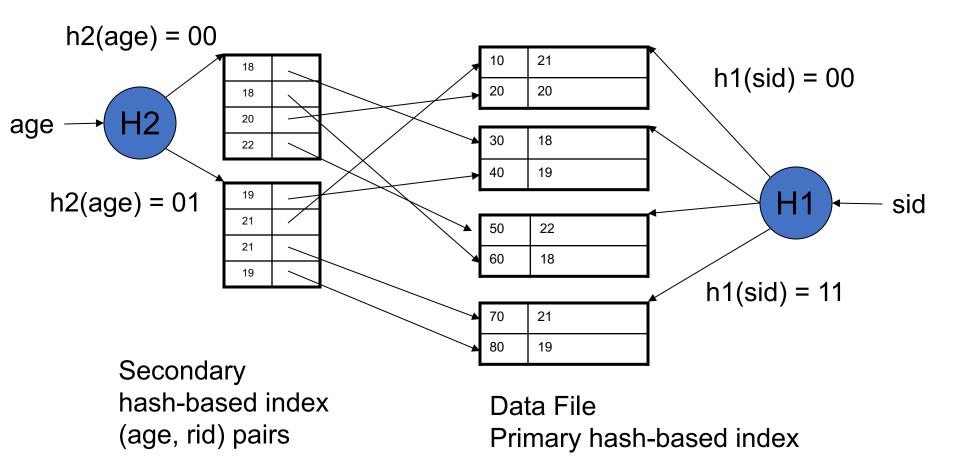
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Data File

Good for point queries but not range queries



Data File Primary hash-based index Good for point queries but not range queries



Search trees (quick review in class)

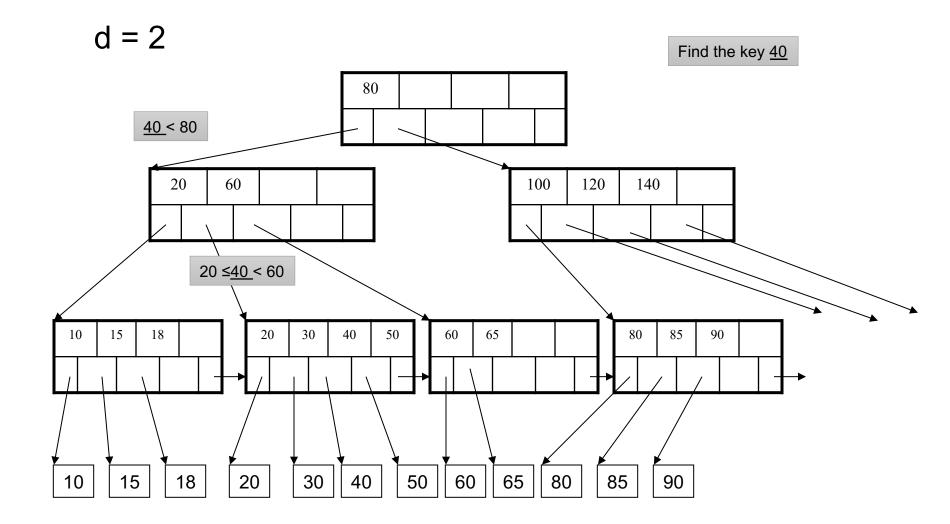
Idea in B Trees

Make 1 node = 1 page (= 1 block)

Idea in B+ Trees

- Keys are stored on the leaves (not internal nodes)
- Leaves are linked in a list, for range queries

B+ Tree Example

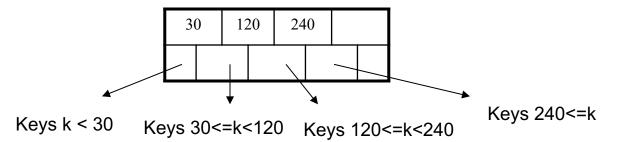


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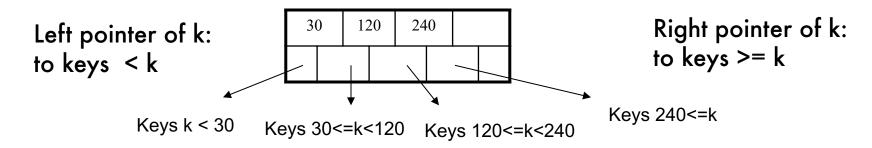
- For each node except the root, maintain 50% occupancy of keys
- Insert and delete must rebalance to maintain constraints

- Parameter d = the <u>degree</u>
- Each node has d <= m <= 2d keys (except root)</p>

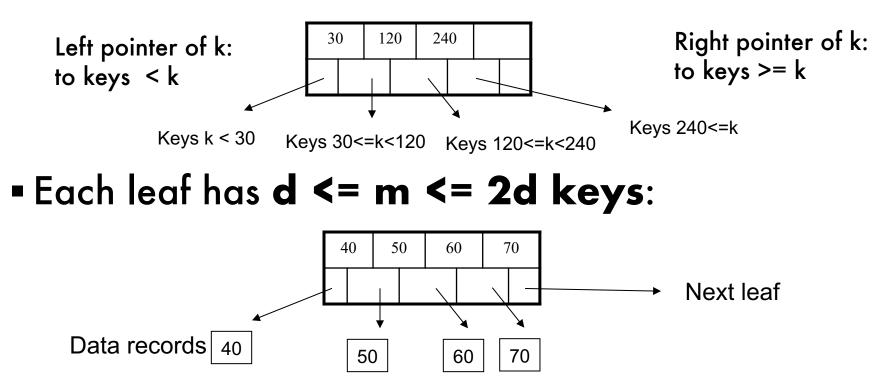
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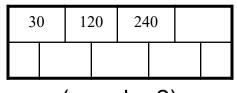


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B+ Tree Design

- How large d ? Make one node fit on one block
- Example:
 - Key size = 4 bytes
 - Pointer size = 8 bytes
 - Block size = 4096 bytes



(e.g. d = 2)

2d x 4 + (2d+1) x 8 <= 4096</p>

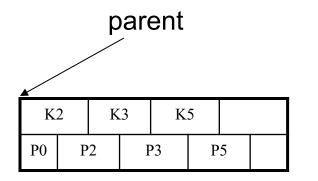
• d = 170

- Typical order: 100. Typical fill-factor: 67%.
 - average fanout = 133
- Typical capacities
 - Height 4: 133⁴ = 312,900,700 records
 - Height 3: 133³ = 2,352,637 records
- Can often hold top levels in buffer pool
 - Level 1 = 1 page = 8 Kbytes
 - Level 2 = 133 pages = 1 Mbyte
 - Level 3 = 17,689 pages = 133 Mbytes

Insert (K, P)

- Find leaf where K belongs, insert
- If no overflow (2d keys or less), halt

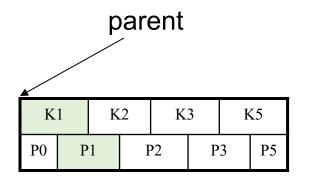




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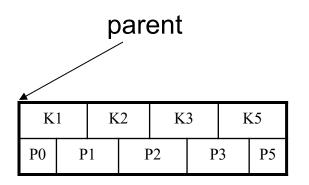
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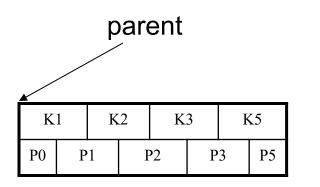


Insert k4

Insert (K, P)

- Find leaf where K belongs, insert
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- If overflow (2d+1 keys), split node, insert in parent:

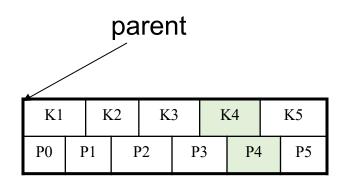
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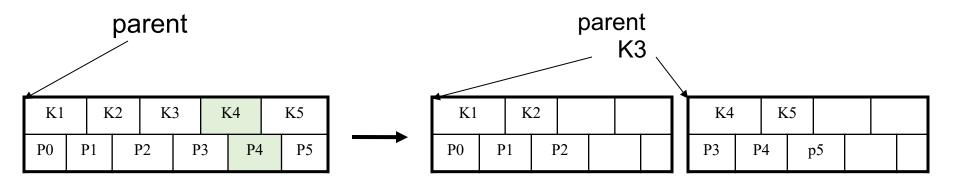
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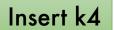
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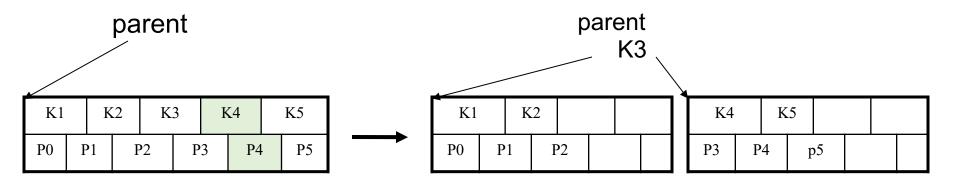




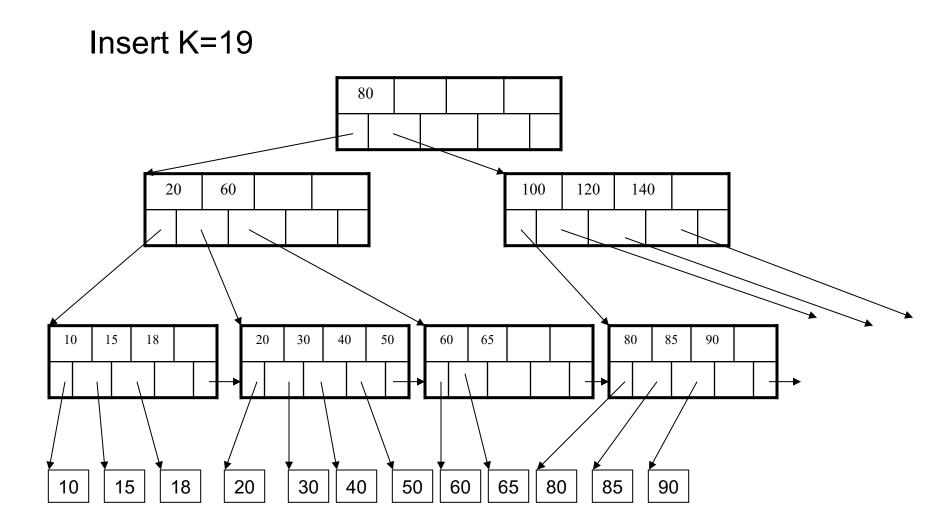
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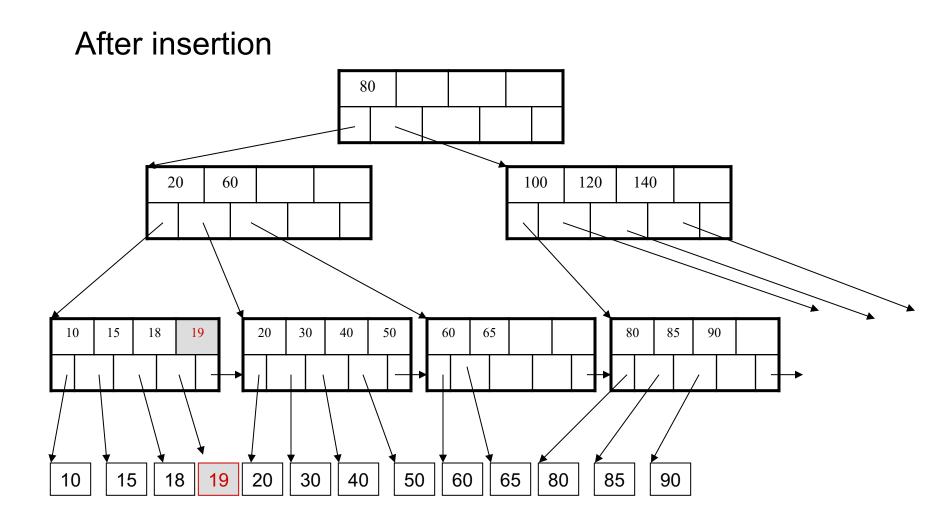
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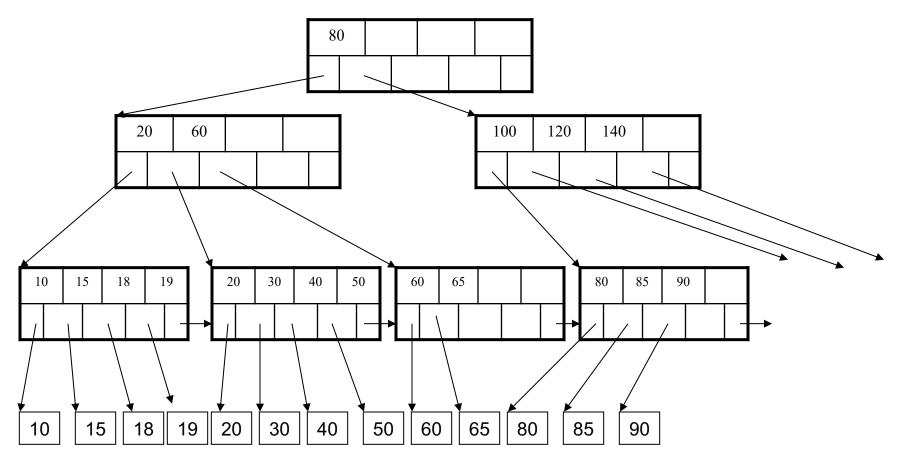


- If leaf, also keep K3 in right node
- When root splits, new root has 1 key only

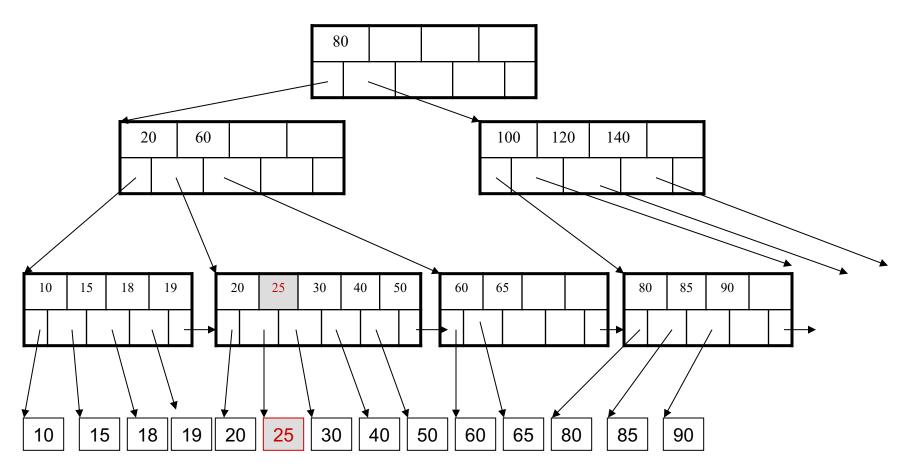




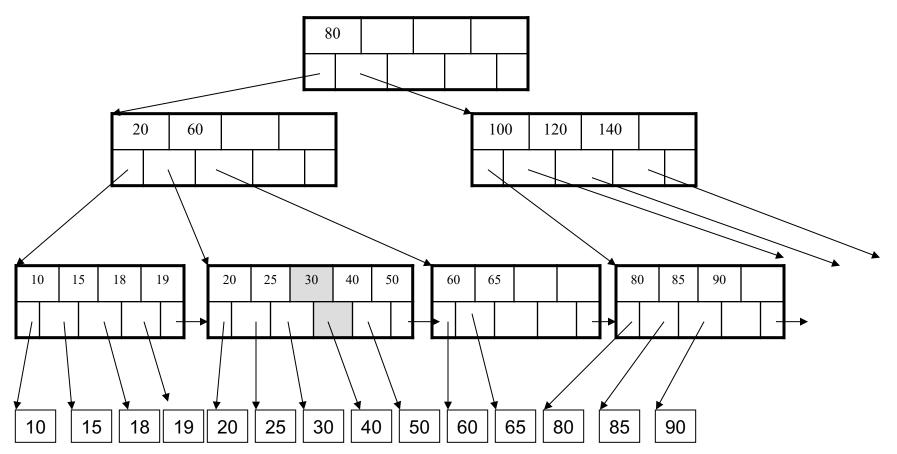
Now insert 25



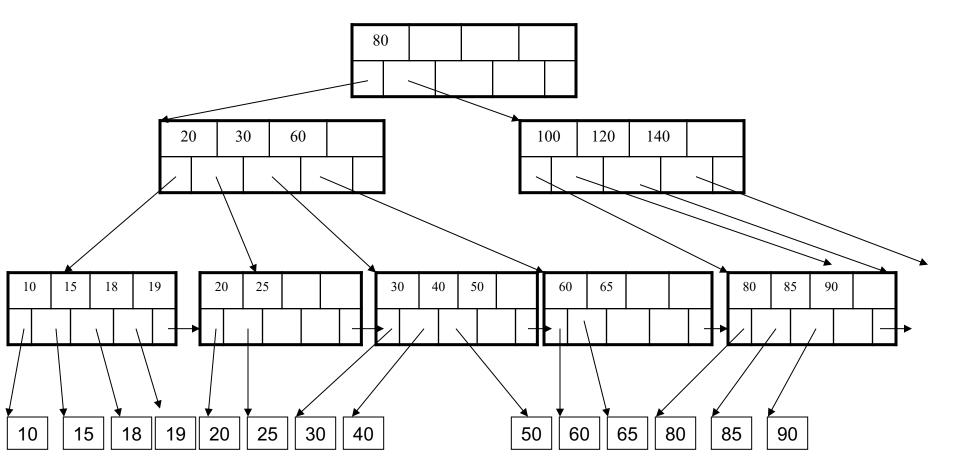
After insertion



But now have to split !

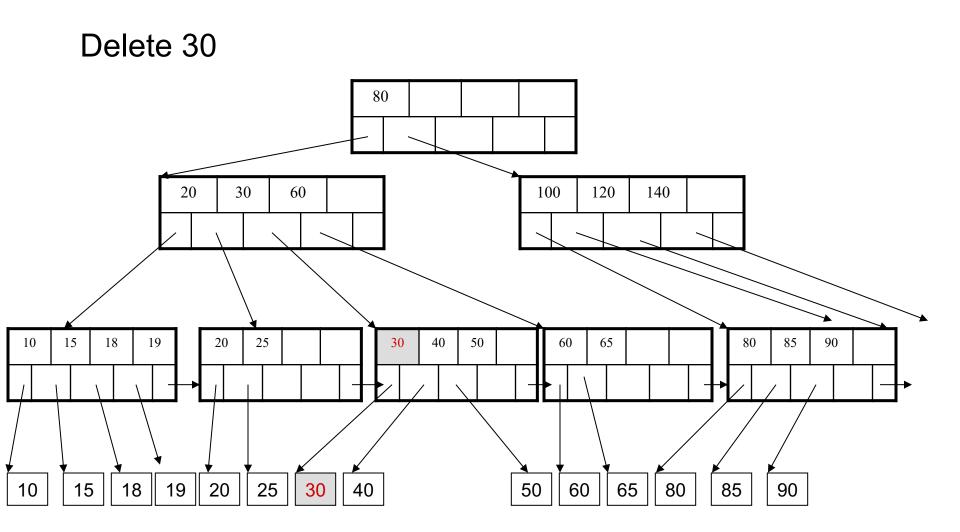


After the split

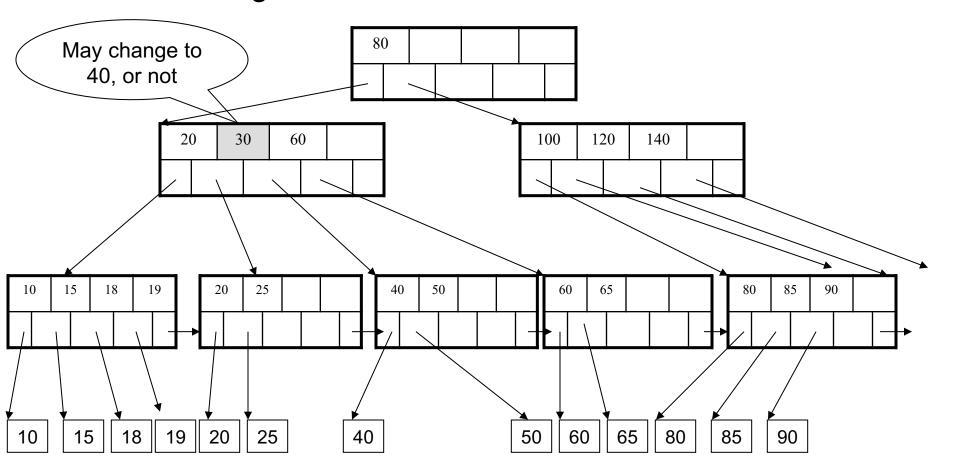


Delete (K, P)

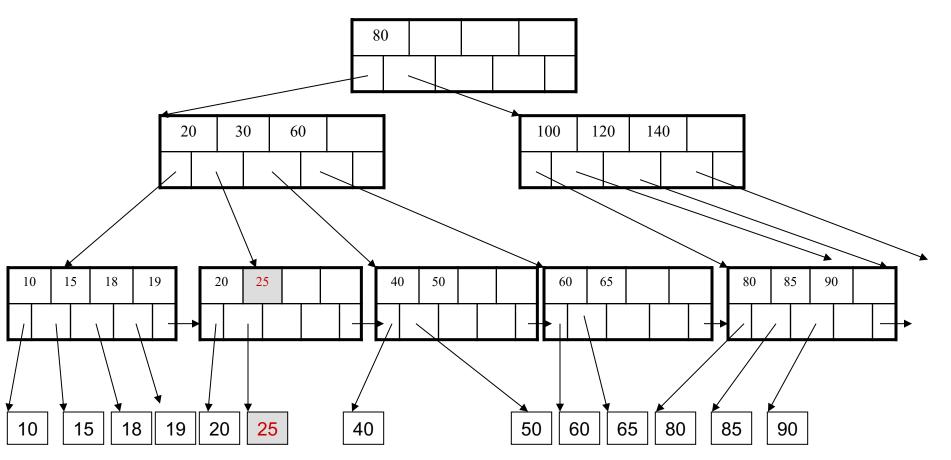
- Find leaf where K belongs, delete
- Check for capacity
- If leaf below capacity, search adjacent nodes (left first, then right) for extra tuples and rotate them to new leaf
- If adjacent nodes 50% full, merge with on adjacent node This removes a key/child from parent; repeat algorithm on parent node

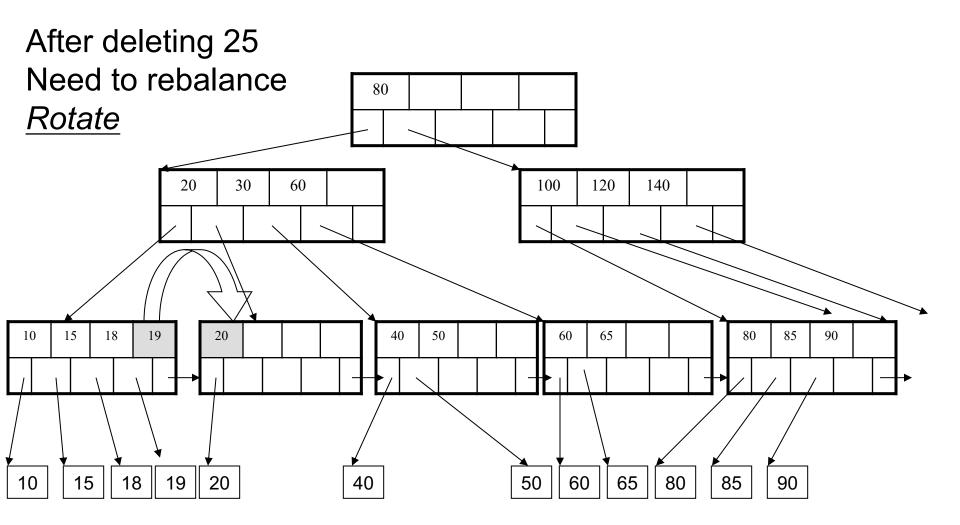


After deleting 30

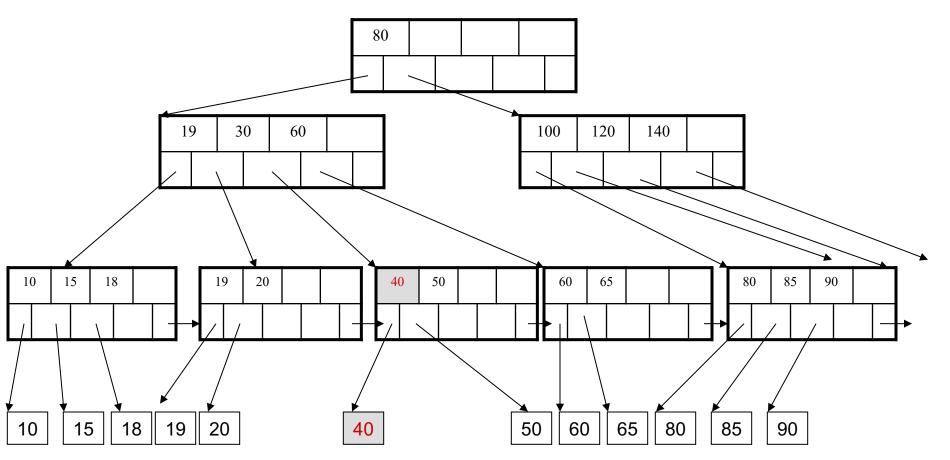


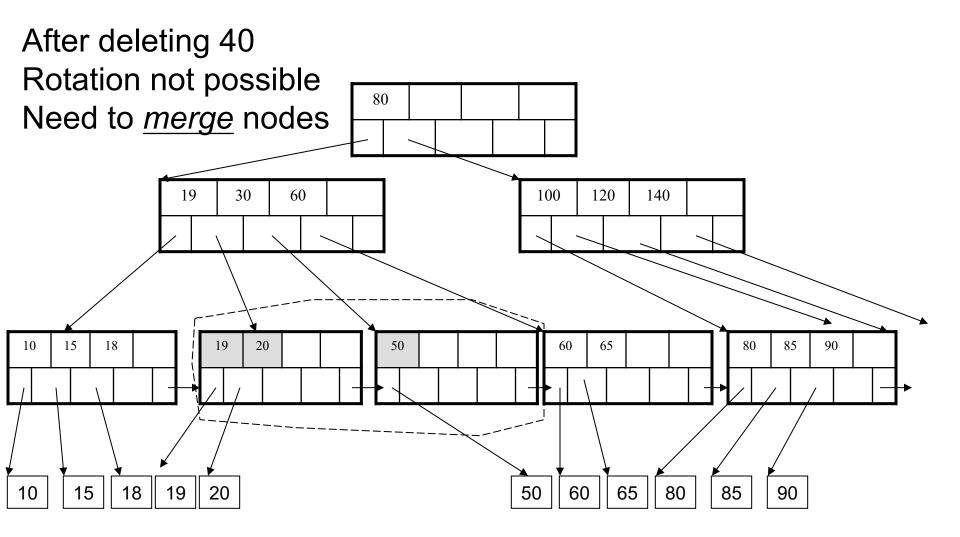
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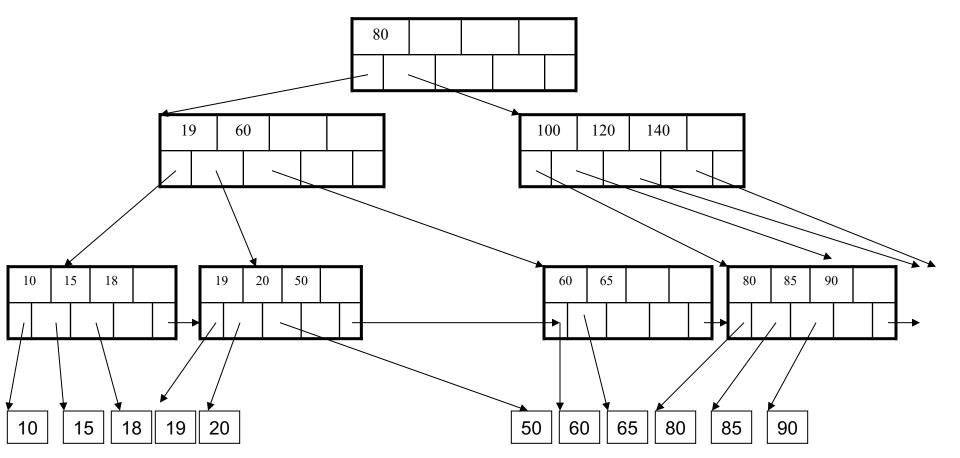


Now delete 40

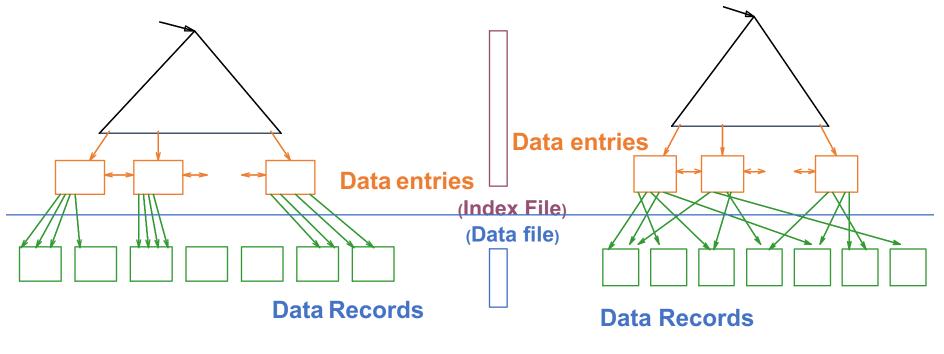




Final tree



Clustered v.s. Unclustered B+ Trees



CLUSTERED

UNCLUSTERED

Note: can also store data records directly as data entries

Searching a B+ Tree

- Exact key values:
 - Start at the root
 - Proceed down, to the leaf
- Range queries:
 - Find lowest bound as above
 - Then sequential traversal
- Less effective for multi-range
 - Can only use one B+ tree, ignore the other(s)
 - Called access path selection

Select name From Student Where age = 25

Select name From Student Where 20 <= age and age <= 30

Select name From Student Where age = 25 and GPA = 3.5

- Default index structure on most DBMSs
- Many improvements/optimizations
 - Prefix compression: "Johannes", "John", "Johnson", "Jon",... store only suffices, to save space
 - Allow fill capacity to decrease slightly below 50% to avoid cascading splits and merges
 - Optimizations for transactions: tree-locking protocol instead of Strict 2PL
- For multi-dimensional queries, need R-trees:
 - E.g. age = 25 and GPA > 3.5
 - R-trees are more difficult to search and rebalance