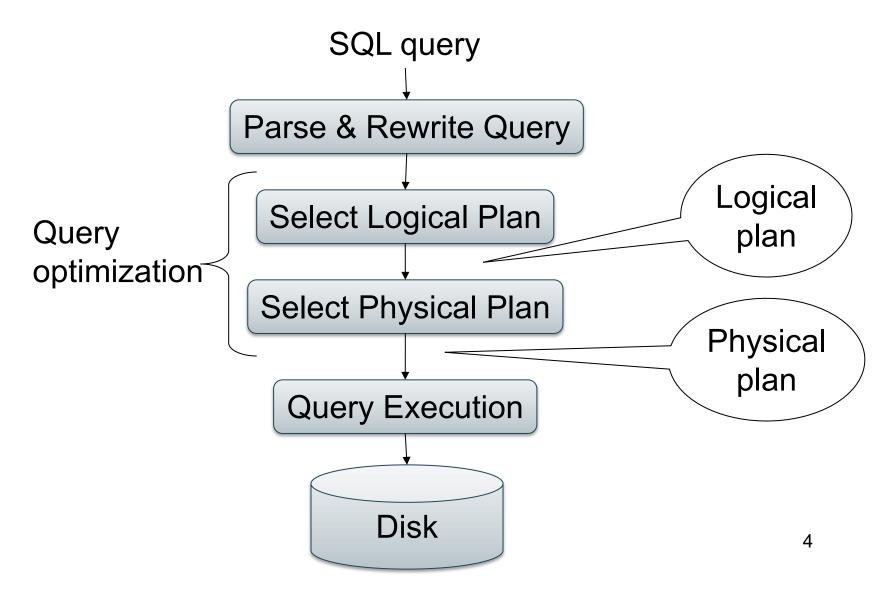
#### CSE 444: Database Internals

#### Lecture 10 Query Optimization (part 1)

Know how to compute the cost of a plan Next: Find a good plan automatically?

This is the role of the query optimizer

#### **Query Optimization Overview**



#### What We Already Know...

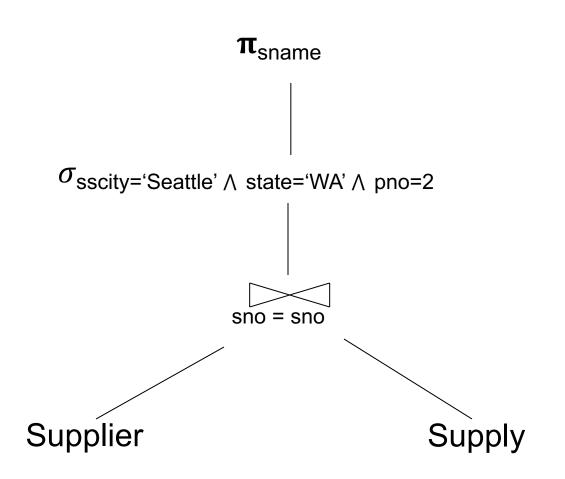
```
Supplier(sno,sname,scity,sstate)
Part(pno,pname,psize,pcolor)
Supply(sno,pno,price)
```

For each SQL query....

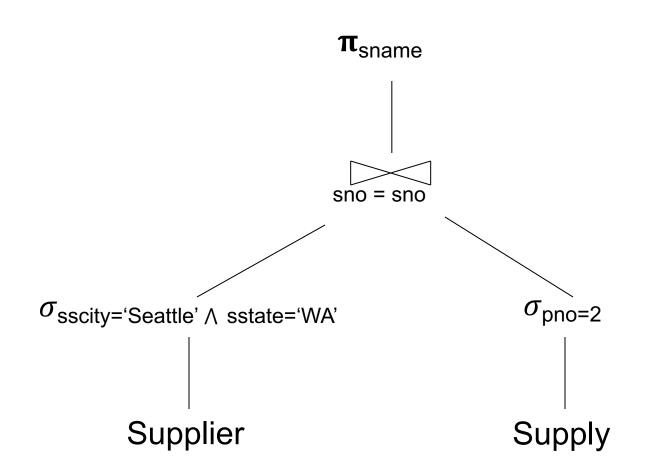
```
SELECT S.sname
FROM Supplier S, Supply U
WHERE S.scity='Seattle' AND S.sstate='WA'
AND S.sno = U.sno
AND U.pno = 2
```

There exist many logical query plan...

### Example Query: Logical Plan 1



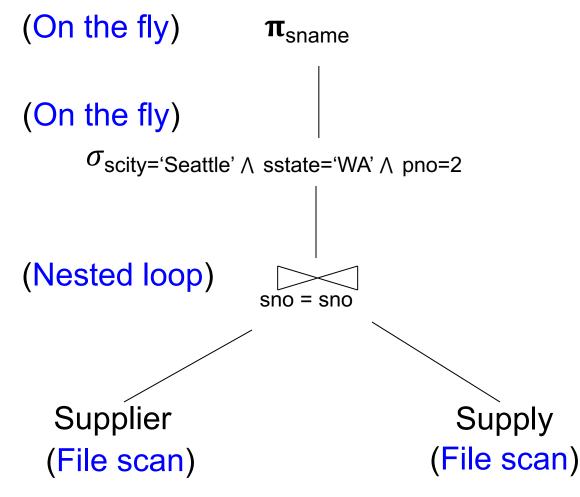
## Example Query: Logical Plan 2



### What We Also Know

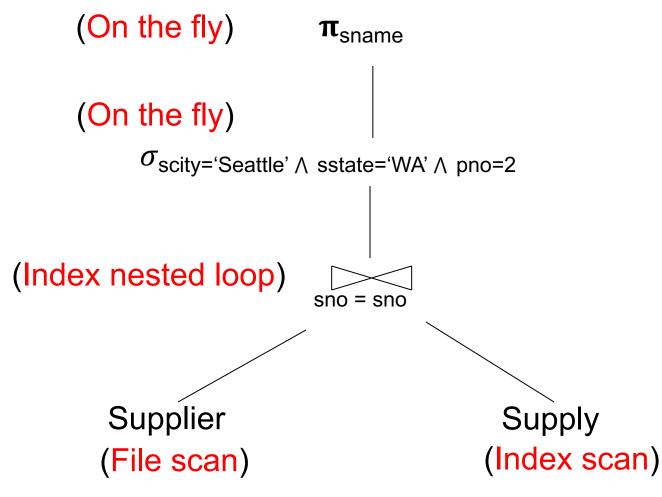
- For each logical plan...
- There exist many physical plans

### **Example Query: Physical Plan 1**



CSE 444 - Winter 2019

### Example Query: Physical Plan 2



CSE 444 - Winter 2019

# Query Optimizer Overview

- Input: A logical query plan
- Output: A good physical query plan
- Basic query optimization algorithm
  - Enumerate alternative plans (logical and physical)
  - Compute estimated cost of each plan
    - Compute number of I/Os
    - Optionally take into account other resources
  - Choose plan with lowest cost
  - This is called cost-based optimization

#### Lessons

- No magic "best" plan: depends on the data
- In order to make the right choice
  - Need to have *statistics* over the data
  - The B's, the T's, the V's
  - Commonly: histograms over base data
    - In SimpleDB as well... see lab 5.

#### Outline

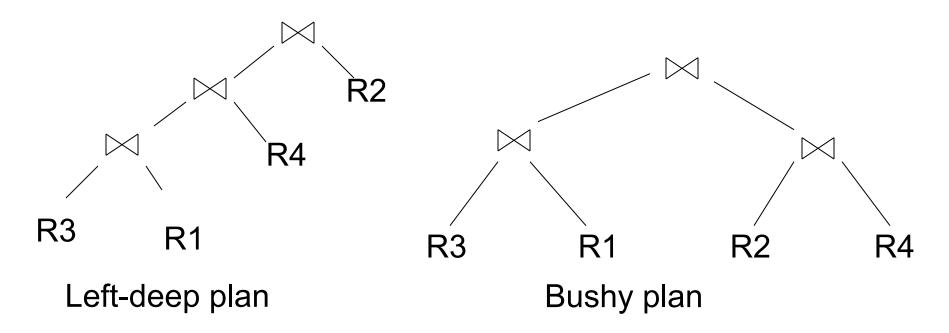
- Search space
- Algorithm for enumerating query plans

### **Relational Algebra Equivalences**

#### Selections

- Commutative:  $\sigma_{c1}(\sigma_{c2}(R))$  same as  $\sigma_{c2}(\sigma_{c1}(R))$
- Cascading:  $\sigma_{c1\wedge c2}(R)$  same as  $\sigma_{c2}(\sigma_{c1}(R))$
- Projections
  - Cascading
- Joins
  - Commutative :  $R \bowtie S$  same as  $S \bowtie R$
  - Associative:  $R \bowtie (S \bowtie T)$  same as  $(R \bowtie S) \bowtie T$

### Left-Deep Plans, Bushy Plans, and Linear Plans



Linear plan: One input to each join is a relation from disk Can be either left or right input

# Commutativity, Associativity, Distributivity

# $R \cup S = S \cup R, R \cup (S \cup T) = (R \cup S) \cup T$ $R \bowtie S = S \bowtie R, R \bowtie (S \bowtie T) = (R \bowtie S) \bowtie T$

## $R \bowtie (S \cup T) = (R \bowtie S) \cup (R \bowtie T)$

#### Laws Involving Selection

$$\sigma_{C \text{ AND } C'}(R) = \sigma_{C}(\sigma_{C'}(R)) = \sigma_{C}(R) \cap \sigma_{C'}(R)$$
  

$$\sigma_{C \text{ OR } C'}(R) = \sigma_{C}(R) \cup \sigma_{C'}(R)$$
  

$$\sigma_{C}(R \bowtie S) = \sigma_{C}(R) \bowtie S$$

$$\sigma_{C}(R - S) = \sigma_{C}(R) - S$$
  

$$\sigma_{C}(R \cup S) = \sigma_{C}(R) \cup \sigma_{C}(S)$$
  

$$\sigma_{C}(R \bowtie S) = \sigma_{C}(R) \bowtie S$$
  
Assuming C on  
attributes of R

# Example: Simple Algebraic Laws

• Example: R(A, B, C, D), S(E, F, G)  $\sigma_{F=3} (R \bowtie_{D=E} S) = ?$  $\sigma_{A=5 \text{ AND } G=9} (R \bowtie_{D=E} S) = ?$ 

# Example: Simple Algebraic Laws

• Example: R(A, B, C, D), S(E, F, G)  $\sigma_{F=3} (R \bowtie_{D=E} S) = R \bowtie_{D=E} \sigma_{F=3} (S)$   $\sigma_{A=5 \text{ AND } G=9} (R \bowtie_{D=E} S) = \sigma_{A=5} (R) \bowtie_{D=E} \sigma_{G=9} (S)$ 

### Laws Involving Projections

$$\begin{split} \Pi_{M}(\mathsf{R}\bowtie\mathsf{S}) &= \Pi_{M}(\Pi_{\mathsf{P}}(\mathsf{R})\bowtie\Pi_{\mathsf{Q}}(\mathsf{S})) \\ \Pi_{M}(\Pi_{\mathsf{N}}(\mathsf{R})) &= \Pi_{M}(\mathsf{R}) \\ & /^{*} \text{ note that } \mathsf{M} \subseteq \mathsf{N} \ ^{*}/ \end{split}$$

• Example R(A,B,C,D), S(E, F, G)  $\Pi_{A,B,G}(R \bowtie_{D=E} S) = \Pi_{?}(\Pi_{?}(R) \bowtie_{D=E} \Pi_{?}(S))$ 

### Laws Involving Projections

$$\begin{split} \Pi_{M}(\mathsf{R}\bowtie\mathsf{S}) &= \Pi_{M}(\Pi_{\mathsf{P}}(\mathsf{R})\bowtie\Pi_{\mathsf{Q}}(\mathsf{S})) \\ \Pi_{M}(\Pi_{\mathsf{N}}(\mathsf{R})) &= \Pi_{M}(\mathsf{R}) \\ & /^{*} \text{ note that } \mathsf{M} \subseteq \mathsf{N} \ ^{*}/ \end{split}$$

• Example R(A,B,C,D), S(E, F, G)  $\Pi_{A,B,G}(R \bowtie_{D=E} S) = \Pi_{A,B,G}(\Pi_{A,B,D}(R) \bowtie_{D=E} \Pi_{E,G}(S))$ 

# Laws involving grouping and aggregation

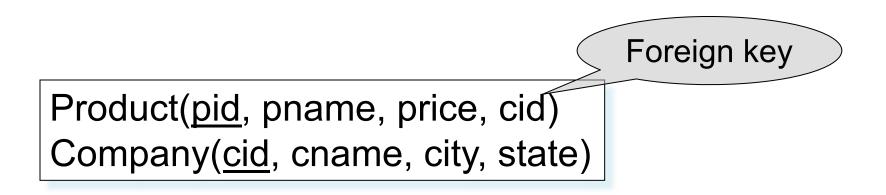
 $\begin{array}{l} \gamma_{A, \operatorname{agg}(D)}(\mathsf{R}(A,B) \bowtie_{\mathsf{B}=\mathsf{C}} \mathsf{S}(\mathsf{C},\mathsf{D})) = \\ \gamma_{A, \operatorname{agg}(D)}(\mathsf{R}(A,B) \bowtie_{\mathsf{B}=\mathsf{C}} (\gamma_{\mathsf{C}, \operatorname{agg}(D)} \mathsf{S}(\mathsf{C},\mathsf{D}))) \end{array}$ 

# Laws involving grouping and aggregation

$$\begin{split} &\delta(\gamma_{A, agg(B)}(\mathsf{R})) = \gamma_{A, agg(B)}(\mathsf{R}) \\ &\gamma_{A, agg(B)}(\delta(\mathsf{R})) = \gamma_{A, agg(B)}(\mathsf{R}) \\ & \text{ if agg is "duplicate insensitive "} \end{split}$$

Which of the following are "duplicate insensitive"? sum, count, avg, min, max

#### Laws Involving Constraints



#### $\Pi_{pid, price}$ (Product $\bowtie_{cid=cid}$ Company) = $\Pi_{pid, price}$ (Product)

### Search Space Challenges

#### • Search space is huge!

- Many possible equivalent trees
- Many implementations for each operator
- Many access paths for each relation
  - File scan or index + matching selection condition
- Cannot consider ALL plans
   Heuristics: only partial plans with "low" cost

#### Outline

- Search space
- Algorithm for enumerating query plans

# Key Decisions

Logical plan

- What logical plans do we consider (left-deep, bushy?); Search Space
- Which algebraic laws do we apply, and in which context(s)?; Optimization rules
- In what order do we explore the search space?; *Optimization algorithm*

# **Key Decisions**

Physical plan

- What physical operators to use?
- What access paths to use (file scan or index)?
- Pipeline or materialize intermediate results?

These decisions also affect the search space

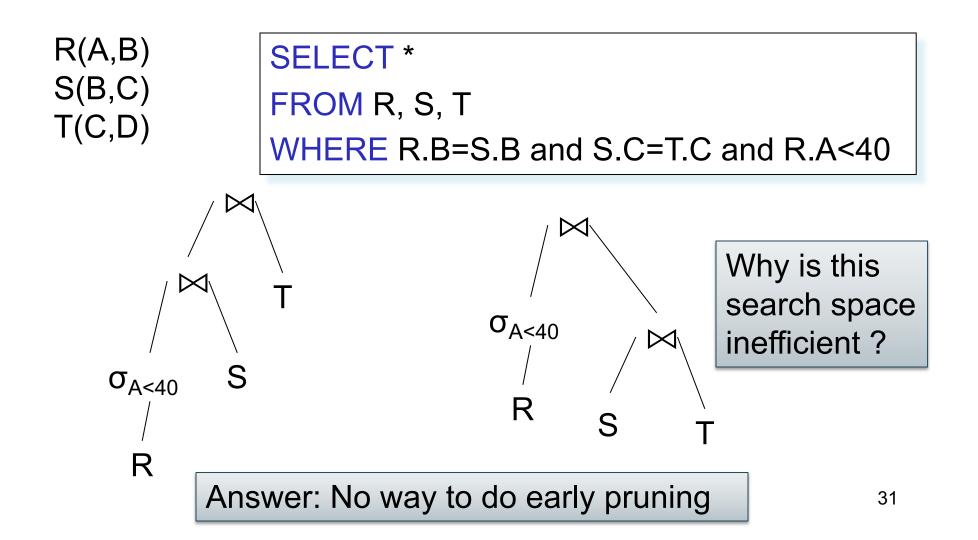
# Two Types of Optimizers

- Heuristic-based optimizers:
  - Apply greedily rules that always improve plan
    - Typically: push selections down
  - Very limited: no longer used today
- Cost-based optimizers:
  - Use a cost model to estimate the cost of each plan
  - Select the "cheapest" plan
  - We focus on cost-based optimizers

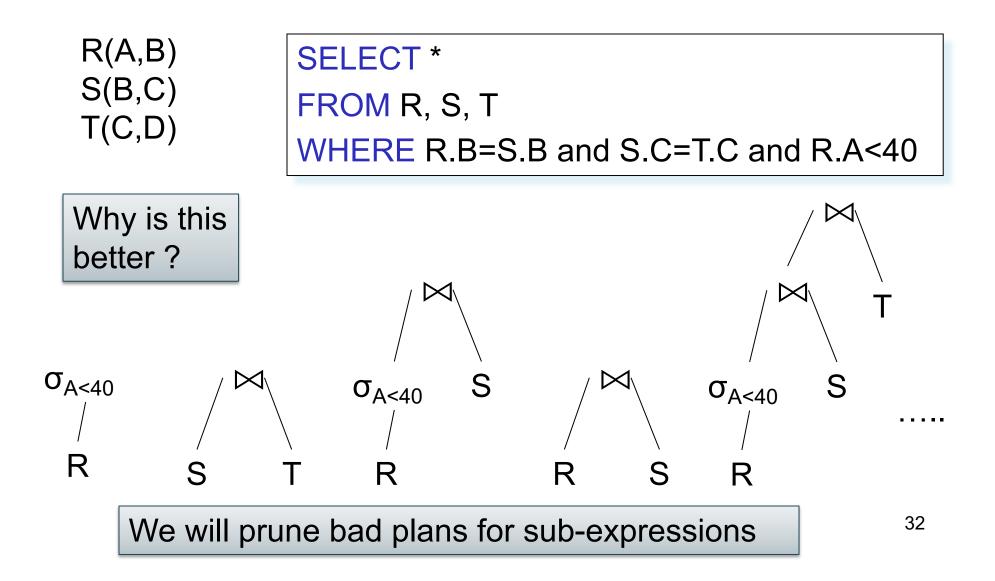
## Three Approaches to Search Space Enumeration

- Complete plans
- Bottom-up plans
- Top-down plans

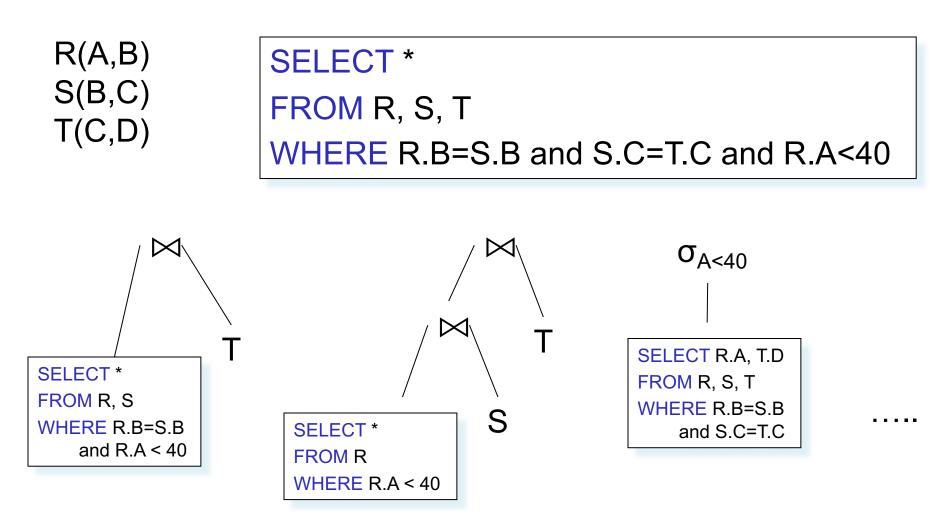
#### **Complete Plans**



#### **Bottom-up Partial Plans**



#### **Top-down Partial Plans**



# Two Types of Plan Enumeration Algorithms

- Dynamic programming (in class)
  - Based on System R (aka Selinger) style optimizer[1979]
  - Limited to joins: join reordering algorithm
  - Bottom-up
- Rule-based algorithm (will not discuss)
  - Database of rules (=algebraic laws)
  - Usually: dynamic programming
  - Usually: top-down