CSE 444: Database Internals

Lecture 10 Query Optimization (part 1)

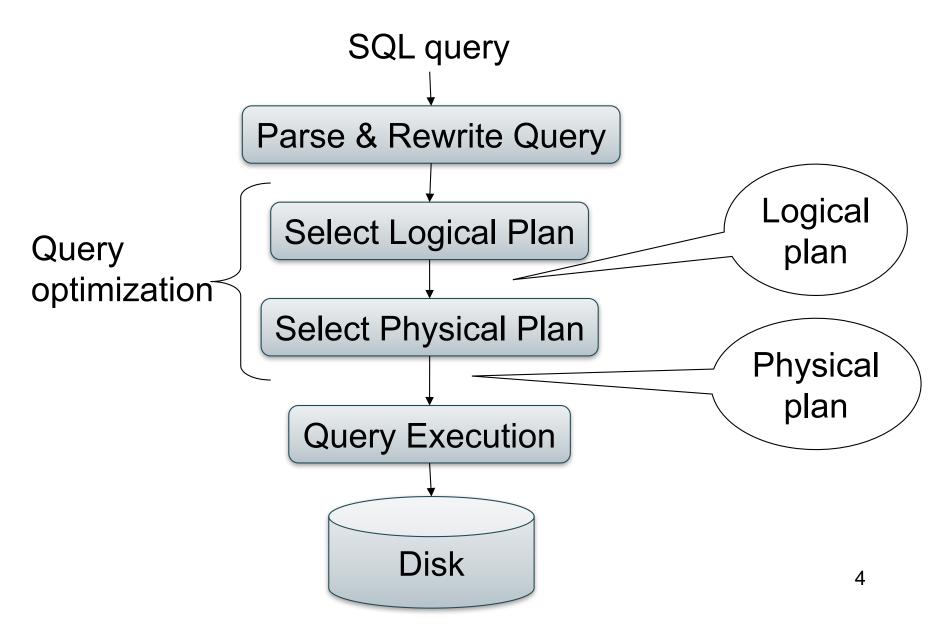
Reminders

- HW2 is due tonight
- 5th year master's reading is due tonight

Know how to compute the cost of a plan Next: Find a good plan automatically?

This is the role of the query optimizer

Query Optimization Overview



What We Already Know...

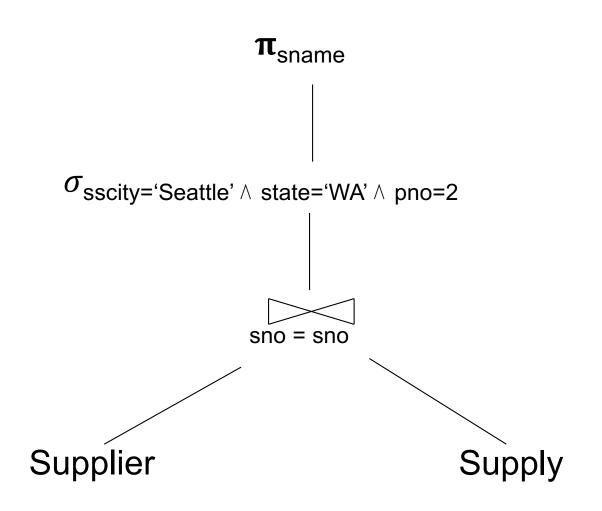
Supplier(sno,sname,scity,sstate)
Part(pno,pname,psize,pcolor)
Supply(sno,pno,price)

For each SQL query....

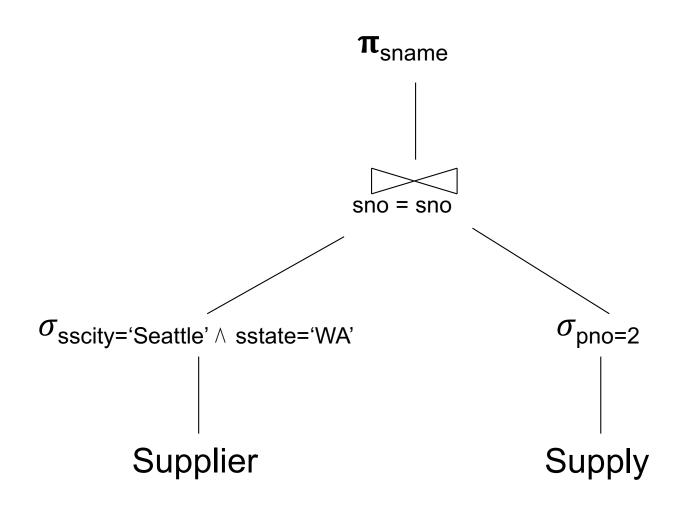
```
SELECT S.sname
FROM Supplier S, Supply U
WHERE S.scity='Seattle' AND S.sstate='WA'
AND S.sno = U.sno
AND U.pno = 2
```

There exist many logical query plan...

Example Query: Logical Plan 1



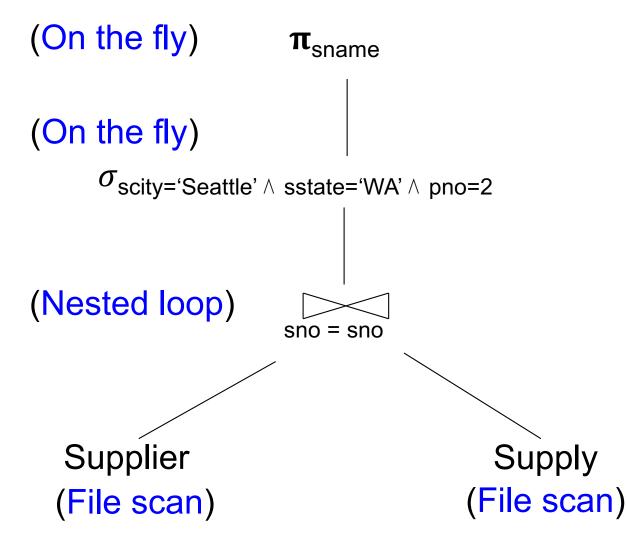
Example Query: Logical Plan 2



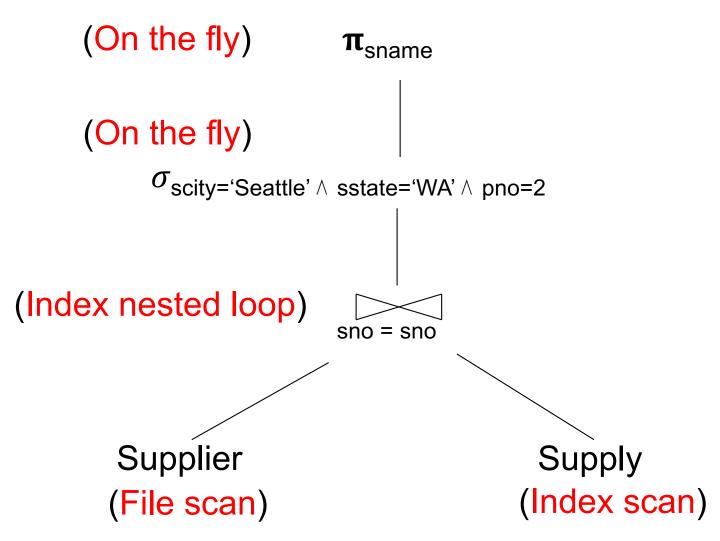
What We Also Know

- For each logical plan...
- There exist many physical plans

Example Query: Physical Plan 1



Example Query: Physical Plan 2



Query Optimizer Overview

- Input: A logical query plan
- Output: A good physical query plan
- Basic query optimization algorithm
 - Enumerate alternative plans (logical and physical)
 - Compute estimated cost of each plan
 - Compute number of I/Os
 - Optionally take into account other resources
 - Choose plan with lowest cost
 - This is called cost-based optimization

Lessons

- No magic "best" plan: depends on the data
- In order to make the right choice
 - Need to have <u>statistics</u> over the data
 - The B's, the T's, the V's
 - Commonly: histograms over base data
 - In SimpleDB as well... see lab 5.

Outline

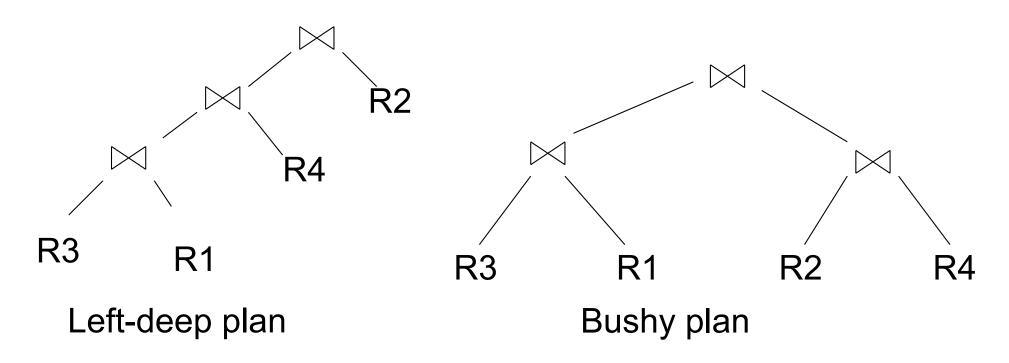
- Search space
- Algorithm for enumerating query plans

Relational Algebra Equivalences

• Selections

- Commutative: $\sigma_{c1}(\sigma_{c2}(R))$ same as $\sigma_{c2}(\sigma_{c1}(R))$
- Cascading: $\sigma_{c1\land c2}(R)$ same as $\sigma_{c2}(\sigma_{c1}(R))$
- Projections
 - Cascading
- Joins
 - Commutative : $R \bowtie S$ same as $S \bowtie R$
 - Associative: $R \bowtie (S \bowtie T)$ same as $(R \bowtie S) \bowtie T$

Left-Deep Plans, Bushy Plans, and Linear Plans



Linear plan: One input to each join is a relation from disk Can be either left or right input

Commutativity, Associativity, Distributivity

$R \cup S = S \cup R, R \cup (S \cup T) = (R \cup S) \cup T$ $R \bowtie S = S \bowtie R, R \bowtie (S \bowtie T) = (R \bowtie S) \bowtie T$

$\mathsf{R}\bowtie(\mathsf{S}\,\cup\,\mathsf{T})\,=\,(\mathsf{R}\bowtie\mathsf{S})\,\cup\,(\mathsf{R}\bowtie\mathsf{T})$

Laws Involving Selection

$$\sigma_{C \text{ AND } C'}(R) = \sigma_{C}(\sigma_{C'}(R)) = \sigma_{C}(R) \cap \sigma_{C'}(R)$$

$$\sigma_{C \text{ OR } C'}(R) = \sigma_{C}(R) \cup \sigma_{C'}(R)$$

$$\sigma_{C}(R \bowtie S) = \sigma_{C}(R) \bowtie S$$

$$\sigma_{C}(R - S) = \sigma_{C}(R) - S$$

$$\sigma_{C}(R \cup S) = \sigma_{C}(R) \cup \sigma_{C}(S)$$

$$\sigma_{C}(R \bowtie S) = \sigma_{C}(R) \bowtie S$$

Assuming C on
attributes of R

Example: Simple Algebraic Laws

• Example: R(A, B, C, D), S(E, F, G) $\sigma_{F=3}(R \bowtie_{D=E} S) = ?$ $\sigma_{A=5 \text{ AND } G=9}(R \bowtie_{D=E} S) = ?$

Example: Simple Algebraic Laws

• Example: R(A, B, C, D), S(E, F, G) $\sigma_{F=3}(R \bowtie_{D=E} S) = R \bowtie_{D=E} \sigma_{F=3}(S)$ $\sigma_{A=5 \text{ AND } G=9}(R \bowtie_{D=E} S) = \sigma_{A=5}(R) \bowtie_{D=E} \sigma_{G=9}(S)$

Laws Involving Projections

$$\begin{split} \Pi_{M}(\mathsf{R}\bowtie\mathsf{S}) &= \Pi_{M}(\Pi_{\mathsf{P}}(\mathsf{R})\bowtie\Pi_{\mathsf{Q}}(\mathsf{S})) \\ \Pi_{M}(\Pi_{\mathsf{N}}(\mathsf{R})) &= \Pi_{\mathsf{M}}(\mathsf{R}) \\ & /^{*} \text{ note that } \mathsf{M} \subseteq \mathsf{N} \ */ \end{split}$$

• Example R(A,B,C,D), S(E, F, G) $\Pi_{A,B,G}(R \bowtie_{D=E} S) = \Pi_{?}(\Pi_{?}(R) \bowtie_{D=E} \Pi_{?}(S))$

Laws Involving Projections

$$\begin{split} \Pi_{M}(\mathsf{R}\bowtie\mathsf{S}) &= \Pi_{M}(\Pi_{\mathsf{P}}(\mathsf{R})\bowtie\Pi_{\mathsf{Q}}(\mathsf{S})) \\ \Pi_{M}(\Pi_{\mathsf{N}}(\mathsf{R})) &= \Pi_{\mathsf{M}}(\mathsf{R}) \\ & /^{*} \text{ note that } \mathsf{M} \subseteq \mathsf{N} \ ^{*}/ \end{split}$$

• Example R(A,B,C,D), S(E, F, G) $\Pi_{A,B,G}(R \bowtie_{D=E} S) = \Pi_{A,B,G}(\Pi_{A,B,D}(R) \bowtie_{D=E} \Pi_{E,G}(S))$

Laws involving grouping and aggregation

$\begin{array}{l} \gamma_{A, \text{ agg}(D)}(\mathsf{R}(A,B) \bowtie_{\mathsf{B}=\mathsf{C}} \mathsf{S}(\mathsf{C},\mathsf{D})) = \\ \gamma_{A, \text{ agg}(D)}(\mathsf{R}(A,B) \bowtie_{\mathsf{B}=\mathsf{C}} (\gamma_{\mathsf{C}, \text{ agg}(D)} \mathsf{S}(\mathsf{C},\mathsf{D}))) \end{array}$

Laws involving grouping and aggregation

$$\begin{split} &\delta(\gamma_{A, \text{ agg}(B)}(\mathsf{R})) = \gamma_{A, \text{ agg}(B)}(\mathsf{R}) \\ &\gamma_{A, \text{ agg}(B)}(\delta(\mathsf{R})) = \gamma_{A, \text{ agg}(B)}(\mathsf{R}) \\ & \text{ if agg is "duplicate insensitive "} \end{split}$$

Which of the following are "duplicate insensitive"? sum, count, avg, min, max

Laws Involving Constraints Foreign key

Product(<u>pid</u>, pname, price, cid) Company(<u>cid</u>, cname, city, state)

$\Pi_{\text{pid, price}}(\text{Product} \Join_{\text{cid=cid}} \text{Company}) = \Pi_{\text{pid, price}}(\text{Product})$

Search Space Challenges

• Search space is huge!

- Many possible equivalent trees
- Many implementations for each operator
- Many access paths for each relation
 - File scan or index + matching selection condition
- Cannot consider ALL plans

- Heuristics: only partial plans with "low" cost

Outline

- Search space
- Algorithm for enumerating query plans

Key Decisions

Logical plan

- What logical plans do we consider (left-deep, bushy?); Search Space
- Which algebraic laws do we apply, and in which context(s)?; Optimization rules
- In what order do we explore the search space?;
 Optimization algorithm

Key Decisions

Physical plan

- What physical operators to use?
- What access paths to use (file scan or index)?
- Pipeline or materialize intermediate results?

These decisions also affect the search space

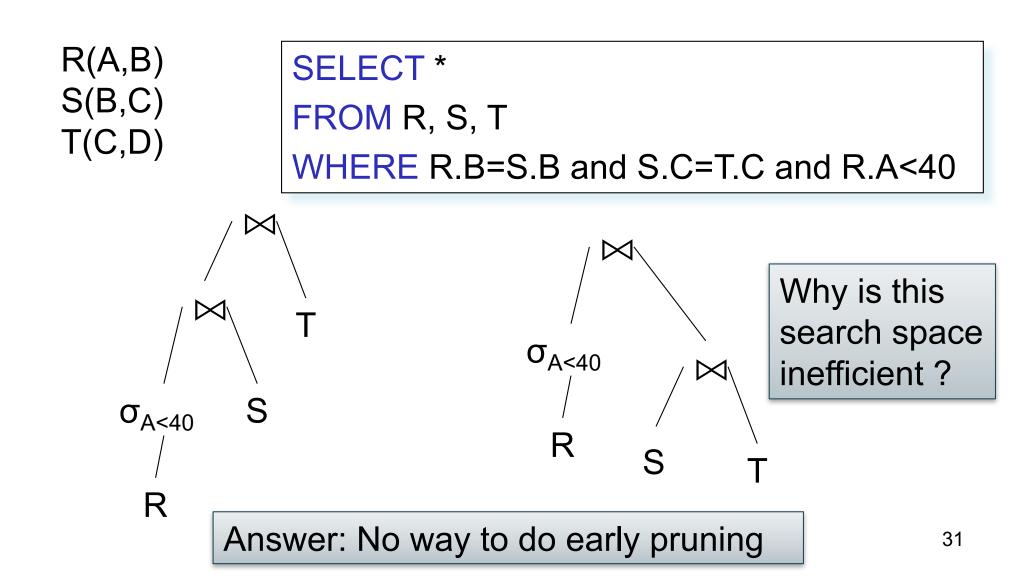
Two Types of Optimizers

- Heuristic-based optimizers:
 - Apply greedily rules that always improve plan
 - Typically: push selections down
 - Very limited: no longer used today
- Cost-based optimizers:
 - Use a cost model to estimate the cost of each plan
 - Select the "cheapest" plan
 - We focus on cost-based optimizers

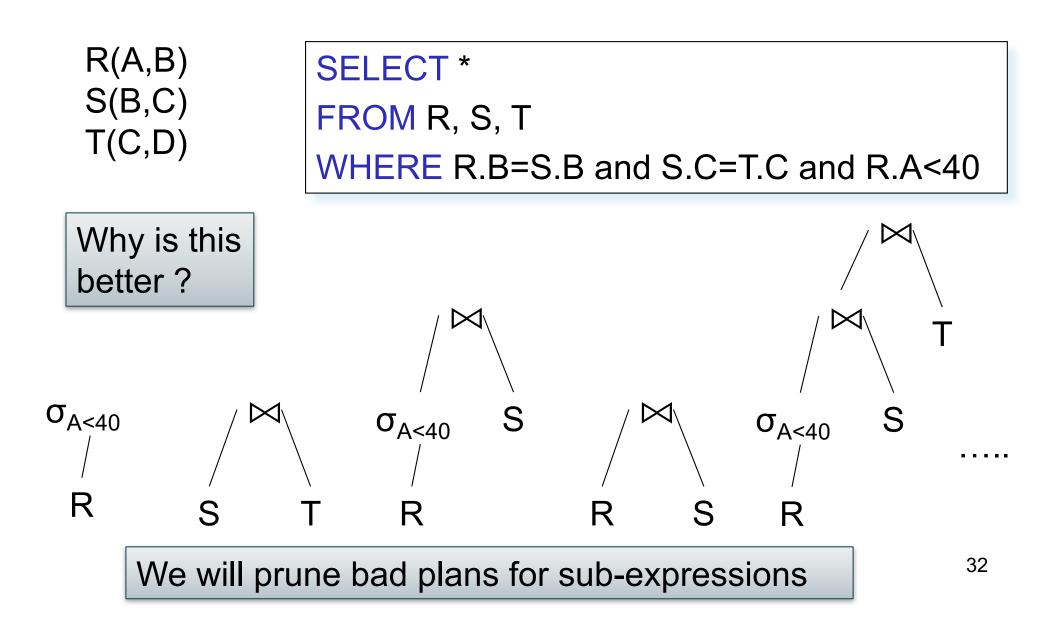
Three Approaches to Search Space Enumeration

- Complete plans
- Bottom-up plans
- Top-down plans

Complete Plans



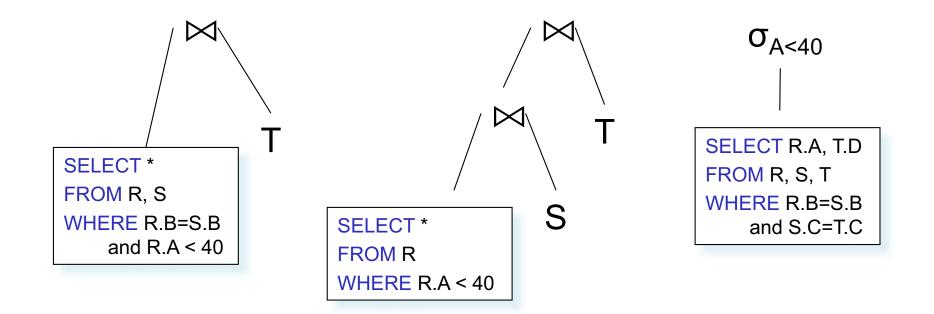
Bottom-up Partial Plans



Top-down Partial Plans

R(A,B) S(B,C) T(C,D)





Two Types of Plan Enumeration Algorithms

- Dynamic programming (in class)
 - Based on System R (aka Selinger) style optimizer[1979]
 - Limited to joins: join reordering algorithm

– Bottom-up

- Rule-based algorithm (will not discuss)
 - Database of rules (=algebraic laws)
 - Usually: dynamic programming
 - Usually: top-down