CSE 444: Database Internals

Lecture 12

Query Optimization (part 3)

Selinger Optimizer

Problem:

- How to order a series joins over N tables A,B,C,…
  E.g. A.a = B.b AND A.c = D.d AND B.e = C.f

- N! ways to order joins; e.g. ABCD, ACBD, ….

- $C_{N-1} = \frac{1}{N}\binom{2(N-1)}{N-1}$ plans/ordering; e.g. (((AB)C)D), ((AB)(CD)))

- Multiple implementations (hash, nested loops)

- Naïve approach does not scale
  - E.g. N = 20, #join orders 20! = 2.4 x 10^{18} ; many more plans

Selinger Optimizer

- Only left-deep plan: (((AB)C)D) – eliminate C_{N-1}.
- Push down selection
- Don’t consider cartesian product
- Dynamic programming algorithm

Dynamic Programming

SimpleDB Lab4:
you implement orderJoin

OrderJoin:

R = set of relations to join

For d = 1 to N: /* where N = |R| */

For S in {all size-d subsets of R}:

optjoin(S) = (S – a) join a,

where a is the single relation that minimizes:

cost(**optjoin**(S – a)) +

min.cost to join (S – a) with a +

min.access cost for a

Note: **optjoin**(S-a) is cached from previous iterations

Example

SimpleDB Lab4: called CostCard(cost, card, plan)

Subplan S	optJoin(S)	Cost(OptJoin(S))
A		

- **optJoin(A, B, C, D)**
- Assume all joins are NL

Example

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
C	Seq scan	120
D	B+tree scan	400

- **optJoin(A, B, C, D)**
- Assume all joins are NL

- d = 1
  - A = best way to access A (sequential scan, predicate-pushdown on index, etc)
  - B = best way to access B
  - C = best way to access C
  - D = best way to access D

- Total number of steps: choose(N, 1)

Example

- **optJoin(A, B, C, D)**

- d = 2
  - {A,B} = AB or BA
    use previously computed
    best way to access A and B

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
…		

Example

- **optJoin(A, B, C, D)**

- d = 2
  - {A,B} = AB or BA
    use previously computed
    best way to access A and B

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
…		
{A, B}	BA	156

Example

- **optJoin(A, B, C, D)**

- d = 2
  - {A,B} = AB or BA
    use previously computed
    best way to access A and B
  - {B,C} = BC or CB

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
…		
{A, B}	BA	156
{B, C}	BC	98

Example

- **optJoin(A, B, C, D)**

- d = 2
  - {A,B} = AB or BA
    use previously computed
    best way to access A and B
  - {B,C} = BC or CB

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
…		
{A, B}	BA	156
{B, C}	BC	98

Example

- **optJoin(A, B, C, D)**

- d = 2
  - {A,B} = AB or BA
    use previously computed
    best way to access A and B
  - {B,C} = BC or CB
  - {C,D} = CD or DC
  - {A,C} = AC or CA
  - {B,D} = BD or DB
  - {A,D} = AD or DA

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
…		
{A, B}	BA	156
{B, C}	BC	98
……..		

Example

- **optJoin(A, B, C, D)**

- d = 2
  - {A,B} = AB or BA
    use previously computed
    best way to access A and B
  - {B,C} = BC or CB
  - {C,D} = CD or DC
  - {A,C} = AC or CA
  - {B,D} = BD or DB
  - {A,D} = AD or DA
- Total number of steps: choose(N, 2) × 2

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
…		
{A, B}	BA	156
{B, C}	BC	98
……..		

Example

- **optJoin(A, B, C, D)**
- d = 3
  - {A,B,C} =
    Remove A: compare A({B,C}) to ({B,C})A

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
….		
{A, B}	BA	156
{B, C}	BC	98
….		

Example

- **optJoin(A, B, C, D)**
- d = 3
  - {A,B,C} =
    Remove A: compare A($\boxed{\text{\{B,C\}}}$) to ({B,C})A

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
….		
{A, B}	BA	156
$\boxed{\text{\{B, C\}}}$	BC	98
….		

optJoin(B,C) and its cost are already cached in table

Example

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
….		
{A, B}	BA	156
{B, C}	BC	98
….		
{A, B, C}	BAC	500
……..		

- **optJoin(A, B, C, D)**
- d = 3
  - {A,B,C} =
    Remove A: compare A({B,C}) to ({B,C})A
    Remove B: compare B({A,C}) to ({A,C})B
    Remove C: compare C({A,B}) to ({A,B})C

optJoin(B,C) and its cost are already cached in table

Example

- **optJoin(A, B, C, D)**

- d = 3
  - $\boxed{\{A,B,C\}}$ =
    Remove A: compare A($\boxed{\{B,C\}}$) to ({B,C})A
    Remove B: compare B({A,C}) to ({A,C})B
    Remove C: compare C({A,B}) to ({A,B})C

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
….		
{A, B}	BA	156
{B, C}	BC	98
…		
{A, B, C}	BAC	500
……..		

optJoin(B,C) and its cost are already cached in table

Example

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
….		
{A, B}	BA	156
{B, C}	BC	98
…		
{A, B, C}	BAC	500
……..		

- **optJoin(A, B, C, D)**
- d = 3
  - {A,B,C} =
    Remove A: compare A({B,C}) to ({B,C})A
    Remove B: compare B({A,C}) to ({A,C})B
    Remove C: compare C({A,B}) to ({A,B})C
  - {A,B,D} =
    Remove A: compare A({B,D}) to ({B,D})A
    …
  - {A,C,D} =…
  - {B,C,D} =…
- Total number of steps: choose(N, 3) × 3 × 2

optJoin(B,C) and its cost are already cached in table

Example

Subplan S	optJoin(S)	Cost(OptJoin(S))
A	Index scan	100
B	Seq. scan	50
{A, B}	BA	156
{B, C}	BC	98
{A, B, C}	BAC	500
{B, C, D}	DBC	150
……..		

- **optJoin(A, B, C, D)**
- d = 4
  - {A,B,C,D} =

Remove A: compare A({B,C,D}) to ({B,C,D})A
Remove B: compare B({A,C,D}) to ({A,C,D})B
Remove C: compare C({A,B,D}) to ({A,B,D})C
Remove D: compare D({A,B,C}) to ({A,B,C})D

optJoin(B, C, D) and its cost are already cached in table

- Total number of steps: choose(N, 4) × 4 × 2

Complexity

- Total #subsets considered
  - Choose(N, 1) + Choose(N, 2) + ….. + Choose (N, N)
  - All nonempty subsets of a size N set: $2^N - 1$
  - Equivalently: number of binary strings of size N, except 00…0: ~~000~~, 001, 010, 011, 100, 101, 110, 111

Complexity

- Total #subsets considered
  - Choose(N, 1) + Choose(N, 2) + ….. + Choose (N, N)
  - All nonempty subsets of a size N set: $2^N - 1$
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- For each subset of size d:
  - d ways to remove a set
  - 2 ways for compute AB or BA (except when d=2, when we already accounted for that – why?)

Complexity

- Total #subsets considered
  - Choose(N, 1) + Choose(N, 2) + ….. + Choose (N, N)
  - All nonempty subsets of a size N set: $2^N - 1$
  - Equivalently: number of binary strings of size N, except 00…0:
    ~~000~~, 001, 010, 011, 100, 101, 110, 111

- For each subset of size d:
  - d ways to remove a set
  - 2 ways for compute AB or BA (except when d=2, when we already accounted for that – why?)

- Total #plans considered
  - Choose(N, 1) + 2 Choose(N, 2) + ….. + N Choose (N, N)
  - Equivalently: total number of 1's in all strings of size N
  - N 2^{N-1} because every 1 occurs 2^{N-1} times
  - Need to further multiply by 2, to account for AB or BA

Interesting Orders

- Some query plans produce data in sorted order
  - E.g scan over a primary index, merge-join
  - Called *interesting order*

- Next operator may use this order
  - E.g. can be another merge-join

- For each subset of relations, compute multiple optimal plans, one for each interesting order

- Increases complexity by factor k+1, where k=number of interesting orders

Why Left-Deep

Asymmetric, cost depends on the order

- Left: Outer relation   Right: Inner relation

- For nested-loop-join, we try to load the outer (typically smaller) relation in memory, then read the inner relation one page at a time

  B(R) + B(R)*B(S) or B(R) + B(R)/M * B(S)

- For index-join,

  we assume right (inner) relation has index

Why Left-Deep

- Advantages of left-deep trees?
  1. Fits well with standard join algorithms (nested loop, one-pass), more efficient

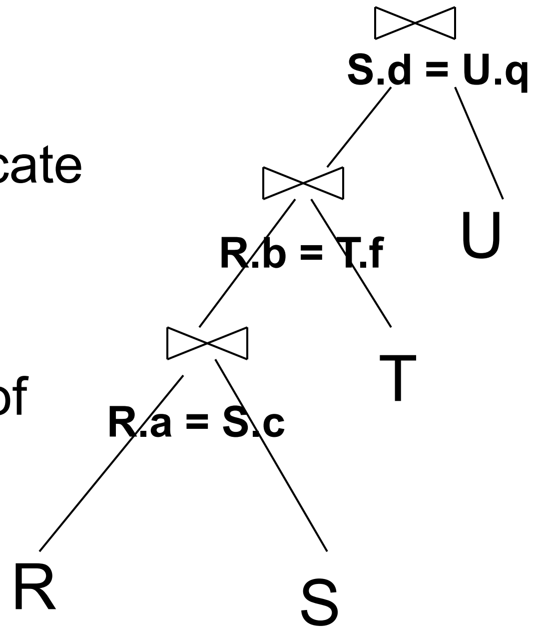
  2. One pass join: Uses smaller memory
     1. ((R, S), T), can reuse the space for R while joining (R, S) with T
     2. (R, (S, T)): Need to hold R, compute (S, T), then join with R, worse if more relations

  3. Nested loop join, consider top-down iterator next()
     1. ((R, S), T), Reads the chunks of (R, S) once, reads stored base relation T multiple times
     2. (R, (S, T)): Reads the chunks of R once, reads computed relation (S, T) multiple times, either more time or more space

Implementation in SimpleDB (lab4)

1. JoinOptimizer.java (and the classes used there)

2. Returns vector of "LogicalJoinNode"
   a) Two base tables, two join attributes, predicate
   b) e.g. R(a, b), S(c, d), T(a, f), U(p, q)
   c) (R, S, R.a, S.c, =)
   d) Recall that SimpleDB stores all attributes of
   R, S after their join R.a, R.b, S.c, S.d



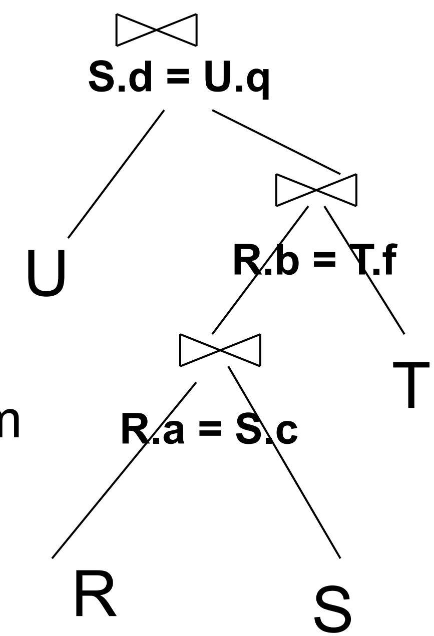
3. Output vector looks like:
   <(R, S, R.a, S.c), (R, T, R.b, T.f), (S, U, S.d, U.q)>

Implementation in SimpleDB (lab4)

Any advantage of returning pairs?

- Flexibility to consider all linear plans

  <(R, S, R.a,S.c), (R, T, R.b, T.f), (U, S, U.q, S.d)>



More Details:

1. You mainly need to implement "orderJoin(..)"
2. "CostCard" data structure stores a plan, its cost and cardinality: you would need to estimate them
3. "PlanCache" stores the table in dyn. Prog:

   Maps a set of LJN to

   a vector of LJN (best plan for the vector),

   its cost,

   and its cardinality

LJN = LogicalJoinNode