

The Problem

Finding where to park should be simple, but it is often hard to predict availability which makes it a time consuming task.

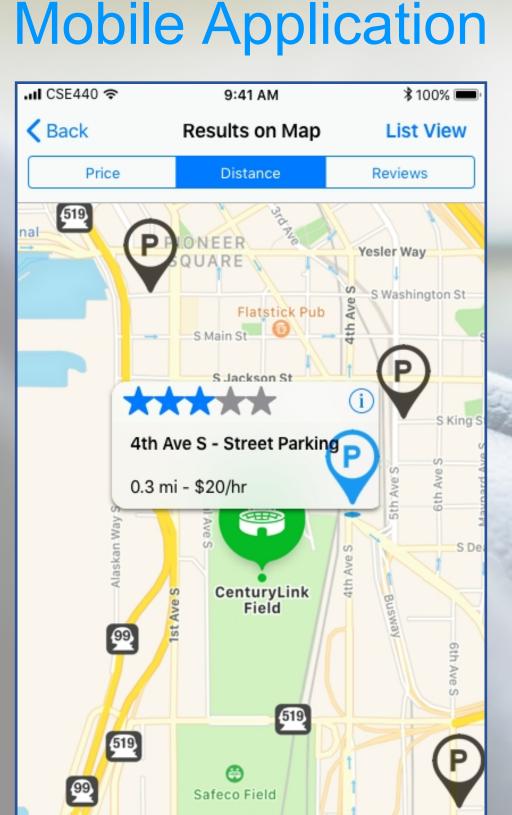
Our Solution

Give drivers a way to find parking based on their preferences, supporting both: **pre-planned** and **real-time** parking.

Key Features

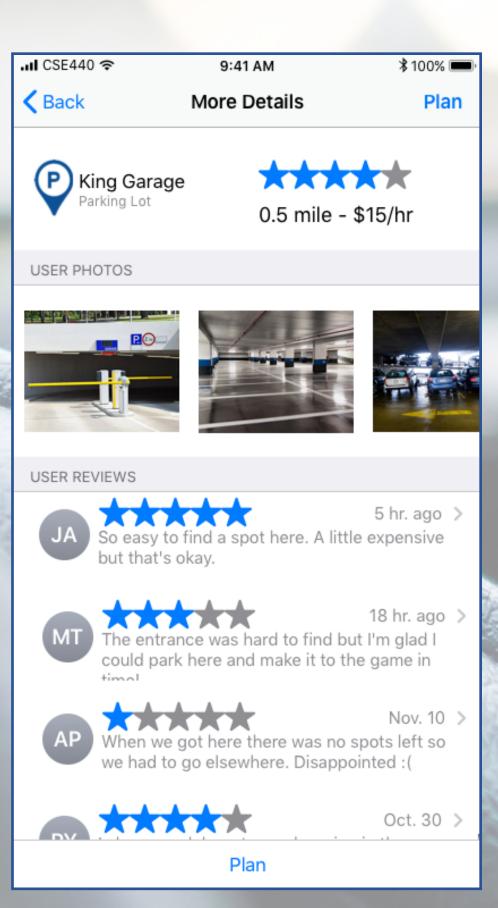
Filter on different factors, view suggestions in list or map view, edit planned drives, and leave feedback on your parking experience.

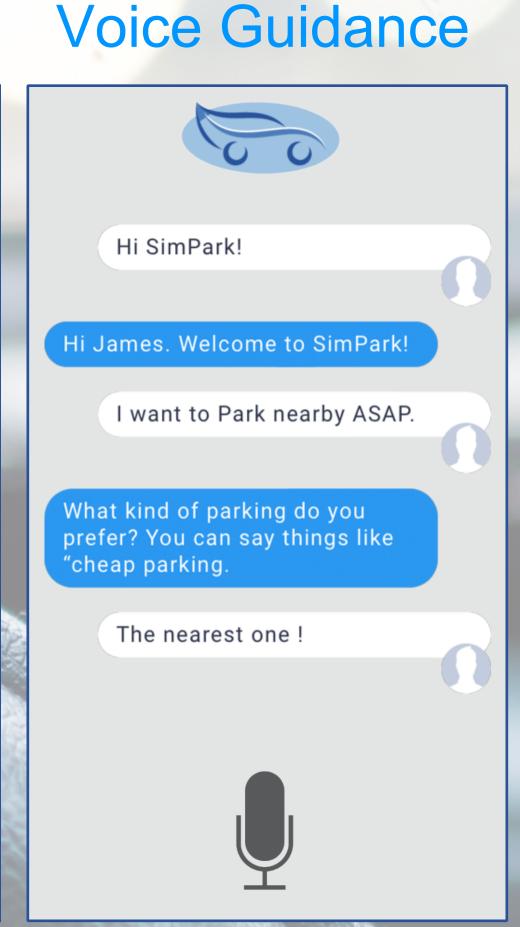
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Cancel



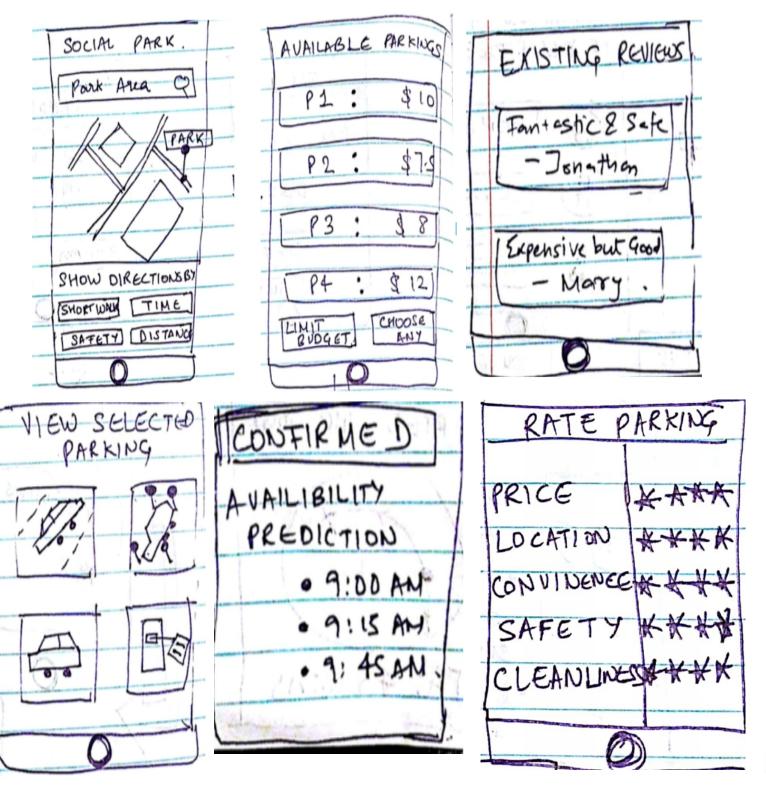




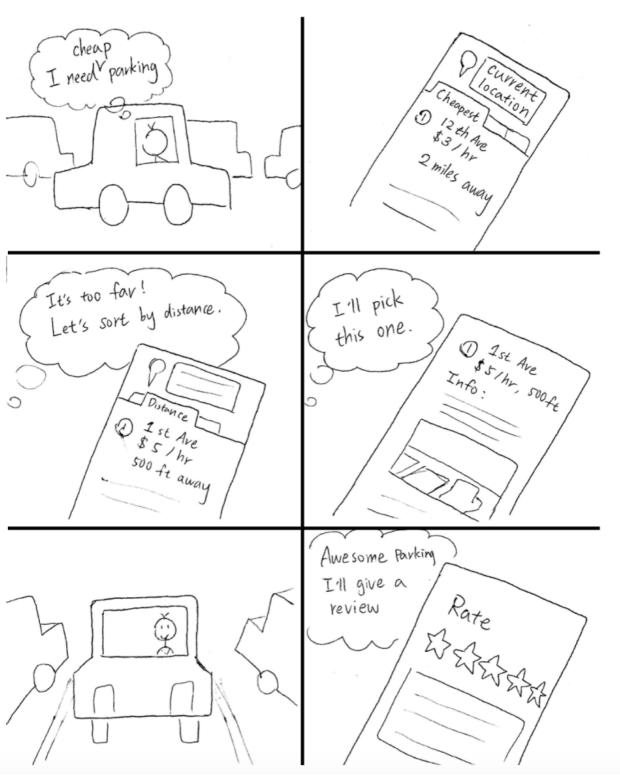
Design Iteration



Next



Storyboards



Paper Prototypes

