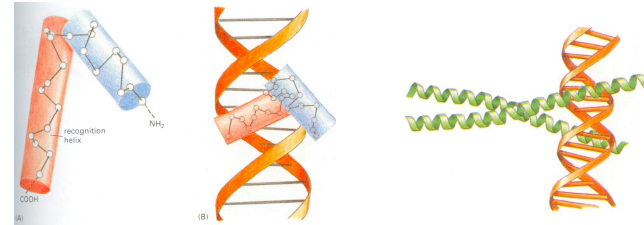


CSE 427

Markov Models and Hidden Markov Models

How Proteins “Read” DNA

E.g.:

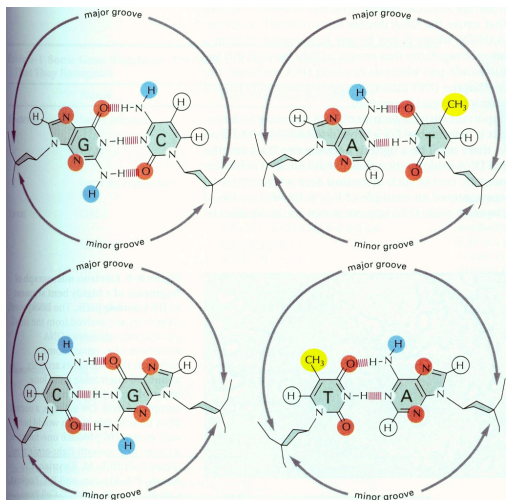


Helix-Turn-Helix Motif

Leucine Zipper Motif

Down in the Groove

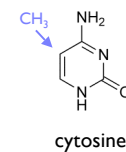
Different patterns of hydrophobic methyls, potential H bonds, etc. at edges of different base pairs. They're accessible, esp. in major groove



DNA Methylation

CpG - 2 adjacent nts, same strand (not Watson-Crick pair; “p” mnemonic for the phosphodiester bond of the DNA backbone)

C of CpG is often (70-80%) methylated in mammals i.e., CH₃ group added (both strands)

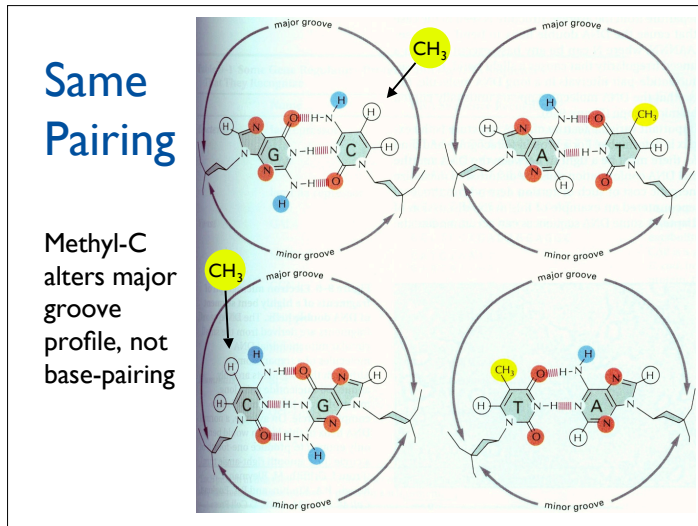


Why? Generally silences transcription.

X-inactivation, imprinting, repression of mobile elements, some cancers, aging, and *developmental differentiation*

How? DNA methyltransferases convert hemi- to fully-methylated

Major exception: promoters of housekeeping genes

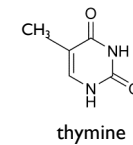
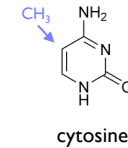


“CpG Islands”

Methyl-C mutates to T relatively easily

Net: CpG is less common than expected genome-wide:
 $f(\text{CpG}) < f(\text{C}) * f(\text{G})$

BUT in promoter (& other) regions, CpG remain unmethylated, so CpG → TpG less likely there: makes “CpG Islands”; often mark gene-rich regions



CpG Islands

CpG Islands

- More CpG than elsewhere
- More C & G than elsewhere, too
- Typical length: few 100 to few 1000 bp

Questions

- Is a short sequence (say, 200 bp) a CpG island or not?
- Given long sequence (say, 10-100kb), find CpG islands?

Markov & Hidden Markov Models

References:

- Eddy, "What is a hidden Markov model?" Nature Biotechnology, 22, #10 (2004) 1315-6.
- Durbin, Eddy, Krogh and Mitchison, “Biological Sequence Analysis”, Cambridge, 1998
- Rabiner, "A Tutorial on Hidden Markov Models and Selected Application in Speech Recognition," Proceedings of the IEEE, v 77 #2, Feb 1989, 257-286

Independence

A key issue: Previous models we've talked about assume *independence* of nucleotides in different positions - definitely unrealistic.

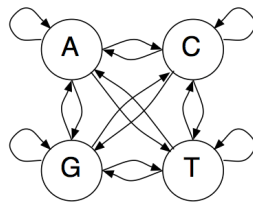
Markov Chains

A sequence x_1, x_2, \dots of random variables is a *k-th order Markov chain* if, for all i , i^{th} value is independent of all but the previous k values:

$$P(x_i | x_1, x_2, \dots, x_{i-1}) = P(x_i | x_{i-k}, x_{i-k+1}, \dots, x_{i-1})$$

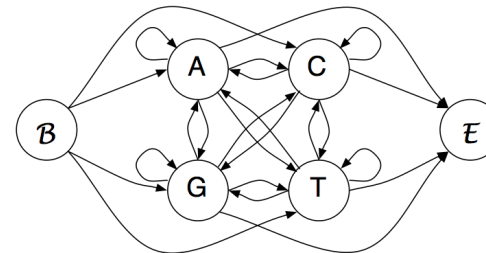
Example 1: Uniform random ACGT	}	0th order
Example 2: Weight matrix model		}
Example 3: ACGT, but \downarrow Pr(G following C)		

A Markov Model (1st order)



States: A,C,G,T
 Emissions: corresponding letter
 Transitions: $a_{st} = P(x_i = t | x_{i-1} = s)$ ← 1st order

A Markov Model (1st order)



States: A,C,G,T
 Emissions: corresponding letter
 Transitions: $a_{st} = P(x_i = t | x_{i-1} = s)$
 Begin/End states

Pr of emitting sequence x

$$x = x_1 x_2 \dots x_n$$

$$\begin{aligned}
 P(x) &= P(x_1, x_2, \dots, x_n) \quad \text{laws of probability} \\
 &= P(x_1) \cdot P(x_2 | x_1) \cdots P(x_n | x_{n-1}, \dots, x_1) \\
 &= P(x_1) \cdot P(x_2 | x_1) \cdots P(x_n | x_{n-1}) \quad \text{if 1st order MC} \\
 &= P(x_1) \prod_{i=1}^{n-1} a_{x_i, x_{i+1}} \\
 &= \prod_{i=0}^{n-1} a_{x_i, x_{i+1}} \quad (\text{with Begin state})
 \end{aligned}$$

Training

Max likelihood estimates for transition probabilities are just the frequencies of transitions when emitting the training sequences

E.g., from 48 CpG islands in 60k bp:

+	A	C	G	T	-	A	C	G	T
A	0.180	0.274	0.426	0.120	A	0.300	0.205	0.285	0.210
C	0.171	0.368	<u>0.274</u>	0.188	C	0.322	0.298	<u>0.078</u>	0.302
G	0.161	0.339	0.375	0.125	G	0.248	0.246	0.298	0.208
T	0.079	0.355	0.384	0.182	T	0.177	0.239	0.292	0.292

Discrimination/Classification

Log likelihood ratio of CpG model vs background model

$$S(x) = \log \frac{P(x|\text{model } +)}{P(x|\text{model } -)} = \sum_{i=1}^L \log \frac{a_{x_{i-1}x_i}^+}{a_{x_{i-1}x_i}^-} = \sum_{i=1}^L \beta_{x_{i-1}x_i}$$

β	A	C	G	T
A	-0.740	0.419	0.580	-0.803
C	-0.913	0.302	1.812	-0.685
G	-0.624	0.461	0.331	-0.730
T	-1.169	0.573	0.393	-0.679

CpG Island Scores

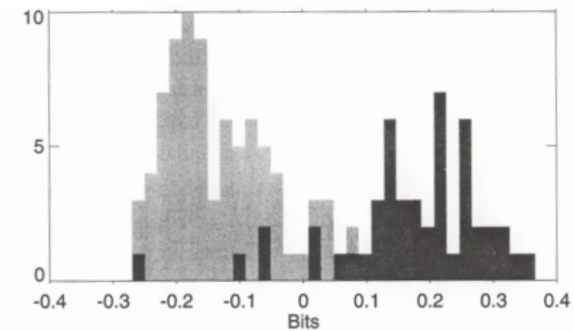


Figure 3.2 The histogram of the length-normalised scores for all the sequences. CpG islands are shown with dark grey and non-CpG with light grey.

What does a 2nd order
Markov Model look like?

3rd order?

Questions

Q1: Given a *short* sequence, is it more likely from feature model or background model? [Above](#)

Q2: Given a *long* sequence, where are the features in it (if any)

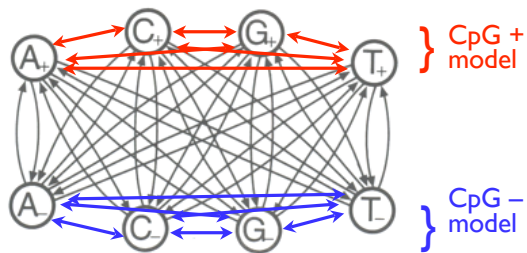
[Approach 1](#): score 100 bp (e.g.) windows

Pro: simple

Con: arbitrary, fixed length, inflexible

[Approach 2](#): *combine +/- models.*

Combined Model



Emphasis is “Which (hidden) state?” not “Which model?”

Hidden Markov Models (HMMs)

States: $1, 2, 3, \dots$

Paths: sequences of states $\pi = (\pi_1, \pi_2, \dots)$

Transitions: $a_{k,l} = P(\pi_i = l \mid \pi_{i-1} = k)$

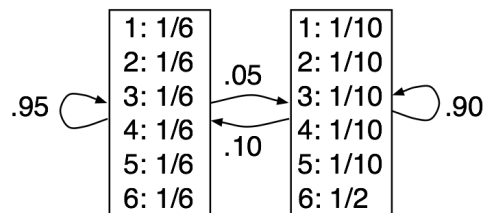
Emissions: $e_k(b) = P(x_i = b \mid \pi_i = k)$

Observed data: emission sequence

Hidden data: state/transition sequence

The Occasionally Dishonest Casino

1 fair die, 1 “loaded” die, occasionally swapped



```
Rolls 315116246446644245311321631164152133625144543631656626566666
Die   FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF

Rolls 65116645313265124563666463163666316232645523626666625151631
Die   LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF

Rolls 222555441666566563564324364131513465146353411126414626253356
Die   FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFLL
Viterbi FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFL

Rolls 366163666466232534413661661163252562462255265252266435353336
Die   LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF

Rolls 233121625364414432335163243633665562466662632666612355245242
Die   FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
```

Figure 3.5 The numbers show 300 rolls of a die as described in the example. Below is shown which die was actually used for that roll (F for fair and L for loaded). Under that the prediction by the Viterbi algorithm is shown.

Inferring hidden stuff

Joint probability of a given path π & emission sequence x :

$$P(x, \pi) = a_{0, \pi_1} \prod_{i=1}^n e_{\pi_i}(x_i) \cdot a_{\pi_i, \pi_{i+1}}$$

But π is hidden; what to do? Some alternatives:

Most probable single path

$$\pi^* = \arg \max_{\pi} P(x, \pi)$$

Sequence of most probable states

$$\hat{\pi}_i = \arg \max_k P(\pi_i = k | x)$$

The Viterbi Algorithm: The most probable path

Viterbi finds: $\pi^* = \arg \max_{\pi} P(x, \pi)$

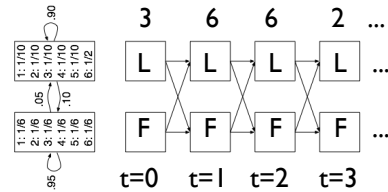
Possibly there are 10^{99} paths of prob 10^{-99}

More commonly, one path (+ slight variants) dominate others.

(If not, other approaches may be preferable.)

Key problem: exponentially many paths π

Unrolling an HMM



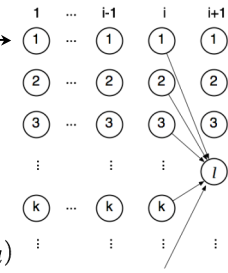
Conceptually, sometimes convenient
Note exponentially many paths

Viterbi

$v_l(i)$ = probability of the most probable path emitting x_1, x_2, \dots, x_i and ending in state l

Initialize:

$$v_l(0) = \begin{cases} 1 & \text{if } l = \text{Begin state} \\ 0 & \text{otherwise} \end{cases}$$



General case:

$$v_l(i+1) = e_l(x_{i+1}) \cdot \max_k (v_k(i) a_{k,l})$$

Viterbi Traceback

Above finds *probability* of best path

To find the path itself, trace *backward* to the state k attaining the max at each stage

```

Rolls 315116246446644245311321631164152133625144543631656626566666
Die   FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFL
Viterbi FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFL

Rolls 65116645313265124563666463163666316232645523626666625151631
Die   LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF

Rolls 22255441666566563564324364131513465146353411126414626253356
Die   FFFFFFFFFLLLLLLLLLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFL

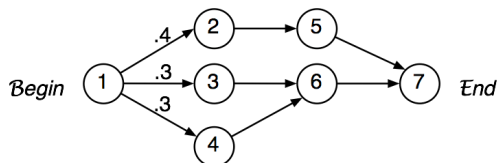
Rolls 366163666466232534413661661163252562462255265252266435353336
Die   LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF

Rolls 233121625364414432335163243633665562466662632666612355245242
Die   FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFL
    
```

Figure 3.5 The numbers show 300 rolls of a die as described in the example. Below is shown which die was actually used for that roll (F for fair and L for loaded). Under that the prediction by the Viterbi algorithm is shown.

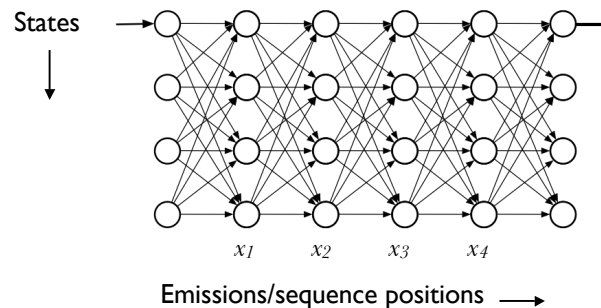
Is Viterbi “best”?

Viterbi finds $\pi^* = \arg \max_{\pi} P(x, \pi)$

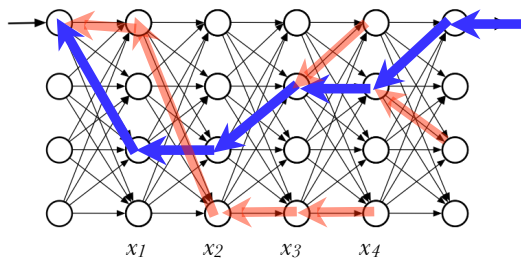


Most probable (Viterbi) *path* goes through 5, but most probable *state* at 2nd step is 6 (i.e., Viterbi is not the only interesting answer.)

An HMM (unrolled)



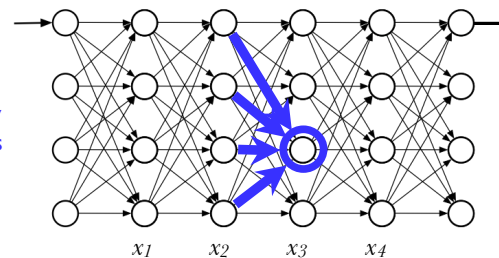
Viterbi: best path to each state



$$v_l(i+1) = e_l(x_{i+1}) \cdot \max_k (v_k(i) a_{k,l})$$

The Forward Algorithm

For each state/time, want *total* probability of all paths leading to it, with given emissions



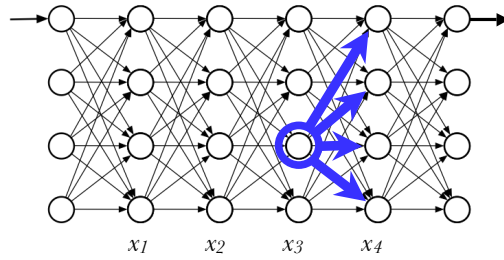
$$f_k(i) = P(x_1 \dots x_i, \pi_i = k)$$

$$f_l(i+1) = e_l(x_{i+1}) \sum_k f_k(i) a_{k,l}$$

$$P(x) = \sum_{\pi} P(x, \pi) = \sum_k f_k(n) a_{k,0}$$

The Backward Algorithm

Similar:
for each
state/time,
want total
probability
of all paths
from it,
with given
emissions,
conditional
on that
state.



$$b_k(i) \triangleq P(x_{i+1} \cdots x_n \mid \pi_i = k)$$

$$b_k(i) = \sum_l a_{k,l} e_l(x_{i+1}) b_l(i+1)$$

$$b_k(n) = a_{k,0}$$

In state k at step i ?

$$P(x, \pi_i = k)$$

$$= P(x_1, \dots, x_i, \pi_i = k) \cdot P(x_{i+1}, \dots, x_n \mid x_1, \dots, x_i, \pi_i = k)$$

$$= P(x_1, \dots, x_i, \pi_i = k) \cdot P(x_{i+1}, \dots, x_n \mid \pi_i = k)$$

$$= f_k(i) \cdot b_k(i)$$

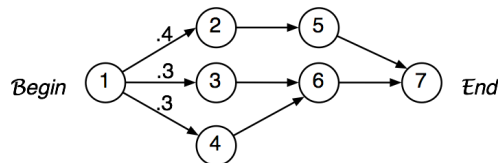
$$P(\pi_i = k \mid x) = \frac{P(x, \pi_i = k)}{P(x)} = \frac{f_k(i) \cdot b_k(i)}{P(x)}$$

Posterior Decoding, I

Alternative 1: what's the most likely state at step i ?

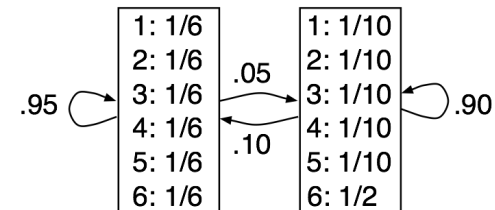
$$\hat{\pi}_i = \arg \max_k P(\pi_i = k \mid x)$$

Note: the sequence of most likely states \neq the most likely sequence of states. May not even be legal!



The Occasionally Dishonest Casino

1 fair die, 1 "loaded" die, occasionally swapped



```

Rolls  315116246446644245311321631164152133625144543631656626566666
Die    FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF

Rolls  65116645313265124563666463163666316232645523626666625151631
Die    LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF

Rolls  222555441666566563564324364131513465146353411126414626253356
Die    FFFFFFFFFLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLLL
Viterbi FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFL

Rolls  366163666466232534413661661163252562462255265252266435353336
Die    LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi LLLLLLFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF

Rolls  233121625364414432335163243633665562466662632666612355245242
Die    FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF
Viterbi FFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF

```

Figure 3.5 The numbers show 300 rolls of a die as described in the example. Below is shown which die was actually used for that roll (F for fair and L for loaded). Under that the prediction by the Viterbi algorithm is shown.

Posterior Decoding

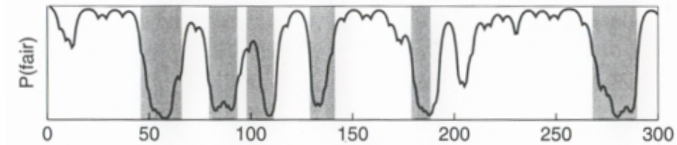


Figure 3.6 The posterior probability of being in the state corresponding to the fair die in the casino example. The x axis shows the number of the roll. The shaded areas show when the roll was generated by the loaded die.

Posterior Decoding, II

Alternative 1: what's most likely state at step i ?

$$\hat{\pi}_i = \arg \max_k P(\pi_i = k | x)$$

Alternative 2: given some function $g(k)$ on states, what's its expectation. E.g., what's probability of "+" model in CpG HMM ($g(k)=1$ iff k is "+" state)?

$$G(i | x) = \sum_k P(\pi_i = k | x) \cdot g(k)$$

CpG Islands again

Data: 41 human sequences, totaling 60kbp, including 48 CpG islands of about 1kbp each

Viterbi:	Post-process:
Found 46 of 48	46/48
plus 121 "false positives"	67 false pos

Posterior Decoding:	
same 2 false negatives	46/48
plus 236 false positives	83 false pos

Post-process: merge within 500; discard < 500

Training

Given model topology & training sequences,
learn transition and emission probabilities

If π known, then MLE is just frequency observed
in training data

$$a_{k,l} = \frac{\text{count of } k \rightarrow l \text{ transitions}}{\text{count of } k \rightarrow \text{anywhere transitions}}$$

$$e_k(b) = \dots$$

+ pseudocounts?

If π hidden, then use EM:

given π , estimate θ ; given θ estimate π . } 2 ways

Viterbi Training

given π , estimate θ ; given θ estimate π

Make initial estimates of parameters θ
Find Viterbi path π for each training sequence
Count transitions/emissions on those paths,
getting new θ
Repeat

Not rigorously optimizing desired likelihood, but
still useful & commonly used.
(Arguably good if you're doing Viterbi decoding.)

Baum-Welch Training

given θ , estimate π ensemble; then re-estimate θ

$$P(\pi_i = k, \pi_{i+1} = l | x, \theta)$$

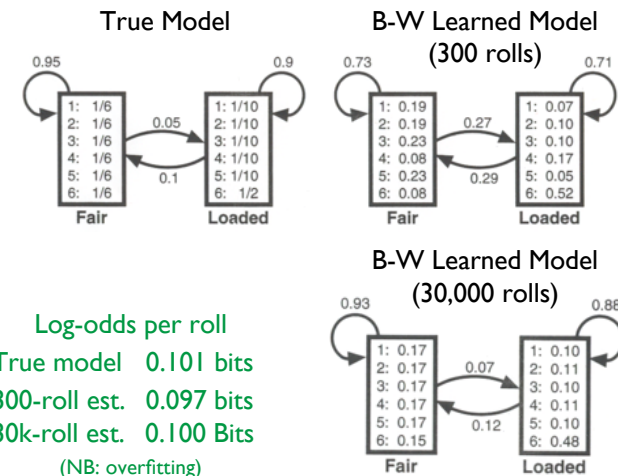
$$= \frac{f_k(i | \theta) a_{k,l} e_l(x_{i+1}) b_l(i+1 | \theta)}{P(x | \theta)}$$

Estimated # of $k \rightarrow l$ transitions $\hat{A}_{k,l}$

$$= \sum_{\text{training seqs } x^j} \sum_i P(\pi_i = k, \pi_{i+1} = l | x^j, \theta)$$

$$\text{New estimate } \hat{a}_{k,l} = \frac{\hat{A}_{k,l}}{\sum_l \hat{A}_{k,l}}$$

Emissions: similar



HMM Summary

joint vs conditional probs

- Viterbi – best single path (max of products)
- Forward – Sum over all paths (sum of products)
- Backward – similar
- Baum-Welch – Training via EM and forward/backward (aka the forward/backward algorithm)
- Viterbi training – also “EM”, but Viterbi-based

HMMs in Action: Pfam

- Proteins fall into families, both across & within species
- Ex: Globins, GPCRs, Zinc Fingers, Leucine zippers,...
- Identifying family very useful: suggests function, etc.
- So, search & alignment are both important
- One very successful approach: profile HMMs

```

Helix      AAAAAAAAAAAAAAAAAA  BBBBBBBBBBBBBBBBBBCCCCCCCCC
HBA_HUMAN  -----VLSPADKTNVKAAGKVGAA--HAGEYGAEALERMPLSFPTTKTYFPHF
HBB_HUMAN  -----VHLTPEEKSAVTALWGKVV---NVDEVGGEALGRLLVVYPWTQRFFESF
MYG_PHYCA  -----VLSGEWQLVHLVWAKVEA--DVAGHGQDILIRLFPKSHPETLEKFDRF
GLB3_CHITP -----LSADQISTVQASFDKVKG-----DPVGILYAVFKADPSIMAKFTQF
GLB5_PETMA FIVDTGSVAFLSAAEKTIIRSAWAPVYS--TYETSGVDILVKFFTSTPAAQEFKPF
LGB2_LUPLU -----GALTESQALVKSSEWFNA--NIPKHTHFPFLVLEIAPAKDLFS-F
GLB1_GLYDI -----GLSAAQROVIAATWKDIAGADNGAGVGDCLIKFLSAHPQMAAVFG-F
Consensus  Ls... v a W kv . . . g . L.. f . P . F F

Helix      DDDDDDEEEEEEEEEEEEEEEEEEE  FFFFFFFF
HBA_HUMAN  ---DLS---HGSAQVKGHGKRVADALTNVAHV---D--DMPNALSALSDLHAHKL-
HBB_HUMAN  GDLSSTPDAMVMNPKVKAHGKVKLGAFSGLAHL---D--NLKGTPTLSELHCIDL-
MYG_PHYCA  KHLKTEAEKKAEDLKKHGVTVLTALGAILKK---K--GHHEALRFLAQSHATKH-
GLB3_CHITP AG-KDLESIKGTAPFETHANRIVGFFSKIIGEL--P--NIEADVNTFVASHKPRG-
GLB5_PETMA RGLTTADQLKKSADVWHAERIIINAVNDAVASM--DDTEKMSMKLRDLGKHAASF-
LGB2_LUPLU LK-GTSEVPQNNPELQAHAGKVFVKLVYEAAIQLOVTVVVTDATLKNLGSVHVSKG-
GLB1_GLYDI LG---AS---DPGVAALGAKVLAQIGVAVSHL--GDEGRMVAQMRAVGRHKGYGN
Consensus  . t . . . v..Hg kv. a . a..l d . a.l.l H .

Helix      FPGGGGGGGGGGGGGGGGGGGGG  HHHHHHHHHHHHHHHHHHHHHHH
HBA_HUMAN  -RVDPVNFKLLSHCLLVTLAHLPAEFTPAVHASLDKFLASVSTVLTSKYR-----
HBB_HUMAN  -HVDPENFRLLGNLVCLLAHFGKEFTFPVQAAYQKVAGVANALAHKYH-----
MYG_PHYCA  -KIPIKYLEFISEAIIHVLHSHRHPGDFGADAQGAMNKALELFRKDIAAKYKELGYQC
GLB3_CHITP --VTHDQLNFRAGFVSYMKAHIT--DFA-GAEAAGWATLDTFPGMIFSKM-----
GLB5_PETMA -QIDPQFVKVLAVIDTVAAG-----DAGFEKLSMVICLLRSAY-----
LGB2_LUPLU --VADAHFPVVKEAILLKTIKEVVGAKWSEELNSAWTIYDELAIVFKEMNDAA--
GLB1_GLYDI KHIIKAQYFPLGASLLSAMEHRIGGMNAAAKDAWAAAYADISGALISGLQS-----
Consensus  v . f l . . . . . f . aa. k . . l sky
    
```

Alignment of 7 globins. A-H mark 8 alpha helices.
 Consensus line: upper case = 6/7, lower = 4/7, dot=3/7.
 Could we have a profile (aka weight matrix) w/ indels?

Profile HMM Structure

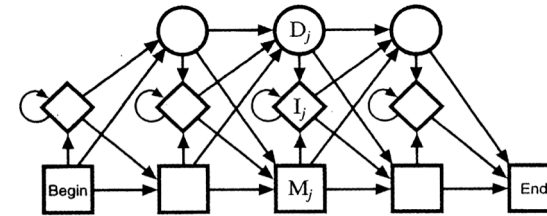


Figure 5.2 The transition structure of a profile HMM.
 Mj: Match states (20 emission probabilities)
 Ij: Insert states (Background emission probabilities)
 Dj: Delete states (silent - no emission)

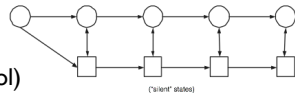
Silent States

Example: chain of states, can skip some



Problem: many parameters.

A solution: chain of "silent" states; fewer parameters (but less detailed control)



Algorithms: basically the same.

Using Profile HMM's

Search

Forward or Viterbi

Scoring

Log likelihood (length adjusted)

Log odds vs background

Z scores from either

} next slides

Alignment

Viterbi

Likelihood vs Odds Scores

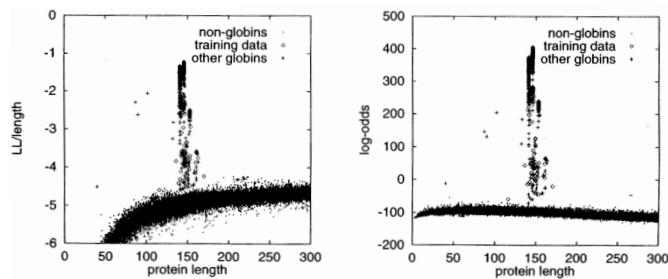


Figure 5.5 To the left the length-normalized LL score is shown as a function of sequence length. The right plot shows the same for the log-odds score.

Z-Scores

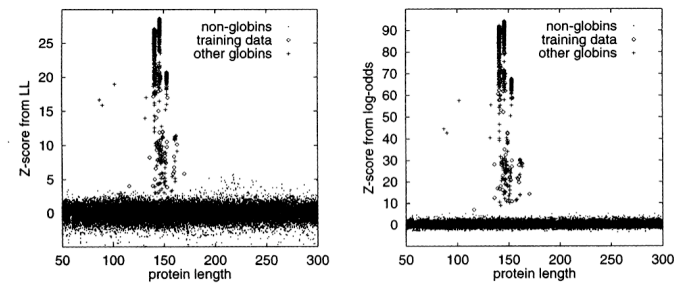


Figure 5.6 The Z-score calculated from the LL scores (left) and the log-odds (right).

Pfam Model Building

Hand-curated “seed” multiple alignments

Train profile HMM from seed alignment

Hand-chosen score threshold(s)

Automatic classification/alignment of all other protein sequences

7973 families in Rfam 18.0, 8/2005
(covers ~75% of proteins)

Model-building refinements

Pseudocounts (count = 0 common when training with 20 aa's)

$$e_i(a) = \frac{C_{i,a} + A \cdot q_a}{\sum_a C_{i,a} + A}, \quad A \sim 20, q_a = \text{background}$$

(~50 training sequences)

Pseudocount “mixtures”, e.g. separate pseudocount vectors for various contexts (hydrophobic regions, buried regions,...)
(~10-20 training sequences)

More refinements

Weighting: may need to down weight highly similar sequences to reflect phylogenetic or sampling biases, etc.

Match/insert assignment: Simple threshold, e.g. “> 50% gap \Rightarrow insert”, may be suboptimal. Can use forward-algorithm-like dynamic programming to compute max *a posteriori* assignment.

Numerical Issues

Products of many probabilities $\rightarrow 0$

For Viterbi: just add logs

For forward/backward: also work with logs, but you need sums of products, so need “log-of-sum-of-product-of-exp-of-logs”, e.g., by table/interpolation

Keep high precision and perhaps scale factor

Working with log-odds also helps.

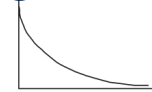
Model structure

Define it as well as you can.

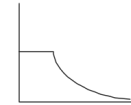
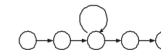
In principle, you can allow all transitions and hope to learn their probabilities from data, but it usually works poorly – too many local optima

Duration Modeling

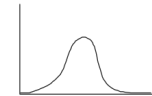
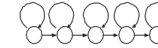
Self-loop duration:
geometric $pn(1-p)$



min, then geometric



“negative binomial”



More general: possible (but slower)