

# CSE 421 Winter 2025

## Lecture 15: Bellman-Ford

### Max Flow

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<http://www.cs.uw.edu/421>

# Single-source shortest paths, with negative edge weights

**Given:** an (un)directed graph  $G = (V, E)$  with each edge  $e$  having a weight  $w(e)$  and a vertex  $s$

**Find:** (length of) shortest paths from  $s$  to each vertex in  $G$ , or else indicate that there is a negative-cost cycle

Called the Bellman-Ford algorithm

(The original DP algorithm!)

(Also, the original shortest path algorithm!)

# Bellman Ford– Four Steps

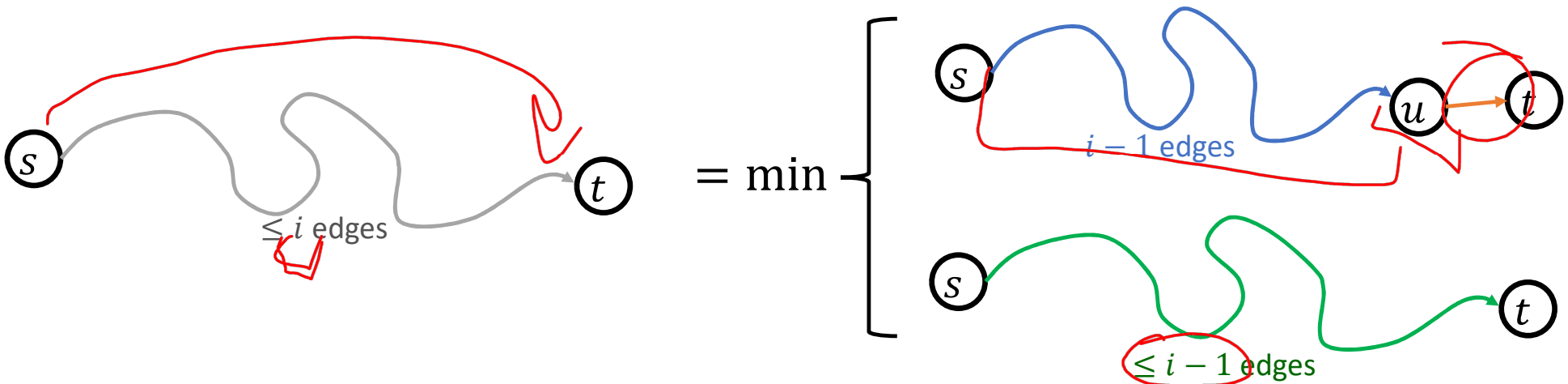
1. Formulate the answer with a recursive structure
  - What are the options for the last choice?
  - For each such option, what does the subproblem look like? How do we use it?
2. Choose a memory structure.
  - Figure out the possible values of all parameters in the recursive calls.
  - How many subproblems (options for last choice) are there?
  - What are the parameters needed to identify each?
  - How many different values could there be per parameter?
3. Specify an order of evaluation.
  - Want to guarantee that the necessary subproblem solutions are in memory when you need them.
  - With this step: a “Bottom-up” (iterative) algorithm
  - Without this step: a “Top-down” (recursive) algorithm
4. See if there’s a way to save space
  - Is it possible to reuse some memory locations?

# Final Recursive Structure

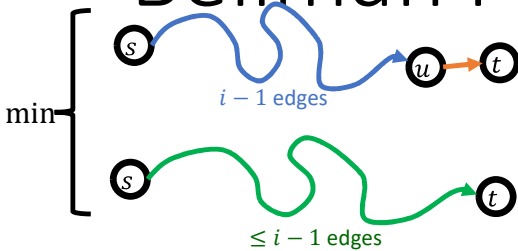
$OPT(i, t)$  = the weight of the shortest path from  $s$  to  $t$  with at most  $i$  edges

$$OPT(i, t) = \begin{cases} 0 & \text{if } i = 0 \text{ and } s = t \\ \infty & \text{if } i = 0 \text{ and } s \neq t \\ \min \left\{ \min_{u \in V} \{OPT(i-1, u) + w(u, t)\} \right. \\ \left. OPT(i-1, t) \right\} \end{cases}$$

Where  $w(u, t)$  is the weight of the edge from  $u$  to  $t$  if it exists and  $\infty$  if not.



# Bellman Ford– Four Steps



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# Identifying the Memory Structure

$$OPT(i, t) = \begin{cases} 0 & \text{if } i = 0 \text{ and } s = t \\ \infty & \text{if } i = 0 \text{ and } s \neq t \\ \min \left\{ \begin{array}{l} \min_{u \in V} \{OPT(i-1, u) + w(u, t)\} \\ OPT(i-1, t) \end{array} \right. \end{cases}$$

- How many parameters?
  - 2
- What does each represent?
  - $i$ : the length of the path
  - $t$ : a node
- How many different values?
  - $i$ :  $|V|$  (from length 0 up to  $|V| - 1$  if the path is simple)
  - $t$ :  $|V|$  (one value per node)

	1	2	3	4	5	6	7
0							
1							
2							
3							
4							
5							
6							

# Top-Down Bellman-Ford

This algorithm correctly finds shortest paths when there are no negative-cost cycles. How can we check for negative cost cycles?

**BF( $i, t$ ):**

if OPT[ $i$ ][ $t$ ] not blank: // Check if we've solved this already

return OPT[ $i$ ][ $t$ ]

if  $i == 0$ : // Check if this is a base case

solution = 0 if  $t == s$  :  $\infty$

OPT[ $i$ ][ $t$ ] = solution // Always save your solution before returning

return solution

solution =  $\infty$

for each  $u \in V$ :

solution = min(solution, BF( $i - 1, u$ ) +  $w(u, t)$ ) // solve each subproblem, pick which to use

solution = min(solution, BF( $i - 1, t$ )) // solve each subproblem, pick which to use

OPT[ $i$ ][ $t$ ] = solution // Always save your solution before returning

return solution

# Checking for Negative Cycles

$$OPT(i, t) = \begin{cases} 0 & \text{if } i = 0 \text{ and } s = t \\ \infty & \text{if } i = 0 \text{ and } s \neq t \\ \min \left\{ \begin{array}{l} \min_{u \in V} \{OPT(i-1, u) + w(u, t)\} \\ OPT(i-1, t) \end{array} \right. \end{cases}$$

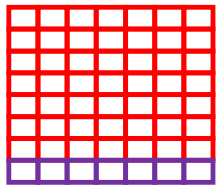
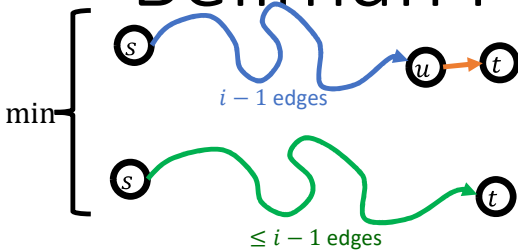
- How many parameters?
  - 2
- What does each represent?
  - $i$ : the length of the path
  - $t$ : a node
- How many different values?
  - $i$ :  $|V|+1$ 
    - a path of  $|V|$  edges is not simple, so if any  $|V|$ -edge path is shorter than one with fewer edges, there must be a negative cycle!
  - $t$ :  $|V|$  (one value per node)



	1	2	3	4	5	6	7
0							
1							
2							
3							
4							
5							
6							
7							



# Bellman Ford– Four Steps



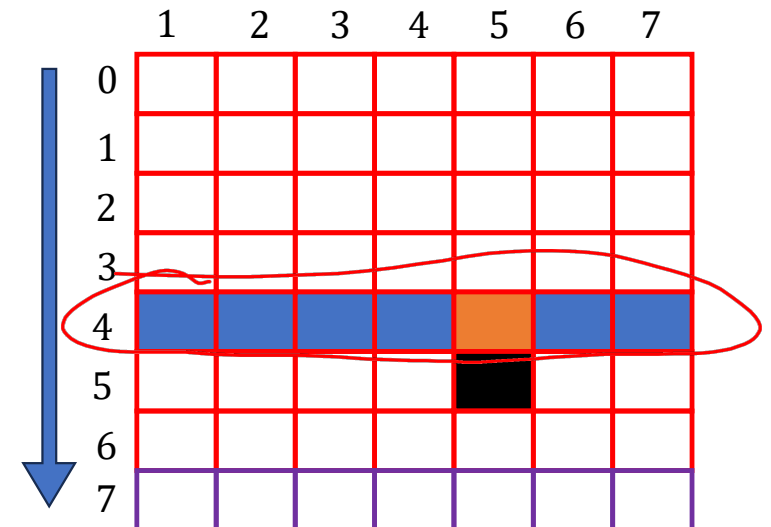
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# Order of Evaluations

$$OPT(i, t) = \begin{cases} 0 & \text{if } i = 0 \text{ and } s = t \\ \infty & \text{if } i = 0 \text{ and } s \neq t \\ \min \left\{ \begin{array}{l} \min_{u \in V} \{ OPT(i-1, u) + w(u, t) \} \\ OPT(i-1, t) \end{array} \right. \end{cases}$$

Each cell depends on every value in the previous row

Solve in order of  $i$



# Bottom-Up Bellman-Ford

**BF**( $s, t$ ):

$OPT[0][s] = 0$  // Solve and save base cases 1

for  $u \in V \setminus \{s\}$ :

$OPT[0][u] = \infty$  // Solve and save base cases

$|V|$   
→ for  $i = 0$  up to  $|V|$ :

for  $u \in V$ :

for  $v \in \text{neighbors}(u)$ :

$OPT[i][u] = \min(OPT[i][u], OPT[i-1][v])$  // solve and pick

$OPT[i][u] = \min(OPT[i][u], OPT[i-1][u])$  // solve and pick

for  $u \in V$ :

if  $OPT[|V|][u] < OPT[|V| - 1][u]$ : // check for negative cycles

return "negative cycle"

return  $OPT[s][t]$  // return the final answer

$|V|$   
 $+ w(u, v)$

# Bottom-Up Bellman-Ford

**BF**( $s, t$ ):

$OPT[0][s] = 0$  // Solve and save base cases  $\Theta(1)$

for  $u \in V \setminus \{s\}$ :

$OPT[0][u] = \infty$  // Solve and save base cases  $\Theta(|V|)$

for  $i = 0$  up to  $|V|$ :

for  $u \in V$ :

for  $v \in \text{neighbors}(u)$ :

$OPT[i][u] = \min(OPT[i][u], OPT[i-1][v])$  // solve and pick

$OPT[i][u] = \min(OPT[i][u], OPT[i-1][u])$  // solve and pick

for  $u \in V$ :

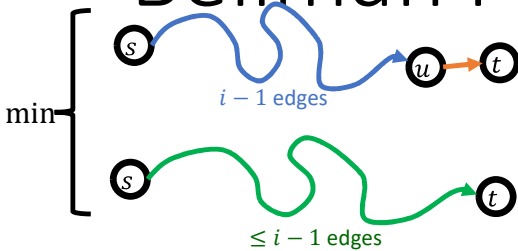
if  $OPT[|V|][u] < OPT[|V|-1][u]$ : // check for negative cycles  $\Theta(|V|)$

return "negative cycle"

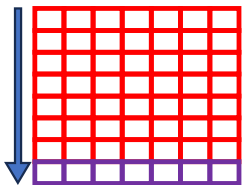
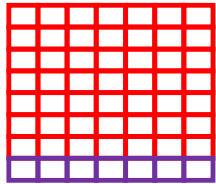
return  $OPT[s][t]$  // return the final answer  $\Theta(1)$

$\Theta(|V||E|)$

# Bellman Ford– Four Steps



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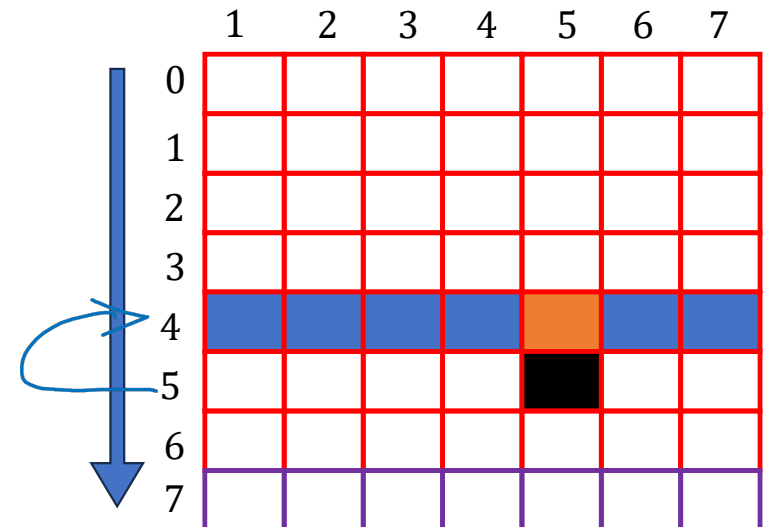


# Order of Evaluations

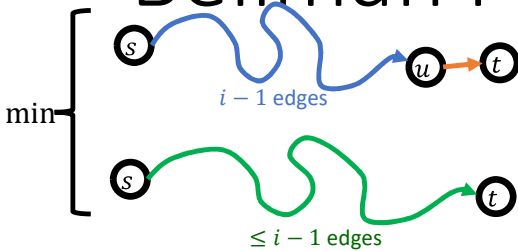
$$OPT(i, t) = \begin{cases} 0 & \text{if } i = 0 \text{ and } s = t \\ \infty & \text{if } i = 0 \text{ and } s \neq t \\ \min \left\{ \begin{array}{l} \min_{u \in V} \{OPT(i-1, u) + w(u, t)\} \\ OPT(i-1, t) \end{array} \right. \end{cases}$$

Each cell depends *only* on values in the previous row

We only need two rows!

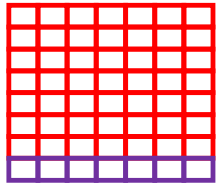


# Bellman Ford– Four Steps

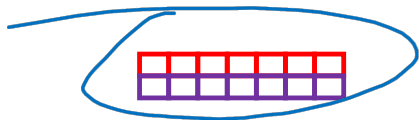
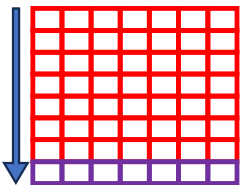


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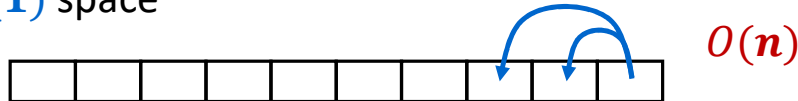


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# Dynamic Programming Patterns

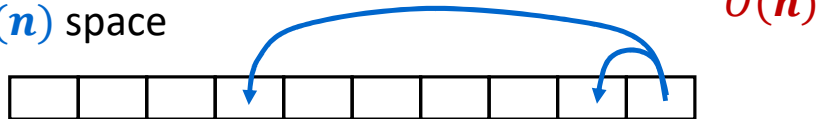
Fibonacci pattern:

- 1-D,  $O(1)$  immediately prior
- $O(1)$  space



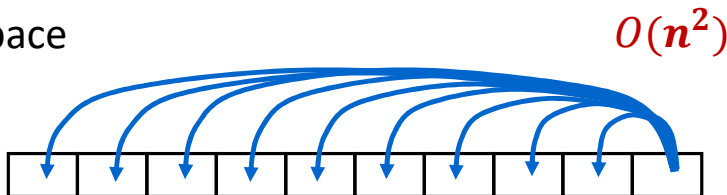
Weighted interval scheduling pattern:

- 1-D,  $O(1)$  arbitrary prior
- $O(n)$  space



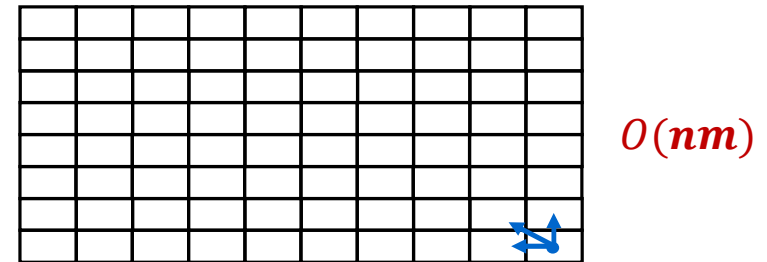
Longest increasing subsequence pattern:

- 1-D, all  $n - 1$  prior
- $O(n)$  space



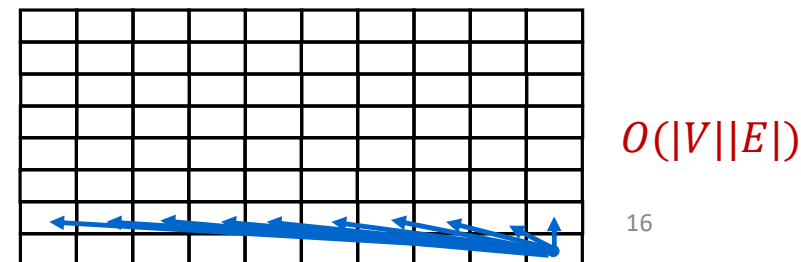
Alignment pattern:

- 2-D,  $O(1)$  in previous row, above, left, diagonal
- $O(n \cdot m)$  space



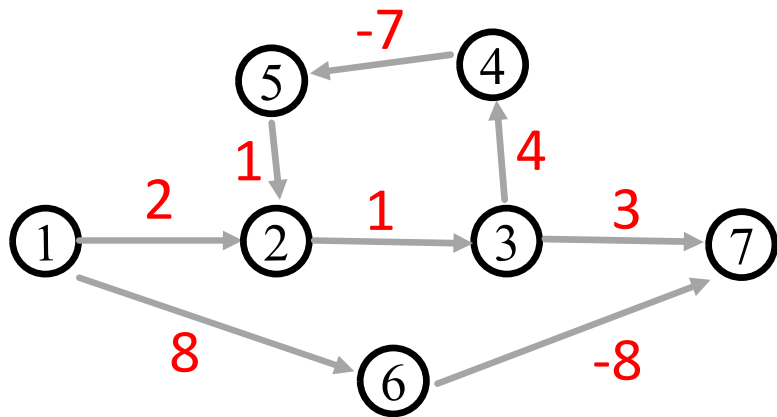
Bellman Ford pattern:

- 2-D,  $O(|V|)$  in previous row,
- $O(|V|)$  space





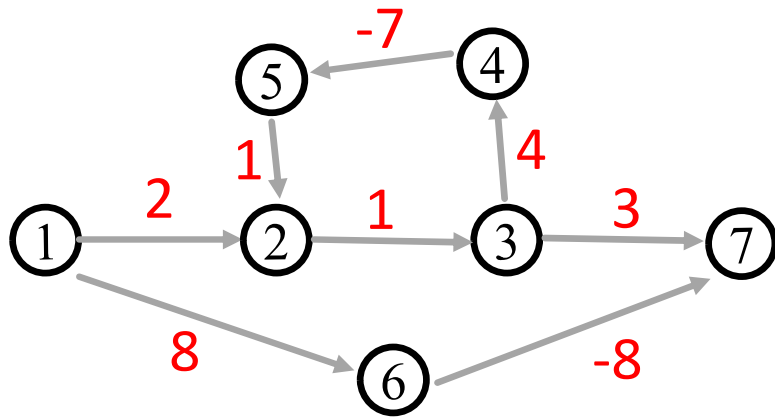
# Example Execution



$$OPT(i, t) = \begin{cases} 0 & \text{if } i = 0 \text{ and } s = t \\ \infty & \text{if } i = 0 \text{ and } s \neq t \\ \min \left\{ \begin{array}{l} \min_{u \in V} \{OPT(i-1, u) + w(u, t)\} \\ OPT(i-1, t) \end{array} \right. \end{cases}$$

	1	2	3	4	5	6	7
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
1							
2							
3							
4							
5							
6							
7							

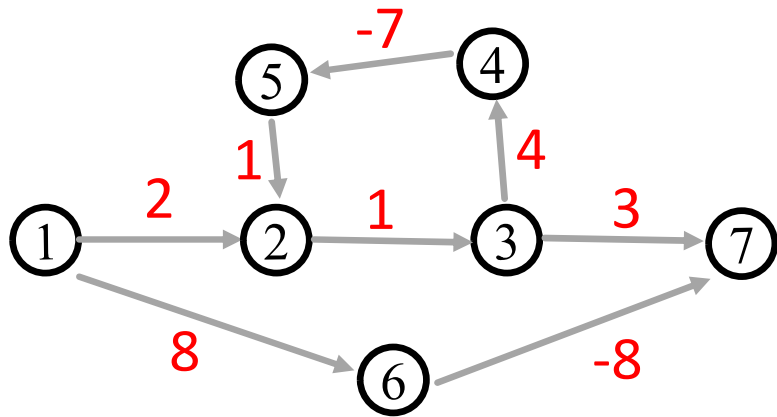
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	1	2	3	4	5	6	7
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
1	0	2	$\infty$	$\infty$	$\infty$	8	$\infty$
2							
3							
4							
5							
6							
7							

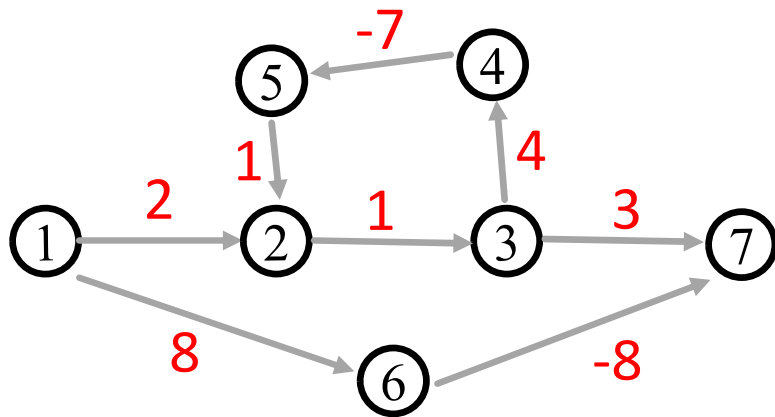
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	1	2	3	4	5	6	7
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
1	0	2	$\infty$	$\infty$	$\infty$	8	$\infty$
2	0	2	3	$\infty$	$\infty$	8	0
3							
4							
5							
6							
7							

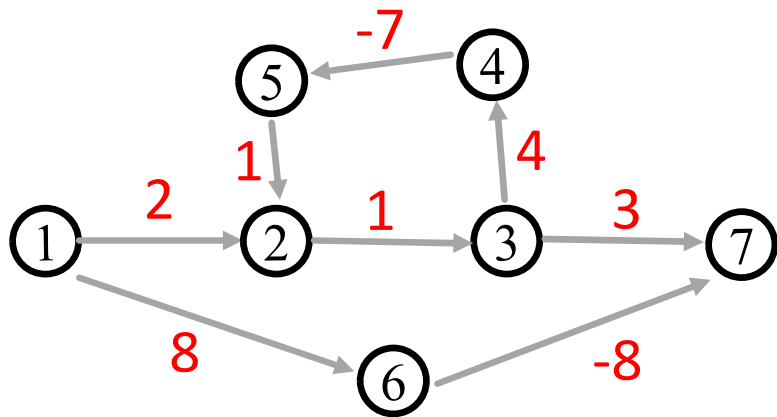
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	1	2	3	4	5	6	7
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
1	0	2	$\infty$	$\infty$	$\infty$	8	$\infty$
2	0	2	3	$\infty$	$\infty$	8	0
3	0	2	3	7	$\infty$	8	0
4							
5							
6							
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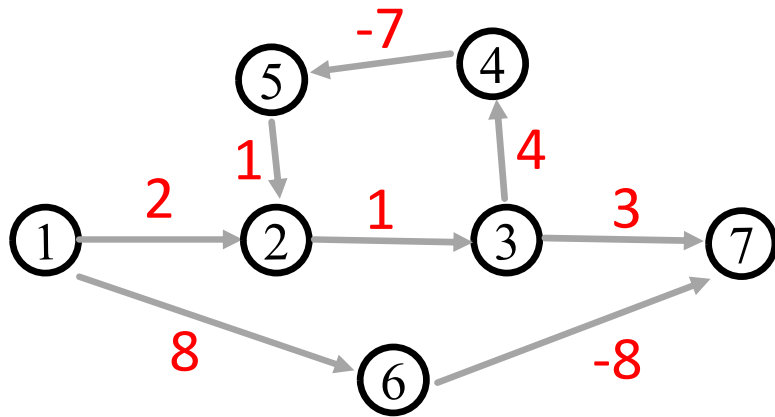
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	1	2	3	4	5	6	7
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
1	0	2	$\infty$	$\infty$	$\infty$	8	$\infty$
2	0	2	3	$\infty$	$\infty$	8	0
3	0	2	3	7	$\infty$	8	0
4	0	2	3	7	0	8	0
5							
6							
7							

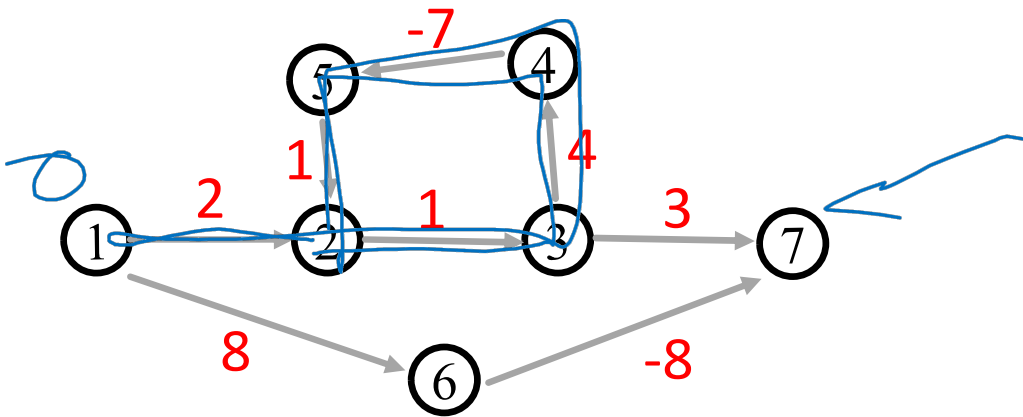
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	1	2	3	4	5	6	7
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
1	0	2	$\infty$	$\infty$	$\infty$	8	$\infty$
2	0	2	3	$\infty$	$\infty$	8	0
3	0	2	3	7	$\infty$	8	0
4	0	2	3	7	0	8	0
5	0	1	3	7	0	8	0
6							
7							

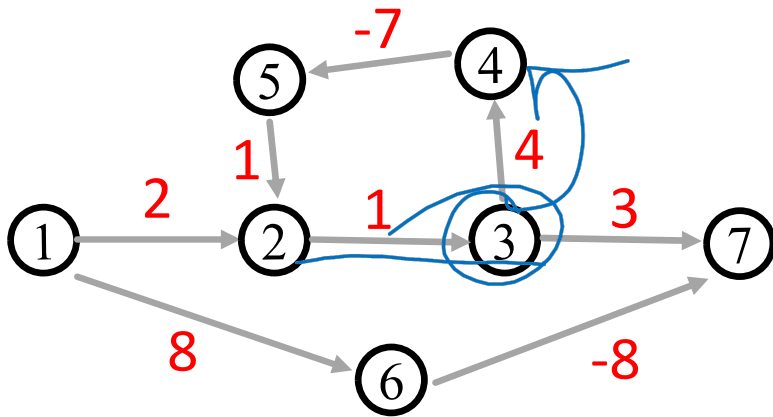
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	1	2	3	4	5	6	7
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
1	0	2	$\infty$	$\infty$	$\infty$	8	$\infty$
2	0	2	3	$\infty$	$\infty$	8	0
3	0	2	3	7	$\infty$	8	0
4	0	2	3	7	0	8	0
5	0	1	3	7	0	8	0
6	0	1	2	7	0	8	0
7							

# Example Execution



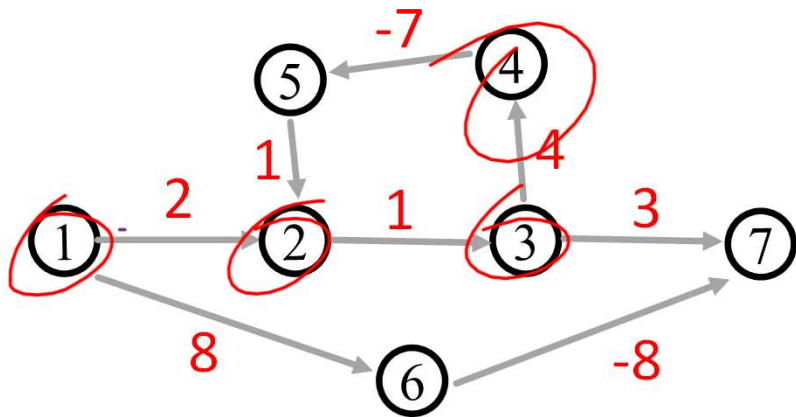
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	1	2	3	4	5	6	7
0	0	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$	$\infty$
1	0	2	$\infty$	$\infty$	$\infty$	8	$\infty$
2	0	2	3	$\infty$	$\infty$	8	0
3	0	2	3	7	$\infty$	8	0
4	0	2	3	7	0	8	0
5	0	1	3	7	0	8	0
6	0	1	2	7	0	8	0
7	0	1	2	3	0	8	0

6



# Example Execution



$$OPT(i, t) = \begin{cases} 0 & \text{if } i = 0 \text{ and } s = t \\ \infty & \text{if } i = 0 \text{ and } s \neq t \\ \min \left\{ \begin{array}{l} \min_{u \in V} \{OPT(i-1, u) + w(u, t)\} \\ OPT(i-1, t) \end{array} \right\} & \text{otherwise} \end{cases}$$

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1	0	2	$\infty$	$\infty$	$\infty$	8	$\infty$
2	0	2	3	$\infty$	$\infty$	8	0
3	0	2	3	<del><math>\infty</math></del>	$\infty$	8	0
4	0	2	3	7	0	8	0
5	0	1	3	7	0	8	0
6	0	1	2	7	0	8	0
7	0	1	2	3	0	8	0

Negative Cycle Found!

# Origins of Max Flow and Min Cut Problems

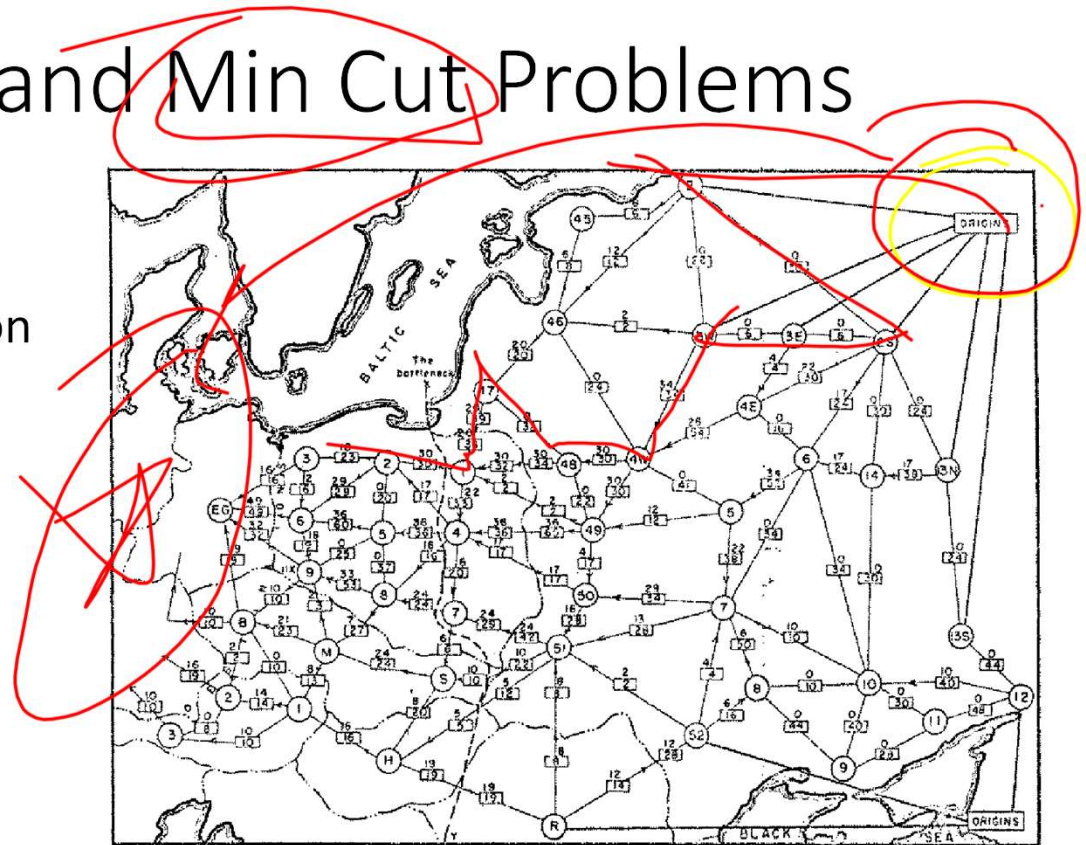
Max Flow problem formulation:

- [Tolstoy 1930] Rail transportation planning for the Soviet Union

Min Cut problem formulation:

- Cold War: US military planners want to find a way to cripple Soviet supply routes
- [Harris 1954] Secret RAND corp report for US Air Force

[Ford-Fulkerson 1955] Problems are equivalent

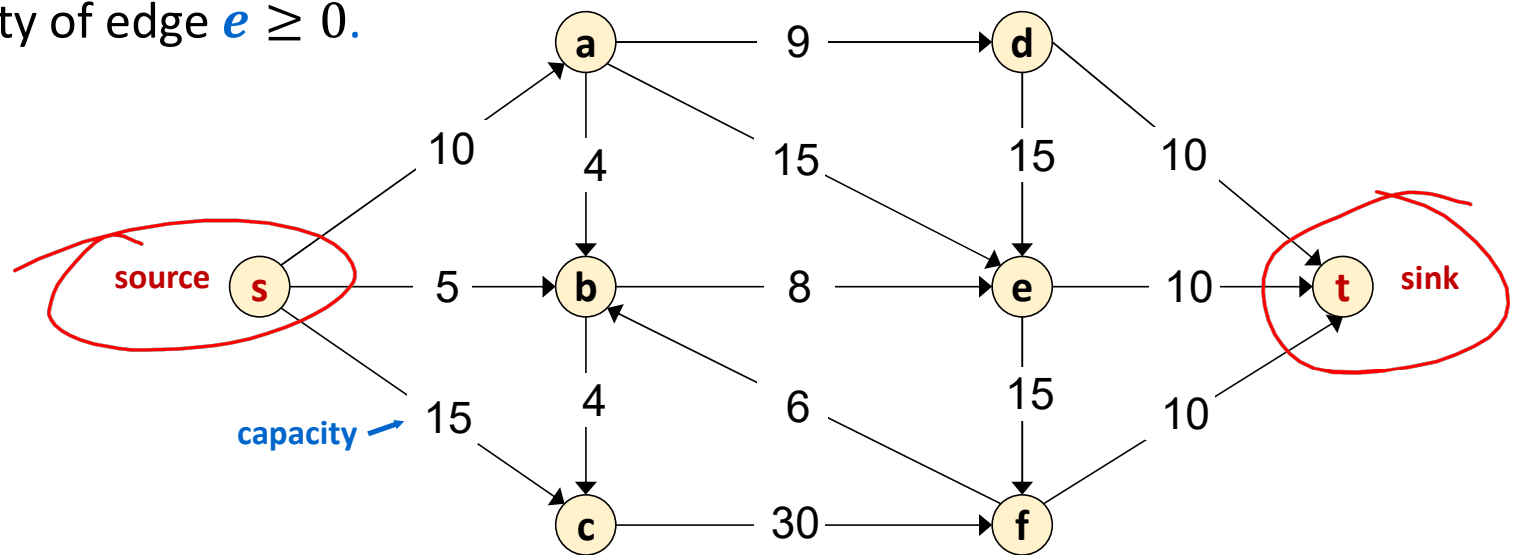


Reference: *On the history of the transportation and maximum flow problems.*  
Alexander Schrijver in Math Programming, 91: 3, 2002.

# Flow Network

## Flow network:

- Abstraction for material *flowing* through the edges.
- $G = (V, E)$  directed graph, no parallel edges.
- Two distinguished nodes:  $s = \text{source}$ ,  $t = \text{sink}$ .
- $c(e) = \text{capacity of edge } e \geq 0$ .



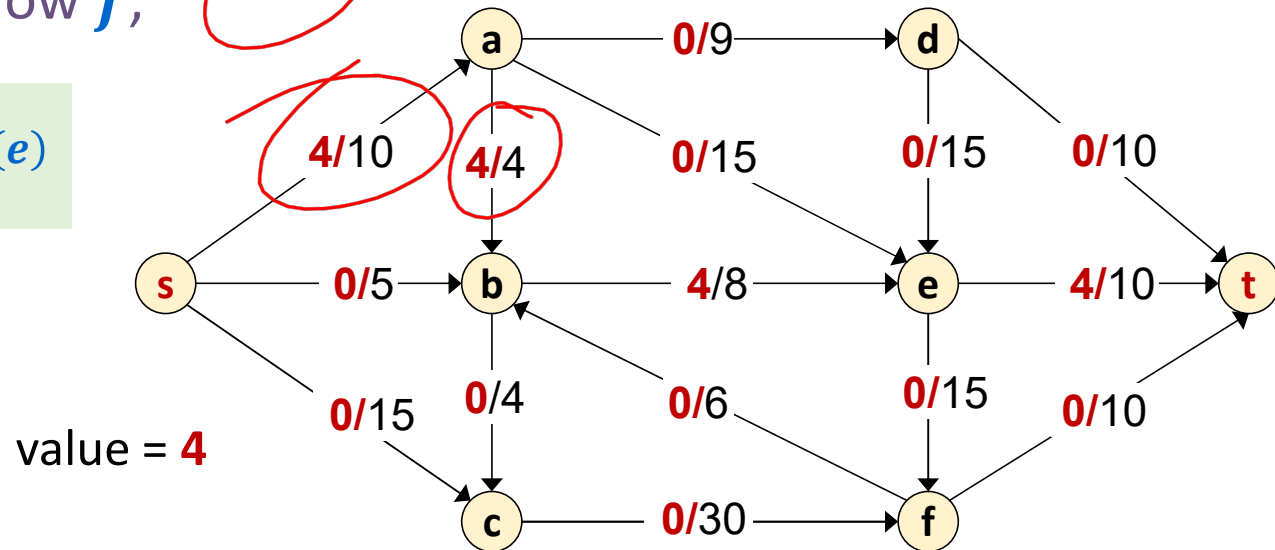
# Flows

**Defn:** An **s-t flow** in a flow network is a function  $f: E \rightarrow \mathbb{R}$  that satisfies:

- For each  $e \in E$ :  $0 \leq f(e) \leq c(e)$  [capacity constraints]
- For each  $v \in V - \{s, t\}$ :  $\sum_{e \text{ into } v} f(e) = \sum_{e \text{ out of } v} f(e)$  [flow conservation]

**Defn:** The **value** of flow  $f$ ,

$$v(f) = \sum_{e \text{ out of } s} f(e)$$



# Flows

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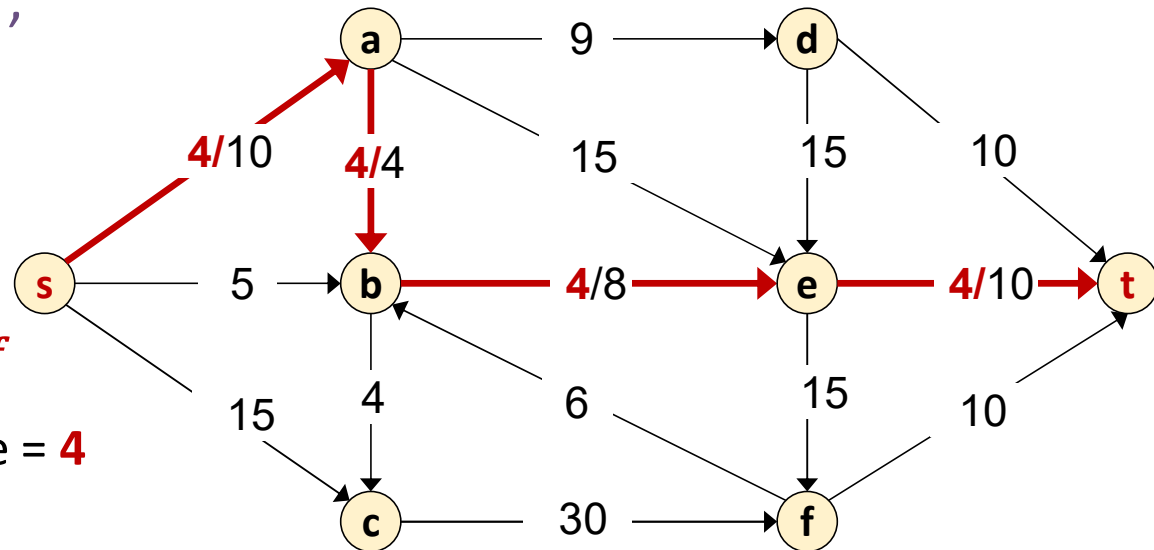
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**Defn:** The **value** of flow  $f$ ,

$$v(f) = \sum_{e \text{ out of } s} f(e)$$

Only show non-zero values of  $f$

value = 4



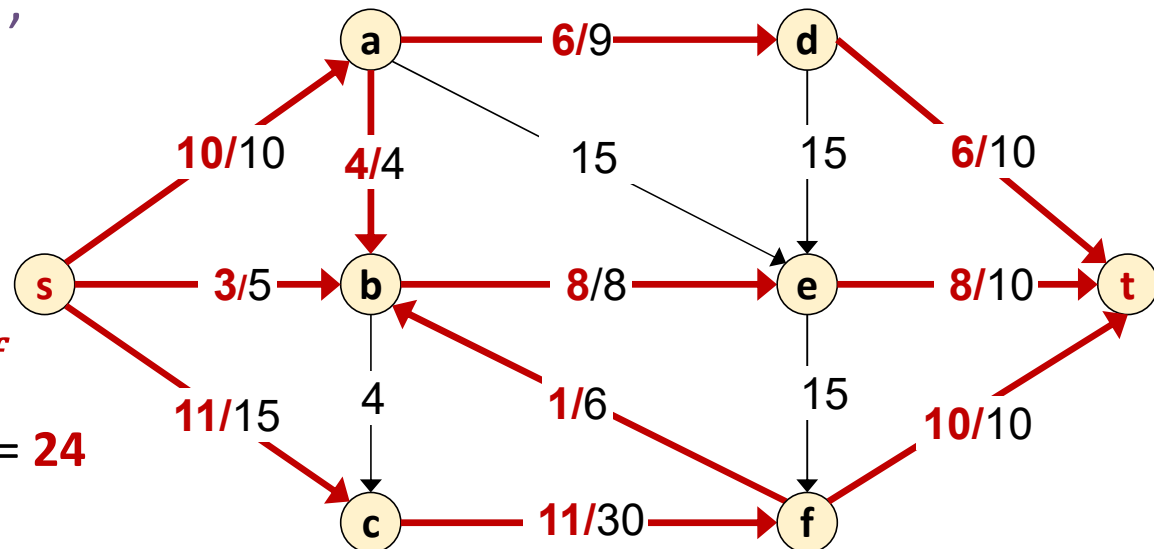
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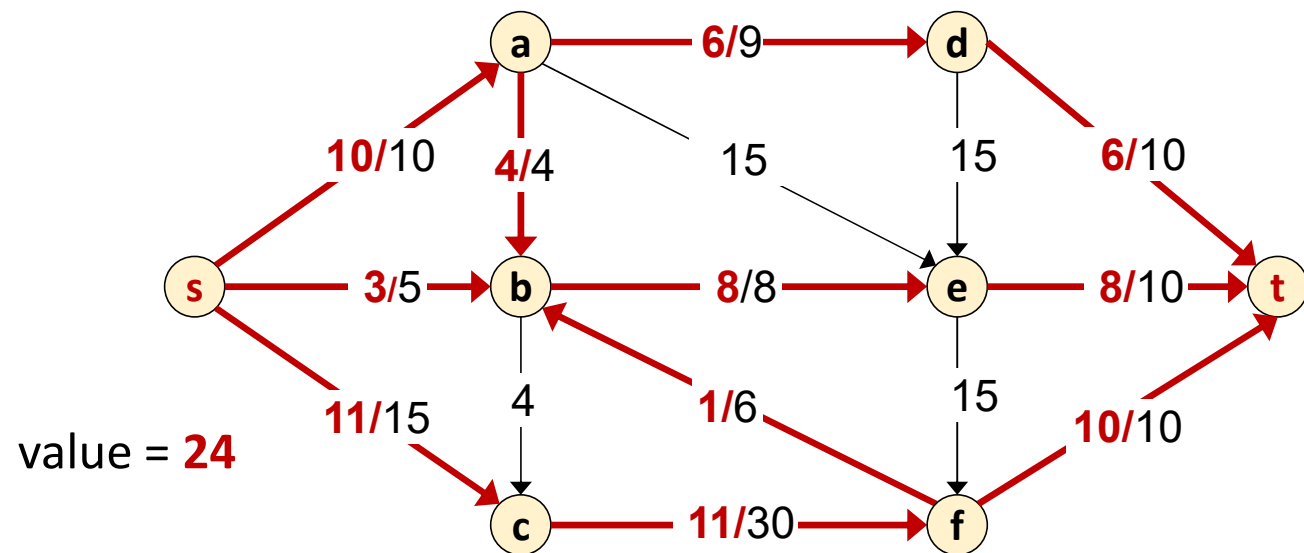


Only show non-zero values of  $f$   
value = **24**

# Maximum Flow Problem

**Given:** a flow network

**Find:** an  $s$ - $t$  flow of maximum value

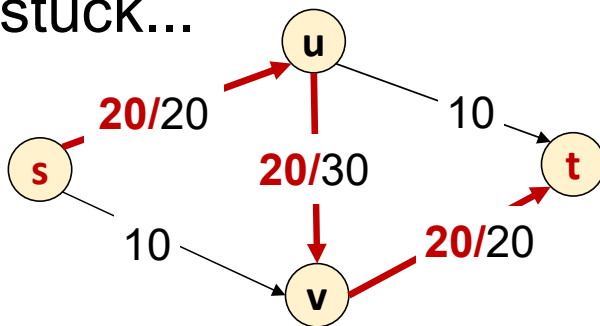


# Towards a Max Flow Algorithm

What about the following greedy algorithm?

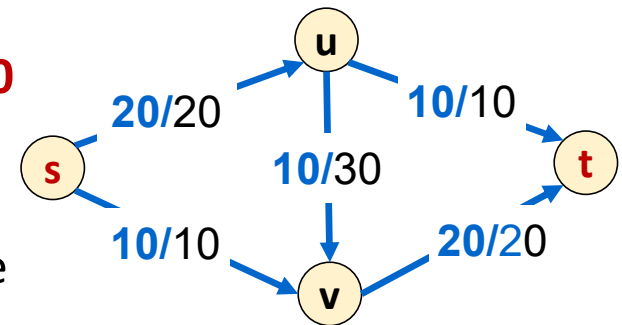
- Start with  $f(e) = 0$  for all edges  $e \in E$ .
- While there is an  $s$ - $t$  path  $P$  where each edge has  $f(e) < c(e)$ .
  - “Augment” flow along  $P$ ; that is:
    - Let  $\alpha = \min_{e \in P} (c(e) - f(e))$
    - Add  $\alpha$  to flow on every edge  $e$  along path  $P$ . (Adds  $\alpha$  to  $v(f)$ .)

Can get stuck...



Has flow value **20**  
and no path  $P$

but **30** is possible

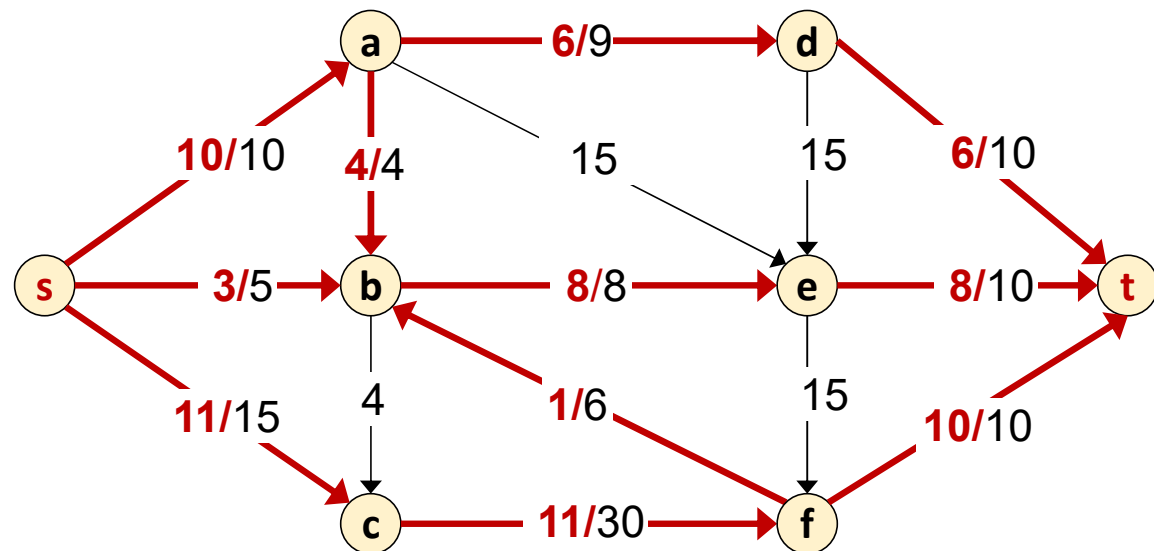




# Another “Stuck” Example

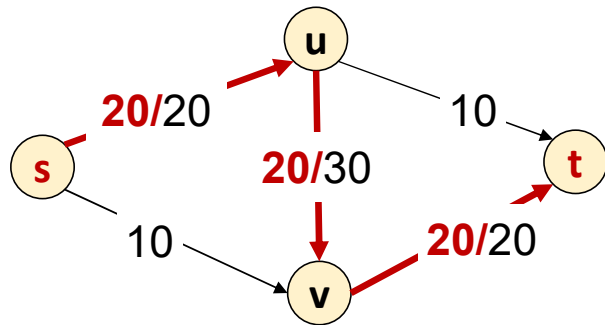
On every  $s-t$  path there is some edge with  $f(e) = c(e)$ :

Value of flow = **24**



**Next idea:** Ford-Fulkerson Algorithm, which applies greedy ideas to a “residual graph” that lets us reverse prior flow decisions from the basic greedy approach to get optimal results!

# Greed Revisited: Residual Graph & Augmenting Paths

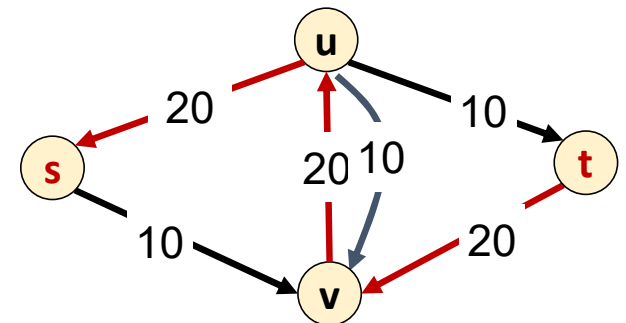


The only way we could route more flow from  $s$  to  $t$  would be to reduce the flow from  $u$  to  $v$  to make room for that amount of extra flow from  $s$  to  $v$ . But to conserve flow we also would need to increase the flow from  $u$  to  $t$  by that same amount.

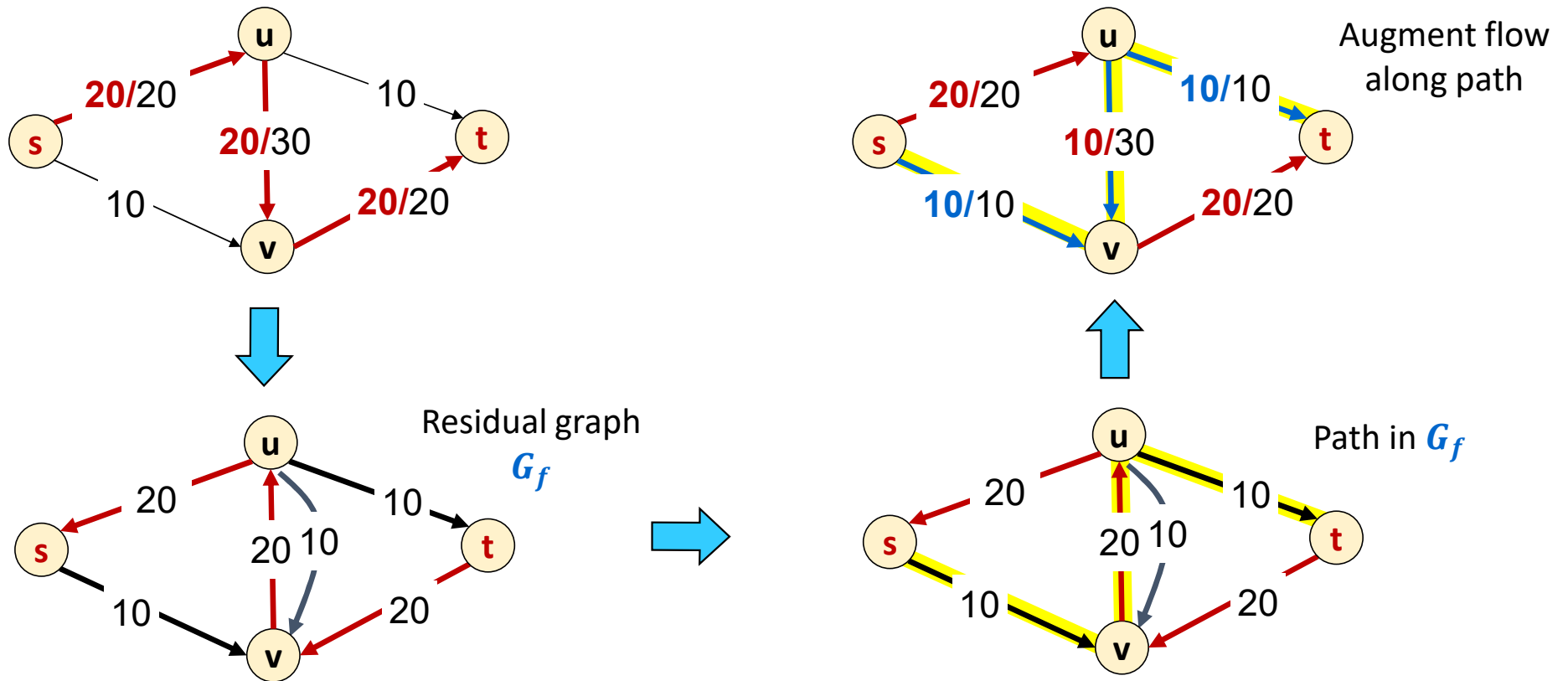
Suppose that we took this flow  $f$  as a baseline, what changes could each edge handle?

- We could add up to 10 units along  $sv$  or  $ut$  or  $uv$
- We could reduce by up to 20 units from  $su$  or  $uv$  or  $vt$

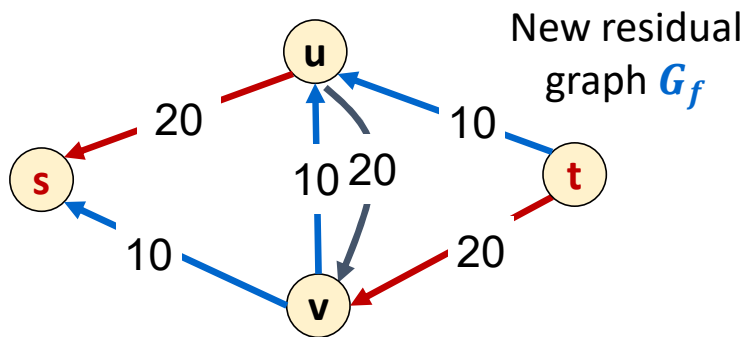
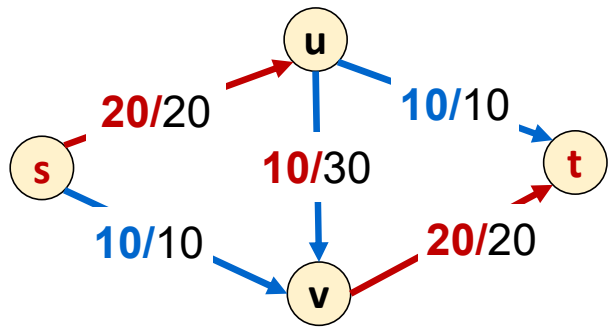
This gives us a **residual graph**  $G_f$  of possible changes where we draw reducing as “sending back”.



# Greed Revisited: Residual Graph & Augmenting Paths



# Greed Revisited: Residual Graph & Augmenting Paths



No path can even leave  $s$ !

# Residual Graphs

An alternative way to represent a flow network

- Represents the net available flow between two nodes

Original edge:  $e = (u, v) \in E$ .

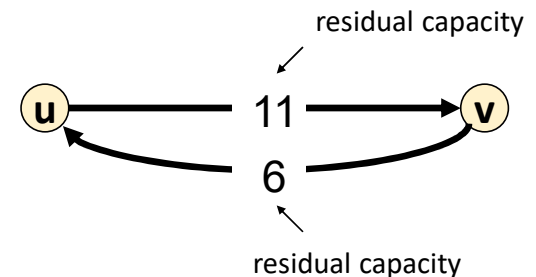
- Flow  $f(e)$ , capacity  $c(e)$ .

Residual edges of two kinds:

- **Forward:**  $e = (u, v)$  with capacity  $c_f(e) = c(e) - f(e)$ 
  - Amount of extra flow we can add along  $e$
- **Backward:**  $e^R = (v, u)$  with capacity  $c_f(e) = f(e)$ 
  - Amount we can reduce/undo flow along  $e$

Residual graph:  $G_f = (V, E_f)$ .

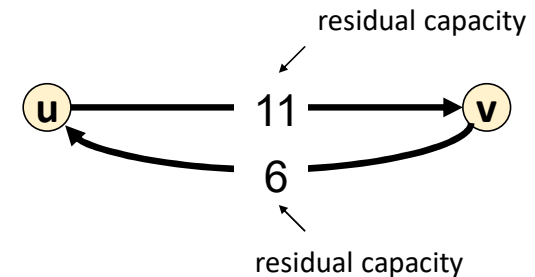
- Residual edges with residual capacity  $c_f(e) > 0$ .
- $E_f = \{e : f(e) < c(e)\} \cup \{e^R : f(e) > 0\}$ .



# Residual Graphs and Augmenting Paths

Residual edges of two kinds:

- **Forward:**  $e = (u, v)$  with capacity  $c_f(e) = c(e) - f(e)$ 
  - Amount of extra flow we can add along  $e$
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Residual graph:  $G_f = (V, E_f)$ .

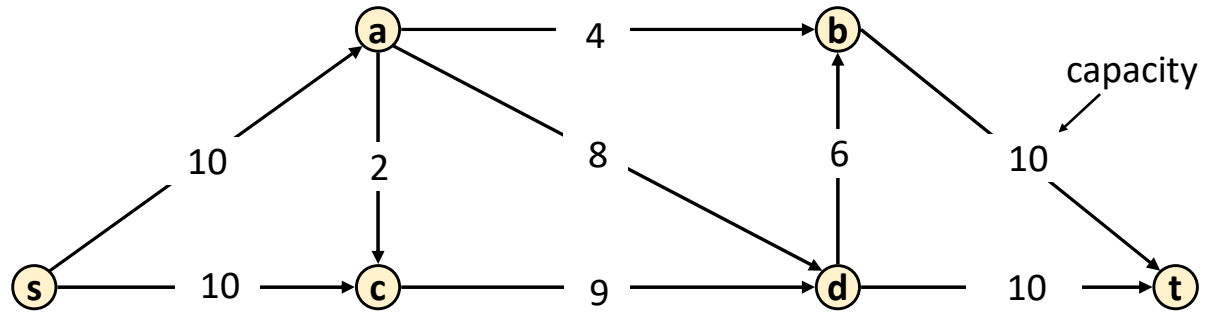
- Residual edges with residual capacity  $c_f(e) > 0$ .
- $E_f = \{e : f(e) < c(e)\} \cup \{e^R : f(e) > 0\}$ .

**Augmenting Path:** Any  $s$ - $t$  path  $P$  in  $G_f$ . Let  $\text{bottleneck}(P) = \min_{e \in P} c_f(e)$ .

**Ford-Fulkerson idea:** Repeat “find an augmenting path  $P$  and increase flow by  $\text{bottleneck}(P)$ ” until none left.

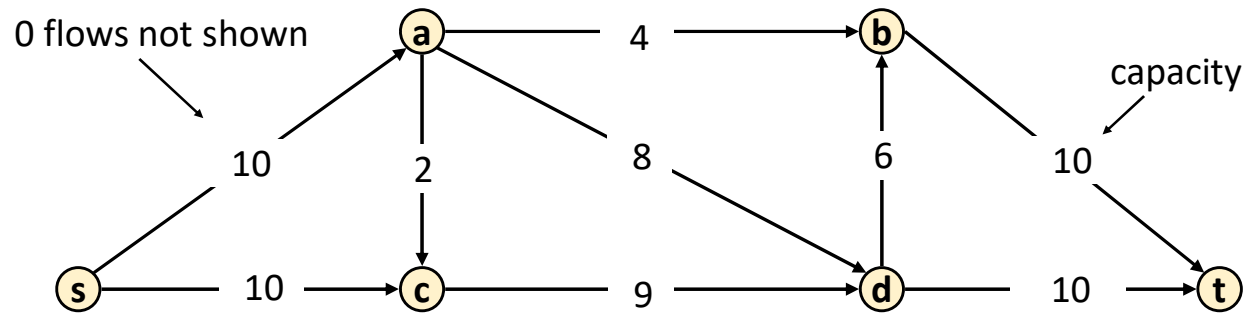
# Ford-Fulkerson Algorithm

*G*:



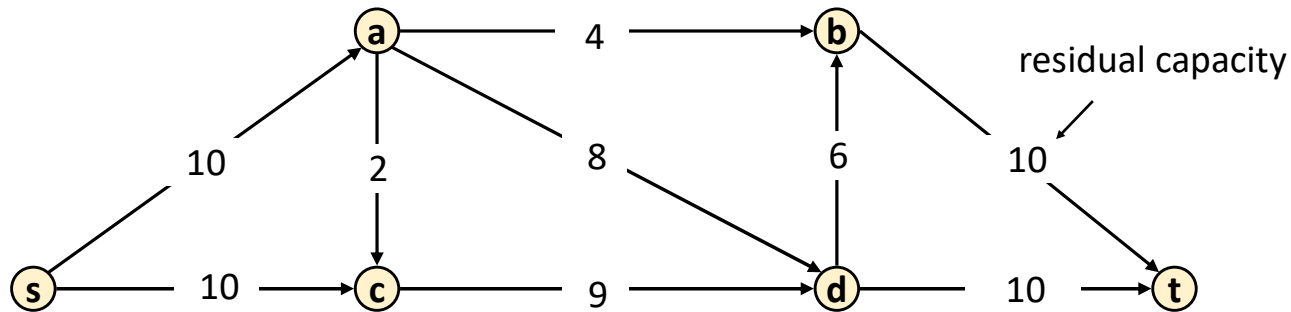
# Ford-Fulkerson Algorithm

$G$ :



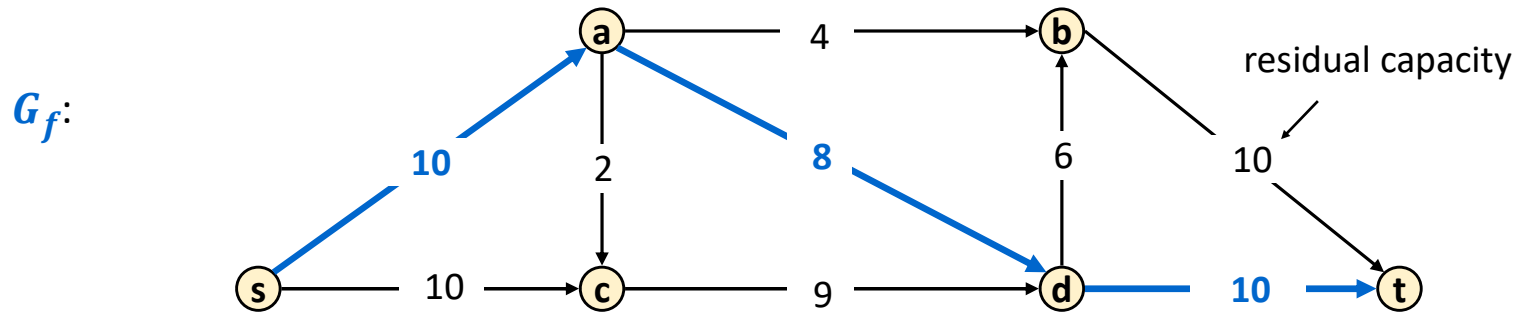
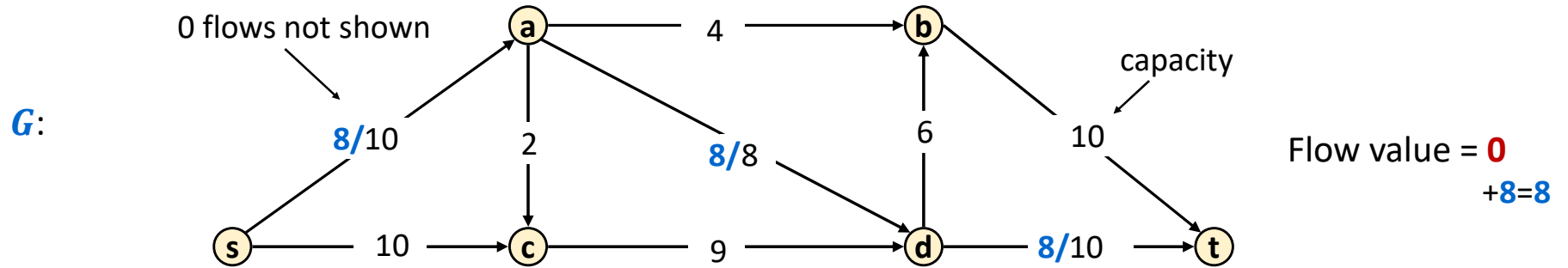
Flow value = 0

$G_f$ :



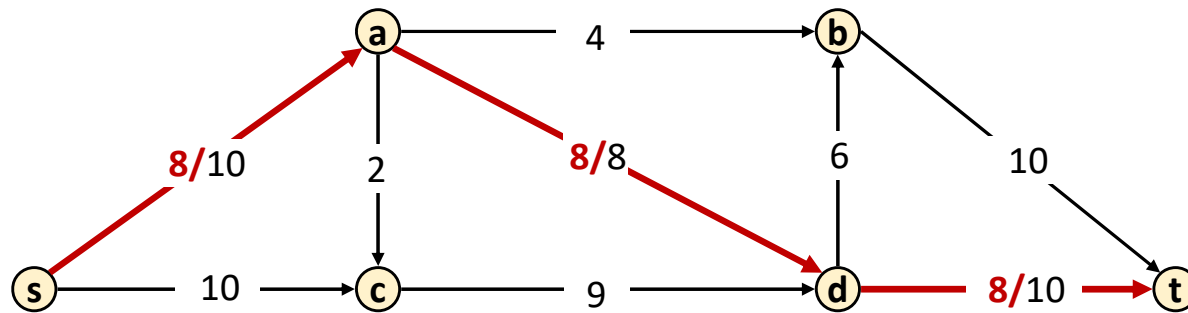


# Ford-Fulkerson Algorithm



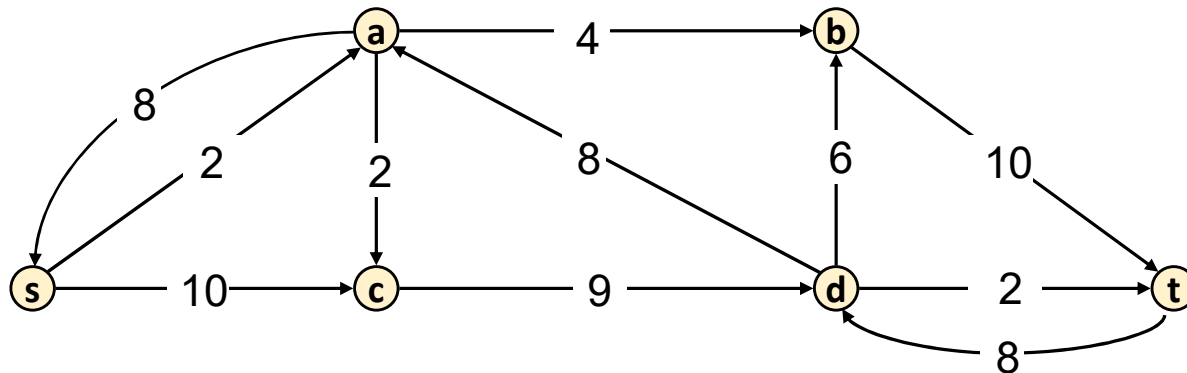
# Ford-Fulkerson Algorithm

$G$ :



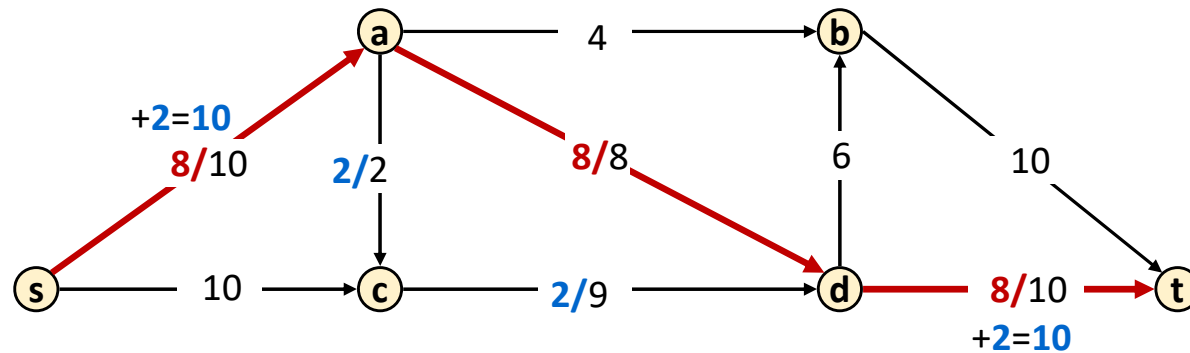
Flow value = 8

$G_f$ :



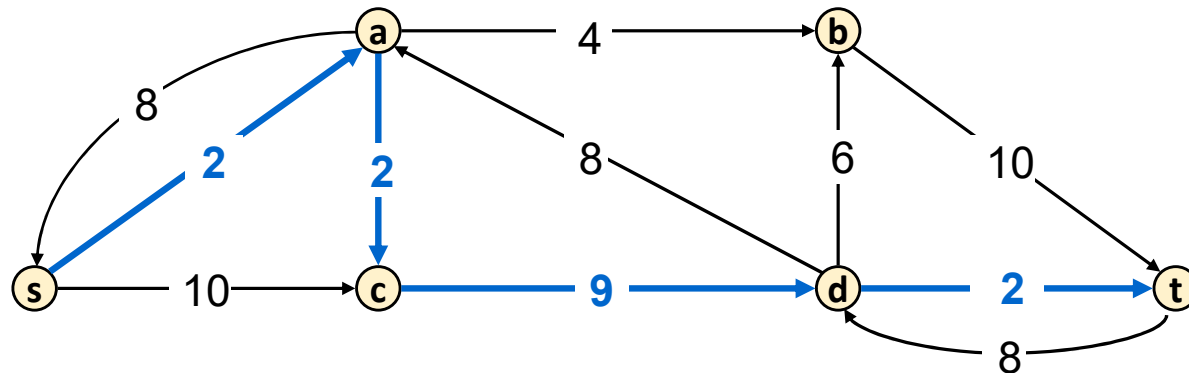
# Ford-Fulkerson Algorithm

$G$ :



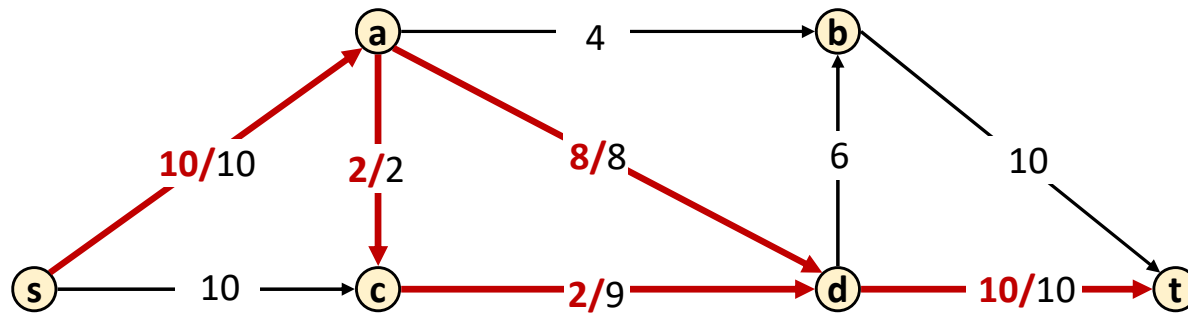
Flow value = **8**  
 $+2=10$

$G_f$ :



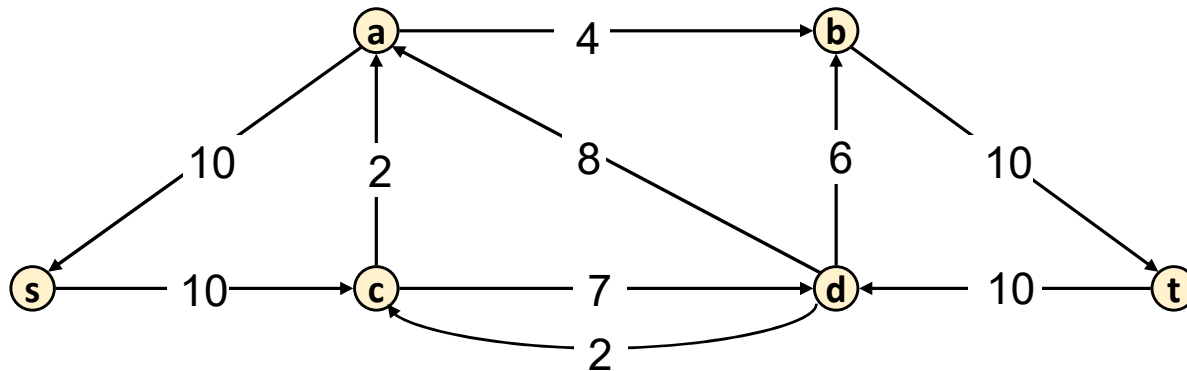
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$G$ :



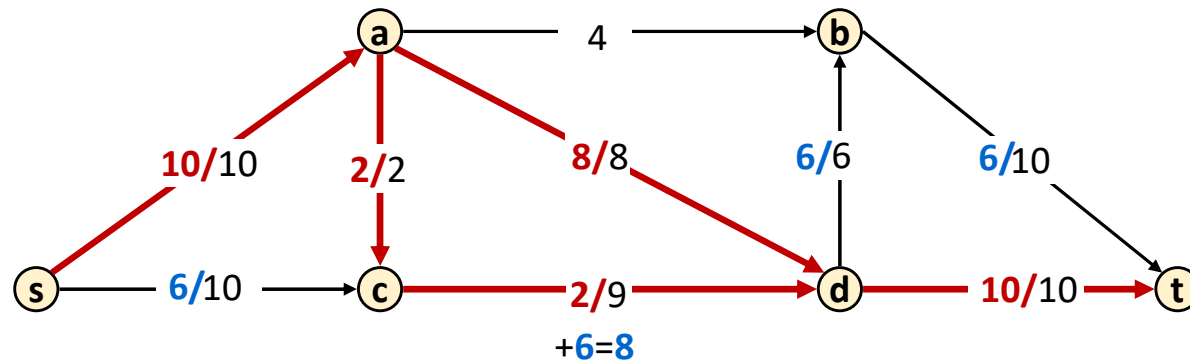
Flow value = **10**

$G_f$ :



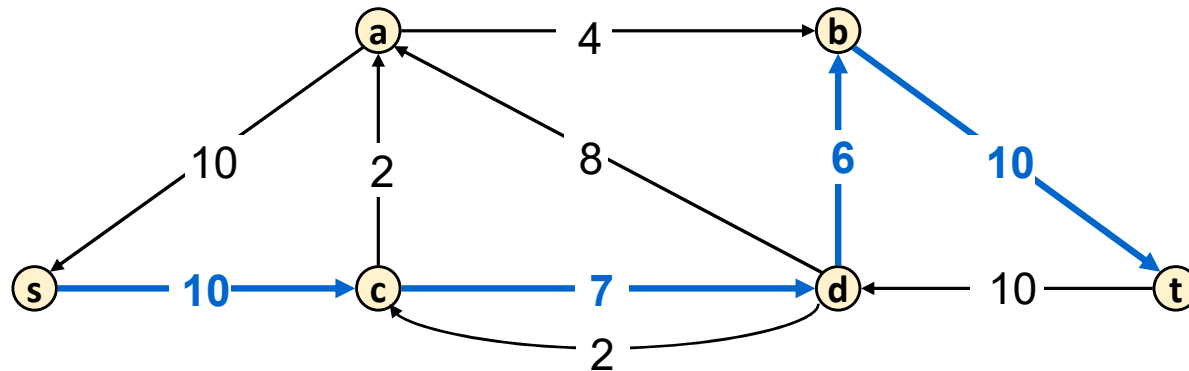
# Ford-Fulkerson Algorithm

$G$ :



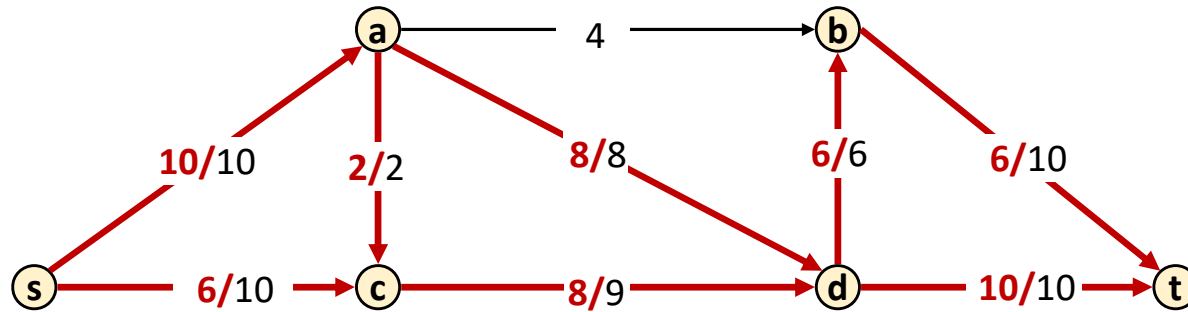
Flow value = **10**  
+**6**=**16**

$G_f$ :



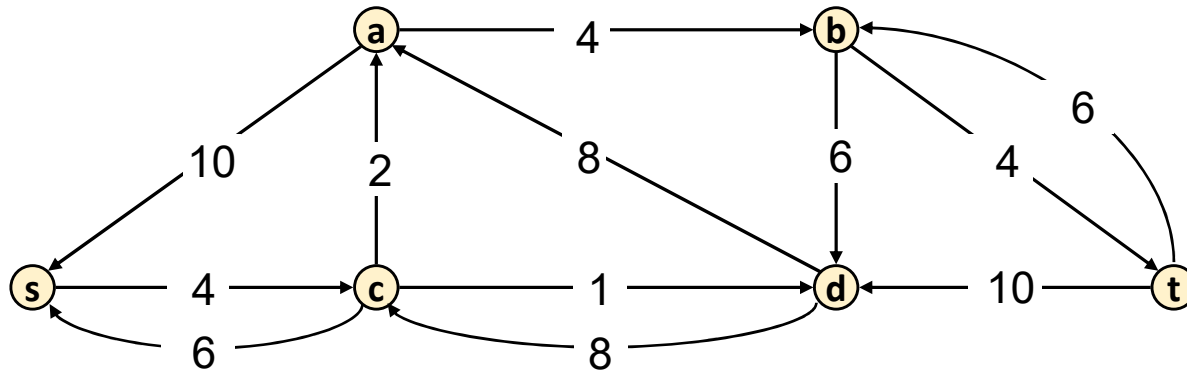
# Ford-Fulkerson Algorithm

$G$ :



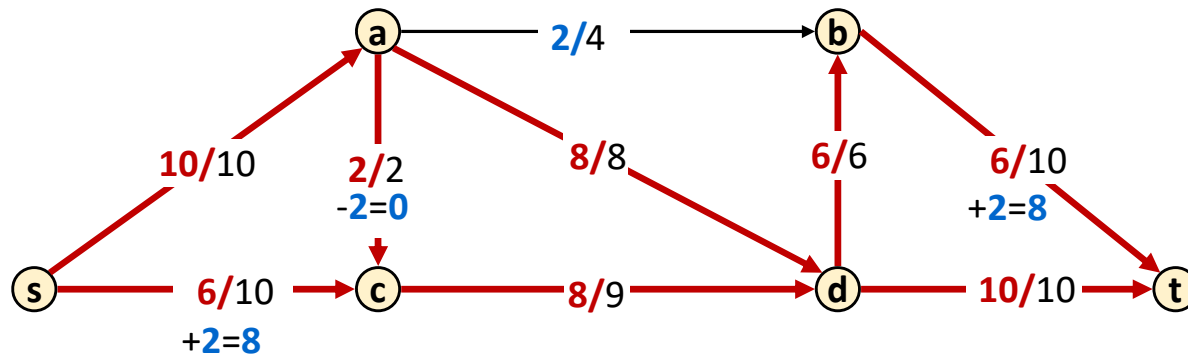
Flow value = **16**

$G_f$ :



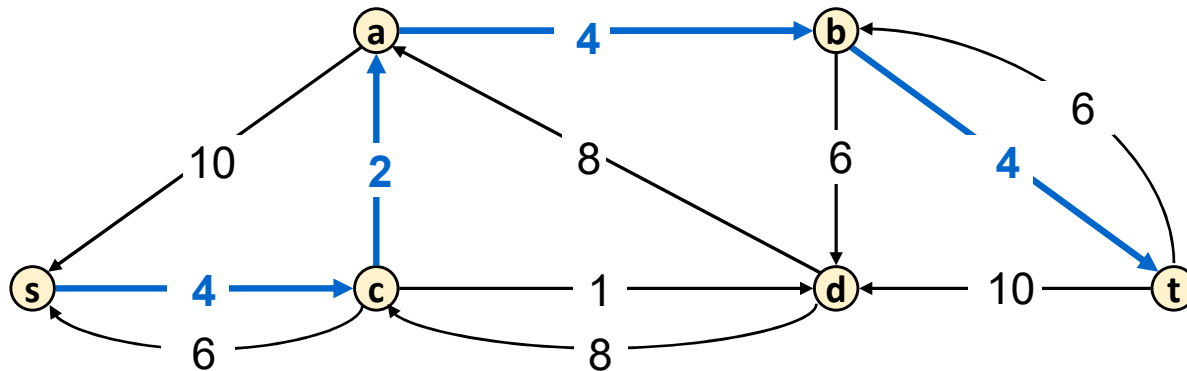
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$G$ :



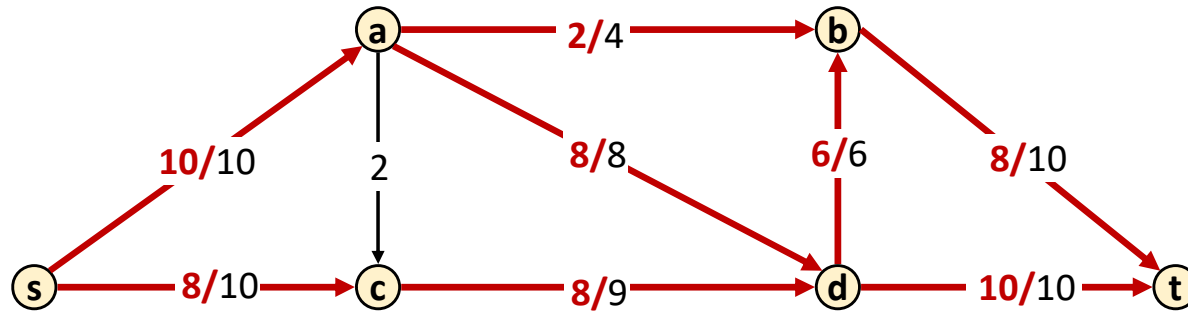
Flow value = **16**  
 $+2=18$

$G_f$ :



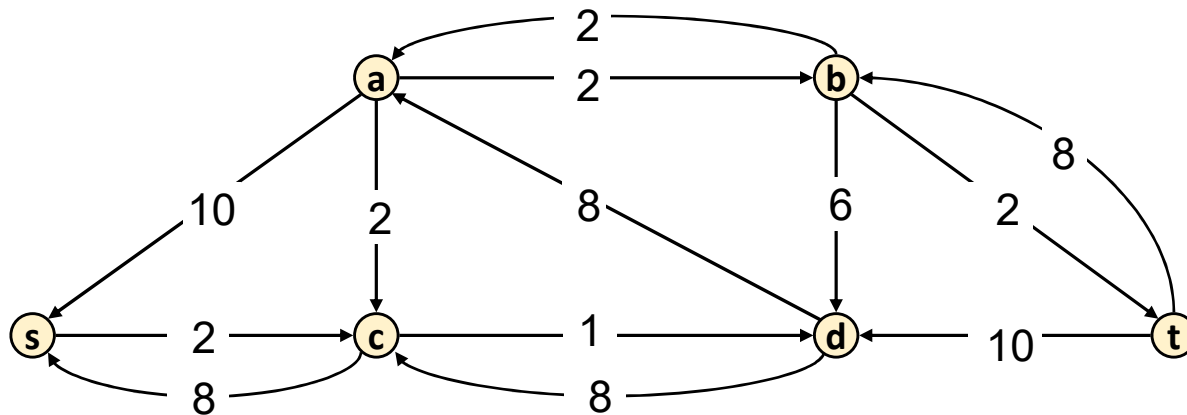
# Ford-Fulkerson Algorithm

$G$ :



Flow value = **18**

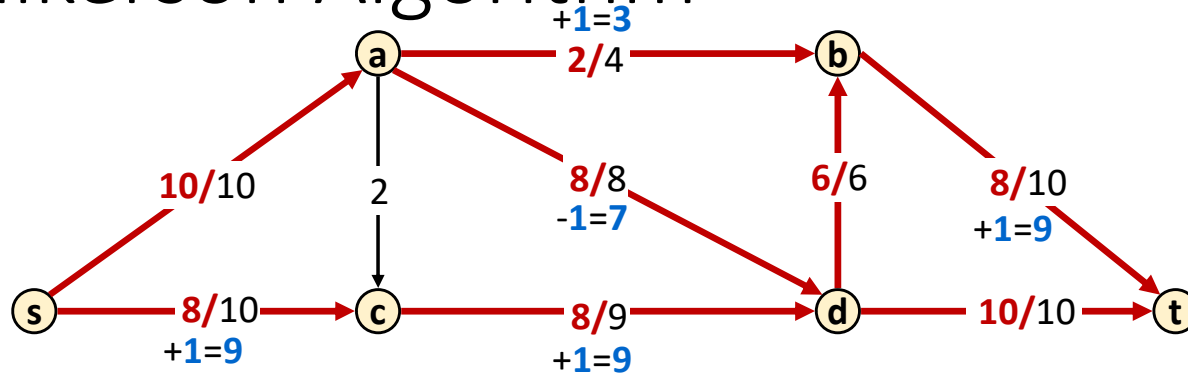
$G_f$ :





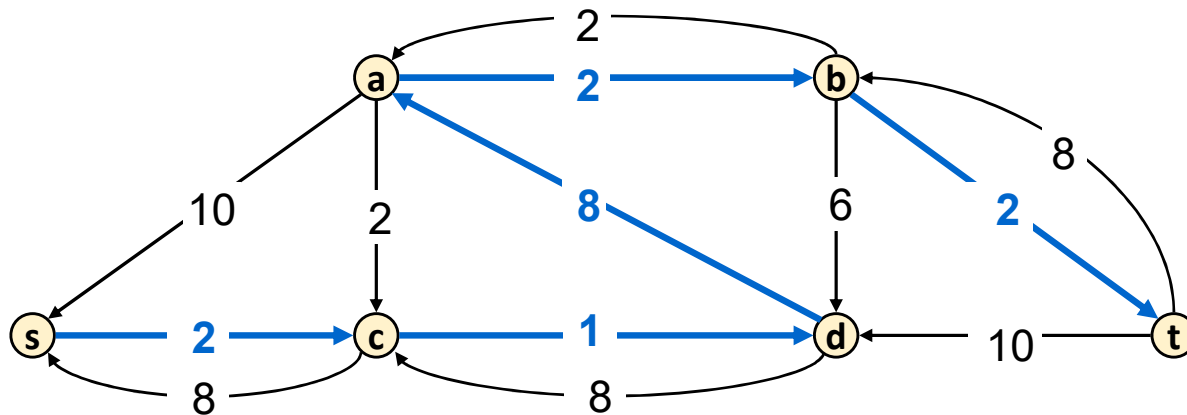
# Ford-Fulkerson Algorithm

$G$ :



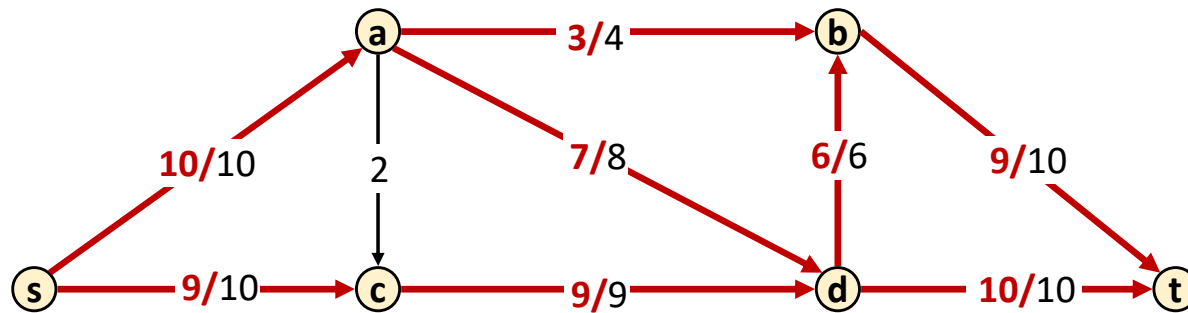
Flow value = **18**  
 $+1=19$

$G_f$ :



# Ford-Fulkerson Algorithm

$G$ :



Flow value = 19

$G_f$ :

