

Lecture 9

Multiplication

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The next couple of weeks

Sunday	Monday	Tuesday	Wednesday	Thursday	Friday	Saturday
	4/21 Lecture 10	Sets 4 & 4 ³ / ₄ released	4/23 Lecture 11 Set 3 due		4/25 Lecture 12	
	4/28 Lecture 13		4/30 Lecture 14 Set 4 due	Midterm Q&A 5:30-7:30pm	5/2 Lecture 15	
	5/5 Midterm	Set 5 released	5/7 Lecture 16 Set 4 ³ / ₄ due		5/9 Lecture 17	
	5/12 Lecture 18		5/14 Lecture 19 Set 5 due		5/16 Lecture 20	

Problem set 4 $\frac{3}{4}$

- A set with one 10 point question
 - The problem is about *dynamic programming*
 - Dynamic programming is covered on the midterm
- It is due on Wednesday May 7th 11:59pm
 - But, I'm posting solutions on Saturday May 3rd (12:01am) before its due
 - You can look at the solution after you upload your solution to Gradescope
 - Not doing so is academic dishonesty. I'm trusting each of you here

Previously in CSE 421...

Principles of divide and conquer

- Identity a division of the problem into a self-similar parts of size n/b
- Recursively solve each subpart of the problem
- Stitch the solutions from each subpart together
- Runtime is defined by the following recursively defined formula:

$$T(n) = a \cdot T\left(\frac{n}{b}\right) + f(n) \text{ and } T(n < b) = O(1)$$

Analysis divide and conquer runtimes

The master theorem

- For solving recursive equations of the form

$$T(n) = a \cdot T\left(\frac{n}{b}\right) + O(n^k) \text{ and } T(n < b) = O(1)$$

- Different cases based on how $f(n)$, a , and b compare:
 - If $a < b^k$, then $T(n) = O(n^k)$
 - If $a = b^k$, then $T(n) = O(n^k \log n)$
 - If $a > b^k$, then $T(n) = O(n^{\log_b a})$

Today: Matrix, integer, and polynomial multiplication

Matrix multiplication

- **Input:** Two matrices $A, B \in \mathbb{R}^{n \times n}$
- **Output:** The matrix $AB \in \mathbb{R}^{n \times n}$

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \cdot \begin{bmatrix} b_{11} & b_{12} & b_{13} \\ b_{21} & b_{22} & b_{23} \\ b_{31} & b_{32} & b_{33} \end{bmatrix} = \begin{bmatrix} c_{11} & c_{12} & c_{13} \\ c_{21} & c_{22} & c_{23} \\ c_{31} & c_{32} & c_{33} \end{bmatrix}$$

where

$$c_{ij} = \sum_k a_{ik} b_{kj}.$$

Trivial algorithm for matrix multiplication

- **Algorithm:**
 - Initialize $n \times n$ array C as zeroes
 - For $i \in [n], j \in [n], k \in [n]$, $C_{ij} \leftarrow C_{ij} + A_{ik} \cdot B_{kj}$
 - Return C .
- **Runtime:** n^3 multiplications + n^3 additions
- Can we improve this with divide and conquer?

Matrix multiplication naturally decomposes

- Matrix multiplication of matrices

$$\begin{array}{|c|c|} \hline A_{11} & A_{12} \\ \hline A_{21} & A_{22} \\ \hline \end{array} \cdot \begin{array}{|c|c|} \hline B_{11} & B_{12} \\ \hline B_{21} & B_{22} \\ \hline \end{array} = \begin{array}{|c|c|} \hline A_{11}B_{11} + A_{12}B_{21} & A_{11}B_{12} + A_{12}B_{22} \\ \hline A_{21}B_{11} + A_{22}B_{21} & A_{21}B_{12} + A_{22}B_{22} \\ \hline \end{array}$$

terms do not commute

- Divide and conquer:

- Decompose into 8 matrix multiplications of $n/2 \times n/2$ matrices and 4 matrix additions of $n/2 \times n/2$ matrices

$$T(n) = 8T\left(\frac{n}{2}\right) + 4\left(\frac{n}{2}\right)^2 \implies T(n) = O(n^{\log_2 8}) = O(n^3)$$

$a = 8$
 $b = 2$
 $k = 2$

$a > b^k$
 leaf-heavy computation

Strassen's divide and conquer (1968)

- Can we decrease the number of mini-multiplications at the cost of increasing the number of mini-additions?
- If we were to somehow decrease to 7 multiplications but 18 additions ...

$$\bullet \quad T(n) = 7T\left(\frac{n}{2}\right) + \frac{18}{4}n^2 \implies T(n) = \frac{18}{4} \cdot O(n^{\log_2 7}) = O(n^{2.8074})$$

- But how do we achieve this decrease?
- **Find repeated terms.**

$$\begin{array}{ll} a = 7 & a > b^k \text{ but} \\ b = 2 & \log_b a \text{ is smaller...} \\ k = 2 & \end{array}$$

A clever decomposition

We know that if

$$\begin{bmatrix} A \end{bmatrix} \cdot \begin{bmatrix} B \end{bmatrix} = \begin{bmatrix} C \end{bmatrix}$$
$$\begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \cdot \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} = \begin{bmatrix} C_{11} & C_{12} \\ C_{21} & C_{22} \end{bmatrix}$$

then $C_{11} = A_{11}B_{11} + A_{12}B_{21}$.

Pictorially, let's represent this fact by

$$C_{11} = \begin{matrix} & \begin{matrix} A_{11} & A_{12} & A_{21} & A_{22} \end{matrix} \\ \begin{matrix} B_{11} \\ B_{12} \\ B_{21} \\ B_{22} \end{matrix} & \begin{array}{|c|c|c|c|} \hline 1 & & & \\ \hline & 1 & & \\ \hline & & & \\ \hline & & & \\ \hline \end{array} \end{matrix}$$

A clever decomposition

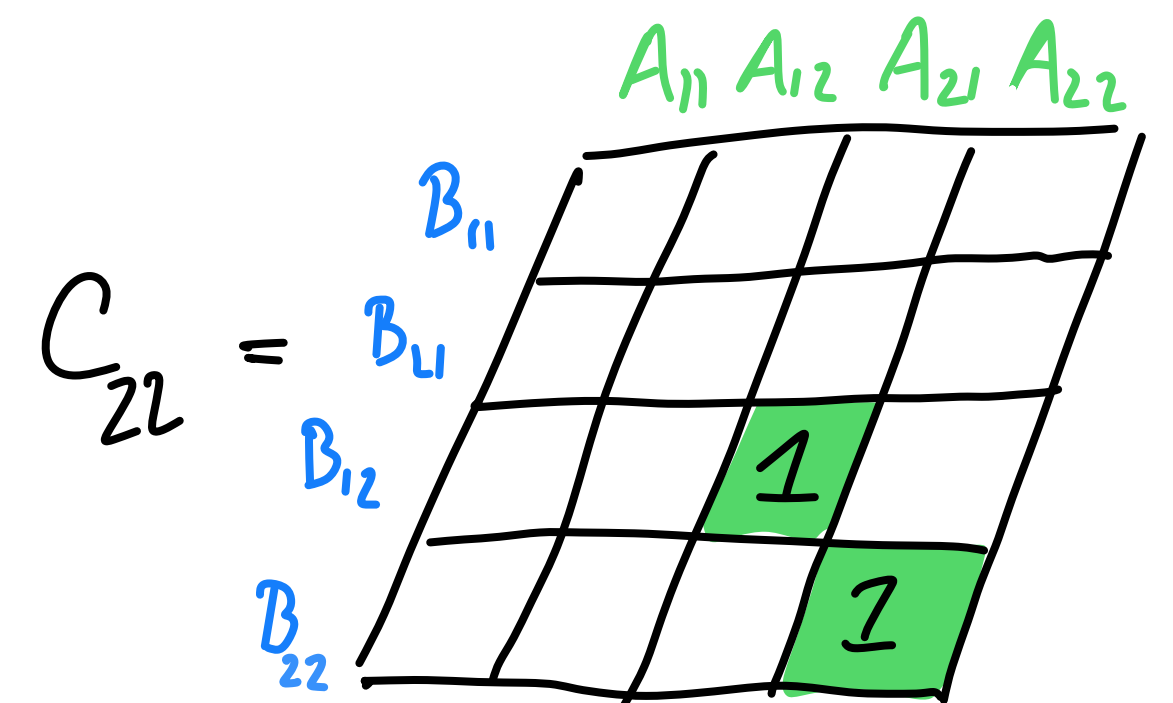
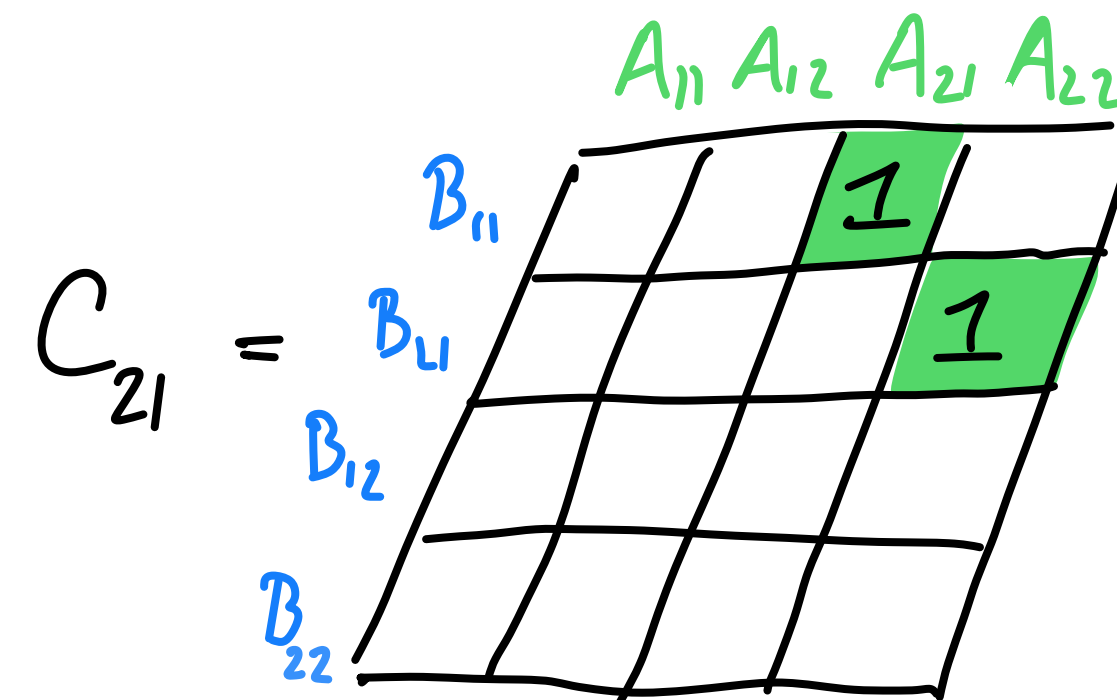
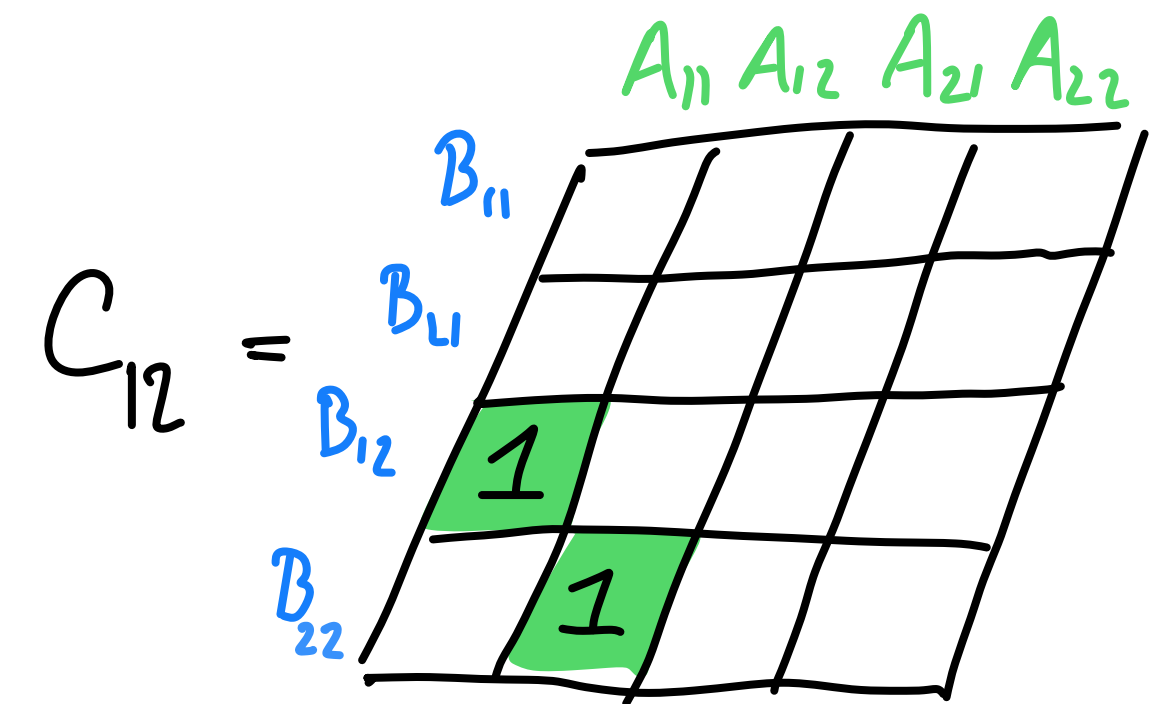
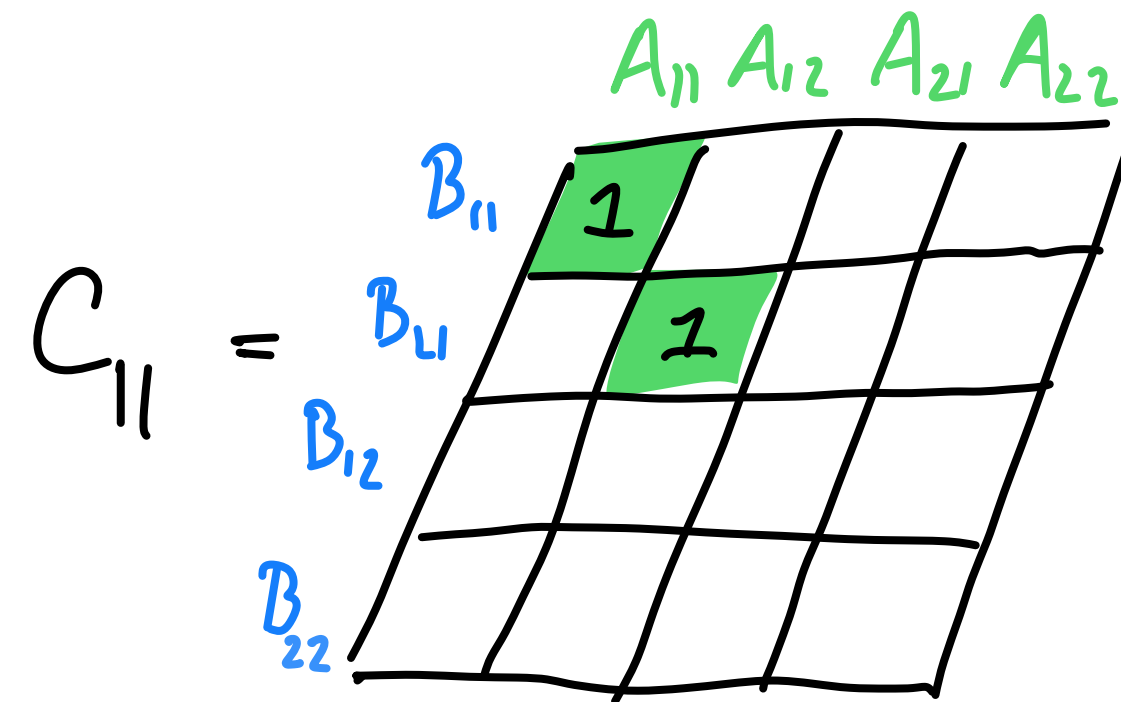
Similarly,

$$C_{11} = A_{11}B_{11} + A_{12}B_{21}$$

$$C_{12} = A_{11}B_{12} + A_{12}B_{22}$$

$$C_{21} = A_{21}B_{11} + A_{22}B_{21}$$

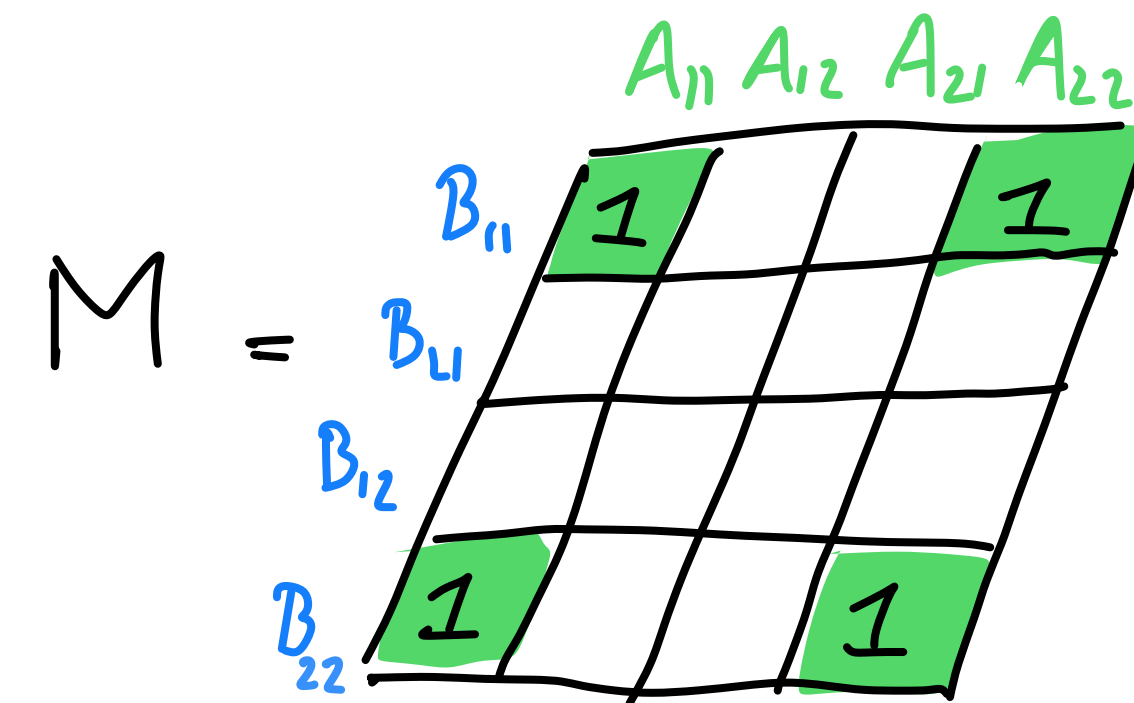
$$C_{22} = A_{21}B_{12} + A_{22}B_{22}$$



A clever decomposition

Now, what happens if we want to calculate

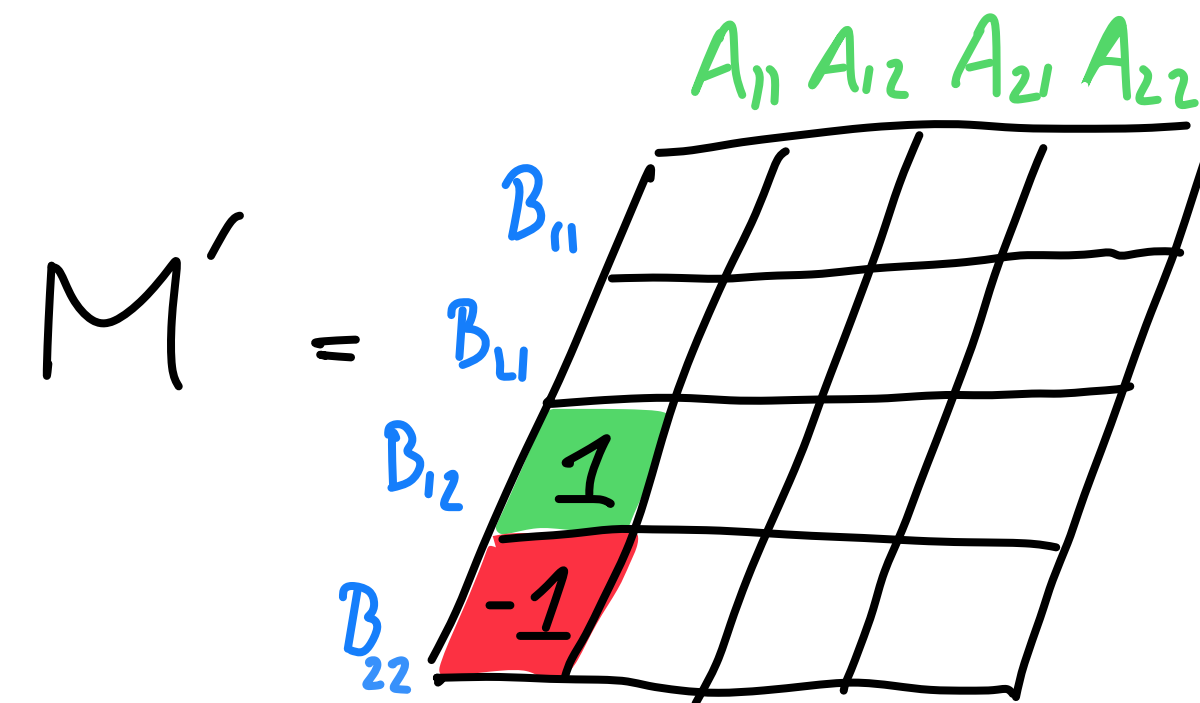
$$\begin{aligned} M &= (A_{11} + A_{22})(B_{11} + B_{22}) \\ &= A_{11}B_{11} + A_{11}B_{22} + A_{22}B_{11} + A_{22}B_{22} \end{aligned}$$



A clever decomposition

Another example...

$$\begin{aligned} M' &= A_{11} (B_{12} - B_{22}) \\ &= A_{11} B_{12} - A_{11} B_{22} \end{aligned}$$

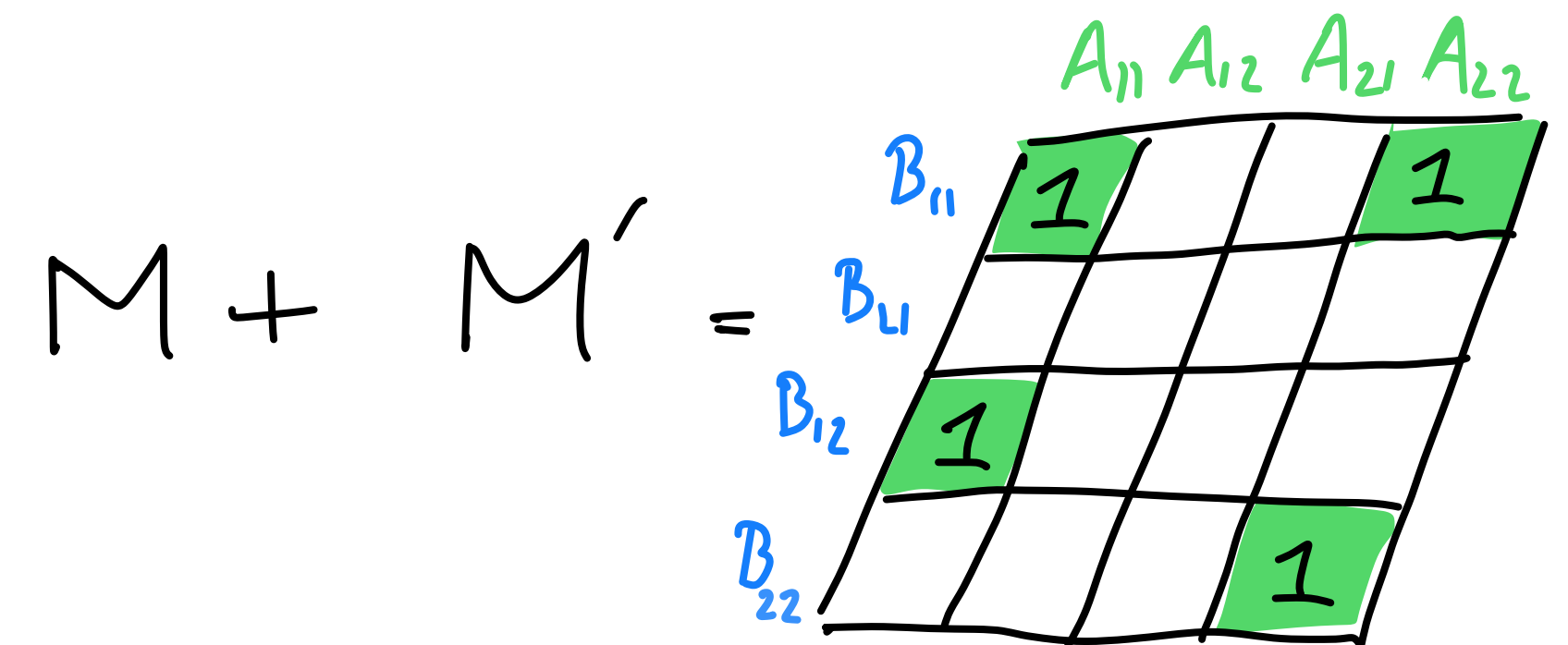
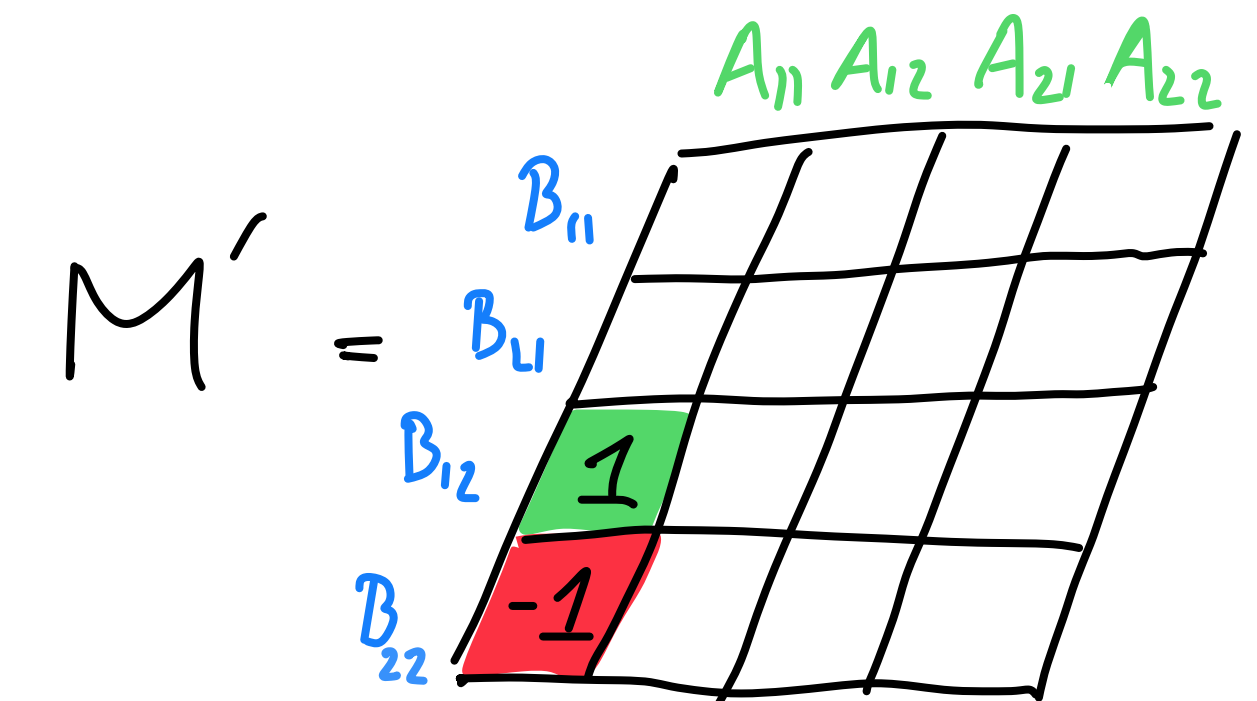
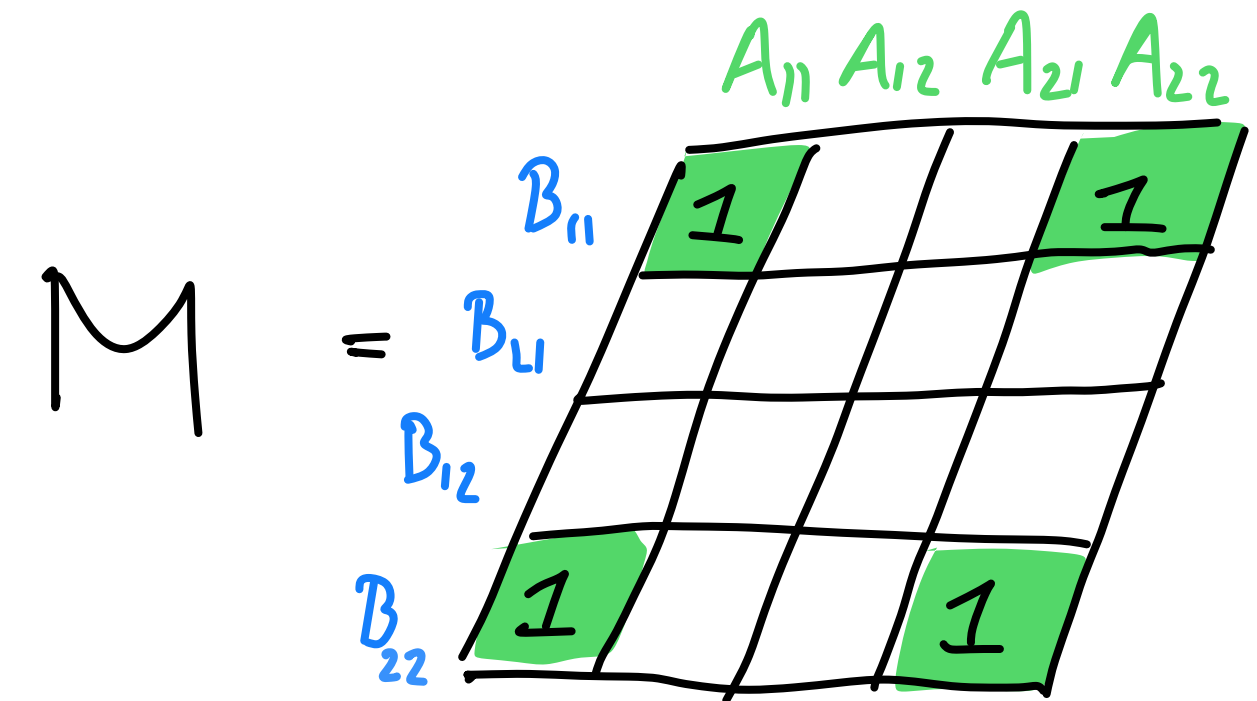


A clever decomposition

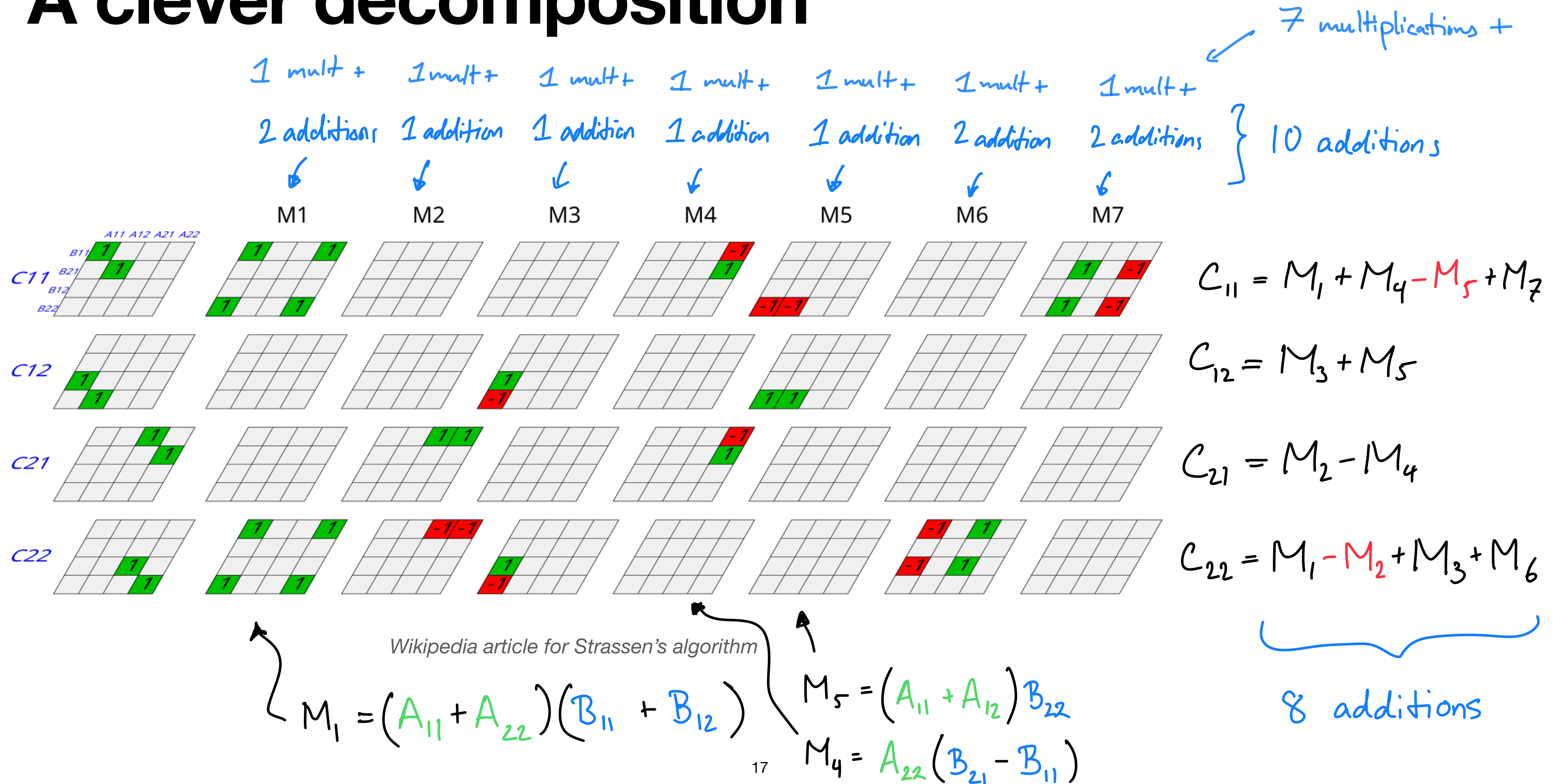
We can add these diagrams...

$$M = (A_{11} + A_{22})(B_{11} + B_{22})$$

$$M' = A_{11}(B_{12} - B_{22})$$



A clever decomposition



Strassen's algorithm details

- Best for matrices of size $2^m \times 2^m$. Pad the matrix with zeroes until it is.
- Strassen's has 18 mini-additions. Only beneficial if $n \geq 32$.
 - For smaller matrices, use $O(n^3)$ algorithm.
 - Still a base case for the recursive definition. Only adjust $O(\cdot)$ constants.
- Is there an even cleverer decomposition into fewer mini-multiplications?
 - Not for dividing into $n/2 \times n/2$ mini-matrices
 - Other divisions plus clever tricks have gotten algorithms down to $O(n^{2.371339})$ [May 2024]
 - **Major open question:** $O(n^{2+\epsilon})$ time algorithm possible for all $\epsilon > 0$.

Integer multiplication

- **Input:** Two n -bit binary numbers $x, y \in \{0, \dots, 2^n - 1\}$
- **Output:** A $2n$ -bit binary number
 - Complexity is not measured in RAM model
 - Instead by number of binary operations required.

$$\begin{array}{r}
 \\
 \\
 \\
 \\
 \times 1 \\
 \hline
 1 \\
 0 \\
 1 \\
 + 1 \\
 \hline
 1
 \end{array}$$

- Gradeschool multiplication algorithm takes $O(n^2)$ time

The Karatsuba method

$$\boxed{x_1} \boxed{x_0} \times \boxed{y_1} \boxed{y_0}$$

$$= (2^{n/2} x_1 + x_0)(2^{n/2} y_1 + y_0)$$

$$= 2^n x_1 y_1 + 2^{n/2} (x_1 y_0 + x_0 y_1) + x_0 y_0$$

$$= 2^n \left(\boxed{x_1} \times \boxed{y_1} \right) + 2^{n/2} \left(\boxed{x_1} \times \boxed{y_0} + \boxed{x_0} \times \boxed{y_1} \right) + \boxed{x_0} \times \boxed{y_0}$$

↑ left shifts ↑

$$T(n) = 4T\left(\frac{n}{2}\right) + O(n) \implies T(n) = O(n^{\log_2 4}) = O(n^2)$$

no improvements.

The Karatsuba method

$$\boxed{x_1 \quad x_0} \times \boxed{y_1 \quad y_0}$$

$$= (2^{n/2} x_1 + x_0)(2^{n/2} y_1 + y_0)$$

$$= 2^n x_1 y_1 + 2^{n/2} (x_1 y_0 + x_0 y_1) + x_0 y_0.$$

$$= 2^n x_1 y_1 + 2^{n/2} \left((x_1 + x_0)(y_1 + y_0) - x_1 y_1 - x_0 y_0 \right) + x_0 y_0.$$

Identify 3 multiplications of size $\frac{n}{2}$

$$T(n) = 3T\left(\frac{n}{2}\right) + O(n) \implies T(n) = O(n^{\log_2 3}) = O(n^{1.58})$$

Improving integer multiplication

- Fast integer multiplication is used in high-precision arithmetic
- Storing a number to n -bits of precision is equal to 2^{-n} precision
- Karatsuba's algorithm is not the fastest
 - Fastest is $O(n \log n)$ based on the fast Fourier transform (next!)
 - These are galactic algorithms (not useful in practice)

Polynomial multiplication

- **Input:** polynomials $p, q \in \mathbb{C}[x]$ of $\deg < n$ expressed by their coefficients

i.e.

$$\begin{aligned} p(x) &= a_{n-1}x^{n-1} + a_{n-2}x^{n-2} + \dots + a_1x + a_0 \\ q(x) &= b_{n-1}x^{n-1} + b_{n-2}x^{n-2} + \dots + b_1x + b_0 \end{aligned}$$

- **Output:** The poly. $pq \in \mathbb{C}[x]$ of $\deg < 2n - 1$ expressed in coefficients.

$$pq(x) = c_{2n-1}x^{2n-1} + c_{2n-2}x^{2n-2} + \dots + c_1x + c_0 \text{ where } c_j = \sum_{k=0}^j a_k b_{j-k}$$

Why is polynomial multiplication useful?

- This algorithm is used as a subroutine in
 - signal processing, image processing, audio compression
 - Many public-key cryptosystems rely on polynomial arithmetic
 - Computing Reed-Solomon (5G) error-correcting codes
 - Polynomial-based error-detection codes
- The major subroutine is equivalent to **convolution**, a fundamental mathematical computation

Polynomial multiplication

- **Output:** The poly. $pq \in \mathbb{C}[x]$ of $\deg < 2n - 1$ expressed in coefficients.

$$pq(x) = c_{2n-1}x^{2n-1} + c_{2n-2}x^{2n-2} + \dots + c_1x + c_0 \text{ where } c_j = \sum_{k=0}^j a_k b_{j-k}$$

- Can be solved using $1 + 2 + \dots + n + \dots + 2 + 1 = O(n^2)$ multiplications
- Can we be any faster? Perhaps using divide and conquer?

When is polynomial multiplication fast?

- **Fundamental theorem of algebra:** A degree $< n$ polynomial p is **uniquely** specified by *any* n distinct evaluation points.
 - Let $\xi_1, \xi_2, \dots, \xi_n \in \mathbb{C}$ be distinct. Then $\{(\xi_i, p(\xi_i))\}$ uniquely define p .
- Let p be the poly defined by $\{(\xi_i, y_i)\}$.
Let q be the poly defined by $\{(\xi_i, z_i)\}$.
For every x , $(pq)(x) = p(x) \cdot q(x)$. So, $(pq)(\xi_i) = y_i \cdot z_i$.
- Then pq is a poly defined by $\{(\xi_i, y_i \cdot z_i)\}$.

↑
degree $< 2n$ poly

↑ only n interpolation points.

When is polynomial multiplication fast?

- **Fundamental theorem of algebra:** A degree $< n$ polynomial p is **uniquely** specified by *any* n distinct evaluation points.
 - Let $\xi_1, \xi_2, \dots, \xi_{2n} \in \mathbb{C}$ be distinct. Then $\{(\xi_i, p(\xi_i))\}_{i \in [2n]}$ uniquely define p .
- Let p be the poly defined by $\{(\xi_i, y_i)\}_{i \in [2n]}$.
Let q be the poly defined by $\{(\xi_i, z_i)\}_{i \in [2n]}$.
- Then pq is the **unique** poly defined by $\{(\xi_i, y_i \cdot z_i)\}_{i \in [2n]}$.

Polynomial multiplication algorithm

- **New algorithm:**

- Pick evaluation points ξ_1, \dots, ξ_{2n} .

compute $\xi_i^1, \xi_i^2, \xi_i^3, \dots, \xi_i^n$ in time $O(n)$
compute $p(\xi_i) = \sum_{j=0}^n a_j \xi_i^j$ in time $O(n)$.

- Evaluate p and q to compute $y_i \leftarrow p(\xi_i), z_i \leftarrow q(\xi_i)$ for $i \in [2n]$.

- Calculate $w_i \leftarrow y_i \cdot z_i$. $\leftarrow O(n)$ total time.

- Compute the coefficients of polynomial uniquely defined by $\{(\xi_i, w_i)\}_{i \in [2n]}$.

↑ we still haven't discussed how to do this.

this is prohibitive. We need to do this faster to improve on naïve alg.

Polynomial multiplication algorithm

- **New idea:** Pick interpolation points $\{\xi_j\}$ intelligently.
 - If done correctly, we can speed up computing $p(\xi_j), q(\xi_j)$.
 - Also will give us a way of un-doing interpolation after multiplication.
- Choose related points to parallelize the computation
- Writing down all the partial computations will take too long

Change of basis

- Let's observe that $p(\xi) = \sum_{j=0}^{2n} a_j \xi^j$ is the **inner product** between two vectors.

- $$p(\xi) = \underbrace{\begin{bmatrix} 1 & \xi & \xi^2 & \dots & \xi^{2n} \end{bmatrix}}_{\text{only depends on } \xi \text{ and not polynomial coefficients.}} \cdot \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{2n} \end{bmatrix}$$

set $a_{n+1} = \dots = a_{2n} = 0$
This only depends on the polynomial coefficients and not ξ .

Change of basis

$$\begin{bmatrix} p(\xi_1) \\ p(\xi_2) \\ \vdots \\ p(\xi_{2n}) \end{bmatrix} = \overbrace{\begin{bmatrix} 1 & \xi_1 & \xi_1^2 & \dots & \xi_1^{2n} \\ 1 & \xi_2 & \xi_2^2 & \dots & \xi_2^{2n} \\ \vdots & & & \ddots & \vdots \\ 1 & \xi_{2n} & \xi_{2n}^2 & \dots & \xi_{2n}^{2n} \end{bmatrix}}^V \cdot \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ \vdots \\ a_{2n} \end{bmatrix}$$

↑ special type of matrix called
a Vandermonde matrix

$$\det V = \prod_{i \neq j} (\xi_i - \xi_j) \quad \leftarrow \begin{array}{l} \text{non-zero iff } \xi_i \text{ are distinct.} \\ \text{if } \det V \text{ is non-zero, } V \text{ is invertible.} \end{array}$$

Polynomial multiplication algorithm

- **New new algorithm:**

- Pick interpolation points $\{\xi_j\}_{j \in [2n]}$.
- Compute Vandermonde matrix V and its inverse V^{-1} .
- Compute $\vec{y} \leftarrow V\vec{a}, \vec{z} \leftarrow V\vec{b}$.
- Compute $\vec{w} \leftarrow \vec{a} \odot \vec{b}$, point-wise multiplication.
- Return $V^{-1}\vec{w}$.

Still too slow if
we are spending the
time writing out V and
 V^{-1} . Need to do the
 $V\vec{a}, V\vec{b}, V^{-1}\vec{w}$
computations "in place".

Choice of interpolation points

- To speed up the algorithm, we are going to pick $\{\xi_j\}$ creatively.
- Let m be the smallest power of 2 that is $\geq 2n$.
- Choose $\omega := e^{2\pi i/m}$, a primitive m -th root of unity.
- Define $\xi_j = \omega^{j-1}$.

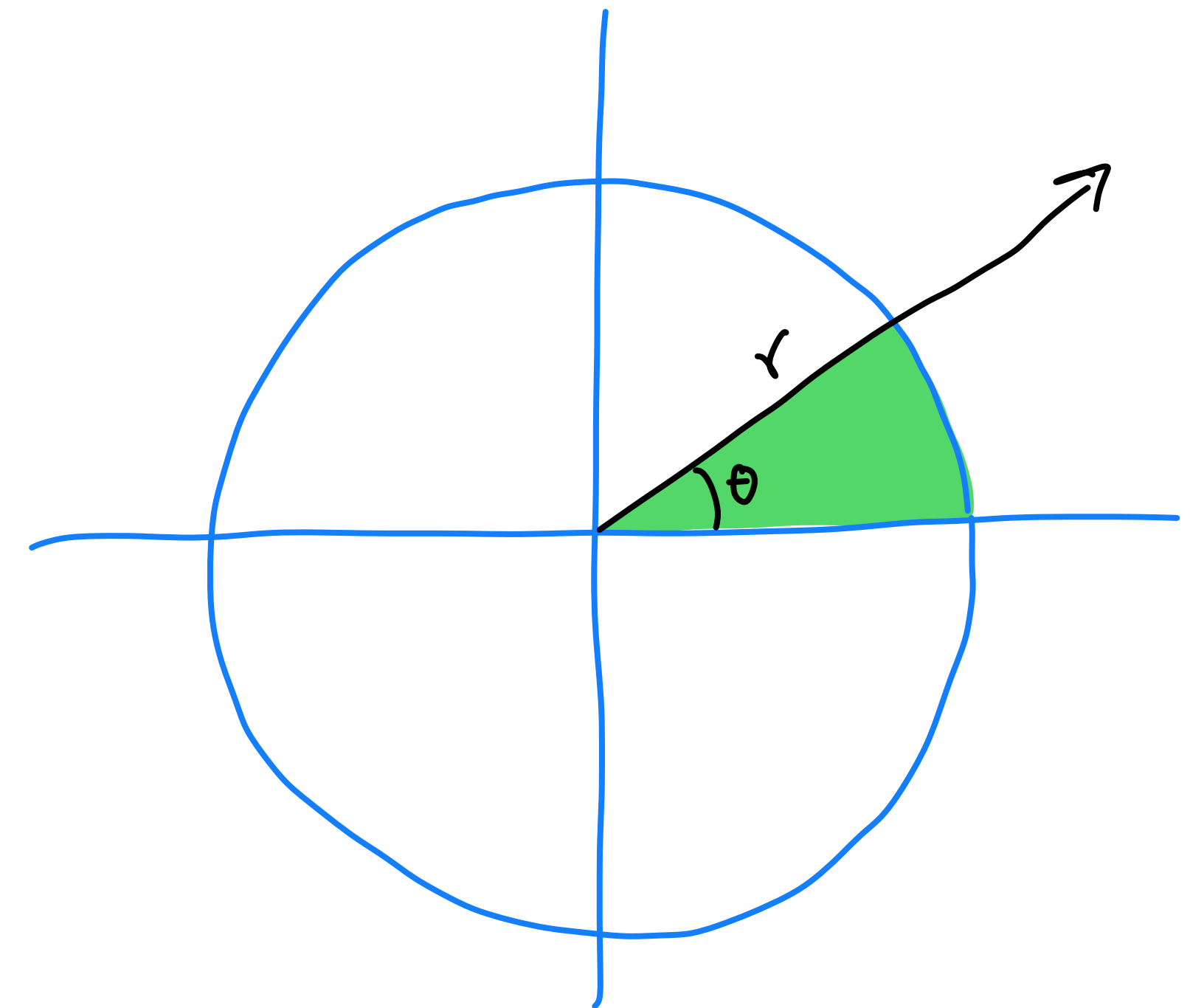
$$V = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & \omega & \omega^2 & \dots & \omega^{m-1} \\ 1 & \omega^2 & \omega^4 & \dots & \omega^{2(m-1)} \\ 1 & \omega^3 & \omega^6 & \dots & \omega^{3(m-1)} \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 1 & \omega^{m-1} & \omega^{2(m-1)} & \dots & \omega^{(m-1)^2} \end{bmatrix}$$

known as $F_m(\omega)$, the Fourier transform over \mathbb{Z}/m .

Complex number review

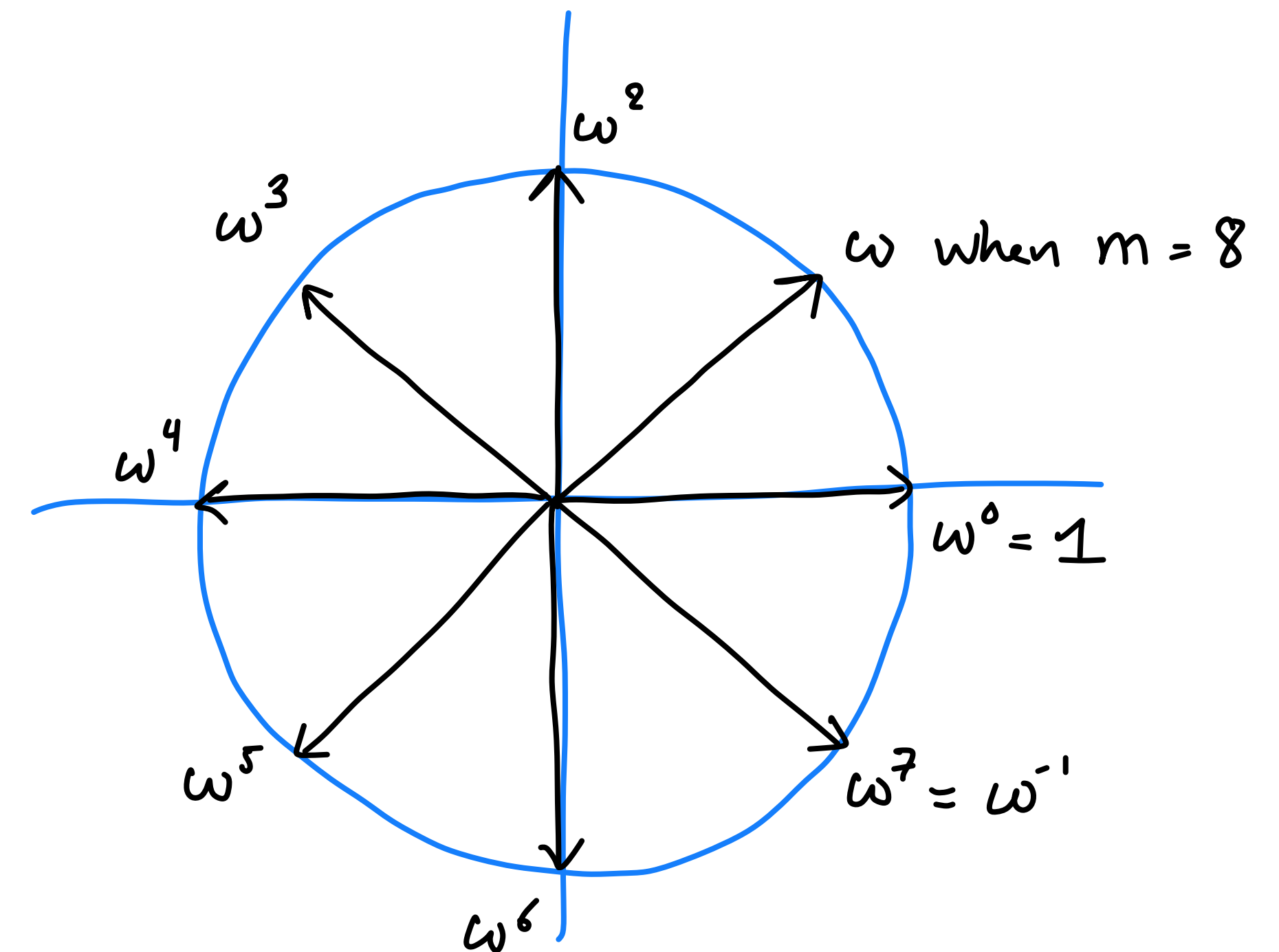
- A complex number can be expressed as $a + bi$ with $a, b \in \mathbb{R}$
- Alternatively, it can be expressed as $re^{i\theta}$ with $r \in \mathbb{R}^{\geq 0}, \theta \in [0, 2\pi)$
- Multiplying complex numbers is easy

$$((r_1 e^{i\theta_1})(r_2 e^{i\theta_2}) = (r_1 r_2) e^{i(\theta_1 + \theta_2)})$$



Complex number review

- A complex number can be expressed as $a + bi$ with $a, b \in \mathbb{R}$
- Alternatively, it can be expressed as $re^{i\theta}$ with $r \in \mathbb{R}^{\geq 0}, \theta \in [0, 2\pi)$
- Multiplying complex numbers is easy
$$((r_1 e^{i\theta_1})(r_2 e^{i\theta_2}) = (r_1 r_2) e^{i(\theta_1 + \theta_2)})$$
- ω , the m -th root of unity can be expressed as $r = 1, \theta = 2\pi/m$



Polynomial multiplication algorithm

- **New new new algorithm:**

- Let m be the smallest power of 2 that is $\geq 2n$. $\omega = e^{2\pi i/m}$.

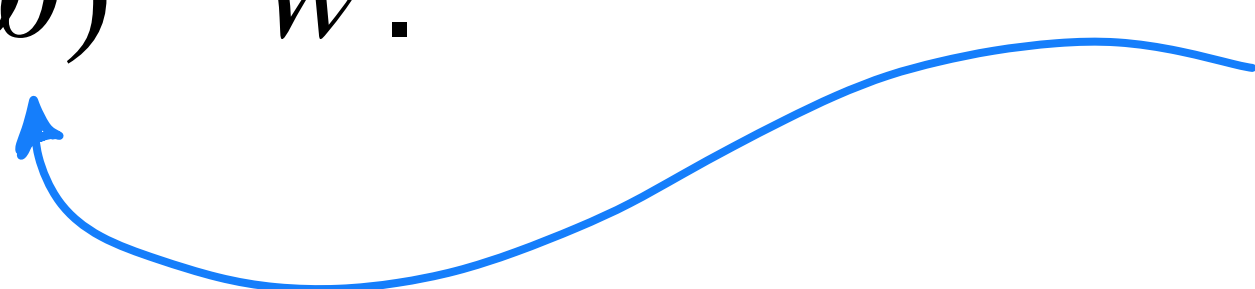
- Pad vectors \vec{a} and \vec{b} with zeroes till length m .

- Compute $\vec{y} \leftarrow F_m(\omega)\vec{a}, \vec{z} \leftarrow F_m(\omega)\vec{b}$.

- Compute $\vec{w} \leftarrow \vec{a} \odot \vec{b}$, point-wise multiplication.

- Return $F_m(\omega)^{-1}\vec{w}$.

Theorem: $F_m(\omega)^{-1} = \frac{1}{m} F_m(\omega^{-1})$.



Polynomial multiplication algorithm

- **New new new algorithm:**

- Let m be the smallest power of 2 that is $\geq 2n$. $\omega = e^{2\pi i/m}$.
- Pad vectors \vec{a} and \vec{b} with zeroes till length m .
- Compute $\vec{y} \leftarrow F_m(\omega)\vec{a}, \vec{z} \leftarrow F_m(\omega)\vec{b}$.
- Compute $\vec{w} \leftarrow \vec{a} \odot \vec{b}$, point-wise multiplication.
- Return $\frac{1}{m}F_m(\omega^{-1})\vec{w}$.

Computing $F_m(\omega)\vec{a}$ efficiently

- Goal is to use **divide and conquer** to do this computation efficiently
- To do so, we need to find similar components to break the problem into smaller parts
- Let's analyze this for $m = 8$ and then generalize.

$$\begin{bmatrix} p(1) \\ p(\omega) \\ p(\omega^2) \\ p(\omega^3) \\ p(\omega^4) \\ p(\omega^5) \\ p(\omega^6) \\ p(\omega^7) \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & \omega & \omega^2 & \omega^3 & \omega^4 & \omega^5 & \omega^6 & \omega^7 \\ 1 & \omega^2 & \omega^4 & \omega^6 & 1 & \omega^2 & \omega^4 & \omega^6 \\ 1 & \omega^3 & \omega^6 & \omega^1 & \omega^4 & \omega^7 & \omega^2 & \omega^5 \\ 1 & \omega^4 & 1 & \omega^4 & 1 & \omega^4 & 1 & \omega^4 \\ 1 & \omega^5 & \omega^2 & \omega^7 & \omega^4 & \omega & \omega^6 & \omega^3 \\ 1 & \omega^6 & \omega^4 & \omega^2 & 1 & \omega^6 & \omega^4 & \omega^2 \\ 1 & \omega^7 & \omega^6 & \omega^5 & \omega^4 & \omega^3 & \omega^2 & \omega^1 \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \\ a_4 \\ a_5 \\ a_6 \\ a_7 \end{bmatrix}$$

Computing $F_m(\omega)\vec{a}$ efficiently

- Nothing says we have to calculate the evaluations in this order!
- Is there a better order in which a pattern emerges?

$$\begin{bmatrix} p(1) \\ p(\omega) \\ p(\omega^2) \\ p(\omega^3) \\ p(\omega^4) \\ p(\omega^5) \\ p(\omega^6) \\ p(\omega^7) \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & \omega & \omega^2 & \omega^3 & \omega^4 & \omega^5 & \omega^6 & \omega^7 \\ 1 & \omega^2 & \omega^4 & \omega^6 & 1 & \omega^2 & \omega^4 & \omega^6 \\ 1 & \omega^3 & \omega^6 & \omega^1 & \omega^4 & \omega^7 & \omega^2 & \omega^5 \\ 1 & \omega^4 & 1 & \omega^4 & 1 & \omega^4 & 1 & \omega^4 \\ 1 & \omega^5 & \omega^2 & \omega^7 & \omega^4 & \omega & \omega^6 & \omega^3 \\ 1 & \omega^6 & \omega^4 & \omega^2 & 1 & \omega^6 & \omega^4 & \omega^2 \\ 1 & \omega^7 & \omega^6 & \omega^5 & \omega^4 & \omega^3 & \omega^2 & \omega^1 \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \\ a_4 \\ a_5 \\ a_6 \\ a_7 \end{bmatrix}$$

Computing $F_m(\omega)\vec{a}$ efficiently

- Nothing says we have to calculate the evaluations in this order!
- Is there a better order in which a pattern emerges?
- **Even** rows then **odd** rows

$$\begin{bmatrix} p(1) \\ p(\omega^2) \\ p(\omega^4) \\ p(\omega^6) \\ p(\omega) \\ p(\omega^3) \\ p(\omega^5) \\ p(\omega^7) \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & \omega^2 & \omega^4 & \omega^6 & 1 & \omega^2 & \omega^4 & \omega^6 \\ 1 & \omega^4 & 1 & \omega^4 & 1 & \omega^4 & 1 & \omega^4 \\ 1 & \omega^6 & \omega^4 & \omega^2 & 1 & \omega^6 & \omega^4 & \omega^2 \\ 1 & \omega & \omega^2 & \omega^3 & \omega^4 & \omega^5 & \omega^6 & \omega^7 \\ 1 & \omega^3 & \omega^6 & \omega^1 & \omega^4 & \omega^7 & \omega^2 & \omega^5 \\ 1 & \omega^5 & \omega^2 & \omega^7 & \omega^4 & \omega & \omega^6 & \omega^3 \\ 1 & \omega^7 & \omega^6 & \omega^5 & \omega^4 & \omega^3 & \omega^2 & \omega^1 \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_2 \\ a_4 \\ a_6 \\ a_1 \\ a_3 \\ a_5 \\ a_7 \end{bmatrix}$$

Computing $F_m(\omega)\vec{a}$ efficiently

- Nothing says we have to calculate the evaluations in this order!
- Is there a better order in which a pattern emerges?
- **Even** rows then **odd** rows

$$\begin{bmatrix} p(1) \\ p(\omega^2) \\ p(\omega^4) \\ p(\omega^6) \\ p(\omega) \\ p(\omega^3) \\ p(\omega^5) \\ p(\omega^7) \end{bmatrix} = \begin{bmatrix} \begin{matrix} 1 & 1 & 1 & 1 \\ 1 & \omega^2 & \omega^4 & \omega^6 \\ 1 & \omega^4 & 1 & \omega^4 \\ 1 & \omega^6 & \omega^4 & \omega^2 \end{matrix} F_m(\omega^2) \\ \begin{matrix} 1 & \omega & \omega^2 & \omega^3 \\ 1 & \omega^3 & \omega^6 & \omega^1 \\ 1 & \omega^5 & \omega^2 & \omega^7 \\ 1 & \omega^7 & \omega^6 & \omega^5 \end{matrix} D F_m(\omega^2) \\ \begin{matrix} 1 & 1 & 1 & 1 \\ 1 & \omega^2 & \omega^4 & \omega^6 \\ 1 & \omega^4 & 1 & \omega^4 \\ 1 & \omega^6 & \omega^4 & \omega^2 \end{matrix} F_m(\omega^2) \\ \begin{matrix} \omega^4 & \omega^5 & \omega^6 & \omega^7 \\ \omega^4 & \omega^5 & \omega^2 & \omega^5 \\ \omega^4 & \omega^6 & \omega^3 & \omega^3 \\ \omega^4 & \omega^3 & \omega^2 & \omega^1 \end{matrix} D' F_m(\omega^2) \end{bmatrix} \cdot \begin{bmatrix} a_0 \\ a_2 \\ a_4 \\ a_6 \\ a_1 \\ a_3 \\ a_5 \\ a_7 \end{bmatrix}$$

Computing $F_m(\omega)\vec{a}$ efficiently

$$\begin{bmatrix} 1 & \omega & \omega^2 & \omega^3 \\ 1 & \omega^3 & \omega^6 & \omega^1 \\ 1 & \omega^5 & \omega^2 & \omega^7 \\ 1 & \omega^7 & \omega^6 & \omega^5 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \omega & 0 & 0 \\ 0 & 0 & \omega^2 & 0 \\ 0 & 0 & 0 & \omega^3 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & \omega^2 & \omega^4 & \omega^6 \\ 1 & \omega^4 & 1 & \omega^4 \\ 1 & \omega^6 & \omega^4 & \omega^2 \end{bmatrix}$$

Computing $F_m(\omega)\vec{a}$ efficiently

$$\begin{bmatrix} 1 & \omega & \omega^2 & \omega^3 \\ 1 & \omega^3 & \omega^6 & \omega^1 \\ 1 & \omega^5 & \omega^2 & \omega^7 \\ 1 & \omega^7 & \omega^6 & \omega^5 \end{bmatrix} = \begin{bmatrix} 1 & 0 & 0 & 0 \\ 0 & \omega & 0 & 0 \\ 0 & 0 & \omega^2 & 0 \\ 0 & 0 & 0 & \omega^3 \end{bmatrix} \cdot \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & \omega^2 & \omega^4 & \omega^6 \\ 1 & \omega^4 & 1 & \omega^4 \\ 1 & \omega^6 & \omega^4 & \omega^2 \end{bmatrix}$$

The blue matrix is labeled $D F_m(\omega^2)$.
 The purple matrix is labeled D .
 The green matrix is labeled $F_m(\omega^2)$.

Computing $F_m(\omega)\vec{a}$ efficiently

$$\begin{bmatrix} | \\ \textcolor{red}{P}_{\text{even}} \\ | \\ \hline | \\ \textcolor{blue}{P}_{\text{odd}} \\ | \end{bmatrix} = \begin{bmatrix} \mathbb{1} & \mathbb{1} \\ \hline \textcolor{red}{D} & \textcolor{blue}{D}' \end{bmatrix} \begin{bmatrix} F_{\frac{m}{2}}(\omega^2) \\ \hline F_{\frac{m}{2}}(\omega^2) \end{bmatrix} \begin{bmatrix} | \\ \textcolor{red}{a}_{\text{even}} \\ | \\ \hline | \\ \textcolor{blue}{a}_{\text{odd}} \\ | \end{bmatrix}$$

where $\textcolor{red}{D} = \begin{bmatrix} 1 & & & \\ & \omega & & \\ & & \omega^2 & \\ & & & \ddots \\ & & & & \omega^{m/2-1} \end{bmatrix}$, $\textcolor{blue}{D}' = \begin{bmatrix} \omega^{m/2} & & & \\ & \omega^{m/2+1} & & \\ & & \ddots & \\ & & & \omega^{m-1} \end{bmatrix}$.

Computing $F_m(\omega)\vec{a}$ efficiently

- Divide and conquer algorithm:**

- Split \vec{a} into \vec{a}_{even} and \vec{a}_{odd} coordinates.
- Compute $\vec{y}_{\text{even}} \leftarrow F_{m/2}(\omega^2)\vec{a}_{\text{even}}$ and $\vec{y}_{\text{odd}} \leftarrow F_{m/2}(\omega^2)\vec{a}_{\text{odd}}$.
- Compute $D\vec{y}_{\text{even}}$ and $D'\vec{y}_{\text{odd}}$.
- Compute $\begin{bmatrix} \vec{y}_{\text{even}} + \vec{y}_{\text{odd}} \\ D\vec{y}_{\text{even}} + D'\vec{y}_{\text{odd}} \end{bmatrix}$.
- Rearrange coordinates to original format.

$$\begin{bmatrix} | \\ \text{P}_{\text{even}} \\ | \\ | \\ \text{P}_{\text{odd}} \\ | \end{bmatrix} = \begin{bmatrix} \mathbb{1} & \mathbb{1} \\ \hline \mathcal{D} & \mathcal{D}' \end{bmatrix} \underbrace{\begin{bmatrix} F_{\frac{m}{2}}(\omega^2) & \\ \hline & F_{\frac{m}{2}}(\omega^2) \end{bmatrix} \begin{bmatrix} | \\ \text{a}_{\text{even}} \\ | \\ | \\ \text{a}_{\text{odd}} \\ | \end{bmatrix}}_{\begin{bmatrix} | \\ \text{y}_{\text{even}} \\ | \\ | \\ \text{y}_{\text{odd}} \\ | \end{bmatrix}}$$

Computing $F_m(\omega)\vec{a}$ efficiently

Total time: $T(m) = 2T\left(\frac{m}{2}\right) + O(m)$

$$T(m) = O(m \log m).$$

- Divide and conquer algorithm:**

- Split \vec{a} into \vec{a}_{even} and \vec{a}_{odd} coordinates. $\leftarrow O(m)$ time.
- Compute $\vec{y}_{\text{even}} \leftarrow F_{m/2}(\omega^2)\vec{a}_{\text{even}}$ and $\vec{y}_{\text{odd}} \leftarrow F_{m/2}(\omega^2)\vec{a}_{\text{odd}}$. \leftarrow Recursion: $2T\left(\frac{m}{2}\right)$ time.
- Compute $D\vec{y}_{\text{even}}$ and $D'\vec{y}_{\text{odd}}$. $\leftarrow D, D'$ diagonal so $O(m)$ time.
- Compute $\begin{bmatrix} \vec{y}_{\text{even}} + \vec{y}_{\text{odd}} \\ D\vec{y}_{\text{even}} + D'\vec{y}_{\text{odd}} \end{bmatrix}$. $\leftarrow O(m)$ time.
- Rearrange coordinates to original format. $\leftarrow O(m)$ time.

Returning to the full algorithm

- **New new new algorithm:**

- Let m be the smallest power of 2 that is $\geq 2n$. $\omega = e^{2\pi i/m}$.

- Pad vectors \vec{a} and \vec{b} with zeroes till length m .

- Compute $\vec{y} \leftarrow F_m(\omega)\vec{a}, \vec{z} \leftarrow F_m(\omega)\vec{b}$.

- Compute $\vec{w} \leftarrow \vec{a} \odot \vec{b}$, point-wise multiplication.

- Return $F_m(\omega)^{-1}\vec{w}$.

Theorem: $F_m(\omega)^{-1} = \frac{1}{m} F_m(\omega^{-1})$.

Returning to the full algorithm

- **New new new algorithm:**

- Let m be the smallest power of 2 that is $\geq 2n$. $\omega = e^{2\pi i/m}$.
- Pad vectors \vec{a} and \vec{b} with zeroes till length m .
- Compute $\vec{y} \leftarrow F_m(\omega)\vec{a}, \vec{z} \leftarrow F_m(\omega)\vec{b}$. $\leftarrow \text{Runtime } O(n \log n)$
- Compute $\vec{w} \leftarrow \vec{a} \odot \vec{b}$, point-wise multiplication. $\leftarrow \text{Runtime } O(n)$
- Return $\frac{1}{m}F_m(\omega^{-1})\vec{w}$. $\leftarrow \text{Runtime } O(n \log n)$

Fast Fourier Transform

- The algorithm for computing $F_m(\omega)\vec{a}$ is known as the **Fast Fourier Transform (FFT)**
- It serves as a major component in many algorithms particularly dealing with polynomial computations
- Quantum computers are capable of “implementing” the FFT on matrices in time $O(\text{polylog } m)$. This is the major step in the quantum factoring algorithm and the hype behind quantum computers.

Final remaining theorem

• **Theorem:** $F_m(\omega)^{-1} = \frac{1}{m} F_m(\omega^{-1})$.

• **Proof:** Suffices to show that $F_m(\omega) \cdot F_m(\omega^{-1}) = m \mathbb{1}$.

$$\underbrace{\left(F_m(\omega) \cdot F_m(\omega^{-1}) \right)}_{\text{matrix coordinate } i,j}_{ij} = \sum_{k=0}^{m-1} \left(F_m(\omega) \right)_{ik} \left(F_m(\omega^{-1}) \right)_{kj}$$

$$= \sum_{k=0}^{m-1} \omega^{ik} \cdot (\omega^{-1})^{kj}$$

$$= \sum_{k=0}^{m-1} \omega^{k(i-j)} = \begin{cases} m & \text{if } i=j \\ 0 & \text{if } i \neq j \end{cases}$$

← sum of all roots of unity is 0.

General algorithm: Convolution

- **Input:** Two vectors $f = (f_0, \dots, f_{n-1}), g = (g_0, \dots, g_{n-1}) \in \mathbb{C}^n$
- **Output:** The convolution vector $f * g$ is defined by

$$(f * g)_k := \sum_{j=0}^n f_j \cdot g_{n-j}$$

- **Algorithm:** Exact same alg. as that of poly. mult.:

$$f * g = \frac{1}{n} F_n(\omega^{-1}) (F_n(\omega) f \odot F_n(\omega) g) \text{ for } \omega = e^{2\pi i/n}.$$

- **Runtime:** $O(n \log n)$

- **Proof:**

- Let p, q be the poly. with coeffs. given by f, g
- Then $f * g$ are the coeffs. of the poly.
 $r = pq \pmod{x^n}$
- Then $r(\omega^j) = p(\omega^j)q(\omega^j)$ for $j = 0$ to $n - 1$
- So, prev algorithm will find the coefficients of the unique polynomial

Overtime (stay if interested)

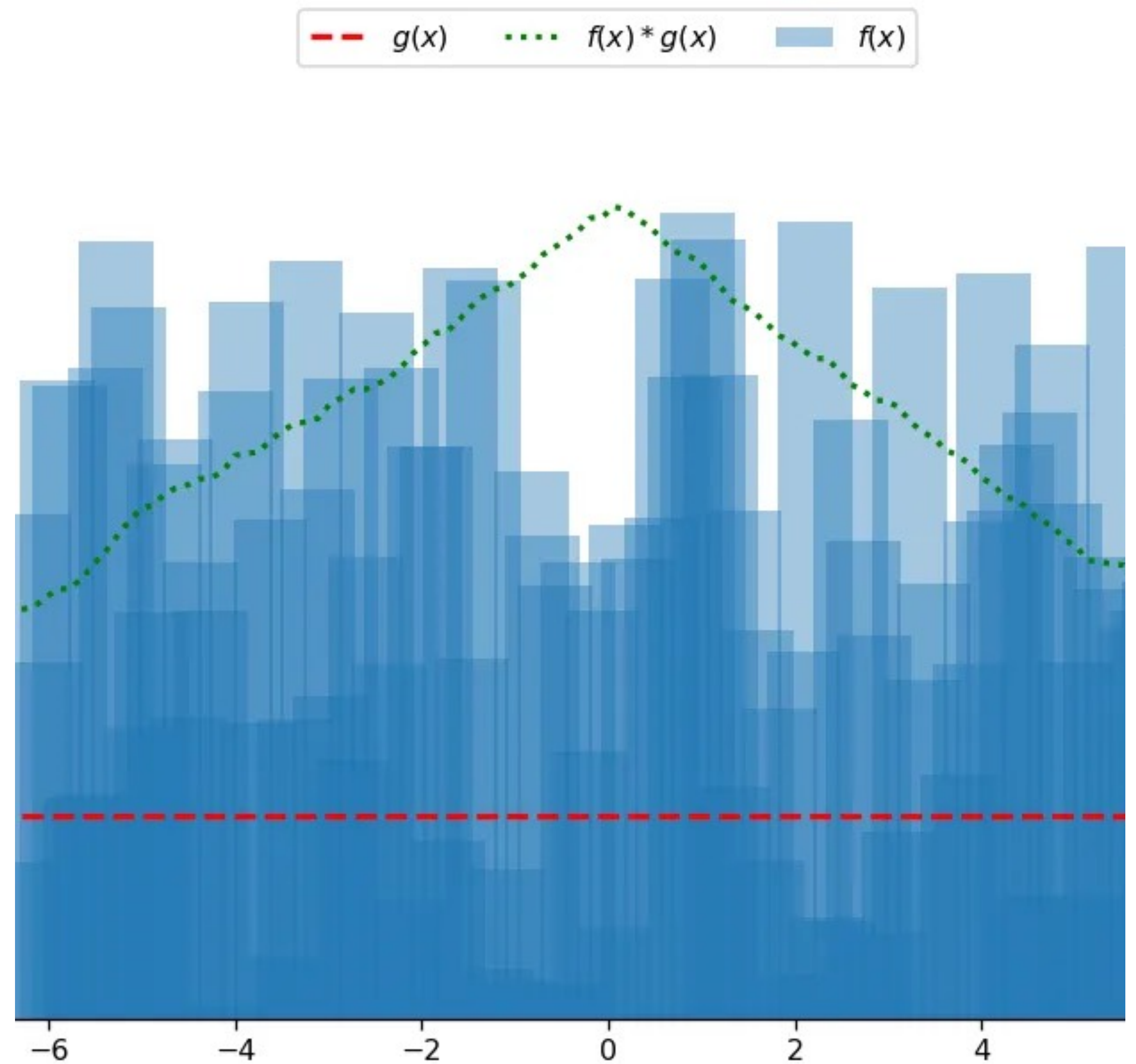
Convolution

- An algorithm for combining two signals to form a third signal
- Shows up most commonly now in *convolution neural networks*

- $(f * g)_k := \sum_{j=0}^n f_j \cdot g_{n-j}$ vs

- $(f * g)(x) = \int_{-\infty}^{\infty} f(\tau)g(x - \tau)d\tau$

- This is the area under the curve f with weights defined by g
- Let's you smooth out the curve f by picking g



Source: Medium post by TDS archive.

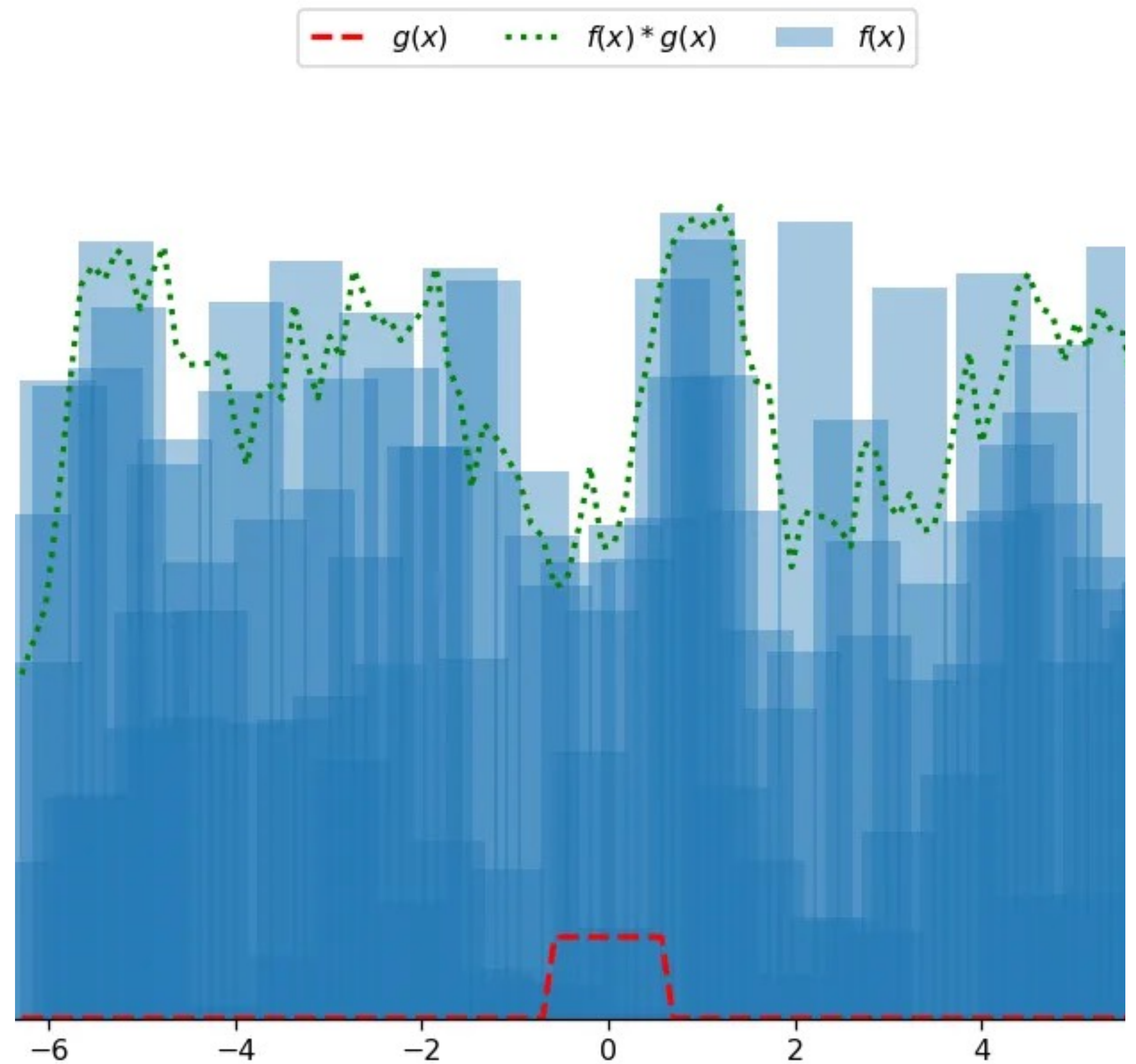
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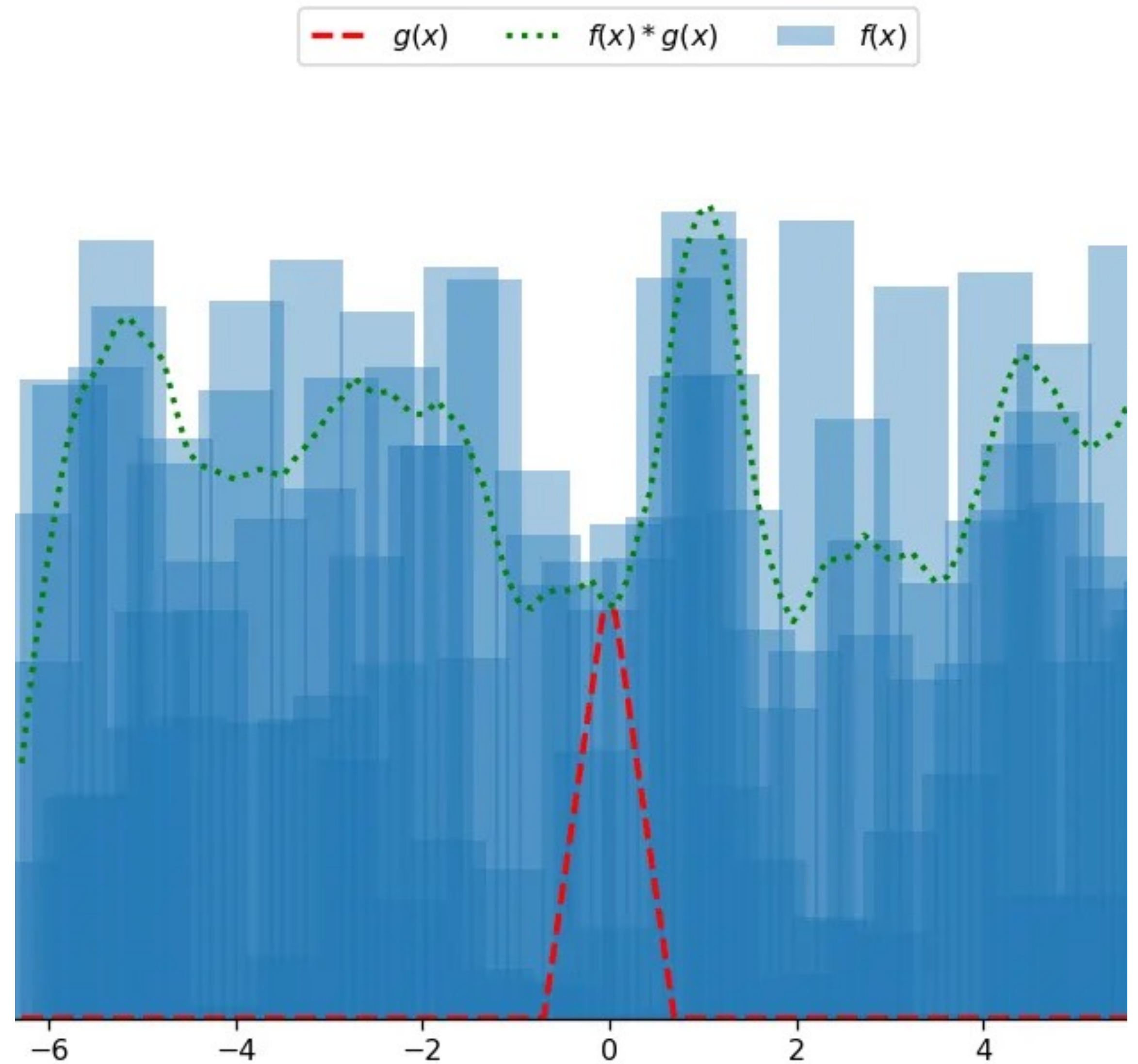
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Source: Medium post by TDS archive.

Convolution

Gaussian blurring and edge detection

- Ex. We can also apply a 2D version of convolution for image processing



Source: Stanford 315b lectures

Convolution

- Filtering signals (low-pass, high-pass)
 - Convolve with a signal to filter out certain frequencies
- Audio effects (reverb, echo, suppression)
- Image processing
- And more!