# CSE 421: Introduction to Algorithms 

## Stable Matching

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## Administrativia Stuffs

HW1 is due Wednesday April 03 at 11:59PM
Please submit to Gradescope
Late Submission: Fill out an extension request
 in edstem.

## How to submit?

- Double check your submission before the deadline!!
- Please typeset your solution if possible


## Guidelines:

- Always justify your answer
- You can collaborate, but you must write solutions on your own
- Read guidelines in the website
- Sanity Check: Spell out when you use assumptions of the problem


## Summary

Stable matching problem: Given $n$ companies and $n$ applicants, and their preferences, find a stable matching if one exists.

- Gale-Shapley algorithm: Guarantees to find a stable matching for any problem instance.
- Q: If there are multiple stable matchings, which one does GS find?
- Q: How to implement GS algorithm efficiently?
- Q: How many stable matchings are there?


## Company Optimal Assignments

Definition: Company $c$ is a valid partner of applicant $a$ if there exists some stable matching in which they are matched.

Company-optimal matching: Each company receives the best valid partner (according to its preferences).

- Not that each company receives its most favorite applicant.

Claim: All executions of GS yield a company-optimal matching, which is a stable matching!

- So, output of GS is unique!!
- No reason a priori to believe that company-optimal matching is perfect, let alone stable.


## Company Optimality

Claim: GS matching S* is company-optimal.

## Proof: (by contradiction)

Suppose some company is paired with someone other than its best valid partner. Companies propose in decreasing order of preference $\Rightarrow$ some company is rejected by a valid partner.

Let $c$ be the first such rejection, and let $a$ be its best valid partner.
Let $\mathbf{S}$ be a stable matching where $c$ and $a$ are matched.
In building $\mathbf{S}^{*}$, when $c$ is rejected, $a$ is assigned to a company, say $c^{\prime}$ whom she prefers to $c$.

Let $c^{\prime}$ be $a^{\prime}$ partner in $\mathbf{S}$.
In building $S^{*}, c^{\prime}$ is not rejected by any valid partner at the point when $c$ is rejected by $a$. Thus, $c^{\prime}$ prefers $a$ to $a^{\prime}$.
But $a$ prefers $c^{\prime}$ to $c$.
Thus $\left(c^{\prime}, a\right)$ is unstable in $\mathbf{S}$.

## Company Optimality Summary

Company-optimality: In version of GS where companies propose, each comapny receives the best valid partner.
$a$ is a valid partner of $c$ if there exist some
stable matching where $c$ and $a$ are paired

Q: Does company-optimality come at the expense of the applicants?

## Applicant Pessimality

Applicant-pessimal assignment: Each applicant receives the worst valid partner.

Claim. GS finds applicant-pessimal stable matching S*.

## Proof.

Suppose ( $c, a$ ) matched in $\mathbf{S}^{*}$, but $c$ is not the worst valid partner for $a$. There exists stable matching $\mathbf{S}$ in which $a$ is paired with a company, say $c^{\prime}$, whom she likes less than $c$.

Let $a^{\prime}$ be $c$ partner in S.
$c$ prefers $a$ to $a^{\prime}$. $\longleftarrow$ company-optimality of $\mathbf{S}^{*}$
Thus, $(c, a)$ is an unstable in $\mathbf{S}$.

## Efficient Implementation

We describe $O\left(n^{2}\right)$ time implementation. This is linear in input size.

## Representing company and applicant:

Assume companies are named $1, \ldots, n$.
Assume applicants are named $\mathrm{n}+1, \ldots, 2 \mathrm{n}$.

## Data Structure:

Maintain a list of free company, e.g., in a queue.
Maintain two arrays applicant[c], and company[a].

- set entry to 0 if unmatched
- if $\mathbf{c}$ matched to a then applicant[c]=a and company[a]=c


## Companies proposing:

For each company, maintain a list of applicants, ordered by preference. Maintain an array count[c] that counts the number of proposals made by company c.

## Efficient Implementation

## Applicants rejecting/accepting.

Does applicant a prefer c to c'?
For each applicant, create inverse of preference list of companies. Constant time access for each query after $\mathbf{O}(n)$ preprocessing per applicant. $\mathbf{O}\left(\mathrm{n}^{2}\right)$ total reprocessing cost.

| $a_{i}$ | $1^{\text {st }}$ | $2^{\text {nd }}$ | $3^{\text {rd }}$ | $4^{\text {th }}$ | $5^{\text {th }}$ | $6^{\text {th }}$ | $7^{\text {th }}$ | $8^{\text {th }}$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Pref | 8 | 3 | 7 | 1 | 4 | 5 | 6 | 2 |


| $a_{i}$ | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Inverse | $4^{\text {th }}$ | $8^{\text {th }}$ | $2^{\text {td }}$ | $5^{\text {th }}$ | $6^{\text {th }}$ | $7^{\text {th }}$ | $3^{\text {rd }}$ | $1^{\text {st }}$ |

```
for i = 1 to n
    for j = 1 to n
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    \(a_{i}\) prefers company 3 to 6
        inverse[i][pref[i][j]] = j since inverse[i][3]=2 < 7=inverse[i][6]
    
## Summary

- Stable matching problem: Given $\mathbf{n}$ men and $\mathbf{n}$ women, and their preferences, find a stable matching if one exists.
- Gale-Shapley algorithm guarantees to find a stable matching for any problem instance.
- GS algorithm finds a stable matching in $\mathbf{O}\left(\mathbf{n}^{2}\right)$ time.
- GS algorithm finds man-optimal woman pessimal matching
- Q: How many stable matching are there?


## How many stable Matchings?

We already show every instance has at least 1 stable matchings.
[Knuth'76] There are instances with about $2.24^{n}$ stable matchings for
[Karlin-O-Weber'17]: Every instance has at most $131072^{n}$ stable matchings
[Palmer-Palvolgyi'20]: Every instance has at most $4.47^{n}$ stable matchings
[Research-Question]:
Is there an "efficient" algorithm that chooses a uniformly random stable matching of a given instance.

# Main Objective: Design Efficient Algorithms that finds optimum solutions in the Worst Case 

## Measuring Efficiency

Time $\approx$ \# of instructions executed in a simple programming language

- Only simple operations (+,, ${ }^{*}$,,,=,if,call,...)
- Each operation takes one time step each memory access takes one time step
- No fancy stuff (add these two matrices, copy this long string, ...) built in; write it/charge for it as above
- Hashing: A hash function takes $O(n)$ to search for an element in the worst case.


## Time Complexity

Problem: An algorithm can have different running time on different inputs

Solution: The complexity of an algorithm associates a number $\mathrm{T}(\mathrm{N})$, the "time" the algorithm takes on problem size N .

Mathematically,
T is a function that maps positive integers giving problem size to positive integers giving number of steps

## Time Complexity (N)

Worst Case Complexity: max \# steps algorithm takes on any input of size $\mathbf{N}$

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Average Case Complexity: avg \# steps algorithm takes on inputs of size $\mathbf{N}$

Best Case Complexity: min \# steps algorithm takes on any input of size $\mathbf{N}$

## Why Worst-case Inputs?

- Analysis is typically easier
- Useful in real-time applications
e.g., space shuttle, nuclear reactors)
- Worst-case instances kick in when an algorithm is run as a module many times
e.g., geometry or linear algebra library
- Useful when running competitions
e.g., airline prices
- Unlike average-case no debate about the right definition


## Time Complexity on Worst Case Inputs



## O-Notation

Given two positive functions $f$ and $g$

- $f(N)$ is $\underline{O}(g(N))$ iff there is a constant $c>0$ s.t., $f(N)$ is eventually always $\leq c g(N)$
- $f(N)$ is $\Omega(g(N))$ iff there is a constant $\varepsilon>0$ s.t., $f(N)$ is $\geq \varepsilon g(N)$ for infinitely
- $f(N)$ is $\Theta(g(N))$ iff there are constants $c_{1}, c_{2}>0$ so that eventually always $c_{1} g(N) \leq f(N) \leq c_{2} g(N)$


## Asymptotic Bounds for common fns

- Polynomials:

$$
a_{0}+a_{1} n+\cdots+a n^{d} \text { is } O\left(n^{d}\right)
$$

- Logarithms:
$\log _{a} n=O\left(\log _{b} n\right)$ for all constants $a, b>0$
- Logarithms: log grows slower than every polynomial For all $x>0, \log n=O\left(n^{k}\right)$
- $n \log n=O\left(n^{1.01}\right)$


## Efficient = Polynomial Time

An algorithm runs in polynomial time if $T(n)=O\left(n^{d}\right)$ for some constant d independent of the input size $n$.

Why Polynomial time?


If problem size grows by at most a constant factor then so does the running time

- E.g. $\mathrm{T}(2 \mathrm{~N}) \leq \mathrm{c}(2 \mathrm{~N})^{\mathrm{k}} \leq 2^{\mathrm{k}}\left(\mathrm{c} \mathrm{N}^{\mathrm{k}}\right)$
- Polynomial-time is exactly the set of running times that have this property

Typical running times are small degree polynomials, mostly less than $\mathbf{N}^{3}$, at worst $\mathbf{N}^{6}$, not $\mathbf{N}^{100}$

## Why it matters?

- \#atoms in universe $<2^{240}$
- Life of the universe $<2^{54}$ seconds
- A CPU does $<2^{30}$ operations a second

If every atom is a CPU, a $2^{n}$ time ALG cannot solve $\mathrm{n}=350$ if we start at Big-Bang.

|  | $n$ | $n \log _{2} n$ | $n^{2}$ | $n^{3}$ | $1.5^{n}$ | $2^{n}$ | $n!$ |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | ---: |
| $n=10$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 4 sec |
| $n=30$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 18 min | $10^{25}$ years |
| $n=50$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 11 min | 36 years | very long |
| $n=100$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 1 sec | 12,892 years | $10^{17}$ years | very long |
| $n=1,000$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 1 sec | 18 min | very long | very long | very long |
| $n=10,000$ | $<1 \mathrm{sec}$ | $<1 \mathrm{sec}$ | 2 min | 12 days | very long | very long | very long |
| $n=100,000$ | $<1 \mathrm{sec}$ | 2 sec | 3 hours | 32 years | very long | very long | very long |
| $n=1,000,000$ | 1 sec | 20 sec | 12 days | 31,710 years | very long | very long | very long |

not only get very big, but do so abruptly, which likely yields erratic performance on small instances

## Why "Polynomial"?

Point is not that $\mathrm{n}^{2000}$ is a practical bound, or that the differences among n and 2 n and $\mathrm{n}^{2}$ are negligible.
Rather, simple theoretical tools may not easily capture such differences, whereas exponentials are qualitatively different from polynomials, so more amenable to theoretical analysis.

- "My problem is in P " is a starting point for a more detailed analysis
- "My problem is not in P" may suggest that you need to shift to a more tractable variant

